

COM-MY Communication Data List

Thank you for purchasing this RKC product. In order to achieve maximum performance and ensure proper operation of your new instrument, carefully read all the instructions in this manual. Please place this manual in a convenient location for easy reference.

This manual describes the communication data of the COM-MY. For the installation, various function settings and SRZ engineering setting data, please read if necessary the following separate manuals.

- COM-MY Installation Manual (IMR02E01-ED): Enclosed with COM-MY
- COM-MY Instruction Manual (IMR02E02-ED): Enclosed with COM-MY
- COM-MY SRZ Communication Data List (IMR02E04-ED): Separate (Download or sold separately)

The above manuals can be downloaded from our website:
URL: http://www.rkcinst.com/english/manual_load.htm

1. EXPLANATION OF DATA MAP ITEMS

The communication data map shows data which can be used for communication between the PLC/host computer and COM-MY.

- Name: Name of communication data
Symbols:
□: Data for each SRZ unit
▲: Data for each channel
On a Z-TIO module (2-channel type), the communication data of CH3 and CH4 becomes invalid.
♦: Data for each module
★: Parameters which can be used in multi-memory area function
♣: Parameters only used for heat/cool control or position proportioning control, therefore data for CH2 and CH4 of Z-TIO module are unused.
[Read is possible (0), but the result of Write is disregarded.]

RKC Identifier: Communication identifier of RKC communication

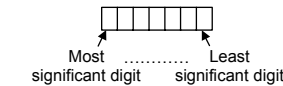
MECHATROLINK/Modbus register address:
A register address of Modbus and MECHATROLINK data item specification
HEX: Hexadecimal DEC: Decimal

Digits: The number of communication data digits in RKC communication

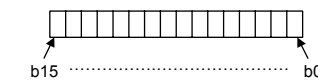
Attribute: A method of how communication data items are read or written when viewed from the PLC/host computer is described.
RO: Read only data [Host computer or PLC ← COM-MY (SRZ)]
R/W: Read and Write data [Host computer or PLC ↔ COM-MY (SRZ)]

Data range and Number of data:
Read or Write range of communication data
[]: Number of data
This is the maximum number per communication data that can be handled by one SRZ unit.

- ASCII code data (Example: 7 digits)



- 16-bit data



Factory set value: Factory set value of communication data

2. COMMUNICATION DATA MAP

■ Communication data of COM-MY

Name	RKC Identifier	MECHATROLINK/Modbus register address	Digits	Attribute	Data range and Number of data	Factory set value
		HEX DEC				
Model code ♦ (COM-MY)	ID	— —	32	RO	Model code (character)	[1]
Model code ♦ (Function module ¹)	IE	— —	32	RO	Model code (character)	[100]
ROM version ♦ (COM-MY)	VR	— —	8	RO	ROM version	[1]
ROM version ♦ (Function module ¹)	VQ	— —	8	RO	ROM version	[100]
Integrated operating time monitor ♦ (COM-MY)	UT	— —	7	RO	0 to 19999 hours	[1]
Integrated operating time monitor ♦ (Function module ¹)	UV	— —	7	RO	0 to 19999 hours	[100]

