Digital I/O Module



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IMS01T03-E5

Thank you for purchasing this RKC product. In order to achieve maximum performance and ensure proper operation of your new instrument, carefully read all the instructions in this manual. Please place this manual in a convenient location for easy reference.

This manual describes the mounting, wiring and specifications only. For detailed handling procedures and various function settings, please refer to separate SRZ Instruction Manual

The above manuals can be downloaded from our website: URL: http://www.rkcinst.com/english/manual\_load.htm

## **■ Product Check**

Z-DIO Instruction Manual (IMS01T03-E5)	1
Joint connector cover (KSRZ-517A)	2
Power terminal cover (KSRZ-518A)	

## ■ Safety Precautions

# **WARNING**

- An external protection device must be installed if failure of this instrument could result in damage to the instrument, equipment or injury to personnel.
- All wiring must be completed before power is turned on to prevent electric shock, fire or damage to instrument and equipment.
- This instrument must be used in accordance with the specifications to prevent fire or damage to instrument and equipment.
- This instrument is not intended for use in locations subject to flammable or explosive gases
- Do not touch high-voltage connections such as power supply terminals, etc. to avoid electric shock.
- RKC is not responsible if this instrument is repaired, modified or disassembled by other than factory-approved personnel. Malfunction can occur and warranty is void under these conditions.

# CAUTION

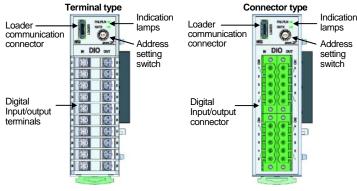
- This product is intended for use with industrial machines, test and measuring equipment. It is not designed for use with medical equipment and nuclear energy
- This is a Class A instrument. In a domestic environment, this instrument may cause radio interference, in which case the user may be required to take adequate measures
- This instrument is protected from electric shock by reinforced insulation. Provide reinforced insulation between the wire for the input signal and the wires for instrument power supply, source of power and loads.
- Be sure to provide an appropriate surge control circuit respectively for the following: If input/output or signal lines within the building are longer than 30 meters
- If input/output or signal lines leave the building, regardless the length.
- This instrument is designed for installation in an enclosed instrumentation panel. All high-voltage connections such as power supply terminals must be enclosed in the instrumentation panel to avoid electric shock by operating personnel.
- All precautions described in this manual should be taken to avoid damage to the instrument or equipment.
- All wiring must be in accordance with local codes and regulations.
- To prevent instrument damage or failure, protect the power line and the input/output lines from high currents with a protection device such as fuse, circuit breaker, etc.
- Prevent metal fragments or lead wire scraps from falling inside instrument case to avoid electric shock, fire or malfunction.
- Tighten each terminal screw to the specified torque found in the manual to avoid electric
- For proper operation of this instrument, provide adequate ventilation for heat dispensation. • Do not connect wires to unused terminals as this will interfere with proper operation of
- Turn off the power supply before cleaning the instrument.
- Do not use a volatile solvent such as paint thinner to clean the instrument. Deformation or discoloration will occur. Use a soft, dry cloth to remove stains from the instrument.
- To avoid damage to instrument display, do not rub with an abrasive material or push front panel with a hard object.

## NOTICE

- This manual assumes that the reader has a fundamental knowledge of the principles of electricity, process control, computer technology and communications.
- The figures, diagrams and numeric values used in this manual are only for purpose of • RKC is not responsible for any damage or injury that is caused as a result of using this
- instrument instrument failure or indirect damage • RKC is not responsible for any damage and/or injury resulting from the use of instruments
- made by imitating this instrument.
- Periodic maintenance is required for safe and proper operation of this instrument. Some components have a limited service life, or characteristics that change over time.
- Every effort has been made to ensure accuracy of all information contained herein. RKC makes no warranty expressed or implied, with respect to the accuracy of the information. The information in this manual is subject to change without prior notice.
- No portion of this document may be reprinted, modified, copied, transmitted, digitized, stored, processed or retrieved through any mechanical, electronic, optical or other means without prior written approval from RKC.

