Quick Operation Manual

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IMR01N16-E2

The HA430/HA930 Series controllers are a digital controller with a built-in amplifier for the strain gauge type resin pressure sensor. Pressure control is performed by directly connecting our pressure sensor (without amplifier) * to the Input 1 side. In addition, pressure or temperature control is enabled only by using this controller with either temperature (TC/RTD) or voltage/current input selected on the Input 2 side.

This manual describes procedures from initial settings (zero/full scale adjustment, PI constant setting, etc.) necessary for performing pressure control using the Input 1 side to operation of this controller.

For details of setting parameters other than those in the following and of conducting wiring, refer to the HA430/HA930 Instruction Manual (IMR01N11-E^{III}), or the HA430/HA930 Operation Manual (IMR01N12-E^{III}).

* CZ-100P, CZ-200P, CZ-GP100, or the other strain gauge type sensors

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the other strain gauge type sensors...... 23

BEFORE OPERATE

< Key Operation >

Scrolling through parameters:

• Press to scroll through parameters in the same mode/area. To go back to the first parameter, keep pressing SET keys until it is displayed again.

Changing set value (SV):

- The high-lighted digit indicates which digit can be set. Press Shift key to go to a different digit. Every time the shift key is pressed, the high-lighted digit moves.
- The set value can be selected by pressing the UP or DOWN key.

Registering set value (SV):

- The changed content cannot be registered only by the operation of the UP and DOWN keys.
- To store a new value for the parameter, always press the SET key. The display changes to the next parameter and the new value will be stored.
- After a new value has been displayed by using the UP and DOWN keys, the SET key must be pressed within one minute, or the new value is not stored and the display will return to the PV1/SV1 monitor screen.

< Engineering Mode >

In Engineering mode, it is possible to select operating conditions such as the input/output and control function specific to the customer. Initial setting parameters are included in this Engineering mode. The parameter setting is enabled with the RUN mode suspended (STOP). For parameters that are not necessary to be changed, use the same setting values as the factory set values. If they are changed unnecessarily, it may result in malfunction or failure of the instrument.

PROCEDURES FROM INITIAL SETTING TO OPERATION

Conduct the procedures from initial setting to operation according to the procedure described below.

1. Setting the Input Function (Engineering Mode F21)

Step 1: Turn on the power to this instrument



SV setting & Monitor mode (PV1/SV1 monitor screen)



Turn on the power to this controller after being mounted on equipment and then wired. This controller displays the input type symbol and input range just after the power is turned on, and then the PV1/SV1 monitor screen.

Ш A power supply switch is not furnished with this controller. In the Manual mode, operation is started as soon as the power is turned on.

[Factory set value: RUN (Control action start)]

Step 2: Change from RUN mode to STOP mode



Press the RUN/STOP key (R/S) at the PV1/SV1 monitor screen (SV setting & Monitor mode).

(RUN/STOP transfer screen) After the RUN/STOP transfer screen in operation mode (STOP state) is displayed, the display returns to the PV1/SV1 monitor screen. The STOP character is displayed on the measured value display unit. The operation mode changes to the STOP state (Control action stop). Ш The output or function when changed to STOP from RUN is in the same state as that when the power is turned off (excluding the display function).

SV setting & Monitor mode (PV1/SV1 monitor screen)

Automatically

(SET)



Next, go to the "Step 3-1" on page 3.

Character is indicated the STOP state (Control action stop).



Power ON RUN → STOP Input Function Setting T MV Scaling Zero Point Adjustment Full Scale Point Adjustment CZ-GP100, the other strain gauge type sensors PI constants Setting Set Value (SV) Setting Operation

Continued from the previous page.

When using CZ-100P or CZ-200P

Gain setting screen

А



Shunt resistance output value setting screen

С

Use to set the gain of the pressure sensor input. Set the rated output value (mV/V) engraved on the rated nameplate attached to the pressure sensor housing.

Data range: 0.500 to 4.000 mV/V Factory set value: 1.500 mV/V



Select the linearizing type symbol engraved on the rated nameplate attached to the pressure sensor housing.

Data range: 0 (Unused), 1 to 20 (Used)

[Linearizing type selection table]

Set Value	Linearzing type symbol	Set Value	Linearzing type symbol	Set Value	Linearzing type symbol
0	No symbol	7	J	14	S
1	С	8	K	15	Т
2	D	9	L	16	U
3	Е	10	М	17	V
4	F	11	Р	18	W
5	G	12	Q	19	Х
6	Н	13	R	20	Y

Factory set value: 0



The symbol described at the end of the rated output value denotes the linearizing type. In the example at the left, "C" is the symbol of denoting the linearizing type.

Do not change the factory set value. This setting cannot be used for CZ-100P or CZ-200P.

P. 5 (To the Input 1_decimal point position selection screen)



P.6 (To the Input 1_Input scale high setting screen)

D



Use to set the value that is high limit of the input scale range. Set the range printed on the pressure sensor as it is.

the selected input range

Input scale low to Maximum value of

Minimum value of the selected input



Factory set value:



50.0

0.0

Use to set the value that is low limit of the input scale range. Set the range printed on the pressure sensor as it is.



