



Temperature Controller

GZ400/GZ900

Instruction Manual
[Part2: Parameters/Functions]

NOTICE

- This manual assumes that the reader has a fundamental knowledge of the principles of electricity, process control, computer technology and communications.
- The figures, diagrams and numeric values used in this manual are only for explanation purpose.
- RKC is not responsible for any damage or injury that is caused as a result of using this instrument, instrument failure or indirect damage.
- RKC is not responsible for any damage and/or injury resulting from the use of instruments made by imitating this instrument.
- Periodic maintenance is required for safe and proper operation of this instrument. Some components have a limited service life, or characteristics that change over time.
- Every effort has been made to ensure accuracy of all information contained herein. RKC makes no warranty, expressed or implied, with respect to the accuracy of the information. The information in this manual is subject to change without prior notice.
- No portion of this document may be reprinted, modified, copied, transmitted, digitized, stored, processed or retrieved through any mechanical, electronic, optical or other means without prior written approval from RKC.

- Modbus is a registered trademark of Schneider Electric.
- Company names and product names used in this manual are the trademarks or registered trademarks of the respective companies.

Symbols

■ Screens used in this manual

It should be noted that this manual describes various screens of GZ400/900 according to the following rules.

- GZ400/900 are available in two types: single input type and dual input type.
The dual input type is further categorized into two types: Dual PV type and PV + Remote setting type.
For a dual input model, the same parameter may exist in both Input 1 and Input 2. “**1.**” or “**2.**” is added to the top of the parameters for identification. “**1.**” is not added to the top of the parameters list for the single input type.

[Display example of the dual input type]

Input 1_Set value (SV) Input 2_Set value (SV)

1. 5V	2. 5V
--------------	--------------

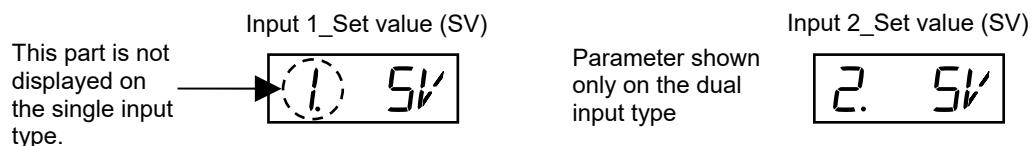
[Display example of a single input type]

Set value (SV)

5V

This manual uses the dual inputs for explanation. For other types such as a single input type, ignore the first character “**1.**” at the top of the parameter.

[Notation in this manual]



- In the explanation of the operating navigation “**2. SELECTING PARAMETERS (P. 2-1)**,” such display frames as shown below are used to show the difference.

--

 Parameters always displayed

--

 Parameters that are displayed if the display requirements are satisfied.

■ Character Symbols

11-segment character

0	1	2	3	4	5	6	7	8	9	Minus	Period
0	1	2	3	4	5	6	7	8	9	-	.
A	B (b)	C	c	D (d)	E	F	G	H	I	J	K
A	b	C	c	d	E	F	G	H	I	J	K
L	M	N	n	O (o)	P	Q	R	S	T	t	U
L	M	N	n	o	P	Q	R	S	T	t	U
u	v	w	x	y	z	Degree	/	Prime	*	(Asterisk)	→
u	v	w	x	y	z	o	/	'	*	†	‡

7-segment character

0	1	2	3	4	5	6	7	8	9	Minus	Period
0	1	2	3	4	5	6	7	8	9	-	.
A	B (b)	C	c	D (d)	E	F	G	H	I	J	K
A	b	C	c	d	E	F	G	H	I	J	K
L	M	N (n)	O (o)	P	Q	R	S	T	t	U	u
L	M	N	n	o	P	Q	R	S	T	U	u
v	w	x	y	z	Degree	/	Prime	*	(Asterisk)		
v	w	x	y	z	o	/	'	u			

■ Abbreviation symbols

These abbreviations are used in this manual:

Abbreviation symbols	Name	Abbreviation symbols	Name
PV	Measured value	TC (input)	Thermocouple (input)
SV	Set value	RTD (input)	Resistance temperature detector (input)
MV	Manipulated output value	V (input)	Voltage (input)
AT	Autotuning	I (input)	Current (input)
ST	Startup tuning	HBA (1, 2)	Heater break alarm (1, 2)
OUT (1 to 3)	Output (1 to 3)	CT (1, 2)	Current transformer (1, 2)
DI (1 to 6)	Digital input (1 to 6)	LBA	Control loop break alarm
DO (1 to 4)	Digital output (1 to 4)	LBD	LBA deadband

Document Configuration

There are seven manuals pertaining to this product. Please be sure to read all manuals specific to your application requirements.

The following manuals can be downloaded from the official RKC website:

<https://www.rkcinst.co.jp/english/download-center/>

Manual	Manual Number	Remarks
GZ400/GZ900 Installation Manual	IMR03D01-E□	This manual is enclosed with instrument. This manual explains the mounting and wiring.
GZ400/GZ900 Quick Operation Manual	IMR03D02-E□	This manual is enclosed with instrument. This manual explains the basic key operation, mode menu, and data setting.
GZ400/GZ900 Parameter List	IMR03D03-E□	This manual is enclosed with instrument. This list is a compilation of the parameter data of each mode.
GZ400/GZ900 Instruction Manual [Part 1: Hardware]	IMR03D04-E□	This manual describes installation, wiring, troubleshooting and product specification.
GZ400/GZ900 Instruction Manual [Part 2: Parameters/Functions]	IMR03D05-E2	This manual you are reading now. [Parameters] This manual describes how to switch the operation modes and parameters, the range of parameters, and initialization/automatic conversion associated with the change of settings. [Functions] This manual describes how to set up and each function.
GZ400/GZ900 Instruction Manual [Host Communication]	IMR03D07-E□	This manual explains RKC communication protocol (ANSI X3.28-1976) and Modbus relating to communication parameters setting.
GZ400/GZ900 Instruction Manual [PLC Communication]	IMR03D08-E□	This manual describes how to set up the instrument for communication with a programmable controller (PLC).



Read this manual carefully before operating the instrument. Please place the manual in a convenient location for easy reference.

Contents

	Page
NOTICE	
Symbols.....	i-1
■ Screens used in this manual	i-1
■ Character Symbols	i-2
■ Abbreviation symbols	i-2
Document Configuration.....	i-3

[Parameters]

1. MODE SWITCHING 1-1

Chapter 1 describes various mode types and how to switch between them.

2. SELECTING PARAMETERS 2-1

Chapter 2 describes various parameter types and how to switch between them.

2.1 Monitor & SV Setting Mode [A]	2-2
■ 1-loop control (Including Remote setting input/Input circuit error alarm)	2-2
■ 2-loop control	2-3
■ Control with PV select.....	2-4
■ Differential temperature control	2-5
2.2 Parameter Select Mode [B].....	2-6
2.3 Operation Transfer Mode [C]	2-7
2.4 Setting Lock Mode [D]	2-8
2.5 Memory Area Transfer Mode [E].....	2-9
2.6 Parameter Setting Mode [F].....	2-10
2.7 Setup Setting Mode [G]	2-13
2.8 Engineering Mode [H]	2-16

3. PARAMETER LIST 3-1

Chapter 3 describes displays, names and data ranges of each parameter.

3.1 How to Read the Table	3-2
3.2 Monitor & SV Setting Mode [A]	3-3
3.3 Parameter Select Mode [B].....	3-5
3.4 Operation Transfer Mode [C]	3-6
3.5 Setting Lock Mode [D]	3-7
3.6 Memory Area Transfer Mode [E].....	3-8

	Page
3.7 Parameter Setting Mode [F]	3-9
■ Parameter group No. 00: Setting (<i>SG</i>)	3-9
■ Parameter group No. 40: Event (<i>EH</i>)	3-9
■ Parameter group No. 51: Input 1_Control (<i>I.Conf</i>)	3-10
■ Parameter group No. 52: Input 2_Control (<i>2.Conf</i>)	3-12
■ Parameter group No. 56: Input 1_Cooling control (<i>I.Cool</i>)	3-13
■ Parameter group No. 70: Memory area (<i>MER</i>)	3-14
■ Parameter group No. 71: Input 1_Input knee point correction (<i>I.I.nLr</i>)	3-16
■ Parameter group No. 72: Input 2_Input knee point correction (<i>2.I.nLr</i>)	3-17
3.8 Setup Setting Mode [G]	3-18
■ Setting group No. 10: Display (<i>dSP</i>)	3-18
■ Setting group No. 21: Input 1 (<i>I.I.nP</i>)	3-18
■ Setting group No. 22: Input 2 (<i>2.I.nP</i>)	3-18
■ Setting group No. 30: Output (<i>oUf</i>)	3-19
■ Setting group No. 45: Heater break alarm 1 (<i>HbR1</i>)	3-19
■ Setting group No. 46: Heater break alarm 2 (<i>HbR2</i>)	3-20
■ Setting group No. 51: Input 1_Control (<i>I.Conf</i>)	3-20
■ Setting group No. 52: Input 2_Control (<i>2.Conf</i>)	3-21
■ Setting group No. 53: Input 1_Tuning (<i>I.TunE</i>)	3-21
■ Setting group No. 54: Input 2_Tuning (<i>2.TunE</i>)	3-22
■ Setting group No. 57: Proactive (<i>PAC</i>)	3-22
■ Setting group No. 58: 2-input function (<i>2PF</i>)	3-22
■ Setting group No. 91: System (<i>SYS</i>)	3-23
3.9 Engineering Mode [H]	3-24
■ Function block No. 10: Display (<i>dSP</i>)	3-24
■ Function block No. 11: Key operation (<i>KEY</i>)	3-25
■ Function block No. 21: Input 1 (<i>I.I.nP</i>)	3-26
■ Function block No. 22: Input 2 (<i>2.I.nP</i>)	3-28
■ Function block No. 23: Digital input (<i>di</i>)	3-30
■ Function block No. 30: Output (<i>oUf</i>)	3-31
■ Function block No. 31: Retransmission output 1 (<i>Ro1</i>)	3-32
■ Function block No. 32: Retransmission output 2 (<i>Ro2</i>)	3-33
■ Function block No. 33: Retransmission output 3 (<i>Ro3</i>)	3-33
■ Function block No. 34: Digital output (<i>do</i>)	3-34
■ Function block No. 41: Event 1 (<i>EH1</i>)	3-35
■ Function block No. 42: Event 2 (<i>EH2</i>)	3-36
■ Function block No. 43: Event 3 (<i>EH3</i>)	3-36
■ Function block No. 44: Event 4 (<i>EH4</i>)	3-36
■ Function block No. 45: CT1 (<i>CF1</i>)	3-37
■ Function block No. 46: CT2 (<i>CF2</i>)	3-37
■ Function block No. 50: Control (<i>Conf</i>)	3-38
■ Function block No. 51: Input 1_Control (<i>I.Conf</i>)	3-39
■ Function block No. 52: Input 2_Control (<i>2.Conf</i>)	3-40
■ Function block No. 56: Input 1_Cooling control (<i>I.Cool</i>)	3-41

	Page
■ Function block No. 57: Proactive (<i>PACT</i>).....	3-41
■ Function block No. 58: 2-input function (<i>2PV</i>).....	3-41
■ Function block No. 60: Communication (<i>SCI</i>)	3-42
■ Function block No. 62: PLC communication (<i>PLC</i>)	3-43
■ Function block No. 70: Memory area (<i>MR</i>)	3-43
■ Function block No. 71: Input 1_Setting limiter (<i>I. SBL</i>)	3-43
■ Function block No. 72: Input 2_Setting limiter (<i>2. SBL</i>)	3-44
■ Function block No. 91: System (<i>SYS</i>)	3-44

4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED 4-1

Chapter 4 describes the parameters that are initialized/modified when setting is changed.

4.1 Parameters to Be Initialized.....	4-2
4.1.1 When Select function for input 2 (<i>2PV</i>) is changed [Engineering mode: Function block No. 58]	4-3
4.1.2 When Input 1_Input type (<i>I. I NP</i>) and Input 1_Display unit (<i>I.UNI F</i>) are changed [Engineering mode: Function block No. 21]	4-6
4.1.3 When Input 1_Decimal point position (<i>I.PC dP</i>) is changed [Engineering mode: Function block No. 21]	4-9
4.1.4 When Input 2_Input type (<i>2. I NP</i>) and Input 2_Display unit (<i>2.UNI F</i>) are changed [Engineering mode: Function block No. 22]	4-10
4.1.5 When Input 1_Control action (<i>I. oS</i>) is changed [Engineering mode: Function block No. 51]	4-12
4.1.6 When Input 1_Selection of correction value setting (<i>I. rVS</i>) is changed [Engineering mode: Function block No. 21]	4-13
4.1.7 When Input 2_Selection of correction value setting (<i>2. rVS</i>) is changed [Engineering mode: Function block No. 22]	4-13
4.1.8 When OUT1 function selection (<i>oSL 1</i>) is changed [Engineering mode: Function block No. 30]	4-14
4.1.9 When OUT2 function selection (<i>oSL 2</i>) is changed [Engineering mode: Function block No. 30]	4-14
4.1.10 When OUT3 function selection (<i>oSL 3</i>) and Universal output type selection (<i>UNI o</i>) are changed [Engineering mode: Function block No. 30].....	4-14
4.1.11 When Retransmission output 1 type (<i>Ro 1</i>) is changed [Engineering mode: Function block No. 31].....	4-15
4.1.12 When Retransmission output 2 type (<i>Ro2</i>) is changed [Engineering mode: Function block No. 32].....	4-16
4.1.13 When Retransmission output 3 type (<i>Ro3</i>) is changed [Engineering mode: Function block No. 33].....	4-16
4.1.14 When Event 1 type (<i>E5 1</i>) and Event 1 assignment (<i>EVR 1</i>) are changed [Engineering mode: Function block No. 41].....	4-16

	Page
4.1.15 When Event 2 type (<i>E52</i>) and Event 2 assignment (<i>EVRA2</i>) are changed [Engineering mode: Function block No. 42].....	4-17
4.1.16 When Event 3 type (<i>E53</i>) and Event 3 assignment (<i>EVRA3</i>) are changed [Engineering mode: Function block No. 43].....	4-17
4.1.17 When Event 4 type (<i>E54</i>) and Event 4 assignment (<i>EVRA4</i>) are changed [Engineering mode: Function block No. 44].....	4-18
4.1.18 When CT1 type (<i>CET1</i>) is changed [Engineering mode: Function block No. 45].....	4-18
4.1.19 When CT2 type (<i>CET2</i>) is changed [Engineering mode: Function block No. 46].....	4-18
4.1.20 When Integral/Derivative time decimal point position (<i>I_ddP</i>) is changed [Engineering mode: Function block No. 50].....	4-19
4.1.21 When Communication protocol (<i>CMPS</i>) is changed [Engineering mode: Function block No. 60].....	4-19
4.1.22 When Register type (<i>MP.REG</i>) is changed [Engineering mode: Function block No. 62].....	4-19
4.1.23 When Soak time unit (<i>SFddP</i>) is changed [Engineering mode: Function block No. 70].....	4-20
4.1.24 When Initialization (<i>dEF</i>) is changed [Engineering mode: Function block No. 91].....	4-20
4.2 Parameters to Be Automatically Converted	4-21
■ Example of automatic conversion.....	4-22
4.2.1 When Input data type (<i>I_NdF</i>) is changed [Engineering mode: Function block No. 21].....	4-23
4.2.2 When Input 1_Decimal point position (<i>I_PGdP</i>), Input 1_Input range high (<i>I_PGSH</i>) and Input 1_Input range low (<i>I_PGS_L</i>) are changed [Engineering mode: Function block No. 21].....	4-25
4.2.3 When Input 1_Control action (<i>I_aS</i>) is changed [Engineering mode: Function block No. 51].....	4-27
4.2.4 When Input 1_Setting limiter high/low (<i>I_SLH</i> , <i>I_SLL</i>) is changed [Engineering mode: Function block No. 71].....	4-27
4.2.5 When Input 1_Output limiter high/low (heat-side) (<i>I_aLH</i> , <i>I_aLL</i>) is changed [Parameter setting mode: Parameter group No. 51].....	4-27
4.2.6 When Input 1_Output limiter high/low (cool-side) (<i>I_aLHC</i> , <i>I_aLLC</i>) is changed [Parameter setting mode: Parameter group No. 56].....	4-27
4.2.7 When Input 2_Decimal point position (<i>2PGdP</i>) is changed [Engineering mode: Function block No. 22].....	4-28
4.2.8 When Input 2_Input range high/low (<i>2PGSH</i> , <i>2PGSL</i>) is changed [Engineering mode: Function block No. 22].....	4-30
4.2.9 When Input 2_Setting limiter high/low (<i>2_SLH</i> , <i>2_SLL</i>) is changed [Engineering mode: Function block No. 72].....	4-32
4.2.10 When Input 2_Output limiter high/low (<i>2_aLH</i> , <i>2_aLL</i>) is changed [Parameter setting mode: Parameter group No. 52].....	4-32
4.2.11 When Memory area transfer (<i>RRETR</i>) is changed Memory area transfer mode]	4-32

	Page
4.2.12 When Input 1_Knee point correction limit value (<i>I_rVML</i>) is changed [Engineering mode: Function block No. 21].....	4-32
4.2.13 When Input 2_Knee point correction limit value (<i>I_rVML</i>) is changed [Engineering mode: Function block No. 22].....	4-33
4.2.14 When Input 1_Level PID setting 1 (<i>ILEV1</i>) is changed [Setup setting mode: Setting group No. 51].....	4-33
4.2.15 When Input 1_Level PID setting 2 (<i>ILEV2</i>) is changed [Setup setting mode: Setting group No. 51].....	4-33
4.2.16 When Input 1_Level PID setting 3 (<i>ILEV3</i>) is changed [Setup setting mode: Setting group No. 51].....	4-34
4.2.17 When Input 1_Level PID setting 4 (<i>ILEV4</i>) is changed [Setup setting mode: Setting group No. 51].....	4-34
4.2.18 When Input 1_Level PID setting 5 (<i>ILEV5</i>) is changed [Setup setting mode: Setting group No. 51].....	4-34
4.2.19 When Input 1_Level PID setting 6 (<i>ILEV6</i>) is changed [Setup setting mode: Setting group No. 51].....	4-35
4.2.20 When Input 1_Level PID setting 7 (<i>ILEV7</i>) is changed [Setup setting mode: Setting group No. 51].....	4-35
4.2.21 When Input 2_Level PID setting 1 (<i>ILEV1</i>) is changed [Setup setting mode: Setting group No. 52].....	4-35
4.2.22 When Input 2_Level PID setting 2 (<i>ILEV2</i>) is changed [Setup setting mode: Setting group No. 52].....	4-36
4.2.23 When Input 2_Level PID setting 3 (<i>ILEV3</i>) is changed [Setup setting mode: Setting group No. 52].....	4-36
4.2.24 When Input 2_Level PID setting 4 (<i>ILEV4</i>) is changed [Setup setting mode: Setting group No. 52].....	4-36
4.2.25 When Input 2_Level PID setting 5 (<i>ILEV5</i>) is changed [Setup setting mode: Setting group No. 52].....	4-37
4.2.26 When Input 2_Level PID setting 6 (<i>ILEV6</i>) is changed [Setup setting mode: Setting group No. 52].....	4-37
4.2.27 When Input 2_Level PID setting 7 (<i>ILEV7</i>) is changed [Setup setting mode: Setting group No. 52].....	4-37

[Functions]

5. INPUT FUNCTION 5-1

This chapter describes input related functions, setting contents and setting procedure based on the key words related to inputs.

5.1 Changing Input	5-2
5.2 Switching Functions Using Digital Inputs (DI).....	5-16
5.3 Correcting Input (PV Bias and PV Ratio).....	5-28
5.4 Preventing the Input Flicker.....	5-31
5.5 Inverting the Input.....	5-33
5.6 Extracting Square Root of Input.....	5-35
5.7 Changing Error Handling at Input Error	5-39
5.8 Using Dual Input Function	5-48
5.9 Changing Power Supply Frequency	5-51
5.10 Making Corrections at Multiple Points (Input Knee Point Correction)	5-52

6. OUTPUT FUNCTION 6-1

This chapter describes output related functions, setting contents and setting procedure based on the key words related to outputs.

6.1 Changing Output Assignment [Control Output, Retransmission Output, Logic Calculation (Event) Output, Instrument Status Output]	6-2
6.2 Changing Output Type of OUT3.....	6-12
6.3 Using Retransmission Output.....	6-14
6.4 Changing Proportional Cycle Time.....	6-20
6.5 Changing Energizing/De-energizing Output	6-24
6.6 Limiting Output	6-26
6.7 Suppressing Sudden Change in Output (Output Change Rate Limiter)	6-29
6.8 Suppressing Sudden Change in Output (Balanceless Bumpless).....	6-33
6.9 Changing the Output Action While in Control Stop Mode.....	6-39
6.10 Monitoring Manipulated Output Value	6-42

7. EVENT FUNCTION 7-1

This chapter describes event related functions, setting contents and setting procedure based on the key words related to events.

7.1 Using Event Function	7-2
7.1.1 Changing input for event.....	7-3

	Page
7.1.2 Changing event type	7-7
7.1.3 Adding hold action to the event action.....	7-16
7.1.4 Setting a differential gap in event action.....	7-19
7.1.5 Preventing event from turning on due to a transient abnormal input.....	7-21
7.1.6 Changing event output assignment	7-23
7.1.7 Changing the event set value	7-23
7.2 Using Heater Break Alarm (HBA).....	7-24
7.2.1 Setting the Heater break alarm (HBA) set value.....	7-25
7.2.2 Preventing Heater break alarm (HBA) from turning on due to a transient abnormal input	7-28
7.2.3 Changing the output monitored by the Heater break alarm (HBA).....	7-30
7.2.4 Changing the Current transformer (CT) type	7-33
7.2.5 Forcing the CT input value to 0.0 A when the heater is OFF	7-35
7.3 Using Control Loop Break Alarm (LBA).....	7-36
7.4 Checking Event ON State	7-40
7.5 Keeping the Event State (Interlock Function)	7-42
7.6 Releasing the Event State (Interlock Release).....	7-44
7.7 Preventing Control with Input Errors (Input Circuit Error Alarm).....	7-46

8. CONTROL FUNCTION 8-1

This chapter describes control related functions, setting contents and setting procedure based on the key words related to controls.

8.1 Running/Stopping Control (RUN/STOP Transfer)	8-2
8.2 Changing Control Action	8-5
8.3 Setting PID Values Automatically (Autotuning)	8-11
8.4 Setting PID Values Automatically (Startup tuning)	8-18
8.5 Setting PID Values Manually	8-24
8.6 Controlling with ON/OFF Action	8-31
8.7 Controlling with Heat/Cool Control	8-36
8.8 Controlling with Manual Control	8-44
8.9 Using Remote Setting Input	8-49
8.10 Executing 2-Loop Control.....	8-55
8.11 Executing Differential Temperature Control	8-58
8.12 Executing Control with PV Select.....	8-63
8.13 Controlling with Level PID	8-72
8.14 Eliminating Offset Inherent to Proportioning Control (Manual Reset).....	8-83
8.15 Continuing Stable Control after the Operation Transfer (SV Tracking)	8-85

	Page
8.16 Suppressing Overshoot.....	8-90
8.17 Changing the Action at Power ON (Hot/Cold Start).....	8-98

9. DISPLAY RELATED FUNCTIONS 9-1

This chapter describes display related functions, setting contents and setting procedure based on the key words related to Display.

9.1 Grouping Necessary Screens (Parameter Select Function).....	9-2
9.2 Hiding Unnecessary Screens	9-9
9.3 Hiding the Display of the Set Value (SV).....	9-15
9.4 Changing the Display Position of STOP during the Control Stop	9-17
9.5 Changing the ALM Lamp Lighting Condition	9-19
9.6 Changing the Display Contents of the MV Display.....	9-21
9.7 Checking Input Peak Value/Bottom Value.....	9-23
9.8 Suppressing the Display Flickering	9-27
9.9 Checking the Instrument Information	9-29

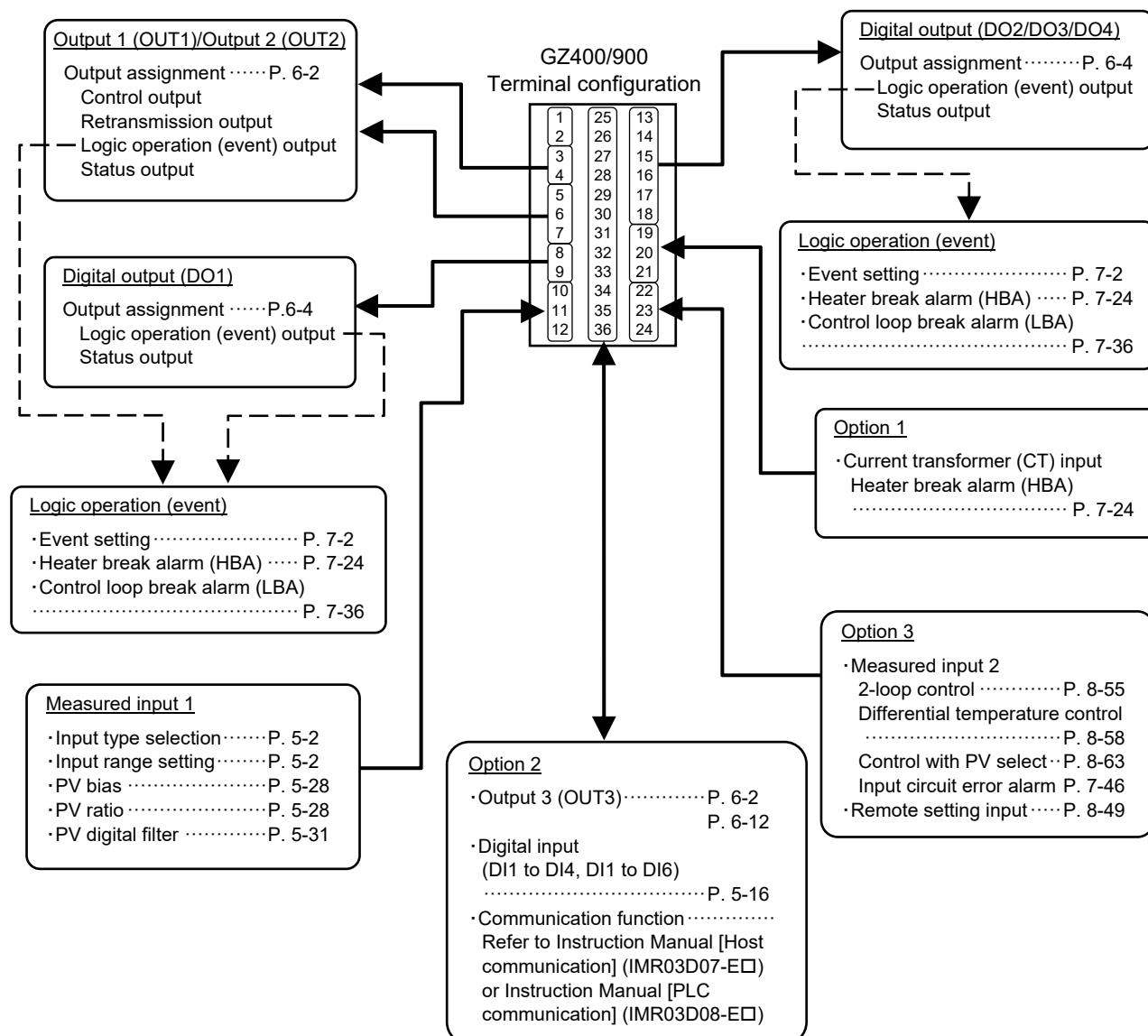
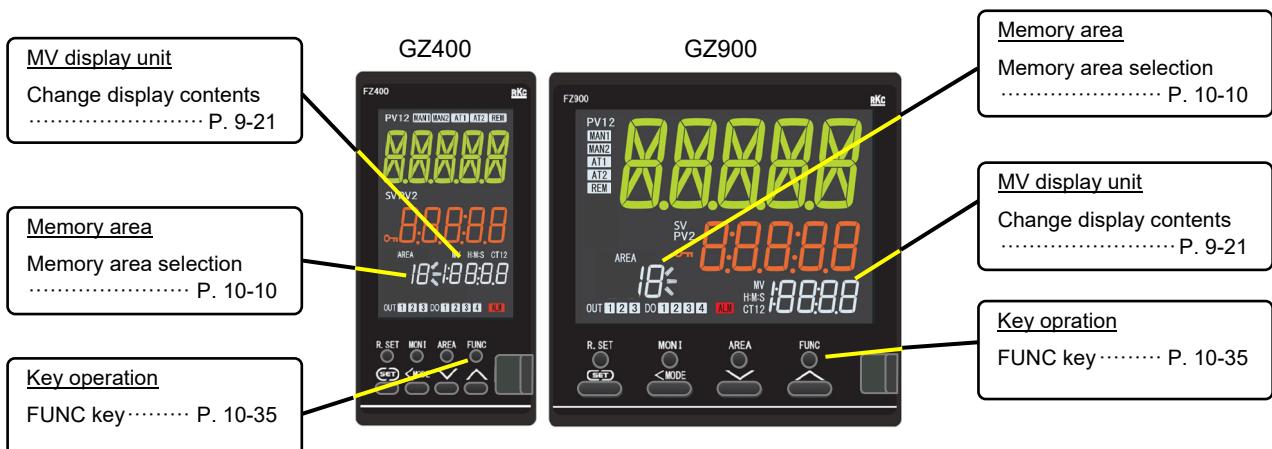
10. SETTING AND KEY OPERATION 10-1

This chapter describes setting and key operation related functions, setting contents and setting procedure based on the keywords related to setting and key operation.

10.1 Limiting the Setting Range of Set Value (SV)	10-2
10.2 Eliminating a Sudden Set Value Change (Setting Change Rate Limiter) ...	10-6
10.3 Storing the Control Related Set Values (Memory Area Function)	10-10
10.4 Copying the Data in Memory Area to Set Other Areas.....	10-16
10.5 Running a Simple Ramp/Soak Operation	10-18
10.6 Using a Simple Sequence Operation	10-26
10.7 Registering a Set Value (SV) Without Pressing the SET Key	10-33
10.8 Accessing Some Functions Directly (FUNC Key)	10-35
10.9 Restricting Key Operation (Set Data Lock)	10-38
10.10 Fixing the Set Value to a Specified Value (Fix Parameter Setting)	10-41
10.11 Initializing the Set Data	10-45

Pictorial table of contents

Pages that mainly describe the hardware are shown.



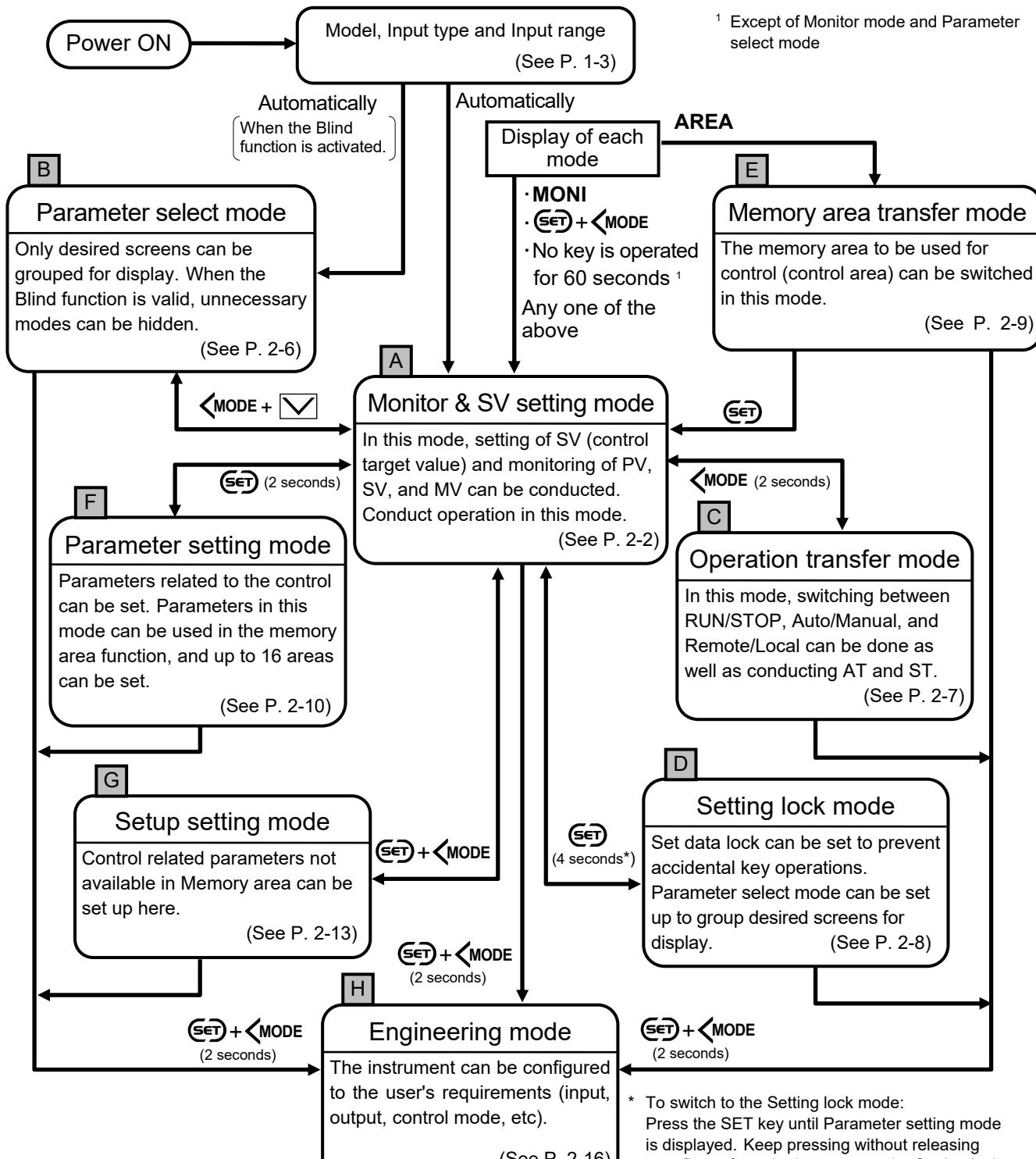
1

MODE SWITCHING

This chapter describes various modes and how to switch between them.

■ Mode switching

The instrument has eight different modes for operation and setting. Modes can be switched through the key operation of **SET** and **<MODE** keys.



* To switch to the Setting lock mode:
Press the SET key until Parameter setting mode is displayed. Keep pressing without releasing your finger from the key to enter the Setting lock mode. Parameter mode is not displayed if the operation is attempted in the reverse order.

■ Model, Input type, Unit and Input range

Immediately after the instrument is powered, the input type, the unit symbol and the input range will be displayed.

Example: Thermocouple input (type K) and -200 to +1372 °C

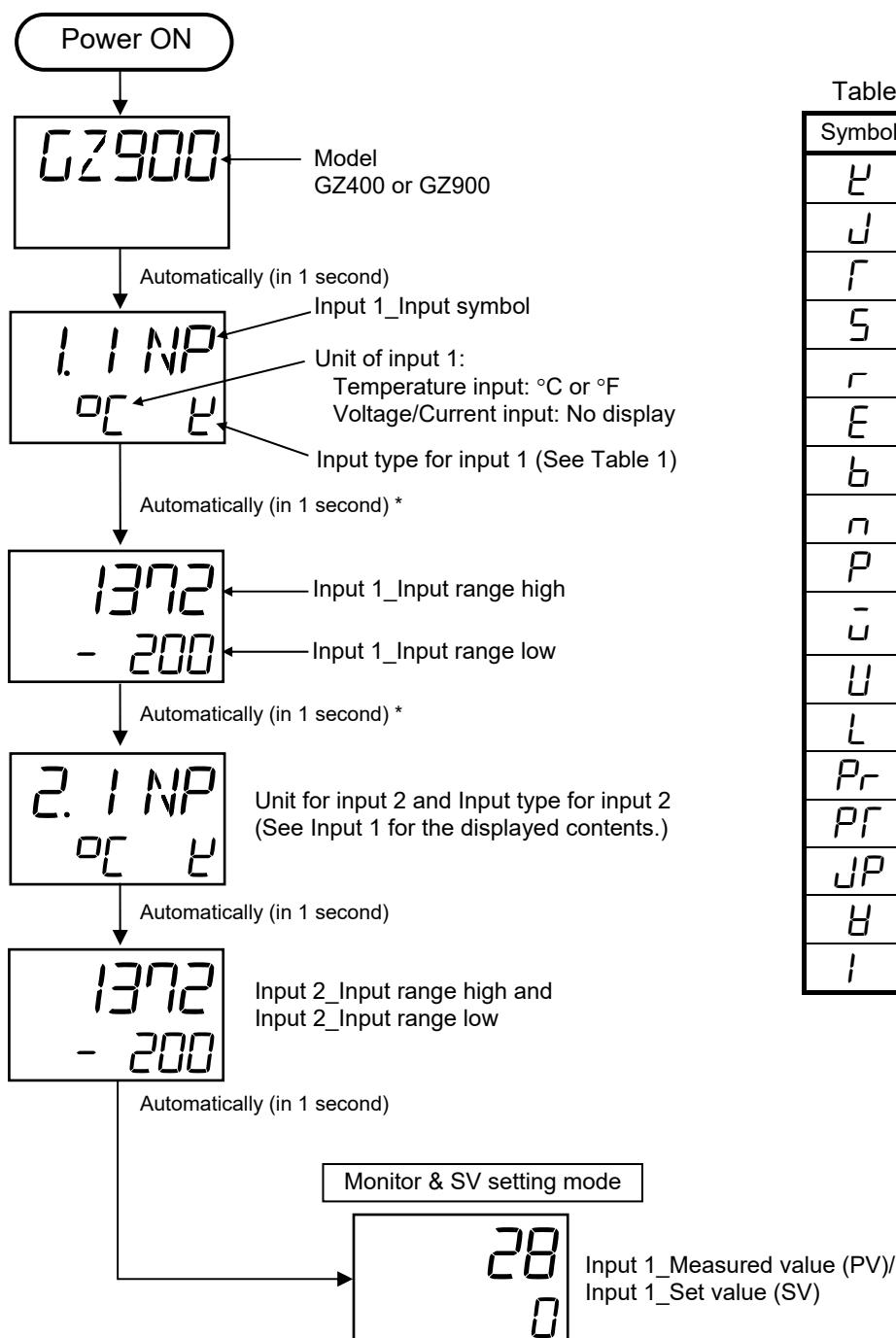


Table 1 Input type symbol

Symbol	Input type
<i>K</i>	Thermocouple K
<i>J</i>	Thermocouple J
<i>T</i>	Thermocouple T
<i>S</i>	Thermocouple S
<i>R</i>	Thermocouple R
<i>E</i>	Thermocouple E
<i>B</i>	Thermocouple B
<i>N</i>	Thermocouple N
<i>P</i>	Thermocouple PLII
<i>W</i>	Thermocouple W5Re/W26Re
<i>U</i>	Thermocouple U
<i>L</i>	Thermocouple L
<i>Pr</i>	Thermocouple PR40-20
<i>Pt</i>	RTD Pt100
<i>JPt</i>	RTD JPt100
<i>V</i>	Voltage
<i>I</i>	Current

* Displayed for 2 seconds (Single input type)

MEMO

2

SELECTING PARAMETERS

This chapter describes various parameter types and how to switch between them.

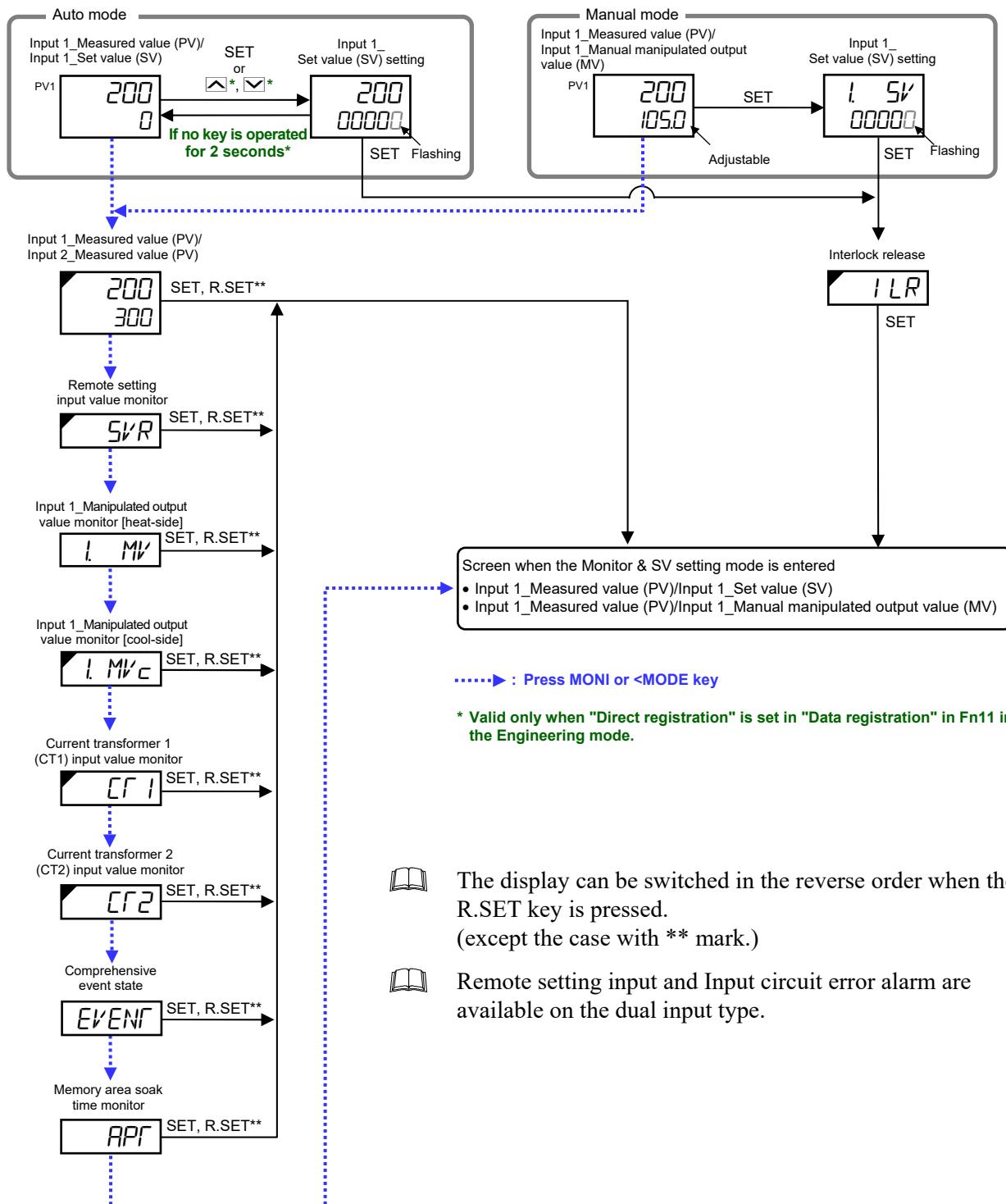
2.1 Monitor & SV Setting Mode [A].....	2-2
2.2 Parameter Select Mode [B]	2-6
2.3 Operation Transfer Mode [C].....	2-7
2.4 Setting Lock Mode [D].....	2-8
2.5 Memory Area Transfer Mode [E]	2-9
2-6 Parameter Setting Mode [F]	2-10
2.7 Setup Setting Mode [G].....	2-13
2.8 Engineering Mode [H]	2-16

2.1 Monitor & SV Setting Mode [A]

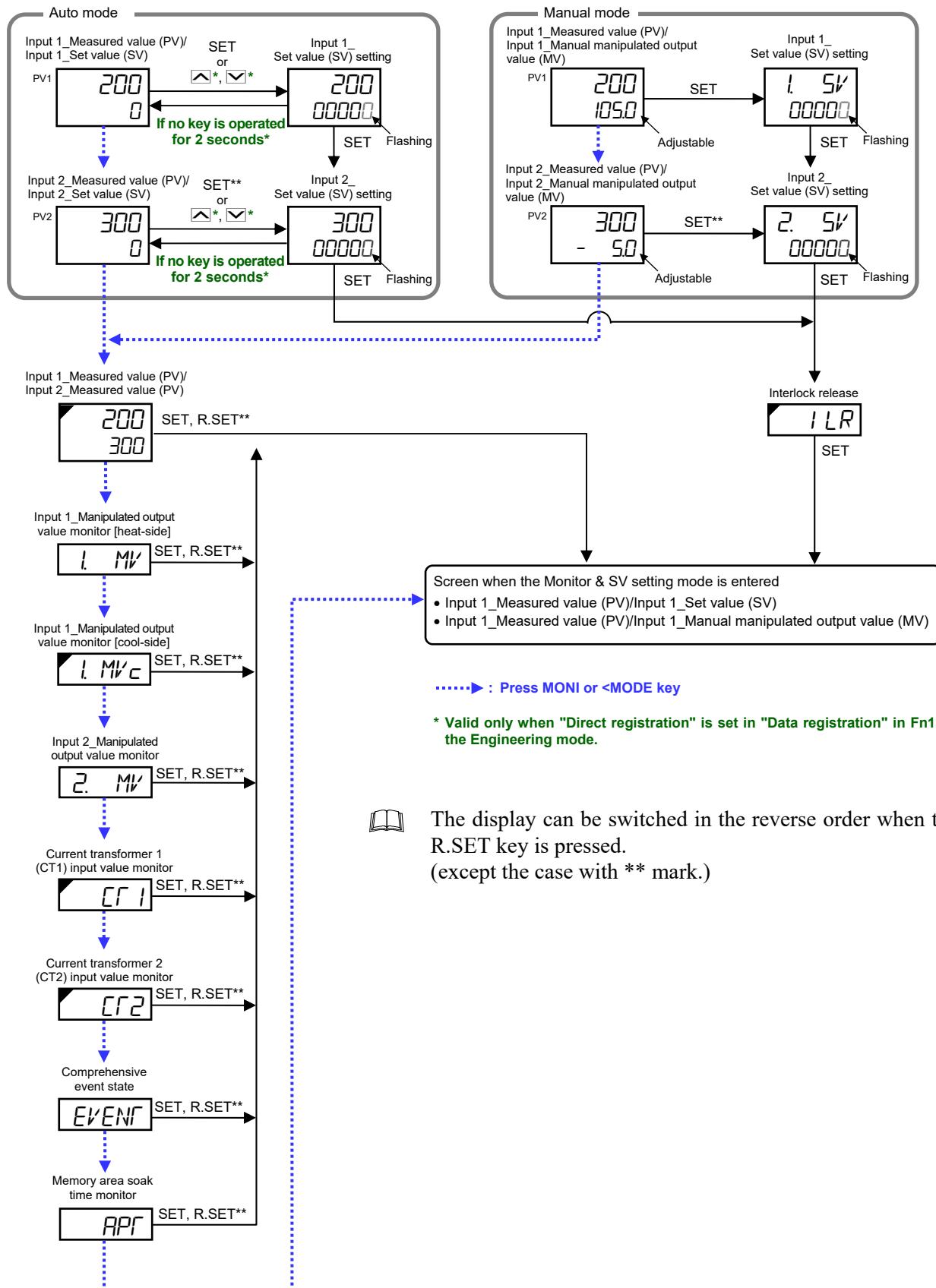
When the Monitor and SV setting mode is entered, there are 4 (four) display contents depending on the control. Each display also differs between the Auto mode and the Manual mode.

