



Module Type Controller SRZ

Communication
Extension Module

Z-COM

Host Communication

Quick Instruction
Manual

IMS01T09-E6

Thank you for purchasing this RKC product. In order to achieve maximum performance and ensure proper operation of your new instrument, carefully read all the instructions in this manual. Please place the manual in a convenient location for easy reference. This manual explains the communication settings using DIP switches and the communication data when performing Host communication while joining the Z-COM module to the Z-TIO, Z-DIO and Z-CT modules. For the installation, the detail handling procedures and various function settings, please read if necessary the following separate manuals.

- Z-COM Installation Manual (IMS01T05-E0): Enclosed with Z-COM
- Z-COM Host Communication Quick Instruction Manual (IMS01T09-E0): Enclosed with Z-COM
- Z-COM PLC Communication Quick Instruction Manual (IMS01T14-E0): Enclosed with Z-COM
- Z-COM PLC Communication Data List (IMS01T15-E0): Enclosed with Z-COM
- Z-COM Instruction Manual (IMS01T22-E0): Separate *
- Z-COM Host Communication Instruction Manual (IMS01T23-E0): Separate *
- Z-TIO INSTRUCTION MANUAL (IMS01T01-E0): Enclosed with Z-TIO
- Z-TIO Host Communication Quick Instruction Manual (IMS01T02-E0): Enclosed with Z-TIO
- SRZ Instruction Manual (IMS01T04-E0): Separate *
- Z-DIO INSTRUCTION MANUAL (IMS01T03-E0): Enclosed with Z-DIO
- Z-CT INSTRUCTION MANUAL (IMS01T16-E0): Enclosed with Z-CT
- Z-CT Instruction Manual [Detailed version] (IMS01T21-E0): Separate *

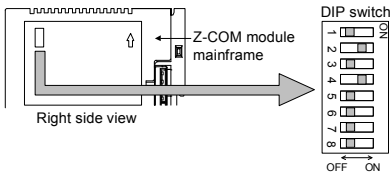
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The manual can be downloaded from the official RKC website:
https://www.rkcinst.com/english/manual_load.htm

1. COMMUNICATION SETTING OF Z-COM MODULE

Use the DIP switch on the right side of Z-COM module to select communication speed, data bit configuration and protocol.

The data change become valid the power of the Z-COM module is turned on again or when control is switched from STOP to RUN.



■ Contents of the DIP switch

• Communication 1 (COM. PORT1 and COM. PORT2) setting

Use switches No. 1, No. 2, and No. 3 to set the Communication speed, Communication protocol and Data bit configuration for Communication 1.

1	2	Communication speed
OFF	OFF	4800 bps
ON	OFF	9600 bps
OFF	ON	19200 bps (Factory set value)
ON	ON	38400 bps
3	Communication protocol and Data bit configuration ¹	
OFF	Host communication (RKC communication) (Factory set value ²)	
ON	Host communication (Modbus) Data 8-bit, without parity, Stop 1-bit	

• Communication 2 (COM. PORT3 and COM. PORT4) setting

Use switches No. 4, No. 5, No. 6, and No. 7 to set the Communication speed, Communication protocol and Data bit configuration for Communication 2.

4	Communication speed ³		
OFF	9600 bps		
ON	19200 bps (Factory set value)		
5	6	7	Communication protocol and Data bit configuration ¹
OFF	OFF	OFF	Host communication (RKC communication) Data 8-bit, without parity, Stop 1-bit (Factory set value ²)
ON	OFF	OFF	Host communication (Modbus) Data 8-bit, without parity, Stop 1-bit

• DIP switch setting validity/invalidity

Set switch No.8 to "ON" when performing communication by the communication settings set via Host communication or Loader communication. When set to "ON", the DIP switch settings are disabled.

8	DIP switch setting validity/invalidity	
OFF	Valid	(Factory set value)
ON	Invalid	(According to the settings in Host communication or Loader communication)

- ¹ The Data bit configuration other than the above can be changed by the Host communication or Loader communication.
² Factory set values when the Communication protocol is not specified at the factory.
³ When the Communication speed of communication 2 is changed to "4800 bps" or "38400 bps," it can be changed by the Host communication or Loader communication.

2. HOST COMMUNICATION DATA MAP

■ Symbols used in MAP

Attribute
R/O: Read only data (Host computer ← SRZ)
R/W: Read and Write data (Host computer ↔ SRZ)

Symbols
□: Data for each SRZ unit ▲: Data for each channel
◆: Data for each module ★: Parameters which can be used in multi-memory area function
★: Parameters only used for Heat/Cool Control or Position proportioning control, therefore data for CH2 and CH4 of Z-TIO module are unused.
[Read is possible (0), but the result of Write is disregarded.]