# 1. PARTS DESCRIPTION

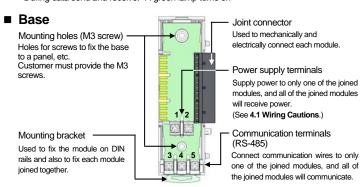
# **■ Module Mainframe**



[Indication lamps]

- FAIL/RUN When normal (RUN): Self-diagnostic error (FAIL):
- A green lamp is on A green lamp flashes Instrument abnormality (FAIL): A red lamp is on

During data send and receive: A green lamp turns on



# 2. COMMUNICATION SETTING

Set communication setting before mounting and wiring of the Z-DIO

# CAUTION

Do not separate the module mainframe from the base with the power turned on. If so, strument failure may result.

## 2.1 Module Address Setting

Set an address for the module using a small blade screwdriver.



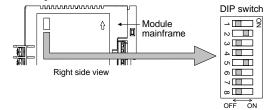
Setting range: 0 to F [0 to 15: Decimal] Factory set value: 0



- For RKC communication, the value obtained by adding "16" to the set address corresponds to the address used for the actual program.
  - For Modbus, the value obtained by adding "17" to the set address corresponds to the address used for the actual program.
  - . To avoid problems or malfunction, do not duplicate an address on the same communication line.

# 2.2 Protocol Selections and Communication Speed Setting —

Use the DIP switch on the right side of module to select communication speed, data bit configuration and protocol. The data changes become valid when the power is turned on again or when changed to RUN/STOP.



(The above figure is for the terminal type. However, the switch positions are the same for the connector type.)

1	2	Communication speed
OFF	OFF	4800 bps
ON	OFF	9600 bps
OFF	ON	19200 bps
ON	ON	38400 bps

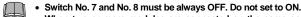
Factory set value: 19200 bps

3	4	5	Data bit configuration	
OFF	OFF	OFF	Data 7-bit, without parity, Stop 1-bit	*
ON	OFF	OFF	Don't set this one	
OFF	ON	OFF	Data 7-bit, Even parity, Stop 1-bit	*
ON	ON	OFF	Data 7-bit, Odd parity, Stop 1-bit	*
OFF	OFF	ON	Data 8-bit, without parity, Stop 1-bit	
ON	OFF	ON	Don't set this one	
OFF	ON	ON	Data 8-bit, Even parity, Stop 1-bit	
ON	ON	ON	Data 8-bit, Odd parity, Stop 1-bit	

Factory set value: Data 8-bit, without parity, Stop 1-bit When the Modbus communication protocol is selected, this setting becomes invalid.

6	Protocol
OFF	RKC communication
ON	Modbus

Factory set value: RKC communication



- When two or more modules are connected on the same communication line, the DIP switch settings of all modules must be the same. However, when a Z-DIO module is joined to a Z-TIO-C/D module used for "PLC communication," set the communication speed and data bit configuration to the same settings as the Z-TIO-C/D module and set the communication protocol to "RKC communication."
- Connect a termination resistor between the communication terminals (No.3 and 4) of the module at the end of the communication line from the host computer.

# 3. MOUNTING

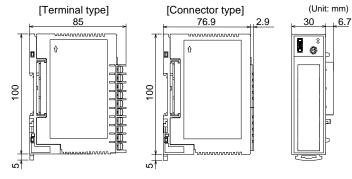


To prevent electric shock or instrument failure, always turn off the power before mounting or removing the instrument.

# 3.1 Mounting Cautions

- (1) This instrument is intended to be used under the following environmental conditions. (IEC61010-1) [OVERVOLTAGE CATEGORY II, POLLUTION DEGREE 2]
- (2) Use this instrument within the following environment conditions.
- Allowable ambient temperature:
- Allowable ambient humidity: 5 to 95 %RH
  (Absolute humidity: MAX. W. C 29.3 g/m³ dry air at 101.3 kPa)
- Installation environment conditions: Indoor use
  - Altitude up to 2000 m
- (3) Avoid the following conditions when selecting the mounting location: Rapid changes in ambient temperature which may cause condensation.
- Corrosive or inflammable gases.
- Direct vibration or shock to the mainframe.
- Water, oil, chemicals, vapor or steam splashes.
- Excessive dust, salt or iron particles.
- Excessive induction noise, static electricity, magnetic fields or noise
- Direct air flow from an air conditioner.
- Exposure to direct sunlight
- Excessive heat accumulation.
- (4) Take the following points into consideration when mounting this instrument in the panel.
- Ensure at least 50 mm space on top and bottom of the instrument for maintenance and
- Do not mount this instrument directly above equipment that generates large amount of
- heat (heaters, transformers, semi-conductor functional devices, large-wattage resistors). • If the ambient temperature rises above 50 °C, cool this instrument with a forced air fan, cooler, or the like. However, do not allow cooled air to blow this instrument directly.
- In order to improve safety and the immunity to withstand noise, mount this instrument as far away as possible from high voltage equipment, power lines, and rotating machinery. High voltage equipment: Do not mount within the same panel.
  - Power lines: Separate at least 200 mm. Rotating machinery: Separate as far as possible
- (5) This instrument is Permanently connected to equipment, please take the following A switch or circuit-breaker shall be included in the building installation
- It shall be in close proximity to the equipment and within easy reach of the operator.
- It shall be marked as the disconnecting device for the equipment.