Name	RKC Identifier	MECHATROLINK/Modbus register address		Digits	Attribute	Data range and Number of data	Factory set value
		HEX	DEC				
Error code □ (COM-MY)	ER	0000	0	7	RO	<ul style="list-style-type: none"> • RKC communication <ul style="list-style-type: none"> 1: Adjustment data error ^{a,b} 2: Data back-up error ^{a,b,c} 4: A/D conversion error ^{a,b,c} 32: Logic output data error ^a 64: Stack overflow ^c 512: MECHATROLINK monitoring error ^c • MECHATROLINK/Modbus <ul style="list-style-type: none"> b0: Adjustment data error ^{a,b} b1: Data back-up error ^{a,b,c} b2: A/D conversion error ^{a,b,c} b3, b4: Unused b5: Logic output data error ^a b6: Stack overflow ^c b7, b8: Unused b9: MECHATROLINK monitoring error ^c b10 to b15: Unused Data: 0: OFF 1: ON [Decimal number: 0 to 39] For the identifier ER, the error condition is shown by the OR of each module. When multiple errors occur, the error number is the sum value. ^a Item of the Z-TIO/Z-DIO module ^b Item of the Z-CT module ^c Item of the COM-MY [COM-MY: 1] [Z-TIO, Z-DIO and Z-CT: 100]	—
Error code ♦ (Function module ¹)	EZ	0001 : 0064	1 : 100	7	RO	<ul style="list-style-type: none"> • RKC communication <ul style="list-style-type: none"> 1: Adjustment data error ^{a,b} 2: Data back-up error ^{a,b,c} 4: A/D conversion error ^{a,b,c} 32: Logic output data error ^a 64: Stack overflow ^c 512: MECHATROLINK monitoring error ^c • MECHATROLINK/Modbus <ul style="list-style-type: none"> b0: Adjustment data error ^{a,b} b1: Data back-up error ^{a,b,c} b2: A/D conversion error ^{a,b,c} b3, b4: Unused b5: Logic output data error ^a b6: Stack overflow ^c b7, b8: Unused b9: MECHATROLINK monitoring error ^c b10 to b15: Unused Data: 0: OFF 1: ON [Decimal number: 0 to 39] For the identifier ER, the error condition is shown by the OR of each module. When multiple errors occur, the error number is the sum value. ^a Item of the Z-TIO/Z-DIO module ^b Item of the Z-CT module ^c Item of the COM-MY [COM-MY: 1] [Z-TIO, Z-DIO and Z-CT: 100]	—
Backup memory state monitor ♦ (COM-MY)	EM	0065	101	1	RO	0: The content of the backup memory does not coincide with that of the RAM.	—
Backup memory state monitor ♦ (Function module ¹)	CZ	0066 : 00C9	102 : 201	1	RO	1: The content of the backup memory coincides with that of the RAM. [COM-MY: 1] [Z-TIO, Z-DIO and Z-CT: 100]	—
Unused	—	00CA : 00CB	202 : 303	—	—	—	—
Network error code □	ES	00CC	204	7	RO	0: Normal 1: Initialization error 2: Device access error 3: Abnormal break [1]	—
Network state □	QN	00CD	205	7	RO	0: Not connected 1: Waiting for ID read 2: Connected [1]	—
Unused	—	00CE : 0131	206 : 305	—	—	—	—
Monitor for the number of connected modules □	QK	0132	306	7	RO	0 to 31 [1]	—
RUN/STOP transfer □	SR	0133	307	1	R/W	0: STOP (Control stop) 1: RUN (Control start) [1]	0
RUN/STOP transfer ♦	SW	0134 : 0197	308 : 407	1	R/W	0: STOP (Control stop) 1: RUN (Control start) [100]	0
Control RUN/STOP holding setting ♦	X1	0198 : 01FB	408 : 507	1	R/W	0: Not holding (STOP start) 1: Holding (RUN/STOP hold) [100]	1
The following items are enabled when the power is turned on again or when control is changed from STOP to RUN.							
Unused	—	8000 : 8003	32768 : 32771	—	—	—	—
Communication protocol □	VP	8004	32772	1	R/W	0: RKC communication 1: Modbus [1]	0
Communication speed □	VU	8005	32773	1	R/W	0: 4800 bps 2: 19200 bps 1: 9600 bps 3: 38400 bps [1]	2
Communication data bit configuration □	VW	8006	32774	7	R/W	0 to 5 See table 1. [1]	0
Communication interval time □	VX	8007	32775	7	R/W	0 to 250 ms [1]	10
Unused	—	8008 : 8010	32776 : 32784	—	—	—	—
Method for setting the number of connected modules □	RY	8011	32785	7	R/W	0: No action. 1: Automatically set the maximum number of connected function modules only when power is turned on. 2: Execute automatic setting of the maximum number of connected function modules.* * After automatic setting of the number of connected function modules, the value automatically reverts to 0. [1]	1
Number of connected modules ² (Z-TIO module) □	QY	8013	32787	7	R/W	0 to 16 Maximum number of Z-TIO modules connected to COM-MY. [1]	—
Number of connected modules ² (Z-DIO module) □	QU	8014	32788	7	R/W	0 to 16 Maximum number of Z-DIO modules connected to COM-MY. [1]	—
Number of connected modules ² (Z-CT module) □	QO	8015	32789	7	R/W	0 to 16 Maximum number of Z-CT modules connected to COM-MY. [1]	—

Name	RKC Identifier	MECHATROLINK/Modbus register address		Digits	Attribute	Data range and Number of data	Factory set value
		HEX	DEC				
Unused	—	8016 : 801A	32790 : 32794	—	—	—	—
Control RUN/STOP holding setting □	X2	801B	32795	1	R/W	0: Not holding (STOP start) 1: Holding (RUN/STOP hold) [1]	1

¹ Function module: Z-TIO module, Z-DIO module or Z-CT module
² When 1 or 2 is set for the communication identifier RY (method of setting the number of connected modules), the maximum number of connected modules is set automatically. When 0 is set, the maximum number of connected modules is set manually.
Maximum number of connected modules:
Maximum address of function modules (address setting switch set value + 1)
COM-MY uses this set value to calculate the number of channels of communication data (Only for RKC communication).