On a Z-TIO module (2-channel type), the communication data of CH3 and CH4 becomes invalid.

Data range and Number of data in the table:
[]: Number of data (This is the maximum number per communication data that can be handled by one SRZ unit.)

■ Host communication data of Z-COM module

Name	RKC Identifier	Modbus register address HEX DEC	Digits	Attribute	Data range and Number of data	Factory set value
Model code ◆ (Z-COM module)	ID	—	—	32 RO	Model code (character)	—
Model code ◆ (Function module *)	IE	—	—	32 RO	Model code (character)	—
ROM version ◆ (Z-COM module)	VR	—	—	8 RO	ROM version	—
ROM version ◆ (Function module *)	VQ	—	—	8 RO	ROM version	—
Integrated operating time monitor ◆ (Z-COM module)	UT	—	—	7 RO	0 to 19999 hours	—
Integrated operating time monitor ◆ (Function module *)	UV	—	—	7 RO	0 to 19999 hours	—
Error code □ (Z-COM module)	ER	0000	0	7 RO	• RKC communication 1: SRAM error? Adjustment data error ¹ 2: Data back-up error ¹ 4: A/D conversion error ¹ 32: Logic output data error 64: Stack overflow ² • Modbus Bit 0: SRAM error? Adjustment data error ¹ Bit 1: Data back-up error ¹ Bit 2: A/D conversion error ¹ Bit 3, Bit 4: Unused Bit 5: Logic output data error Bit 6: Stack overflow ² Bit 7 to Bit 15: Unused ¹ The error code of the Z-CT module is these three types. ² Only the Z-COM module Data 0: OFF 1: ON [Decimal number: 0 to 127] For the identifier ER, the error condition is shown by the OR of each module. When multiple errors occur, the error No. is the sum value. [Z-COM: 1] [Z-TIO, Z-DIO and Z-CT: 100]	—
Error code ◆ (Function module *)	EZ	0001 : 0064	1 : 100	7 RO	Bit 1: Data back-up error ¹ Bit 2: A/D conversion error ¹ Bit 3, Bit 4: Unused Bit 5: Logic output data error Bit 6: Stack overflow ² Bit 7 to Bit 15: Unused ¹ The error code of the Z-CT module is these three types. ² Only the Z-COM module Data 0: OFF 1: ON [Decimal number: 0 to 127] For the identifier ER, the error condition is shown by the OR of each module. When multiple errors occur, the error No. is the sum value. [Z-COM: 1] [Z-TIO, Z-DIO and Z-CT: 100]	—
Backup memory state monitor ◆ (Z-COM module)	EM	0065	101	1 RO	0: The content of the backup memory does not coincide with that of the RAM. 1: The content of the backup memory coincides with that of the RAM. [Z-COM: 1] [Z-TIO, Z-DIO and Z-CT: 100]	—
Backup memory state monitor ◆ (Function module *)	CZ	0066 : 00C9	102 : 201	1 RO	0: The content of the backup memory coincides with that of the RAM. 1: The content of the backup memory coincides with that of the RAM. [Z-COM: 1] [Z-TIO, Z-DIO and Z-CT: 100]	—
System communication state □	QM	00CA	202	1 RO	Bit data Bit 0: Data collection condition Bit 1 to Bit 15: Unused Data 0: Before data collection is completed 1: Data collection is completed [Decimal number: 0, 1]	—
SRZ normal communication flag □	QL	00CB	203	1 RO	0/1 transfer (For communication checking) "0" and "1" are repeated for each communication period.	—
PLC communication error code □	ES	00CC	204	7 RO	Bit data Bit 0: PLC register read/write error Bit 1: Slave communication timeout Bit 2: Unused Bit 3: Internal communication error Bit 4: Master communication timeout Bit 5 to Bit 15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 31]	—
Unit recognition flag □	QN	00CD	205	7 RO	Bit data Bit 0: SRZ unit 1 Bit 1: SRZ unit 2 Bit 2: SRZ unit 3 Bit 3: SRZ unit 4 Bit 4 to Bit 15: Unused Data 0: No unit exists 1: Unit exists [Decimal number: 0 to 15]	—
Unused	—	00CE : 0131	206 : 305	—	—	—
Monitor for the number of connected modules □	QK	0132	306	7 RO	0 to 31	—
RUN/STOP transfer □	SR	0133	307	1 R/W	0: STOP (Control stop) 1: RUN (Control start)	0
RUN/STOP transfer ◆	SW	0134 : 0197	308 : 407	1 R/W	0: STOP (Control stop) 1: RUN (Control start)	0
Control RUN/STOP holding setting ◆	X1	0198 : 01FB	408 : 507	1 R/W	0: Not holding (STOP start) 1: Holding (RUN/STOP hold)	1
The following items are enabled when the power is turned on again or when control is changed from STOP to RUN.						
Communication 1 protocol □	VK	8000	32768	1 R/W	0: RKC communication 1: Modbus	0
Communication 1 communication speed □	VL	8001	32769	1 R/W	0: 4800 bps 2: 19200 bps 1: 9600 bps 3: 38400 bps	2
Communication 1 data bit configuration □	VM	8002	32770	7 R/W	0 to 5 Refer to Table 1 Data bit configuration .	0
Communication 1 interval time □	VN	8003	32771	7 R/W	0 to 250 ms	10