- 1-loop control (including Remote setting input/Input circuit error alarm)
- 2-loop control
- Control with PV select
- Differential temperature control

■ 1-loop control (including Remote setting input/Input circuit error alarm)

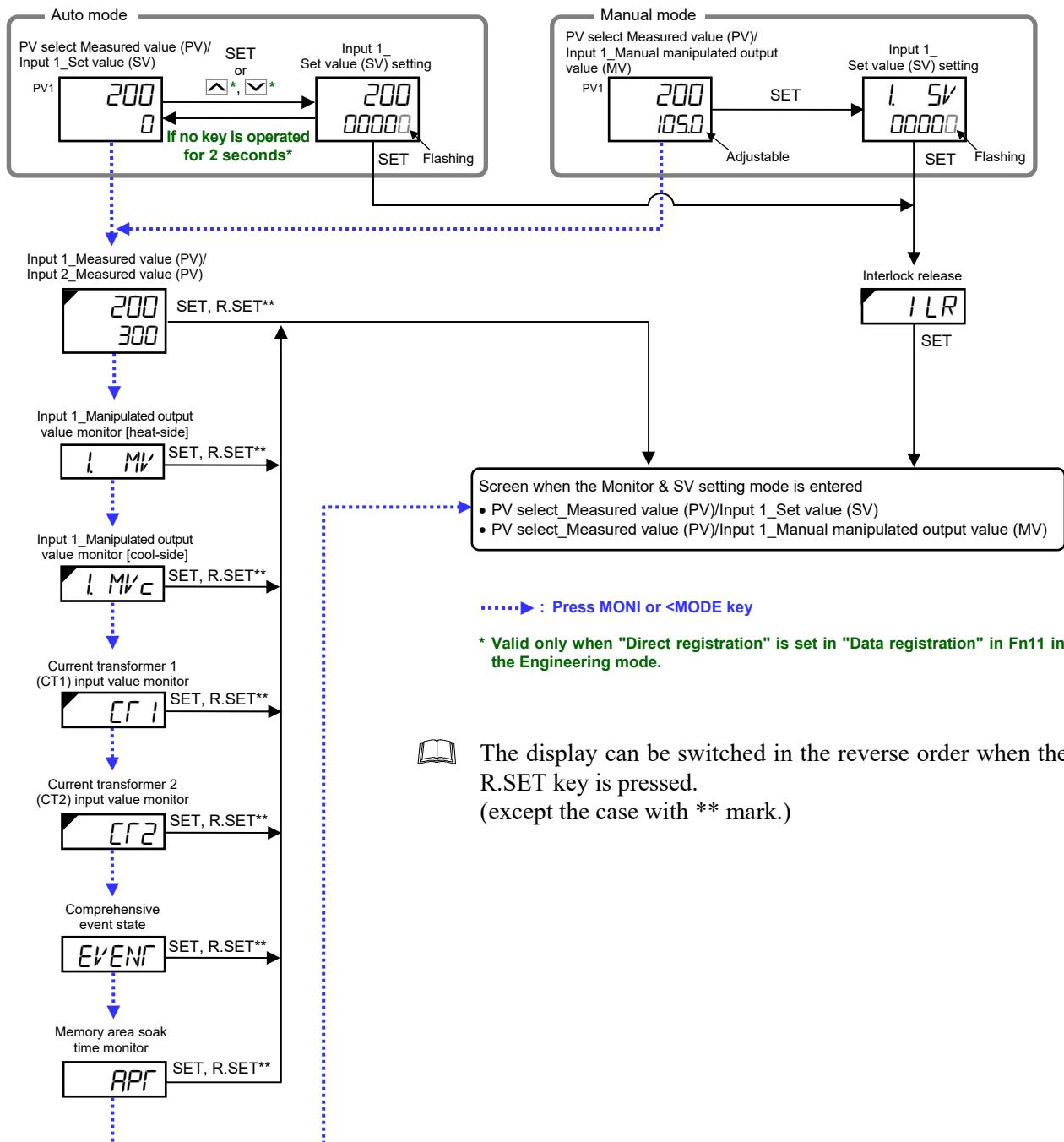


■ 2-loop control

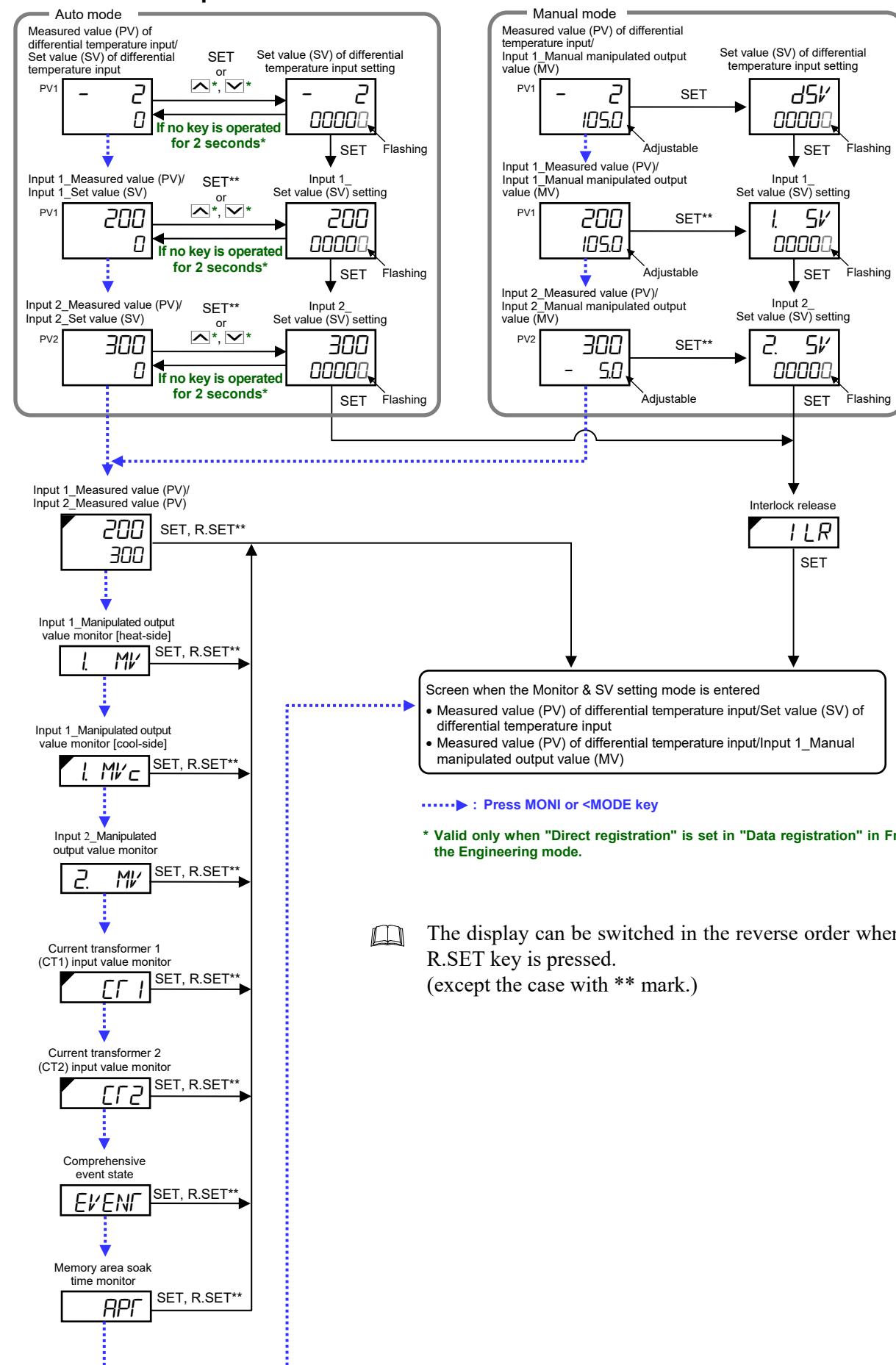


The display can be switched in the reverse order when the R.SET key is pressed.
(except the case with ** mark.)

■ Control with PV select

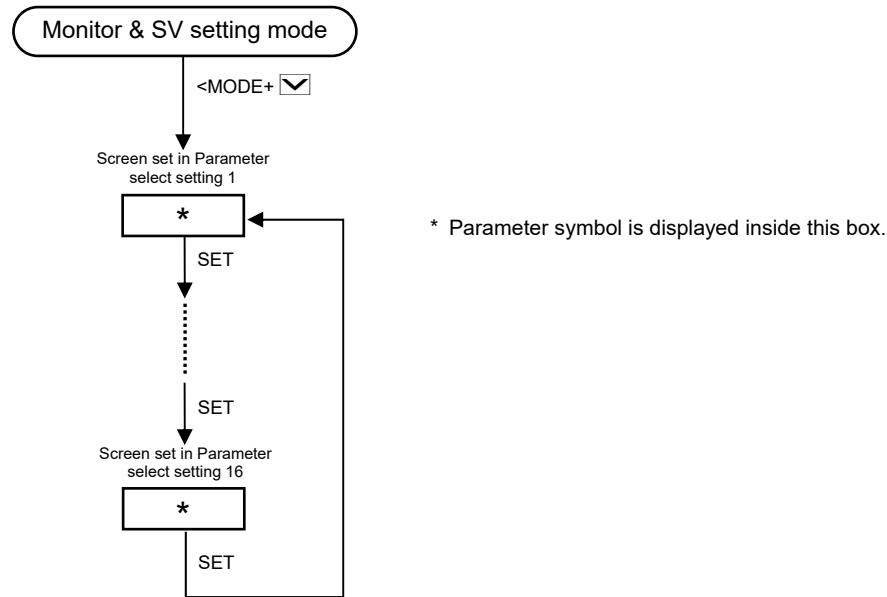


■ Differential temperature control



2.2 Parameter Select Mode [B]

Displays the screens registered in Parameter select setting.

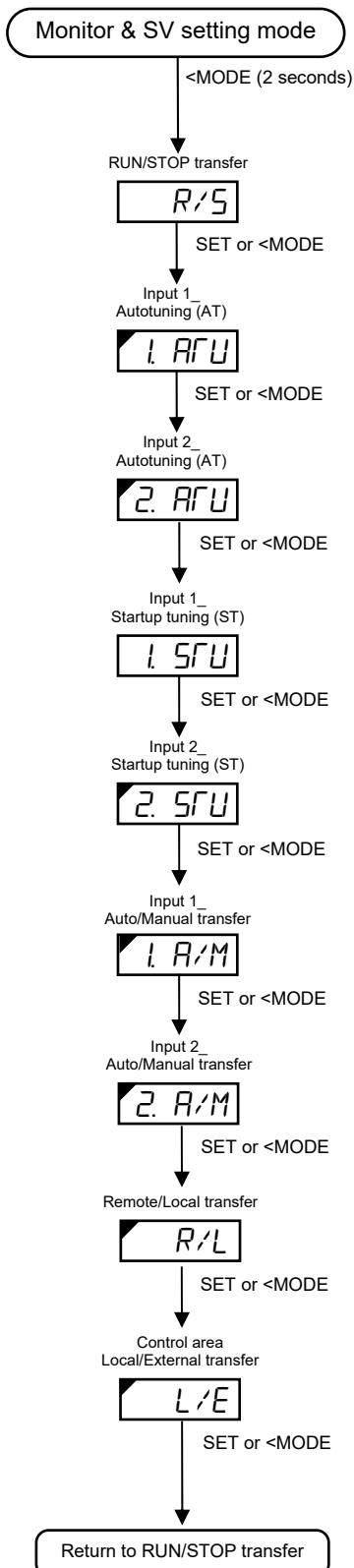


- The display can be switched in the reverse order when the R.SET key is pressed.
 - While the Blind function is valid, only Parameter select setting screen, Set data lock mode, and PV/SV monitor * screens are displayed. The instrument starts from the Parameter select mode after powered on.

* The PV/SV monitor includes SV setting mode and Manual manipulated output value setting.

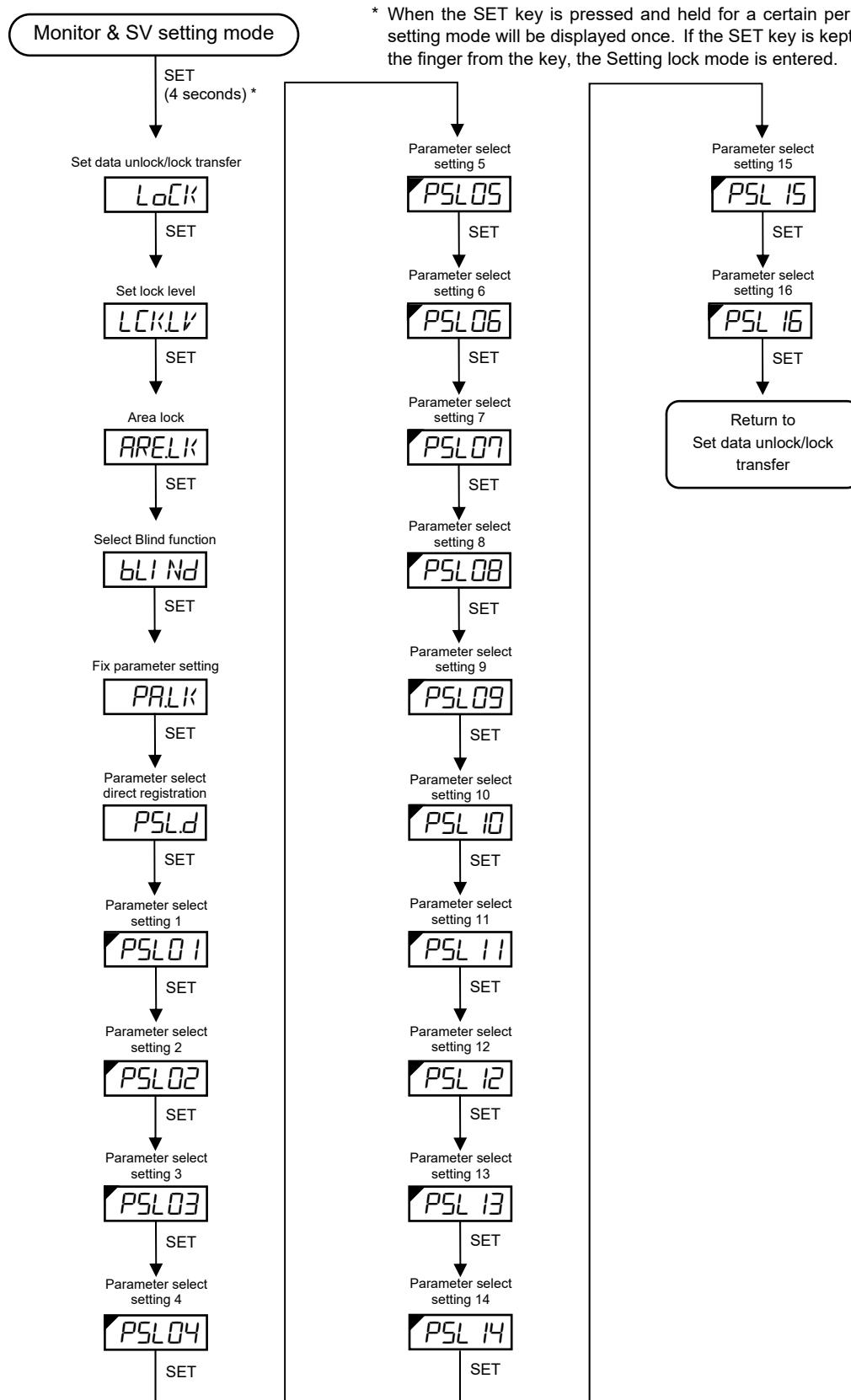
-  Pressing the MONI key somewhere in the Parameter select mode will bring you back to the top screen of the Parameter select mode.

2.3 Operation Transfer Mode [C]



The display can be switched in the reverse order when the R.SET key is pressed.

2.4 Setting Lock Mode [D]

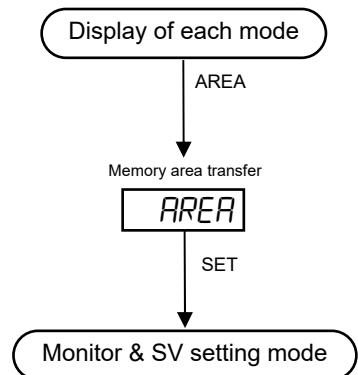


* When the SET key is pressed and held for a certain period of time, the Parameter setting mode will be displayed once. If the SET key is kept pressing without releasing the finger from the key, the Setting lock mode is entered.

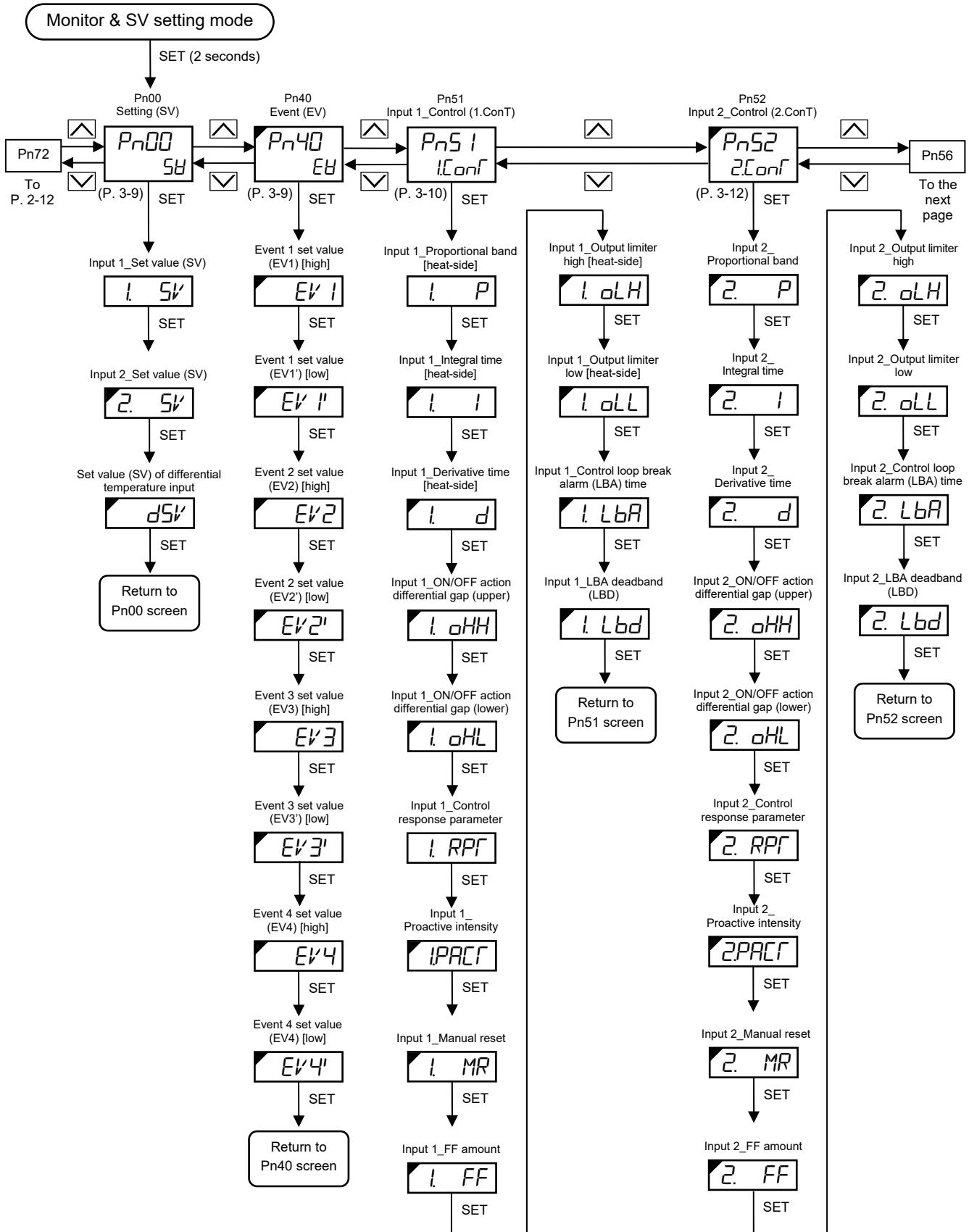


The display can be switched in the reverse order when the R.SET key is pressed. (Except the operation to enter the Set data lock)

2.5 Memory Area Transfer Mode [E]

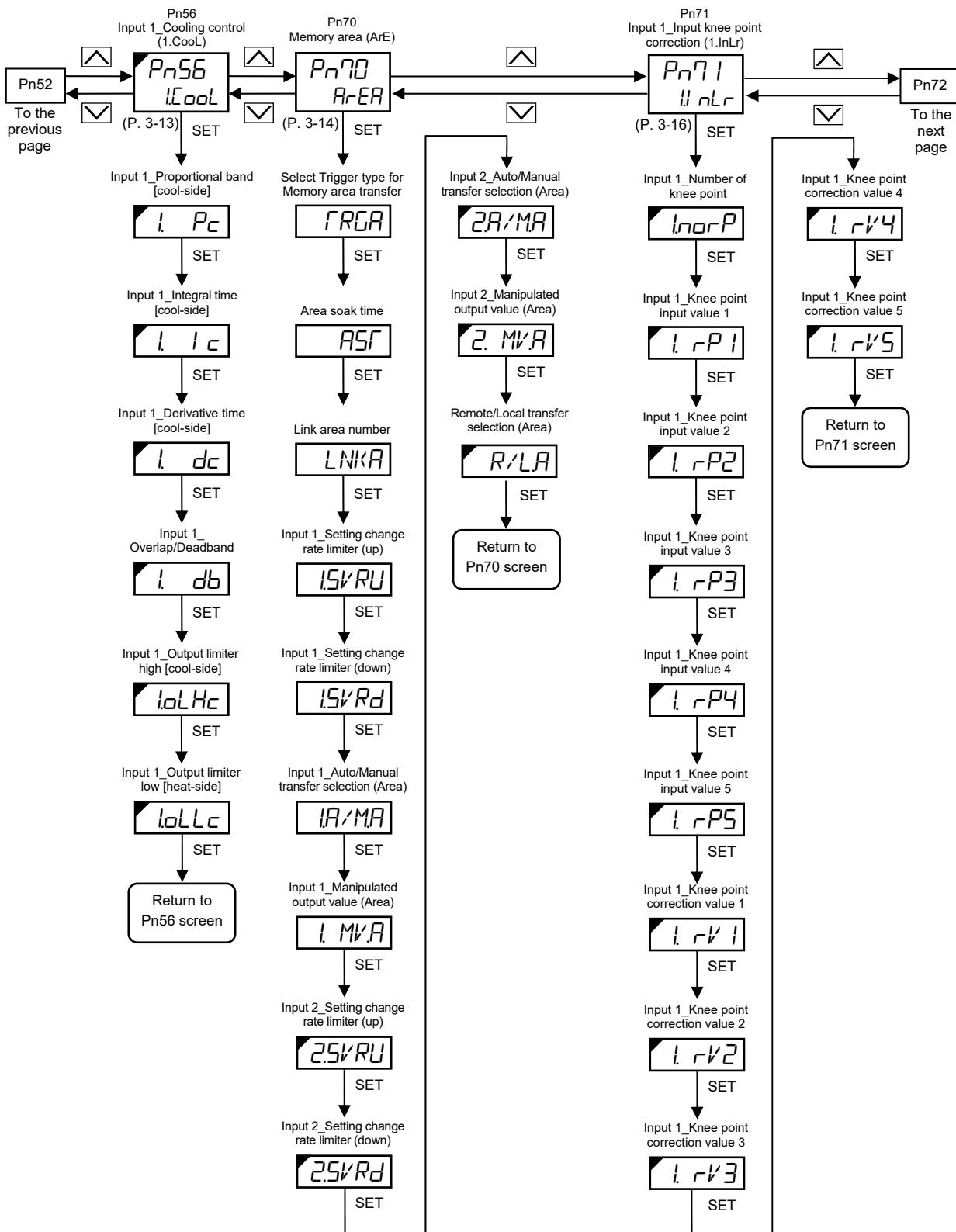


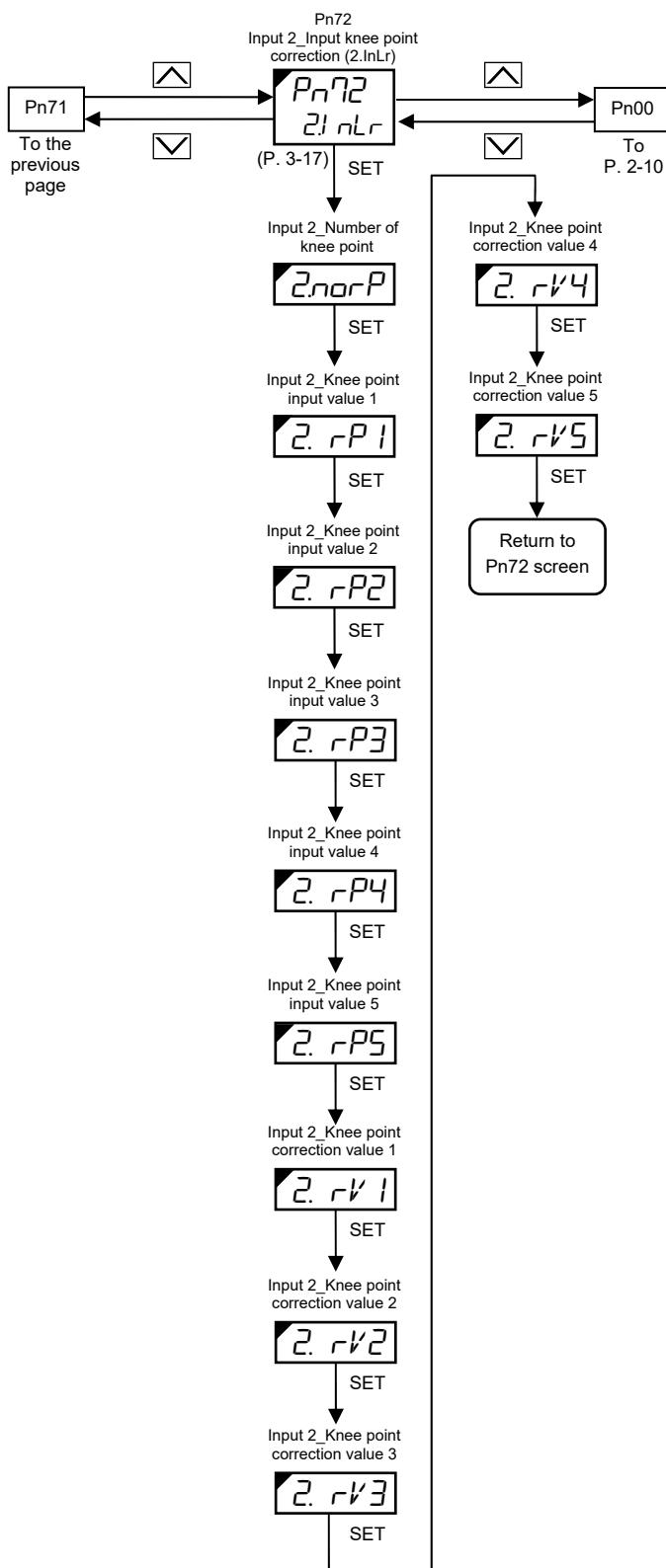
2.6 Parameter Setting Mode [F]



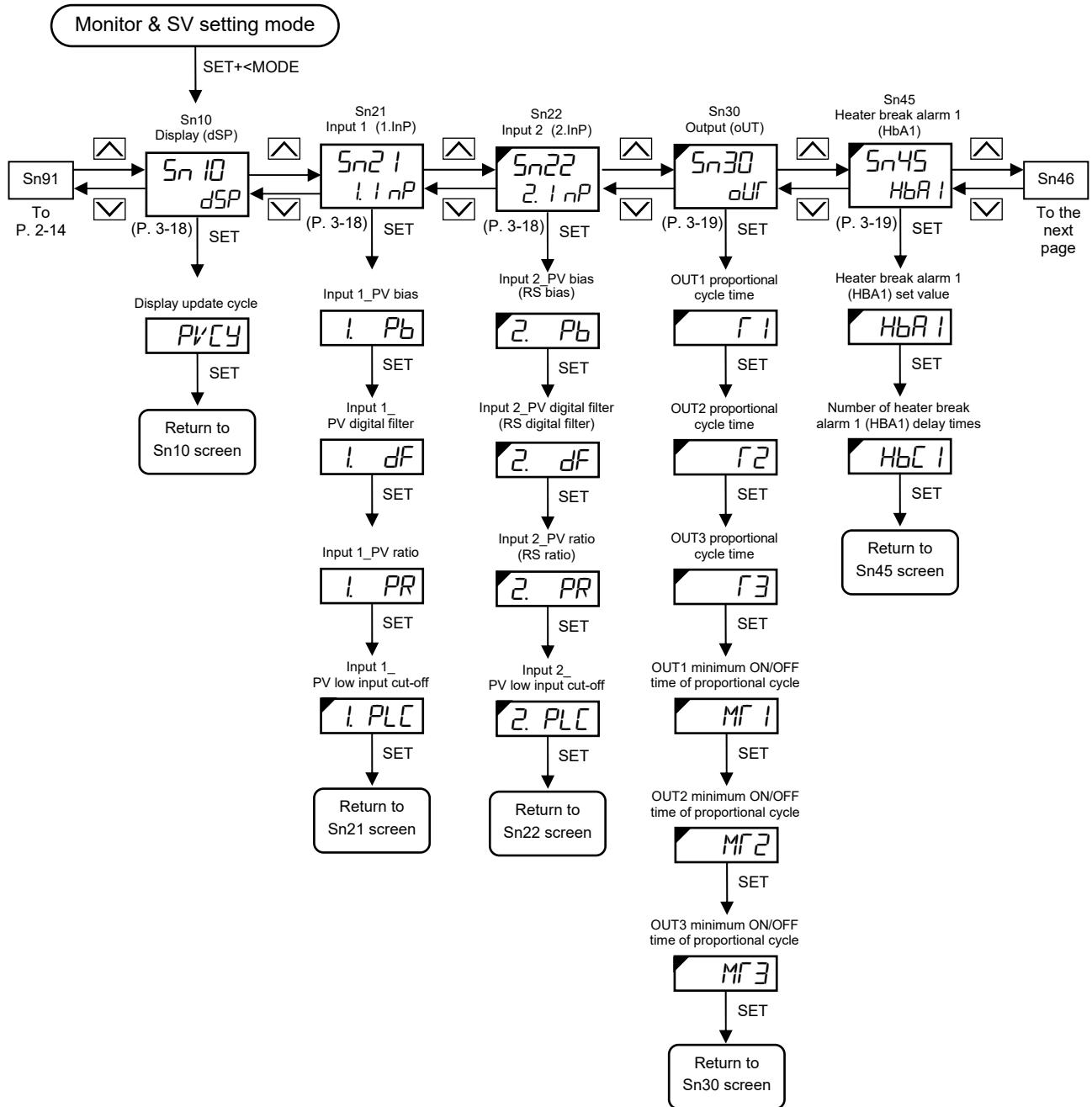


The display can be switched in the reverse order when the R.SET key is pressed. (Except the operation to enter the Set data lock)



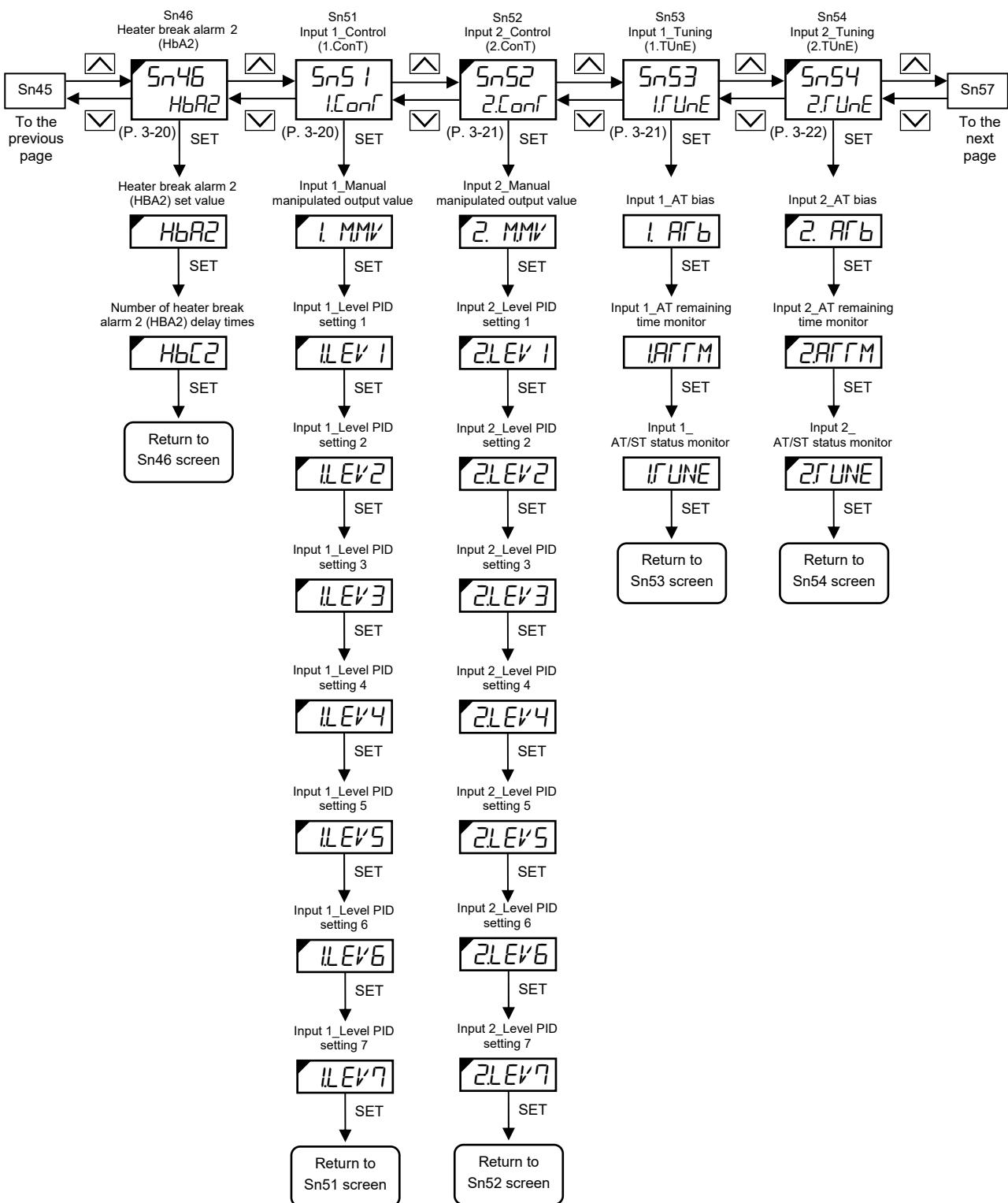


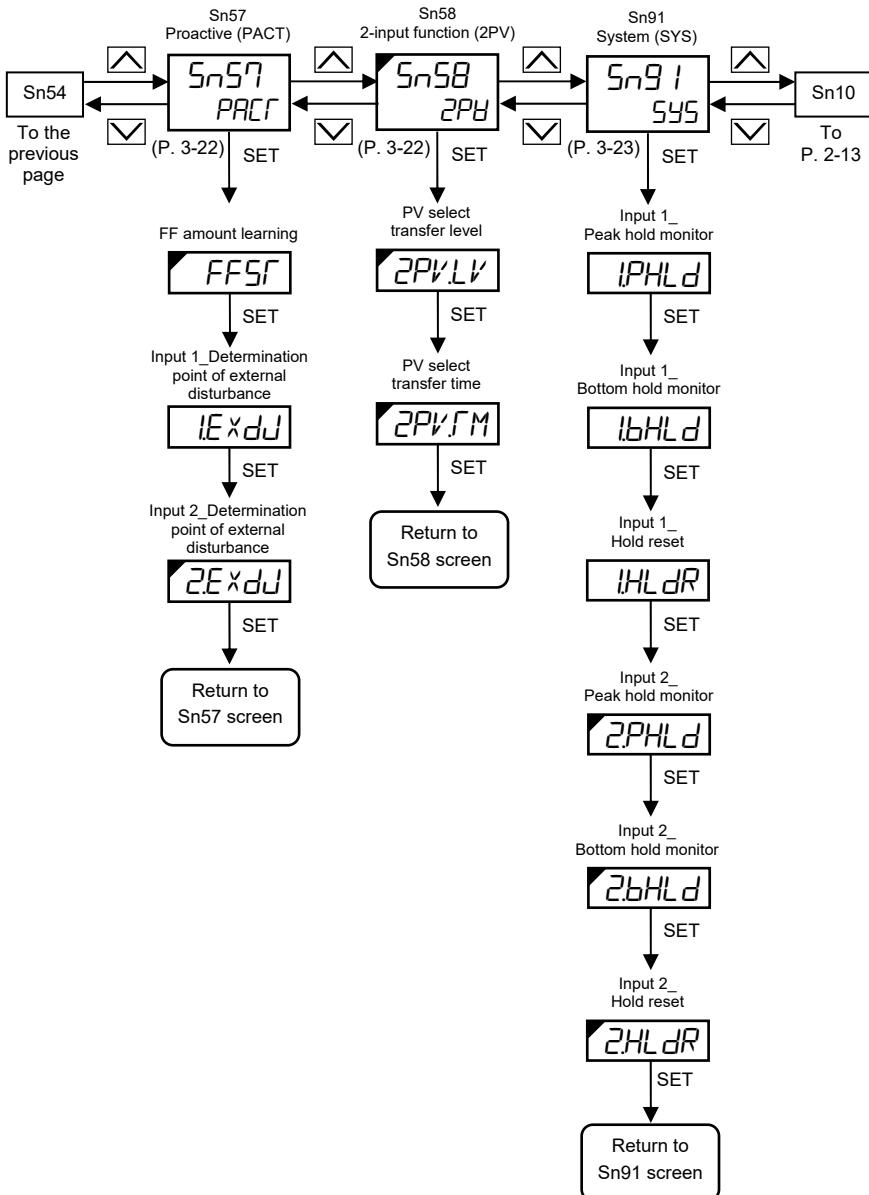
2.7 Setup Setting Mode [G]



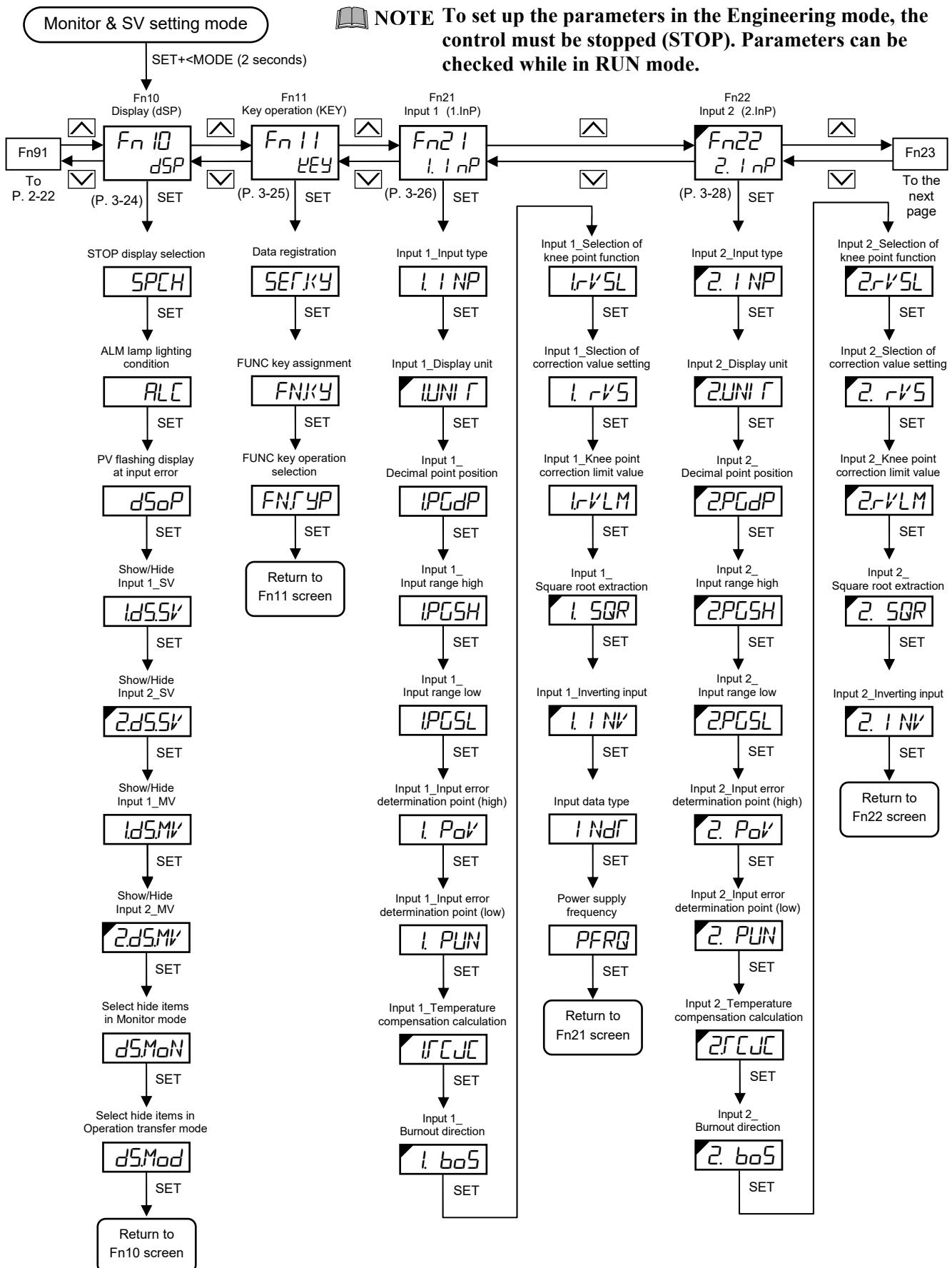


The display can be switched in the reverse order when the R.SET key is pressed.



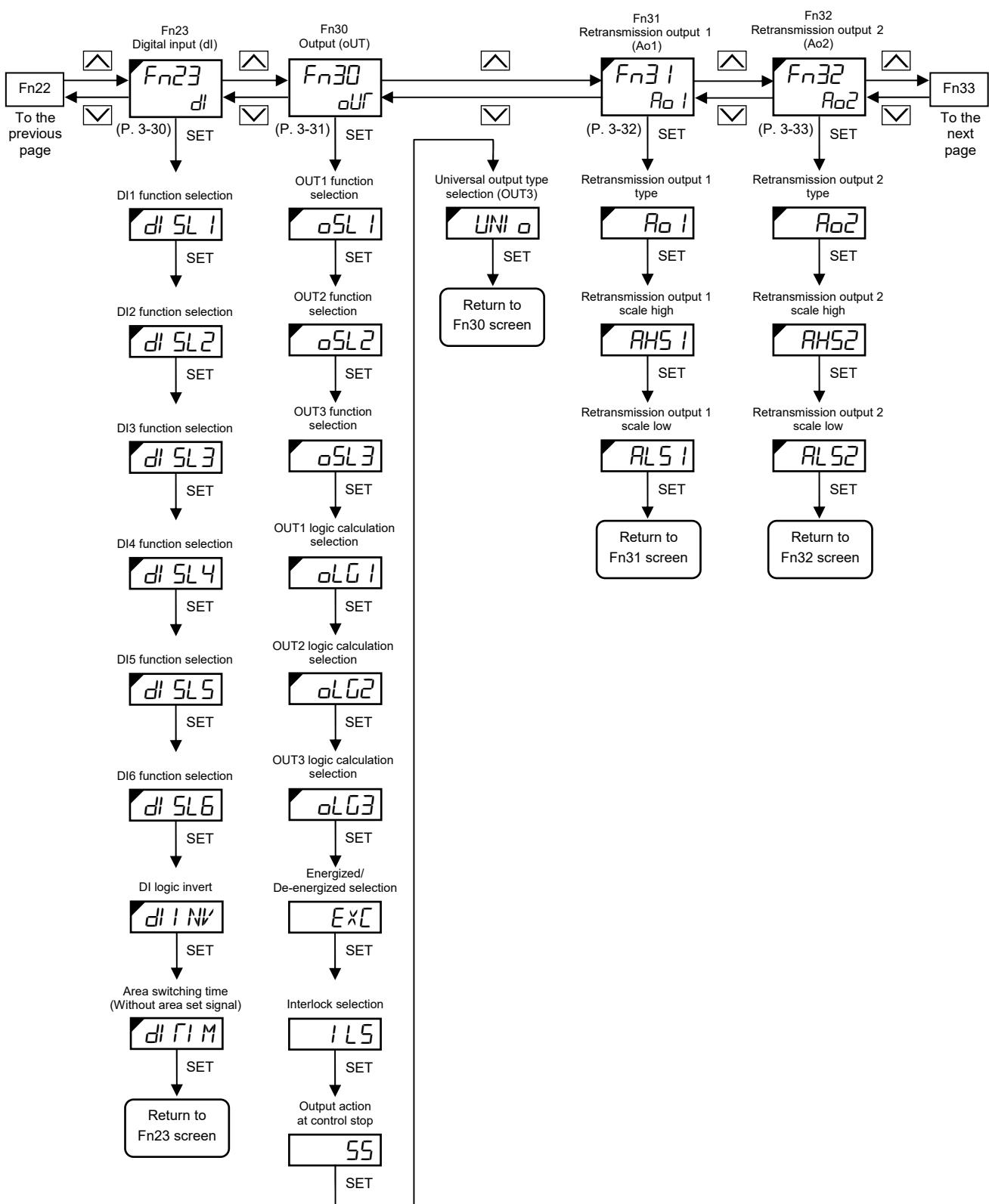


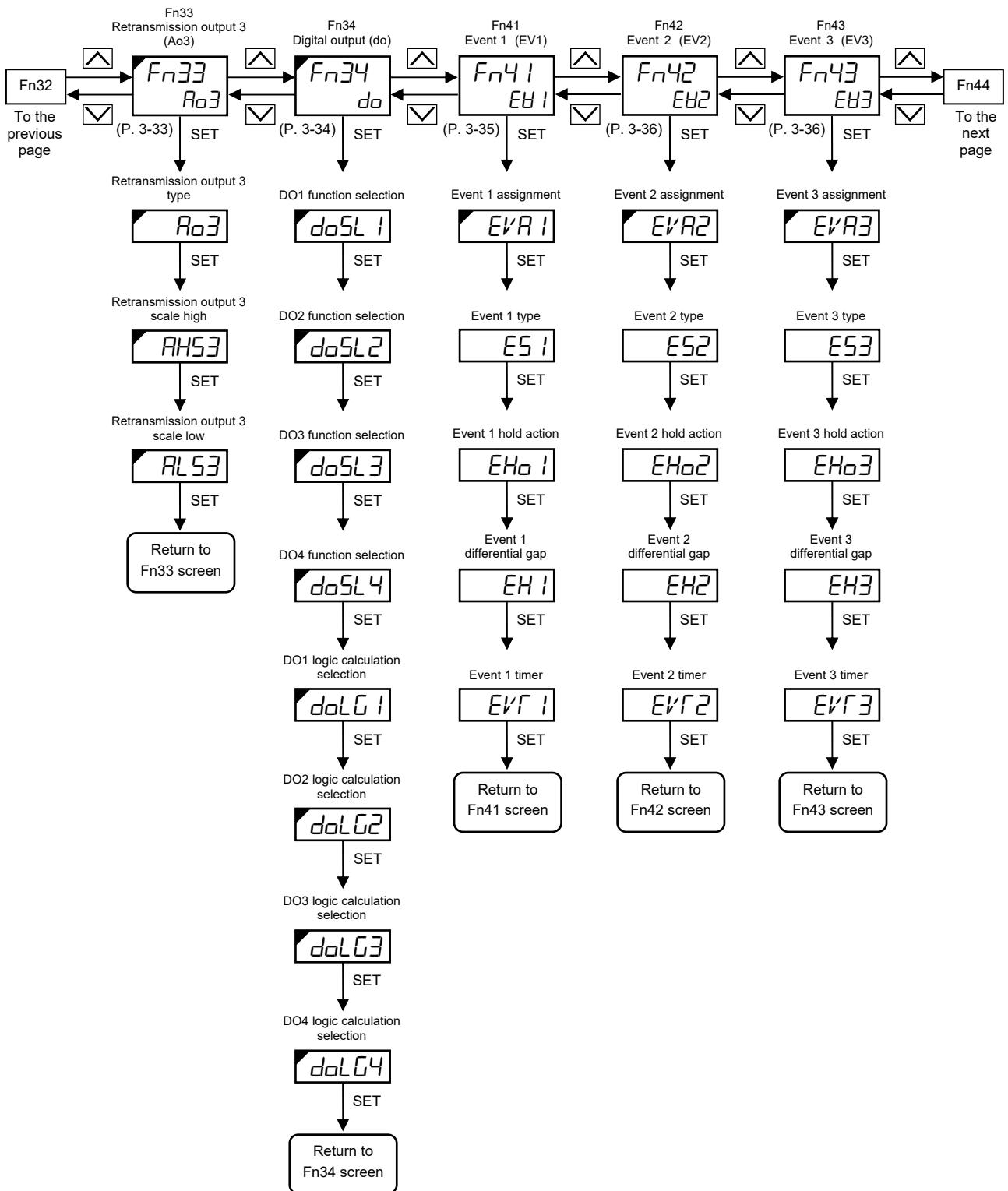
2.8 Engineering Mode [H]