# 3.2 Dimensions



- When the module is mounted on the panel, allow a minimum of 50 mm at the top and bottom of the module to attach the module to the mainframe.
  - · Space for connectors and cable must be considered when installing.
- For instruction of module joining, mounting and removal, refer to the Z-TIO Instruction Manual (IMS01T01-ED).



Up to 16 Z-DIO modules can be connected. The maximum number of SRZ modules (including other function modules) on the same communication line is 31.



In case of PLC communication, Z-DIO module cannot be connected to a Z-COM

# 4. WIRING



**WARNING** 

To prevent electric shock or instrument failure, do not turn on the power until all the wiring is completed.

#### 4.1 Wiring Cautions

the most effective noise reduction.

- To avoid noise induction, keep input/output signal wires away from instrument power line, load lines and power lines of other electric equipment.
- If there is electrical noise in the vicinity of the instrument that could affect operation, use a
- Shorten the distance between the twisted power supply wire pitches to achieve the most effective noise reduction
- Always install the noise filter on a grounded panel. Minimize the wiring distance between the noise filter output and the instrument power supply terminals to achieve
- Do not connect fuses or switches to the noise filter output wiring as this will reduce the effectiveness of the noise filter
- About eight seconds are required as preparation time for contact output every time the instrument is turned on. Use a delay relay when the output line is used for an external interlock circuit.
- Power supply wiring must be twisted and have a low voltage drop.
- For an instrument with 24 V power supply, supply power from a SELV circuit.
- A suitable power supply should be considered in the end-use equipment. The power supply must be in compliance with a limited-energy circuits (maximum available current
- Supply the power to only one of the joined modules. When power is supplied to any one of the joined modules, all of the joined modules will receive power
- Select the power capacity which is appropriate for the total power consumption of all joined modules and the initial current surge when the power is turned on.
- Power consumption (at maximum load): 70 mA max. (at 24 V DC)

Rush current: 10 A or less

• For the connector type module, use the following our connector (plug) [sold separately]. Connector type: SRZP-01 (Front-screw type), SRZP-02 (Side-screw type) Screw size:

Recommended tightening torque: 0.43 to 0.5 N·m (4.3 to 5.0 kgf·cm)

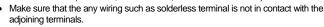
Used cable specifications:

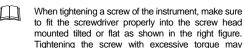
Lead wire type: Solid (AWG 28 [cross-section: 0.081 mm²] to 12 [cross-section: 3.309 mm²]) or Twisted wire (AWG 30 [cross-section: 0.051 mm²] to 12 [cross-section: 3.309 mm²]) Stripping length: 9 to 10 mm (SRZP-01), 7 to 8 mm (SRZP-02)

• For the terminal type module, use the specified solderless terminals. Only these specified solderless terminals can be used due to the insulation between the terminals.

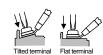
Screw Size:  $M3 \times 7$  (with  $5.8 \times 5.8$  square washer) Recommended tightening torque: 0.4 N·m (4 kgf·cm) Applicable wire: Solid/twisted wire of 0.25 to 1.65 mm<sup>2</sup> Specified solderless terminals:

Manufactured by J.S.T MFG CO., LTD. Circular terminal with isolation V1.25–MS3 5.6 mm (M3 screw, width 5.5 mm, hole diameter 3.2 mm)





damage the screw thread.



