EtherCAT Communication Converted

COM-ME-3 [For FZ series/GZ series]

Installation Manual

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In order to achieve maximum performance and ensure proper operation of the instrument, carefully read all the instructions in this manual. Please place the manual in a convenient location for easy reference. This manual describes the mounting, wiring and specifications only.

For detailed handling procedures and various function settings, refer to separate COM-ME-3 [For FZ series/GZ series] Instruction Manual (IMR02E35-E□).

The manual can be downloaded from the official RKC website https://www.rkcinst.co.jp/english/download-center/

■ Product check

COM-ME-3 [For FZ series/GZ series] Installation Manual (IMR02E34-E1)1
Joint connector cover (KSRZ-517A)2
Power terminal cover (KSRZ-518A)1
ESI file *

The ESI file is a configuration tool (software to set the environment and create a program) to recognize the COM-ME on EtherCAT. The ESI file can be downloaded from RKC website

■ Safety precautions

/!\ WARNING

- To prevent injury to persons, damage to the instrument and the equipment, a suitable external protection device shall be required.
- All wiring must be completed before power is turned on to preven electric shock, fire or damage to the instrument and the equipment.
- This instrument must be used in accordance with the specifications to prevent fire or damage to the instrument and the equipment.
- This instrument is not intended for use in locations subject to flammable or explosive gases.
- Do not touch high-voltage connections such as power supply terminals, etc. to avoid electric shock.
- RKC is not responsible if this instrument is repaired, modified or disassembled by other than factory-approved personnel. Malfunction may occur and warranty is void under these conditions.

- This product is intended for use with industrial machines, test and measuring equipment (It is not designed for use with medical equipment and nuclear energy plant.)
- This is a Class A instrument. In a domestic environment, this instrument may cause radio interference, in which case the user may be required to take additional measures.
- Be sure to provide an appropriate surge control circuit respectively for the following
- If input/output or signal lines within the building are longer than 30 meters. If input/output or signal lines leave the building, regardless the length.
- This instrument is designed for installation in an enclosed instrumentation panel. All high-voltage connections such as power supply terminals must be enclosed in the instrumentation panel to avoid electric shock to operating personnel.

 • All precautions described in this manual should be taken to avoid damage to the instrument or
- If the equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.
- All wiring must be in accordance with local codes and regulations.
- To prevent instrument damage as a result of failure, protect the power line and the input/output lines from high currents with a suitable overcurrent protection device with adequate breaking capacity such as a fuse, circuit breaker, etc.
- A malfunction in this product may occasionally make control operations impossible or prevent alarm outputs, resulting in a possible hazard. Take appropriate measures in the end use to prevent hazards in the event of malfunction.
- Prevent metal fragments or lead wire scraps from falling inside instrument case to avoid • Tighten each terminal screw to the specified torque found in the manual to avoid electric
- shock, fire or malfunction. For proper operation of this instrument, provide adequate ventilation for heat dissipation. Do not connect wires to unused terminals as this will interfere with proper operation of the
- Turn off the power supply before cleaning the instrument.
- Do not use a volatile solvent such as paint thinner to clean the instrument. Deformation or discoloration may occur. Use a soft, dry cloth to remove stains from the instrument.
- Do not connect modular connectors to telephone line.

NOTICE

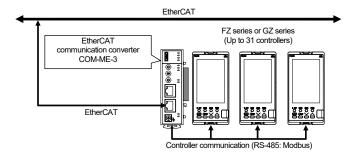
- This manual assumes that the reader has a fundamental knowledge of the principles of electricity, process control, computer technology and communications.
- The figures, diagrams and numeric values used in this manual are only for explanation purpose. • RKC is not responsible for any damage or injury that is caused as a result of using this instrument, instrument failure or indirect damage
- RKC is not responsible for any damage and/or injury resulting from the use of instruments made by imitating this instrument.
- Periodic maintenance is required for safe and proper operation of this instrument. Some
- components have a limited service life, or characteristics that change over time.