* Function module: Z-TIO-A/B module, Z-DIO module or Z-CT module

Name	RKC Identifier	Modbus register address HEX DEC	Digits	Attribute	Data range and Number of data	Factory set value
Communication 2 protocol □	VP	8004	32772	1 R/W	0: RKC communication 1: Modbus 2: MITSUBISHI MELSEC series special protocol • A-compatible 1C frame (format 4) AnA/AnUCPU common command (ORQW) • QnA-compatible 3C frame (format 4) command (0401/1401) The available register is only a ZR register. (QnA or Q series) 3: OMRON SYSMAC series special protocol 4: MITSUBISHI MELSEC series special protocol A-compatible 1C frame (format 4) ACPU common command (WRWW) 5: YOKOGAWA FA-M3R special protocol	0
Communication 2 communication speed □	VU	8005	32773	1 R/W	0: 4800 bps 2: 19200 bps 1: 9600 bps 3: 38400 bps	2
Communication 2 data bit configuration □	VW	8006	32774	7 R/W	0 to 11 Refer to Table 1 Data bit configuration .	0
Communication 2 interval time □	VX	8007	32775	7 R/W	0 to 250 ms	10
Station number □	QV	8008	32776	7 R/W	0 to 31: MITSUBISHI MELSEC series, OMRON SYSMAC series 1 to 31: YOKOGAWA FA-M3R	Note 1
PC number (CPU No.) □	QW	8009	32777	7 R/W	0 to 255: MITSUBISHI MELSEC Series 1 to 4: YOKOGAWA FA-M3R (OMRON SYSMAC series: Unused)	Note 2
Register type □	QZ	800A	32778	7 R/W	MITSUBISHI MELSEC series 0: D register (Data register) 1: R register (File register) 2: W register (Link register) 3: ZR register Only enabled when the "QnA-compatible 3C frame (format 4)" is used. 4 to 29: Unused OMRON SYSMAC series 0: DM register (Data memory) 1 to 9: Unused 10 to 22: EM register (Extended data memory) [Specify the bank No.] Set the bank No.+10. 23 to 28: Unused 29: EM register (Extended data memory) [Specify the current bank] YOKOGAWA FA-M3R 0: D register (Data register) 1: R register (Shared register) 2: W register (Link register) 3: Unused 4: B register (File register) 5 to 29: Unused	0
Register start number □ (High-order 4-bit)	QS	800B	32779	7 R/W	0 to 15: QnA-compatible 3C frame	0
Register start number □ (Low-order 16-bit)	QX	800C	32780	7 R/W	0 to 9999: MITSUBISHI MELSEC series A-compatible 1C frame (format 4) ACPU common command (WRWW), OMRON SYSMAC series 0 to 65535: MITSUBISHI MELSEC series A-compatible 1C frame (format 4), AnA/AnUCPU common command (ORQW), QnA-compatible 3C frame (format 4) command (0401/1401) and YOKOGAWA FA-M3R	1000
System data address bias □	QQ	800D	32781	7 R/W	0 to 9999 OMRON SYSMAC series 0 to 65535 MITSUBISHI MELSEC series and YOKOGAWA FA-M3R	2100
COM module link recognition time □	QT	800E	32782	7 R/W	0 to 255 seconds	10
PLC scanning time □	VT	800F	32783	7 R/W	0 to 3000 ms	255
PLC communication start time □	R5	8010	32784	7 R/W	1 to 255 seconds	5
Method for setting the number of connected modules □	RY	8011	32785	7 R/W	0: No action. 1: Automatically set the maximum number of connected function modules only when power is turned on. 2: Execute automatic setting of the maximum number of connected function modules. ¹	1
Slave mapping method □	RK	8012	32786	7 R/W	0: Bias from the address setting switch [Register address + (Remainder of set value of address setting switch/4) × System data address bias] 1: Bias disabled	0
Number of connected modules ² (Z-TIO module) □	QY	8013	32787	7 R/W	0 to 16 Maximum number of Z-TIO modules connected to Z-COM.	—

¹ After automatic setting of the number of connected function modules, the value automatically reverts to 0.