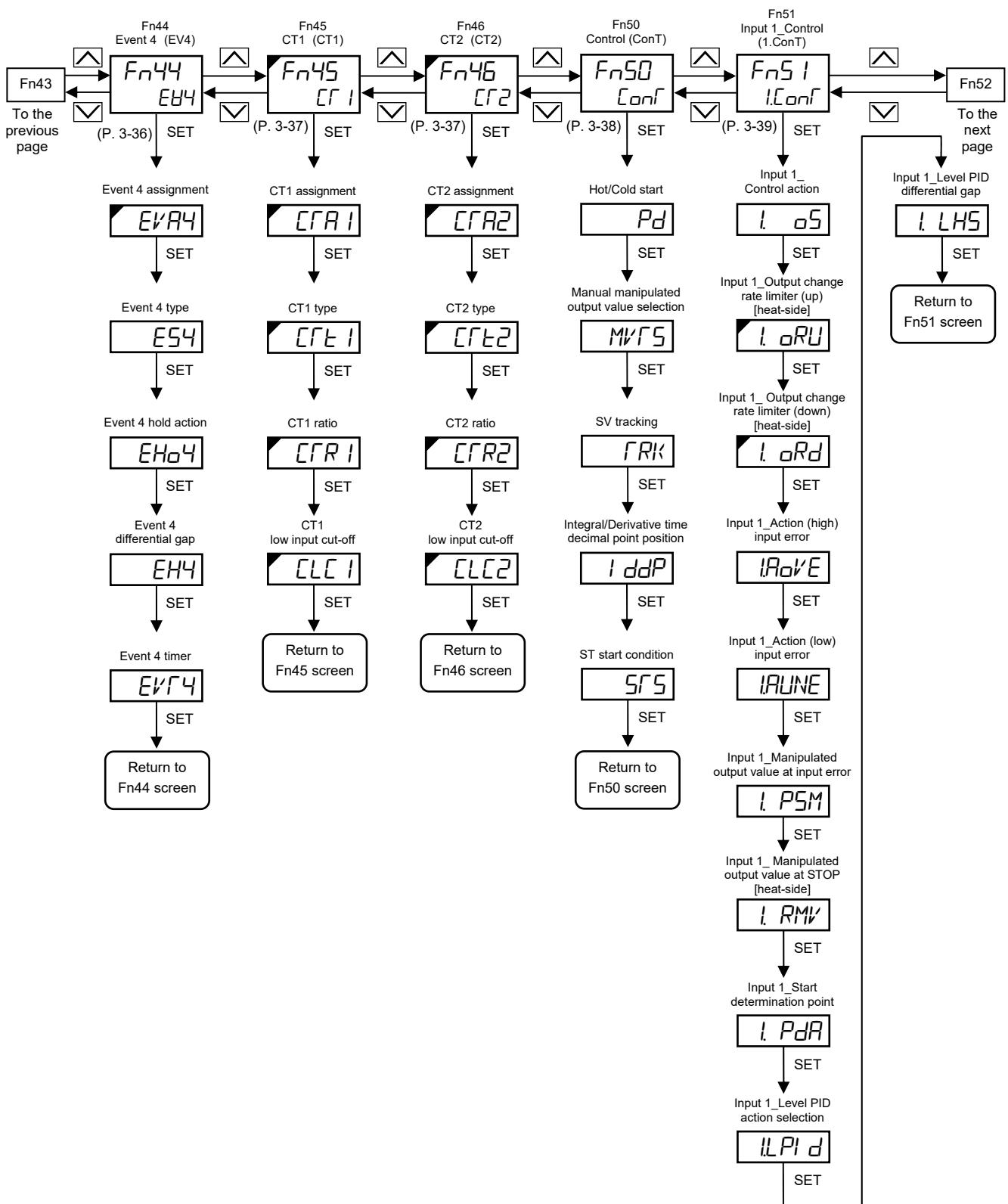


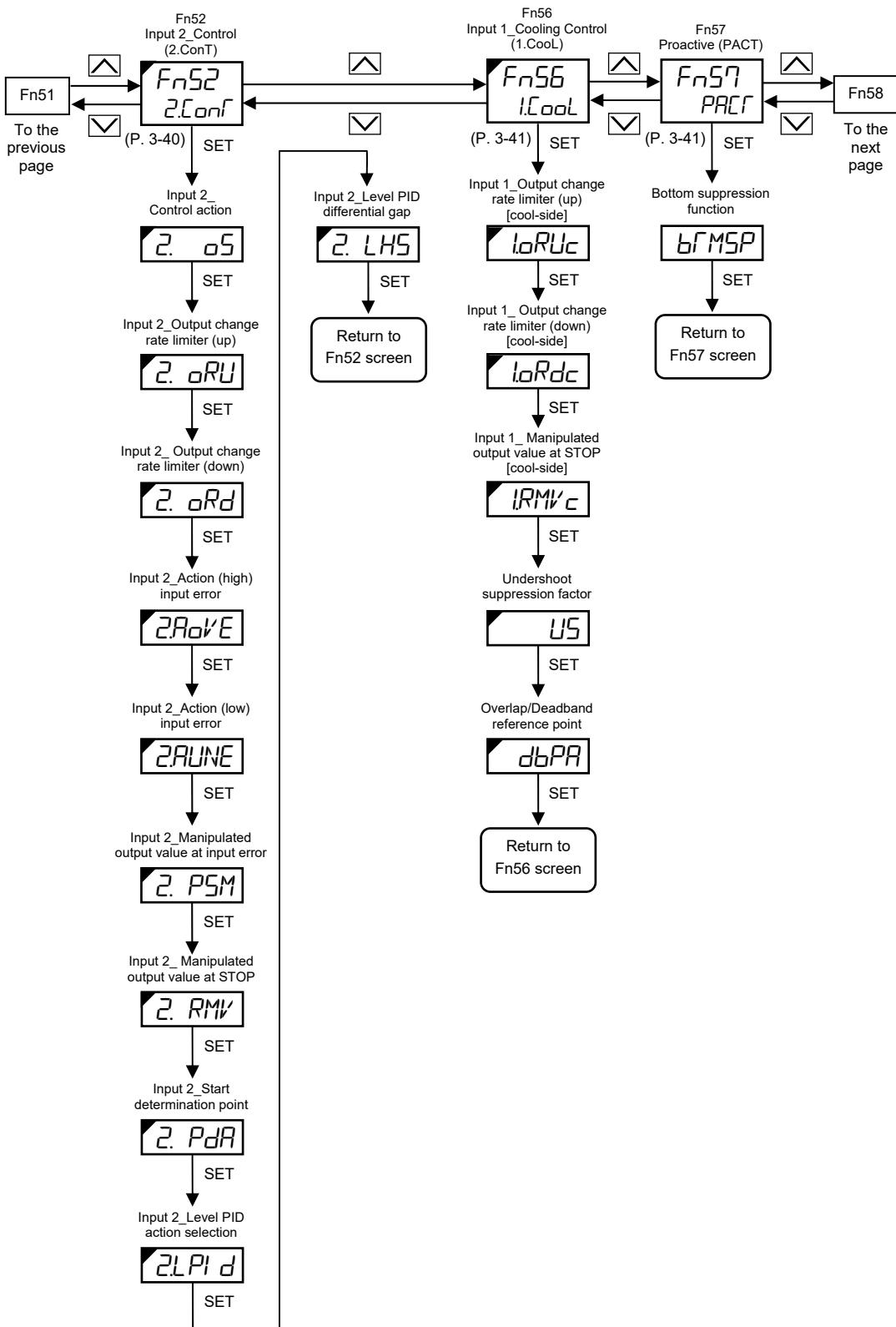


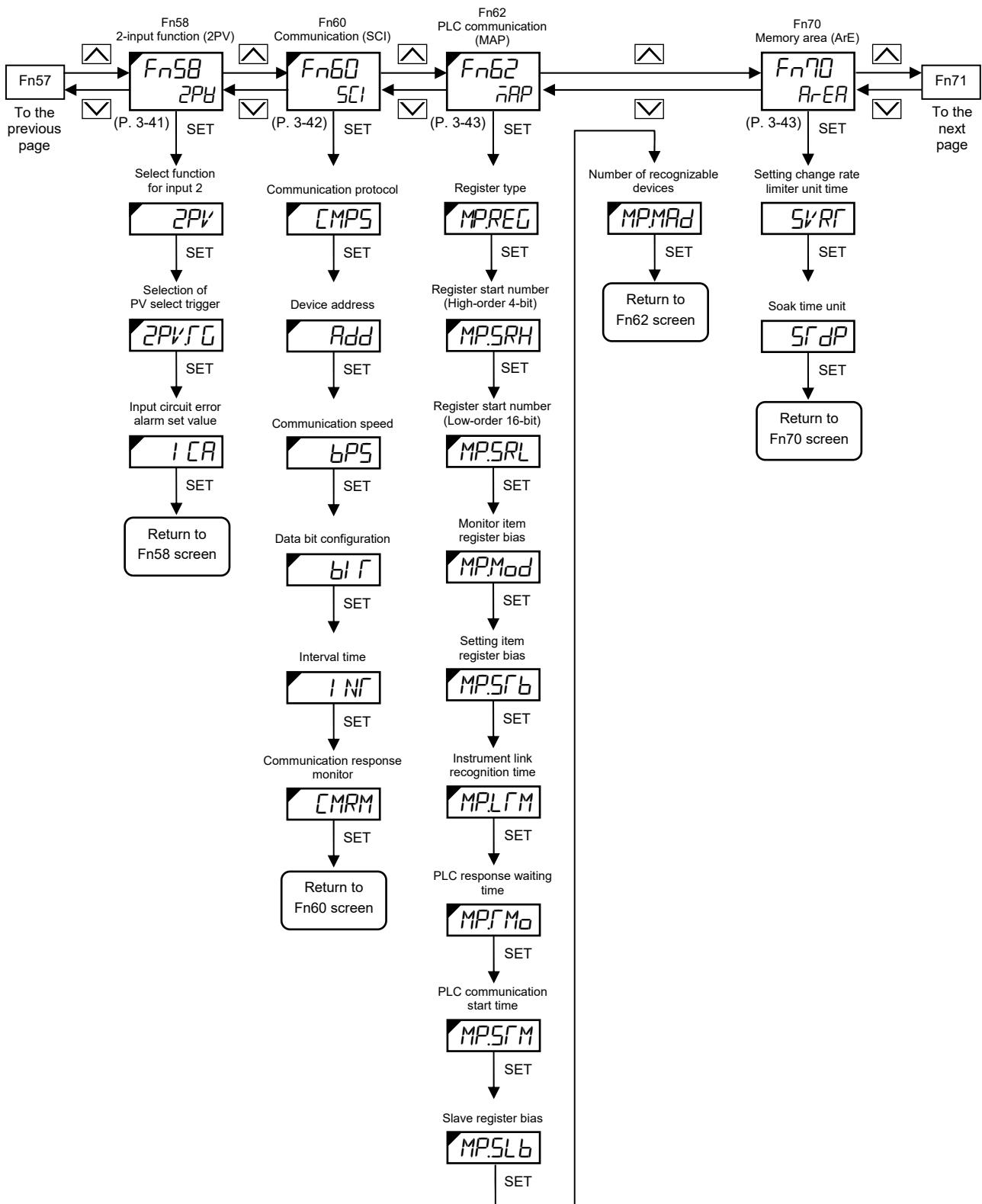
The display can be switched in the reverse order when the R.SET key is pressed.

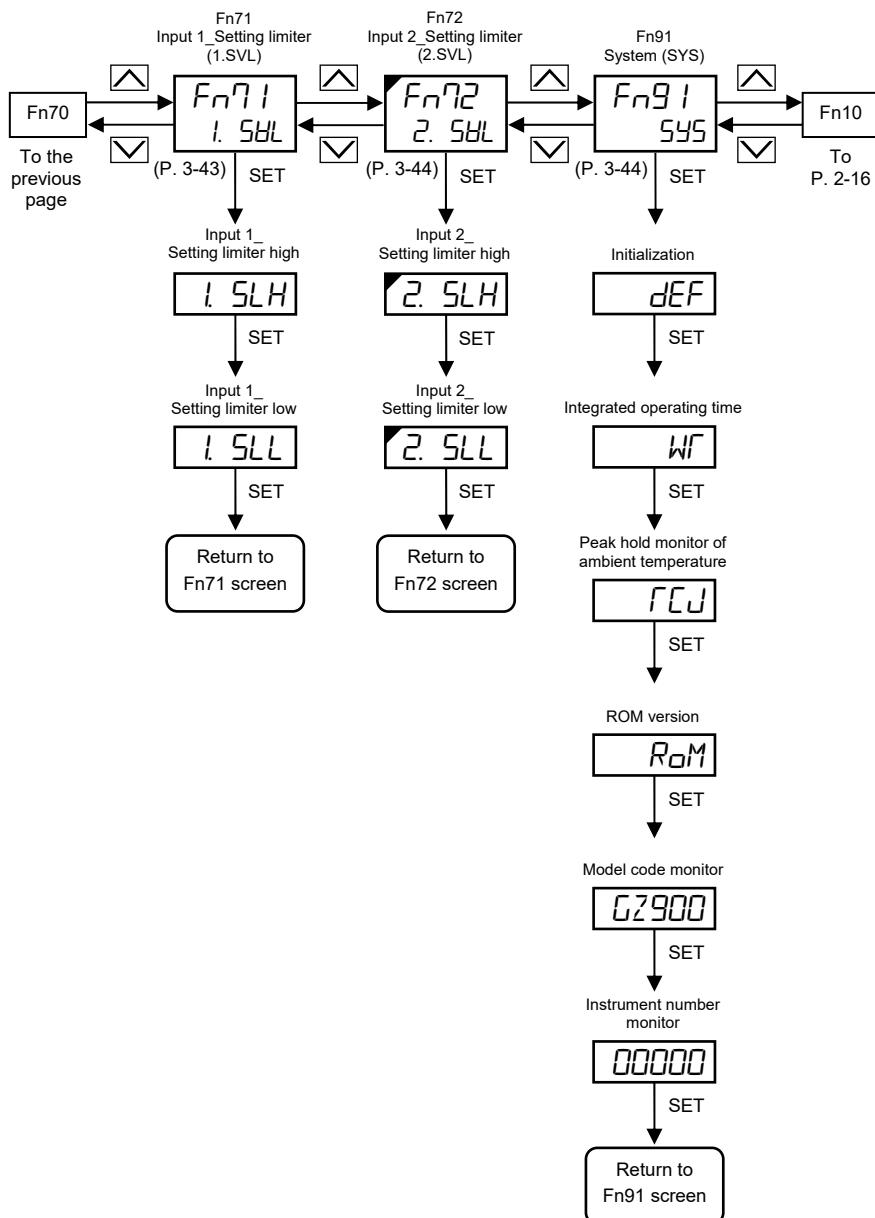












3

PARAMETER LIST

This chapter describes displays, names and data ranges of each parameter.

3.1 How to Read the Table	3-2
3.2 Monitor & SV Setting Mode [A].....	3-3
3.3 Parameter Select Mode [B]	3-5
3.4 Operation Transfer Mode [C].....	3-6
3.5 Setting Lock Mode [D]	3-7
3.6 Memory Area Transfer Mode [E]	3-8
3.7 Parameter Setting Mode [F]	3-9
3.8 Setup Setting Mode [G].....	3-18
3.9 Engineering Mode [H]	3-24

3.1 How to Read the Table

No.	Symbol	Name	Data range	Factory set value	User set value

- (1) **No. :** This is a screen number used to register screens displayed in the Parameter select mode. The screen number can be registered in the Parameter select setting screen. Parameters without the number can not be registered in Parameter select setting screen. If there are two items with the same number, one of them will be displayed according to the display requirements.
- (2) **Symbol:** 11-segment parameter symbols shown on the PV display.
- (3) **Name:** Name of parameter
- (4) **Data range:** Data range of parameter
- (5) **Factory set value:** Factory set value of parameters
- (6) **User set value:** Stores parameter values set by the user
This may be useful when the data is initialized.

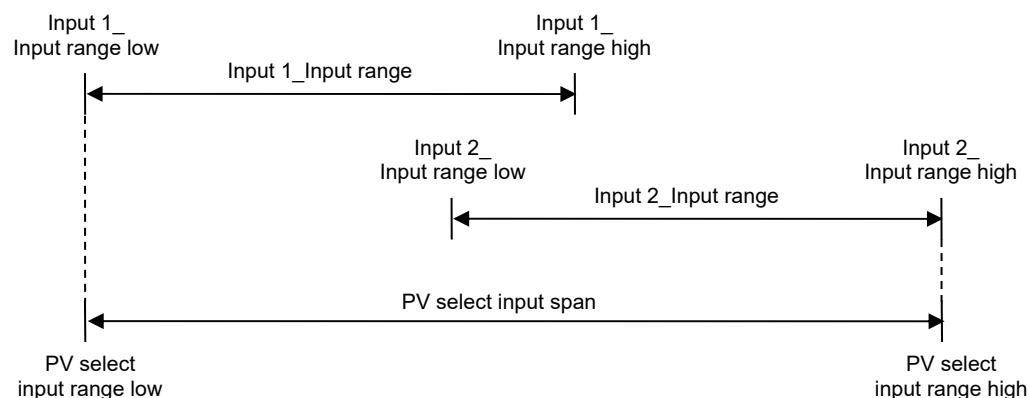


In the data range and the factory set value some unfamiliar expressions are used. These are used for Control with PV select and can be rephrased as follows:
 PV select input span as Input span
 PV select input range high as Input range high
 PV select input range low as Input range low

The setting range is as follows.

- PV select input range high: Input range high of Input 1 and Input 2, whichever is larger
- PV select input range low: Input range low of Input 1 and Input 2, whichever is smaller
- PV select input span: PV select input range low up to PV select input range high

[Example] When there is a relation as follows between the Input range of Input 1 and Input 2.



3.2 Monitor & SV Setting Mode [A]

No.	Symbol	Name	Data range	Factory set value	User set value
1	—	Input 1_Measured value (PV)/ Input 1_Set value (SV) ¹	PV display unit: Input 1_Input range low – (Input 1_5 % of input span) to Input 1_Input range high + (Input 1_5 % of input span) [Varies with the setting of the Decimal point position.] SV display unit ² : • Input 1_Set value (SV) (Auto mode: at RUN) • STOP display [S_{P} , dS_{P} , HS_{P}] • Remote setting input value (at Remote mode) • Input 1_Manual manipulated output value (at Manual mode)	—	—
1	—	PV select Measured value (PV)/ Input 1_Set value (SV) ³	PV display unit: When controlling with Input 1: Input 1_Input range low – (Input 1_5 % of input span) to Input 1_Input range high + (Input 1_5 % of input span) When controlling with Input 2: Input 2_Input range low – (Input 2_5 % of input span) to Input 2_Input range high + (Input 2_5 % of input span) [Varies with the setting of the Decimal point position.] SV display unit ² : • Input 1_Set value (SV) (Auto mode: at RUN) • STOP display [S_{P} , dS_{P} , HS_{P}] • Input 1_Manual manipulated output value (at Manual mode)	—	—
2	—	Input 2_Measured value (PV)/ Input 2_Set value (SV) ⁴	PV display unit: Input 2_Input range low – (Input 2_5 % of input span) to Input 2_Input range high + (Input 2_5 % of input span) [Varies with the setting of the Decimal point position.] SV display unit ¹ : • Input 2_Set value (SV) (Auto mode: at RUN) • STOP display [S_{P} , dS_{P} , HS_{P}] • Input 2_Manual manipulated output value (at Manual mode)	—	—

¹ Not displayed when "Control with PV select" is selected in "Select function for input 2."

² See the following table for the display range and the setting range of each data.

Display data	Data type	Data range
Input 1_Set value (SV)	Monitor/Setting	Input 1_Setting limiter low to Input 1_Setting limiter high
Input 2_Set value (SV)	Monitor/Setting	Input 2_Setting limiter low to Input 2_Setting limiter high
Remote setting input value	Monitor	Input 1_Setting limiter low to Input 1_Setting limiter high
Input 1_Manual manipulated output value	Setting	<ul style="list-style-type: none"> • In the case of PID control: Input 1_Output limiter low [heat-side] to Input 1_Output limiter high [heat-side] • In the case of Heat/Cool PID control: –Input 1_Output limiter low [cool-side] to +Input 1_Output limiter high [heat-side]
Input 2_Manual manipulated output value	Setting	Input 2_Output limiter low to Input 2_Output limiter high

³ Displayed when "Control with PV select" is selected in "Select function for input 2."

⁴ Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2."

Continued on the next page.

No.	Symbol	Name	Data range	Factory set value	User set value
3	—	Measured value (PV) of differential temperature input/ Set value (SV) of differential temperature input ¹	PV display unit: -19999 to +99999* or -1999 to +9999** * In case of Input data type 0 or 2 ** In case of Input data type 1 [Varies with the setting of the Decimal point position.] SV display unit: -(Input 1_Input span) to +(Input 1_Input span) [Varies with the setting of the Decimal point position.]	—	—
4	—	Input 1_Measured value (PV)/ Input 2_Measured value (PV) ²	PV display unit: Input 1_Input range low – (Input 1_5 % of input span) to Input 1_Input range high + (Input 1_5 % of input span) [Varies with the setting of the Decimal point position.] SV display unit: Input 2_Input range low – (Input 2_5 % of input span) to Input 2_Input range high + (Input 2_5 % of input span) [Varies with the setting of the Decimal point position.]	—	—
24	I. SV	Input 1_Set value (SV) ³	Input 1_Setting limiter low to Input 1_Setting limiter high ★ [Varies with the setting of the Decimal point position.]	0	
25	Z. SV	Input 2_Set value (SV) ^{3,4}	Input 2_Setting limiter low to Input 2_Setting limiter high ★ [Varies with the setting of the Decimal point position.]	0	
26	dSV	Set value (SV) of differential temperature input ^{1, 3}	-(Input 1_Input span) to +(Input 1_Input span) ★ [Varies with the setting of the Decimal point position.]	0	
5	SVR	Remote setting input value monitor ⁵	Input 1_Setting limiter low to Input 1_Setting limiter high [Varies with the setting of the Decimal point position.]	—	—
6	I. MV	Input 1_Manipulated output value monitor [heat-side]	-5.0 to +105.0 %	—	—
7	Z. MV	Input 1_Manipulated output value monitor [cool-side] ⁶	-5.0 to +105.0 %	—	—
8	Z. MV	Input 2_Manipulated output value monitor ⁷	-5.0 to +105.0 %	—	—
9	CT1	Current transformer 1 (CT1) input value monitor ⁸	0.0 to 100.0 A	—	—
10	CT2	Current transformer 2 (CT2) input value monitor ⁹	0.0 to 100.0 A	—	—
11	EVENF	Comprehensive event state	When an event occurs, the character of the occurring event is displayed on the Set value (SV) display unit. If two or more events occur at the same time, the relevant characters are displayed alternately every 0.5 seconds. EVR1: Event 1 EVR2: Event 2 EVR3: Event 3 EVR4: Event 4 HbR1: Heater break alarm 1 (HBA1) HbR2: Heater break alarm 2 (HBA2) LbR1: Control loop break alarm 1 (LBA1) LbR2: Control loop break alarm 2 (LBA2) I n I UP: Input 1_Input error high I n I dn: Input 1_Input error low I n2 UP: Input 2_Input error high I n2 dn: Input 2_Input error low	—	—

★ Data included in Memory area

¹ Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2" AND "Differential temperature control" is selected in "2-loop control/Differential temperature control."² Displayed when "2-loop control/Differential temperature control," "Control with PV select" or "Input circuit error alarm" is selected in "Select function for input 2."³ Displayed in Manual mode.⁴ Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2."⁵ Displayed when "Remote setting input" is selected in "Select function for input 2."⁶ Displayed when Input 1 is Heat/Cool PID control.⁷ Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2."⁸ Displayed when Current transformer (CT) input is supplied.⁹ Displayed when two Current transformer (CT) inputs are supplied.

Continued on the next page.

No.	Symbol	Name	Data range	Factory set value	User set value
12	<i>RPT</i>	Memory area soak time monitor	0 hours 00 minutes 00 seconds to 9 hours 59 minutes 59 seconds* 0 hours 00 minutes to 99 hours 59 minutes 0 minutes 00 seconds to 199 minutes 59 seconds 0.00 seconds to 59.99 seconds (Calculation is performed every 50ms.) * Displayed only when the input data type is 0 or 2. [Data range of Memory area soak time monitor can be selected on the Soak time unit.]	—	—
13	<i>ILR</i>	Interlock release *	<i>oFF</i> : Interlock release <i>on</i> : Interlock state	<i>oFF</i>	

¹ Displayed when Interlock function is valid.

3.3 Parameter Select Mode [B]

Up to 16 screens registered on the Parameter select setting screen (Set data lock mode) by the user can be displayed.

3.4 Operation Transfer Mode [C]

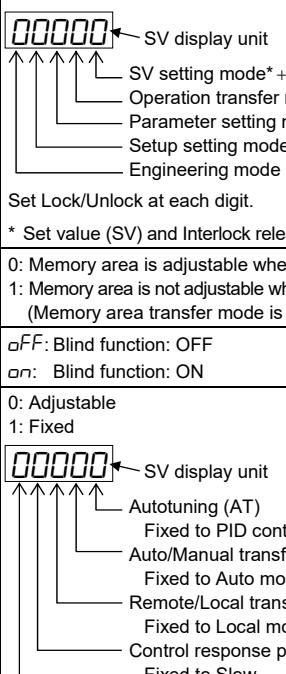
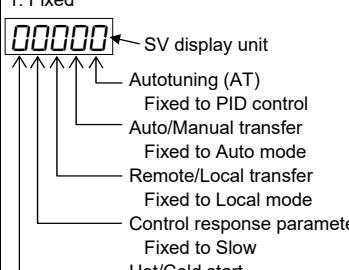
No.	Symbol	Name	Data range	Factory set value	User set value
15	R/S	RUN/STOP transfer	rUn: RUN (Control start) StoP: STOP (Control stop)	rUn	
16	I. RfU	Input 1_Autotuning (AT) ¹	oFF: PID control on: Start Autotuning When the Autotuning (AT) is finished, the control will automatically return to "oFF."	oFF	
17	2. RfU	Input 2_Autotuning (AT) ^{1,2}	oFF: PID control on: Start Autotuning When the Autotuning (AT) is finished, the control will automatically return to "oFF."	oFF	
18	I. StoU	Input 1_Startup tuning (ST)	oFF: ST unused on I: Execute once * on2: Execute always * When the ST is finished, the control will automatically return to "oFF."	oFF	
19	2. StoU	Input 2_Startup tuning (ST) ²	oFF: ST unused on I: Execute once * on2: Execute always * When the ST is finished, the control will automatically return to "oFF."	oFF	
20	I. R/M	Input 1_Auto/Manual transfer ¹	RfUo: Auto mode nRn: Manual mode	RfUo	
21	2. R/M	Input 2_Auto/Manual transfer ^{1,2}	RfUo: Auto mode nRn: Manual mode	RfUo	
22	R/L	Remote/Local transfer ^{1,3}	<ul style="list-style-type: none"> When "Remote setting input" is selected at Select function for Input 2⁴ LoC: Local mode REn: Remote mode When "Control with PV select" is selected at Select function for input 2⁵ InP I: Input 1 InP2: Input 2 When "2-loop control/Differential temperature control" is selected at Select function for input 2¹ 2Loop: 2-loop control dI FF: Differential temperature control 	LoC InP I 2Loop	
23	L/E	Control area Local/External transfer ⁶	LoC: Local mode EYF: External mode	LoC	

¹ Not displayed when "Fixed" is selected in Fix parameter setting.² Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2."³ Displayed when any of the following is selected in Select function for input 2: "Remote setting input," "Control with PV select," or "2-loop control/Differential temperature control."⁴ Displayed when "Remote setting input" is selected in "Select function for input 2."⁵ Displayed when "Control with PV select" is selected in "Select function for input 2."

When "Switching by level" is selected at "Selection of PV select trigger," the parameter becomes display only.

⁶ Displayed when "Memory area transfer (without area set signal)" is selected in DI function selection.

3.5 Setting Lock Mode [D]

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>LOCK</i>	Set data unlock/lock transfer	<i>OFF</i> : Unlock state <i>on</i> : Lock state	<i>OFF</i>	
—	<i>LOCKLV</i>	Set lock level	0: Unlock 1: Lock  Set Lock/Unlock at each digit. * Set value (SV) and Interlock release	00000	
—	<i>ARE.Lock</i>	Area lock	0: Memory area is adjustable when the setting data is locked. 1: Memory area is not adjustable when the setting data is locked. (Memory area transfer mode is not displayed)	0	
—	<i>BLIND</i>	Select Blind function	<i>OFF</i> : Blind function: OFF <i>on</i> : Blind function: ON	<i>OFF</i>	
—	<i>PRLK</i>	Fix parameter setting	0: Adjustable 1: Fixed  Independently set parameters to be fixed at each digit.	00000	
—	<i>PSL.D</i>	Parameter select direct registration	<i>OFF</i> : Direct registration: OFF <i>on</i> : Direct registration: ON	<i>OFF</i>	
—	<i>PSL01</i>	Parameter select setting 1	0 to 313 (Screen No.) 0: No registration	0	
—	<i>PSL02</i>	Parameter select setting 2	0 to 313 (Screen No.) 0: No registration	0	
—	<i>PSL03</i>	Parameter select setting 3	0 to 313 (Screen No.) 0: No registration	0	
—	<i>PSL04</i>	Parameter select setting 4	0 to 313 (Screen No.) 0: No registration	0	
—	<i>PSL05</i>	Parameter select setting 5	0 to 313 (Screen No.) 0: No registration	0	
—	<i>PSL06</i>	Parameter select setting 6	0 to 313 (Screen No.) 0: No registration	0	
—	<i>PSL07</i>	Parameter select setting 7	0 to 313 (Screen No.) 0: No registration	0	
—	<i>PSL08</i>	Parameter select setting 8	0 to 313 (Screen No.) 0: No registration	0	
—	<i>PSL09</i>	Parameter select setting 9	0 to 313 (Screen No.) 0: No registration	0	
—	<i>PSL10</i>	Parameter select setting 10	0 to 313 (Screen No.) 0: No registration	0	
—	<i>PSL11</i>	Parameter select setting 11	0 to 313 (Screen No.) 0: No registration	0	
—	<i>PSL12</i>	Parameter select setting 12	0 to 313 (Screen No.) 0: No registration	0	
—	<i>PSL13</i>	Parameter select setting 13	0 to 313 (Screen No.) 0: No registration	0	

Continued on the next page.

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>PSL 14</i>	Parameter select setting 14	0 to 313 (Screen No.) 0: No registration	0	
—	<i>PSL 15</i>	Parameter select setting 15	0 to 313 (Screen No.) 0: No registration	0	
—	<i>PSL 16</i>	Parameter select setting 16	0 to 313 (Screen No.) 0: No registration	0	

3.6 Memory Area Transfer Mode [E]

No.	Symbol	Name	Data range	Factory set value	User set value
14	<i>AREAR</i>	Memory area transfer *	1 to 16	1	

* This parameter is display only (not settable) if "Memory area transfer (without area set signal)" is selected in DI function selection AND "External mode" is selected in "Control area Local/External transfer."

Not displayed when "Memory area is not adjustable when the setting data is locked" is selected in Area lock.

3.7 Parameter Setting Mode [F]

■ Parameter group No. 00: Setting (SH)

No.	Symbol	Name	Data range	Factory set value	User set value
—	Pn00	Parameter group No. 00	This is the first parameter symbol of Parameter group No. 00.	—	—
24	I. SV	Input 1_Set value (SV) ★	Input 1_Setting limiter low to Input 1_Setting limiter high [Varies with the setting of the Decimal point position.]	0	
25	2. SV	Input 2_Set value (SV) ¹ ★	Input 2_Setting limiter low to Input 2_Setting limiter high [Varies with the setting of the Decimal point position.]	0	
26	dSV	Set value (SV) of differential temperature input ² ★	-(Input 1_Input span) to +(Input 1_Input span) [Varies with the setting of the Decimal point position.]	0	

★ Data included in Memory area

¹ Displayed when “2-loop control/Differential temperature control” is selected in “Select function for input 2.”

² Displayed when “2-loop control/Differential temperature control” is selected in “Select function for input 2” AND “Differential temperature control” is selected in “2-loop control/Differential temperature control.”

■ Parameter group No. 40: Event (EH)

No.	Symbol	Name	Data range	Factory set value	User set value
—	Pn40	Parameter group No. 40 ¹	This is the first parameter symbol of Parameter group No. 40.	—	—
27	EV 1	Event 1 set value (EV1) ² Event 1 set value (EV1) [high] ^{2,3} ★	<u>Deviation:</u> • When assigned to Input_1 or Differential temperature input -(Input 1_Input span) to +(Input 1_Input span) • When assigned to Input 2 -(Input 2_Input span) to +(Input 2_Input span) • When Control with PV select is selected at Select function for input 2. -(PV select input span) to +(PV select input span) [Varies with the setting of the Decimal point position.] <u>Input value or Set value:</u> • When assigned to Input 1 Input 1_Input range low to Input 1_Input range high • When assigned to Input 2 Input 2_Input range low to Input 2_Input range high • When assigned to Differential temperature input -(Input 1_Input span) to +(Input 1_Input span) • When Control with PV select is selected at Select function for input 2. PV select input range low to PV select input range high [Varies with the setting of the Decimal point position.] <u>Manipulated output value:</u> -5.0 to +105.0 %	For Deviation, Input value and Set value: TC/RTD inputs: 10 V/I inputs: 5 % of input span For Manipulated output value: 50.0	
28	EV 1'	Event 1 set value (EV1') [low] ^{2,3} ★	<u>Deviation:</u> • When assigned to Input_1 or Differential temperature input -(Input 1_Input span) to +(Input 1_Input span) • When assigned to Input 2 -(Input 2_Input span) to +(Input 2_Input span) • When Control with PV select is selected at Select function for input 2. -(PV select input span) to +(PV select input span) <u>Input value or Set value:</u> • When assigned to Input 1 Input 1_Input range low to Input 1_Input range high • When assigned to Input 2 Input 2_Input range low to Input 2_Input range high • When assigned to Differential temperature input -(Input 1_Input span) to +(Input 1_Input span) • When Control with PV select is selected at Select function for input 2. PV select input range low to PV select input range high [Varies with the setting of the Decimal point position.]	TC/RTD inputs: -10 V/I inputs: -5 % of input span	

★ Data included in Memory area

¹ Displayed when the Event function is valid.

² Displayed when Event 1 is valid.

³ Displayed when Event 1 type is high/low with individual setting.

Continued on the next page.

No.	Symbol	Name	Data range	Factory set value	User set value
29	<i>EV2</i>	Event 2 set value (EV2) ¹ Event 2 set value (EV2) [high] ^{1, 2} ★	Same as Event 1 set value (EV1)/Event 1 set value (EV1) [high]		
30	<i>EV2'</i>	Event 2 set value (EV2') [low] ^{1, 2} ★	Same as Event 1 set value (EV1') [low]		
31	<i>EV3</i>	Event 3 set value (EV3) ³ Event 3 set value (EV3) [high] ^{3, 4} ★	Same as Event 1 set value (EV1)/Event 1 set value (EV1) [high]		
32	<i>EV3'</i>	Event 3 set value (EV3') [low] ^{3, 4} ★	Same as Event 1 set value (EV1') [low]		
33	<i>EV4</i>	Event 4 set value (EV4) ⁵ Event 4 set value (EV4) [high] ^{5, 6} ★	Same as Event 1 set value (EV1)/Event 1 set value (EV1) [high]		
34	<i>EV4'</i>	Event 4 set value (EV4') [low] ^{5, 6} ★	Same as Event 1 set value (EV1') [low]		

★ Data included in Memory area

¹ Displayed when Event 2 is valid.² Displayed when Event 2 type is high/low with individual setting.³ Displayed when Event 3 is valid.⁴ Displayed when Event 3 type is high/low with individual setting.⁵ Displayed when Event 4 is valid.⁶ Displayed when Event 4 type is high/low with individual setting.

■ Parameter group No. 51: Input 1_Control (*I.Conf*)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Pn5_1</i>	Parameter group No. 51	This is the first parameter symbol of Parameter group No. 51	—	—
35	<i>I. P</i>	Input 1_Proportional band [heat-side] ★	TC/RTD inputs: 0 (0.0, 0.00) to Input 1_Input span (Unit: °C [°F]) (When Control with PV select: 0 to PV select input span) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.0 to 1000.0 % of Input 1_Input span (When Control with PV select: 0.0 to 1000.0 % of PV select input span) 0 (0.0, 0.00): ON/OFF action	TC/RTD inputs: 30 V/I inputs: 3.0	
36	<i>I. I</i>	Input 1_Integral time [heat-side] ¹ ★	PID control or Heat/Cool PID control: 0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds 0 (0.0, 0.00, 0.000): PD action [Varies with the setting of the Integral/Derivative time decimal point position.]	240.00	
37	<i>I. d</i>	Input 1_Derivative time [heat-side] ¹ ★	0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds 0 (0.0, 0.00, 0.000): PI action [Varies with the setting of the Integral/Derivative time decimal point position.]	60.00	

★ Data included in Memory area

¹ Displayed when the "Input 1_Proportional band [heat-side]" in the same memory area is other than 0 (0.0).

Continued on the next page.

No.	Symbol	Name	Data range	Factory set value	User set value
38	<i>I. oHH</i>	Input 1_ON/OFF action differential gap (upper) ¹	TC/RTD inputs: 0 (0.0, 0.00) to Input 1_Input span (Unit: °C [°F]) (When Control with PV select: 0 to PV select input span) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.0 to 100.0 % of Input 1_Input span (When Control with PV select: 0.0 to 100.0 % of PV select input span)	TC/RTD inputs: 1 V/I inputs: 0.1	
39	<i>I. oHL</i>	Input 1_ON/OFF action differential gap (lower) ¹	TC/RTD inputs: 0 (0.0, 0.00) to Input 1_Input span (Unit: °C [°F]) (When Control with PV select: 0 to PV select input span) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.0 to 100.0 % of Input 1_Input span (When Control with PV select: 0.0 to 100.0 % of PV select input span)	TC/RTD inputs: 1 V/I inputs: 0.1	
40	<i>I. RPF</i>	Input 1_Control response parameter	0: Slow 1: Medium 2: Fast ★ [When the P or PD action is selected, this setting becomes invalid]	PID control: 0 Heat/Cool PID control: 2	
41	<i>I.PRCF</i>	Input 1_Proactive intensity ^{2,3}	0 to 4 ★ 0: No function	2	
42	<i>I. MR</i>	Input 1_Manual reset ^{2,4}	-100.0 to +100.0 % ★	0.0	
43	<i>I. FF</i>	Input 1_FF amount ^{1,3,5}	-100.0 to +100.0 % ★	0.0	
44	<i>I. oLH</i>	Input 1_Output limiter high [heat-side]	Input 1_Output limiter low [heat-side] to 105.0 % ★	105.0	
45	<i>I. oLL</i>	Input 1_Output limiter low [heat-side]	-5.0 % to Input 1_Output limiter high [heat-side] ★	-5.0	
46	<i>I. LbA</i>	Input 1_Control loop break alarm (LBA) time	0 to 7200 seconds 0: No function ★	LBA function is specified: 480 LBA function is not specified: 0	
47	<i>I. Lbd</i>	Input 1_LBA deadband (LBD)	0 to Input 1_Input span (When Control with PV select: 0 to PV select input span) [Varies with the setting of the Decimal point position.] ★	0	

★ Data included in Memory area

¹ Displayed when the "Input 1_Proportional band [heat-side]" in any memory area is 0 (0.0, 0.00). (Common setting in memory area)

² Displayed when the "Input 1_Proportional band [heat-side]" in the same memory area is other than 0 (0.0, 0.00).

³ Displayed when the "Input 1_Integral time [heat-side]" in the same memory area is other than 0 (0.0, 0.00, 0.000).

⁴ Displayed when the "Input 1_Integral time [heat-side]" in the same memory area is 0 (0.0, 0.00, 0.000).

⁵ Displayed when Bottom suppression function is valid.

■ Parameter group No. 52: Input 2_Control (2.Cntr)

No.	Symbol	Name	Data range	Factory set value	User set value
—	Pn52	Parameter group No. 52 ¹	This is the first parameter symbol of Parameter group No. 52	—	—
48	2. P	Input 2_Proportional band ¹	TC/RTD inputs: 0 (0.0, 0.00) to Input 2_Input span (Unit: °C [°F]) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.0 to 1000.0 % of Input 2_Input span 0 (0.0, 0.00): ON/OFF action	TC/RTD inputs: 30 V/I inputs: 3.0	
49	2. I	Input 2_Integral time ^{1,2}	0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds ★ 0 (0.0, 0.00, 0.000): PD action [Varies with the setting of the Integral/Derivative time decimal point position.]	240.00	
50	2. d	Input 2_Derivative time ^{1,2}	0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds ★ 0 (0.0, 0.00, 0.000): PI action [Varies with the setting of the Integral/Derivative time decimal point position.]	60.00	
51	2. oHH	Input 2_ON/OFF action differential gap (upper) ^{2,3}	TC/RTD inputs: 0 (0.0, 0.00) to Input 2_Input span (Unit: °C [°F]) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.0 to 100.0 % of Input 2_Input span	TC/RTD inputs: 1 V/I inputs: 0.1	
52	2. oHL	Input 2_ON/OFF action differential gap (lower) ^{2,3}	TC/RTD inputs: 0 (0.0, 0.00) to Input 2_Input span (Unit: °C [°F]) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.0 to 100.0 % of Input 2_Input span	TC/RTD inputs: 1 V/I inputs: 0.1	
53	2. RPF	Input 2_Control response parameter ¹	0: Slow 1: Medium 2: Fast ★ [When the P or PD action is selected, this setting becomes invalid]	0	
54	2.PACT	Input 2_Proactive intensity ^{1,2,4}	0 to 4 ★ 0: No function	2	
55	2. MR	Input 2_Manual reset ^{1,2,5}	-100.0 to +100.0 %	0.0	
56	2. FF	Input 2_FF amount ^{1,2,4,6}	-100.0 to +100.0 %	0.0	
57	2. oLH	Input 2_Output limiter high ²	Input 2_Output limiter low to 105.0 %	105.0	
58	2. oLL	Input 2_Output limiter low ²	-5.0 % to Input 2_Output limiter high	-5.0	
59	2. LbR	Input 2_Control loop break alarm (LBA) time ¹	0 to 7200 seconds 0: No function	LBA function is specified: 480 LBA function is not specified: 0	
60	2. Lbd	Input 2_LBA deadband (LBD) ¹	0 to Input 2_Input span ★ [Varies with the setting of the Decimal point position.]	0	

★ Data included in Memory area

¹ Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2."

² Displayed when the "Input 2_Proportional band" in the same memory area is other than 0 (0.0, 0.00).

³ Displayed when the "Input 2_Proportional band" in any memory area is 0 (0.0, 0.00). (Common setting in memory area)

⁴ Displayed when the "Input 2_Integral time" in the same memory area is other than 0 (0.0, 0.00, 0.000).

⁵ Displayed when the "Input 2_Integral time" in the same memory area is 0 (0.0, 0.00, 0.000).

⁶ Displayed when Bottom suppression function is valid.

■ Parameter group No. 56: Input 1_Cooling control (*I.Cool*)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Pn56</i>	Parameter group No. 56 ¹	This is the first parameter symbol of Parameter group No. 56	—	—
61	<i>I. P_c</i>	Input 1_Proportional band [cool-side] ^{1,2}	TC/RTD inputs: 1 (0.1, 0.01) to Input 1_Input span (Unit: °C [°F]) (When Control with PV select: 1 to PV select input span) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.1 to 1000.0 % of Input 1_Input span (When Control with PV select: 0.1 to 1000.0 % of PV select input span)	TC/RTD inputs: 30 V/I inputs: 3.0	
62	<i>I. I_c</i>	Input 1_Integral time [cool-side] ^{1,2}	0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds 0 (0.0, 0.00, 0.000): PD action [Varies with the setting of the Integral/Derivative time decimal point position.]	240.00	
63	<i>I. d_c</i>	Input 1_Derivative time [cool-side] ^{1,2}	0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds 0 (0.0, 0.00, 0.000): PI action [Varies with the setting of the Integral/Derivative time decimal point position.]	60.00	
64	<i>I. db</i>	Input 1_Overlap/Deadband ¹	TC/RTD inputs: -(Input 1_Input span) to +(Input 1_Input span) (When Control with PV select: -(PV select input span) to +(PV select input span)) (Unit: °C [°F]) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: -100.0 to +100.0 % of Input 1_Input span (When Control with PV select: -100.0 to +100.0 % of PV select input span) ★ Minus (-) setting results in Overlap. However, the overlapping range is within the proportional range.	TC/RTD inputs: 0 V/I inputs: 0.0	
65	<i>I.oLHc</i>	Input 1_Output limiter high [cool-side] ¹	Input 1_Output limiter low [cool-side] to 105.0 %	105.0	
66	<i>I.oLLc</i>	Input 1_Output limiter low [cool-side] ¹	-5.0 % to Input 1_Output limiter high [cool-side]	-5.0	

★ Data included in Memory area

¹ Displayed when the “Input 1_Control action” is Heat/Cool PID control.

² Displayed when the “Input 1_Proportional band [heat-side]” in the same memory area is other than 0 (0.0, 0.00).

■ Parameter group No. 70: Memory area (ArEA)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Pn70</i>	Parameter group No. 70	This is the first parameter symbol of Parameter group No. 70	—	—
67	<i>TRGR</i>	Select Trigger type for Memory area transfer	0 to 63 0: No assignment +1: Event 1 +2: Event 2 +4: Event 3 +8: Event 4 +16: Digital input 1 (DI1) Close edge +32: Digital input 1 (DI1) Open edge ★ To select two or more functions, sum each value.	0	
68	<i>ASR</i>	Area soak time	0 hours 00 minutes 00 seconds to 9 hours 59 minutes 59 seconds * 0 hours 00 minutes to 99 hours 59 minutes 0 minutes 00 seconds to 199 minutes 59 seconds 0.00 seconds to 59.99 seconds (Calculation is performed every 50ms.) ★ * Settable only when the Input data type is 0 or 2. [Data range of Area soak time can be selected on the Soak time unit.]	0:00 (0.00 seconds)	
69	<i>LNKA</i>	Link area number	0 to 16 ★ 0: No link	0	
70	<i>ISVRU</i>	Input 1_Setting change rate limiter (up)	0 to Input 1_Input span (When Control with PV select: 0 to PV select input span) 0: No function ★ [Varies with the setting of the Decimal point position.]	0	
71	<i>ISVRd</i>	Input 1_Setting change rate limiter (down)	0 to Input 1_Input span (When Control with PV select: 0 to PV select input span) 0: No function ★ [Varies with the setting of the Decimal point position.]	0	
72	<i>IR/MR</i>	Input 1_Auto/Manual transfer selection (Area)	0: No transfer 1: Auto mode (bumpless) 2: Auto mode (bump) 3: Manual mode (bumpless) 4: Manual mode (bump)	0	
73	<i>I. MV.R</i>	Input 1_Manipulated output value (Area)	PID control: -5.0 to +105.0 % Heat/Cool PID control: -105.0 to +105.0 %	PID control: -5.0 Heat/Cool PID control: 0.0	
74	<i>ZSVRU</i>	Input 2_Setting change rate limiter (up) *	0 to Input 2_Input span 0: No function ★ [Varies with the setting of the Decimal point position.]	0	
75	<i>ZSVRd</i>	Input 2_Setting change rate limiter (down) *	0 to Input 2_Input span 0: No function ★ [Varies with the setting of the Decimal point position.]	0	
76	<i>ZR/MR</i>	Input 2_Auto/Manual transfer selection (Area) *	0: No transfer 1: Auto mode (bumpless) 2: Auto mode (bump) 3: Manual mode (bumpless) 4: Manual mode (bump)	0	
77	<i>Z. MV.R</i>	Input 2_Manipulated output value (Area) *	-5.0 to +105.0 %	-5.0	

★ Data included in Memory area

* Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2."

Continued on the next page.

No.	Symbol	Name	Data range	Factory set value	User set value
78	R/L.R	Remote/Local transfer selection (Area) ¹	<ul style="list-style-type: none"> • When “Remote setting input” is selected at Select function for Input 2² 0: No transfer 1: Local mode 2: Remote mode <ul style="list-style-type: none"> • When “Control with PV select” is selected at Select function for input 2³ 0: No transfer 1: Input 1 2: Input 2 <ul style="list-style-type: none"> • When “2-loop control/Differential temperature control” is selected at Select function for input 2⁴ 0: No transfer 1: 2-loop control 2: Differential temperature control <p style="text-align: center;">★</p>	0	

★ Data included in Memory area

¹ Displayed when any of the following is selected in Select function for input 2: “Remote setting input,” “Control with PV select,” or “2-loop control/Differential temperature control.”

² Displayed when “Remote setting input” is selected in “Select function for input 2.”

³ Displayed when “Control with PV select” is selected in “Select function for input 2.”

⁴ Displayed when “2-loop control/Differential temperature control” is selected in “Select function for input 2.”

■ Parameter group No. 71: Input 1_Input knee point correction (I1 nLr)

No.	Symbol	Name	Data range	Factory set value	User set value
—	Pn71	Parameter group No. 71 *	This is the first parameter symbol of Parameter group No. 71	—	—
79	I.norP	Input 1_Number of knee point *	0 to 5 ★ 0: Input knee point correction function is disabled	5	
80	I.rP1	Input 1_Knee point input value 1 *	Input 1_Input range low to Input 1_Input range high ★ [Varies with the setting of the Decimal point position.]	Input 1_Input range high	
81	I.rP2	Input 1_Knee point input value 2 *	Same as Input 1_Knee point input value 1 ★	Same as Input 1_Knee point input value 1	
82	I.rP3	Input 1_Knee point input value 3 *	Same as Input 1_Knee point input value 1 ★	Same as Input 1_Knee point input value 1	
83	I.rP4	Input 1_Knee point input value 4 *	Same as Input 1_Knee point input value 1 ★	Same as Input 1_Knee point input value 1	
84	I.rP5	Input 1_Knee point input value 5 *	Same as Input 1_Knee point input value 1 ★	Same as Input 1_Knee point input value 1	
85	I.rV1	Input 1_Knee point correction value 1 *	Deviation setting: -(Input 1_Knee point correction limit value) to +(Input 1_Knee point correction limit value) Direct setting: Input 1_Input range low to Input 1_Input range high [Varies with the setting of the Decimal point position.]	Deviation setting: 0 Direct setting: Input 1_Input range high	
86	I.rV2	Input 1_Knee point correction value 2 *	Same as Input 1_Knee point correction value 1 ★	Same as Input 1_Knee point correction value 1	
87	I.rV3	Input 1_Knee point correction value 3 *	Same as Input 1_Knee point correction value 1 ★	Same as Input 1_Knee point correction value 1	
88	I.rV4	Input 1_Knee point correction value 4 *	Same as Input 1_Knee point correction value 1 ★	Same as Input 1_Knee point correction value 1	
89	I.rV5	Input 1_Knee point correction value 5 *	Same as Input 1_Knee point correction value 1 ★	Same as Input 1_Knee point correction value 1	

★ Data included in Memory area

* Displayed when Input knee point correction function is valid.