 Every effort has been made to ensure accuracy of all information contained herein. RKC makes no warranty, expressed or implied, with respect to the accuracy of the information. The information in this manual is subject to change without prior notice.
- No portion of this document may be reprinted, modified, copied, transmitted, digitized, stored, processed or retrieved through any mechanical, electronic, optical or other means without prior written approval from RKC
- Various symbols are used on the equipment, they have the following meaning
- 1 : Caution (This symbol is used where the instruction manual needs to be consulted for the safety of operator and equipment.)
 - This symbol on the left side of the product denotes caution for electric shock and damages to the equipment. Read the following items before using this product.

 - ■ Safety precautions "WARNING" 3. MOUNTING "WARNING" and 4. WIRING "WARNING

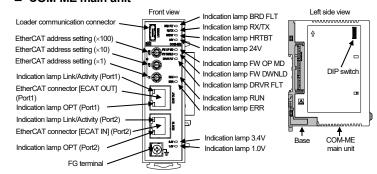
1. OUTLINE

The model COM-ME-3 [for FZ series/GZ series] (hereinafter called the COM-ME) is a communication converter for connecting the FZ series [FZ110/400/900] or GZ series [GZ400/900] controller (hereinafter called the controller) to EtherCAT.



2. PARTS DESCRIPTION

■ COM-ME main unit



Indication lamp

BRD FLT	[Red]	While in normal state:	Turns off
		Self-diagnostic error (Major fault):	Red lamp turns on
RX/TX	[Green]	During controller communication data send ar	nd receive: Green lamp turns on
HRTBT	[Green]	While software is properly running: WDT(watchdog timer)error:	Green lamp turns on Turns off
24V	[Green]	While 24V power is supplied:	Green lamp turns on
FW OP MD	[Green]	While OP is functioning: While Safe-OP is functioning:	Green lamp turns on Green lamp blinks
FW DWNLD	[Green]	When the firmware is successfully started: When the firmware fails to be started: When the firmware is re-written:	Green lamp turns on Turns off Turns off
DRVR FLT		This lamp is not used.	
RUN	[Green]	INIT or No power: OPERATIONAL: PRE-OPERATIONAL: SAFE-OPERATIONAL:	Turns off Green lamp turns on Green lamp blinks Green lamp single-flashes
ERR	[Red]	No error or No power: Configuration error: Local error: Communication refused by the Master: WDTO inside the Slave: Starting error:	Turns off Red lamp blinks Red lamp single-flashes * Red lamp double-flashes * Red lamp turns on Red lamp flashes fast
3.4V	[Green]	While 3.4V power is properly supplied:	Green lamp turns on
1.0V	[Green]	While 1.0V power is properly supplied:	Green lamp turns on
Link/Activity (P	ort1/Port2) [Green]	No link or No power: Link sensed, activity detected: Link sensed, no activity:	Turns off Green lamp flashes fast Green lamp turns on
OPT (Port1/Po	[Yellow]	Constantly off	

* Single-flashes: Repeats ON (200 ms)/OFF (1000 ms).

Double-flashes: Repeats ON (200 ms)/OFF (200 ms)/ON (200 ms)/OFF (1000 ms).

Communication po	ort (modular connector) and communication connector
Loader communication connector	Use to connecting the communication converter and personal computer when loader communication is performed.
EtherCAT connector (Port1) [ECAT OUT]	Designed to connect EtherCAT with the next slave instrument.
EtherCAT connector (Port2) [ECAT IN]	Designed to connect EtherCAT with the master instrument or the slave instrument located near the master instrument.