Table 1: Data bit configuration

Set value	Data bit	Parity bit	Stop bit	Settable communication
0	8	Without	1	Modbus
1	8	Even	1	
2	8	Odd	1	RKC communication
3	7	Without	1	
4	7	Even	1	RKC communication
5	7	Odd	1	

Data range: Modbus: 0 to 2 RKC communication: 0 to 5

■ Communication data of Z-TIO module

Name	RKC Identifier	MECHATROLINK/Modbus register address		Digits	Attribute	Data range and Number of data	Factory set value
		HEX	DEC				
Measured value (PV) ▲	M1	01FC : 023B	508 : 571	7	RO	Input scale low to Input scale high [64]	—
Comprehensive event state ▲	AJ	023C : 027B	572 : 635	7	RO	<ul style="list-style-type: none"> • RKC communication Least significant digit to 4th digit: <ul style="list-style-type: none"> Event 1 to Event 4 5th digit: Heater break alarm 6th digit: Temperature rise completion 7th digit: Burnout Data: 0: OFF 1: ON • MECHATROLINK/Modbus b0 to b3: Event 1 to Event 4 b4: Heater break alarm b5: Temperature rise completion b6: Burnout b7 to b15: Unused Data: 0: OFF 1: ON [Decimal number: 0 to 127] [64] 	—
Operation mode state monitor ▲	L0	027C : 02BB	636 : 699	7	RO	<ul style="list-style-type: none"> • RKC communication Least significant digit: <ul style="list-style-type: none"> Control STOP 2nd digit: Control RUN 3rd digit: Manual mode 4th digit: Remote mode 5th digit to Most significant digit: Unused Data: 0: OFF 1: ON • MECHATROLINK/Modbus b0: Control STOP b1: Control RUN b2: Manual mode b3: Remote mode b4 to b15: Unused Data: 0: OFF 1: ON [Decimal number: 0 to 15] [64] 	—
Unused	—	02BC : 02CB	700 : 715	—	—	—	—
Manipulated output value (MV) monitor [heat-side] ♣ ▲	O1	02CC : 030B	716 : 779	7	RO	PID control or heat/cool PID control: -5.0 to +105.0 % Position proportioning control (FBR input): 0.0 to 100.0 % [64]	—
Manipulated output value (MV) monitor [cool-side] ♣ ▲	O2	030C : 034B	780 : 843	7	RO	-5.0 to +105.0 % [64]	—
Current transformer (CT) input value monitor ▲	M3	034C : 038B	844 : 907	7	RO	CTL-6-P-N: 0.0 to 30.0 A CTL-12-S56-10L-N: 0.0 to 100.0 A [64]	—
Set value (SV) monitor ▲	MS	038C : 03CB	908 : 971	7	RO	Setting limiter (low) to Setting limiter (high) [64]	—
Remote setting (RS) input value monitor ▲	S2	03CC : 040B	972 : 1035	7	RO	Setting limiter (low) to Setting limiter (high) [64]	—
Burnout state monitor ▲	B1	040C : 044B	1036 : 1099	1	RO	0: OFF 1: ON [64]	—
Event 1 state monitor ▲	AA	044C : 048B	1100 : 1163	1	RO	0: OFF 1: ON [64]	—
Event 2 state monitor ▲	AB	048C : 04CB	1164 : 1227	1	RO	If the Event 3 type is temperature rise completion, check the temperature rise completion state in the comprehensive event state (Identifier: AJ, Register address: 023C to 027B). (The Event 3 state monitor does not turn ON.) [Each 64]	—
Event 3 state monitor ▲	AC	04CC : 050B	1228 : 1291	1	RO	—	—
Event 4 state monitor ▲	AD	050C : 054B	1292 : 1355	1	RO	—	—
Heater break alarm (HBA) state monitor ▲	AE	054C : 058B	1356 : 1419	1	RO	0: OFF 1: ON [64]	—