■ Parameter group No. 72: Input 2_Input knee point correction (2.I nLr)

No.	Symbol	Name	Data range	Factory set value	User set value
—	Pn72	Parameter group No. 72 *	This is the first parameter symbol of Parameter group No. 72	—	—
90	2.norP	Input 2_Number of knee point *	0 to 5 ★ 0: Input knee point correction function is disabled	5	
91	2. rP1	Input 2_Knee point input value 1 *	Input 2_Input range low to Input 2_Input range high ★ [Varies with the setting of the Decimal point position.]	Input 2_Input range high	
92	2. rP2	Input 2_Knee point input value 2 *	Same as Input 2_Knee point input value 1 ★	Same as Input 2_Knee point input value 1	
93	2. rP3	Input 2_Knee point input value 3 *	Same as Input 2_Knee point input value 1 ★	Same as Input 2_Knee point input value 1	
94	2. rP4	Input 2_Knee point input value 4 *	Same as Input 2_Knee point input value 1 ★	Same as Input 2_Knee point input value 1	
95	2. rP5	Input 2_Knee point input value 5 *	Same as Input 2_Knee point input value 1 ★	Same as Input 2_Knee point input value 1	
96	2. rV1	Input 2_Knee point correction value 1 *	Deviation setting: -(Input 2_Knee point correction limit value) to +(Input 2_Knee point correction limit value) Direct setting: Input 2_Input range low to Input 2_Input range high ★ [Varies with the setting of the Decimal point position.]	Deviation setting: 0 Direct setting: Input 2_Input range high	
97	2. rV2	Input 2_Knee point correction value 2 *	Same as Input 2_Knee point correction value 1 ★	Same as Input 2_Knee point correction value 1	
98	2. rV3	Input 2_Knee point correction value 3 *	Same as Input 2_Knee point correction value 1 ★	Same as Input 2_Knee point correction value 1	
99	2. rV4	Input 2_Knee point correction value 4 *	Same as Input 2_Knee point correction value 1 ★	Same as Input 2_Knee point correction value 1	
100	2. rV5	Input 2_Knee point correction value 5 *	Same as Input 2_Knee point correction value 1 ★	Same as Input 2_Knee point correction value 1	

★ Data included in Memory area

* Displayed when Input knee point correction function is valid. Not displayed when "No function" is selected in "Select function for input 2."

3.8 Setup Setting Mode [G]

■ Setting group No. 10: Display (dSP)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Sn 10</i>	Setting group No. 10	This is the first parameter symbol of Setting group No. 10	—	—
101	<i>PV CY</i>	Display update cycle	1: 50 ms 5: 250 ms 9: 450 ms 2: 100 ms 6: 300 ms 10: 500 ms 3: 150 ms 7: 350 ms 4: 200 ms 8: 400 ms	1	

■ Setting group No. 21: Input 1 (I. / nP)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Sn21</i>	Setting group No. 21	This is the first parameter symbol of Setting group No. 21	—	—
102	<i>I. Pb</i>	Input 1_PV bias	-(Input 1_Input span) to +(Input 1_Input span) When Control with PV select: -(PV select input span) to +(PV select input span) [Varies with the setting of the Decimal point position.]	0	
103	<i>I. dF</i>	Input 1_PV digital filter	0.00 to 10.00 seconds 0.00: Filter OFF	0.00	
104	<i>I. PR</i>	Input 1_PV ratio	0.500 to 1.500	1.000	
105	<i>I. PLC</i>	Input 1_PV low input cut-off *	0.00 to 25.00 % of Input 1_Input span (When Control with PV select: 0.00 to 25.00 % of PV select input span)	0.00	

* Displayed when Input 1 is Voltage/Current and when Square root extraction is valid.

■ Setting group No. 22: Input 2 (Z. / nP)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Sn22</i>	Setting group No. 22 ¹	This is the first parameter symbol of Setting group No. 22	—	—
106	<i>Z. Pb</i>	Input 2_PV bias ¹ (RS bias) ²	-(Input 2_Input span) to +(Input 2_Input span) [Varies with the setting of the Decimal point position.]	0	
107	<i>Z. dF</i>	Input 2_PV digital filter ¹ (RS digital filter) ³	0.00 to 10.00 seconds 0.00: Filter OFF	0.00	
108	<i>Z. PR</i>	Input 2_PV ratio ¹ (RS ratio) ⁴	Input 2_PV ratio 0.500 to 1.500 RS ratio 0.001 to 9.999	1.000	
109	<i>Z. PLC</i>	Input 2_PV low input cut-off ⁵	0.00 to 25.00 % of Input 2_Input span	0.00	

¹ Displayed with dual inputs. Not displayed when "No function" is selected in "Select function for input 2."

² Displayed as "RS bias" if "Remote setting input" is selected in Select function for input 2.

³ Displayed as "RS digital filter" if "Remote setting input" is selected in Select function for input 2.

⁴ Displayed as "RS ratio" if "Remote setting input" is selected in Select function for input 2.

⁵ Displayed when Input 2 is Voltage/Current and when Square root extraction is valid. Not displayed when "No function" or "Remote setting input" is selected in "Select function for input 2."

■ Setting group No. 30: Output (oUT)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>S_n30</i>	Setting group No. 30 ¹	This is the first parameter symbol of Setting group No. 30	—	—
110	<i>T₁</i>	OUT1 proportional cycle time ²	0.1 to 100.0 seconds	Relay contact output: 20.0 Voltage pulse output, Transistor output: Note1	
111	<i>T₂</i>	OUT2 proportional cycle time ³	0.1 to 100.0 seconds	Relay contact output: 20.0 Voltage pulse output, Transistor output: Note2	
112	<i>T₃</i>	OUT3 proportional cycle time ⁴	0.1 to 100.0 seconds	Voltage pulse output: Note3	
113	<i>M_T1</i>	OUT1 minimum ON/OFF time of proportional cycle ²	0 to 1000 ms	0	
114	<i>M_T2</i>	OUT2 minimum ON/OFF time of proportional cycle ³	0 to 1000 ms	0	
115	<i>M_T3</i>	OUT3 minimum ON/OFF time of proportional cycle ⁴	0 to 1000 ms	0	

Note1: In case OUT1 function selection is "Input 1_Control output [cool-side]" AND Inpu1_Control action is "Heat/Cool PID control [air cooling] or [water cooling)": 20.0.
Other casees: 2.0

Note2: In case OUT2 function selection is "Input 1_Control output [cool-side]" AND Inpu1_Control action is "Heat/Cool PID control [air cooling] or [water cooling)": 20.0.
Other casees: 2.0

Note3: In case OUT3 function selection is "Input 1_Control output [cool-side]" AND Inpu1_Control action is "Heat/Cool PID control [air cooling] or [water cooling)": 20.0.
Other casees: 2.0

¹ Displayed when any one of OUT1 to OUT3 is Relay contact output, Voltage pulse output or Transistor output.

² Displayed when OUT1 is Relay contact output, Voltage pulse output or Transistor output.

³ Displayed when OUT2 is Relay contact output, Voltage pulse output or Transistor output.

⁴ Displayed when OUT3 is supplied and "Universal output type selection" is "Voltage pulse output."

■ Setting group No. 45: Heater break alarm 1 (HbA1)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>S_n45</i>	Setting group No. 45	This is the first parameter symbol of Setting group No. 45	—	—
116	<i>HbA1</i>	Heater break alarm 1 (HBA1) set value ^{1,2}	0.0 to 100.0 A 0.0: HBA function OFF	0.0	
117	<i>HbC1</i>	Number of heater break alarm 1 (HBA1) delay times ¹	0 to 255 times	5	

¹ Displayed when Current transformer (CT) input is supplied. Not displayed in the following cases.

- CT1 assignment is "None."
- The output type of CT1 assignment is Current output or Continuous voltage output.

² Current transformer 1 (CT1) input is displayed on the MV display.

■ Setting group No. 46: Heater break alarm 2 (HbA2)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Sn46</i>	Setting group No. 46	This is the first parameter symbol of Setting group No. 46	—	—
118	<i>HbA2</i>	Heater break alarm 2 (HBA2) set value ^{1,2}	0.0 to 100.0 A 0.0: HBA function OFF	0.0	
119	<i>HbC2</i>	Number of heater break alarm 2 (HBA2) delay times ¹	0 to 255 times	5	

¹ Displayed when two Current transformer (CT) inputs are supplied. Not displayed in the following cases.

- CT2 assignment is "None."
- The output type of CT2 assignment is Current output or Continuous voltage output.

² Current transformer 2 (CT2) input is displayed on the MV display.

■ Setting group No. 51: Input 1_Control (I_Conf)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Sn51</i>	Setting group No. 51	This is the first parameter symbol of Setting group No. 51	—	—
120	<i>I_MMV</i>	Input 1_Manual manipulated output value	PID control: Input 1_Output limiter low [heat-side] to Input 1_Output limiter high [heat-side] Heat/Cool PID control ¹ : -(Input 1_Output limiter high [cool-side]) to +(Input 1_Output limiter high [heat-side])	PID control: -5.0 Heat/Cool PID control: 0.0	
121	<i>ILEV1</i>	Input 1_Level PID setting 1 ^{2,3}	Input 1_Input range low to Input 1_Input range high When Control with PV select: PV select input range low to PV select input range high [Varies with the setting of the Decimal point position.]	Input 1_Input range high Control with PV select: PV select input range high	
122	<i>ILEV2</i>	Input 1_Level PID setting 2 ^{2,3}	Same as Input 1_Level PID setting 1		
123	<i>ILEV3</i>	Input 1_Level PID setting 3 ^{2,3}	Same as Input 1_Level PID setting 1		
124	<i>ILEV4</i>	Input 1_Level PID setting 4 ^{2,3}	Same as Input 1_Level PID setting 1		
125	<i>ILEV5</i>	Input 1_Level PID setting 5 ^{2,3}	Same as Input 1_Level PID setting 1		
126	<i>ILEV6</i>	Input 1_Level PID setting 6 ^{2,3}	Same as Input 1_Level PID setting 1		
127	<i>ILEV7</i>	Input 1_Level PID setting 7 ^{2,3}	Same as Input 1_Level PID setting 1		

¹ In case of Heat/Cool PID control, the data range has such exceptional conditions as shown below.

(1) Input 1_Output limiter high [cool-side] is ≤ 0.0 %

- Input 1_Output limiter low [heat-side] is ≤ 0.0 %: 0.0 % to +(Input 1_Output limiter high [heat-side])
- Input 1_Output limiter low [heat-side] is > 0.0 %: Input 1_Output limiter low [heat-side] to Input 1_Output limiter high [heat-side]

(2) Input 1_Output limiter high [heat-side] is ≤ 0.0 %

- Input 1_Output limiter low [cool-side] is ≤ 0.0 %: -(Input 1_Output limiter high [cool-side]) to 0.0 %
- Input 1_Output limiter low [cool-side] is > 0.0 %: -(Input 1_Output limiter high [cool-side]) to -(Input 1_Output limiter low [cool-side])

(3) Fixed at 0.0% in the following cases:

Input 1_Output limiter high [cool-side] ≤ 0.0 %, AND Input 1_Output limiter high [heat-side] ≤ 0.0 %

² Displayed when Input 1 is with Level-PID.

³ Input 1_Level PID settings 1 to 7 always maintain the following relation.

(Input 1_Level PID setting 1) ≤ (Input 1_Level PID setting 2) ≤ (Input 1_Level PID setting 3) ≤ (Input 1_Level PID setting 4) ≤ (Input 1_Level PID setting 5) ≤ (Input 1_Level PID setting 6) ≤ (Input 1_Level PID setting 7)

■ Setting group No. 52: Input 2_Control (2_Conf)

No.	Symbol	Name	Data range	Factory set value	User set value
—	5n52	Setting group No. 52 ¹	This is the first parameter symbol of Setting group No. 52	—	—
128	2_MMV	Input 2_Manual manipulated output value ¹	Input 2_Output limiter low to Input 2_Output limiter high	-5.0	
129	2LEV1	Input 2_Level PID setting 1 ^{2,3}	Input 2_Input range low to Input 2_Input range high [Varies with the setting of the Decimal point position.]	Input 2_Input range high	
130	2LEV2	Input 2_Level PID setting 2 ^{2,3}	Same as Input 2_Level PID setting 1		
131	2LEV3	Input 2_Level PID setting 3 ^{2,3}	Same as Input 2_Level PID setting 1		
132	2LEV4	Input 2_Level PID setting 4 ^{2,3}	Same as Input 2_Level PID setting 1		
133	2LEV5	Input 2_Level PID setting 5 ^{2,3}	Same as Input 2_Level PID setting 1		
134	2LEV6	Input 2_Level PID setting 6 ^{2,3}	Same as Input 2_Level PID setting 1		
135	2LEV7	Input 2_Level PID setting 7 ^{2,3}	Same as Input 2_Level PID setting 1		

¹ Displayed if “2-loop control/Differential temperature control” is selected in “Select function for input 2.”

² Displayed when Input 2 is with Level-PID AND “2-loop control/Differential temperature control” is selected in “Select function for input 2.”

³ Input 2_Level PID settings 1 to 7 always maintain the following relation.

(Input 2_Level PID setting 1) ≤ (Input 2_Level PID setting 2) ≤ (Input 2_Level PID setting 3) ≤ (Input 2_Level PID setting 4) ≤ (Input 2_Level PID setting 5) ≤ (Input 2_Level PID setting 6) ≤ (Input 2_Level PID setting 7)

■ Setting group No. 53: Input 1_Tuning (1_TUNE)

No.	Symbol	Name	Data range	Factory set value	User set value
—	5n53	Setting group No. 53	This is the first parameter symbol of Setting group No. 53	—	—
136	1_ATb	Input 1_AT bias	-(Input 1_Input span) to +(Input 1_Input span) When Control with PV select: -(PV select input span) to +(PV select input span) [Varies with the setting of the Decimal point position.]	0	
137	1ATTM	Input 1_AT remaining time monitor	0 hours 00 minutes to 48 hours 00 minutes	—	—
138	1TUNE	Input 1_AT/ST status monitor	0: AT/ST complete 1: AT running now 2: ST running now -1: Aborted. Setting changed. -2: Aborted. Abnormal input. -3: Aborted. Timeout. -4: Aborted. Abnormal calculated values.	—	—

■ Setting group No. 54: Input 2_Tuning ($2.\Gamma U\eta E$)

No.	Symbol	Name	Data range	Factory set value	User set value
—	S_n54	Setting group No. 54 *	This is the first parameter symbol of Setting group No. 54	—	—
139	$2.\Gamma b$	Input 2_AT bias *	-(Input 2_Input span) to +(Input 2_Input span) [Varies with the setting of the Decimal point position.]	0	
140	$2.R\Gamma M$	Input 2_AT remaining time monitor *	0 hours 00 minutes to 48 hours 00 minutes	—	—
141	$2.\Gamma UNE$	Input 2_AT/ST status monitor *	0: AT/ST complete 1: AT running now 2: ST running now -1: Aborted. Setting changed. -2: Aborted. Abnormal input. -3: Aborted. Timeout. -4: Aborted. Abnormal calculated values.	—	—

* Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2."

■ Setting group No. 57: Proactive ($PRACT$)

No.	Symbol	Name	Data range	Factory set value	User set value
—	S_n57	Setting group No. 57	This is the first parameter symbol of Setting group No. 57	—	—
142	$FFSF$	FF amount learning ¹	0 to 3 0: No learning +1: Learn Input 1 +2: Learn Input 2 To select two or more functions, sum each value.	0	
143	$1.E\times du$	Input 1_Determination point of external disturbance	-(Input 1_Input span) to +(Input 1_Input span) When Control with PV select: -(PV select input span) to +(PV select input span) [Varies with the setting of the Decimal point position.]	-1	
144	$2.E\times du$	Input 2_Determination point of external disturbance ²	-(Input 2_Input span) to +(Input 2_Input span) [Varies with the setting of the Decimal point position.]	-1	

¹ Displayed when Bottom suppression function is valid.

² Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2."

■ Setting group No. 58: 2-input function ($2PB$)

No.	Symbol	Name	Data range	Factory set value	User set value
—	S_n58	Setting group No. 58 *	This is the first parameter symbol of Setting group No. 58	—	—
145	$2PV.LV$	PV select transfer level *	Input 1_Input range low to Input 1_Input range high [Varies with the setting of the Decimal point position.]	Input 1_Input range high	
146	$2PV.\Gamma M$	PV select transfer time *	0.0 to 100.0 seconds	0.0	

* Displayed when "Control with PV select" is selected in "Select function for input 2."

■ Setting group No. 91: System (545)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Sn91</i>	Setting group No. 91	This is the first parameter symbol of Setting group No. 91	—	—
147	<i>I.PHLd</i>	Input 1_Peak hold monitor	Input 1_Input range low – (Input 1_5 % of input span) to Input 1_Input range high + (Input 1_5 % of input span) [Varies with the setting of the Decimal point position.]	—	—
148	<i>I.bHLd</i>	Input 1_Bottom hold monitor	Input 1_Input range low – (Input 1_5 % of input span) to Input 1_Input range high + (Input 1_5 % of input span) [Varies with the setting of the Decimal point position.]	—	—
149	<i>I.HLdR</i>	Input 1_Hold reset	<i>Hold</i> : Hold <i>rESEF</i> : Reset Returns to Hold state automatically after reset.	<i>Hold</i>	—
150	<i>Z.PHLd</i>	Input 2_Peak hold monitor *	Input 2_Input range low – (Input 2_5 % of input span) to Input 2_Input range high + (Input 2_5 % of input span) [Varies with the setting of the Decimal point position.]	—	—
151	<i>Z.bHLd</i>	Input 2_Bottom hold monitor *	Input 2_Input range low – (Input 2_5 % of input span) to Input 2_Input range high + (Input 2_5 % of input span) [Varies with the setting of the Decimal point position.]	—	—
152	<i>Z.HLdR</i>	Input 2_Hold reset *	<i>Hold</i> : Hold <i>rESEF</i> : Reset Returns to Hold state automatically after reset.	<i>Hold</i>	—

* Displayed when any of the following is selected in Select function for input 2: "Control with PV select," "2-loop control/Differential temperature control" or "Input circuit error alarm."

3.9 Engineering Mode [H]



WARNING

Parameters in the Engineering mode should be set according to the application before setting any parameter related to operation. Once the parameters in the Engineering mode are set correctly, no further changes need to be made to parameters for the same application under normal conditions. If they are changed unnecessarily, it may result in malfunction or failure of the instrument. RKC will not bear any responsibility for malfunction or failure as a result of improper changes in the Engineering mode.



NOTE

**Parameters in Engineering mode are settable only when the controller is in STOP mode.
However, only checking can be made even in the RUN state.**

■ Function block No. 10: Display (*dSP*)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn 10</i>	Function block No. 10	This is the first parameter symbol of Function block No. 10	—	—
153	<i>SPCH</i>	STOP display selection	0: Stop on PV display 1: Stop on SV display 2: Stop on MV display	1	
154	<i>RLC</i>	ALM lamp lighting condition	0 to 4095 0: OFF +1: Event 1 +2: Event 2 +4: Event 3 +8: Event 4 +16: Heater break alarm 1 (HBA1) +32: Heater break alarm 2 (HBA2) +64: Control loop break alarm 1 (LBA1) +128: Control loop break alarm 2 (LBA2) +256: Input 1_Input error high +512: Input 1_Input error low +1024: Input 2_Input error high +2048: Input 2_Input error low To select two or more functions, sum each value.	255	
155	<i>dSop</i>	PV flashing display at input error	0: Flashing display 1: Non-flashing display	0	
156	<i>1.d5.5V</i>	Show/Hide Input 1_SV	0: Hide Input 1_SV 1: Show Input 1_SV	1	
157	<i>2.d5.5V</i>	Show/Hide Input 2_SV *	0: Hide Input 2_SV 1: Show Input 2_SV	1	
158	<i>1.d5.MV</i>	Show/Hide Input 1_MV	0: Hide 1: Show Input 1_Manipulated output value (MV) 2: Show Memory area soak time 3: Show Current transformer 1 (CT1) input value 4: Show Current transformer 2 (CT2) input value	1	
159	<i>2.d5.MV</i>	Show/Hide Input 2_MV *	0: Hide 1: Show Input 2_Manipulated output value (MV) 2: Show Memory area soak time 3: Show Current transformer 1 (CT1) input value 4: Show Current transformer 2 (CT2) input value	1	

* Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2."

No.	Symbol	Name	Data range	Factory set value	User set value
160	<i>d5.MoN</i>	Select hide items in Monitor mode	0 to 31 0: Show all +1: Remote setting input value monitor +2: Manipulated output value (MV) monitor +4: Current transformer (CT) input value monitor +8: Comprehensive event state +16: Memory area soak time To select two or more functions, sum each value.	0	
161	<i>d5.Mod</i>	Select hide items in Operation transfer mode	0 to 63 0: Show all +1: RUN/STOP transfer +2: Autotuning (AT) +4: Startup tuning (ST) +8: Auto/Manual transfer +16: Remote/Local transfer (PV select transfer, 2-loop control/Differential temperature control) +32: Control area Local/External transfer To select two or more functions, sum each value.	0	

■ Function block No. 11: Key operation (F11)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn.11</i>	Function block No. 11	This is the first parameter symbol of Function block No. 11	—	—
162	<i>SET.KY</i>	Data registration	0: SET key method Used to register the Set value (SV) using the SET key. 1: Direct registration Used to register the Set value (SV) without pressing the SET key.	0	
163	<i>FN.KY</i>	FUNC key assignment	0: Unused 1: RUN/STOP transfer 2: Autotuning (AT) (Common to Input 1 and 2) 3: Input 1_Autotuning (AT) 4: Input 2_Autotuning (AT) 5: Auto/Manual transfer (Common to Input 1 and 2) 6: Input 1_Auto/Manual transfer 7: Input 2_Auto/Manual transfer 8: Remote/Local transfer (PV select transfer, 2-loop control/Differential temperature control) 9: Control area Local/External transfer 10: Interlock release 11: Hold reset (Common to Input 1 and 2) 12: Input 1_Hold reset 13: Input 2_Hold reset 14: Set data unlock/lock transfer 15: Area jump	1	
164	<i>FN.FYP</i>	FUNC key operation selection	0: Press once The function set at "FUNC key assignment" is activated upon a press of the FUNC key. 1: Press and hold The function set at "FUNC key assignment" is activated by holding the FUNC key pressed.	0	

■ Function block No. 21: Input 1 (I. I nP)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn21</i>	Function block No. 21	This is the first parameter symbol of Function block No. 21	—	—
165	<i>I. INP</i>	Input 1_Input type	0: TC input K 1: TC input J 2: TC input R 3: TC input S 4: TC input B 5: TC input E 6: TC input N 7: TC input T 8: TC input W5Re/W26Re 9: TC input PLII 10: TC input U 11: TC input L 12: TC input PR40-20 13: RTD input Pt100 14: RTD input JPt100 15: Current input 0 to 20 mA DC 16: Current input 4 to 20 mA DC 17: Voltage input 0 to 10 V DC 18: Voltage input 0 to 5 V DC 19: Voltage input 1 to 5 V DC 20: Voltage input 0 to 1 V DC 21: Voltage input -10 to +10 V DC 22: Voltage input -5 to +5 V DC 23: Voltage input 0 to 100 mV DC 24: Voltage input 0 to 10 mV DC	Same as the input type of the input range code specified at the time of order.	
166	<i>I.UNI 1</i>	Input 1_Display unit ¹	0: °C 1: °F	Same as the display unit of the input range code specified at the time of order.	
167	<i>I.PCdp</i>	Input 1_Decimal point position	0: No decimal place 1: One decimal place 2: Two decimal places 3: Three decimal places 4: Four decimal places TC input: W5Re/W26Re, PR40-20: 0 (fixed) Thermocouples other than those shown above: 0 to 1 RTD input: 0 to 2 Voltage (V)/Current (I) input: In case of Input data type 0 or 2: 0 to 4 In case of Input data type 1: 0 to 3 When Control with PV select: Decimal point position setting of Input 1 and Input 2 is compared and the smaller will be used.	Same as the decimal point position of the input range code specified at the time of order. For V/I inputs: 1	
168	<i>I.PGSH</i>	Input 1_Input range high	(Input 1_Input range low + 1 digit) to Input 1_Maximum value of input range [Varies with the setting of the Decimal point position.]	High limit value of the input range code specified at the time of order. For V/I inputs: 100.0	
169	<i>I.PGSL</i>	Input 1_Input range low	Input 1_Minimum value of input range to (Input 1_Input range high - 1 digit) [Varies with the setting of the Decimal point position.]	Low limit value of the input range code specified at the time of order. For V/I inputs: 0.0	
170	<i>I. Pov</i>	Input 1_Input error determination point (high)	Input 1_Input error determination point (low) to Input 1_Input range high + (Input 1_5 % of input span) [Varies with the setting of the Decimal point position.]	Input 1_Input range high + (Input 1_5 % of input span)	
171	<i>I. PUN</i>	Input 1_Input error determination point (low)	Input 1_Input range low - (Input 1_5 % of input span) * to Input 1_Input error determination point (high) [Varies with the setting of the Decimal point position.] * When Input type of Input 1 is RTD, low limit value is about 2 Ohms. (Pt100: -245.5 °C [-409.8 °F], JPt100: -237.6 °C [-395.7 °F])	Input 1_Input range low - (Input 1_5 % of input span)	
172	<i>I.TCJC</i>	Input 1_Temperature compensation calculation ²	0: No temperature compensation calculation 1: With temperature compensation calculation	1	
173	<i>I. boS</i>	Input 1_Burnout direction ³	0: Upscale 1: Downscale	0	

¹ Displayed when "Input 1_Input type" is either Thermocouple (TC) or RTD.² Displayed when "Input 1_Input type" is Thermocouple (TC).³ Displayed when "Input 1_Input type" is Thermocouple (TC) or Low voltage input (0 to 100 mV DC and 0 to 10 mV DC).

Continued on the next page.

No.	Symbol	Name	Data range	Factory set value	User set value
174	I_rVSL	Input 1_Selection of knee point function	0: Disable input knee point correction function 1: Enable input knee point correction function	0	
175	I_rVS	Input 1_Selection of correction value setting	0: Deviation setting (set as a deviation from the knee point input value) 1: Direct setting (value after the correction can directly be set)	0	
176	I_rVML	Input 1_Knee point correction limit value	0 to Input 1_Input span [Varies with the setting of the Decimal point position.]	10	
177	I_SQR	Input 1_Square root extraction ¹	0: Unused 1: Used	0	
178	I_INV	Input 1_Inverting input ¹	0: Unused 1: Used	0	
179	I_NdF	Input data type	0: Number of measured value digits: 5 Number of RKC communication digits: 7 Modbus: Double word PLC communication: Double word (System data: Single word) 1: Number of measured value digits: 4 Number of RKC communication digits: 6 Modbus: Single word * PLC communication: Single word 2: HA series equivalent (Communication identifiers of RKC communication and register address of Modbus switch to the HA series equivalent data.) Number of measured value digits: 5 Number of RKC communication digits: 7 Modbus: Double word PLC communication: Double word (System data: Single word) * The data of the FB series and its equivalent are included. When changing the Input data type from 0 (or 2) to 1 and when the present Input range has 5 digits (example: Input range high: 1372.0), you need to configure the Input range to have 4 digits beforehand. The unit of time depends on the Input data type. In case of Input data type 0 or 2 hour/minute/second, hour/minute, minute/second, second In case of Input data type 1 hour/minute, minute/second, second	Conforms to Input range code to specified at the time of ordering	
180	PFRQ	Power supply frequency	0: 50 Hz 1: 60 Hz	0	

¹ Displayed when Input 1 is Voltage (V)/Current (I).

■ Function block No. 22: Input 2 (2. I nP)

No.	Symbol	Name	Data range	Factory set value	User set value
—	F_{n22}	Function block No. 22 ¹	This is the first parameter symbol of Function block No. 22	—	—
181	$2. I\ nP$	Input 2_Input type ^{1,2}	0: TC input K 1: TC input J 2: TC input R 3: TC input S 4: TC input B 5: TC input E 6: TC input N 7: TC input T 8: TC input W5Re/W26Re 9: TC input PLII 10: TC input U 11: TC input L 12: TC input PR40-20 <ul style="list-style-type: none"> • When Measured Input 2 is selected: 0 to 24 • When Remote setting input is selected: 15 to 24 	13: RTD input Pt100 14: RTD input JPt100 15: Current input 0 to 20 mA DC 16: Current input 4 to 20 mA DC 17: Voltage input 0 to 10 V DC 18: Voltage input 0 to 5 V DC 19: Voltage input 1 to 5 V DC 20: Voltage input 0 to 1 V DC 21: Voltage input -10 to +10 V DC 22: Voltage input -5 to +5 V DC 23: Voltage input 0 to 100 mV DC 24: Voltage input 0 to 10 mV DC	Same as Input 1_Input type When Remote setting input is specified at the time of order, but the input type is not specified: 17
182	$2. UNI\ F$	Input 2_Display unit ^{2,3,4}	0: °C 1: °F	Same as Input 1_Display unit	
183	$2. P\ G\ dP$	Input 2_Decimal point position ^{2,4}	0: No decimal place 1: One decimal place 2: Two decimal places 3: Three decimal places 4: Four decimal places TC input: W5Re/W26Re, PR40-20: 0 (fixed) Thermocouples other than those shown above: 0 to 1 RTD input: 0 to 2 Voltage (V)/Current (I) input: For Input data type is 0 or 2: 0 to 4 For Input data type is 1: 0 to 3	Same as Input 1_Decimal point position	
184	$2. P\ G\ SH$	Input 2_Input range high ¹	TC/RTD inputs and Voltage (V)/Current (I) Inputs (For other than Remote setting input): (Input 2_Input range low + 1 digit) to Input 2_Maximum value of input range Voltage (V)/Current (I) Inputs (For Remote setting input): (Input 2_Input range low + 1 digit) to Input 1_Maximum value of input range [Varies with the setting of the Decimal point position.]	Same as Input 1_Input range high	
185	$2. P\ G\ SL$	Input 2_Input range low ¹	TC/RTD inputs and Voltage (V)/Current (I) Inputs (For other than Remote setting input): Input 2_Minimum value of input range to (Input 2_Input range high - 1 digit) Voltage (V)/Current (I) Inputs (For Remote setting input): Input 1_Minimum value of input range to (Input 2_Input range high - 1 digit) [Varies with the setting of the Decimal point position.]	Same as Input 1_Input range low	

¹ Displayed when Remote setting input or Measured input 2 is supplied.

² Not displayed when "No function" is selected in "Select function for input 2."

³ Displayed when Input 2 is either Thermocouple (TC) or RTD.

⁴ Not settable when Remote setting input or Control with PV select is selected.

Continued on the next page.

No.	Symbol	Name	Data range	Factory set value	User set value
186	$2.P_{oV}$	Input 2_Input error determination point (high) ¹	Input 2_Input error determination point (low) to Input 2_Input range high + (Input 2_5 % of input span) [Varies with the setting of the Decimal point position.]	Input 2_Input range high + (Input 2_5 % of input span)	
187	$2.P_{UN}$	Input 2_Input error determination point (low) ¹	Input 2_Input range low – (Input 2_5 % of input span)* to Input 2_Input error determination point (high) [Varies with the setting of the Decimal point position.] * When Input type of Input 2 is RTD, low limit value is about 2 Ohms. (Pt100: -245.5 °C [-409.8 °F], JPt100: -237.6 °C [-395.7 °F])	Input 2_Input range low – (Input 2_5 % of input span)	
188	$2.T_{CUC}$	Input 2_Temperature compensation calculation ^{2,3}	0: No temperature compensation calculation 1: With temperature compensation calculation	1	
189	$2.boS$	Input 2_Burnout direction ^{2,4}	0: Upscale 1: Downscale	0	
190	$2.rVSL$	Input 2_Selection of knee point function	0: Disable input knee point correction function 1: Enable input knee point correction function	0	
191	$2.rVS$	Input 2_Selection of correction value setting	0: Deviation setting (set as a deviation from the knee point input value) 1: Direct setting (value after the correction can directly be set)	0	
192	$2.rVML$	Input 2_Knee point correction limit value	0 to Input 2_Input span [Varies with the setting of the Decimal point position.]	10	
193	$2.SQR$	Input 2_Square root extraction ^{1,5}	0: Unused 1: Used	0	
194	$2.INV$	Input 2_Inverting input ^{1,5}	0: Unused 1: Used	0	

¹ Not displayed when "No function" or "Remote setting input" is selected in "Select function for input 2."

² Not displayed when "No function" is selected in "Select function for input 2."

³ Displayed when Input 2 is either Thermocouple (TC) or RTD.

⁴ Displayed when Input 2 is Thermocouple (TC) or Low voltage input (0 to 100 mV DC and 0 to 10 mV DC).

⁵ Displayed when Input 2 is Voltage (V)/Current (I).

■ Function block No. 23: Digital input (dI)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn23</i>	Function block No. 23 ¹	This is the first parameter symbol of Function block No. 23	—	—
195	<i>dI SL 1</i>	DI1 function selection ¹	0: No function 1: RUN/STOP transfer 2: Auto/Manual transfer (Common to Input 1 and 2) 3: Input 1_Auto/Manual transfer 4: Input 2_Auto/Manual transfer 5: Remote/Local transfer (PV select transfer, 2-loop control/Differential temperature control) 6: Interlock release 7: Hold reset (Common to Input 1 and 2) 8: Input 1_Hold reset 9: Input 2_Hold reset 10: Autotuning (AT) (Common to Input 1 and 2) 11: Input 1_Autotuning (AT) 12: Input 2_Autotuning (AT) 13: Set data unlock/lock transfer 14: Direct/Reverse action transfer 15: Memory area transfer (2 points, without area set signal) 16: Memory area transfer (8 points, without area set signal) 17: Memory area transfer (8 points, with area set signal) 18: Memory area transfer (16 points, without area set signal) 19: Memory area transfer (16 points, with area set signal) 20: Area jump	Based on Model code	
196	<i>dI SL 2</i>	DI2 function selection ¹	0 to 14 Same as DI1 function selection (0 to 14)	Based on Model code	
197	<i>dI SL 3</i>	DI3 function selection ¹	0 to 14 Same as DI1 function selection (0 to 14)	Based on Model code	
198	<i>dI SL 4</i>	DI4 function selection ¹	0 to 14 Same as DI1 function selection (0 to 14)	Based on Model code	
199	<i>dI SL 5</i>	DI5 function selection ²	0 to 14 Same as DI1 function selection (0 to 14)	Based on Model code	
200	<i>dI SL 6</i>	DI6 function selection ²	0 to 14 Same as DI1 function selection (0 to 14)	Based on Model code	
201	<i>dI I NV</i>	DI logic invert ¹	0 to 31 0: No logic invert +1: RUN/STOP transfer +2: Auto/Manual transfer +4: Remote/Local transfer (PV select transfer, 2-loop control/Differential temperature control) +8: Set data unlock/lock transfer +16: Direct/Reverse action transfer To select two or more functions, sum each value.	0	
202	<i>dI TI M</i>	Area switching time ¹ (without area set signal)	1 to 5 seconds	2	

¹ Displayed when Digital input function is supplied.² Displayed when six Digital inputs (DI) are supplied.

■ Function block No. 30: Output (OUT)

No.	Symbol	Name	Data range	Factory set value	User set value
—	F_{n30}	Function block No. 30	This is the first parameter symbol of Function block No. 30	—	—
203	oSL_1	OUT1 function selection ¹	0: No assignment 1: Input 1_Control output [heat-side] 2: Input 1_Control output [cool-side] 3: Input 2_Control output 4: Retransmission output 5: Logic calculation output (Event, HBA, LBA, Input error) 6: RUN state output 7: Input 1_Manual mode state output 8: Input 2_Manual mode state output 9: Remote mode state output (Output of differential temperature control state, Input 2 state output of Control with PV select) 10: Input 1_Autotuning (AT) state output 11: Input 2_Autotuning (AT) state output 12: Output while Set value of Input 1 is changing 13: Output while Set value of Input 2 is changing 14: Output of the communication monitoring result 15: FAIL output	Based on Model code	
204	oSL_2	OUT2 function selection ²	Same as OUT1 function selection	Based on Model code	
205	oSL_3	OUT3 function selection ³	Same as OUT1 function selection	4	
206	oLG_1	OUT1 logic calculation selection ¹	0 to 4095 0: OFF +1: Event 1 +2: Event 2 +4: Event 3 +8: Event 4 +16: Heater break alarm 1 (HBA1) +32: Heater break alarm 2 (HBA2) +64: Control loop break alarm 1 (LBA1) +128: Control loop break alarm 2 (LBA2) +256: Input 1_Input error high +512: Input 1_Input error low +1024: Input 2_Input error high +2048: Input 2_Input error low To select two or more functions, sum each value.	0	
207	oLG_2	OUT2 logic calculation selection ²	Same as OUT1 logic calculation selection	Based on Model code	
208	oLG_3	OUT3 logic calculation selection ³	Same as OUT1 logic calculation selection	0	
209	$E\times C$	Energized/De-energized selection	0 to 127 0: All outputs are energized +1: OUT1 de-energized +2: OUT2 de-energized +4: OUT3 de-energized +8: DO1 de-energized +16: DO2 de-energized +32: DO3 de-energized +64: DO4 de-energized To select two or more functions, sum each value.	0	
210	ILS	Interlock selection	0 to 4095 0: Unused +1: Event 1 +2: Event 2 +4: Event 3 +8: Event 4 +16: Heater break alarm 1 (HBA1) +32: Heater break alarm 2 (HBA2) +64: Control loop break alarm 1 (LBA1) +128: Control loop break alarm 2 (LBA2) +256: Input 1_Input error high +512: Input 1_Input error low +1024: Input 2_Input error high +2048: Input 2_Input error low To select two or more functions, sum each value.	0	

¹ Displayed when OUT1 is supplied.² Displayed when OUT2 is supplied.³ Displayed when OUT3 is supplied.

No.	Symbol	Name	Data range	Factory set value	User set value
211	55	Output action at control stop	0 to 7 0: OFF +1: Logic calculation output: Action continues +2: Retransmission output: Action continues +4: Instrument status output: Action continues To select two or more functions, sum each value.	0	
212	UNI □	Universal output type selection (OUT3) *	0: Voltage pulse output 1: Current output (4 to 20 mA DC) 2: Current output (0 to 20 mA DC)	1	

* Displayed when OUT3 is supplied.

■ Function block No. 31: Retransmission output 1 (Ro I)

No.	Symbol	Name	Data range	Factory set value	User set value
—	Fn3 I	Function block No. 31 *	This is the first parameter symbol of Function block No. 31	—	—
213	Ro I	Retransmission output 1 type *	0: No retransmission output 1: Input 1_Measured value (PV) 2: Input 1_Local SV 3: Input 1_SV monitor value 4: Input 1_Deviation 5: Input 1_Manipulated output value [heat-side] 6: Input 1_Manipulated output value [cool-side] 7: Input 2_Measured value (PV) 8: Input 2_Local SV 9: Input 2_SV monitor value 10: Input 2_Deviation 11: Input 2_Manipulated output value 12: Remote setting input value 13: Current transformer 1 (CT1) input value 14: Current transformer 2 (CT2) input value 15: Measured value (PV) of differential temperature input	0	
214	RHS I	Retransmission output 1 scale high *	No retransmission output, Input 1_Measured value (PV), Input 1_Local SV, Input 1_SV monitor value, and Remote setting input value: Input 1_Input range low to Input 1_Input range high When Control with PV select: PV select input range low to PV select input range high [Varies with the setting of the Decimal point position.] Input 1_Deviation: -(Input 1_Input span) to +(Input 1_Input span) [Varies with the setting of the Decimal point position.] Input 2_Measured value (PV), Input 2_Local SV, and Input 2_SV monitor value: Input 2_Input range low to Input 2_Input range high [Varies with the setting of the Decimal point position.] Input 2_Deviation: -(Input 2_Input span) to +(Input 2_Input span) [Varies with the setting of the Decimal point position.] Manipulated output value: -5.0 to +105.0 % Current transformer (CT) input value: 0.0 to 100.0 % Measured value (PV) of differential temperature input: -(Input 1_Input span) to +(Input 1_Input span) [Varies with the setting of the Decimal point position.]	No retransmission output, Input 1_Measured value (PV), Input 1_Local SV, Input 1_SV monitor value, and Remote setting input value: Input 1_Input range high Control with PV select: PV select input range high Input 1_Deviation: +(Input 1_Input span) Input 2_Measured value (PV), Input 2_Local SV, and Input 2_SV monitor value: Input 2_Input range high Input 2_Deviation: +(Input 2_Input span) Manipulated output value, and Current transformer (CT) input value: 100.0 Measured value (PV) of differential temperature input: 100	

* Displayed when OUT1 type is Current output or Continuous voltage output.

Continued on the next page.

No.	Symbol	Name	Data range	Factory set value	User set value
215	<i>RLS1</i>	Retransmission output 1 scale low *	<p>No retransmission output, Input 1_Measured value (PV), Input 1_Local SV, Input 1_SV monitor value, and Remote setting input value:</p> <p>Input 1_Input range low to Input 1_Input range high When Control with PV select: PV select input range low to PV select input range high [Varies with the setting of the Decimal point position.]</p> <p>Input 1_Deviation: -(Input 1_Input span) to +(Input 1_Input span) [Varies with the setting of the Decimal point position.]</p> <p>Input 2_Measured value (PV), Input 2_Local SV, and Input 2_SV monitor value:</p> <p>Input 2_Input range low to Input 2_Input range high [Varies with the setting of the Decimal point position.]</p> <p>Input 2_Deviation: -(Input 2_Input span) to +(Input 2_Input span) [Varies with the setting of the Decimal point position.]</p> <p>Manipulated output value: -5.0 to +105.0 %</p> <p>Current transformer (CT) input value: 0.0 to 100.0 %</p> <p>Measured value (PV) of differential temperature input: -(Input 1_Input span) to +(Input 1_Input span) [Varies with the setting of the Decimal point position.]</p>	<p>No retransmission output, Input 1_Measured value (PV), Input 1_Local SV, Input 1_SV monitor value, and Remote setting input value: Input 1_Input range low Control with PV select: PV select input range low</p> <p>Input 1_Deviation: -(Input 1_Input span)</p> <p>Input 2_Measured value (PV), Input 2_Local SV, and Input 2_SV monitor value: Input 2_Input range low</p> <p>Input 2_Deviation: -(Input 2_Input span)</p> <p>Manipulated output value, and Current transformer (CT) input value: 0.0</p> <p>Measured value (PV) of differential temperature input: -100</p>	

* Displayed when OUT1 type is Current output or Continuous voltage output.

■ Function block No. 32: Retransmission output 2 (*Ro2*)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn32</i>	Function block No. 32 *	This is the first parameter symbol of Function block No. 32	—	—
216	<i>Ro2</i>	Retransmission output 2 type *	Same as Retransmission output 1 type	0	
217	<i>RHS2</i>	Retransmission output 2 scale high *	Same as Retransmission output 1 scale high		
218	<i>RLS2</i>	Retransmission output 2 scale low *	Same as Retransmission output 1 scale low		

* Displayed when OUT2 type is Current output or Continuous voltage output.

■ Function block No. 33: Retransmission output 3 (*Ro3*)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn33</i>	Function block No. 33 *	This is the first parameter symbol of Function block No. 33	—	—
219	<i>Ro3</i>	Retransmission output 3 type *	Same as Retransmission output 1 type	1	
220	<i>RHS3</i>	Retransmission output 3 scale high *	Same as Retransmission output 1 scale high		
221	<i>RLS3</i>	Retransmission output 3 scale low *	Same as Retransmission output 1 scale low		

* Displayed when OUT3 is supplied and “Universal output type selection” is “Current output.”

■ Function block No. 34: Digital output (do)

No.	Symbol	Name	Data range	Factory set value	User set value
—	F_{n34}	Function block No. 34 ¹	This is the first parameter symbol of Function block No. 34	—	—
222	$doSL_1$	DO1 function selection ¹	0: No assignment 1: Logic calculation output (Event, HBA, LBA, Input error) 2: RUN state output 3: Input 1_Manual mode state output 4: Input 2_Manual mode state output 5: Remote mode state output (Output of differential temperature control state, Input 2 state output of Control with PV select) 6: Input 1_Autotuning (AT) state output 7: Input 2_Autotuning (AT) state output 8: Output while Set value of Input 1 is changing 9: Output while Set value of Input 2 is changing 10: Output of the communication monitoring result 11: FAIL output	Based on Model code	
223	$doSL_2$	DO2 function selection ²	Same as DO1 function selection	Based on Model code	
224	$doSL_3$	DO3 function selection ²	Same as DO1 function selection	Based on Model code	
225	$doSL_4$	DO4 function selection ²	Same as DO1 function selection	Based on Model code	
226	doL_1	DO1 logic calculation selection ¹	0 to 4095 0: OFF +1: Event 1 +2: Event 2 +4: Event 3 +8: Event 4 +16: Heater break alarm 1 (HBA1) +32: Heater break alarm 2 (HBA2) +64: Control loop break alarm 1 (LBA1) +128: Control loop break alarm 2 (LBA2) +256: Input 1_Input error high +512: Input 1_Input error low +1024: Input 2_Input error high +2048: Input 2_Input error low To select two or more functions, sum each value.	Based on Model code	
227	doL_2	DO2 logic calculation selection ²	Same as DO1 logic calculation selection	Based on Model code	
228	doL_3	DO3 logic calculation selection ²	Same as DO1 logic calculation selection	Based on Model code	
229	doL_4	DO4 logic calculation selection ²	Same as DO1 logic calculation selection	Based on Model code	

¹ Displayed when Digital output (DO) is supplied.

² Displayed when four Digital outputs (DO) are supplied.

■ Function block No. 41: Event 1 (EB1)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn41</i>	Function block No. 41	This is the first parameter symbol of Function block No. 41	—	—
230	<i>EVA1</i>	Event 1 assignment *	1: Input 1 2: Input 2 3: Differential temperature input	1	
231	<i>ES1</i>	Event 1 type	0: None 1: Deviation high (Using SV monitor value) ^a 2: Deviation low (Using SV monitor value) ^a 3: Deviation high/low (Using SV monitor value) ^a 4: Band (Using SV monitor value) ^a 5: Deviation high/low (Using SV monitor value) [High/Low individual setting] ^a 6: Band (Using SV monitor value) [High/Low individual setting] ^a 7: SV high (Using SV monitor value) 8: SV low (Using SV monitor value) 9: Process high ^b 10: Process low ^b 11: Deviation high (Using local SV) ^a 12: Deviation low (Using local SV) ^a 13: Deviation high/low (Using local SV) ^a 14: Band (Using local SV) ^a 15: Deviation high/low (Using local SV) [High/Low individual setting] ^a 16: Band (Using local SV) [High/Low individual setting] ^a 17: SV high (Using local SV) 18: SV low (Using local SV) 19: MV high [heat-side] ^b 20: MV low [heat-side] ^b 21: MV high [cool-side] ^b 22: MV low [cool-side] ^b 23: Process high/low [High/Low individual setting] ^b 24: Process band [High/Low individual setting] ^b	If the Event type is specified by the initial setting code when ordering, that Event type will be the factory set value. If the Event type is not specified: 1	
232	<i>EHa1</i>	Event 1 hold action	0: Hold action OFF 1: Hold action ON 2: Re-hold action ON Setting hold or re-hold action on the event that is not available with hold and re-hold actions will just be ignored.	If the Event type is specified by the initial setting code when ordering, the factory set value of Event hold action differs depending on the Event type. If the Event type is not specified: 0	
233	<i>EH1</i>	Event 1 differential gap	Deviation, Process and SV: • If event assignment is either Input 1 or Differential temperature. 0 to Input 1_Input span (When Control with PV select: 0 to PV select input span) • If event assignment is Input 2 0 to Input 2_Input span [Varies with the setting of the Decimal point position.] MV: 0.0 to 110.0 %	Deviation, Process and SV: TC/RTD inputs: 2 V/I inputs: 0.2 % of input span MV: 0.2	
234	<i>EVT1</i>	Event 1 timer	0.0 to 600.0 seconds	0.0	

* Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2."