² When 1 or 2 is set for the communication identifier RY (method of setting the number of connected modules), the maximum number of connected modules is set automatically. When 0 is set, the maximum number of connected modules is set manually.

Maximum number of connected modules:
Maximum address of function modules (address setting switch set value + 1)
Z-COM uses this set value to calculate the number of channels of communication data (RKC communication only).
Note 1: Factory set value: 0 (MITSUBISHI MELSEC series, OMRON SYSMAC series) 1 (YOKOGAWA FA-M3R)
Note 2: Factory set value: 255 (MITSUBISHI MELSEC series) 1 (YOKOGAWA FA-M3R)

Name	RKC Identifier	Modbus register address HEX DEC	Digits	Attribute	Data range and Number of data	Factory set value
Number of connected modules * (Z-DIO module) □	QU	8014	32788	7 R/W	0 to 16 Maximum number of Z-DIO modules connected to Z-COM.	—
Number of connected modules * (Z-CT module) □	QO	8015	32789	7 R/W	0 to 16 Maximum number of Z-CT modules connected to Z-COM.	—
Unused	—	8016 8019	32790 32793	—	—	—
Number of valid groups □	QA	801A	32794	7 RO	0 to 128	—
Control RUN/STOP holding setting □ (Each unit)	X2	802B	32795	1 R/W	0: Not holding (STOP start) 1: Holding (RUN/STOP hold)	1

* When 1 or 2 is set for the communication identifier RY (method of setting the number of connected modules), the maximum number of connected modules is set automatically. When 0 is set, the maximum number of connected modules is set manually.

Maximum number of connected modules:
Maximum address of function modules (address setting switch set value + 1)
Z-COM uses this set value to calculate the number of channels of communication data (RKC communication only).

Table 1: Data bit configuration

Set value	Data bit	Parity bit	Stop bit	Settable communication	Set value	Data bit	Parity bit	Stop bit	Settable communication
0	8	Without	1	Modbus	6	8	Without	2	PLC communication
1	8	Even	1	RKC communication	7	8	Even	2	
2	8	Odd	1	PLC communication	8	8	Odd	2	
3	7	Without	1	RKC communication	9	7	Without	2	
4	7	Even	1	PLC communication	10	7	Even	2	
5	7	Odd	1	PLC communication	11	7	Odd	2	

Data range: Modbus: 0 to 2 RKC communication: 0 to 5 PLC communication: 0 to 11

■ Host communication data of Z-TIO module

Name	RKC Identifier	Modbus register address HEX DEC	Digits	Attribute	Data range and Number of data	Factory set value
Measured value (PV) ▲	M1	01FC : 023B	508 : 571	7 RO	Input scale low to Input scale high	—
Comprehensive event state ▲	AJ	023C : 027B	572 : 635	7 RO	• RKC communication Least significant digit to 4th digit: Event 1 to Event 4 5th digit: Heater break alarm 6th digit: Temperature rise completion 7th digit: Burnout Data 0: OFF 1: ON • Modbus Bit 0 to Bit 3: Event 1 to Event 4 Bit 4: Heater break alarm Bit 5: Temperature rise completion Bit 6: Burnout Bit 7 to Bit 15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 127]	—
Operation mode state monitor ▲	L0	027C : 02BB	636 : 699	7 RO	• RKC communication Least significant digit: STOP 2nd digit: RUN 3rd digit: Manual mode 4th digit: Remote mode 5th digit to Most significant digit: Unused Data 0: OFF 1: ON [Decimal number: 0 to 15]	—
Unused	—	02BC : 02CB	700 : 715	—	—	—
Manipulated output value (MV) monitor [heat-side] ▲ ▲	O1	02CC : 030B	716 : 779	7 RO	PID control or Heat/Cool PID control -5.0 to +105.0 % Position proportioning control (FBR input): 0.0 to 100.0 %	—
Manipulated output value (MV) monitor [cool-side] ▲ ▲	O2	030C : 034B	780 : 843	7 RO	-5.0 to +105.0 %	—
Current transformer (CT) input value monitor ▲	M3	034C : 038B	844 : 907	7 RO	CTL-6-P-N: 0.0 to 30.0 A CTL-12-S56-10L-N: 0.0 to 100.0 A	—
Set value (SV) monitor ▲	MS	038C : 03CB	908 : 971	7 RO	Setting limiter low to Setting limiter high	—
Remote setting (RS) input value monitor ▲	S2	03CC : 040B	972 : 1035	7 RO	Setting limiter low to Setting limiter high	—
Burnout state monitor ▲	B1	040C : 044B	1036 : 1099	1 RO	0: OFF 1: ON	—
Event 1 state monitor ▲	AA	044C : 048B	1100 : 1163	1 RO	0: OFF 1: ON	—
Event 2 state monitor ▲	AB	048C : 04CB	1164 : 1227	1 RO	If the Event 3 type is Temperature rise completion, check the Temperature rise completion state in the Comprehensive event state. (The Event 3 state monitor does not turn ON.)	—
Event 3 state monitor ▲	AC	04CC : 050B	1228 : 1291	1 RO		—
Event 4 state monitor ▲	AD	050C : 054B	1292 : 1355	1 RO		—
Heater break alarm (HBA) state monitor ▲	AE	054C : 058B	1356 : 1419	1 RO	0: OFF 1: ON	—