Name	RKC Identifier	MECHATROLINK/Modbus register address		Digits	Attribute	Data range and Number of data	Factory set value
		HEX	DEC				
Output state monitor ♦	Q1	058C : 059B	1420 : 1435	7	RO	<ul style="list-style-type: none"> • RKC communication Least significant digit to 4th digit: <ul style="list-style-type: none"> OUT1 to OUT4 5th digit to Most significant digit: Unused Data: 0: OFF 1: ON • MECHATROLINK/Modbus b0 to b3: OUT1 to OUT4 b4 to b15: Unused Data: 0: OFF 1: ON [Decimal number: 0 to 15] [16] 	—
Memory area soak time monitor ▲	TR	059C : 05DB	1436 : 1499	7	RO	0 minutes 00 seconds to 199 minutes 59 seconds: RKC communication: 0:00 to 199:59 (min:sec) MECHATROLINK/Modbus: 0 to 11999 seconds 0 hours 00 minutes to 99 hours 59 minutes: RKC communication: 0:00 to 99:59 (hrs:min) MECHATROLINK/Modbus: 0 to 5999 minutes [64]	—
Unused	—	05DC : 05EB	1500 : 1515	—	—	—	—
Holding peak value ambient temperature monitor ▲	Hp	05EC : 062B	1516 : 1579	7	RO	-10.0 to +100.0 °C or 14.0 to 212.0 °F [64]	—
Unused	—	062C : 063B	1580 : 1595	—	—	—	—
Logic output monitor 1 ♦	ED	063C : 064B	1596 : 1611	7	RO	<ul style="list-style-type: none"> • RKC communication Least significant digit to 4th digit: <ul style="list-style-type: none"> Logic output 1 to 4 5th digit to Most significant digit: Unused Data: 0: OFF 1: ON • MECHATROLINK/Modbus b0 to b7: Logic output 1 to 8 b8 to b15: Unused Data: 0: OFF 1: ON [Decimal number: 0 to 255] [16] 	—
Logic output monitor 2 ♦	EE	—	—	7	RO	Only for RKC communication Least significant digit to 4th digit: <ul style="list-style-type: none"> Logic output 5 to 8 5th digit to Most significant digit: Unused Data: 0: OFF 1: ON [16]	—
Unused	—	064C : 080B	1612 : 2059	—	—	—	—
PID/AT transfer ▲	G1	080C : 084B	2060 : 2123	1	R/W	0: PID control 1: Autotuning (AT) * * Automatically reverts to 0 after auto-tuning ends. [64]	0
Auto/Manual transfer ▲	J1	084C : 088B	2124 : 2187	1	R/W	0: Auto mode 1: Manual mode [64]	0
Remote/Local transfer ▲	C1	088C : 08CB	2188 : 2251	1	R/W	0: Local mode 1: Remote mode [64]	0
Unused	—	08CC : 08DB	2252 : 2267	—	—	—	—
Memory area transfer ▲	ZA	08DC : 091B	2268 : 2331	7	R/W	1 to 8 [64]	1
Interlock release ▲	AR	091C : 095B	2332 : 2395	1	R/W	0: Normal state 1: Interlock release execution [64]	0
Event 1 set value (EV1) ★ ▲	A1	095C : 099B	2396 : 2459	7	R/W	Deviation action, Deviation action between channels, Temperature rise completion range *: -Input span to +Input span Process action, SV action: Input scale low to Input scale high MV action: -5.0 to +105.0 % * When temperature rise completion is selected at Event 3 action type. [Each 64]	50
Event 2 set value (EV2) ★ ▲	A2	099C : 09DB	2460 : 2523	7	R/W	—	50
Event 3 set value (EV3) ★ ▲	A3	09DC : 0A1B	2524 : 2587	7	R/W	—	50
Event 4 set value (EV4) ★ ▲	A4	0A1C : 0A5B	2588 : 2651	7	R/W	—	50
Control loop break alarm (LBA) time ★ ▲	A5	0A5C : 0A9B	2652 : 2715	7	R/W	0 to 7200 seconds (0: Unused) [64]	480
LBA deadband ★ ▲	N1	0A9C : 0ADB	2716 : 2779	7	R/W	0 (0.0) to Input span [64]	0 (0.0)
Set value (SV) ★ ▲	S1	0ADC : 0B1B	2780 : 2843	7	R/W	Setting limiter (low) to Setting limiter (high) [64]	TC/RTD: 0 V/I: 0.0
Proportional band [heat-side] ★ ★ ▲	P1	0B1C : 0B5B	2844 : 2907	7	R/W	TC/RTD inputs: 0 (0.0) to Input span (Unit: °C [°F]) Voltage (V)/current (I) inputs: 0.0 to 1000.0 % of input span 0 (0.0): ON/OFF action ON/OFF action for both heat and cool actions in case of a heat/cool control type. [64]	TC/RTD: 30 (30.0) V/I: 30.0
Integral time [heat-side] ★ ★ ▲	I1	0B5C : 0B9B	2908 : 2971	7	R/W	PID control or heat/cool PID control: 0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PD action) Position proportioning control: 1 to 3600 seconds or 0.1 to 1999.9 seconds [64]	240