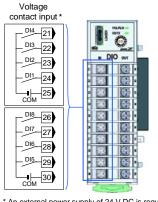
φ5.5 MAX

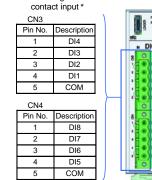
 $\phi$ 3.2 MIN

9.0 mm

# 4.2 Terminal Configuration

# ■ Digital input (DI1 to DI8)

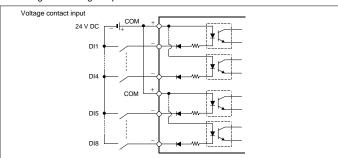




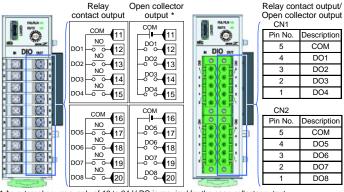
Voltage

\* An external power supply of 24 V DC is required for the voltage contact input.

#### Circuit configuration of digital input:

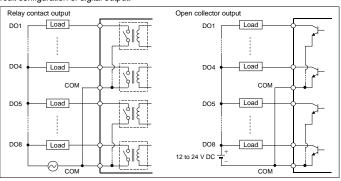


# ■ Digital output (DO1 to DO8)



<sup>\*</sup> An external power supply of 12 to 24 V DC is required for the open collector output.

#### Circuit configuration of digital output:



## ■ Base

Terminal configurations of the base are the same as the base of Z-TIO module. For the details, see the Z-TIO Instruction Manual (IMS01T01-ED).

# 5. SPECIFICATIONS

Digital input (DI)

None or 8 points (DI1 to DI8) Number of inputs:

Isolated input (each common block)

Number of commons: 2 points (DI 4 points/common)

Input method: Voltage contact input (Sink type)

Open state: 5 V or less, Close state: 17.5 V or more

Contact current: 3.0 mA or less Allowable applied voltage: 26.4 V DC or less

Capture judgment time:

Digital output (DO)

None or 8 points (DO1 to DO8) Number of outputs:

Number of commons: 2 points (DO 4 points/common)

Output method:

• Relay contact output:

Contact type:

Contact rating (Resistive load): 250 V AC 1 A, 30 V DC 1 A Electrical life:

300,000 times or more (Rated load)
20 million times or more (Switching: 300 times/min) Mechanical life:

Open collector output (Sink type):

100 mA Allowable load current: 30 V DC or less Load voltage:

Minimum load current: 0.5 mA 2 V or less (at maximum load current) ON voltage:

Leakage current at OFF: 0.1 mA or less

# Digital input (DI) function

The following Z-TIO functions can be assigned as digital input:

Memory area transfer, Operation mode, Interlock release, Auto/Manual transfer Remote/Local transfer, RUN/STOP transfer, Area soak time stop function, EDS start signal

#### Digital output (DO) function

The following signals can be assigned as digital output:

Z-TIO module: Event output 1 to 4 states. Heater break alarm (HBA) state. Temperature

rise completion, Burnout state Z-DIO module: DO manual output 1 to 8 states Z-CT module: Heater break alarm (HBA) state

# **Output distribution function**

Outputs the value calculated by another channel of Z-TIO or Z-DIO modules from the DO.

Communication

Based on RS-485 EIA standard

RKC communication (ANSI X3.28-1976 subcategory 2.5, B1) Protocol: Modbus-RTU

### **General specifications**

Power supply voltage: 24 V DC (Rating) 21.6 to 26.4 V DC [Including power supply voltage variation]

Power consumption (at maximum load): 70 mA max. (at 24 V DC)

Rush current: 10 A or less Allowable ambient temperature:  $-10 \text{ to } +50 \,^{\circ}\text{C}$ 

Allowable ambient humidity: 5 to 95 %RH

(Absolute humidity: MAX.W.C 29.3 g/m<sup>3</sup> dry air at 101.3 kPa)

Installation environment conditions: Indoor use

Altitude up to 2000 m Terminal type module: Approx. 150 g Connector type module: Approx. 130 g Weight:

Standard UL: UL61010-1 Safety standards:

CE marking:

• LVD:

EN61010-1

OVERVOLTAGE CATEGORYII, POLLUTION DEGREE 2,

• EMC: FN61326-1 RCM:

# 6. COMMUNICATION DATA MAP



Modbus register address (HEX: Hexadecimal DEC: Decimal)

cUL: CAN/CSA-C22.2 No.61010-1

The register address of the Z-DIO module.