Host communication data of Z-TIO module

Name	RKC Identifier	Modbus register address		Digits	Attribute	Data range and Number of data	Factory set value
		HEX	DEC				
Output state monitor ★	Q1	058C 059B	1420 1435	7	RO	★ RKC communication Least significant digit to 4th digit: OUT1 to OUT4 5th digit to Most significant digit: Unused Data 0: OFF 1: ON ★ Modbus Bit 0 to Bit 3: OUT1 to OUT4 Bit 4 to Bit 15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 15] [16]	—
Memory area soak time monitor ▲	TR	059C 05DB	1436 1499	7	RO	0 minutes 00 seconds to 199 minutes 59 seconds: RKC communication: 0:00 to 199:59 (min:sec) Modbus: 0 to 11999 seconds 0 hours 00 minutes to 99 hours 59 minutes: RKC communication: 0:00 to 99:59 (hrs:min) Modbus: 0 to 5999 minutes [64]	—
Unused	—	05DC 05EB	1500 1515	—	—	—	—
Holding peak value ambient temperature monitor ▲	Hp	05EC 062B	1516 1579	7	RO	−10.0 to +100.0 °C (14.0 to 212.0 °F) [64]	—
Unused	—	062C 063B	1580 1595	—	—	—	—
Logic output monitor 1 ★	ED	063C 064B	1596 1611	7	RO	★ RKC communication Least significant digit to 4th digit: Logic output 1 to 4 5th digit to Most significant digit: Unused Data 0: OFF 1: ON ★ Modbus Bit 0 to Bit 7: Logic output 1 to 8 Bit 8 to Bit 15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 255] [16]	—
Logic output monitor 2 ★	EE	—	—	7	RO	RKC communication Least significant digit to 4th digit: Logic output 5 to 8 5th digit to Most significant digit: Unused Data 0: OFF 1: ON [16]	—
Unused	—	064C 080B	1612 2059	—	—	—	—
PID/AT transfer ▲	G1	080C 084B	2060 2123	1	R/W	0: PID control 1: Autotuning (AT) When the Autotuning (AT) is finished, the control will automatically returns to 0: PID control. [64]	0
Auto/Manual transfer ▲	J1	084C 088B	2124 2187	1	R/W	0: Auto mode 1: Manual mode [64]	0
Remote/Local transfer ▲	C1	089C 08CB	2188 2251	1	R/W	0: Local mode 1: Remote mode [64]	0
Unused	—	08CC 08DB	2252 2267	—	—	—	—
Memory area transfer ▲	ZA	08DC 091B	2268 2331	7	R/W	1 to 8 [64]	1
Interlock release ▲	AR	091C 095B	2332 2395	1	R/W	0: Normal state 1: Interlock release execution [64]	0
Event 1 set value (EV1) ★ ▲	A1	095C 099B	2396 2459	7	R/W	Deviation action, Deviation action between channels, Temperature rise completion range*, [64]	50
Event 2 set value (EV2) ★ ▲	A2	099C 09DB	2460 2523	7	R/W	−Input span to +Input span * When temperature rise completion is selected at Event 3 action type.	50
Event 3 set value (EV3) ★ ▲	A3	09DC 0A1B	2524 2587	7	R/W	Process action, SV action: Input scale low to Input scale high	50
Event 4 set value (EV4) ★ ▲	A4	0A1C 0A5B	2588 2651	7	R/W	MV action: −5.0 to +105.0 % [Each 64]	50
Control loop break alarm (LBA) time ★ ▲	A5	0A5C 0A9B	2652 2715	7	R/W	0 to 7200 seconds (0: Unused) [64]	480
LBA deadband ★ ▲	N1	0A9C 0ADB	2716 2779	7	R/W	0 (0.0) to Input span [64]	0 (0.0)
Set value (SV) ★ ▲	S1	0ADC 0B1B	2780 2843	7	R/W	Setting limiter low to Setting limiter high [64]	TC/RTD: 0 V/I: 0.0
Proportional band [heat-side] ★ ★ ▲	P1	0B1C 0B5B	2844 2907	7	R/W	TC/RTD inputs: 0 (0.0) to Input span (Unit: °C [°F]) Voltage (V)/Current (I) inputs: 0.0 to 1000.0 % of input span 0 (0.0): ON/OFF action [64]	TC/RTD: 30 (30.0) V/I: 30.0
Integral time [heat-side] ★ ★ ▲	I1	0B5C 0B9B	2908 2971	7	R/W	PID control or Heat/Cool PID control: 0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PD action) Position proportioning control: 1 to 3600 seconds or 0.1 to 1999.9 seconds [64]	240
Derivative time [heat-side] ★ ★ ▲	D1	0B9C 0BDB	2972 3035	7	R/W	0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PI action) [64]	60
Control response parameter ★ ★ ▲	CA	0BDC 0C1B	3036 3099	1	R/W	0: Slow 1: Medium 2: Fast When the P or PD action is selected, this setting becomes invalid. [64]	PID control, Position proportioning control: 0 Heat/Cool PID control: 2
Proportional band [cool-side] ★ ★ ▲	P2	0C1C 0C5B	3100 3163	7	R/W	TC/RTD inputs: 1 (0.1) to Input span (Unit: °C [°F]) Voltage (V)/Current (I) inputs: 0.1 to 1000.0 % of input span [64]	TC/RTD: 30 (30.0) V/I: 30.0