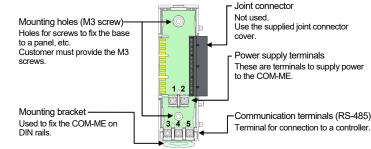
Switch

•	
EtherCAT address setting switch (ID selector) (×100, ×10, ×1)	Sets the fixed address of EtherCAT devices (hexadecimal). Supports Explicit Device Identification (Required ID) and Configured Station Alias. The set address is written into the register 0x0012 (Configured Station Alias) of the ESC (EtherCAT Slave Controller) at the start-up.
DIP switch	Sets communication speed corresponding to controller communication. Sets DIP switch setting validity/invalidity.

Terminal

G terminal	Terminal for grounding

■ Base



3. MOUNTING

∕!\ WARNING

To prevent electric shock or instrument failure, always turn off the power before mounting or removing the instrument.

3.1 Mounting Cautions

- (1) This instrument is intended to be used under the following environmental conditions. (IEC 61010-1) [POLLUTION DEGREE 2]
- (2) Use this instrument within the following environment conditions: -10 to +55 °C
- Allowable ambient temperature: Allowable ambient humidity:

5 to 95 %RH

- (Absolute humidity: MAX. W. C 29 g/m³ dry air at 101.3 kPa) Installation environment conditions: Indoor use, Altitude up to 2000
- (3) Avoid the following conditions when selecting the mounting location:
 Rapid changes in ambient temperature which may cause condensation
- Corrosive or inflammable gases.
- Direct vibration or shock to the mainframe
- Water, oil, chemicals, vapor or steam splashes.Excessive dust, salt or iron particles.
- Excessive induction noise, static electricity, magnetic fields or noise.
- Direct air flow from an air conditioner.
- Exposure to direct sunlight.
- (4) Mount this instrument in the panel considering the following conditions:
- Ensure at least 50 mm space on top and bottom of the instrument for maintenance and environmental reasons.
- Do not mount this instrument directly above the equipment that generates large amount of heat
- (heaters, transformers, semi-conductor functional devices, large-wattage resistors.)

 If the ambient temperature rises above 55 °C, cool this instrument with a forced air fan, cooler, etc.
- Cooled air should not blow directly on this instrument.

 In order to improve safety and the immunity to withstand noise, mount this instrument as far away as possible from high voltage equipment, power lines, and rotating machinery.

 High voltage equipment: Do not mount within the same panel.

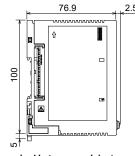
Power lines: Separate at least 200 mm.

Rotating machinery: Separate as far as possible.

• Do not connect the COM-ME module to the others. Otherwise the communication may not be

(5) In case this instrument is connected to a supply by means of a permanent connection, a switch or circuit-breaker shall be included in the installation. This shall be in close proximity to the equipment and within easy reach of the operator. It shall be marked as the disconnecting device

3.2 Dimensions



• Space required between each instrument

To install/uninstall the main unit of the COM-ME on/from the Base unit, the main unit needs to be slightly inclined and thus requires at least 50mm clearance above and below it



②

6.7

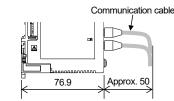
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Depth for communication cables

Space for communication cables must be considered when installing

(Unit: mm)

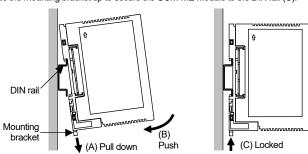
(Unit: mm)



3.3 DIN Rail Mounting -

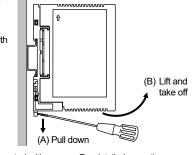
■ Mounting procedures

- 1. Pull down the mounting bracket at the bottom of the base (A). Attach the hooks on the top of the base to the DIN rail and push the lower section into place on the DIN rail (B).
- 2. Slide the mounting bracket up to secure the COM-ME module to the DIN rail (C)



■ Removing procedures

- 1. Turn the power OFF
- 2. Remove the wiring.
- 3. Pull down a mounting bracket with a slotted screwdriver (A) Lift the COM-ME module from bottom, and take it off (B).