Digits

The number of communication data digits in RKC communication.

RO: Read only data (Host computer ← The controller) R/W: Read and Write data (Host computer The controller)

 Data RKC communication

Modbus ASCII code data (Example: 7 digits) 16-bit data 

Most significant Least significant

Symbols used in MAP ♠: Data for each channel

♦: Data for each module



For details on the data and the Modbus data mapping function, see the SRZ Instruction Manual (IMS01T04-E□).

# ■ Communication data (RKC communication)

Name	Iden- tifier	Digits	Attri- bute	Data range	Factory set value
Model code ♦	ID	32	RO	Model character code	_
ROM version ◆	VR	8	RO	ROM version	_
Digital input (DI) state 1	L1	7	RO	Least significant digit to 4th digit: DI1 to DI4 5th digit to Most significant digit: Unused Data 0: Contact open 1: Contact closed	_
Digital input (DI) state 2	L6	7	RO	Least significant digit to 4th digit: DI5 to DI8 5th digit to Most significant digit: Unused Data 0: Contact open 1: Contact closed	
Digital output (DO) state 1	Q2	7	RO	Least significant digit to 4th digit: DO1 to DO4 5th digit to Most significant digit: Unused Data 0: OFF 1: ON	
Digital output (DO) state 2 ◆	Q3	7	RO	Least significant digit to 4th digit: DO5 to DO8 5th digit to Most significant digit: Unused Data 0: OFF 1: ON	I
Error code ◆	ER	7	RO	2: Data back-up error	
Integrated operating time monitor	υT	7	RO	0 to 19999 hours	
Backup memory state monitor	EM	1	RO	The content of the backup memory does not coincide with that of the RAM.     The content of the backup memory coincides with that of the RAM.	
RUN/STOP transfer	SR	1	R/W	0: STOP (Control stop) 1: RUN (Control start)	0
DO manual output 1	Q4	7	RW	Least significant digit to 4th digit: DO1 manual output to DO4 manual output 5th digit to Most significant digit: Unused Data 0: OFF 1: ON	0
DO manual output 2	Q5	7	R/W	Least significant digit to 4th digit: DO5 manual output to DO8 manual output 5th digit to Most significant digit: Unused Data 0: OFF 1: ON	0

Name	RKC Iden- tifier	Digits	Attri- bute	Data range	Factory set value
DO output distribution selection	DO	1	R/W	0: DO output 1: Distribution output	0
DO output distribution bias ♠	O8	7	R/W	-100.0 to +100.0 %	0.0
DO output distribution ratio ♠	O9	7	R/W	-9.999 to +9.999	1.000
DO proportioning cycle time A	V0	7	R/W	0.1 to 100.0 seconds M: Relay contact output, D: Open collector output	M: 20 D: 2
DO minimum ON/OFF time of proportioning cycle	۸٦	7	R/W	0 to 1000 ms	0

# ■ Communication data (Modbus)

	Modbus register address		Attri-	_	Factory	
Name	register	DEC	bute	Data range	set value	
Digital input (DI)	0000	0	RO	b0 to b7: DI1 to DI8		
state				b8 to b15: Unused		
<b>*</b>				Data		
				0: Contact open 1: Contact closed		
D: :: 1: (DO)	0004			[Decimal number: 0 to 255]		
Digital input (DO) state	0001	1	RO	b0 to b7: DO1 to DO8 b8 to b15: Unused	_	
siaie ♦				Data 0: OFF 1: ON		
•				[Decimal number: 0 to 255]		
Error code	0002	2	RO	b1: Data back-up error		
<b>*</b>		_		b0, b2 to b15: Unused		
				Data 0: OFF 1: ON		
				[Decimal number: 0 to 2]		
Integrated operating	0003	3	RO	0 to 19999 hours		
time monitor						
♦ Backup memory	0004	4	RO	0: The content of the backup memory		
state monitor	0004	4	NO	does not coincide with that of the RAM.	_	
•				1: The content of the backup memory		
				coincides with that of the RAM.		
Unused	0005	5		_		
	:					
	0045	69				
RUN/STOP transfer	0046	70	R/W	0: STOP (Control stop)	0	
DO manual output	0047	71	R/W	1: RUN (Control start) b0 to b7: DO1 manual output to	0	
♦	0041	<i>'</i> '	1000	DO8 manual output	O	
•				b8 to b15: Unused		
				Data 0: OFF 1: ON		
				[Decimal number: 0 to 255]		
DO output	0048	72	R/W	0: DO output	0	
distribution selection	:	: 79		1: Distribution output		
DO output	004F	79 80	R/W	-100.0 to +100.0 %	0.0	
distribution bias	0050	- 80	F/VV	-100.0 to +100.0 %	0.0	
distribution bias	0057	87				
DO output	0058	88	R/W	-9.999 to +9.999	1.000	
distribution ratio	:	i	,			
٨	005F	95				
DO proportioning	0060	96	R/W	0.1 to 100.0 seconds	M: 20	
cycle time				M: Relay contact output	D: 2	
<b>A</b>	0067	103		D: Open collector output		
DO minimum ON/OFF time of	0068	104 :	R/W	0 to 1000 ms	0	
proportioning cycle	: 006F	111				
proportioning cycle	0001	111				
Unused	0070	112	_	_	_	
	:	:				
	00A3	163				
For communication da	ata (Engine	ering settin	g), refer to	the SRZ Instruction Manual (IMS01T04-E□).		