■ Function block No. 42: Event 2 (EB2)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>F_n42</i>	Function block No. 42	This is the first parameter symbol of Function block No. 42	—	—
235	<i>EVA2</i>	Event 2 assignment *	Same as Event 1 assignment		
236	<i>E52</i>	Event 2 type	Same as Event 1 type		
237	<i>EHa2</i>	Event 2 hold action	Same as Event 1 hold action		
238	<i>EH2</i>	Event 2 differential gap	Same as Event 1 differential gap		
239	<i>EVT2</i>	Event 2 timer	Same as Event 1 timer		

* Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2."

■ Function block No. 43: Event 3 (EB3)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>F_n43</i>	Function block No. 43	This is the first parameter symbol of Function block No. 43	—	—
240	<i>EVA3</i>	Event 3 assignment *	Same as Event 1 assignment		
241	<i>E53</i>	Event 3 type	Same as Event 1 type		
242	<i>EHa3</i>	Event 3 hold action	Same as Event 1 hold action		
243	<i>EH3</i>	Event 3 differential gap	Same as Event 1 differential gap		
244	<i>EVT3</i>	Event 3 timer	Same as Event 1 timer		

* Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2."

■ Function block No. 44: Event 4 (EB4)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>F_n44</i>	Function block No. 44	This is the first parameter symbol of Function block No. 44	—	—
245	<i>EVA4</i>	Event 4 assignment *	Same as Event 1 assignment		
246	<i>E54</i>	Event 4 type	Same as Event 1 type		
247	<i>EHa4</i>	Event 4 hold action	Same as Event 1 hold action		
248	<i>EH4</i>	Event 4 differential gap	Same as Event 1 differential gap		
249	<i>EVT4</i>	Event 4 timer	Same as Event 1 timer		

* Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2."

■ Function block No. 45: CT1 (CT1)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn45</i>	Function block No. 45 *	This is the first parameter symbol of Function block No. 45	—	—
250	<i>CTA1</i>	CT1 assignment *	0: None 1: OUT1 2: OUT2 3: OUT3	1	
251	<i>CTE1</i>	CT1 type *	0: CTL-6-P-N 1: CTL-12-S56-10L-N 2: CTL-6-P-Z	Based on Model code	
252	<i>CTR1</i>	CT1 ratio *	0 to 9999 When the CT type is changed, the following value will be automatically set. CTL-6-P-N: 800 CTL-12-S56-10L-N: 1000 CTL-6-P-Z: 800	If CTL-6-P-N or CTL-6-P-Z is specified for the Current transformer (CT) type: 800 If CTL-12-S56-10L-N is specified for the Current transformer (CT) type: 1000	
253	<i>CLC1</i>	CT1 low input cut-off *	0.0 to 1.0 A	0.0	

* Displayed when Current transformer (CT) input is supplied.

■ Function block No. 46: CT2 (CT2)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn46</i>	Function block No. 46 *	This is the first parameter symbol of Function block No. 46	—	—
254	<i>CTA2</i>	CT2 assignment *	0: None 1: OUT1 2: OUT2 3: OUT3	Based on Model code	
255	<i>CTE2</i>	CT2 type *	0: CTL-6-P-N 1: CTL-12-S56-10L-N 2: CTL-6-P-Z	Based on Model code	
256	<i>CTR2</i>	CT2 ratio *	0 to 9999 When the CT type is changed, the following value will be automatically set. CTL-6-P-N: 800 CTL-12-S56-10L-N: 1000 CTL-6-P-Z: 800	If CTL-6-P-N or CTL-6-P-Z is specified for the Current transformer (CT) type: 800 If CTL-12-S56-10L-N is specified for the Current transformer (CT) type: 1000	
257	<i>CLC2</i>	CT2 low input cut-off *	0.0 to 1.0 A	0.0	

* Displayed when two Current transformer (CT) inputs are supplied.

■ Function block No. 50: Control (Cont)

No.	Symbol	Name	Data range	Factory set value	User set value
—	F_{n50}	Function block No. 50	This is the first parameter symbol of Function block No. 50	—	—
258	P_d	Hot/Cold start	0: Hot start 1 1: Hot start 2 2: Cold start 3: STOP start	0	
259	$MVFS$	Manual manipulated output value selection	0: The last manipulated output value (Balanceless-bumpless function) 1: Manual manipulated output value	0	
260	FRK	SV tracking	0 to 3 0: No SV tracking function +1: SV tracking at transferring Remote/Local * * Including 2-loop control/Differential temperature control transfer +2: SV tracking at transferring Auto/Manual To select two or more functions, sum each value.	1	
261	$IddP$	Integral/Derivative time decimal point position	0: No decimal place 1: One decimal place 2: Two decimal places 3: Three decimal places	2	
262	SFS	ST start condition	0: Activate the Startup tuning (ST) function when the power is turned on; when transferred from STOP to RUN; or when the Set value (SV) is changed. 1: Activate the Startup tuning (ST) function when the power is turned on; or when transferred from STOP to RUN. 2: Activate the Startup tuning (ST) function when the Set value (SV) is changed.	0	

■ Function block No. 51: Input 1_Control (*I.Cntr*)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn51</i>	Function block No. 51	This is the first parameter symbol of Function block No. 51	—	—
263	<i>I.oS</i>	Input 1_Control action	0: Brilliant II PID control (direct action) 1: Brilliant II PID control (reverse action) 2: Brilliant II Heat/Cool PID control [water cooling] 3: Brilliant II Heat/Cool PID control [air cooling] 4: Brilliant II Heat/Cool PID control [Cooling linear type] For 2-loop control/Differential temperature control, only 0 or 1 is selectable.	Control action specified at the time of order.	
264	<i>I.oRU</i>	Input 1_Output change rate limiter (up) [heat-side]	0.0 to 1000.0 %/seconds of manipulated output 0.0: OFF	0.0	
265	<i>I.oRd</i>	Input 1_Output change rate limiter (down) [heat-side]	0.0 to 1000.0 %/seconds of manipulated output 0.0: OFF	0.0	
266	<i>I.RovE</i>	Input 1_Action (high) input error	0: Control continues (with the latest output) 1: Manipulated output value at input error (Manual mode) The operation mode is switched to the Manual mode and the Input 1_Manipulated output value at input error is output. 2: Manipulated output value at input error (Auto mode) The operation mode remains in the Auto mode and the Input 1_Manipulated output value at input error of is output. When the error is recovered, the operation mode is switched to the PID control.	2	
267	<i>I.RUNE</i>	Input 1_Action (low) input error	0: Control continues (with the latest output) 1: Manipulated output value at input error (Manual mode) The operation mode is switched to the Manual mode and the Input 1_Manipulated output value at input error is output. 2: Manipulated output value at input error (Auto mode) The operation mode remains in the Auto mode and the Input 1_Manipulated output value at input error of is output. When the error is recovered, the operation mode is switched to the PID control.	2	
268	<i>I.PSM</i>	Input 1_Manipulated output value at input error	PID control: -5.0 to +105.0 % Heat/Cool PID control: -105.0 to +105.0 %	PID control: -5.0 Heat/Cool PID control: 0.0	
269	<i>I.RMV</i>	Input 1_Manipulated output value at STOP [heat-side]	-5.0 to +105.0 %	-5.0	
270	<i>I.PdR</i>	Input 1_Start determination point	0 to Input 1_Input span (When Control with PV select: 0 to PV select input span) 0: Operation starts from any start state selected by Hot/Cold start [Varies with the setting of the Decimal point position.]	3 % of Input 1_Input span Control with PV select: 3 % of PV select input span	
271	<i>I.LPI_d</i>	Input 1_Level PID action selection	0: Switching by Memory area number 1: Switching by Set value (SV) (Level PID action) 2: Switching by Measured value (PV) (Level PID action)	0	
272	<i>I.LHS</i>	Input 1_Level PID differential gap	0 to Input 1_Input span (When Control with PV select: 0 to PV select input span) [Varies with the setting of the Decimal point position.]	TC/RTD inputs: 2 V/I inputs: 0.2 % of Input 1_input span Control with PV select: 0.2 % of PV select input span	

■ Function block No. 52: Input 2_Control (2.Cntr)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn52</i>	Function block No. 52 *	This is the first parameter symbol of Function block No. 52	—	—
273	<i>2.oS</i>	Input 2_Control action *	0: Brilliant II PID control (direct action) 1: Brilliant II PID control (reverse action)	Same as Input 1_Control action	
274	<i>2.oRU</i>	Input 2_Output change rate limiter (up) *	0.0 to 1000.0 %/seconds of manipulated output 0.0: OFF	0.0	
275	<i>2.oRd</i>	Input 2_Output change rate limiter (down) *	0.0 to 1000.0 %/seconds of manipulated output 0.0: OFF	0.0	
276	<i>2.RovE</i>	Input 2_Action (high) input error *	0: Control continues (with the latest output) 1: Manipulated output value at input error (Manual mode) The operation mode is switched to the Manual mode and the Input 2_Manipulated output value at input error is output. 2: Manipulated output value at input error (Auto mode) The operation mode remains in the Auto mode and the Input 2_Manipulated output value at input error of is output. When the error is recovered, the operation mode is switched to the PID control.	2	
277	<i>2.RUNE</i>	Input 2_Action (low) input error *	0: Control continues (with the latest output) 1: Manipulated output value at input error (Manual mode) The operation mode is switched to the Manual mode and the Input 2_Manipulated output value at input error is output. 2: Manipulated output value at input error (Auto mode) The operation mode remains in the Auto mode and the Input 2_Manipulated output value at input error of is output. When the error is recovered, the operation mode is switched to the PID control.	2	
278	<i>2.PSM</i>	Input 2_Manipulated output value at input error *	-5.0 to +105.0 %	-5.0	
279	<i>2.RMV</i>	Input 2_Manipulated output value at STOP *	-5.0 to +105.0 %	-5.0	
280	<i>2.PdR</i>	Input 2_Start determination point *	0 to Input 2_Input span 0: Operation starts from any start state selected by Hot/Cold start [Varies with the setting of the Decimal point position.]	3 % of Input 2_Input span	
281	<i>2.LPI_d</i>	Input 2_Level PID action selection *	0: Switching by Memory area number 1: Switching by Set value (SV) (Level PID action) 2: Switching by Measured value (PV) (Level PID action)	0	
282	<i>2.LHS</i>	Input 2_Level PID differential gap *	0 to Input 2_Input span [Varies with the setting of the Decimal point position.]	TC/RTD inputs: 2 V/I inputs: 0.2 % of Input 2_input span	

* Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2."

■ Function block No. 56: Input 1_Cooling control (*I.Cool*)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn56</i>	Function block No. 56 *	This is the first parameter symbol of Function block No. 56	—	—
283	<i>I.oRUC</i>	Input 1_Output change rate limiter (up) [cool-side] *	0.0 to 1000.0 %/seconds of manipulated output 0.0: OFF	0.0	
284	<i>I.oRdc</i>	Input 1_Output change rate limiter (down) [cool-side] *	0.0 to 1000.0 %/seconds of manipulated output 0.0: OFF	0.0	
285	<i>IRMVC</i>	Input 1_Manipulated output value at STOP [cool-side] *	-5.0 to +105.0 %	-5.0	
286	<i>US</i>	Undershoot suppression factor *	0.000 to 1.000	Water cooling: 0.100 Air cooling: 0.250 Cooling linear: 1.000	
287	<i>dbPR</i>	Overlap/Deadband reference point *	0.0 to 1.0	0.0	

* Displayed when the Control action is Heat/Cool PID control.

■ Function block No. 57: Proactive (*PACT*)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn57</i>	Function block No. 57	This is the first parameter symbol of Function block No. 57	—	—
288	<i>bFMSF</i>	Bottom suppression function	0: No function 1: FF amount is added by level 2: FF amount is forcibly added	0	

■ Function block No. 58: 2-input function (*2PV*)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn58</i>	Function block No. 58 ¹	This is the first parameter symbol of Function block No. 58	—	—
289	<i>2PV</i>	Select function for input 2 ¹	0: No function 1: Remote setting input 2: 2-loop control/Differential temperature control * 3: Control with PV select 6: Input circuit error alarm * This parameter cannot be specified if the instrument is a Heat/Cool PID type. • When Measured input 2 is selected at the time of order: 0 to 3, 6 • When the Remote setting input is selected: 0 to 1	Based on Model code	
290	<i>2PV.GG</i>	Selection of PV select trigger ²	0: Switching by level 1: Switching by signal (Key, DI and Communication)	0	
291	<i>I.CR</i>	Input circuit error alarm set value ³	0 to Input 1_Input span 0: No function [Varies with the setting of the Decimal point position.]	TC/RTD inputs: 10 V/I inputs: 5 % of Input 1_Input span	

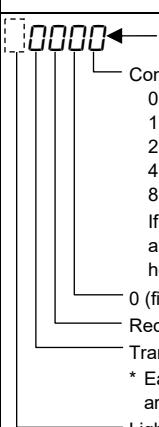
¹ Displayed when Remote setting input or Measured input 2 ** is supplied.

** Even if Measured input 2 is specified at the time of order, the Remote setting input can be selected later. In this case, thermocouple (TC) or RTD can be selected as a Remote setting input type. (If Remote setting input is specified, selecting a thermocouple or an RTD is not available.)

² Displayed when "Control with PV select" is selected in "Select function for input 2."

³ Displayed when "Input circuit error alarm" is selected in "Select function for input 2."

■ Function block No. 60: Communication (SCI)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn60</i>	Function block No. 60 *	This is the first parameter symbol of Function block No. 60	—	—
292	<i>CMP5</i>	Communication protocol *	0: RKC communication 1: Modbus (Order of data transfer: upper word to lower word) 2: Modbus (Order of data transfer: lower word to upper word) 3: PLC communication (MITSUBISHI MELSEC series special protocol QnA-compatible 3C frame [format 4])	When the communication protocol is specified at the time of order, the specified communication protocol will be the factory preset value. With communication, communication protocol not specified: 0	
293	<i>Rdd</i>	Device address *	RKC communication: 0 to 99 Modbus: 1 to 99 PLC communication: 0 to 30	RKC communication: 0 Modbus: 1 PLC communication: 0	
294	<i>bPS</i>	Communication speed *	0: 2400 bps 1: 4800 bps 2: 9600 bps 3: 19200 bps 4: 38400 bps 5: 57600 bps 6: 115200 bps	3	
295	<i>bit</i>	Data bit configuration *	0 to 11 See Data bit configuration table	0	
296	<i>INr</i>	Interval time *	0 to 250 ms	10	
297	<i>CMRM</i>	Communication response monitor *	 Communication response monitor 0: Normal response 1: Overrun error 2: Parity error 4: Framing error 8: Receive buffer overflow If two or more errors occur, the error values are summed up. Errors are displayed in the hexadecimal format (0 to F). 0 (fixed) Reception status monitor * Transmission status monitor * * Each time signal is sent or received, 0 and 1 are displayed in turns. Lights off	—	—

* Displayed when Communication function is supplied.

Data bit configuration table

Set value	Data bit	Parity bit	Stop bit
0	8	Without	1
1	8	Without	2
2	8	Even	1
3	8	Even	2
4	8	Odd	1
5	8	Odd	2

Set value	Data bit	Parity bit	Stop bit
6	7	Without	1
7	7	Without	2
8	7	Even	1
9	7	Even	2
10	7	Odd	1
11	7	Odd	2

: Not settable for Modbus

■ Function block No. 62: PLC communication (Fn62)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn62</i>	Function block No. 62 ¹	This is the first parameter symbol of Function block No. 62	—	—
298	<i>MP.REG</i>	Register type ¹	Mitsubishi PLC 0: D register (data register) 1: R register (file register) 2: W register (link register) 3: ZR register (Method of specifying consecutive numbers when 32767 of R register is exceeded.)	0	
299	<i>MP.SRH</i>	Register start number (High-order 4-bit) ¹	0 to 15	0	
300	<i>MP.SRL</i>	Register start number (Low-order 16-bit) ¹	0 to 65535	1000	
301	<i>MP.Mod</i>	Monitor item register bias ¹	12 to 65535	12	
302	<i>MP.SLb</i>	Setting item register bias ¹	0 to 65535	0	
303	<i>MP.LFM</i>	Instrument link recognition time ¹	0 to 255 seconds	5	
304	<i>MP.FMo</i>	PLC response waiting time ¹	0 to 3000 ms	255	
305	<i>MP.SFM</i>	PLC communication start time ¹	1 to 255 seconds	5	
306	<i>MP.SLB</i>	Slave register bias ¹	0 to 65535	80	
307	<i>MP.MAd</i>	Number of recognizable devices ¹	0 to 30	8	

¹ Displayed when both Communication function and PLC communication protocol are supplied.

■ Function block No. 70: Memory area (Fn70)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn70</i>	Function block No. 70	This is the first parameter symbol of Function block No. 70	—	—
308	<i>SvRF</i>	Setting change rate limiter unit time	0.1 to 360.0 seconds	0.1	
309	<i>SrdP</i>	Soak time unit	0: 0 hours 00 minutes to 99 hours 59 minutes 1: 0 minutes 00 seconds to 199 minutes 59 seconds 2: 0 hours 0 minutes 0 seconds to 9 hours 59 minutes 59 seconds 3: 0.00 seconds to 59.99 seconds In case of Input data type 0 or 2: 0 to 3 In case of Input data type 1: 0 or 1, 3	3	

■ Function block No. 71: Input 1_Setting limiter (I. SRL)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>Fn71</i>	Function block No. 71	This is the first parameter symbol of Function block No. 71	—	—
310	<i>I. SLH</i>	Input 1_Setting limiter high	Input 1_Setting limiter low to Input 1_Input range high When Control with PV select Input 1_Setting limiter low to PV select input range high [Varies with the setting of the Decimal point position.]	Input 1_ Input range high Control with PV select: PV select input range high	
311	<i>I. SLL</i>	Input 1_Setting limiter low	Input 1_Input range low to Input 1_Setting limiter high When Control with PV select PV select input range low to Input 1_Setting limiter high [Varies with the setting of the Decimal point position.]	Input 1_ Input range low Control with PV select: PV select input range low	

■ Function block No. 72: Input 2_Setting limiter (2. *SL*)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>F_n72</i>	Function block No. 72 *	This is the first parameter symbol of Function block No. 72	—	—
312	<i>2. SLH</i>	Input 2_Setting limiter high *	Input 2_Setting limiter low to Input 2_Input range high [Varies with the setting of the Decimal point position.]	Input 2_ Input range high	
313	<i>2. SLL</i>	Input 2_Setting limiter low *	Input 2_Input range low to Input 2_Setting limiter high [Varies with the setting of the Decimal point position.]	Input 2_ Input range low	

* Displayed when "2-loop control/Differential temperature control" is selected in "Select function for input 2."

■ Function block No. 91: System (S95)

No.	Symbol	Name	Data range	Factory set value	User set value
—	<i>F_n91</i>	Function block No. 91	This is the first parameter symbol of Function block No. 91	—	—
—	<i>dEF</i>	Initialization	1225: Start initialization Other values: Set values are maintained After the initialization, this instrument is restarted. This setting will automatically go back to zero.	0	—
—	<i>WF</i>	Integrated operating time	0 to 65535 hours	—	—
—	<i>FCJ</i>	Peak hold monitor of ambient temperature	-120 to +120 °C	—	—
—	<i>R_oM</i>	ROM version	The installed ROM version is displayed	—	—
—	<i>GZ900</i>	Model code monitor	Model code is displayed. Use the UP or DOWN key to scroll the display horizontally (left or right).	—	—
—	<i>00000</i> The serial number of the instrument is displayed.	Instrument number monitor	Instrument number is displayed.	—	—

PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED

4

This chapter describes the parameters that are initialized/modified when setting is changed.

4.1 Parameters to Be Initialized	4-2
4.2 Parameters to Be Automatically Converted.....	4-21

4.1 Parameters to Be Initialized

Changing any of the following parameters will require initialization * of the related settings.

* Settings are reset to the factory preset values. Some parameters may not be set to a factory preset value (such as change of input type).



Make sure all settings are recorded before changing the set values.



Check all set values after having changed the settings.

			See page
• <u>Select function for input 2</u>	Engineering Mode	Function block No. 58	4-3
• <u>Input 1_Input type</u>	Engineering Mode	Function block No. 21	4-6
• <u>Input 1_Display unit</u>	Engineering Mode	Function block No. 21	4-6
• <u>Input 1_Decimal point position</u>	Engineering Mode	Function block No. 21	4-9
• <u>Input 2_Input type</u>	Engineering Mode	Function block No. 22	4-10
• <u>Input 2_Display unit</u>	Engineering Mode	Function block No. 22	4-10
• <u>Input 1_Control action</u>	Engineering Mode	Function block No. 51	4-12
• <u>Input 1_Selection of correction value setting</u>	Engineering Mode	Function block No. 21	4-13
• <u>Input 2_Selection of correction value setting</u>	Engineering Mode	Function block No. 22	4-13
• <u>OUT1 function selection</u>	Engineering Mode	Function block No. 30	4-14
• <u>OUT2 function selection</u>	Engineering Mode	Function block No. 30	4-14
• <u>OUT3 function selection</u>	Engineering Mode	Function block No. 30	4-14
• <u>Universal output type selection</u>	Engineering Mode	Function block No. 30	4-14
• <u>Retransmission output 1 type</u>	Engineering Mode	Function block No. 31	4-15
• <u>Retransmission output 2 type</u>	Engineering Mode	Function block No. 32	4-16
• <u>Retransmission output 3 type</u>	Engineering Mode	Function block No. 33	4-16
• <u>Event 1 type</u>	Engineering Mode	Function block No. 41	4-16
• <u>Event 1 assignment</u>	Engineering Mode	Function block No. 41	4-16
• <u>Event 2 type</u>	Engineering Mode	Function block No. 42	4-17
• <u>Event 2 assignment</u>	Engineering Mode	Function block No. 42	4-17
• <u>Event 3 type</u>	Engineering Mode	Function block No. 43	4-17
• <u>Event 3 assignment</u>	Engineering Mode	Function block No. 43	4-17
• <u>Event 4 type</u>	Engineering Mode	Function block No. 44	4-18
• <u>Event 4 assignment</u>	Engineering Mode	Function block No. 44	4-18
• <u>CT1 type</u>	Engineering Mode	Function block No. 45	4-18
• <u>CT2 type</u>	Engineering Mode	Function block No. 46	4-18
• <u>Integral/Derivative time decimal point position</u>	Engineering Mode	Function block No. 50	4-19
• <u>Communication protocol</u>	Engineering Mode	Function block No. 60	4-19
• <u>Register type</u>	Engineering Mode	Function block No. 62	4-19
• <u>Soak time unit</u>	Engineering Mode	Function block No. 70	4-20
• <u>Initialization</u>	Engineering Mode	Function block No. 91	4-20

4.1.1 When Select function for input 2 ($2PV$) is changed [Engineering Mode: Function block No. 58]

The following parameters will be initialized.

Some parameters may have prerequisites for initialization. (See the prerequisite and P. 4-5)

Mode	Items	Symbol	Initial value	Condition
Operation Transfer Mode	Remote/Local transfer When "Remote setting input" is selected at Select function for Input 2	R/L	LoC	—
	Remote/Local transfer When "Control with PV select" is selected at Select function for input 2	R/L	InP/I	—
	Remote/Local transfer When "2-loop control/Differential temperature control" is selected at Select function for input 2	R/L	2Loop	—
Monitor & SV Setting Mode	Input 1_Set value (SV)		0	1
Parameter Setting Mode	Parameter group No. 00	Input 1_Set value (SV)	I. SV	0
		Event 1 set value (EV1) Event 1 set value (EV1) [high]	EV1	4
		Event 2 set value (EV2) Event 2 set value (EV2) [high]	EV2	4
		Event 3 set value (EV3) Event 3 set value (EV3) [high]	EV3	4
		Event 4 set value (EV4) Event 4 set value (EV4) [high]	EV4	4
		Event 1 set value (EV1') [low]	EV1'	4
		Event 2 set value (EV2') [low]	EV2'	4
		Event 3 set value (EV3') [low]	EV3'	4
		Event 4 set value (EV4') [low]	EV4'	4
	Parameter group No. 40	Input 1_Proportional band [heat-side]	I. P	TC/RTD inputs: 30 V/I inputs: 3.0
		Input 1_Integral time [heat-side]	I. I	240
		Input 1_Derivative time [heat-side]	I. d	60
		Input 1_Control response parameter	I. RPF	PID control: 0 Heat/Cool PID control: 2
		Input 1_Proactive intensity	I. PACF	2
		Input 1_Manual reset	I. MR	0.0
		Input 1_FF amount	I. FF	0.0
		Input 1_Control loop break alarm (LBA) time	I. Lba	LBA function is specified: 480 LBA function is not specified: 0
	Parameter group No. 51	Input 1_LBA deadband (LBD)	I. Lbd	0
		Input 1_ON/OFF action differential gap (upper)	I. oHH	TC/RTD inputs: 1
		Input 1_ON/OFF action differential gap (lower)	I. oHL	V/I inputs: 0.1
		Input 1_Proportional band [cool-side]	I. Pc	TC/RTD inputs: 30 V/I inputs: 3.0
		Input 1_Integral time [cool-side]	I. Ic	240
		Input 1_Derivative time [cool-side]	I. dc	60
		Input 1_Overlap/Deadband	I. db	TC/RTD inputs: 0 V/I inputs: 0.0
		Parameter group No. 70	I. SVRU	0
Setup Setting Mode	Setting group No. 21	Input 1_Setting change rate limiter (up)	I. SVRU	1
	Setting group No. 22	Input 1_Setting change rate limiter (down)	I. SVRd	1
	Setting group No. 21	Input 2_PV bias	I. Pb	0
	Setting group No. 22	Input 2_PV bias (RS bias)	2. Pb	0
			2	

Mode	Items	Symbol	Initial value	Condition
Setup Setting Mode	Setting group No. 22	Input 2_PV digital filter (RS digital filter)	2.dF	0.00
		Input 2_PV ratio (RS ratio)	2.PR	1.000
	Setting group No. 51	Input 1_Level PID setting 1	1.LEV1	1
		Input 1_Level PID setting 2	1.LEV2	1
		Input 1_Level PID setting 3	1.LEV3	1
		Input 1_Level PID setting 4	1.LEV4	1
		Input 1_Level PID setting 5	1.LEV5	1
		Input 1_Level PID setting 6	1.LEV6	1
		Input 1_Level PID setting 7	1.LEV7	1
	Setting group No. 53	Input 1_AT bias	1.RFB	0
	Setting group No. 57	Input 1_Determination point of external disturbance	1.EXDJ	-1
Engineering Mode	Function block No. 21	Input 1_Decimal point position	1.PGdP	0
	Function block No. 22	Input 2_Input type	2.INP	Same as Input 1_Input type When Remote setting input is specified at the time of order: 17
		Input 2_Display unit	2.UNI	Same as Input 1_Display unit Only when the input type is Control with PV select, Input circuit error alarm, and Remote setting input (V/I inputs). Not initialized in other cases.
		Input 2_Decimal point position	2.PGdP	Same as Input 1_Decimal point position Only when the input type is Control with PV select, Input circuit error alarm, and Remote setting input (V/I inputs). Zero (0) for other cases.
		Input 2_Input range high	2.PGSH	•TC/RTD inputs Input 2_Maximum value of input range •V/I inputs Remote setting input: Input 1_Maximum value of input range Others: 100
		Input 2_Input range low	2.PGSL	•TC/RTD inputs Input 2_Minimum value of input range •V/I inputs Remote setting input: Input 1_Minimum value of input range Others: 0
	Function block No. 31	Retransmission output 1 scale high	RHS1	Input 1_Measured value (PV), Input 1_Local SV, Input 1_SV monitor value, and Remote setting input value: Input 1_Input range high Control with PV select: PV select input range high Input 1_Deviation: +(Input 1_Input span) Measured value (PV) of differential temperature input: 100
		Retransmission output 1 scale low	RLS1	Input 1_Measured value (PV), Input 1_Local SV, Input 1_SV monitor value, and Remote setting input value: Input 1_Input range low Control with PV select: PV select input range low Input 1_Deviation: -(Input 1_Input span) Measured value (PV) of differential temperature input: -100
	Function block No. 32	Retransmission output 2 scale high	RHS2	Same as Retransmission output 1 scale high
		Retransmission output 2 scale low	RLS2	Same as Retransmission output 1 scale low

Mode	Items	Symbol	Initial value	Condition
Engineering Mode	Function block No. 33	Retransmission output 3 scale high	RHS3	Same as Retransmission output 1 scale high 1 and 7
		Retransmission output 3 scale low	RLS3	Same as Retransmission output 1 scale low 1 and 7
	Function block No. 41	Event 1 assignment	EVRI	1 —
		Event 1 differential gap	EH1	Deviation, Process and SV: TC/RTD inputs: 2 V/I inputs: 0.2 % of Input 1_input span Control with PV select: 0.2 % of PV select input span MV: 0.2 4
	Function block No. 42	Event 2 assignment	EVR2	1 —
		Event 2 differential gap	EH2	Same as Event 1 differential gap 4
	Function block No. 43	Event 3 assignment	EVR3	1 —
		Event 3 differential gap	EH3	Same as Event 1 differential gap 4
	Function block No. 44	Event 4 assignment	EVR4	1 —
		Event 4 differential gap	EH4	Same as Event 1 differential gap 4
	Function block No. 51	Input 1_Start determination point	I_PdR	3 % of Input 1_Input span Control with PV select: 3 % of PV select input span 1
	Function block No. 51	Input 1_Level PID differential gap	I_LHS	TC/RTD inputs: 2 V/I inputs: 0.2 % of Input 1_input span Control with PV select: 0.2 % of PV select input span 1
	Function block No. 58	Input circuit error alarm set value	I_CRA	TC/RTD inputs: 10 V/I inputs: 5 % of Input 1_Input span 3
	Function block No. 71	Input 1_Setting limiter high	I_SLH	Input 1_Input range high Control with PV select: PV select input range high 1
		Input 1_Setting limiter low	I_SLL	Input 1_Input range low Control with PV select: PV select input range low 1

Condition

- 1: "Select function for input 2" is switched between "Control with PV select" and "Others *."
 * No function, Remote setting input, 2-loop control/Differential temperature control, and Input circuit error alarm.
- 2: "Select function for input 2" is switched between "Remote setting input" and "Others *."
 * No function, Control with PV select, 2-loop control/Differential temperature control, and Input circuit error alarm.
- 3: "Select function for input 2" is switched between "Input circuit error alarm" and "Others *."
 * No function, Remote setting input, Control with PV select, and 2-loop control/Differential temperature control.
- 4: Event type is other than Manipulated output value AND "Select function for input 2" is switched between "Control with PV select" and "Others *."
 * No function, Remote setting input, 2-loop control/Differential temperature control, and Input circuit error alarm.
- 5: "Select function for input t 2" is switched to any one of "Remote setting input," "Control with PV select," or "Input circuit error alarm" and "Others *."
 * No function, and 2-loop control/Differential temperature control.
- 6: "Select function for input 2" is switched to any one of "Remote setting input" or "Input circuit error alarm" and "Others *."
 * No function, Control with PV select, and 2-loop control/Differential temperature control.
- 7: Retransmission output is "No retransmission output," "Input 1_Measured value (PV)," "Input 1_Set value (SV)," "Input 1_Deviation," "Input 1_Remote setting input value," OR Measured value (PV) of differential temperature input.

4.1.2 When Input 1_Input type (I, I NP) and Input 1_Display unit (IUNI Γ) are changed [Engineering Mode: Function block No. 21]

The following parameters will be initialized.

Some parameters may have prerequisites for initialization. (See the prerequisite and P. 4-9)

Mode	Items	Symbol	Initial value	Condition
Monitor & SV Setting Mode	Input 1_Set value (SV)	$\text{I. } \cancel{SV}$	Input 1_Set value (SV)	—
	Set value (SV) of differential temperature input	$\text{I. } \cancel{SV}$	Set value (SV) of differential temperature input	—
Parameter group No. 00	Input 1_Set value (SV)	$I. \text{ } 5V$	0	—
	Set value (SV) of differential temperature input	$d5V$	0	—
Parameter group No. 40	Event 1 set value (EV1) Event 1 set value (EV1) [high]	$EV \text{ } 1$	Deviation, Process and SV: TC/RTD inputs: 10 V/I inputs: 5 % of input span MV: 50.0	3
	Event 2 set value (EV2) Event 2 set value (EV2) [high]	$EV \text{ } 2$		3
	Event 3 set value (EV3) Event 3 set value (EV3) [high]	$EV \text{ } 3$		3
	Event 4 set value (EV4) Event 4 set value (EV4) [high]	$EV \text{ } 4$		3
	Event 1 set value (EV1') [low]	$EV \text{ } 1'$		3
	Event 2 set value (EV2') [low]	$EV \text{ } 2'$		3
	Event 3 set value (EV3') [low]	$EV \text{ } 3'$		3
	Event 4 set value (EV4') [low]	$EV \text{ } 4'$		3
	Input 1_Proportional band [heat-side]	$I. \text{ } P$	TC/RTD inputs: 30 V/I inputs: 3.0	—
	Input 1_Integral time [heat-side]	$I. \text{ } I$	240	—
Parameter Setting Mode	Input 1_Derivative time [heat-side]	$I. \text{ } d$	60	—
	Input 1_Control response parameter	$I. \text{ } RPI$	PID control: 0 Heat/Cool PID control: 2	—
	Input 1_Proactive intensity	$I. \text{ } PRACI$	2	—
	Input 1_Manual reset	$I. \text{ } MR$	0.0	—
	Input 1_FF amount	$I. \text{ } FF$	0.0	—
	Input 1_Control loop break alarm (LBA) time	$I. \text{ } LbR$	LBA function is specified: 480 LBA function is not specified: 0	—
	Input 1_LBA deadband (LBD)	$I. \text{ } Lbd$	0	—
	Input 1_ON/OFF action differential gap (upper)	$I. \text{ } \alpha HH$	TC/RTD inputs: 1 V/I inputs: 0.1	—
	Input 1_ON/OFF action differential gap (lower)	$I. \text{ } \alpha HL$		—
Parameter group No. 56	Input 1_Proportional band [cool-side]	$I. \text{ } P_c$	TC/RTD inputs: 30 V/I inputs: 3.0	—
	Input 1_Integral time [cool-side]	$I. \text{ } I_c$	240	—
	Input 1_Derivative time [cool-side]	$I. \text{ } dc$	60	—
	Input 1_Overlap/Deadband	$I. \text{ } db$	TC/RTD inputs: 0 V/I inputs: 0.0	—
Parameter group No. 70	Input 1_Setting change rate limiter (up)	$I. \text{ } SVRU$	0	—
	Input 1_Setting change rate limiter (down)	$I. \text{ } SVRd$	0	—
Parameter group No. 71	Input 1_Knee point input value 1	$I. \text{ } rP \text{ } 1$	Input 1_Input range high	—
	Input 1_Knee point input value 2	$I. \text{ } rP \text{ } 2$		—
	Input 1_Knee point input value 3	$I. \text{ } rP \text{ } 3$		—
	Input 1_Knee point input value 4	$I. \text{ } rP \text{ } 4$		—
	Input 1_Knee point input value 5	$I. \text{ } rP \text{ } 5$		—
	Input 1_Knee point correction value 1	$I. \text{ } rV \text{ } 1$	Deviation setting: 0 Direct setting: Input 1_Input range high	—
	Input 1_Knee point correction value 2	$I. \text{ } rV \text{ } 2$		—
	Input 1_Knee point correction value 3	$I. \text{ } rV \text{ } 3$		—
	Input 1_Knee point correction value 4	$I. \text{ } rV \text{ } 4$		—
	Input 1_Knee point correction value 5	$I. \text{ } rV \text{ } 5$		—

Mode	Items	Symbol	Initial value	Condition
Setup Setting Mode	Setting group No. 21	Input 1_PV bias	I. Pb	0
		Input 1_PV digital filter	I. dF	0.00
		Input 1_PV ratio	I. PR	1.000
		Input 1_PV low input cut-off ¹	I. PLC	0.00
	Setting group No. 22	Input 2_PV bias (RS bias)	2. Pb	0
		Input 2_PV digital filter (RS digital filter)	2. dF	0.00
		Input 2_PV ratio (RS ratio)	2. PR	1.000
	Setting group No. 51	Input 1_Level PID setting 1	ILEV1	—
		Input 1_Level PID setting 2	ILEV2	—
		Input 1_Level PID setting 3	ILEV3	—
		Input 1_Level PID setting 4	ILEV4	—
		Input 1_Level PID setting 5	ILEV5	—
		Input 1_Level PID setting 6	ILEV6	—
		Input 1_Level PID setting 7	ILEV7	—
	Setting group No. 53	Input 1_AT bias	I. ATb	0
	Setting group No. 57	Input 1_Determination point of external disturbance	IEXDD	-1
	Setting group No. 58	PV select transfer level	2PVLV	Input 1_Input range high
	Setting group No. 91	Input 1_Peak hold monitor	IPHLd	—
		Input 1_Bottom hold monitor	IbHLD	—
Engineering Mode	Function block No. 21	Input 1_Decimal point position ¹	I.PGdP	0
		Input 1_Input range high	I.PGS _H	• TC/RTD inputs: Input 1_Maximum value of input range • V/I inputs: 100
		Input 1_Input range low	I.PGS _L	• TC/RTD inputs: Input 1_Minimum value of input range • V/I inputs: 0
		Input 1_Input error determination point (high)	I. PoV	Input 1_Input range high + (Input 1_5 % of input span)
		Input 1_Input error determination point (low)	I. PUN	Input 1_Input range low - (Input 1_5 % of input span)
	Function block No. 22	Input 2_Display unit ²	2UNI _F	Same as Input 1_Display unit Only when the input type is Control with PV select, Input circuit error alarm, and Remote setting input (V/I inputs). Not initialized in other cases.
		Input 2_Decimal point position ¹	2PGdP	Same as Input 1_Decimal point position Only when the input type is Control with PV select, Input circuit error alarm, and Remote setting input (V/I inputs). Zero (0) for other cases.
		Input 2_Input range high	2PGSH	• TC/RTD inputs Input 2_Maximum value of input range • V/I inputs Remote setting input: Input 1_Maximum value of input range Others: 100
		Input 2_Input range low	2PGSL	• TC/RTD inputs Input 2_Minimum value of input range • V/I inputs Remote setting input: Input 1_Minimum value of input range Others: 0

¹ When the Input 1_Input type was changed.² When the Input 1_Display unit was changed.

Mode	Items	Symbol	Initial value	Condition
Engineering Mode	Function block No. 31	Retransmission output 1 scale high	RHS 1	Input 1_Measured value (PV), Input 1_Local SV, Input 1_SV monitor value, and Remote setting input value: Input 1_Input range high Control with PV select: PV select input range high Input 1_Deviation: +(Input 1_Input span) Measured value (PV) of differential temperature input: 100
				4
	Function block No. 32	Retransmission output 1 scale low	RLS 1	Input 1_Measured value (PV), Input 1_Local SV, Input 1_SV monitor value, and Remote setting input value: Input 1_Input range low Control with PV select: PV select input range low Input 1_Deviation: -(Input 1_Input span) Measured value (PV) of differential temperature input: -100
				4
	Function block No. 33	Retransmission output 2 scale high	RHS2	Same as Retransmission output 1 scale high
		Retransmission output 2 scale low	RLS2	Same as Retransmission output 1 scale low
	Function block No. 41	Retransmission output 3 scale high	RHS3	Same as Retransmission output 1 scale high
		Retransmission output 3 scale low	RLS3	Same as Retransmission output 1 scale low
	Function block No. 42	Event 1 differential gap	EH1	Deviation, Process and SV: TC/RTD inputs: 2 V/I inputs: 0.2 % of Input 1_input span Control with PV select: 0.2 % of PV select input span
	Function block No. 43	Event 2 differential gap	EH2	
	Function block No. 44	Event 3 differential gap	EH3	
	Function block No. 44	Event 4 differential gap	EH4	
	Function block No. 51	Input 1_Start determination point	I_PdR	3 % of Input 1_Input span Control with PV select: 3 % of PV select input span
		Input 1_Level PID differential gap	I_LHS	TC/RTD inputs: 2 V/I inputs: 0.2 % of Input 1_input span Control with PV select: 0.2 % of PV select input span
	Function block No. 58	Input circuit error alarm set value	I_CRA	TC/RTD inputs: 10 V/I inputs: 5 % of Input 1_Input span
	Function block No. 71	Input 1_Setting limiter high	I_SLH	Input 1_Input range high Control with PV select: PV select input range high
		Input 1_Setting limiter low	I_SLL	Input 1_Input range low Control with PV select: PV select input range low

Condition

- 1: “Select function for input 2” is Remote setting input AND Input 2_Input type is either voltage input or current input.
- 2: “Select function for input 2” is Remote setting input AND Input 2_Input type is either voltage input or current input, or Select function for input 2 is Control with PV select.
- 3: The condition is either of the following.
 - Event type is other than Manipulated output value AND “Select function for input 2” is set to “Control with PV select.”
 - Event type is other than Manipulated output value AND Event assignment is either “Input 1” or “Differential temperature input.”
- 4: Retransmission output is “No retransmission output,” “Input 1_Measured value (PV),” “Input 1_Set value (SV),” “Input 1_Deviation,” “Input 1_Remote setting input value,” OR Measured value (PV) of differential temperature input.

4.1.3 When Input 1_Decimal point position ($IPGdP$) is changed [Engineering Mode: Function block No. 21]

The following parameters will be initialized.

If Select function for input 2 is “Remote setting input” AND Input 2_Input type is Voltage/Current input, OR Select function for input 2 is “Control with PV select.”

Mode	Items	Symbol	Initial value
Engineering Mode	Function block No. 22	$IPGdP$	Same as Input 1_Decimal point position Only when the input type is Control with PV select, Input circuit error alarm, and Remote setting input (V/I inputs). Zero (0) for other cases.

4.1.4 When Input 2_Input type (2. I NP) and Input 2_Display unit (2.UNI Γ) are changed [Engineering Mode: Function block No. 22]

The following parameters will be initialized.

Some parameters may have prerequisites for initialization. (See the prerequisite and P. 4-12)

Mode	Items	Symbol	Initial value	Condition
Monitor & SV Setting Mode	Input 2_Set value (SV)		0	—
Parameter group No. 00	Input 2_Set value (SV)	2. 5V	0	—
	Event 1 set value (EV1) Event 1 set value (EV1) [high]	EV 1		3
	Event 2 set value (EV2) Event 2 set value (EV2) [high]	EV 2		3
	Event 3 set value (EV3) Event 3 set value (EV3) [high]	EV 3		3
	Event 4 set value (EV4) Event 4 set value (EV4) [high]	EV 4		3
	Event 1 set value (EV1') [low]	EV 1'		3
	Event 2 set value (EV2') [low]	EV 2'		3
	Event 3 set value (EV3') [low]	EV 3'		3
	Event 4 set value (EV4') [low]	EV 4'		3
Parameter Setting Mode	Input 2_Proportional band	2. P	TC/RTD inputs: 30 V/I inputs: 3.0	—
	Input 2_Integral time	2. I	240	—
	Input 2_Derivative time	2. d	60	—
	Input 2_Control response parameter	2. RPF	0	—
	Input 2_Proactive intensity	2.PACF	2	—
	Input 2_Manual reset	2. MR	0.0	—
	Input 2_FF amount	2. FF	0.0	—
	Input 2_Control loop break alarm (LBA) time	2. Lba	LBA function is specified: 480 LBA function is not specified: 0	—
	Input 2_LBA deadband (LBD)	2. Lbd	0	—
	Input 2_ON/OFF action differential gap (upper)	2. oHH	TC/RTD inputs: 1	—
Parameter group No. 70	Input 2_ON/OFF action differential gap (lower)	2. oHL	V/I inputs: 0.1	—
	Input 2_Setting change rate limiter (up)	2.5VRU	0	—
Parameter group No. 72	Input 2_Setting change rate limiter (down)	2.5VRd	0	—
	Input 2_Knee point input value 1	2. rP 1		—
	Input 2_Knee point input value 2	2. rP 2		—
	Input 2_Knee point input value 3	2. rP 3		—
	Input 2_Knee point input value 4	2. rP 4		—
	Input 2_Knee point input value 5	2. rP 5		—
	Input 2_Knee point correction value 1	2. rV 1		—
	Input 2_Knee point correction value 2	2. rV 2		—
	Input 2_Knee point correction value 3	2. rV 3		—
	Input 2_Knee point correction value 4	2. rV 4		—
	Input 2_Knee point correction value 5	2. rV 5		—

Mode	Items	Symbol	Initial value	Condition
Setup Setting Mode	Setting group No. 22	Input 2_PV bias (RS bias)	2. Pb	0
		Input 2_PV digital filter (RS digital filter)	2. dF	0.00
		Input 2_PV ratio (RS ratio)	2. PR	1.000
		Input 2_PV low input cut-off *	2. PLC	0.00
	Setting group No. 52	Input 2_Level PID setting 1	2LEV1	—
		Input 2_Level PID setting 2	2LEV2	—
		Input 2_Level PID setting 3	2LEV3	—
		Input 2_Level PID setting 4	2LEV4	—
		Input 2_Level PID setting 5	2LEV5	—
		Input 2_Level PID setting 6	2LEV6	—
		Input 2_Level PID setting 7	2LEV7	—
	Setting group No. 54	Input 2_AT bias	2. ATb	0
	Setting group No. 57	Input 2_Determination point of external disturbance	2EXdU	-1
	Setting group No. 91	Input 2_Peak hold monitor	2PHLd	—
		Input 2_Bottom hold monitor	2bHLd	—
Engineering Mode	Function block No. 21	Input 1_Decimal point position *	1PGdP	0
	Function block No. 22	Input 2_Decimal point position *	2PGdP	Same as Input 1_Decimal point position Only when the input type is Control with PV select, Input circuit error alarm, and Remote setting input (V/I inputs). Zero (0) for other cases.
		Input 2_Input range high	2PGSH	·TC/RTD inputs Input 2_Maximum value of input range ·V/I inputs Remote setting input: Input 1_Maximum value of input range Others: 100
		Input 2_Input range low	2PGSL	·TC/RTD inputs Input 2_Minimum value of input range ·V/I inputs Remote setting input: Input 1_Minimum value of input range Others: 0
		Input 2_Input error determination point (high)	2. Pv	Input 2_Input range high + (Input 2_5 % of input span)
		Input 2_Input error determination point (low)	2. PUN	Input 2_Input range low - (Input 2_5 % of input span)
	Function block No. 31	Retransmission output 1 scale high	RHS1	Input 2_Measured value (PV), Input 2_Local SV, and Input 2_SV monitor value: Input 2_Input range high Input 2_Deviation: +(Input 2_Input span)
		Retransmission output 1 scale low	RLS1	Input 2_Measured value (PV), Input 2_Local SV, and Input 2_SV monitor value: Input 2_Input range low Input 2_Deviation: -(Input 2_Input span)
	Function block No. 32	Retransmission output 2 scale high	RHS2	Same as Retransmission output 1 scale high
		Retransmission output 2 scale low	RLS2	Same as Retransmission output 1 scale low
	Function block No. 33	Retransmission output 3 scale high	RHS3	Same as Retransmission output 1 scale high
		Retransmission output 3 scale low	RLS3	Same as Retransmission output 1 scale low

* When the Input 2_Input type was changed.

Mode	Items	Symbol	Initial value	Condition
Engineering Mode	Function block No. 41	EH1	Deviation, Process and SV: TC/RTD inputs: 2 V/I inputs: 0.2 % of Input 2_input span MV: 0.2	3
	Function block No. 42	EH2		3
	Function block No. 43	EH3		3
	Function block No. 44	EH4		3
	Input 2_Start determination point	2. PdR	3 % of Input 2_Input span	—
	Function block No. 52	2. LHS	TC/RTD inputs: 2 V/I inputs: 0.2 % of Input 2_input span	—
	Input 2_Setting limiter high	2. SLH	Input 2_Input range high	—
	Input 2_Setting limiter low	2. SLL	Input 2_Input range low	—

Condition

- 1: If “Select function for input 2” is “Control with PV select.”
- 2: If “Select function for input 2” is other than “Control with PV select.”
- 3: If Event type is other than manipulated output AND “Select function for input 2” is other than “Control with PV select,” AND Event assignment is “Input 2.”
- 4: Retransmission output is “Input 1_Measured value (PV),” “Input 1_Set value (SV),” or “Input 1_Deviation.”

4.1.5 When Input 1_Control action (I. a5) is changed [Engineering Mode: Function block No. 51]

The following parameters will be initialized.

Some parameters may have prerequisites for initialization. (See following for the prerequisites)

Mode	Items	Symbol	Initial value	Condition
Parameter Setting Mode	Parameter group No. 51	I. RPF	PID control: 0 Heat/Cool PID control: 2	1
Engineering Mode	Function block No. 56	U5	Water cooling: 0.100 Air cooling: 0.250 Cooling linear: 1.000	—

Condition

- 1: When Input 1_Control action is other than switching between Dir/Rev action and Cooling action.