Factory set value:



Input Error Determination function is activated when a measured value reaches the limit, and control output value selected by Action at input error will be output. Changing the Input scale high automatically changes the Input error determination point (high).

range to Input scale high



Input scale low – (5 % of input span) to Input scale high + (5 % of input span) Input scale high + (5 % of input span)



Input scale high + (5 % of input span)

The action at input error is in accordance with setting of the Input 1_action at input error (high) in F51 (1.AoVE).

Input Error Determination function is activated when a measured value reaches the limit, and control output value selected by Action at input error will be output. Changing the Input scale low automatically changes the Input error determination point (low).



The action at input error is in accordance with setting of the Input 1_action at input error (low) in F51 (1.AUnE).

P. 7 (To the Input 1_burnout direction selection screen)



Use to select Burnout Direction in input break. When input break is detected by the controller, the measured value go either Upscale or Downscale according to the Burnout Direction setting.

Data range:	0 (Upscale)
	1 (Downscale)
Factory set value:	0 (Upscale)

Do not change the factory set value. This setting cannot be used.

Use to select the presence or absence of the peak hold/bottom hold function for a measured value (PV).

Data range:	0 (Unused)
	1 (Used)
Factory set value:	0 (Unused)

The peak hold/bottom hold value can check on the PV1 peak hold value monitor screen and the PV1 bottom hold value monitor screen (SV setting & Monitor mode) when set to "1: Used" on the Input 1_PV1 hold function selection screen.

Use to select the power supply frequency of the controller suited to the application.

Data range:	0 (50 Hz)
	1 (60 Hz)
Factory set value:	0 (50 Hz)

The screen returns to the F21 group number screen. Next, set the MV scaling function.

Go to the "2. Setting the MV Scaling Function (Engineering Mode F10)" on page 8.

2. Setting the MV Scaling Function (Engineering Mode F10)

The MV scaling function is used to make scaling of manipulated output value 1 (MV1) from 0 to 100 % between the high and low MV scaling limits as the motor RPM. Conduct the setting in accordance with the following procedure.





3. Zero Point Adjustment (Setup Setting Mode)

To adjust the zero point of the measured value (PV1) of Input 1, it is necessary to change to the Setup Setting mode. Conduct the adjustment according to the procedure described below.

Prior to adjust the zero point, check each of the following:

- No load is applied to the pressure sensor.
- The equipment that is mounted the pressure sensor is at the operating temperature.
- The operation mode is always the STOP mode.



Continued from the previous page.



PV ratio is a multiplier to be applied to the measured value (PV). The PV bias is used to compensate the individual variations of the sensors or correct the difference between the measured value (PV) of other instruments.

Data range:0.500 to 1.500Factory set value:1.000

•CZ-100P, CZ-200P (Explosionproof specification type):

Set the barrier correction factor of the safety barrier RZB-001 (RKC product) to the Input 1_PV ratio (1. Pr). Use to correct a pressure indication error caused by the dispersion of RZB-001 internal resistance value. The barrier correction factor is entered on the nameplate of the RZB-001.

- •CZ-100P, CZ-200P (Non-explosionproof specification type) : As the Input 1_PV ratio, use a factory set value "1.000."
- •CZ-GP100 (without amplifier) or the other strain gauge type sensors :

The result obtained by Auto calibration (P. 13) is reflected to the Input 1_PV ratio (1. Pr). Manual full scale adjustment can be performed by changing this PV ratio value.

Proportional Cycle Time is to set control cycle time for time based control output such as voltage pulse for SSR, triac and relay output.

Data range: 0.1 to 100.0 seconds Factory set value:

Relay contact output:20.0 secondsVoltage pulse output and triac output:2.0 seconds

When the following screen (Input 2_PV bias, etc.) is displayed, press the SET key successively until the Auto-zero screen is displayed.



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(SET)

Step 3: Adjust the zero point of the measured value (PV1) of Input 1



4. Full Scale Point Adjustment (Setup Setting Mode) *

* CZ-GP100 (without amplifier), the other strain gauge type sensors

To adjust the full scale point of the measured value (PV1) of Input 1, conduct the adjustment according to the procedure described below.

Prior to adjust the full scale point, check each of the following:

- No load is applied to the pressure sensor.
- The equipment that is mounted the pressure sensor is at the operating temperature.
- The operation mode is always the STOP mode.



5. Setting the PI Constants (Parameter Setting Mode)

To set the PI constants of PID control of Input 1, it is necessary to change to the Parameter Setting mode. Conduct the setting according to the procedure described below.



Step 1: Change from Setup Setting Mode to Parameter Setting Mode



6. Setting the Set Value (SV) (SV Setting & Monitor Mode)

To set the set value (SV1) of Input 1, it is necessary to change to the SV setting & Monitor mode. Conduct the setting according to the procedure described below.



7. Operation

For the Operation start/stop, conduct the operation according to the procedure described below.