# 7. MODEL CODE

**Z-DIO-A**  $\Box$  -  $\Box\Box$  -  $\Box$ (1) (2)(3)(4) (5) (6) (7) (8)

: Code 5, 6, 7and 8 are for quick start codes to specify software configurable settings. If not specified, these codes will not be printed on labels and all settings will be factory default.

(1) Wiring type

T: Terminal type (2) Digital input (DI)

C: Connector type

□: See DI Assignment Code Table.

N: None (3) Digital output (DO)

A: 8 points

M: Relay contact output (8 points) D: Open collector output (8 points)

(4) Quick start code (DI/DO assignments)

N: No quick start code (Configured as factory default)

1: Specify quick start code 1

None

(5) DI signal assignments (DI1 to DI8) [Quick start code 1] No code: No specify quick start code

(6) DO signal assignments (DO1 to DO4) [Quick start code 1]

(7) DO signal assignments (DO5 to DO8) [Quick start code 1] No code: No specify quick start code

☐: See DO Assignment Code Table.

(8) Communication [Quick start code 1] No code: No specify quick start code

1: RKC communication (ANSI X3.28)

# 2: Modbus

#### ●DI Assignment Code Table

Code	DI1	DI2	DI3	DI4	DI5	DI6	DI7	DI8
00				No assi	gnment			
01								AUTO/MAN
02								REMLOC
03							Interlock	EDS start signal 1
04							release	Soak stop
05								RUN/STOP
06								REMLOC
07							AUTO/MAN	EDS start signal 1
80					Operation	n mode 3		Soak stop
09								RUN/STOP
10								EDS start signal 1
11							REMILOC	Soak stop
12								RUN/STOP
13	Memo	ry area transfer (	1 to 8)1	Area set 2			EDS start signal 1	Soak stop
14								RUN/STOP
15							Soak stop	
16								EDS start signal 1
17							REMLOC	Soak stop
18					Interlock	AUTO/MAN		RUN/STOP
19					release		EDS start signal 1	Soak stop
20								RUN/STOP
21							Soak stop	
22							EDS start signal 1	Soak stop
23					AUTO/MAN	REMLOC		
24							Soak stop	RUN/STOP
25			•		REMLOC	EDS start signal 1		
26	Memory area	Area set 2	Interlock	RUN/STOP	AUTO/MAN	REMLOC	Operatio	n mode 3
07	transfer (1, 2)1	J	release	. 2		. 3		
27 28		ry area transfer (	1 to 8) '	Area set 2	Operatio	n mode 3		
28	Memory area	Area set 2	Interlock	DUNIOTOR	ALITO A AANI	DEM 00	EDS start signal 1	EDS start signal 2
29	transfer (1, 2)1	EDS start signal 2	release	RUN/STOP	AUTO/MAN	REMLOC	Occasio	n mode 3
						l	Operatio	n mode '
UNISTOP: RUNISTOP transfer (Contact closed: RUN) UTO/MAN: Auto/Manual transfer (Contact closed: Manual mode) EMM OC: Bemotel and transfer (Contact closed: Menual mode) after the closed contact is held for 250n								