4.1.6 When Input 1_Selection of correction value setting (I. rV5) is changed [Engineering Mode: Function block No. 21]

Mode	Items	Symbol	Initial value	Condition
Parameter Setting Mode	Input 1_Number of knee point	I.norP	5	—
	Input 1_Knee point input value 1	I. rP1		—
	Input 1_Knee point input value 2	I. rP2		—
	Input 1_Knee point input value 3	I. rP3		Input 1_Input range high
	Input 1_Knee point input value 4	I. rP4		—
	Input 1_Knee point input value 5	I. rP5		—
	Input 1_Knee point correction value 1	I. rV1		—
	Input 1_Knee point correction value 2	I. rV2		Deviation setting: 0
	Input 1_Knee point correction value 3	I. rV3		Direct setting:
	Input 1_Knee point correction value 4	I. rV4		Input 1_Input range high
	Input 1_Knee point correction value 5	I. rV5		—

4.1.7 When Input 2_Selection of correction value setting (2. rV5) is changed [Engineering Mode: Function block No. 22]

Mode	Items	Symbol	Initial value	Condition
Parameter Setting Mode	Input 2_Number of knee point	2.norP	5	—
	Input 2_Knee point input value 1	2. rP1		—
	Input 2_Knee point input value 2	2. rP2		—
	Input 2_Knee point input value 3	2. rP3		Input 2_Input range high
	Input 2_Knee point input value 4	2. rP4		—
	Input 2_Knee point input value 5	2. rP5		—
	Input 2_Knee point correction value 1	2. rV1		—
	Input 2_Knee point correction value 2	2. rV2		Deviation setting: 0
	Input 2_Knee point correction value 3	2. rV3		Direct setting:
	Input 2_Knee point correction value 4	2. rV4		Input 2_Input range high
	Input 2_Knee point correction value 5	2. rV5		—

4.1.8 When OUT1 function selection ($\alpha S L_1$) is changed [Engineering Mode: Function block No. 30]

The following parameters will be initialized.

Mode	Items	Symbol	Initial value
Setup Setting Mode	Setting group No. 30	F_1	Relay contact output: 20.0 Voltage pulse output, Transistor output: Note1

Note1: In case OUT1 function selection is “Input 1_Control output [cool-side]” AND Inpu1_Control action is “Heat/Cool PID control [air cooling] or [water cooling]”: 20.0, Other casees: 2.0

4.1.9 When OUT2 function selection ($\alpha S L_2$) is changed [Engineering Mode: Function block No. 30]

The following parameters will be initialized.

Mode	Items	Symbol	Initial value
Setup Setting Mode	Setting group No. 30	F_2	Relay contact output: 20.0 Voltage pulse output, Transistor output: Note2

Note2: In case OUT2 function selection is “Input 1_Control output [cool-side]” AND Inpu1_Control action is “Heat/Cool PID control [air cooling] or [water cooling]”: 20.0, Other casees: 2.0

4.1.10 When OUT3 function selection ($\alpha S L_3$) and Universal output type selection ($U N I \alpha$) are changed [Engineering Mode: Function block No. 30]

The following parameters will be initialized.

Mode	Items	Symbol	Initial value
Setup Setting Mode	Setting group No. 30	F_3	Voltage pulse output: Note3

Note3: In case OUT3 function selection is “Input 1_Control output [cool-side]” AND Inpu1_Control action is “Heat/Cool PID control [air cooling] or [water cooling]”: 20.0, Other casees: 2.0

4.1.11 When Retransmission output 1 type ($R_o\ 1$) is changed [Engineering Mode: Function block No. 31]

The following parameters will be initialized.

Mode	Items	Symbol	Initial value
Engineering Mode	Retransmission output 1 scale high	$RHS\ 1$	<ul style="list-style-type: none"> • Input 1_Measured value (PV), Input 1_Local SV, Input 1_SV monitor value, and Remote setting input value: Input 1_Input range high $\left[\begin{array}{l} \text{Control with PV select:} \\ \text{PV select input range high} \end{array} \right]$ • Input 1_Deviation: +(Input 1_Input span) • Input 2_Measured value (PV), Input 2_Local SV, and Input 2_SV monitor value: Input 2_Input range high • Input 2_Deviation: +(Input 2_Input span) • Manipulated output value, and Current transformer (CT) input value: 100.0 • Measured value (PV) of differential temperature input: 100
	Retransmission output 1 scale low	$RLS\ 1$	<ul style="list-style-type: none"> • Input 1_Measured value (PV), Input 1_Local SV, Input 1_SV monitor value, and Remote setting input value: Input 1_Input range low $\left[\begin{array}{l} \text{Control with PV select:} \\ \text{PV select input range low} \end{array} \right]$ • Input 1_Deviation: -(Input 1_Input span) • Input 2_Measured value (PV), Input 2_Local SV, and Input 2_SV monitor value: Input 2_Input range low • Input 2_Deviation: -(Input 2_Input span) • Manipulated output value, and Current transformer (CT) input value: 0.0 • Measured value (PV) of differential temperature input: -100

4.1.12 When Retransmission output 2 type ($Ro2$) is changed [Engineering Mode: Function block No. 32]

The following parameters will be initialized.

Mode		Items	Symbol	Initial value
Engineering Mode	Function block No. 32	Retransmission output 2 scale high	$RHS2$	Same as Retransmission output 1 scale high
		Retransmission output 2 scale low	$RLS2$	Same as Retransmission output 1 scale low

4.1.13 When Retransmission output 3 type ($Ro3$) is changed [Engineering Mode: Function block No. 33]

The following parameters will be initialized.

Mode		Items	Symbol	Initial value
Engineering Mode	Function block No. 33	Retransmission output 3 scale high	$RHS3$	Same as Retransmission output 1 scale high
		Retransmission output 3 scale low	$RLS3$	Same as Retransmission output 1 scale low

4.1.14 When Event 1 type ($EV1$) and Event 1 assignment ($EVA1$) are changed [Engineering Mode: Function block No. 41]

The following parameters will be initialized.

Mode		Items	Symbol	Initial value
Parameter Setting Mode	Parameter group No. 40	Event 1 set value (EV1) Event 1 set value (EV1) [high]	$EV1$	Deviation, Process and SV: TC/RTD inputs: 10 V/I inputs: 5 % of input span MV: 50.0
		Event 1 set value (EV1') [low]	$EV1'$	TC/RTD inputs: -10 V/I inputs: -5 % of input span
Engineering Mode	Function block No. 41	Event 1 hold action	$EHO1$	If the Event type is specified by the initial setting code when ordering, the factory set value of Event hold action differs depending on the Event type. If the Event type is not specified: 0
		Event 1 differential gap	$EH1$	Deviation, Process and SV: TC/RTD inputs: 2 V/I inputs: 0.2 % of input span MV: 0.2
		Event 1 timer	$EVF1$	0.0

4.1.15 When Event 2 type ($EV2$) and Event 2 assignment ($EV\bar{R}2$) are changed [Engineering Mode: Function block No. 42]

The following parameters will be initialized.

Mode		Items	Symbol	Initial value
Parameter Setting Mode	Parameter group No. 40	Event 2 set value (EV2) Event 2 set value (EV2) [high]	$EV2$	Deviation, Process and SV: TC/RTD inputs: 10 V/I inputs: 5 % of input span MV: 50.0
		Event 2 set value (EV2') [low]	$EV2'$	TC/RTD inputs: -10 V/I inputs: -5 % of input span
Engineering Mode	Function block No. 42	Event 2 hold action	$EHo2$	If the Event type is specified by the initial setting code when ordering, the factory set value of Event hold action differs depending on the Event type. If the Event type is not specified: 0
		Event 2 differential gap	$EH2$	Deviation, Process and SV: TC/RTD inputs: 2 V/I inputs: 0.2 % of input span MV: 0.2
		Event 2 timer	$EV\bar{R}2$	0.0

4.1.16 When Event 3 type ($EV3$) and Event 3 assignment ($EV\bar{R}3$) are changed [Engineering Mode: Function block No. 43]

The following parameters will be initialized.

Mode		Items	Symbol	Initial value
Parameter Setting Mode	Parameter group No. 40	Event 3 set value (EV3) Event 3 set value (EV3) [high]	$EV3$	Deviation, Process and SV: TC/RTD inputs: 10 V/I inputs: 5 % of input span MV: 50.0
		Event 3 set value (EV3') [low]	$EV3'$	TC/RTD inputs: -10 V/I inputs: -5 % of input span
Engineering Mode	Function block No. 43	Event 3 hold action	$EHo3$	If the Event type is specified by the initial setting code when ordering, the factory set value of Event hold action differs depending on the Event type. If the Event type is not specified: 0
		Event 3 differential gap	$EH3$	Deviation, Process and SV: TC/RTD inputs: 2 V/I inputs: 0.2 % of input span MV: 0.2
		Event 3 timer	$EV\bar{R}3$	0.0

4.1.17 When Event 4 type ($EV4$) and Event 4 assignment ($EV4$) are changed [Engineering Mode: Function block No. 44]

The following parameters will be initialized.

Mode		Items	Symbol	Initial value
Parameter Setting Mode	Parameter group No. 40	Event 4 set value (EV4) Event 4 set value (EV4) [high]	$EV4$	Deviation, Process and SV: TC/RTD inputs: 10 V/I inputs: 5 % of input span MV: 50.0
		Event 4 set value (EV4') [low]	$EV4'$	TC/RTD inputs: -10 V/I input: -5 % of input span
Engineering Mode	Function block No. 43	Event 4 hold action	$EH4$	If the Event type is specified by the initial setting code when ordering, the factory set value of Event hold action differs depending on the Event type. If the Event type is not specified: 0
		Event 4 differential gap	$EH4$	Deviation, Process and SV: TC/RTD inputs: 2 V/I inputs: 0.2 % of input span MV: 0.2
		Event 4 timer	$EV4$	0.0

4.1.18 When CT1 type ($CTR1$) is changed [Engineering Mode: Function block No. 45]

The following parameters will be initialized.

Mode		Items	Symbol	Initial value
Engineering Mode	Function block No. 45	CT1 ratio	$CTR1$	CTL-6-P-N or CTL-6-P-Z: 800 CTL-12-S56-10L-N: 1000

4.1.19 When CT2 type ($CTR2$) is changed [Engineering Mode: Function block No. 46]

The following parameters will be initialized.

Mode		Items	Symbol	Initial value
Engineering Mode	Function block No. 46	CT2 ratio	$CTR2$	CTL-6-P-N or CTL-6-P-Z: 800 CTL-12-S56-10L-N: 1000

4.1.20 When Integral/Derivative time decimal point position (*I ddP*) is changed [Engineering Mode: Function block No. 50]

The following parameters will be initialized.

Mode	Items	Symbol	Initial value
Parameter Setting Mode	Parameter group No. 51	<i>I. I</i>	240
	Input 1_Integral time [heat-side]	<i>I. I</i>	240
	Input 1_Derivative time [heat-side]	<i>I. d</i>	60
	Parameter group No. 52	<i>I. I</i>	240
		<i>I. d</i>	60
	Parameter group No. 56	<i>I. Ic</i>	240
	Input 1_Integral time [cool-side]	<i>I. Ic</i>	240
	Input 1_Derivative time [cool-side]	<i>I. dc</i>	60

4.1.21 When Communication protocol (*MP5*) is changed [Engineering Mode: Function block No. 60]

The following parameters will be initialized.

Mode	Items	Symbol	Initial value
Engineering Mode	Function block No. 60	<i>Rdd</i>	RKC communication: 0 Modbus: 1 PLC communication: 0
		<i>blf</i>	0
	Function block No. 62	<i>MPREG</i>	0

4.1.22 When Register type (*MPREG*) is changed [Engineering Mode: Function block No. 62]

The following parameters will be initialized.

Mode	Items	Symbol	Initial value
Engineering Mode	Register start number (High-order 4-bit)	<i>MPSRH</i>	0
	Register start number (Low-order 16-bit)	<i>MPSRL</i>	1000

4.1.23 When Soak time unit ($S\Gamma dP$) is changed [Engineering Mode: Function block No. 70]

The following parameters will be initialized.

Mode	Items	Symbol	Initial value
Parameter Setting Mode	Parameter group No. 70	Area soak time	$R5\Gamma$ 0:00 (0.00 seconds)

4.1.24 When Initialization (dEF) is changed [Engineering Mode: Function block No. 91]

If Initialization is done by setting “1225” at [Engineering Mode: Function block No. 91], all the settings will be set to the factory set values.



NOTE

Make sure all settings are recorded before Initializing.

4.2 Parameters to Be Automatically Converted

If the data of the following parameter is changed, related set values are also automatically converted.



Make sure all settings are recorded before changing the set values.



Check all set values after having changed the settings.



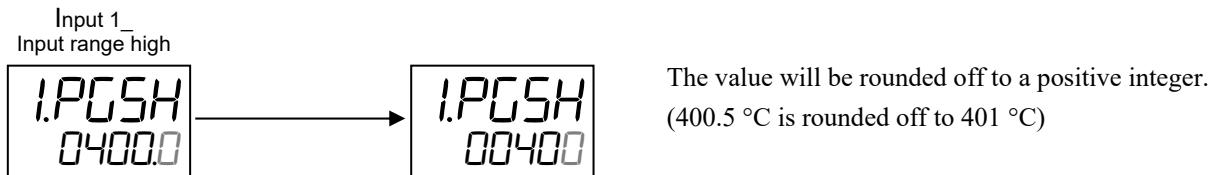
See ■ **Example of automatic conversion (P. 4-22)** for details of automatic conversion.

			See page
• <u>Input data type</u>	Engineering Mode	Function block No. 21	4-23
• <u>Input 1_Decimal point position</u>	Engineering Mode	Function block No. 21	4-25
• <u>Input 1_Input range high/low</u>	Engineering Mode	Function block No. 21	4-25
• <u>Input 1_Control action</u>	Engineering Mode	Function block No. 51	4-27
• <u>Input 1_Setting limiter high/low</u>	Engineering Mode	Function block No. 71	4-27
• <u>Input 1_Output limiter high/low [heat-side]</u>	Parameter Setting Mode	Parameter group No. 51	4-27
• <u>Input 1_Output limiter high/low [cool-side]</u>	Parameter Setting Mode	Parameter group No. 56	4-27
• <u>Input 2_Decimal point position</u>	Engineering Mode	Function block No. 22	4-28
• <u>Input 2_Input range high/low</u>	Engineering Mode	Function block No. 22	4-30
• <u>Input 2_Setting limiter high/low</u>	Engineering Mode	Function block No. 72	4-32
• <u>Input 2_Output limiter high/low</u>	Parameter Setting Mode	Parameter group No. 52	4-32
• <u>Memory area transfer</u>	Memory Area Transfer Mode		4-32
• <u>Input 1_Knee point correction limit value</u>	Engineering Mode	Function block No. 21	4-32
• <u>Input 2_Knee point correction limit value</u>	Engineering Mode	Function block No. 22	4-33
• <u>Input 1_Level PID setting 1</u>	Setup Setting Mode	Setting group No. 51	4-33
• <u>Input 1_Level PID setting 2</u>	Setup Setting Mode	Setting group No. 51	4-33
• <u>Input 1_Level PID setting 3</u>	Setup Setting Mode	Setting group No. 51	4-34
• <u>Input 1_Level PID setting 4</u>	Setup Setting Mode	Setting group No. 51	4-34
• <u>Input 1_Level PID setting 5</u>	Setup Setting Mode	Setting group No. 51	4-34
• <u>Input 1_Level PID setting 6</u>	Setup Setting Mode	Setting group No. 51	4-35
• <u>Input 1_Level PID setting 7</u>	Setup Setting Mode	Setting group No. 51	4-35
• <u>Input 2_Level PID setting 1</u>	Setup Setting Mode	Setting group No. 52	4-35
• <u>Input 2_Level PID setting 2</u>	Setup Setting Mode	Setting group No. 52	4-36
• <u>Input 2_Level PID setting 3</u>	Setup Setting Mode	Setting group No. 52	4-36
• <u>Input 2_Level PID setting 4</u>	Setup Setting Mode	Setting group No. 52	4-36
• <u>Input 2_Level PID setting 5</u>	Setup Setting Mode	Setting group No. 52	4-37
• <u>Input 2_Level PID setting 6</u>	Setup Setting Mode	Setting group No. 52	4-37
• <u>Input 2_Level PID setting 7</u>	Setup Setting Mode	Setting group No. 52	4-37

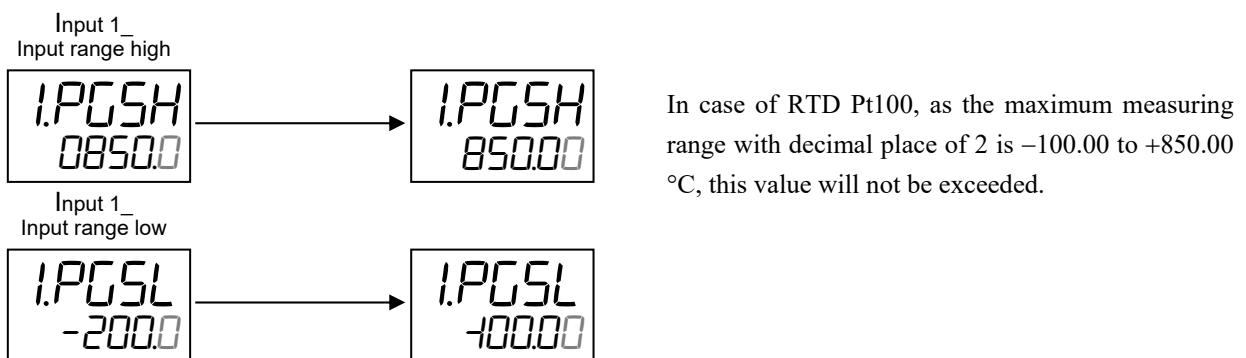
■ Example of automatic conversion

- If the position of a decimal point is changed, the decimal point is shifted according to the setting.

Example 1: When the Input 1_Input range high is set to 400.0 °C, changing the decimal point position to 0 from 1 will change the Input 1_Input range high to 400 °C.

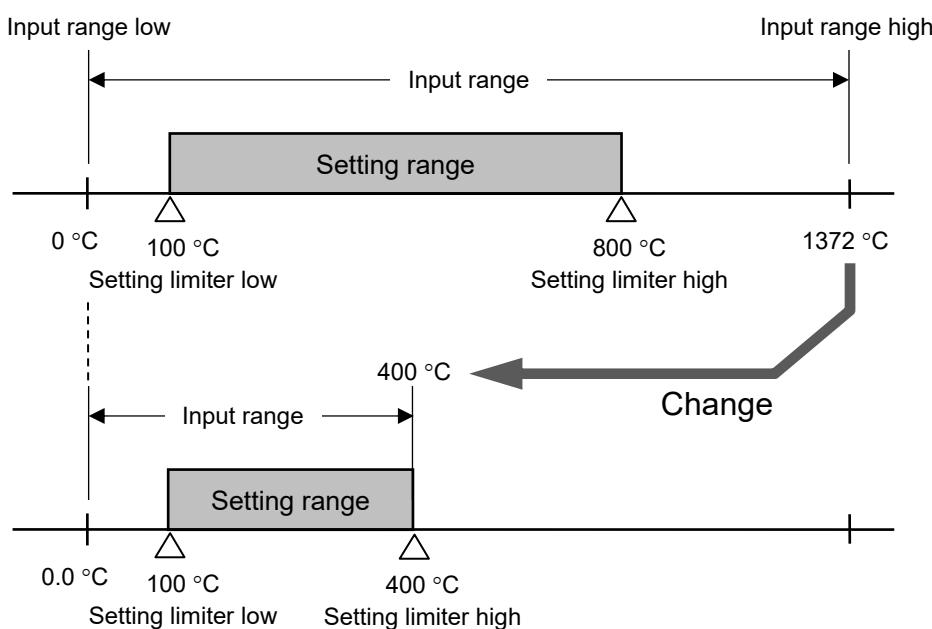


Example 2: When the Input 1_input range is -200.0 to +850.0 °C (Input type: RTD Pt100), changing the decimal point position to 2 from 1 will change the input range to -100.00 to +850.00 °C.



- When the input range is changed, the setting limiter will be also changed according to the setting.

Example: Input 1_Input range is 0 to 1372 °C, Input 1_Setting limiter high is 800 °C. Changing the Input 1_Input range high to 400 °C will change the Setting limiter high to 400 °C accordingly.



4.2.1 When Input data type (*I NdF*) is changed [Engineering Mode: Function block No. 21]

The following parameters will be automatically converted.

Some parameters may have prerequisite for automatic conversion. (See the prerequisite and P. 4-24)

Mode	Items	Symbol	Condition
Monitor & SV Setting Mode	Set value (SV) of differential temperature input	$\triangleleft SV$	—
Parameter Setting Mode	Set value (SV) of differential temperature input	dSV	—
	Event 1 set value (EV1) Event 1 set value (EV1) [high]	$EV\ 1$	4
	Event 1 set value (EV1') [low]	$EV\ 1'$	4
	Event 2 set value (EV2) Event 2 set value (EV2) [high]	$EV\ 2$	4
	Event 2 set value (EV2') [low]	$EV\ 2'$	4
	Event 3 set value (EV3) Event 3 set value (EV3) [high]	$EV\ 3$	4
	Event 3 set value (EV3') [low]	$EV\ 3'$	4
	Event 4 set value (EV4) Event 4 set value (EV4) [high]	$EV\ 4$	4
	Event 4 set value (EV4') [low]	$EV\ 4'$	4
	Input 1_Proportional band [heat-side]	$I.\ P$	1
	Input 1_ON/OFF action differential gap (upper)	$I.\ oHH$	1
	Input 1_ON/OFF action differential gap (lower)	$I.\ oHL$	1
	Input 1_LBA deadband (LBD)	$I.\ Lbd$	—
	Input 2_Proportional band	$2.\ P$	1
Parameter group No. 51	Input 2_ON/OFF action differential gap (upper)	$2.\ oHH$	1
	Input 2_ON/OFF action differential gap (lower)	$2.\ oHL$	1
	Input 2_LBA deadband (LBD)	$2.\ Lbd$	—
	Input 1_Proportional band [cool-side]	$I.\ P_c$	1
Parameter group No. 56	Input 1_Overlap/Deadband	$I.\ db$	1
	Input 1_Setting change rate limiter (up)	$I.SVRU$	—
	Input 1_Setting change rate limiter (down)	$I.SVRd$	—
	Input 2_Setting change rate limiter (up)	$2.SVRU$	—
Parameter group No. 70	Input 2_Setting change rate limiter (down)	$2.SVRd$	—
	Input 1_Knee point input value 1	$I.\ rP\ 1$	—
	Input 1_Knee point input value 2	$I.\ rP\ 2$	—
	Input 1_Knee point input value 3	$I.\ rP\ 3$	—
	Input 1_Knee point input value 4	$I.\ rP\ 4$	—
	Input 1_Knee point input value 5	$I.\ rP\ 5$	—
	Input 1_Knee point correction value 1	$I.\ rV\ 1$	—
	Input 1_Knee point correction value 2	$I.\ rV\ 2$	—
	Input 1_Knee point correction value 3	$I.\ rV\ 3$	—
	Input 1_Knee point correction value 4	$I.\ rV\ 4$	—
Parameter group No. 71	Input 1_Knee point correction value 5	$I.\ rV\ 5$	—
	Input 2_Knee point input value 1	$2.\ rP\ 1$	—
	Input 2_Knee point input value 2	$2.\ rP\ 2$	—
	Input 2_Knee point input value 3	$2.\ rP\ 3$	—
	Input 2_Knee point input value 4	$2.\ rP\ 4$	—
	Input 2_Knee point input value 5	$2.\ rP\ 5$	—
	Input 2_Knee point correction value 1	$2.\ rV\ 1$	—
	Input 2_Knee point correction value 2	$2.\ rV\ 2$	—
	Input 2_Knee point correction value 3	$2.\ rV\ 3$	—
	Input 2_Knee point correction value 4	$2.\ rV\ 4$	—
Parameter group No. 72	Input 2_Knee point correction value 5	$2.\ rV\ 5$	—

Mode	Items	Symbol	Condition
Parameter Setting Mode	Input 2_Knee point correction value 1	2. rV1	—
	Input 2_Knee point correction value 2	2. rV2	—
	Input 2_Knee point correction value 3	2. rV3	—
	Input 2_Knee point correction value 4	2. rV4	—
	Input 2_Knee point correction value 5	2. rV5	—
Setup Setting Mode	Setting group No. 21	1. Pb	—
	Setting group No. 22	2. Pb	—
	Setting group No. 53	1. RΓb	—
	Setting group No. 54	2. RΓb	—
	Setting group No. 57	1.E×dJ	—
		2.E×dJ	—
	Setting group No. 91	1.PHLd	—
		1.bHLd	—
		2.PHLd	—
		2.bHLd	—
Engineering Mode	Function block No. 21	1. PaV	—
		1. PUN	—
		1.rVML	—
	Function block No. 22	2. PaV	—
		2. PUN	—
		2.rVML	—
	Function block No. 31	RHS1	2
		RLS1	2
	Function block No. 32	RHS2	2
		RLS2	2
	Function block No. 33	RHS3	2
		RLS3	2
	Function block No. 41	EH1	3
	Function block No. 42	EH2	3
	Function block No. 43	EH3	3
	Function block No. 44	EH4	3
	Function block No. 51	1. PdR	—
		1. LHS	—
	Function block No. 52	2. PdR	—
		2. LHS	—
	Function block No. 58	1.CA	—

Condition

- 1: When Input type is Thermocouple/RTD input.
- 2: When Retransmission output is “Input 1_Deviation,” “Input 2_Deviation,” or Measured value (PV) of differential temperature input.
- 3: Event type is other than Manipulated output value
- 4: In any one of the following cases
 - Event type is a deviation action
 - Event type is an input value action, AND Event assignment is “Differential temperature input.”
 - Event type is a set value action, AND Event assignment is “Differential temperature input.”

4.2.2 When Input 1_Decimal point position (I.PGdP), Input 1_Input range high (I.PGSH) and Input 1_Input range low (I.PGSL) are changed [Engineering Mode: Function block No. 21]

The following parameters will be automatically converted.

Some parameters may have prerequisite for automatic conversion. (See the prerequisite and P. 4-26)

Mode	Items	Symbol	Condition
Monitor & SV Setting Mode	Input 1_Set value (SV)		—
	Set value (SV) of differential temperature input		—
Parameter group No. 00	Input 1_Set value (SV)	I. 5V	—
	Set value (SV) of differential temperature input	d5V	—
	Event 1 set value (EV1)	EV 1	3
	Event 1 set value (EV1) [high]		
	Event 1 set value (EV1') [low]	EV 1'	3
	Event 2 set value (EV2)	EV 2	3
	Event 2 set value (EV2) [high]		
	Event 2 set value (EV2') [low]	EV 2'	3
	Event 3 set value (EV3)	EV 3	3
	Event 3 set value (EV3) [high]		
Parameter group No. 40	Event 3 set value (EV3') [low]	EV 3'	3
	Event 4 set value (EV4)	EV 4	3
	Event 4 set value (EV4) [high]		
	Event 4 set value (EV4') [low]	EV 4'	3
	Input 1_Proportional band [heat-side]	I. P	2
	Input 1_ON/OFF action differential gap (upper)	I. oHH	2
	Input 1_ON/OFF action differential gap (lower)	I. oHL	2
	Input 1_LBA deadband (LBD)	I. Lbd	—
	Input 1_Proportional band [cool-side]	I. Pc	2
	Input 1_Overlap/Deadband	I. db	2
Parameter group No. 56	Input 1_Setting change rate limiter (up)	I.SVRU	—
	Input 1_Setting change rate limiter (down)	I.SVRd	—
	Input 1_Knee point input value 1	I. rP 1	—
	Input 1_Knee point input value 2	I. rP2	—
	Input 1_Knee point input value 3	I. rP3	—
	Input 1_Knee point input value 4	I. rP4	—
	Input 1_Knee point input value 5	I. rP5	—
	Input 1_Knee point correction value 1	I. rV 1	—
	Input 1_Knee point correction value 2	I. rV2	—
	Input 1_Knee point correction value 3	I. rV3	—
Parameter group No. 70	Input 1_Knee point correction value 4	I. rV4	—
	Input 1_Knee point correction value 5	I. rV5	—
	Input 2_Knee point input value 1	2. rP 1	1
	Input 2_Knee point input value 2	2. rP2	1
	Input 2_Knee point input value 3	2. rP3	1
	Input 2_Knee point input value 4	2. rP4	1
	Input 2_Knee point input value 5	2. rP5	1
	Input 2_Knee point correction value 1	2. rV 1	1
	Input 2_Knee point correction value 2	2. rV2	1
	Input 2_Knee point correction value 3	2. rV3	1
Parameter group No. 72	Input 2_Knee point correction value 4	2. rV4	1
	Input 2_Knee point correction value 5	2. rV5	1

Mode	Items	Symbol	Condition
Setup Setting Mode	Setting group No. 21 Input 1_PV bias	I. Pb	—
	Setting group No. 22 Input 2_PV bias (RS bias) *	I. Pb	1
	Setting group No. 51 Input 1_Level PID setting 1 Input 1_Level PID setting 2 Input 1_Level PID setting 3 Input 1_Level PID setting 4 Input 1_Level PID setting 5 Input 1_Level PID setting 6 Input 1_Level PID setting 7	IL EV 1	—
		IL EV 2	—
		IL EV 3	—
		IL EV 4	—
		IL EV 5	—
		IL EV 6	—
		IL EV 7	—
	Setting group No. 53 Input 1_AT bias	I. ATB	—
	Setting group No. 57 Input 1_Determination point of external disturbance	I. EDU	—
	Setting group No. 58 PV select transfer level	2PVLV	—
	Setting group No. 91 Input 1_Peak hold monitor Input 1_Bottom hold monitor	I.PHLd	—
		I.bHLD	—
Engineering Mode	Function block No. 21 Input 1_Input range high * Input 1_Input range high * Input 1_Input error determination point (high) Input 1_Knee point correction limit value	IPGS H	—
		IPGS L	—
		I. Pov	—
		I. PUN	—
		I.rVML	—
	Function block No. 22 Input 2_Input range high * Input 2_Input range high * Input 2_Knee point correction limit value	2PGSH	1
		2PGSL	1
		2.rVML	1
	Function block No. 31 Retransmission output 1 scale high Retransmission output 1 scale low	RHS 1	4
		RLS 1	4
	Function block No. 32 Retransmission output 2 scale high Retransmission output 2 scale low	RHS 2	4
		RLS 2	4
	Function block No. 33 Retransmission output 3 scale high Retransmission output 3 scale low	RHS 3	4
		RLS 3	4
	Function block No. 41 Event 1 differential gap	EH 1	3
	Function block No. 42 Event 2 differential gap	EH 2	3
	Function block No. 43 Event 3 differential gap	EH 3	3
	Function block No. 44 Event 4 differential gap	EH 4	3
	Function block No. 51 Input 1_Start determination point Input 1_Level PID differential gap	I. PdR	—
		I. LHS	—
	Function block No. 58 Input circuit error alarm set value	I.CA	—
	Function block No. 71 Input 1_Setting limiter high Input 1_Setting limiter low	I. SLH	—
		I. SLL	—

* Only if the Input 1_Decimal point position has been changed. (Not applicable to high and low limit of Input 1)

Condition

- 1: “Select function for input 2” is not Remote setting input AND Input 2_Input type is not either voltage output or current output.
- 2: When Input 1_Input type is Thermocouple/RTD input.
- 3: The condition is either of the following.
 - Event type is other than Manipulated output value AND “Select function for input 2” is set to “Control with PV select.”
 - Event type is other than Manipulated output value AND Event assignment is either “Input 1” or “Differential temperature input.”
- 4: Retransmission output is “No retransmission output,” “Input 1_Measured value (PV),” “Input 1_Set value (SV),” “Input 1_Deviation,” “Input 1_Remote setting input value,” OR Measured value (PV) of differential temperature input.

4.2.3 When Input 1_Control action (I_{a5}) is changed [Engineering Mode: Function block No. 51]

The following parameters will be automatically converted.

Mode	Items	Symbol
Parameter Setting Mode	Parameter group No. 51	I_{a5}
	Parameter group No. 70	I_{MV_A}
Setup Setting Mode	Setting group No. 51	I_{MMV}
Engineering Mode	Function block No. 51	I_{PSM}

4.2.4 When Input 1_Setting limiter high/low (I_{SLH} , I_{SLL}) is changed [Engineering Mode: Function block No. 71]

The following parameters will be automatically converted.

Mode	Items	Symbol
Monitor & SV Setting Mode	Input 1_Set value (SV)	Δ
Parameter Setting Mode	Parameter group No. 00	I_{SV}

4.2.5 When Input 1_Output limiter high/low [heat-side] (I_{aLH} , I_{aLL}) is changed [Parameter Setting Mode: Parameter group No. 51]

The following parameters will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Setting group No. 51	I_{MMV}

4.2.6 When Input 1_Output limiter high/low [cool-side] (I_{oLH_C} , I_{oLL_C}) is changed [Parameter Setting Mode: Parameter group No. 56]

The following parameters will be automatically converted.

If the control action is set to “Heat/Cool PID control,” the data of the following parameter will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Setting group No. 51	I_{MMV}

4.2.7 When Input 2_Decimal point position (2PGdP) is changed [Engineering Mode: Function block No. 22]

The following parameters will be automatically converted.

Some parameters may have prerequisite for automatic conversion. (See the prerequisite and P. 4-29)

Mode	Items	Symbol	Condition	
Monitor & SV Setting Mode	Input 2_Set value (SV)	\triangle	—	
Parameter Setting Mode	Input 2_Set value (SV)	$2.5V$	—	
	Event 1 set value (EV1) Event 1 set value (EV1) [high]	$EV1$	3	
	Event 1 set value (EV1') [low]	$EV1'$	3	
	Event 2 set value (EV2) Event 2 set value (EV2) [high]	$EV2$	3	
	Event 2 set value (EV2') [low]	$EV2'$	3	
	Event 3 set value (EV3) Event 3 set value (EV3) [high]	$EV3$	3	
	Event 3 set value (EV3') [low]	$EV3'$	3	
	Event 4 set value (EV4) Event 4 set value (EV4) [high]	$EV4$	3	
	Event 4 set value (EV4') [low]	$EV4'$	3	
	Input 2_Proportional band	$2.P$	2	
Parameter group No. 52	Input 2_ON/OFF action differential gap (upper)	$2.oHH$	2	
	Input 2_ON/OFF action differential gap (lower)	$2.oHL$	2	
	Input 2_LBA deadband (LBD)	$2.Lbd$	—	
	Input 2_Setting change rate limiter (up)	$2.5VRU$	—	
	Input 2_Setting change rate limiter (down)	$2.5VRd$	—	
Parameter group No. 72	Input 2_Knee point input value 1	$2.rP1$	1	
	Input 2_Knee point input value 2	$2.rP2$	1	
	Input 2_Knee point input value 3	$2.rP3$	1	
	Input 2_Knee point input value 4	$2.rP4$	1	
	Input 2_Knee point input value 5	$2.rP5$	1	
	Input 2_Knee point correction value 1	$2.rV1$	1	
	Input 2_Knee point correction value 2	$2.rV2$	1	
	Input 2_Knee point correction value 3	$2.rV3$	1	
	Input 2_Knee point correction value 4	$2.rV4$	1	
	Input 2_Knee point correction value 5	$2.rV5$	1	
Setup Setting Mode	Setting group No. 22	Input 2_PV bias (RS bias)	$2.Pb$	1
	Setting group No. 52	Input 2_Level PID setting 1	$2.LEV1$	—
		Input 2_Level PID setting 2	$2.LEV2$	—
		Input 2_Level PID setting 3	$2.LEV3$	—
		Input 2_Level PID setting 4	$2.LEV4$	—
		Input 2_Level PID setting 5	$2.LEV5$	—
		Input 2_Level PID setting 6	$2.LEV6$	—
		Input 2_Level PID setting 7	$2.LEV7$	—
	Setting group No. 54	Input 2_AT bias	$2.Rfb$	—
	Setting group No. 57	Input 2_Determination point of external disturbance	$2.ExdJ$	—
Setting group No. 91	Input 2_Peak hold monitor	$2.PHLd$	—	
	Input 2_Bottom hold monitor	$2.bHLd$	—	

Mode	Items	Symbol	Condition
Engineering Mode	Function block No. 22	Input 2_Input range high	2PGSH
		Input 2_Input range low	2PGSL
		Input 2_Input error determination point (high)	2_PoV
		Input 2_Input error determination point (low)	2_PUN
		Input 2_Knee point correction limit value	2_rVML
	Function block No. 31	Retransmission output 1 scale high	RHS1
		Retransmission output 1 scale low	RLS1
	Function block No. 32	Retransmission output 2 scale high	RHS2
		Retransmission output 2 scale low	RLS2
Engineering Mode	Function block No. 33	Retransmission output 3 scale high	RHS3
		Retransmission output 3 scale low	RLS3
	Function block No. 41	Event 1 differential gap	EH1
	Function block No. 42	Event 2 differential gap	EH2
	Function block No. 43	Event 3 differential gap	EH3
	Function block No. 44	Event 4 differential gap	EH4
	Function block No. 52	Input 2_Start determination point	2_PdR
		Input 2_Level PID differential gap	2_LHS
	Function block No. 72	Input 2_Setting limiter high	2_SLH
		Input 2_Setting limiter low	2_SLL

Condition

- 1: “Select function for input 2” is not Remote setting input AND Input 2_Input type is not either voltage output or current output.
- 2: When Input 1_Input type is Thermocouple/RTD input.
- 3: If Event type is other than manipulated output AND “Select function for input 2” is other than “Control with PV select,” AND Event assignment is “Input 2.”
- 4: Retransmission output is “Input 2_Measured value (PV),” “Input 2_Set value (SV),” or “Input 2_Deviation.”

4.2.8 When Input 2_Setting limiter high/low (2PGSH, 2PGSL) is changed [Engineering Mode: Function block No. 22]

The following parameters will be automatically converted.

Some parameters may have prerequisite for automatic conversion. (See the prerequisite and P. 4-31)

Mode	Items	Symbol	Condition
Monitor & SV Setting Mode	Input 2_Set value (SV)		—
Parameter Setting Mode	Input 1_Set value (SV)	I. 5V	1
	Input 2_Set value (SV)	I. 5V	—
	Event 1 set value (EV1) Event 1 set value (EV1) [high]	EV 1	5
	Event 1 set value (EV1') [low]	EV 1'	5
	Event 2 set value (EV2) Event 2 set value (EV2) [high]	EV 2	5
	Event 2 set value (EV2') [low]	EV 2'	5
	Event 3 set value (EV3) Event 3 set value (EV3) [high]	EV 3	5
	Event 3 set value (EV3') [low]	EV 3'	5
	Event 4 set value (EV4) Event 4 set value (EV4) [high]	EV 4	5
	Event 4 set value (EV4') [low]	EV 4'	5
Setup Setting Mode	Input 1_Proportional band [heat-side]	I. P	3
	Input 1_ON/OFF action differential gap (upper)	I. oHH	3
	Input 1_ON/OFF action differential gap (lower)	I. oHL	3
	Input 1_LBA deadband (LBD)	I. Lbd	1
	Input 2_Proportional band	2. P	2
	Input 2_ON/OFF action differential gap (upper)	2. oHH	2
	Input 2_ON/OFF action differential gap (lower)	2. oHL	2
	Input 2_LBA deadband (LBD)	2. Lbd	—
	Input 1_Proportional band [cool-side]	I. P _c	3
	Input 1_Overlap/Deadband	I. db	3
Parameter group No. 22	Input 1_Setting change rate limiter (up)	1.5VRU	1
	Input 1_Setting change rate limiter (down)	1.5VRd	1
	Input 2_Setting change rate limiter (up)	2.5VRU	—
	Input 2_Setting change rate limiter (down)	2.5VRd	—
	Input 2_Knee point input value 1	2. rP1	—
	Input 2_Knee point input value 2	2. rP2	—
	Input 2_Knee point input value 3	2. rP3	—
	Input 2_Knee point input value 4	2. rP4	—
	Input 2_Knee point input value 5	2. rP5	—
	Input 2_Knee point correction value 1	2. rV1	—
Setting group No. 22	Input 2_Knee point correction value 2	2. rV2	—
	Input 2_Knee point correction value 3	2. rV3	—
	Input 2_Knee point correction value 4	2. rV4	—
	Input 2_Knee point correction value 5	2. rV5	—
	Input 2_PV bias (RS bias)	2. Pb	4
Setting group No. 51	Input 1_Level PID setting 1	ILEV 1	1
	Input 1_Level PID setting 2	ILEV 2	1
	Input 1_Level PID setting 3	ILEV 3	1
	Input 1_Level PID setting 4	ILEV 4	1

Mode	Items	Symbol	Condition
Setup Setting Mode	Input 1_Level PID setting 5	<i>I.LEV5</i>	1
	Input 1_Level PID setting 6	<i>I.LEV6</i>	1
	Input 1_Level PID setting 7	<i>I.LEV7</i>	1
	Input 2_Level PID setting 1	<i>2.LEV1</i>	—
	Input 2_Level PID setting 2	<i>2.LEV2</i>	—
	Input 2_Level PID setting 3	<i>2.LEV3</i>	—
	Input 2_Level PID setting 4	<i>2.LEV4</i>	—
	Input 2_Level PID setting 5	<i>2.LEV5</i>	—
	Input 2_Level PID setting 6	<i>2.LEV6</i>	—
	Input 2_Level PID setting 7	<i>2.LEV7</i>	—
	Setting group No. 53	<i>I.RFB</i>	1
	Setting group No. 54	<i>2.RFB</i>	—
	Setting group No. 57	<i>I.EXdJ</i>	1
	Setting group No. 91	<i>2.EXdJ</i>	—
Engineering Mode	Input 2_Peak hold monitor	<i>2.PHLd</i>	—
	Input 2_Bottom hold monitor	<i>2.bHLD</i>	—
	Function block No. 22	<i>2.PoV</i>	—
	Input 2_Input error determination point (high)	<i>2.PUN</i>	—
	Input 2_Knee point correction limit value	<i>2.rVML</i>	—
	Function block No. 31	<i>RHS1</i>	6
	Retransmission output 1 scale high	<i>RLS1</i>	6
	Function block No. 32	<i>RHS2</i>	6
	Retransmission output 2 scale high	<i>RLS2</i>	6
	Function block No. 33	<i>RHS3</i>	6
	Retransmission output 3 scale high	<i>RLS3</i>	6
	Function block No. 41	<i>EH1</i>	5
	Function block No. 42	<i>EH2</i>	5
	Function block No. 43	<i>EH3</i>	5
	Function block No. 44	<i>EH4</i>	5
	Function block No. 51	<i>I.PdR</i>	1
	Input 1_Start determination point	<i>I.LPId</i>	1
	Input 1_Level PID differential gap	<i>2.PdR</i>	—
	Function block No. 52	<i>2.LHS</i>	—
	Input 2_Start determination point	<i>I.SLH</i>	1
	Input 2_Level PID differential gap	<i>I.SLL</i>	1
	Function block No. 71	<i>I.SLH</i>	—
	Input 1_Setting limiter high	<i>I.SLL</i>	—
	Input 1_Setting limiter low	<i>2.SLH</i>	—
	Function block No. 72	<i>2.SLL</i>	—
	Input 2_Setting limiter high	<i>I.SLL</i>	—
	Input 2_Setting limiter low	<i>2.SLH</i>	—

Condition

- 1: If “Select function for input 2” is “Control with PV select.”
- 2: When Input type is Thermocouple/RTD input.
- 3: “Select function for input 2” is “Control with PV select” AND Input 2_Input type is Thermocouple/RTD input.
- 4: “Select function for input 2” is other than Remote setting input
- 5: If Event type is other than manipulated output AND “Select function for input 2” is other than “Control with PV select,” AND Event assignment is “Input 2.”
- 6: The condition is either of the following.
 - Retransmission output is “Input 2_Measured value (PV),” “Input 2_Set value (SV),” or “Input 2_Deviation.”
 - When “Select function for Input 2” is “Control with PV select,” the Retransmission output will be as follows.
“No retransmission output,” “Input 1_Measured value (PV),” “Input 1_Set value (SV),” “Input 1_Deviation,” “Input 1_Remote setting input value,” OR Measured value (PV) of differential temperature input.

4.2.9 When Input 2_Setting limiter high/low (2. 5LH, 2. 5LL) is changed [Engineering Mode: Function block No. 72]

The following parameters will be automatically converted.

Mode	Items	Symbol
Monitor & SV Setting Mode	Input 2_Set value (SV)	\triangle
Parameter Setting Mode	Parameter group No. 00	2. 5V

4.2.10 When Input 2_Output limiter high/low (2. oLH, 2. oLL) is changed [Parameter Setting Mode: Parameter group No. 52]

The following parameters will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Input 2_Manual manipulated output value	2. MMV

4.2.11 When Memory area transfer (RREA) is changed [Memory Area Transfer Mode]

The following parameters will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Input 1_Manual manipulated output value	1. MMV
	Input 2_Manual manipulated output value	2. MMV

4.2.12 When Input 1_Knee point correction limit value (1.rVML) is changed [Engineering Mode: Function block No. 21]

The following parameters will be automatically converted.

Mode	Items	Symbol
Parameter Setting Mode	Input 1_Knee point correction value 1	1. rV1
	Input 1_Knee point correction value 2	1. rV2
	Input 1_Knee point correction value 3	1. rV3
	Input 1_Knee point correction value 4	1. rV4
	Input 1_Knee point correction value 5	1. rV5

4.2.13 When Input 2_Knee point correction limit value ($2.rVML$) is changed [Engineering Mode: Function block No. 22]

The following parameters will be automatically converted.

Mode		Items	Symbol
Parameter Setting Mode	Parameter group No. 72	Input 2_Knee point correction value 1	$2.rV1$
		Input 2_Knee point correction value 2	$2.rV2$
		Input 2_Knee point correction value 3	$2.rV3$
		Input 2_Knee point correction value 4	$2.rV4$
		Input 2_Knee point correction value 5	$2.rV5$

4.2.14 When Input 1_Level PID setting 1 ($1LEV1$) is changed [Setup Setting Mode: Setting group No. 51]

The following parameters will be automatically converted.

Mode		Items	Symbol
Setup Setting Mode	Setting group No. 51	Input 1_Level PID setting 2	$1LEV2$
		Input 1_Level PID setting 3	$1LEV3$
		Input 1_Level PID setting 4	$1LEV4$
		Input 1_Level PID setting 5	$1LEV5$
		Input 1_Level PID setting 6	$1LEV6$
		Input 1_Level PID setting 7	$1LEV7$

4.2.15 When Input 1_Level PID setting 2 ($1LEV2$) is changed [Setup Setting Mode: Setting group No. 51]

The following parameters will be automatically converted.