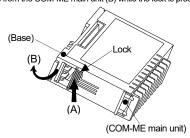


Mounting with screws

The module can be also mounted with screws. For detailed mounting procedure, refer to COM-ME-3 [For the FZ series/GZ series] Instruction manual

3.4 How to Separate the COM-ME Module and Base

Remove the base from the COM-ME main unit (B) while the lock is pressed (A).



4. WIRING

∕!\ WARNING

To prevent electric shock or instrument failure, do not turn on the power until all the wiring is completed. Make sure that the wiring has been properly made before applying power to the instrument.

4.1 Wiring Cautions

as IEC 60950-1

- To avoid noise induction, keep communication signal wire away from instrument power line,
- load lines and power lines of other electric equipment.

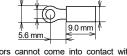
 If there is electrical noise in the vicinity of the instrument that could affect operation, use a
 - Shorten the distance between the twisted power supply wire pitches to achieve the most Always install the noise filter on a grounded panel. Minimize the wiring distance between
 - the noise filter output and the instrument power supply terminals to achieve the most effective noise reduction.
- Do not connect fuses or switches to the noise filter output wiring as this will reduce the effectiveness of the noise filter Power supply wiring must be twisted and have a low voltage drop. • For an instrument with 24 V power supply input, supply power from a "SELV" circuit defined
- A suitable power supply should be considered in end-use equipment. The power supply must be in compliance with a limited-energy circuits (maximum available current of 5.6 A).
- The power supply must handle the rush current when the power is turned on.

Power consumption (at maximum load): 150 mA max. (at 24 V DC) Rush current: 15 A or less

· When connecting the wiring to the terminals, use the specified solderless terminals. Only these specified solderless terminals can be used due to the insulation between the terminals. Power supply terminals, Communication terminals: M3 × 7 (with 5.8 × 5.8 square washer)

Recommended tightening torque: 0.4 N·m (4 kgf·cm) Applicable wire: Solid/twisted wire of 0.25 to 1.65 mm²

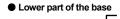
cified solderless terminal Manufactured by J.S.T MFG CO., LTD. Circular terminal with isolation V1.25–MS3
(M3 screw, width 5.5 mm, hole diameter 3.2 mm)

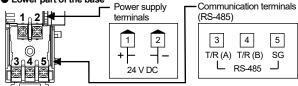


φ3.2 MIN

· Make sure that during field wiring parts of conductors cannot come into contact with adjacent conductive parts.

4.2 Terminal Configuration —





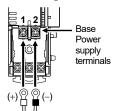
Lower part of the front



FG terminal

Ground the instrument separately from other equipment. The grounding resistance should be 100 Ω or less. Use grounding wires with a cross section area of 2 mm² or more.

4.3 Wiring of Power Supply Terminals —



- 1. Turn the power OFF.
- 2. Remove the COM-ME main unit from the base
- 3. Remove the power terminal cover on the base.
- 4. Attach the solderless terminals to the power supply terminals with a Phillips head screwdriver. When attaching the terminals, make sure that the polarity (+ and -) is correct.
- 5. Attach the power supply terminal cover on the terminal and return the COM-ME main unit to the base. This completes the wiring work.

4.4 Connection to Controller

Conduct wiring of the COM-ME and the controller by referring to the following connection

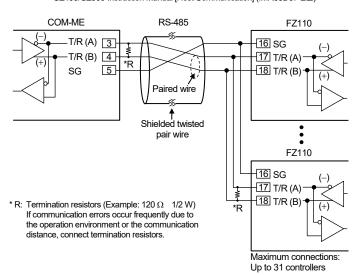


(Communication to	erminals (RS-485))
	Terminal No.	Symbol	Signal name
	3	T/R (A)	Send data/Receive data
	4	T/R (B)	Send data/Receive data
	5	SG	Signal ground

■ Wiring example (FZ110)

The communication cable and termination resistor(s) must be provided by the customer.