Step 2: Set the manipulated output value (MV1) of Input 1 (Motor RPM) in the Manual mode



The motor RPM is displayed on the Set value (SV) display. Gradually increase the motor RPM by the UP key so that the Measured value 1 (PV1) will approach the preset pressure.

When no MV scaling function is used, the manual output value (%) is displayed on the Set value (SV) display.

Continued from the previous page.



Continued from the previous page.



PV. ARE/ (SED Press the RUN/STOP transfer key (R/S) at the PV1/SV1 monitor screen.

After the RUN/STOP transfer screen of the Operation mode (STOP state) is displayed, the display returns to the PV1/SV1 monitor screen. The STOP character that is indicative of the STOP state is displayed on the Measured value (PV1/PV2) display. Thus, the Operation mode has been changed to the control STOP state.

If the controller is transferred to STOP mode from RUN mode, the controller status is the same as the Power-off. (However, with the exception of the display function.)



SELECTION OPERATION BY EXTERNAL CONTACT **INPUT (RUN/STOP, Auto/Manual)**

The RUN/STOP transfer and the Auto/Manual transfer can be transferred by using an external contact input (event input). For this purpose, it is necessary to select the set value which enables the transfer of RUN/STOP and Auto/Manual by setting the event input logic selection (dISL) of the Engineering mode, F23. The procedure for setting the event input logic selection (dISL) is described in the following.



Step 1: Change the Operation mode from RUN mode to STOP mode

Continued from the previous page.

The setting procedure of the event input logic selection:

Step 3: Select the type of external contact input (Event input).

Event input logic selection screen

Returns to the F23 group number screen

section in the function assignment table.3. Press the SET key to store the new set value.

1. Press the SET key at the F23 group number screen.

The Event input logic selection screen is displayed.

2. Press the UP key to select the desired set value from the shaded

0 to 15

(see the following table and the next page)

Factory set value: 1

Data range:

[Function Assignment Table]

Set		DI2			DI5
value	(Terminal No. 30-31)	(Terminal No. 30-32)	(Terminal No. 30-33)	(Terminal No. 30-34)	(Terminal No. 35-36)
0	Unused (No function assignment)			t)	
1		Memory area number selection (1 to 16)			Memory area set
2		Memory area number	er selection (1 to 16)		Memory area set
3	Memory area number selection (1 to 16) Memory ar			Memory area set	
4	Me	mory area number selection (1 t	to 8)	Memory area set	RUN/STOP transfer
5	Memory area number selection (1 t		to 8)	Memory area set	Remote/Local transfer
6	Me	mory area number selection (1 t	to 8)	Memory area set	Auto/Manual transfer
7	Memory area number selection (1 t		to 8)	Memory area set	Hold reset
8	Memory area number selection (1 t		to 8)	Memory area set	Interlock release
9	Memory area number selection (1 to 4)		Memory area set	RUN/STOP transfer	Auto/Manual transfer
10	Memory area number selection (1 to 4)		Memory area set	RUN/STOP transfer	Remote/Local transfer
11	Memory area number selection (1 to 4)		Memory area set	Remote/Local transfer	Auto/Manual transfer
12	Memory area number selection (1 to 4)		Memory area set	Hold reset	Interlock release
13	Auto/Manual transfer	RUN/STOP transfer	Remote/Local transfer	Hold reset	Interlock release
14	Auto/Manual transfer	Input 1_manual output down	Input 1_manual output up	Input 1_manual output 0 %	RUN/STOP transfer
		(motor RPM down) ¹	(motor RPM up) ²	reset (motor RPM reset) ³	
15	Auto/Manual transfer	Input 2_manual output down	Input 2_manual output up	Input 2_manual output 0 %	RUN/STOP transfer
		(motor RPM down) ¹	(motor RPM up) ²	reset (motor RPM reset) ³	

¹ Decreases manipulated output value (motor RPM) under Manual control with contacts closed.

² Increases manipulated output value (motor RPM) under Manual control with contacts closed.

³ The manipulated output value (motor RPM) is reset to 0 % based on the edge discrimination of "open" to "closed."

In addition, switched to "Manual Control" regardless of Auto/Manual transfer setting.

Relationship between RUN/STOP transfer and contact state:

Mode select from front key	Status of event input (DI)	Actual operation mode	STOP display
RUN	Contact closed	RUN	STOP is not displayed
(Control RUN)	Contact open		dSГР
STOP	Contact closed	STOP	ĽSſP
(Control STOP)	Contact open		SroP

Relationship between Auto/Manual transfer and contact state:

Mode select from front key	Status of event input (DI)	Actual operation mode	Display lamp	
Auto	Contact closed	Auto	MAN mode lamp ON	
Auto	Contact open			
Manual	Contact closed	Manual	Manual MAN mode lamp OF	MAN mode lamp OFF
Manual	Contact open			

Transfer timing of RUN/STOP and Auto/Manual:

The selection operation is taken when DI contact is closed from the open condition (Rising edge).

Contact closed '



* To make contact activation valid, it is necessary to maintain the same contact state (contact closed) for more than 200 ms.



APPENDIX

Connection to our CZ-100P, CZ-200P, CZ-GP100, or the other strain gauge type sensors



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