Name	RKC Identifier	MECHATROLINK/Modbus register address		Digits	Attribute	Data range and Number of data	Factory set value
		HEX	DEC				
Derivative time [heat-side] ★★▲	D1	0B9C 0BDB	2972 3035	7	R/W	0 to 3600 seconds or 0.0 to 1999.9 seconds (0.0: PI action) [64]	60
Control response parameter ★★▲	CA	0BDC 0C1B	3036 3099	1	R/W	0: Slow 1: Medium 2: Fast When the P or PD action is selected, this setting becomes invalid. [64]	PID control, Position proportioning control: 0 Heat/cool PID control: 2
Proportional band [cool-side] ★★▲	P2	0C1C 0C5B	3100 3163	7	R/W	TC/RTD inputs: 1 (0.1) to Input span (Unit: °C [°F]) Voltage (V)/current (I) inputs: 0.1 to 1000.0 % of input span [64]	TC/RTD: 30 (30.0) V/I: 30.0
Integral time [cool-side] ★★▲	I2	0C5C 0C9B	3164 3227	7	R/W	0 to 3600 seconds or 0.0 to 1999.9 seconds (0.0: PD action) [64]	240
Derivative time [cool-side] ★★▲	D2	0C9C 0CDB	3228 3291	7	R/W	0 to 3600 seconds or 0.0 to 1999.9 seconds (0.0: PI action) [64]	60
Overlap/Deadband ★★▲	V1	0CDC 0D1B	3292 3355	7	R/W	TC/RTD inputs: -Input span to +Input span (Unit: °C [°F]) Voltage (V)/current (I) inputs: -100.0 to +100.0 % of input span [64]	0
Manual reset ★▲	MR	0D1C 0D5B	3356 3419	7	R/W	-100.0 to +100.0 % [64]	0.0
Setting change rate limiter (up) ★▲	HH	0D5C 0D9B	3420 3483	7	R/W	0 (0.0) to Input span/unit time 0 (0.0): Unused Unit time: 60 seconds (factory set value) [64]	0 (0.0)
Setting change rate limiter (down) ★▲	HL	0D9C 0DDB	3484 3547	7	R/W	0 (0.0) to Input span/unit time 0 (0.0): Unused Unit time: 60 seconds (factory set value) [64]	0 (0.0)
Area soak time ★▲	TM	0DDC 0E1B	3548 3611	7	R/W	0 minutes 00 seconds to 199 minutes 59 seconds: RKC communication: 0:00 to 199:59 (min:sec) MECHATROLINK/Modbus: 0 to 11999 seconds 0 hours 00 minutes to 99 hours 59 minutes: RKC communication: 0:00 to 99:59 (hrs:min) MECHATROLINK/Modbus: 0 to 5999 minutes [64]	RKC communication: 0:00 MECHATROLINK/Modbus: 0
Link area number ★▲	LP	0E1C 0E5B	3612 3675	7	R/W	0 to 8 (0: No link) [64]	0
Heater break alarm (HBA) set value ▲	A7	0E5C 0E9B	3676 3739	7	R/W	When CT is CTL-6-P-N: 0.0 to 30.0 A (0.0: Not used) When CT is CTL-12-S56-10L-N: 0.0 to 100.0 A (0.0: Not used) [64]	0.0
Heater break determination point ▲	NE	0E9C 0EDB	3740 3803	7	R/W	0.0 to 100.0 % of HBA set value (0.0: Heater break determination is invalid) [64]	30.0
Heater melting determination point ▲	NF	0EDC 0F1B	3804 3867	7	R/W	0.0 to 100.0 % of HBA set value (0.0: Heater melting determination is invalid) [64]	30.0
PV bias ▲	PB	0F1C 0F5B	3868 3931	7	R/W	-Input span to +Input span [64]	0
PV digital filter ▲	F1	0F5C 0F9B	3932 3995	7	R/W	0.0 to 100.0 seconds (0.0: Unused) [64]	0.0
PV ratio ▲	PR	0F9C 0FDB	3996 4059	7	R/W	0.500 to 1.500 [64]	1.000
PV low input cut-off ▲	DP	0FDC 101B	4060 4123	7	R/W	0.00 to 25.00 % of input span [64]	0.00
RS bias * ▲	RB	101C 105B	4124 4187	7	R/W	-Input span to +Input span [64]	0
RS digital filter * ▲	F2	105C 109B	4188 4251	7	R/W	0.0 to 100.0 seconds (0.0: Unused) [64]	0.0
RS ratio * ▲	RR	109C 10DB	4252 4315	7	R/W	0.001 to 9.999 [64]	1.000
Output distribution selection ▲	DV	10DC 111B	4316 4379	1	R/W	0: Control output 1: Distribution output [64]	0
Output distribution bias ▲	DW	111C 115B	4380 4443	7	R/W	-100.0 to +100.0 % [64]	0.0
Output distribution ratio ▲	DQ	115C 119B	4444 4507	7	R/W	-9.999 to +9.999 [64]	1.000
Proportional cycle time ▲	T0	119C 11DB	4508 4571	7	R/W	0.1 to 100.0 seconds M: Relay contact output T: Triac output V: Voltage pulse output D: Open collector output [64]	M output: 20.0 V, T, D output: 2.0
Minimum ON/OFF time of proportioning cycle ▲	VI	11DC 121B	4572 4635	7	R/W	0 to 1000 ms [64]	0