Name	RKC Identifier	Modbus register address		Digits	Attribute	Data range and Number of data	Factory set value
		HEX	DEC				
Integral time [cool-side] ★ ★ ▲	I2	0C5C 0C9B	3164 3227	7	R/W	0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PD action) [64]	240
Derivative time [cool-side] ★ ★ ▲	D2	0C9C 0CDB	3228 3291	7	R/W	0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PI action) [64]	60
Overlap/Deadband ★ ★ ▲	V1	0CDC 0D1B	3292 3355	7	R/W	TC/RTD inputs: −Input span to +Input span (Unit: °C [°F]) Voltage (V)/Current (I) inputs: −100.0 to +100.0 % of input span [64]	0
Manual reset ★ ▲	MR	0D1C 0D5B	3356 3419	7	R/W	−100.0 to +100.0 % [64]	0.0
Setting change rate limiter (up) ★ ▲	HH	0D5C 0D9B	3420 3483	7	R/W	0 (0.0) to Input span/unit time 0 (0.0): Unused Unit time: 60 seconds (factory set value) [64]	0 (0.0)
Setting change rate limiter (down) ★ ▲	HL	0D9C 0DDB	3484 3547	7	R/W	0 (0.0) to Input span/unit time 0 (0.0): Unused Unit time: 60 seconds (factory set value) [64]	0 (0.0)
Area soak time ★ ▲	TM	0DDC 0E1B	3548 3611	7	R/W	0 minutes 00 seconds to 199 minutes 59 seconds: RKC communication: 0:00 to 199:59 (min:sec) Modbus: 0 to 11999 seconds 0 hours 00 minutes to 99 hours 59 minutes: RKC communication: 0:00 to 99:59 (hrs:min) Modbus: 0 to 5999 minutes [64]	RKC communication: 0:00 Modbus: 0
Link area number ★ ▲	LP	0E1C 0E5B	3612 3675	7	R/W	0 to 8 (0: No link) [64]	0
Heater break alarm (HBA) set value ▲	A7	0E5C 0E9B	3676 3739	7	R/W	When CT is CTL-6-P-N: 0.0 to 30.0 A (0.0: Not used) When CT is CTL-12-S56-10L-N: 0.0 to 100.0 A (0.0: Not used) [64]	0.0
Heater break determination point ▲	NE	0E9C 0EDB	3740 3803	7	R/W	0.0 to 100.0 % of HBA set value (0.0: Heater break determination is invalid) [64]	30.0
Heater melting determination point ▲	NF	0EDC 0F1B	3804 3867	7	R/W	0.0 to 100.0 % of HBA set value (0.0: Heater melting determination is invalid) [64]	30.0
PV bias ▲	PB	0F1C 0F5B	3868 3931	7	R/W	−Input span to +Input span [64]	0
PV digital filter ▲	F1	0F5C 0F9B	3932 3995	7	R/W	0.0 to 100.0 seconds (0.0: Unused) [64]	0.0
PV ratio ▲	PR	0F9C 0FDB	3996 4059	7	R/W	0.500 to 1.500 [64]	1.000
PV low input cut-off ▲	DP	0FDC 101B	4060 4123	7	R/W	0.00 to 25.00 % of input span [64]	0.00
RS bias * ▲	RB	101C 105B	4124 4187	7	R/W	−Input span to +Input span [64]	0
RS digital filter * ▲	F2	105C 109B	4188 4251	7	R/W	0.0 to 100.0 seconds (0.0: Unused) [64]	0.0
RS ratio * ▲	RR	109C 10DB	4252 4315	7	R/W	0.001 to 9.999 [64]	1.000
Output distribution selection ▲	DV	10DC 111B	4316 4379	1	R/W	0: Control output 1: Distribution output [64]	0
Output distribution bias ▲	DW	111C 115B	4380 4443	7	R/W	−100.0 to +100.0 % [64]	0.0
Output distribution ratio ▲	DQ	115C 119B	4444 4507	7	R/W	−9.999 to +9.999 [64]	1.000
Proportional cycle time ▲	T0	119C 11DB	4508 4571	7	R/W	0.1 to 100.0 seconds M: Relay contact output T: Triac output V: Voltage pulse output D: Open collector output [64]	M output: 20.0 V, T, D output: 2.0
Minimum ON/OFF time of proportioning cycle ▲	VI	11DC 121B	4572 4635	7	R/W	0 to 1000 ms [64]	0
Manual manipulated output value ★ ▲	ON	121C 125B	4636 4699	7	R/W	PID control: Output limiter low to Output limiter high Heat/Cool PID control: −Cool-side output limiter (high) to +Heat-side output limiter (high) Position proportioning control (with FBR input): Output limiter low to Output limiter high Position proportioning control (without FBR input): 0: Close-side output OFF, Open-side output OFF 1: Close-side output ON, Open-side output OFF 2: Close-side output OFF, Open-side output ON [64]	0.0
Area soak time stop function ▲	RV	125C 129B	4700 4763	1	R/W	0: No function 1: Event 1 2: Event 2 [64]	0
EDS mode (for disturbance 1) ▲	NG	129C 12DB	4764 4827	1	R/W	0: No function 1: EDS function mode 2: Learning mode 3: Tuning mode	0
EDS mode (for disturbance 2) ▲	NX	12DC 131B	4828 4891	1	R/W	EDS function: External disturbance suppression function [Each 64]	0