- Refer to the instruction manual of the relevant model for the details of the size of the solderless terminal and how to conduct transition wiring.
 - FZ110/FZ400/FZ900 Instruction Manual [Host Communication] (IMR03A07-E□) • GZ400/GZ900 Instruction Manual [Host Communication] (IMR03D07-E□)



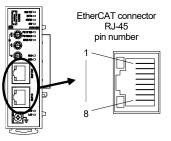
FZ110/FZ400/FZ900 Communication terminals (RS-485)

Termi	nal No.	Comple ed	Simusl manns
FZ110	FZ400/FZ900	Symbol	Signal name
16	34	SG	Signal ground
17	35	T/R (A)	Send data/Receive data
18	36	T/R (B)	Send data/Receive data

GZ400/GZ900 Communication terminals (RS-485)

Terminal No.	Symbol	Signal name
34	SG	Signal ground
35	T/R (A)	Send data/Receive data
36	T/R (B)	Send data/Receive data

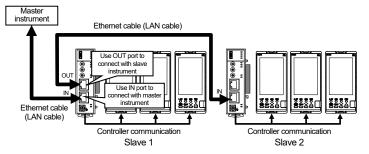
4.5 Connection to EtherCAT



Pin No	Signal name	Symbol
1	Send data +	TX+
2	Send data –	TX-
3	Receive data +	RX+
4	Unused	_
5	Unused	_
6	Receive data –	RX-
7	Unused	_
8	Unused	_

■ Connection Example

The Ethernet cable (LAN cable) which is marketed can be connected. The Ethernet cable (LAN cable) must be provided by the customer

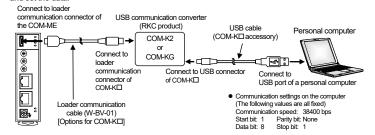


Use category 5 Ethernet cable (LAN cable).

The details of the EtherCAT are connected to the website of ETG (EtherCAT Technology Group), and obtain necessary information. URL: https://www.ethercat.org/

4.6 Connection to Loader Communication

Connect a USB communication converter COM-K2 or COM-KG (sold separately) between the personal computer and the COM-ME. Loader communication makes it possible to check and set data of the COM-ME and the controller. Our communication tool PROTEM2 can be used to check and set the data



The Loader port is only for parameter setup. Not used for data logging during

During the loader communication, the COM-ME requires an external power source. The COM-ME will not function on the USB power from a personal computer alone

The COM-ME address for loader communication is fixed at "0."

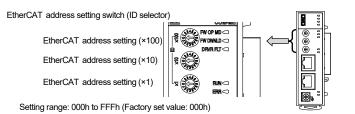
Refer to the instruction manual of the relevant USB communication converter for the details

5. COMMUNICATION SETTINGS

5.1 EtherCAT Address Setting

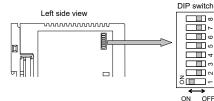
Use three rotary switches to set the fixed address (Hexadecimal) of the EtherCAT so that the Master can recognize the Slave Supports Explicit Device Identification (Required ID) and Configured Station Alias. The set address is written into the register 0x0012 (Configured Station Alias) of the ESC (EtherCAT Slave Controller) at the start-up. Use a small flat-blade screwdriver to configure the setting

To activate the EtherCAT address setting, turn off the power once and turn it back on again



5.2 Setting on the DIP switch

Use the DIP switch to set the communication speed of controller communication, and DIP switch enable/disable.