* Data on RS bias, RS ratio and RS digital filter is that in cascade control or ratio setting.

Name	RKC Identifier	MECHATROLINK/Modbus register address		Digits	Attribute	Data range and Number of data	Factory set value
		HEX	DEC				
Manual manipulated output value ★▲	ON	121C 125B	4636 4699	7	R/W	PID control: Output limiter (low) to Output limiter (high) Heat/cool PID control: -Cool-side output limiter (high) to -Heat-side output limiter (high) Position proportioning control (with FBR input): Output limiter (low) to Output limiter (high) Position proportioning control (without FBR input): 0: Close-side output OFF, Open-side output OFF 1: Close-side output ON, Open-side output OFF 2: Close-side output OFF, Open-side output ON [64]	0.0
Area soak time stop function ▲	RV	125C 129B	4700 4763	1	R/W	0: No function 3: Event 3 1: Event 1 4: Event 4 2: Event 2 [64]	0
EDS mode (for disturbance 1) ▲	NG	129C 12DB	4764 4827	1	R/W	0: No function 1: EDS function mode 2: Learning mode 3: Tuning mode [64]	0
EDS mode (for disturbance 2) ▲	NX	12DC 131B	4828 4891	1	R/W	EDS function: External disturbance suppression function [64]	0
EDS value 1 (for disturbance 1) ▲	NI	131C 135B	4892 4955	7	R/W	-100.0 to +100.0 % [64]	0.0
EDS value 1 (for disturbance 2) ▲	NJ	135C 139B	4956 5019	7	R/W		0.0
EDS value 2 (for disturbance 1) ▲	NK	139C 13DB	5020 5083	7	R/W		0.0
EDS value 2 (for disturbance 2) ▲	NM	13DC 141B	5084 5147	7	R/W		0.0
EDS transfer time (for disturbance 1) ▲	NN	141C 145B	5148 5211	7	R/W	0 to 3600 seconds or 0.0 to 1999.9 seconds [64]	0
EDS transfer time (for disturbance 2) ▲	NO	145C 149B	5212 5275	7	R/W		0
EDS action time (for disturbance 1) ▲	NQ	149C 14DB	5276 5339	7	R/W	1 to 3600 seconds [64]	600
EDS action time (for disturbance 2) ▲	NL	14DC 151B	5340 5403	7	R/W		600
EDS action wait time (for disturbance 1) ▲	NR	151C 155B	5404 5467	7	R/W	0.0 to 600.0 seconds [64]	0.0
EDS action wait time (for disturbance 2) ▲	NY	155C 159B	5468 5531	7	R/W		0.0
EDS value learning times ▲	NT	159C 15DB	5532 5595	7	R/W	0 to 10 times (0: No learning mode) [64]	1
EDS start signal ▲	NU	15DC 161B	5596 5659	1	R/W	0: EDS start signal OFF 1: EDS start signal ON (for disturbance 1) 2: EDS start signal ON (for disturbance 2) [64]	0
Operation mode ▲	EI	161C 165B	5660 5723	1	R/W	0: Unused 1: Monitor 2: Monitor + Event function 3: Control [64]	3
Startup tuning (ST) ▲	ST	165C 169B	5724 5787	1	R/W	0: ST unused 1: Execute once * 2: Execute always * Automatically reverts to 0 after Startup tuning (ST) ends. [64]	0
Automatic temperature rise learning ▲	Y8	169C 16DB	5788 5851	1	R/W	0: Unused 1: Learning * * Automatically reverts to 0 after automatic temperature rise learning ends. [64]	0
Communication switch (for logic) ▲	EF	16DC 16EB	5852 5867	7	R/W	* RKC communication Least significant digit to 4th digit: Communication switch 1 to 4 5th digit to Most significant digit: Unused Data 0: OFF 1: ON * MECHATROLINK/Modbus b0 to b3: Communication switch 1 to 4 b4 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 15] [16]	0
Unused		16EC 196B	5868 6507				

For communication data (Engineering setting), see the **COM-MY SRZ Communication Data List (IMR02E04-ED)**.