* Data on RS bias, RS ratio and RS digital filter is that in cascade control or ratio setting.

Name	RKC Identifier	Modbus register address		Digits	Attribute	Data range and Number of data	Factory set value
		HEX	DEC				
EDS value 1 (for disturbance 1) ▲	NI	131C 135B	4892 4955	7	R/W	−100.0 to +100.0 %	0.0
EDS value 1 (for disturbance 2) ▲	NJ	135C 139B	4956 5019	7	R/W	0.0	0.0
EDS value 2 (for disturbance 1) ▲	NK	139C 13DB	5020 5083	7	R/W	0.0	0.0
EDS value 2 (for disturbance 2) ▲	NM	13DC 141B	5084 5147	7	R/W	0.0 [Each 64]	0.0
EDS transfer time (for disturbance 1) ▲	NN	141C 145B	5148 5211	7	R/W	0 to 3600 seconds or 0.0 to 1999.9 seconds	0
EDS transfer time (for disturbance 2) ▲	NO	145C 149B	5212 5275	7	R/W	0.0 [Each 64]	0
EDS action time (for disturbance 1) ▲	NQ	149C 14DB	5276 5339	7	R/W	1 to 3600 seconds	600
EDS action time (for disturbance 2) ▲	NL	14DC 151B	5340 5403	7	R/W	0.0 [Each 64]	600
EDS action wait time ▲ (for disturbance 1)	NR	151C 155B	5404 5467	7	R/W	0.0 to 600.0 seconds	0.0
EDS action wait time ▲ (for disturbance 2)	NY	155C 159B	5468 5531	7	R/W	0.0 [Each 64]	0.0
EDS value learning times ▲	NT	159C 16DB	5532 5595	7	R/W	0 to 10 times (0: No learning mode) [64]	1
EDS start signal ▲	NU	16DC 161B	5596 5659	1	R/W	0: EDS start signal OFF 1: EDS start signal ON (for disturbance 1) 2: EDS start signal ON (for disturbance 2) [64]	0
Operation mode ▲	EI	161C 165B	5660 5723	1	R/W	0: Unused 1: Monitor 2: Monitor + Event function 3: Control [64]	3
Startup tuning (ST) ▲	ST	165C 169B	5724 5787	1	R/W	0: ST unused 1: Execute once (Returns to "0" after the tuning is finished.) 2: Execute always [64]	0
Automatic temperature rise learning ▲	Y8	169C 16DB	5788 5851	1	R/W	0: Unused 1: Learning (Returns to "0" after the tuning is finished.) [64]	0
Communication switch (for logic) ▲	EF	16DC 16EB	5852 5867	7	R/W	★ RKC communication Least significant digit to 4th digit: Communication switch 1 to 4 5th digit to Most significant digit: Unused Data 0: OFF 1: ON ★ Modbus Bit 0 to Bit 3: Communication switch 1 to 4 Bit 4 to Bit 15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 15] [16]	0
Unused	—	16EC 196B	5868 6507	—	—	—	—
For communication data (Engineering setting), refer to the Z-COM Host Communication Instruction Manual (IMS01T23-ED).							