Mode		Items	Symbol
Setup Setting Mode	Setting group No. 51	Input 1_Level PID setting 1	$1LEV1$
		Input 1_Level PID setting 3	$1LEV3$
		Input 1_Level PID setting 4	$1LEV4$
		Input 1_Level PID setting 5	$1LEV5$
		Input 1_Level PID setting 6	$1LEV6$
		Input 1_Level PID setting 7	$1LEV7$

4.2.16 When Input 1_Level PID setting 3 (*ILEV3*) is changed [Setup Setting Mode: Setting group No. 51]

The following parameters will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Input 1_Level PID setting 1	<i>ILEV1</i>
	Input 1_Level PID setting 2	<i>ILEV2</i>
	Input 1_Level PID setting 4	<i>ILEV4</i>
	Input 1_Level PID setting 5	<i>ILEV5</i>
	Input 1_Level PID setting 6	<i>ILEV6</i>
	Input 1_Level PID setting 7	<i>ILEV7</i>

4.2.17 When Input 1_Level PID setting 4 (*ILEV4*) is changed [Setup Setting Mode: Setting group No. 51]

The following parameters will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Input 1_Level PID setting 1	<i>ILEV1</i>
	Input 1_Level PID setting 2	<i>ILEV2</i>
	Input 1_Level PID setting 3	<i>ILEV3</i>
	Input 1_Level PID setting 5	<i>ILEV5</i>
	Input 1_Level PID setting 6	<i>ILEV6</i>
	Input 1_Level PID setting 7	<i>ILEV7</i>

4.2.18 When Input 1_Level PID setting 5 (*ILEV5*) is changed [Setup Setting Mode: Setting group No. 51]

The following parameters will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Input 1_Level PID setting 1	<i>ILEV1</i>
	Input 1_Level PID setting 2	<i>ILEV2</i>
	Input 1_Level PID setting 3	<i>ILEV3</i>
	Input 1_Level PID setting 4	<i>ILEV4</i>
	Input 1_Level PID setting 6	<i>ILEV6</i>
	Input 1_Level PID setting 7	<i>ILEV7</i>

4.2.19 When Input 1_Level PID setting 6 (ILEV6) is changed [Setup Setting Mode: Setting group No. 51]

The following parameters will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Input 1_Level PID setting 1	ILEV1
	Input 1_Level PID setting 2	ILEV2
	Input 1_Level PID setting 3	ILEV3
	Input 1_Level PID setting 4	ILEV4
	Input 1_Level PID setting 5	ILEV5
	Input 1_Level PID setting 7	ILEV7

4.2.20 When Input 1_Level PID setting 7 (ILEV7) is changed [Setup Setting Mode: Setting group No. 51]

The following parameters will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Input 1_Level PID setting 1	ILEV1
	Input 1_Level PID setting 2	ILEV2
	Input 1_Level PID setting 3	ILEV3
	Input 1_Level PID setting 4	ILEV4
	Input 1_Level PID setting 5	ILEV5
	Input 1_Level PID setting 6	ILEV6

4.2.21 When Input 2_Level PID setting 1 (2LEV1) is changed [Setup Setting Mode: Setting group No. 52]

The following parameters will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Input 2_Level PID setting 2	2LEV2
	Input 2_Level PID setting 3	2LEV3
	Input 2_Level PID setting 4	2LEV4
	Input 2_Level PID setting 5	2LEV5
	Input 2_Level PID setting 6	2LEV6
	Input 2_Level PID setting 7	2LEV7

4.2.22 When Input 2_Level PID setting 2 (2LEV2) is changed [Setup Setting Mode: Setting group No. 52]

The following parameters will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Input 2_Level PID setting 1	2LEV1
	Input 2_Level PID setting 3	2LEV3
	Input 2_Level PID setting 4	2LEV4
	Input 2_Level PID setting 5	2LEV5
	Input 2_Level PID setting 6	2LEV6
	Input 2_Level PID setting 7	2LEV7

4.2.23 When Input 2_Level PID setting 3 (2LEV3) is changed [Setup Setting Mode: Setting group No. 52]

The following parameters will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Input 2_Level PID setting 1	2LEV1
	Input 2_Level PID setting 2	2LEV2
	Input 2_Level PID setting 4	2LEV4
	Input 2_Level PID setting 5	2LEV5
	Input 2_Level PID setting 6	2LEV6
	Input 2_Level PID setting 7	2LEV7

4.2.24 When Input 2_Level PID setting 4 (2LEV4) is changed [Setup Setting Mode: Setting group No. 52]

The following parameters will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Input 2_Level PID setting 1	2LEV1
	Input 2_Level PID setting 2	2LEV2
	Input 2_Level PID setting 3	2LEV3
	Input 2_Level PID setting 5	2LEV5
	Input 2_Level PID setting 6	2LEV6
	Input 2_Level PID setting 7	2LEV7

4.2.25 When Input 2_Level PID setting 5 (2LEV5) is changed [Setup Setting Mode: Setting group No. 52]

The following parameters will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Input 2_Level PID setting 1	2LEV1
	Input 2_Level PID setting 2	2LEV2
	Input 2_Level PID setting 3	2LEV3
	Input 2_Level PID setting 4	2LEV4
	Input 2_Level PID setting 6	2LEV6
	Input 2_Level PID setting 7	2LEV7

4.2.26 When Input 2_Level PID setting 6 (2LEV6) is changed [Setup Setting Mode: Setting group No. 52]

The following parameters will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Input 2_Level PID setting 1	2LEV1
	Input 2_Level PID setting 2	2LEV2
	Input 2_Level PID setting 3	2LEV3
	Input 2_Level PID setting 4	2LEV4
	Input 2_Level PID setting 5	2LEV5
	Input 2_Level PID setting 7	2LEV7

4.2.27 When Input 2_Level PID setting 7 (2LEV7) is changed [Setup Setting Mode: Setting group No. 52]

The following parameters will be automatically converted.

Mode	Items	Symbol
Setup Setting Mode	Input 2_Level PID setting 1	2LEV1
	Input 2_Level PID setting 2	2LEV2
	Input 2_Level PID setting 3	2LEV3
	Input 2_Level PID setting 4	2LEV4
	Input 2_Level PID setting 5	2LEV5
	Input 2_Level PID setting 6	2LEV6

MEMO

5

INPUT FUNCTION

This chapter describes input related functions, setting contents and setting procedure based on the key words related to inputs.

5.1	Changing Input	5-2
5.2	Switching Functions Using Digital Inputs (DI).....	5-16
5.3	Correcting Input (PV Bias and PV Ratio)	5-28
5.4	Preventing the Input Flicker	5-31
5.5	Inverting the Input	5-33
5.6	Extracting Square Root of Input.....	5-35
5.7	Changing Error Handling at Input Error	5-39
5.8	Using Dual Input Function	5-48
5.9	Changing Power Supply Frequency	5-51
5.10	Making Corrections at Multiple Points (Input Knee Point Correction)	5-52

5.1 Changing Input

Measured input can be changed at following parameters. Set the input according to the sensor and the application.

- Input type
- Dispaly unit
- Decimal point position
- Input range high/Input range low
- Input data type

■ Description of function

Input type

Input type can be easily configured to thermocouple, RTD, current or voltage only by changing the settings.

- TC input type: K, J, R, S, B, E, N, T, W5Re/W26Re, PL II, U, L, PR40-20
- RTD input type: Pt100, JPt100
- Current input type: 0 to 20 mA DC, 4 to 20 mA DC
- Voltage input type: 0 to 10 V DC, 0 to 5 V DC, 1 to 5 V DC, 0 to 1 V DC, -10 to +10 V DC, -5 to +5 V DC, 0 to 100 mV DC, 0 to 10 mV DC

Display unit

In case of thermocouple or RTD input, the measurement unit can be selected from °C and °F.

Decimal point position

The decimal point position depends on the input type.

- TC input: K, J, R, S, B, E, N, T, PL II, U, L: No decimal place or One decimal place
Thermocouples other than those shown above: No decimal place (fixed)
- RTD input: No decimal place, One decimal place or Two decimal places
- Voltage/Current input: In case of Input data type 0 or 2: No decimal place, One decimal place, Two decimal places, Three decimal places or Four decimal places
In case of Input data type 1: No decimal place, One decimal place, Two decimal places or Three decimal places



For the Input data type, see **Input range table (P. 5-11)**.

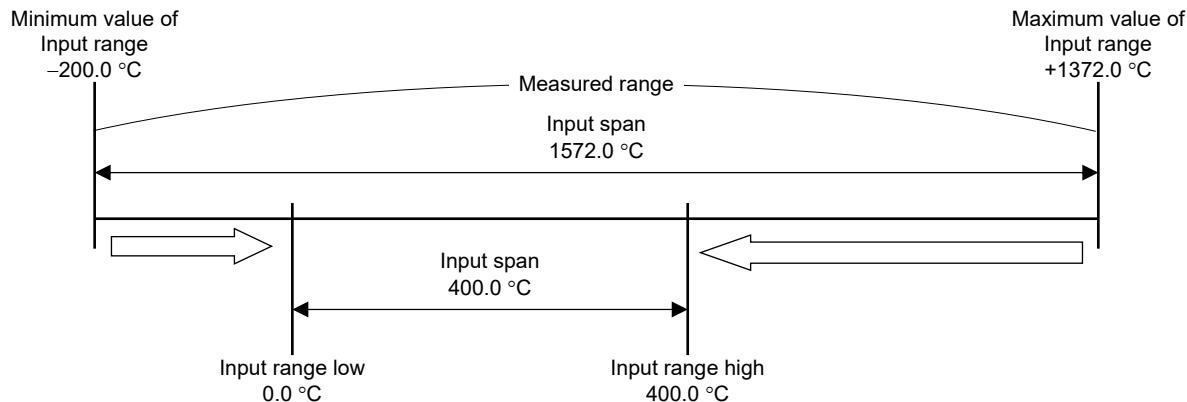
Input range high/low

In the case of temperature input (TC and RTD), input ranges can be changed. In the case of voltage (V) and current (I) inputs, the display range is programmable within -19999 and +99999.

(The input range specified when ordered can be changed by setting the input range high and low.)

Example of input change 1:

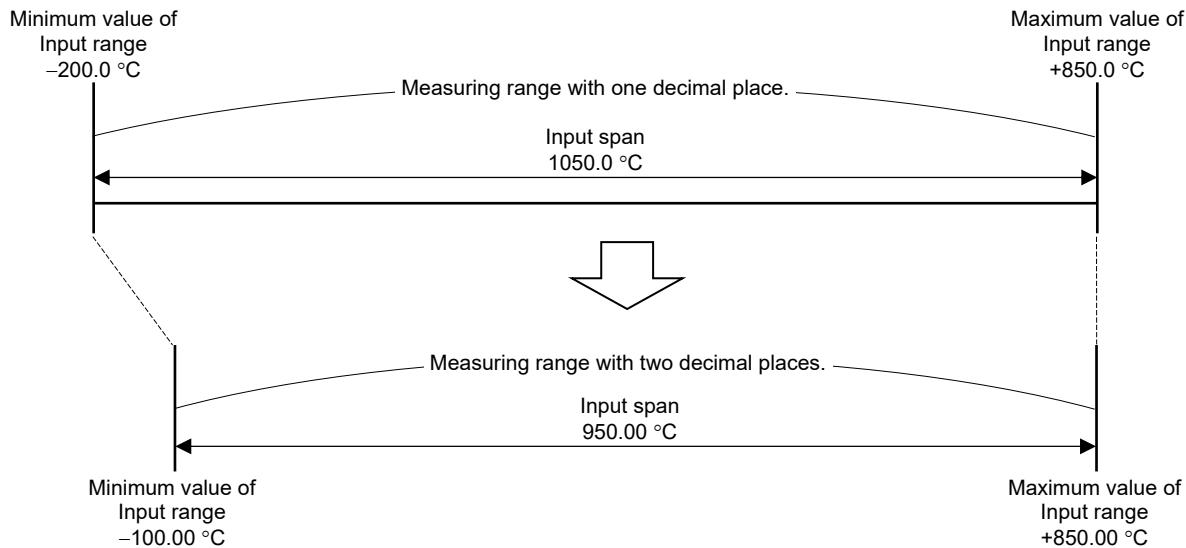
Changing thermocouple K “-200.0 to +1372.0 °C” to “0.0 to 400.0 °C”



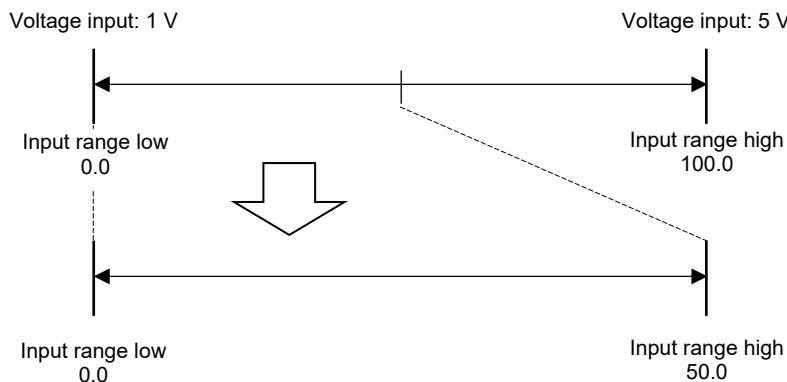
Example of input change 2:

When the input range is -200.0 to $+850.0$ °C (Input type: RTD Pt100), changing the decimal point position to 2 from 1 will change the input range to -100.00 to $+850.00$ °C.

The maximum range with an RTD Pt100 input with two decimal places is -100.00 to $+850.00$ °C. Accordingly setting beyond this range is not possible.

**Example of input change 3:**

In the case of Voltage input (1 to 5 V DC), the input range has been reduced from “0.0 to 100.0” to “0.0 to 50.0.”

**Input data type**

The number of digits of the Measured value (PV), the number of data digits in RKC communication, the data type in Modbus communication (double word or single word) can be changed.

■ Parameter setting

-  See the **Input range table (P. 5-11)** for the input range of each input type.
-  For the input range code, see **Input range code table (P. 5-13)**.

● Input 1_Input type

[Engineering Mode: Function block No. 21 (Fn21)]

Parameter symbol	Data range	Factory set value	
I_1NP	0: TC input K 1: TC input J 2: TC input R 3: TC input S 4: TC input B 5: TC input E 6: TC input N 7: TC input T 8: TC input W5Re/W26Re 9: TC input PL II 10: TC input U 11: TC input L 12: TC input PR40-20 13: RTD input Pt100 14: RTD input JPt100	15: Current input 0 to 20 mA DC 16: Current input 4 to 20 mA DC 17: Voltage input 0 to 10 V DC 18: Voltage input 0 to 5 V DC 19: Voltage input 1 to 5 V DC 20: Voltage input 0 to 1 V DC 21: Voltage input -10 to +10 V DC 22: Voltage input -5 to +5 V DC 23: Voltage input 0 to 100 mV DC 24: Voltage input 0 to 10 mV DC	Same as the input type of the input range code specified at the time of order.

NOTE

When the input type is changed from current or high voltage input * to TC, RTD or low voltage input *, remove the wirings of the measured input before attempting the input change. Changing the input type with the signal applied to the instrument may lead to a failure of the instrument.

* High voltage input: 0 to 10 V DC, 0 to 5 V DC, 1 to 5 V DC, 0 to 1 V DC, -10 to +10 V DC, -5 to +5 V DC
 Low voltage input: 0 to 100 mV DC, 0 to 10 mV DC

-  See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are initialized or changed when the input type is changed.

● Input 2_Input type

[Engineering Mode: Function block No. 22 (Fn22)]

Parameter symbol	Data range	Factory set value
2. I NP	0: TC input K 1: TC input J 2: TC input R 3: TC input S 4: TC input B 5: TC input E 6: TC input N 7: TC input T 8: TC input W5Re/W26Re 9: TC input PL II 10: TC input U 11: TC input L 12: TC input PR40-20 13: RTD input Pt100 14: RTD input JPt100 ● When Measured input 2 is selected: 0 to 24 ● When Remote setting input is selected: 15 to 24	Same as Input 1_Input type When Remote setting input is specified at the time of order, but the input type is not specified: 17



NOTE

When the input type is changed from current or high voltage input * to TC, RTD or low voltage input *, remove the wirings of the measured input before attempting the input change.

Changing the input type with the signal applied to the instrument may lead to a failure of the instrument.

* High voltage input: 0 to 10 V DC, 0 to 5 V DC, 1 to 5 V DC, 0 to 1 V DC, -10 to +10 V DC, -5 to +5 V DC

Low voltage input: 0 to 100 mV DC, 0 to 10 mV DC



To display Input 2_Input type, “Measured input 2” or “Remote setting input” must be specified at the time of order.



Input 2_Input type is not displayed if “No function” is selected at Select function for input 2 in Function block No. 58 in the Engineering mode.



See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are initialized or changed when the input type is changed.

● Input 1_Display unit

[Engineering Mode: Function block No. 21 (Fn21)]

Parameter symbol	Data range	Factory set value
I.UNI_F	0: °C 1: °F	Same as the display unit of the input range code specified at the time of order.



To show “Input 1_Display unit,” thermocouple or RTD must be selected at Input 1_Input type in Function block No. 21 in the Engineering mode.



See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized or changed when the display unit is changed.

● Input 2_Display unit

[Engineering Mode: Function block No. 22 (Fn22)]

Parameter symbol	Data range	Factory set value
2.UNI_F	0: °C 1: °F	Same as Input 1_Temperature unit



To show “Input 2_Display unit,” “Measured input 2” must be specified at the time of order and thermocouple or RTD must be selected at “Input 2_Input type” in Function block No. 22 in the Engineering mode.



Input 2_Input type is not displayed if “No function” is selected at Select function for input 2 in Function block No. 58 in the Engineering mode. The setting cannot be changed if Remote setting input and Control with PV select are set.



See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized or changed when the display unit is changed.

● **Input 1_Decimal point position**
[Engineering Mode: Function block No. 21 (Fn21)]

Parameter symbol	Data range	Factory set value
<i>I.PGdP</i>	<p>0: No decimal place 1: One decimal place 2: Two decimal places 3: Three decimal places 4: Four decimal places</p> <p>TC input: W5Re/W26Re, PR40-20: 0 (fixed) Thermocouples other than those shown above: 0 to 1</p> <p>RTD input: 0 to 2</p> <p>Voltage (V)/Current (I) input: In case of Input data type 0 or 2: 0 to 4 In case of Input data type 1: 0 to 3</p> <p>When Control with PV select: Decimal point position setting of Input 1 and Input 2 is compared and the smaller will be used.</p>	Same as the decimal point position of the input range code specified at the time of order. For V/I inputs: 1

-  See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized or automatically converted when the decimal point position is changed.

● **Input 2_Decimal point position**
[Engineering Mode: Function block No. 22 (Fn22)]

Parameter symbol	Data range	Factory set value
<i>2.PGdP</i>	<p>0: No decimal place 1: One decimal place 2: Two decimal places 3: Three decimal places 4: Four decimal places</p> <p>TC input: W5Re/W26Re, PR40-20: 0 (fixed) Thermocouples other than those shown above: 0 to 1</p> <p>RTD input: 0 to 2</p> <p>Voltage (V)/Current (I) input: In case of Input data type 0 or 2: 0 to 4 In case of Input data type 1: 0 to 3</p>	Same as Input 1_Decimal point position

-  To show the “Input 2_Decimal point position,” “Measured input 2” must be specified at the time of order.
-  Input 2_Input type is not displayed if “No function” is selected at Select function for input 2 in Function block No. 58 in the Engineering mode. The setting cannot be changed if Remote setting input and Control with PV select are set.
-  When Control with PV select is set in “Select function for input 2” in Function block No. 58 in the Engineering mode, a smaller value (of Decimal point position setting for Input 1 and Input 2) will be used.
-  See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized or automatically converted when the decimal point position is changed.

● **Input 1_Input range high**
[Engineering Mode: Function block No. 21 (Fn21)]

Parameter symbol	Data range	Factory set value
I.PGSH	(Input 1_Input range low + 1 digit) to Input 1_Maximum value of input range [Varies with the setting of the Decimal point position.] See the Input range table (P. 5-11) for the input range of each input type.	High limit value of the input range code specified at the time of order. For V/I inputs: 100.0

 See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are automatically converted when the Input range high is changed.

● **Input 2_Input range high**
[Engineering Mode: Function block No. 22 (Fn22)]

Parameter symbol	Data range	Factory set value
2.PGSH	<ul style="list-style-type: none"> TC/RTD inputs and Voltage (V)/Current (I) inputs (For other than Remote setting input): (Input 2_Input range low + 1 digit) to Input 2_Maximum value of input range [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs (For Remote setting input): (Input 2_Input range low + 1 digit) to Input 1_Maximum value of input range [Varies with the setting of the Decimal point position.] See the Input range table (P. 5-11) for the input range of each input type.	Same as Input 1_Input range high

 To display Input 2_Input range high, “Measured input 2” or “Remote setting input” must be specified at the time of order.

 See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are automatically converted when the Input range high is changed.

● Input 1_Input range low

[Engineering Mode: Function block No. 21 (Fn21)]

Parameter symbol	Data range	Factory set value
I.PGSL	Input 1_Minimum value of input range to (Input 1_Input range high – 1 digit) [Varies with the setting of the Decimal point position.] See the Input range table (P. 5-11) for the input range of each input type.	Low limit value of the input range code specified at the time of order. For V/I inputs: 0.0

-  See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are automatically converted when the Input range low is changed.

● Input 2_Input range low

[Engineering Mode: Function block No. 22 (Fn22)]

Parameter symbol	Data range	Factory set value
2.PGSL	<ul style="list-style-type: none"> • TC/RTD inputs and Voltage (V)/Current (I) inputs (For other than Remote setting input): Input 2_Minimum value of input range to (Input 2_Input range high – 1 digit) [Varies with the setting of the Decimal point position.] • Voltage (V)/Current (I) inputs (For Remote setting input): Input 1_Minimum value of input range to (Input 2_Input range high – 1 digit) [Varies with the setting of the Decimal point position.] See the Input range table (P. 5-11) for the input range of each input type.	Same as Input 1_Input range low

-  To display Input 2_Input range low, “Measured input 2” or “Remote setting input” must be specified at the time of order.

-  See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are automatically converted when the Input range low is changed.

● **Input data type**

[Engineering Mode: Function block No. 21 (F_{n2}^2)]

Parameter symbol	Data range	Factory set value
$I\ Ndf$	<p>0: Number of measured value digits: 5 Number of RKC communication digits: 7 Modbus: Double word PLC communication: Double word (System data: Single word)</p> <p>1: Number of measured value digits: 4 Number of RKC communication digits: 6 Modbus: Single word * PLC communication: Single word</p> <p>2: HA series equivalent (Communication identifiers of RKC communication and register address of Modbus switch to the HA series equivalent data.) Number of measured value digits: 5 Number of RKC communication digits: 7 Modbus: Double word PLC communication: Double word (System data: Single word) * The data of the FB series and its equivalent are included.</p> <p>When changing the Input data type from 0 (or 2) to 1 and when the present Input range has 5 digits (example: Input range high: 1372.0), you need to configure the Input range to have 4 digits beforehand.</p> <p>The unit of time depends on the Input data type. In case of Input data type 0 or 2 hour/minute/second, hour/minute, minute/second, second In case of Input data type 1 hour/minute, minute/second, second</p>	0



See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are automatically converted when the Input data type is changed.

■ Input range table

The input range may vary with the Input data type.

The Input data types are as follows.

- Measured value (PV): 5 or 4 digits for the display
- RKC communication: 7 or 6 digits for the data
- Modbus: Double word or single word
- PLC communication: Double word or single word

 The Input data type can be changed at “Input data type” in Function block No. 21 in the Engineering mode.

 The input resolution may vary with the selected input range, display unit, and decimal point position.

● TC input

Input type	Decimal point position	In case of Input data type 0 or 2		In case of Input data type 1	
		Number of measured value digits: 5 Number of RKC communication digits: 7 Modbus: Double word PLC communication: Double word	°C °F	Number of measured value digits: 4 Number of RKC communication digits: 6 Modbus: Single word PLC communication: Single word	°C °F
K	No decimal place	-200 to +400 °C	-328 to +752 °F	-200 to +400 °C	-328 to +752 °F
		-200 to +1372 °C	-328 to +2502 °F	-200 to +1372 °C	-328 to +2502 °F
	One decimal place	-200.0 to +400.0 °C	-328.0 to +752.0 °F	-199.9 to +400.0 °C	-199.9 to +752.0 °F
		-200.0 to +1372.0 °C	-328.0 to +2502.0 °F	-199.9 to +999.9 °C	-199.9 to +999.9 °F
J	No decimal place	-200 to +400 °C	-328 to +752 °F	-200 to +400 °C	-328 to +752 °F
		-200 to +1200 °C	-328 to +2192 °F	-200 to +1200 °C	-328 to +2192 °F
	One decimal place	-200.0 to +400.0 °C	-328.0 to +752.0 °F	-199.9 to +400.0 °C	-199.9 to +752.0 °F
		-200.0 to +1200.0 °C	-328.0 to +2192.0 °F	-199.9 to +999.9 °C	-199.9 to +999.9 °F
T	No decimal place	-200 to +400 °C	-328 to +752 °F	-200 to +400 °C	-328 to +752 °F
	One decimal place	-200.0 to +400.0 °C	-328.0 to +752.0 °F	-199.9 to +400.0 °C	-199.9 to +752.0 °F
S *	No decimal place	-50 to +1768 °C	-58 to +3214 °F	-50 to +1768 °C	-58 to +3214 °F
	One decimal place	-50.0 to +1768.0 °C	-58.0 to +3214.0 °F	-50.0 to +999.9 °C	-58.0 to +999.9 °F
R *	No decimal place	-50 to +1768 °C	-58 to +3214 °F	-50 to +1768 °C	-58 to +3214 °F
	One decimal place	-50.0 to +1768.0 °C	-58.0 to +3214.0 °F	-50.0 to +999.9 °C	-58.0 to +999.9 °F
E *	No decimal place	-200 to +1000 °C	-328 to +1832 °F	-200 to +1000 °C	-328 to +1832 °F
	One decimal place	-200.0 to +1000.0 °C	-328.0 to +1832.0 °F	-199.9 to +999.9 °C	-199.9 to +999.9 °F
B *	No decimal place	0 to 1800 °C	0 to 3272 °F	0 to 1800 °C	0 to 3272 °F
	One decimal place	0.0 to 1800.0 °C	0.0 to 3272.0 °F	0.0 to 999.9 °C	0.0 to 999.9 °F
N *	No decimal place	0 to 1300 °C	0 to 2372 °F	0 to 1300 °C	0 to 2372 °F
	One decimal place	0.0 to 1300.0 °C	0.0 to 2372.0 °F	0.0 to 999.9 °C	0.0 to 999.9 °F
W5Re/W26Re	No decimal place	0 to 2300 °C	0 to 4200 °F	0 to 2300 °C	0 to 4200 °F
PL II *	No decimal place	0 to 1390 °C	0 to 2534 °F	0 to 1390 °C	0 to 2534 °F
	One decimal place	0.0 to 1390.0 °C	0.0 to 2534.0 °F	0.0 to 999.9 °C	0.0 to 999.9 °F
U	No decimal place	-200 to +600 °C	-328 to +1112 °F	-200 to +600 °C	-328 to +1112 °F
	One decimal place	-200.0 to +600.0 °C	-328.0 to +1112.0 °F	-199.9 to +600.0 °C	-199.9 to +999.9 °F
L	No decimal place	0 to 900 °C	0 to 1652 °F	0 to 900 °C	0 to 1652 °F
	One decimal place	0.0 to 900.0 °C	0.0 to 1652.0 °F	0.0 to 900.0 °C	0.0 to 999.9 °F
PR40-20	No decimal place	0 to 1800 °C	0 to 3200 °F	0 to 1800 °C	0 to 3200 °F

* The least significant digit (LSD) may flicker when the display resolution is set to 0.1°C (0.1°F).

 If there is no decimal point, there is no difference in the input range by Input data type.

 Thermcouple inputs K, J, T, S, R, E, B, N, PL II, U, and L are settable to one decimal place.

● RTD input

Input type	Decimal point position	In case of Input data type 0 or 2		In case of Input data type 1	
		Number of measured value digits: 5 Number of RKC communication digits: 7 Modbus: Double word PLC communication: Double word		Number of measured value digits: 4 Number of RKC communication digits: 6 Modbus: Single word PLC communication: Single word	
Pt100	No decimal place	-200 to +850 °C	-328 to +1562 °F	-200 to +850 °C	-328 to +1562 °F
	One decimal place	-100 to +100 °C	-148 to +212 °F	-100 to +100 °C	-148 to +212 °F
		0 to 50 °C	32 to 122 °F	0 to 50 °C	32 to 122 °F
		-200.0 to +850.0 °C	-328.0 to +1562.0 °F	-199.9 to +850.0 °C	-199.9 to +999.9 °F
	Two decimal places	-100.0 to +100.0 °C	-148.0 to +212.0 °F	-100.0 to +100.0 °C	-148.0 to +212.0 °F
		0.0 to 50.0 °C	32.0 to 122.0 °F	0.0 to 50.0 °C	32.0 to 122.0 °F
JPt100	No decimal place	-100.00 to +850.00 °C	-148.00 to +999.99 °F	-19.99 to +99.99 °C	-19.99 to +99.99 °F
	One decimal place	0.00 to 50.00 °C	32.00 to 122.00 °F	0.00 to 50.00 °C	32.00 to 99.99 °F
		-200 to +640 °C	-328 to +1184 °F	-200 to +640 °C	-328 to +1184 °F
		-100 to +100 °C	-148 to +212 °F	-100 to +100 °C	-148 to +212 °F
	Two decimal places	0 to 50 °C	32 to 122 °F	0 to 50 °C	32 to 122 °F
		-200.0 to +640.0 °C	-328.0 to +1184.0 °F	-199.9 to +640.0 °C	-199.9 to +999.9 °F
		-100.0 to +100.0 °C	-148.0 to +212.0 °F	-100.0 to +100.0 °C	-148.0 to +212.0 °F
		0.0 to 50.0 °C	32.0 to 122.0 °F	0.0 to 50.0 °C	32.0 to 122.0 °F
		-100.00 to +640.00 °C	-148.00 to +999.99 °F	-19.99 to +99.99 °C	-19.99 to +99.99 °F
		0.00 to 50.00 °C	32.00 to 122.00 °F	0.00 to 50.00 °C	32.00 to 99.99 °F



If there is no decimal point, there is no difference in the input range by Input data type.

● Voltage/Current input

Input type	Decimal point position	In case of Input data type 0 or 2		In case of Input data type 1	
		Number of measured value digits: 5 Number of RKC communication digits: 7 Modbus: Double word PLC communication: Double word		Number of measured value digits: 4 Number of RKC communication digits: 6 Modbus: Single word PLC communication: Single word	
Voltage/Current	No decimal place	-19999 to +99999		-1999 to +9999	
	One decimal place	-1999.9 to +9999.9		-199.9 to +999.9	
	Two decimal places	-199.99 to +99.99		-19.99 to +99.99	
	Three decimal places	-19.999 to +9.999		-1.999 to +9.999	
	Four decimal places	-1.9999 to +9.9999			

Input range code table (can be specified when ordering)



The Input range code table is a list of input range codes so that a user can specify the input range at the time of ordering. Even if the input range has been specified when ordered, the input range can be changed later within the measured range.

● TC Input

Type	Code	Range	See Note
K	K01	0 to 200 °C	5
	K02	0 to 400 °C	5
	K03	0 to 600 °C	5
	K04	0 to 800 °C	5
	K06	0 to 1200 °C	5
	K07	0 to 1372 °C	5
	K08	-199.9 to +300.0 °C	5
	K09	0.0 to 400.0 °C	5
	K10	0.0 to 800.0 °C	5
	K14	0 to 300 °C	5
	K41	-200 to +1372 °C	5
	K42	-200.0 to +1372.0 °C	5
	KA1	0 to 800 °F	5
	KA2	0 to 1600 °F	5
	KA3	0 to 2502 °F	5
J	J01	0 to 200 °C	5
	J02	0 to 400 °C	5
	J03	0 to 600 °C	5
	J04	0 to 800 °C	5
	J08	0.0 to 400.0 °C	5
	J29	-200.0 to +1200.0 °C	5
	JA1	0 to 800 °F	5
	JA3	0 to 2192 °F	5
	JA6	0 to 400 °F	5

Type	Code	Range	See Note
T	T01	-199.9 to +400.0 °C	5
	T02	-199.9 to +100.0 °C	5
	T03	-100.0 to +200.0 °C	5
	T19	-200.0 to +400.0 °C	5
R	R01	0 to 1600 °C	5
	R07	-50 to +1768 °C	5
	R08	-50.0 to +1768.0 °C	5
	R09	0.0 to 1600.0 °C	5
S	S06	-50 to +1768 °C	5
	S07	-50.0 to +1768.0 °C	5
B	B03	0 to 1800 °C	5
	B04	0.0 to 1800.0 °C	5
E	E01	0 to 800 °C	5
	E23	0.0 to 800.0 °C	5
N	N02	0 to 1300 °C	5
	N05	0.0 to 1300.0 °C	5
W5Re/ W26Re	W03	0 to 2300 °C	5
PL II	A01	0 to 1300 °C	5
	A05	0.0 to 1300.0 °C	5
U	U01	-199.9 to +600.0 °C	5
L	L04	0.0 to 900.0 °C	5
PR40-20	F02	0 to 1800 °C	5
	FA2	0 to 3200 °F	5

● RTD input

Type	Code	Range	See Note
Pt100	D01	-199.9 to +649.0 °C	5
	D04	-100.0 to +100.0 °C	5
	D05	-100.0 to +200.0 °C	5
	D06	0.0 to 50.0 °C	5
	D07	0.0 to 100.0 °C	5
	D08	0.0 to 200.0 °C	5
	D09	0.0 to 300.0 °C	5
	D10	0.0 to 500.0 °C	5
	D12	-199.9 to +600.0 °C	5
	D21	-200.0 to +200.0 °C	5

Type	Code	Range	See Note
Pt100	D27	0.00 to 50.00 °C	5
	D34	-100.00 to +100.00 °C	5
	D35	-200.0 to +850.0 °C	5
	D48	-100.00 to +850.00 °C	5
	DA1	-199.9 to +999.9 °F	5
	DA9	0.0 to 500.0 °F	5
JPt100	P08	0.0 to 200.0 °C	5
	P29	-100.00 to +100.00 °C	5
	P30	-200.0 to +640.0 °C	5
	P36	-100.00 to +640.00 °C	5

● Voltage/Current input

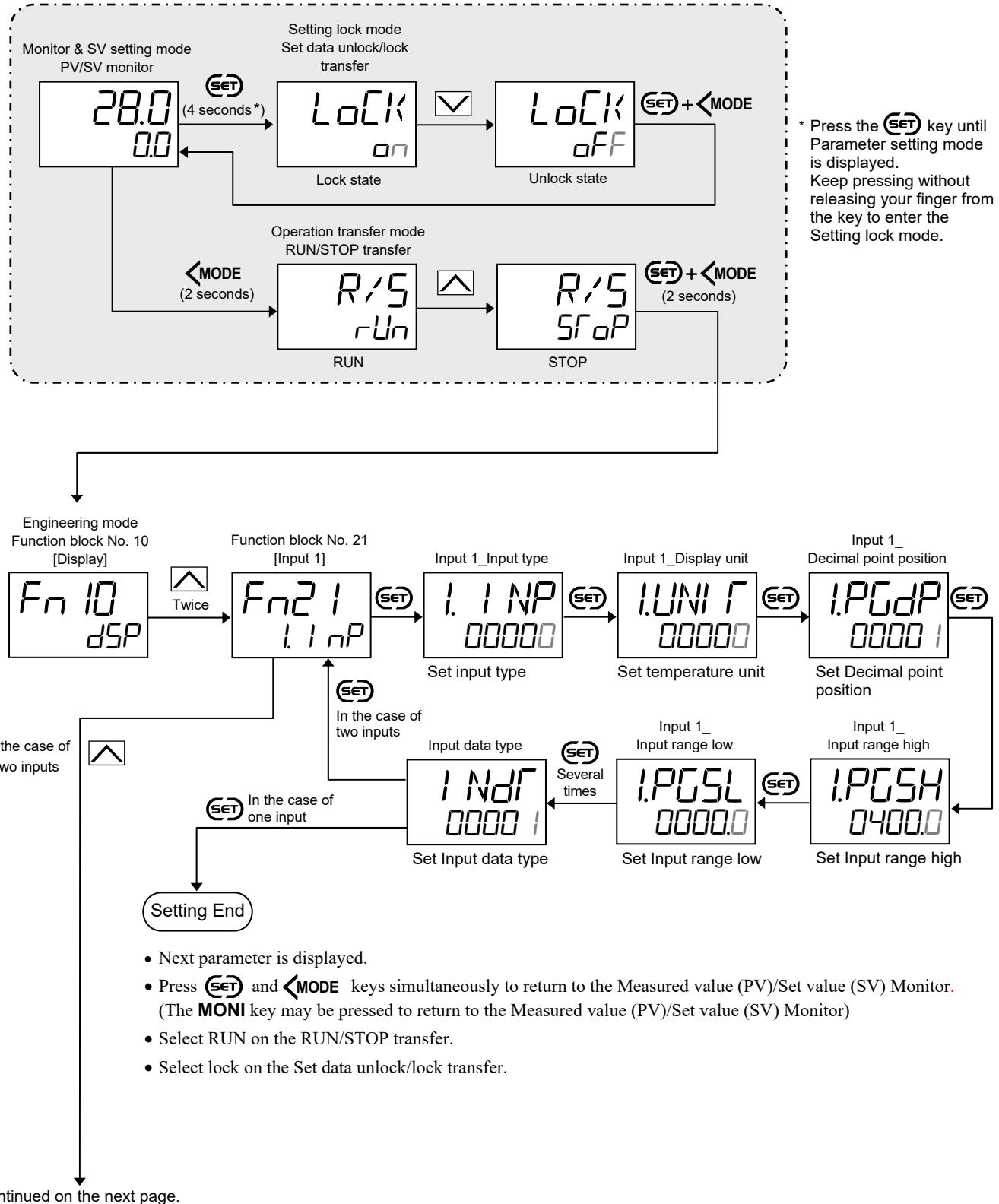
Type	Code	Range	See Note
Voltage/ Current	101	0 to 10 mV DC	5
	201	0 to 100 mV DC	5
	301	0 to 1 V DC	5
	401	0 to 5 V DC	5
	501	0 to 10 V DC	5

Type	Code	Range	See Note
Voltage/ Current	601	1 to 5 V DC	5
	701	0 to 20 mA DC	5
	801	4 to 20 mA DC	5
	904	-10 to +10 V DC	5
	905	-5 to +5 V DC	5

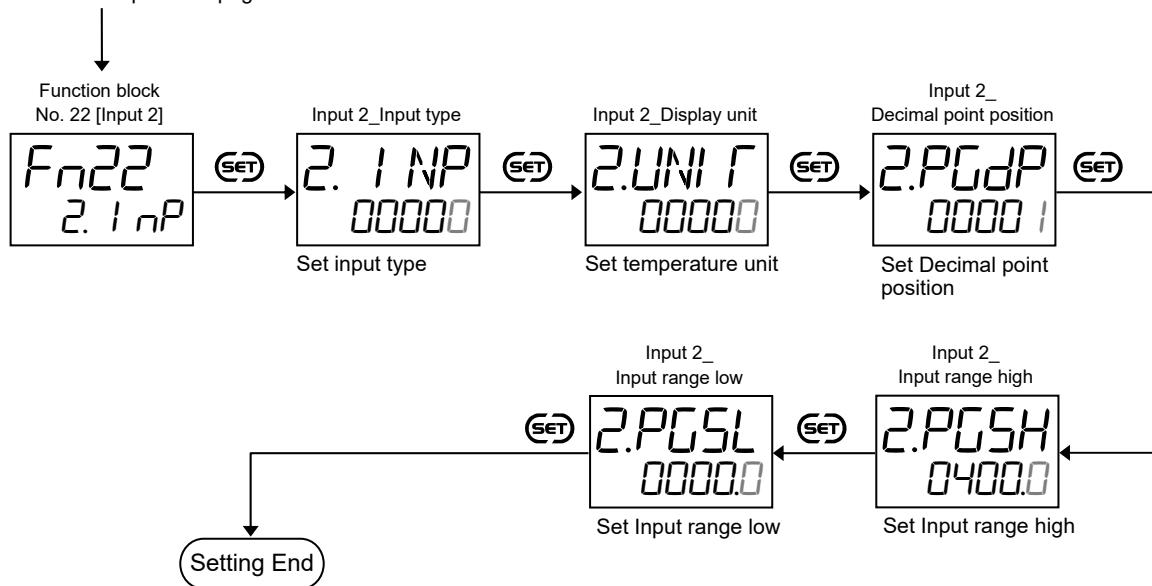
Note The number of displayed digits of the measured value.

■ Setting procedure

To enter the Engineering mode



Continued from the previous page.



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

5.2 Switching Functions Using Digital Inputs (DI)

With the use of Digital input (DI), switching between the following functions is available.

- RUN/STOP transfer
 - Auto/Manual transfer
 - Select function for input 2 transfer * (Remote/Local transfer, PV select transfer
or 2-loop control/Differential temperature control)
- * The function selected at Select function for Input 2 is switchable.
- Interlock release
 - Peak/Bottom holds reset
 - Selection of Autotuning (AT)
 - Set data Unlock/Lock
 - Direct/Reverse action
 - Memory area

■ Number of Digital input (DI)

Maximum 6 points (None, 4, or 6)

■ Functional setting of Digital input (DI)

Set the desired function at each Digital input (DI).

Setting	DI1	DI2	DI3	DI4	DI5	DI6
0	No function					
1	RUN/STOP	RUN/STOP	RUN/STOP	RUN/STOP	RUN/STOP	RUN/STOP
2	AUTO/MAN (1/2)					
3	AUTO/MAN (1)					
4	AUTO/MAN (2)					
5	REM/LOC	REM/LOC	REM/LOC	REM/LOC	REM/LOC	REM/LOC
6	Interlock release					
7	Hold reset (1/2)					
8	Hold reset (1)					
9	Hold reset (2)					
10	AT ON/OFF (1/2)					
11	AT ON/OFF (1)					
12	AT ON/OFF (2)					
13	Unlock/Lock	Unlock/Lock	Unlock/Lock	Unlock/Lock	Unlock/Lock	Unlock/Lock
14	Direct/Reverse action					
15	2 areas					
16	8 areas without SET					
17	8 areas with SET					
18	16 areas without SET					
19	16 areas with SET					
20	Area jump					

: The Setting range of DI2 to DI6 is from 0 to 14. Values 15 or larger cannot be set.

 : When any of 16, 17, 18, and 19 is set for DI1, DI2 to DI5 (which are crossed out with ) are used for switching the Memory area and not settable.

Continued on the next page.

Continued from the previous page.

[Explanation of functional setting]

RUN/STOP:	RUN/STOP transfer
AUTO/MAN (1/2):	Auto/Manual transfer (Common to Input 1/Input 2)
AUTO/MAN (1):	Auto/Manual transfer (Input 1 only)
AUTO/MAN (2):	Auto/Manual transfer (Input 2 only) ¹
REM/LOC:	Remote/Local transfer *
	(PV select transfer, 2-loop control/Differential temperature control)
	* The function selected at Select function for input 2 is switchable.
Interlock release:	Release of Interlock
Hold reset (1/2):	Reset of Peak or Bottom hold value (Common to Input 1/Input 2)
Hold reset (1):	Reset of Peak or Bottom hold value (Input 1 only)
Hold reset (2):	Reset of Peak or Bottom hold value (Input 2 only) ¹
AT ON/OFF (1/2):	Autotuning (AT) ON/OFF (Common to Input 1/Input 2)
AT ON/OFF (1):	Autotuning (AT) ON/OFF (Input 1 only)
AT ON/OFF (2):	Autotuning (AT) ON/OFF (Input 2 only) ¹
Unlock/Lock:	Set data unlock/lock
Direct/Reverse action:	Switching between direct and reverse actions (Common to Input 1/Input 2) ²
2 areas:	Memory area transfer 2 points (without area set signal)
8 areas without SET:	Memory area transfer 8 points (without area set signal) ³
8 areas with SET:	DI2 and DI3 are not settable in this setting. Memory area transfer 8 points (with area set signal) ⁴
16 areas without SET:	DI2, DI3 and DI4 are not settable in this setting. Memory area transfer 16 points (without area set signal) ⁴
16 areas with SET:	DI2, DI3 and DI4 are not settable in this setting. Memory area transfer 16 points (with area set signal) ⁵
Area jump:	DI2, DI3, DI4 and DI5 are not settable in this setting. Move to the linked area No. (If area is not specified, the jump destination is the current area No. + 1)

¹ Effective if two inputs are available

² Effective if setting of control action of Input 1 or Input 2 is any of 0, 1, 5, and 6.

³ Effective if three or more Digital inputs (DI) are available

⁴ Effective if four or more Digital inputs (DI) are available

⁵ Effective if six or more Digital inputs (DI) are available

■ Open/Close action of Digital Input (DI)

- **RUN/STOP transfer, Auto/Manual transfer, Remote/Local transfer, Set data unlock/lock transfer and Direct/Reverse action transfer**

Functions are selected as follows using the open/close action of the contact.

Function	Contact close	Contact open
RUN/STOP transfer	RUN	STOP
Auto/Manual transfer	Auto mode	Manual mode
Remote/Local transfer ¹	Remoto mode	Local mode
	Input 2	Input 1
PV select transfer ²	Differential temperature control	2-loop control
2-loop control/Differential temperature control		
Set data unlock/lock transfer	Lock	Unlock
Direct/Reverse action transfer	Direct action	Reverse action

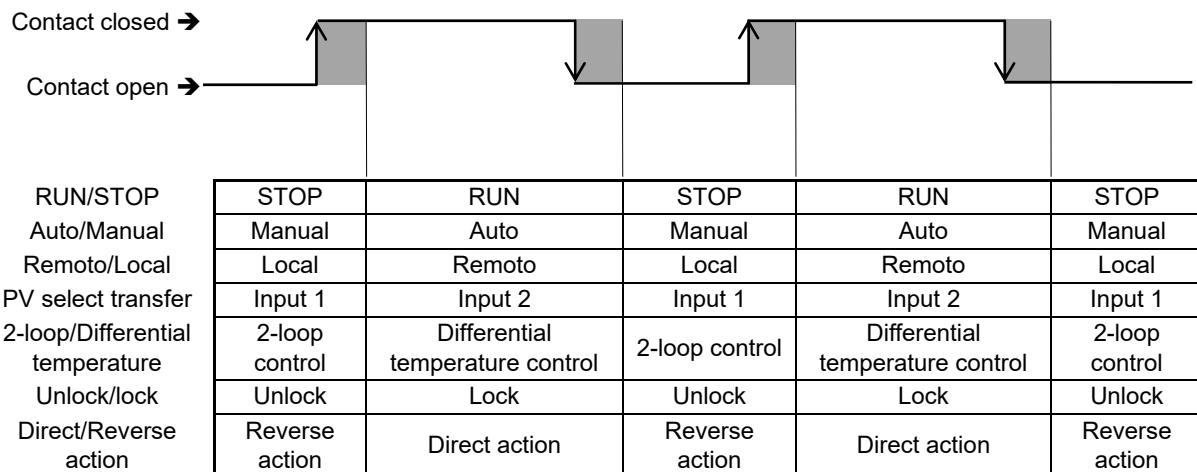
¹ Only one of the functions is available

² When [1: Switch by signal] is selected at Selection of PV select trigger (in Function block No. 58 in the Engineering mode)

- Switching between Direct/Reverse action is available, only while the instrument is at STOP. Switching is not available during RUN. Setting the contact at RUN beforehand will perform switching when the instrument enters the STOP mode. If “Input 1_Control action” or “Input 2_Control action” is set to “0: Brilliant II PID control (direct action)” or “1: Brilliant II PID control (reverse action),” PID action is switched between reverse and direction actions.
- The above open/close action can be reversed (reversing the functions of open and close). This setting can be done in DI logic invert (Function block No. 23 in the Engineering mode).

Timing chart of functions

: Within 50 ms

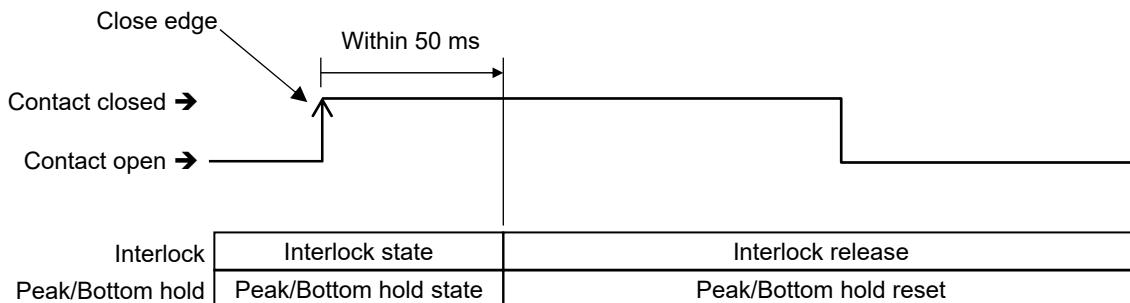


After the contact is transferred, it takes “Within 50 ms” until the action of this instrument is actually selected.

● Interlock release, Peak/Bottom hold reset

Through the detection of close edge (rising edge), Interlock state and Peak (or Bottom) hold values are released.

Timing chart for releasing interlock, peak and bottom hold



After the contact is transferred, it takes “Within 50 ms” until the action of this instrument is actually selected.

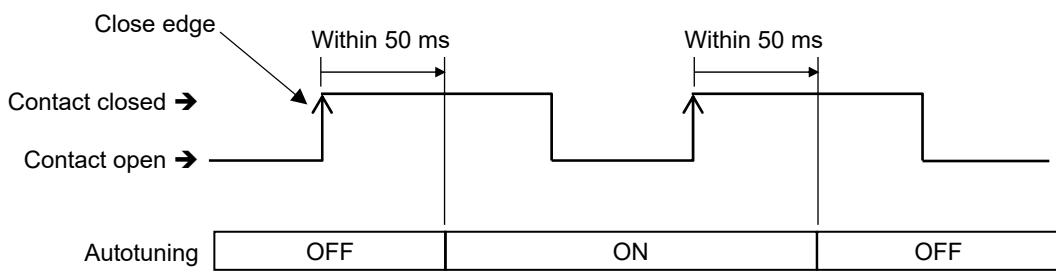
● Autotuning (AT) ON/OFF

Through the detection of the close edge, Autotuning (AT) ON/OFF is switched.

If Input 1 and Input 2 are common, priority is given to the AT start. (See the table below)

Status before AT on/off switching		Status after AT on/off switching	
Input 1	Input 2	Input 1	Input 2
in PID control	in PID control	AT start	AT start
during AT	in PID control	AT continues	AT start
in PID control	during AT	AT start	AT continues
during AT	during AT	PID control	PID control

ON/OFF timing chart of Autotuning (AT)



After the contact is transferred, it takes “Within 50 ms” until the action of this instrument is actually selected.

● Memory area transfer

Selection of Memory area No. can be obtained through such contact status as shown below.