■ Communication data of Z-DIO module

Name	RKC Identifier	MECHATROLINK/Modbus register address		Digits	Attribute	Data range and Number of data	Factory set value
		HEX	DEC				
Digital input (DI) state 1 ▲	L1	3E6C 3E7B	15980 15995	7	RO	* RKC communication Least significant digit to 4th digit: D1 to D4 5th digit to Most significant digit: Unused Data 0: Contact open 1: Contact closed * MECHATROLINK/Modbus b0 to b7: D1 to D8 b8 to b15: Unused Data 0: Contact open 1: Contact closed [Decimal number: 0 to 255] [16]	—
Digital input (DI) state 2 ▲	L6	—	—	7	RO	Only for RKC communication Least significant digit to 4th digit: D5 to D8 5th digit to Most significant digit: Unused Data 0: Contact open 1: Contact closed [16]	—
Digital output (DO) state 1 ▲	Q2	3E7C 3E8B	15996 16011	7	RO	* RKC communication Least significant digit to 4th digit: DO1 to DO4 5th digit to Most significant digit: Unused Data 0: OFF 1: ON * MECHATROLINK/Modbus b0 to b7: DO1 to DO8 b8 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 255] [16]	—
Digital output (DO) state 2 ▲	Q3	—	—	7	RO	Only for RKC communication Least significant digit to 4th digit: DO5 to DO8 5th digit to Most significant digit: Unused Data 0: OFF 1: ON [16]	—
Unused		3E8C 3FDB	16012 16347				
DO manual output 1 ▲	Q4	3FDC 3EFB	16348 16353	7	R/W	* RKC communication Least significant digit to 4th digit: DO1 manual output to DO4 manual output 5th digit to Most significant digit: Unused Data 0: OFF 1: ON * MECHATROLINK/Modbus b0 to b7: DO1 manual output to DO8 manual output b8 to b15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 255] [16]	0
DO manual output 2 ▲	Q5	—	—	7	R/W	Only for RKC communication Least significant digit to 4th digit: DO5 manual output to DO8 manual output 5th digit to Most significant digit: Unused Data 0: OFF 1: ON [16]	0
DO output distribution selection ▲	DO	3FEC 406B	16364 16491	1	R/W	0: DO output 1: Distribution output [128]	0
DO output distribution bias ▲	O8	406C 40EB	16492 16619	7	R/W	-100.0 to +100.0 % [128]	0.0
DO output distribution ratio ▲	O9	40EC 416B	16620 16747	7	R/W	-9.999 to +9.999 [128]	1.000
DO proportioning cycle time ▲	V0	416C 41EB	16748 16875	7	R/W	0.1 to 100.0 seconds M: Relay contact output D: Open collector output [128]	M output: 20.0 D output: 2.0
DO minimum ON/OFF time of proportioning cycle ▲	VJ	41EC 426B	16876 17003	7	R/W	0 to 1000 ms [128]	0
Unused		426C 433B	17004 17211				

For communication data (Engineering setting), see the **COM-MY SRZ Communication Data List (IMR02E04-ED)**.

■ Communication data of Z-CT module

Name	RKC Identifier	MECHATROLINK/Modbus register address		Digits	Attribute	Data range and Number of data	Factory set value
		HEX	DEC				
Current transformer (CT) input value monitor ▲	M4	46BC 477B	18108 18299	7	RO	CTL-6-P-Z: 0.0 to 10.0 A CTL-6-P-N: 0.0 to 30.0 A CTL-12-S56-10L-N: 0.0 to 100.0 A [192]	—
Load factor conversion CT monitor ▲	M5	477C 483B	18300 18491	7	RO	0.0 to 100.0 A [192]	—
Heater break alarm (HBA) state monitor ▲	AF	483C 48FB	18684 18683	1	RO	0: Normal 1: Break 2: Melting [192]	—
Heater overcurrent alarm state monitor ▲	AG	48FC 49BB	18684 18875	1	RO	0: Normal 1: Heater overcurrent [192]	—
Automatic setting state monitor ▲	CJ	49BC 49CB	18876 18891	1	RO	0: Normal state 1: Automatic setting execution 2: Automatic setting failure [16]	—