Remote/Local transfer (Contact closed: Remote mode)

ase (Interlock release when rising edge is detected) (EDS start signal ON when rising edge is detected [for disturbance 1]) EDS start signal 2

(EDS start signal ON when rising edge is detected [for disturbance 2]) Soak stop (Contact closed: Soak stop)

iviemory area	transfer	(x: Contact c	pen -: Cor	itact closed)					
/		Memory area number							
	1	2	3	4	5	6	7	8	
DI1	×	-	×	-	×	-	×	_	
DI2	×	×	-	_	×	×	-	-	
Dio									

<sup>&</sup>lt;sup>2</sup> Area set becomes invalid prior to factory shipment.

<sup>3</sup> Operation mo	de transfer	(x:Contact of	oen -: Contact closed)				
	Operation mode						
	Unused	Monitor	Monitor + Event function	Control			
DI5 (DI7)	×	-	×	-			
DI6 (DI8)	×	×	-	-			

# ●DO Assignment Code Table

Code	DO1	DO2	DO3	DO4		
00	No assignment					
01	DO1 manual output	DO2 manual output	DO3 manual output	DO4 manual output		
02	Event 1 comprehensive	Event 2 comprehensive	Event 3 comprehensive	Event 4 comprehensive		
	output	output	output	output		
03	Event 1 (CH1)	Event 2 (CH1)	Event 3 (CH1)	Event 4 (CH1)		
04	Event 1 (CH2)	Event 2 (CH2)	Event 3 (CH2)	Event 4 (CH2)		
05	Event 1 (CH3)	Event 2 (CH3)	Event 3 (CH3)	Event 4 (CH3)		
06	Event 1 (CH4)	Event 2 (CH4)	Event 3 (CH4)	Event 4 (CH4)		
07	Event 1 (CH1)	Event 1 (CH2)	Event 1 (CH3)	Event 1 (CH4)		
08	Event 2 (CH1)	Event 2 (CH2)	Event 2 (CH3)	Event 2 (CH4)		
09	Event 3 (CH1)	Event 3 (CH2)	Event 3 (CH3)	Event 3 (CH4)		
10	Event 4 (CH1)	Event 4 (CH2)	Event 4 (CH3)	Event 4 (CH4)		
11	Z-TIO HBA (CH1)	Z-TIO HBA (CH2)	Z-TIO HBA (CH3)	Z-TIO HBA (CH4)		
12	Burnout status (CH1)	Burnout status (CH2)	Burnout status (CH3)	Burnout status (CH4)		
13	Temperature rise completion	HBA comprehensive output	Burnout state comprehensive output	DO4 manual output		

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เบบรา	DO8]					
Code	DO5	DO6	DO7	DO8		
00	No assignment					
01	DO5 manual output	DO6 manual output	DO7 manual output	DO8 manual output		
02	Event 1 comprehensive	Event 2 comprehensive	Event 3 comprehensive	Event 4 comprehensive		
	output	output	output	output		
03	Event 1 (CH1)	Event 2 (CH1)	Event 3 (CH1)	Event 4 (CH1)		
04	Event 1 (CH2)	Event 2 (CH2)	Event 3 (CH2)	Event 4 (CH2)		
05	Event 1 (CH3)	Event 2 (CH3)	Event 3 (CH3)	Event 4 (CH3)		
06	Event 1 (CH4)	Event 2 (CH4)	Event 3 (CH4)	Event 4 (CH4)		
07	Event 1 (CH1)	Event 1 (CH2)	Event 1 (CH3)	Event 1 (CH4)		
08	Event 2 (CH1)	Event 2 (CH2)	Event 2 (CH3)	Event 2 (CH4)		
09	Event 3 (CH1)	Event 3 (CH2)	Event 3 (CH3)	Event 3 (CH4)		
10	Event 4 (CH1)	Event 4 (CH2)	Event 4 (CH3)	Event 4 (CH4)		
11	Z-TIO HBA (CH1)	Z-TIO HBA (CH2)	Z-TIO HBA (CH3)	Z-TIO HBA (CH4)		
12	Burnout status (CH1)	Burnout status (CH2)	Burnout status (CH3)	Burnout status (CH4)		
13	Temperature rise	HBA comprehensive	Burnout state	DO8 manual output		
1	completion	output	comprehensive output			

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