Host communication data of Z-DIO module

Name	RKC Identifier	Modbus register address		Digits	Attribute	Data range and Number of data	Factory set value
		HEX	DEC				
Digital input (DI) state 1 ★	L1	3E6C 3E7B	15980 15995	7	RO	★ RKC communication Least significant digit to 4th digit: DI1 to DI4 5th digit to Most significant digit: Unused Data 0: Contact open 1: Contact closed	—
Digital input (DI) state 2 ★	L6	—	—	7	RO	RKC communication Least significant digit to 4th digit: DI5 to DI8 5th digit to Most significant digit: Unused Data 0: Contact open 1: Contact closed [16]	—
Digital output (DO) state 1 ★	Q2	3E7C 3E8B	15996 16011	7	RO	★ RKC communication Least significant digit to 4th digit: DO1 to DO4 5th digit to Most significant digit: Unused Data 0: OFF 1: ON ★ Modbus Bit 0 to Bit 7: DO1 to DO8 Bit 8 to Bit 15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 255] [16]	—
Digital output (DO) state 2 ★	Q3	—	—	7	RO	RKC communication Least significant digit to 4th digit: DO5 to DO8 5th digit to Most significant digit: Unused Data 0: OFF 1: ON [16]	—
Unused	—	3E8C 3FDB	16012 16347	—	—	—	—

Name	RKC Identifier	Modbus register address		Digits	Attribute	Data range and Number of data	Factory set value
		HEX	DEC				
DO manual output 1 ★	Q4	3FDC 3EFB	16348 16353	7	R/W	★ RKC communication Least significant digit to 4th digit: DO1 manual output to DO4 manual output 5th digit to Most significant digit: Unused Data 0: OFF 1: ON ★ Modbus Bit 0 to Bit 7: DO1 manual output to DO8 manual output Bit 8 to Bit 15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 255] [16]	0
DO manual output 2 ★	Q5	—	—	7	R/W	RKC communication Least significant digit to 4th digit: DO5 manual output to DO8 manual output 5th digit to Most significant digit: Unused Data 0: OFF 1: ON [16]	0
DO output distribution selection ▲	DO	3FEC 406B	16364 16491	1	R/W	0: DO output 1: Distribution output [128]	0
DO output distribution bias ▲	O8	406C 40EB	16492 16619	7	R/W	−100.0 to +100.0 % [128]	0.0
DO output distribution ratio ▲	O9	40EC 416B	16620 16747	7	R/W	−9.999 to +9.999 [128]	1.000
DO proportioning cycle time ▲	V0	416C 41EB	16748 16875	7	R/W	0.1 to 100.0 seconds M: Relay contact output D: Open collector output [128]	M: 20 D: 2
DO minimum ON/OFF time of proportioning cycle ▲	VJ	41EC 426B	16876 17003	7	R/W	0 to 1000 ms [128]	0
Unused	—	426C 433B	17004 17211	—	—	—	—
For communication data (Engineering setting), refer to the Z-COM Host Communication Instruction Manual (IMS01T23-ED).							

Host communication data of Z-CT module

For communication data of Z-CT module, refer to the Z-COM Host Communication Instruction Manual (IMS01T23-ED).

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RKC RKC INSTRUMENT INC.

Website:
<https://www.rkcinst.com/>

HEADQUARTERS: 16-6, KUGAHARA 5-CHOME, OHTA-KU TOKYO 146-8515 JAPAN
 PHONE: 03-3751-9799 (+81 3 3751 9799)
 E-mail: info@rkcinst.co.jp



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