Name	RKC Identifier	MECHATROLINK/Modbus register address		Digits	Attribute	Data range and Number of data	Factory set value
		HEX	DEC				
Unused		49CC 4FCB	18892 20427			Do not use this register address as it is used for the internal processing.	—
Heater break/Heater overcurrent alarm automatic setting selection ▲	BT	4FCF 508B	20428 20619	1	R/W	0: Automatic setting is disabled. (Alarm set value cannot be automatically set by the push button and communication.) 1: Automatic setting for heater break alarm is enabled. 2: Automatic setting for heater overcurrent alarm set value is enabled. 3: Automatic setting for heater break alarm (HBA) and heater overcurrent alarm set values are enabled. [192]	1
Automatic setting transfer ▲	BU	508C 514B	20620 20811	1	R/W	0: Normal state 1: Automatic setting execution 2: Automatic setting failure (RO) [192]	0
Heater break alarm (HBA) set value ▲	A8	514C 520B	20812 21003	7	R/W	0.0 to 100.0 A 0.0: Heater break alarm function (HBA) OFF (HBA function OFF: The current transformer (CT) input value monitoring is available.) [192]	0.0
Heater break alarm (HBA) selection ▲	BZ	520C 52CB	21004 21195	1	R/W	0: Heater break alarm (HBA) unused 1: Heater break alarm (HBA) 2: Heater break alarm (HBA) (With alarm interlock function) [192]	1
Heater overcurrent alarm set value ▲	A6	52CC 538B	21196 21387	7	R/W	0.0 to 105.0 A 0.0: Heater overcurrent alarm function OFF [192]	0.0
Heater overcurrent alarm selection ▲	BO	538C 544B	21388 21579	1	R/W	0: Heater overcurrent alarm unused 1: Heater overcurrent alarm 2: Heater overcurrent alarm (With alarm interlock function) [192]	1
Heater break alarm (HBA) interlock release ▲	CX	544C 550B	21580 21771	1	R/W	0: Normal state 1: Interlock release execution [192]	0
Heater overcurrent alarm interlock release ▲	CY	550C 55CB	21772 21963	1	R/W	0: Normal state 1: Interlock release execution [192]	0
Unused		55CC 5E0B	21964 24075				
Set lock ▲	LK	5E0C 5E1B	24076 24091	1	R/W	0: Unlock 1: Lock [192]	0
CT type ▲	BV	5E1C 5EDB	24092 24283	1	R/W *	0: CTL-6-P-N (0.0 to 30.0 A) 1: CTL-12-S56-10L-N (0.0 to 100.0 A) 2: CTL-6-P-Z (0.0 to 10.0 A) [192]	Depends on model code. When not specifying: 0
CT ratio ▲	XT	5EDC 5F9B	24284 24475	7	R/W *	0 to 9999 [192]	Note1
Number of heater break alarm (HBA) delay times ▲	DI	5F9C 605B	24476 24667	7	R/W *	0 to 255 times [192]	5
Automatic setting factor for heater break alarm (HBA) ▲	BW	605C 611B	24668 24859	7	R/W *	1 to 100 % [192]	75
Automatic setting factor for heater overcurrent alarm ▲	B9	611C 61DB	24860 25051	7	R/W *	100 to 1000 % [192]	200
Determination current value for automatic setting ▲	BP	61DC 629B	25052 25243	7	R/W *	0.0 to 100.0 A [192]	1.0
Automatic setting time ▲	BQ	629C 635B	25244 25435	7	R/W *	10 to 250 seconds [192]	60
Module address assignments for CT input ▲	BX	635C 641B	25436 25627	7	R/W *	0 to 99 [192]	0
Module channel assignments for CT input ▲	BY	641C 64DB	25628 25819	7	R/W *	1 to 99 [192]	1
Load factor conversion method ▲	IC	64DC 659B	25820 26011	1	R/W *	0: Mean conversion 1: Root mean squared value conversion [192]	0
CT Interval time ▲	VH	659C 65AB	26012 26027	7	R/W *	0 to 250 ms [16]	10
Unused		65AC 666B	26028 26219				

* When the set lock (Identifier: LK, Register address: 5E0C to 5E1B) is set to "0: Unlock," writing data is possible.

Note1 CTL-6-P-N, CTL-6-P-Z: 800 CTL-12-S56-10L-N: 1000

MECHATROLINK is the trademark of MECHATROLINK Members Association.
Modbus is a registered trademark of Schneider Electric.
Company names and product names used in this manual are the trademarks or registered trademarks of the respective companies.

RKC® RKC INSTRUMENT INC. - The first edition: MAY 2007 [IMQ00]
The second edition: NOV. 2007 [IMQ00]
HEADQUARTERS: 16-6, KUGAHARA 5-CHOME, OHTA-KU TOKYO 146-8515 JAPAN
PHONE: 03-3751-9799 (+81 3 3751 9799) E-mail: info@rkcinst.co.jp
FAX: 03-3751-8585 (+81 3 3751 8585) NOV. 2007