					ON OH	
1	2		Co	ntrolle	r communication speed	
OFF	OFF					
ON	OFF			← Factory set value:		
OFF	ON			19200 bps		
ON	ON					
						_
3	4	5	6	7		
OFF	4 OFF	5 OFF	6 OFF	7 OFF	Fixed (Do not set this one)	← Factory set value
				7 OFF	Fixed (Do not set this one)	← Factory set value
			OFF		Fixed (Do not set this one)	← Factory set value
OFF	OFF	OFF	OFF DI	P switc	,	← Factory set value ← Factory set value:

Communication speed of the controller communication and data bit configuration are enabled with the loader communication setting

- When the communication protocol is set with the DIP switch, the data bit configuration is automatically set to "data 8-bit, without parity, stop 1-bit." To change to another data bit configuration, set the configuration through the loader communication.
- If you wish to set the communication speed and the data bit configuration of the controller communication through the loader communication, first set DIP switch No.8 to ON.

6. SPECIFICATIONS

■ EtherCAT communication

Physical layer: 100BASE-TX User layer: EtherCAT

CAN application protocol over EtherCAT (CoE) Correspondence protocol: Communication object: Service data object (SDO), Process data object (PDO)

Connector type: RJ-45 (2 ports) Network topology: EtherCAT compliant

Category 5 or higher (Shielded cable recommended) Cable type:

Transmission distance: Within 100 meters between nodes Conformance test version:

Version 2.2.1.0

■ Controller communication

Interface: Base on RS-485. EIA standard Synchronous method: Start/Stop synchronous type

Connection method: 2-wire system, half-duplex multi-drop connection Communication speed 9600 bps, 19200 bps, 38400 bps, 57600 bps

Data bit configuration: Start bit:

Data bit: Parity bit: None. Odd or Even

Stop bit: 1 or 2

Protocol: . Modbus-RTU (mast

31 controllers (FZ110/400/900 or GZ400/900) Maximum connections Connection method: Terminal block

Externally connected (Example: 120 Ω , 1/2 W) 0 to 250 ms

■ Loader communication

Connection method: Connection with a loader communication cable for our USB communication converter COM-K2 or COM-KG. (COM-K□ are

sold separately)

RKC communication (ANSI X3.28-1976 subcategories 2.5 and B1) Protocol: Synchronous method: Start/Stop synchronous type

Communication speed: 38400 bps

Data bit configuration: Data bit: 8 Parity bit: None

Maximum connections: One controller

■ General specifications

Power supply voltage: 24 V DC Power supply voltage range: 20.4 V to 26.4 V DC [Including power supply voltage variation] Power consumption (at maximum load):

150 mA max. (24 V DC) Rush current: 15 A or less

Allowable ambient temperature: -10 to +55 °C

Allowable ambient humidity: 5 to 95 %RH

(Absolute humidity: MAX.W.C 29 g/m³ dry air at 101.3 kPa)

Installation environment conditions:

Indoors use, Altitude up to 2000 m

Weight: Approx. 150 g

■ Standard

UL 61010-1 Safety standard: UL: CAN/CSA-C22.2 No.61010-1

EMC: EN61326-1 RoHS: EN50581

EN55011

7. MODEL CODE



(1) Network communication type

3: EtherCAT

(2) Controller communication interface

5: RS-485

(3) Corresponding to the RKC controller

07: FZ series/GZ series

(4) Factory setting (supported communication mode) [optional]

(blank): No factory setting with factory setting

(5) Supported communication mode [optional]

(blank): Communication protocol not specified at the time of shipment

(single word mode supported)

Single word mode is supported

FZ double word mode is supported (Data transfer: in the order from upper word to lower word)

FZ double word mode is supported

(Data transfer: in the order from lower word to upper word) GZ double word mode is supported

(Data transfer: in the order from upper word to lower word) GZ double word mode is supported

(Data transfer: in the order from lower word to upper word)

GZ HA mode is supported (Data transfer: in the order from upper word to lower word)

GZ HA mode is supported

(Data transfer: in the order from lower word to upper word)

■ Other peripherals and accessories (Sold separately)

- Communication converter COM-K2-1 (Optional: with loader communication cable)
- Communication converter COM-KG-1N (Optional: with loader communication cable)
- End plate (DEP-01, Package of 2 plates)

Ether CAT.

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