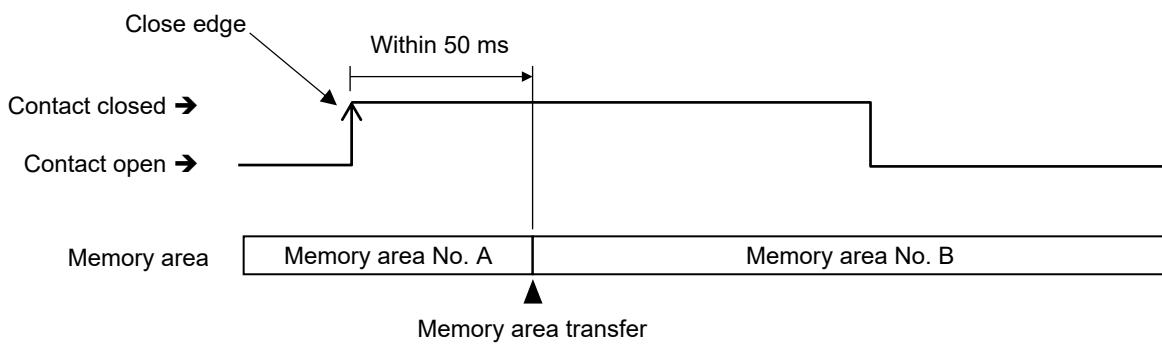
Memory area No.	DI1	DI2	DI3	DI4
1	—	—	—	—
2	x	—	—	—
3	—	x	—	—
4	x	x	—	—
5	—	—	x	—
6	x	—	x	—
7	—	x	x	—
8	x	x	x	—
9	—	—	—	x
10	x	—	—	x
11	—	x	—	x
12	x	x	—	x
13	—	—	x	x
14	x	—	x	x
15	—	x	x	x
16	x	x	x	x

—: Open
x: Closed

-  : Areas used by DI for 2 areas.
-  : Areas used by DI for 8 areas.
-  : Areas used by DI for 16 areas.

Memory area transfer timing

- With SET signal · First, change the contact status to a desired No. referring to the above table, and use a Close edge (Rising edge) of the area SET signal.
The area SET signal contact is: DI4 for 8 memory areas and DI5 for 16 memory areas.



After the contact is transferred, it takes “Within 50 ms” until the action of this instrument is actually selected.

- Without SET signal · First select the memory area using contacts, then wait for 1 to 5 seconds (set in “Area switching time (without area set signal)” [Engineering mode, Function block No. 23]).



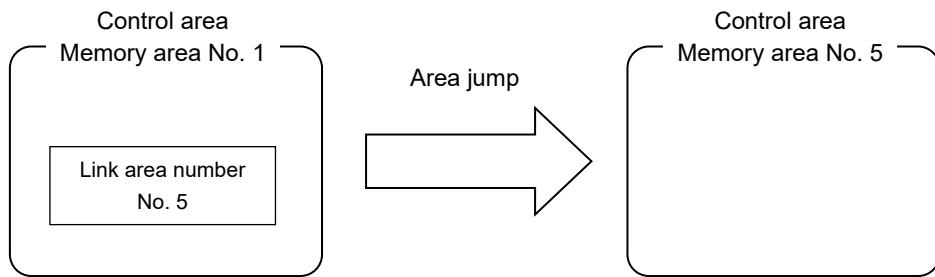
To change the Memory area without using the SET signal, “External mode” must be set at Control area Local/External transfer in the Operation transfer mode.

● Area jump

The memory area will be switched to the area set in the “Link area number” in the Parameter setting mode after the Close edge or Open edge has been detected. If the “Link area number” is not specified, the area number (which is the current number * + 1) will be selected.

* In case the “Link area number” is not specified and the current control area No. is 16, the area will not be changed.

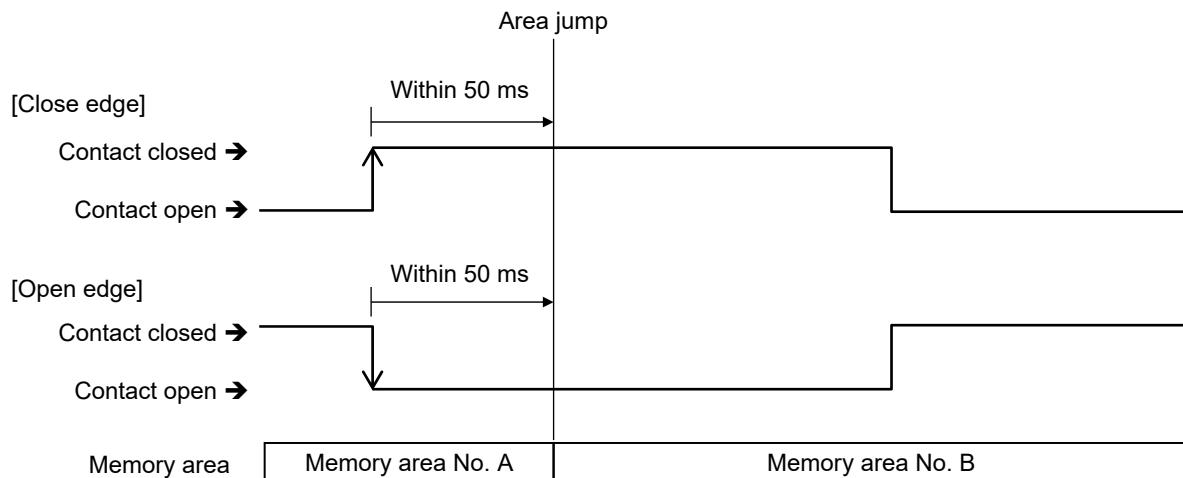
Example: If the current control area is “Memory area No. 1” and the “Link area number” (set in area No. 1) is “No. 5,” the memory area will be changed to No. 5 from No. 1 after the Area jump.



To do the Area jump

“Digital input 1 (DI1) Close edge” or “Digital input 1 (DI1) Open edge,” or both of these must be selected at Select Trigger type for Memory area transfer in the Parameter setting mode.

Timing chart of Area jump



NOTE
After the contact is transferred, it takes “Within 50 ms” until the action of this instrument is actually selected.



If “Event 1 to 4” are selected at the Select Trigger type for Memory area transfer in the Parameter setting mode of the memory area, the area jump will be conducted in case the preset event happens.

■ Relation between Digital Input (DI) and Setting via front keys (or through communication)

● RUN/STOP transfer

Setting via front keys or through communication	Setting via Digital Input (DI)	Instrument status	
RUN	RUN	RUN	Priority to STOP
	STOP	STOP	
STOP	RUN		
	STOP		

● Auto/Manual transfer

Setting via front keys or through communication	Setting via Digital Input (DI)	Instrument status	
Auto mode	Auto mode	Auto mode	Priority to manual mode
	Manual mode	Manual mode	
Manual mode	Auto mode		
	Manual mode		

● Remote/Local transfer

Setting via front keys or through communication	Setting via Digital Input (DI)	Instrument status	
Remoto mode	Remoto mode	Remoto mode	Priority to Local mode
	Local mode	Local mode	
Local mode	Remoto mode		
	Local mode		

PV select transfer

Setting via front keys or through communication	Setting via Digital Input (DI)	Instrument status	
Input 2	Input 2	Input 2	Priority to Input 1
	Input 1	Input 1	
Input 1	Input 2		
	Input 1		

2-loop control/Differential temperature control transfer

Setting via front keys or through communication	Setting via Digital Input (DI)	Instrument status	
Differential temperature control	Differential temperature control	Differential temperature control	Priority to 2-loop control
	2-loop control	2-loop control	
2-loop control	Differential temperature control		
	2-loop control		

- Set data unlock/lock transfer

Setting via front keys or through communication	Setting via Digital Input (DI)	Instrument status
Unlock state	Unlock state	Unlock state
	Lock state	Lock state
Lock state	Unlock state	
	Lock state	

Priority is given to lock status

- Direct/Reverse action transfer

Setting via front keys or through communication	Setting via Digital Input (DI)	Instrument status
Reverse action	Reverse action	Reverse action
	Direct action	Direct action
Direct action	Reverse action	Reverse action
	Direct action	Direct action



Functions like “Interlock release,” “Peak hold/Bottom hold reset,” “Autotuning on/off,” “Memory area transfer (with SET signal),” and “Area jump” basically conform to the operation via front keys, through communication, or via digital inputs.

■ Parameter setting

- DI1 function selection

[Engineering mode: Function block No. 23 (Fn23)]

Parameter symbol	Data range	Factory set value
di SL 1	0: No function 1: RUN/STOP transfer 2: Auto/Manual transfer (Common to Input 1 and 2) 3: Input 1_Auto/Manual transfer 4: Input 2_Auto/Manual transfer ¹ 5: Remote/Local transfer ² (PV select transfer, 2-loop control/Differential temperature control) 6: Interlock release 7: Hold reset (Common to Input 1 and 2) 8: Input 1_Hold reset 9: Input 2_Hold reset ¹ 10: Autotuning (AT) (Common to Input 1 and 2) 11: Input 1_Autotuning (AT) 12: Input 2_Autotuning (AT) ¹ 13: Set data unlock/lock transfer 14: Direct/Reverse action transfer 15: Memory area transfer (2 points, without area set signal) 16: Memory area transfer (8 points, without area set signal) ³ 17: Memory area transfer (8 points, with area set signal) ⁴ 18: Memory area transfer (16 points, without area set signal) ⁴ 19: Memory area transfer (16 points, with area set signal) ⁵ 20: Area jump	Based on Model code

¹ Effective if two inputs are available

² The function selected at Select function for input 2 is switchable.

³ Effective if three or more Digital inputs (DI) are available

⁴ Effective if four or more Digital inputs (DI) are available

⁵ Effective if six or more Digital inputs (DI) are available



To display “DI1 function selection,” Digital input must be specified at the time of order.

● DI2 function selection

[Engineering mode: Function block No. 23 (Fn23)]

Parameter symbol	Data range	Factory set value
<i>di SL 2</i>	0: No function 1: RUN/STOP transfer 2: Auto/Manual transfer (Common to Input 1 and 2) 3: Input 1_Auto/Manual transfer 4: Input 2_Auto/Manual transfer ¹ 5: Remote/Local transfer ² (PV select transfer, 2-loop control/Differential temperature control) 6: Interlock release 7: Hold reset (Common to Input 1 and 2) 8: Input 1_Hold reset 9: Input 2_Hold reset ¹ 10: Autotuning (AT) (Common to Input 1 and 2) 11: Input 1_Autotuning (AT) 12: Input 2_Autotuning (AT) ¹ 13: Set data unlock/lock transfer 14: Direct/Reverse action transfer	Based on Model code

¹ Effective if two inputs are available

² The function selected at Select function for input 2 is switchable



To display “DI2 function selection,” Digital input must be specified at the time of order.

● DI3 function selection

[Engineering mode: Function block No. 23 (Fn23)]

Parameter symbol	Data range	Factory set value
<i>di SL 3</i>	Same as DI2 function selection	Based on Model code



To display “DI3 function selection,” Digital input must be specified at the time of order.

● DI4 function selection

[Engineering mode: Function block No. 23 (Fn23)]

Parameter symbol	Data range	Factory set value
<i>di SL 4</i>	Same as DI2 function selection	Based on Model code



To display “DI4 function selection,” Digital input must be specified at the time of order.

● DI5 function selection

[Engineering mode: Function block No. 23 (Fn23)]

Parameter symbol	Data range	Factory set value
di5l5	Same as DI2 function selection	Based on Model code

 To display “DI5 Function selection,” Digital inputs (6 points) must be specified at the time of order.

● DI6 function selection

[Engineering mode: Function block No. 23 (Fn23)]

Parameter symbol	Data range	Factory set value
di5l6	Same as DI2 function selection	Based on Model code

 To display “DI6 Function selection,” Digital inputs (6 points) must be specified at the time of order.

● DI logic invert

[Engineering mode: Function block No. 23 (Fn23)]

Parameter symbol	Data range	Factory set value
di1nv	0 to 31 0: No logic invert +1: RUN/STOP transfer +2: Auto/Manual transfer +4: Remote/Local transfer * (PV select transfer, 2-loop control/Differential temperature control) +8: Set data unlock/lock transfer +16: Direct/Reverse action transfer To select two or more functions, sum each value.	0

* The function selected at Select function for input 2 is switchable.

 To display “DI logic invert,” Digital input must be specified at the time of order.

● Area switching time (without area set signal)

[Engineering mode: Function block No. 23 (Fn23)]

Parameter symbol	Data range	Factory set value
di1tm	1 to 5 seconds	2

 To display “Area switching time (without area set signal),” Digital input must be specified at the time of order.

 “Area switching time (without area set signal)” becomes valid when any one of 15, 16, and 18 is set at “DI1 function selection”

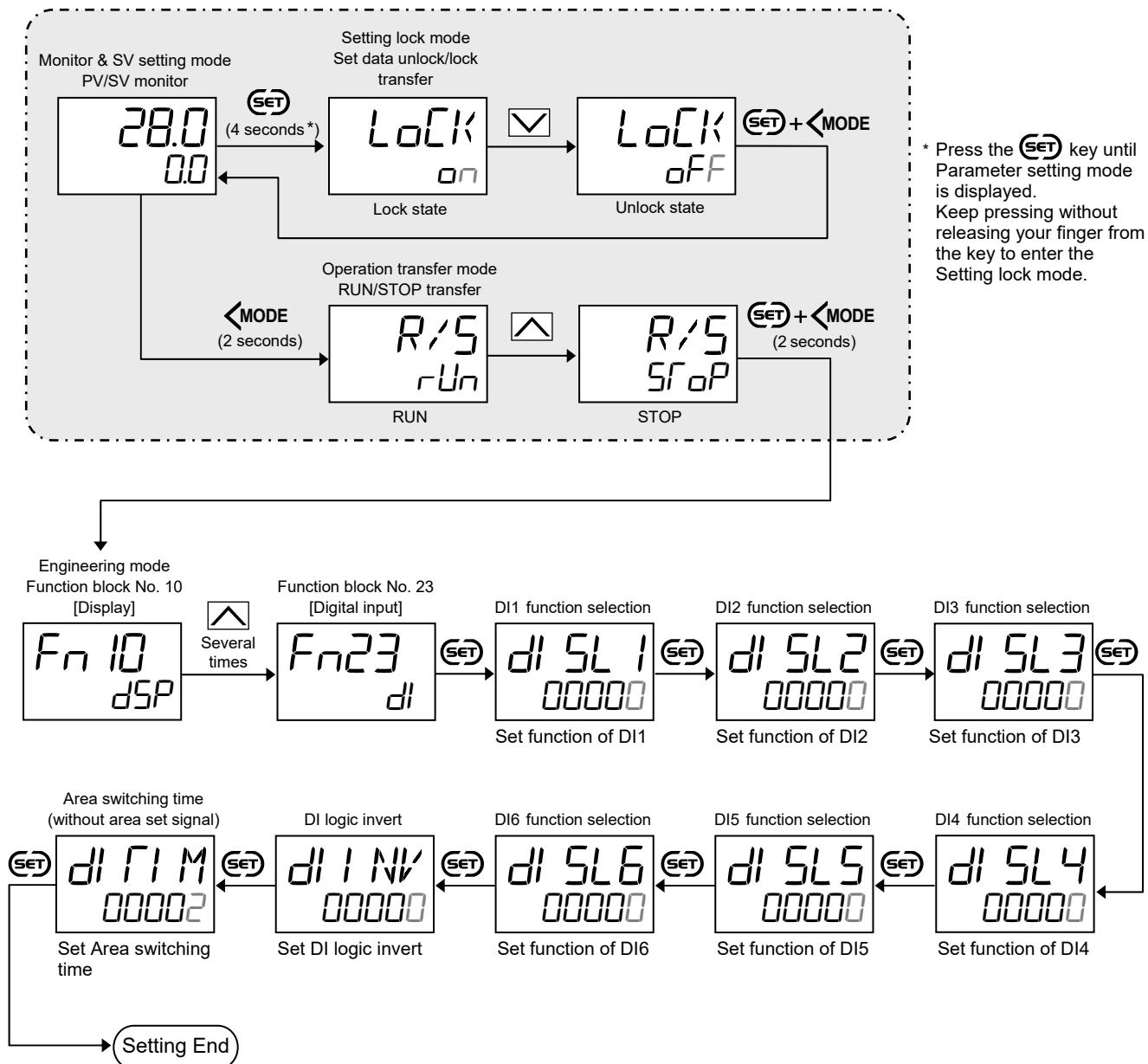
● **Control area Local/External transfer**
[Operation Transfer Mode]

Parameter symbol	Data range	Factory set value
L/E	LoC: Local mode EYF: External mode	LoC

-  To display “Control area Local/External transfer,” any one of 15, 16 and 18 must be set at “DI1 function selection.”
-  If “External mode” is set at “Control area Local/External transfer,” control area cannot be switched via key operations.

■ Setting procedure

To enter the Engineering mode



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

5.3 Correcting Input (PV Bias and PV Ratio)

PV bias and PV ratio can be used for Input correction. The PV bias is used to compensate the individual variations of the sensors or correct the difference between the Measured value (PV) of other instruments.

■ Description of function

● PV bias

PV bias adds bias to the Measured value (PV).

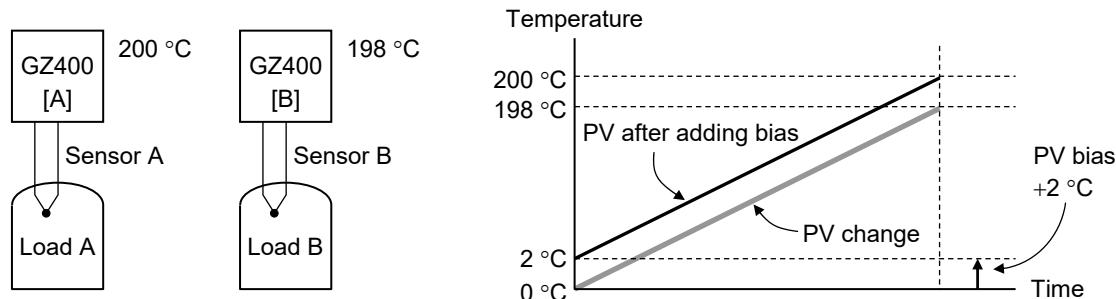
Setting example of PV bias:

When measuring the same type of load by using different sensors, the Measured value (PV) will be displayed differently based on the features of sensors:

GZ400 [A]: 200 °C GZ400 [B]: 198 °C

To correct the Measure value (PV) of GZ400 [B], add bias of +2 °C by PV bias:

$$\text{Displayed value} = \text{Measured value (PV)} + \text{PV bias} = 198 \text{ }^{\circ}\text{C} + 2 \text{ }^{\circ}\text{C} = 200 \text{ }^{\circ}\text{C}$$



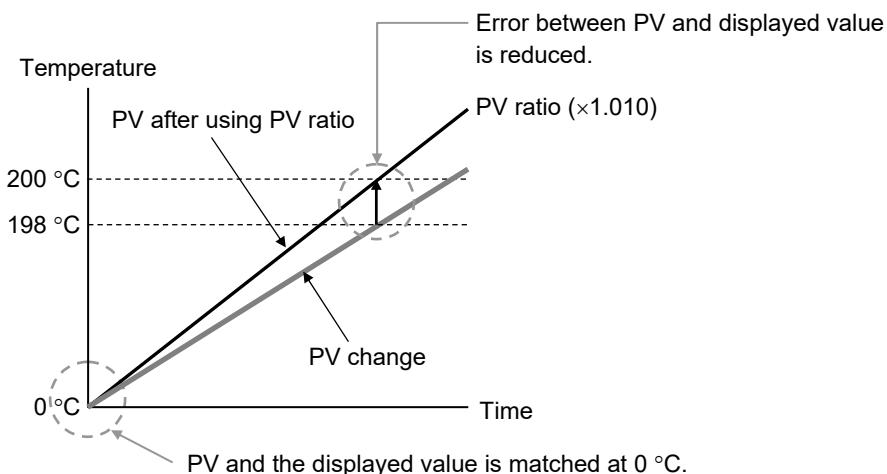
● PV ratio

PV ratio is a multiplier to be applied to the Measured value (PV).

Setting example of PV ratio:

PV ratio can be used to display 200 °C by adding 2 °C when the actual Measured value (PV) is 198 °C but the displayed value remains 0 °C when the actual PV is 0 °C. (The displayed value changes from 0 °C to 2 °C by PV bias setting.)

$$\text{Displayed value} = \text{Measured value (PV)} \times \text{PV ratio} = 198 \text{ }^{\circ}\text{C} \times 1.010 = 199.98 \text{ }^{\circ}\text{C}$$



● When setting PV bias and PV ratio at the same time

[Example]

When PV bias = 15 °C and

Measured value (PV) = 50 °C

If PV ratio = 0.700

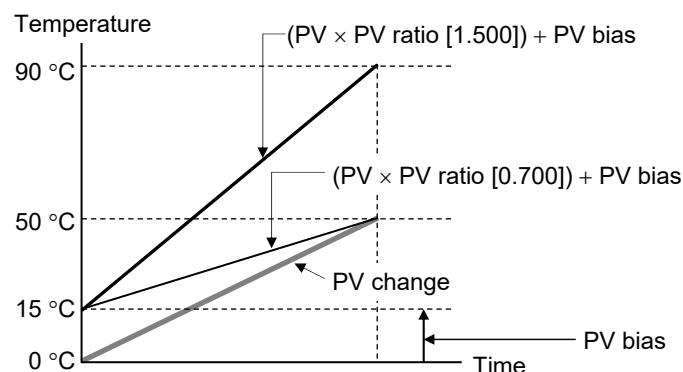
$$\text{Displayed value} = 50 \times 0.700 + 15$$

$$= 50^{\circ}\text{C}$$

PV ratio = 1.500

$$\text{Displayed value} = 50 \times 1.500 + 15$$

$$= 90^{\circ}\text{C}$$



■ Parameter setting

● Input 1_PV bias

[Setup Setting Mode: Setting group No. 21 (Snd1)]

Parameter symbol	Data range	Factory set value
1. Pb	–(Input 1_Input span) to +(Input 1_Input span) When Control with PV select: –(PV select input span) to +(PV select input span) Varies with the setting of the Decimal point position.	0

● Input 2_PV bias (RS bias)

[Setup Setting Mode: Setting group No. 22 (Snd2)]

Parameter symbol	Data range	Factory set value
2. Pb	–(Input 2_Input span) to +(Input 2_Input span) Varies with the setting of the Decimal point position.	0

- 📖 To display Input 2_PV bias, “Measured input 2” or “Remote setting input” must be specified at the time of order.
- 📖 If Remote setting input is supplied, it is displayed as RS bias.
- 📖 Input 2_Input type is not displayed if “No function” is selected at Select function for input 2 in Function block No. 58 in the Engineering mode.

● Input 1_PV ratio

[Setup Setting Mode: Setting group No. 21 (Snd1)]

Parameter symbol	Data range	Factory set value
1. PR	0.500 to 1.500	1.000

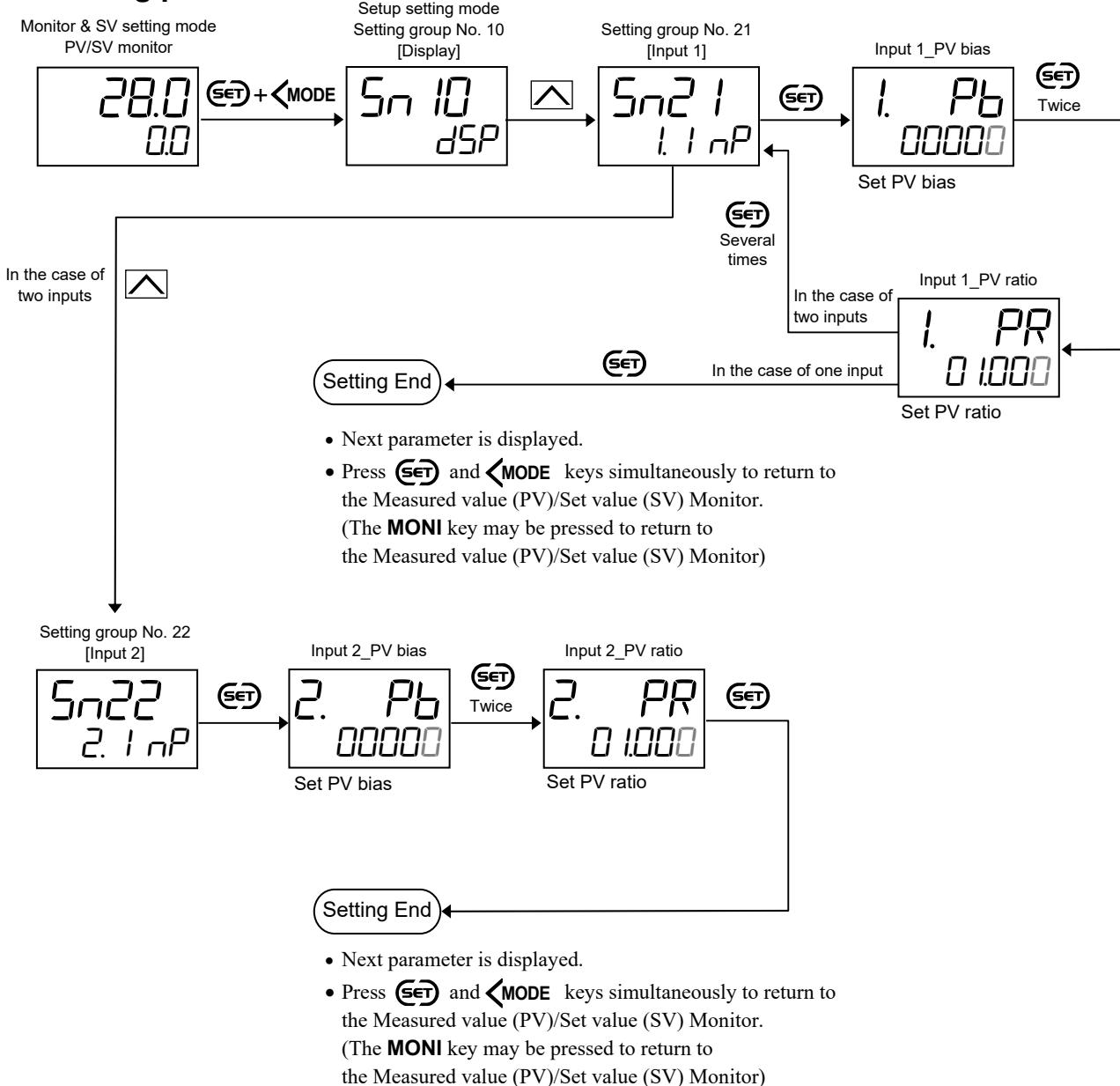
● Input 2_PV ratio

[Setup Setting Mode: Setting group No. 22 (Sn22)]

Parameter symbol	Data range	Factory set value
2. PR	Input 2_PV ratio 0.500 to 1.500 RS ratio 0.001 to 9.999	1.000

- To display Input 2_PV ratio, “Measured input 2” or “Remote setting input” must be specified at the time of order.
- If Remote setting input is supplied, it is displayed as PV ratio.
- Input 2_Input type is not displayed if “No function” is selected at Select function for input 2 in Function block No. 58 in the Engineering mode.

■ Setting procedure

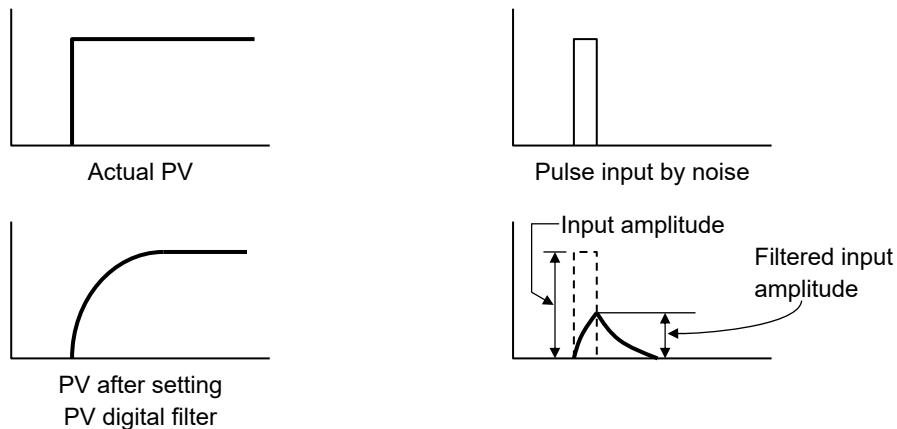


5.4 Preventing the Input Flicker

To prevent the input flicker, PV digital filter with the first-order lag calculation is provided.

■ Description of function

PV digital filter is software designed to reduce variance of PV caused by noise. Effect of Input noise can be reduced by setting time constant of PV digital filter based on the controlled object requirement and its level of noise. Setting a value too small leads to a poor result of PV digital filter; just as an input response will be poor when setting a value too large.



■ Parameter setting

● Input 1_PV digital filter

[Setup Setting Mode: Setting group No. 21 (Snd1)]

Parameter symbol	Data range	Factory set value
1. dF	0.00 to 10.00 seconds 0.00: Filter OFF	0.00

● Input 2_PV digital filter (RS digital filter)

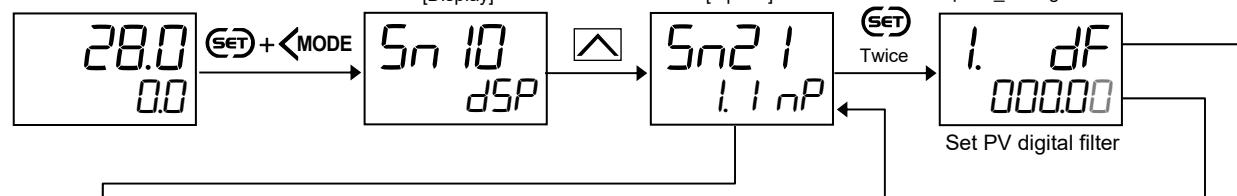
[Setup Setting Mode: Setting group No. 22 (Snd2)]

Parameter symbol	Data range	Factory set value
2. dF	0.00 to 10.00 seconds 0.00: Filter OFF	0.00

- (book icon) To display Input 2_PV digital filter, “Measured input 2” or “Remote setting input” must be specified at the time of order.
- (book icon) If Remote setting input is supplied, it is displayed as RS digital filter.
- (book icon) Input 2_Input type is not displayed if “No function” is selected at Select function for input 2 in Function block No. 58 in the Engineering mode.

■ Setting procedure

Monitor & SV setting mode
PV/SV monitor



In the case of
two inputs

Setting End

- Next parameter is displayed.
- Press **SET** and **MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

Setting group No. 22
[Input 2]



Setting End

- Next parameter is displayed.
- Press **SET** and **MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

In the case of
two inputs

In the case of
one input

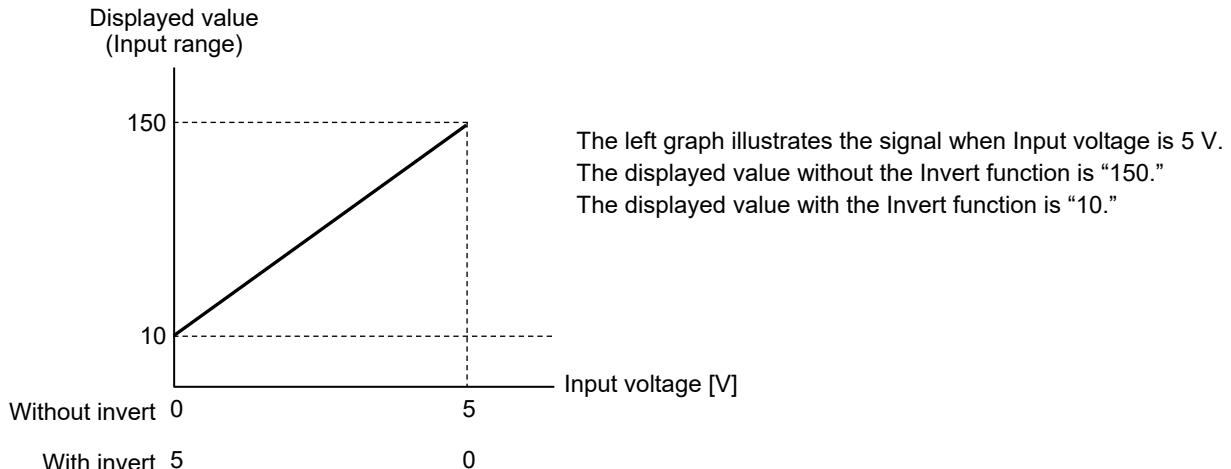
5.5 Inverting the Input

If the instrument is a current/voltage input type, the proportional relation between the input current (voltage) and the displayed value can be inverted.

■ Description of function

Reverse setting (Input range high < Input range low) of Input range high and low is not available on the instrument. However, with the Input invert function, the display relation to the input can be inverted.

Example: with/without invert function for voltage input 0 to 5 V



■ Parameter setting

● Input 1_Inverting input

[Engineering mode: Function block No. 21 (F_{n21})]

Parameter symbol	Data range	Factory set value
$I_1\text{INV}$	0: Unused 1: Used	0

- To show “Input 1_Inverting input,” current or voltage must be selected at Input 1_Input type in Function block No. 21 in the Engineering mode.

● Input 2_Inverting input

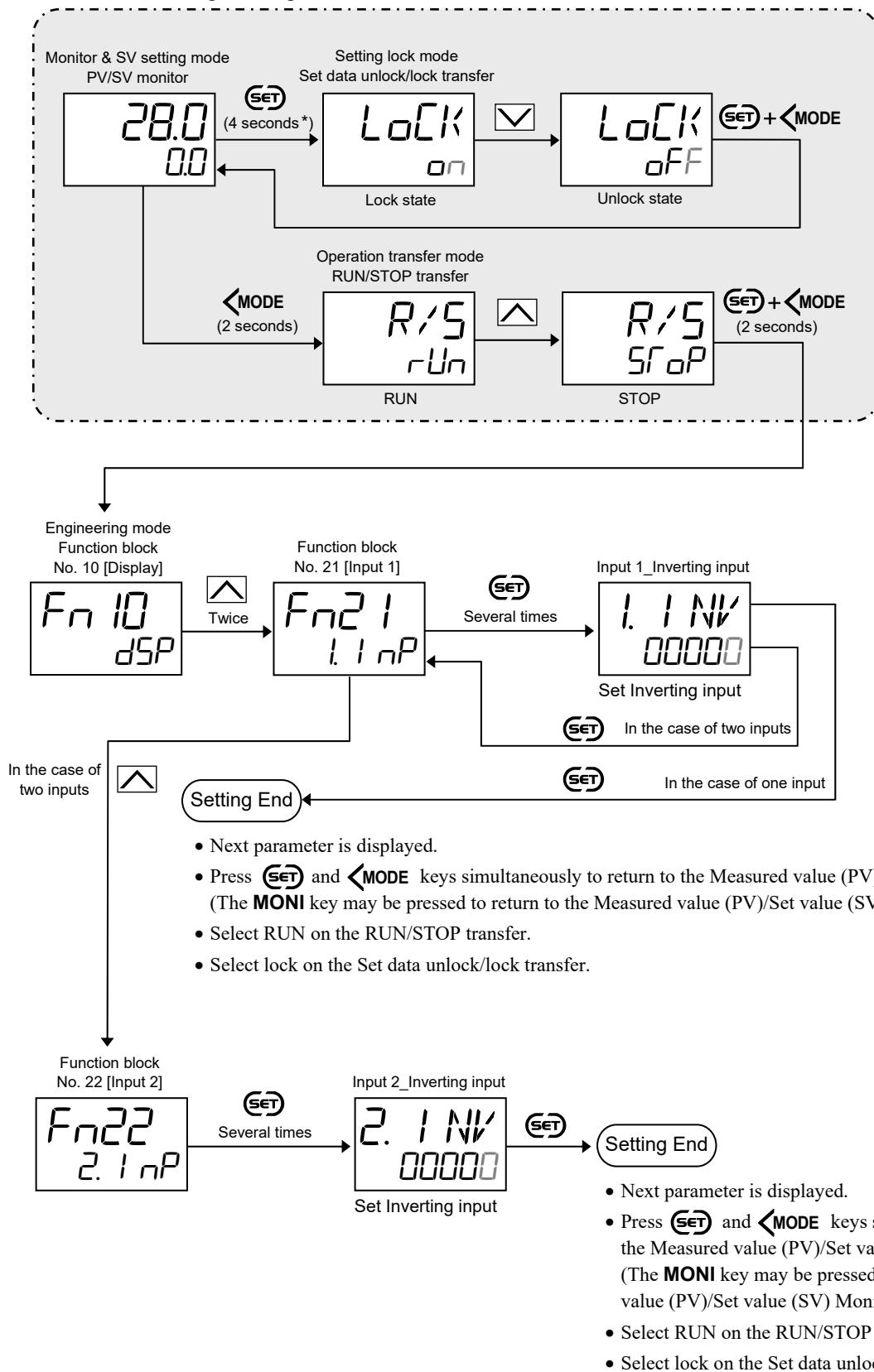
[Engineering mode: Function block No. 22 (F_{n22})]

Parameter symbol	Data range	Factory set value
$E_1\text{INV}$	0: Unused 1: Used	0

- To show “Input 2_Inverting input,” Measured input 2 must be specified at the time of order and voltage or current must be specified at “Input 2_Input type” in Function block No. 22 in the Engineering mode.
- Not displayed if “Select function for input 2” is set in Function block No. 58 in the Engineering mode to “No function” or “Remote setting input.”

■ Setting procedure

To enter the Engineering mode



5.6 Extracting Square Root of Input

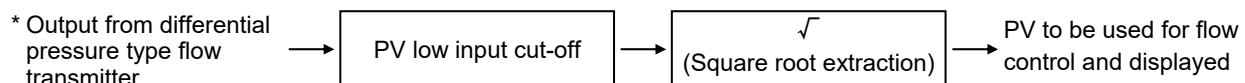
Square root extraction can control flow by sending the output signal directly from a differential pressure type flow transmitter to instrument. By setting PV low input cut-off, Square root extraction will not be performed for the Measured value below the set value of PV low input cut-off.

■ Description of function

● Square root extraction

When using a differential pressure type flow transmitter, the Measured value (PV) is computed by Square root extraction.

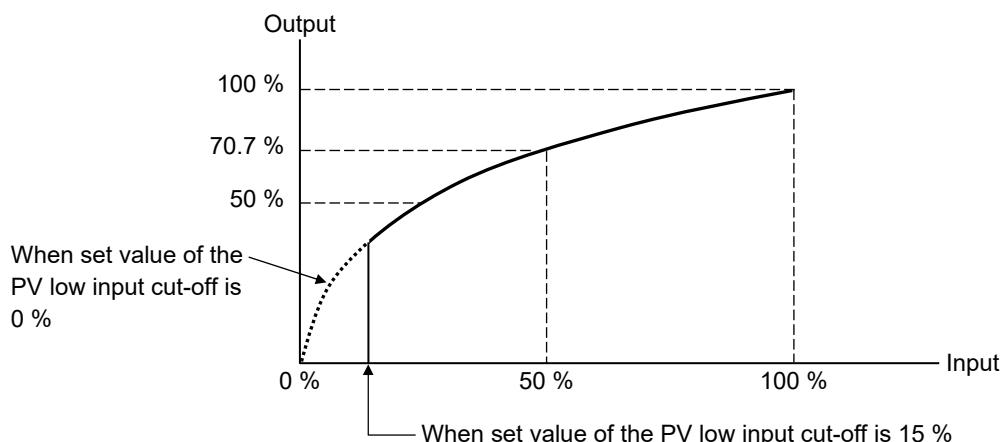
$$\text{Equation: Measured value (PV)} = \sqrt{(\text{Input value}^*)} \times \text{PV ratio} + \text{PV bias}$$



● PV low input cut-off

The result of square root extraction become “0” when the Measured value (PV) drops below the set value of the PV low input cut-off. Output is not produced when the result of square root extraction is zero (0).

When input signal square root extraction is used for in flow control, etc., the Square root extraction result varies widely at the Low measured value range. The Measured value less than the PV low input cut-off is ignored to compute control output in order to prevent control disturbance caused by input variation at Low measured value range.



■ Parameter setting

● Input 1_Square root extraction

[Engineering mode: Function block No. 21 (Fn21)]

Parameter symbol	Data range	Factory set value
I. SQR	0: Unused 1: Used	0



To show “Input 1_Square root extraction,” current or voltage must be selected at Input 1_Input type in Function block No. 21 in the Engineering mode.

● **Input 2_Square root extraction**
[Engineering mode: Function block No. 22 (Fn22)]

Parameter symbol	Data range	Factory set value
2. SQR	0: Unused 1: Used	0

-  To show “Input 2_Square root extraction,” Measured input 2 must be specified at the time of order and voltage or current must be specified at “Input 2_Input type” in Function block No. 22 in the Engineering mode.
-  Not displayed if “Select function for input 2” is set in Function block No. 58 in the Engineering mode to “No function” or “Remote setting input.”

● **Input 1_PV low input cut-off**
[Setup Setting Mode: Setting group No. 21 (Snd1)]

Parameter symbol	Data range	Factory set value
1. PLC	0.00 to 25.00 % of Input 1_Input span (When Control with PV select: 0.00 to 25.00 % of PV select input span)	0.00

-  To display “Input 1_PV low input cut-off,” input type is Voltage/Current input, AND “Input 1_Square root extraction” in Function block No. 21 in the Engineering mode must be set to “Used.”

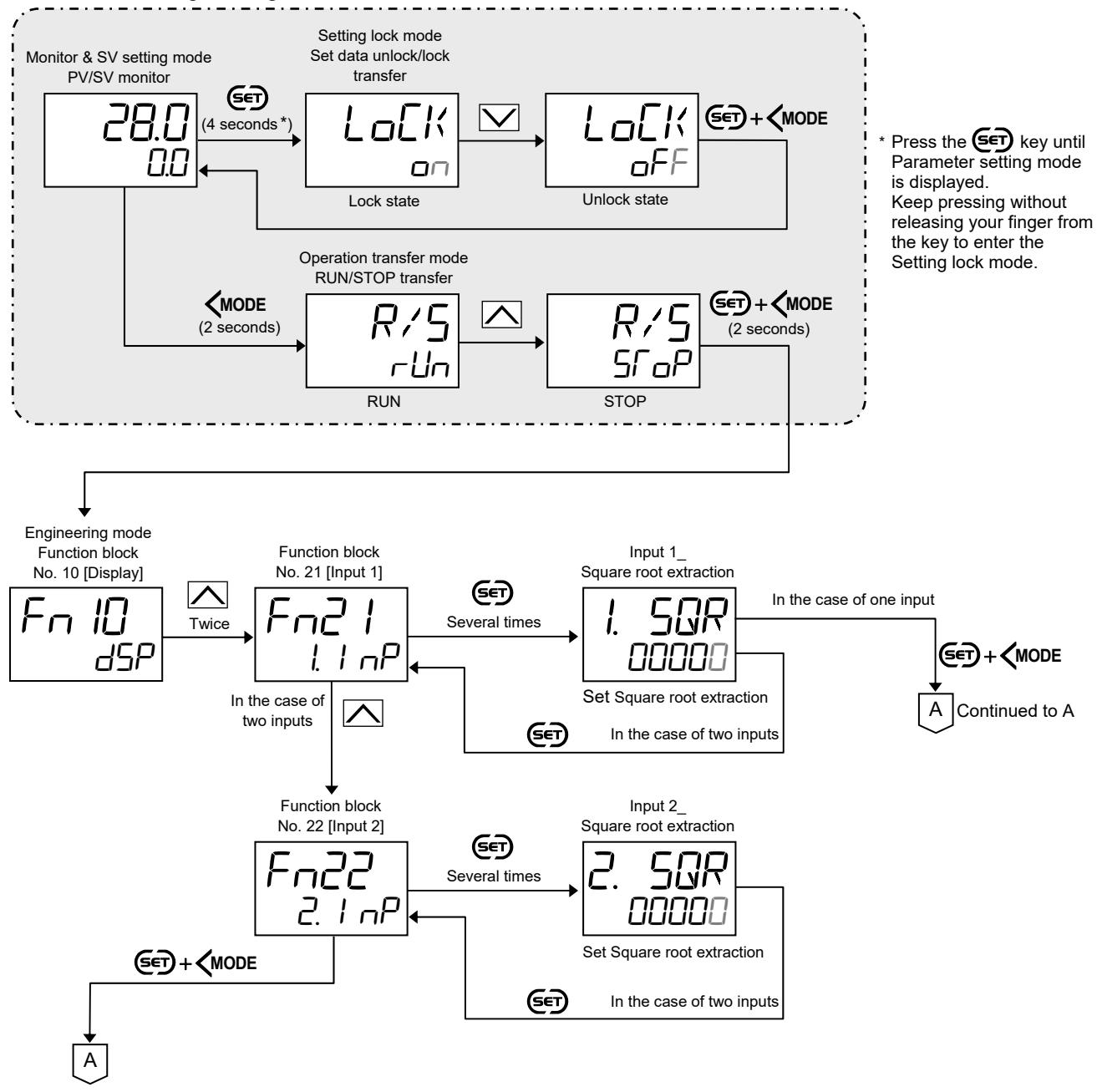
● **Input 2_PV low input cut-off**
[Setup Setting Mode: Setting group No. 22 (Snd2)]

Parameter symbol	Data range	Factory set value
2. PLC	0.00 to 25.00 % of Input 2_Input span	0.00

-  To display “Input 2_PV low input cut-off,” specify “Measured input 2” at the time of order, AND input type is Voltage/Current input, AND “Input 2_Square root extraction” in Function block No. 22 in the Engineering mode must be set to “Used.”
-  Not displayed if “Select function for input 2” is set in Function block No. 58 in the Engineering mode to “No function” or “Remote setting input.”

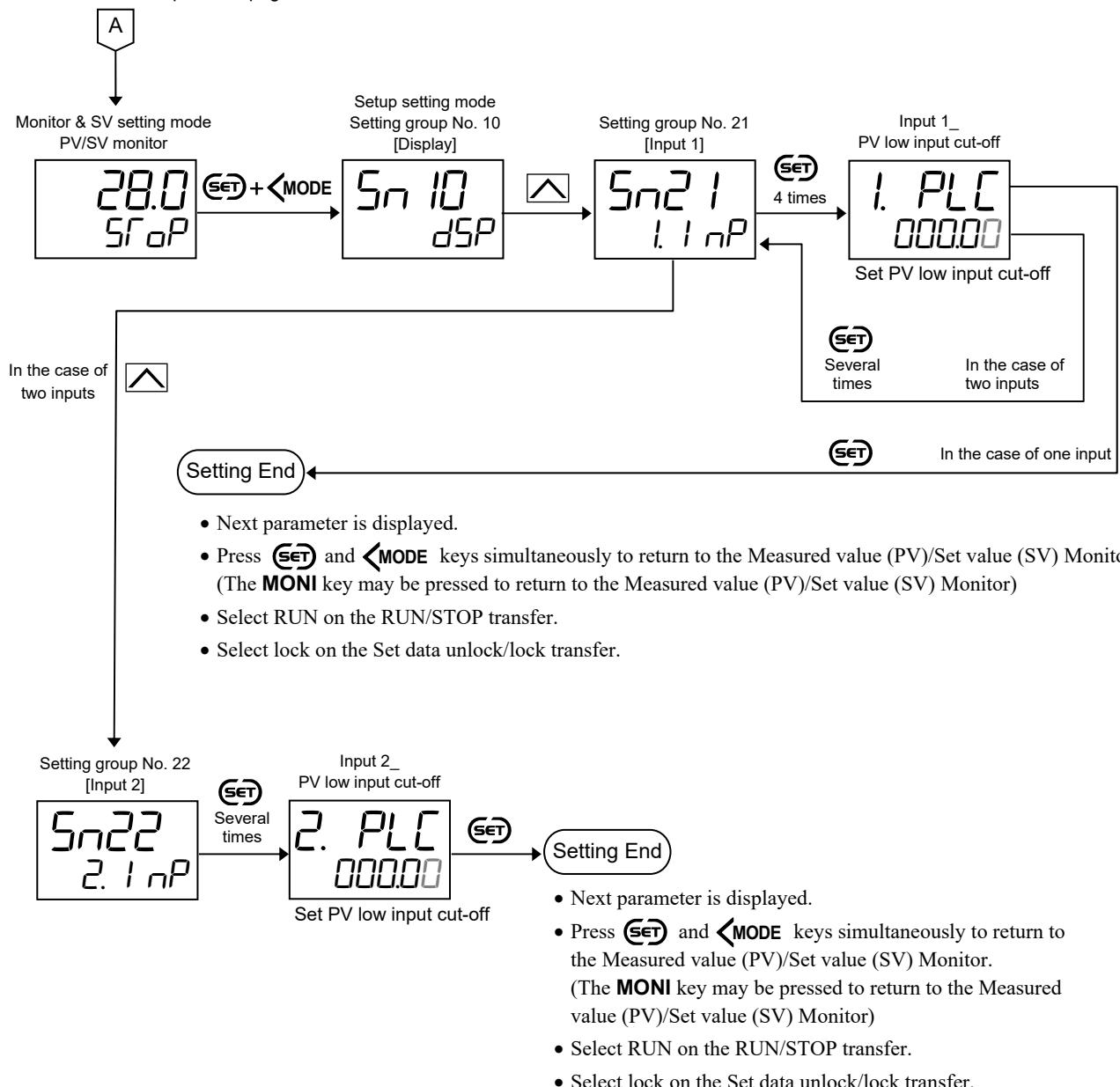
■ Setting procedure

To enter the Engineering mode



Continued on the next page.

Continued from the previous page.



5.7 Changing Error Handling at Input Error

The measures for input errors can be selected from Input burnout direction, Input error determination point, Manipulated output value at Input error, PV flashing display at input error, and Input error status output.

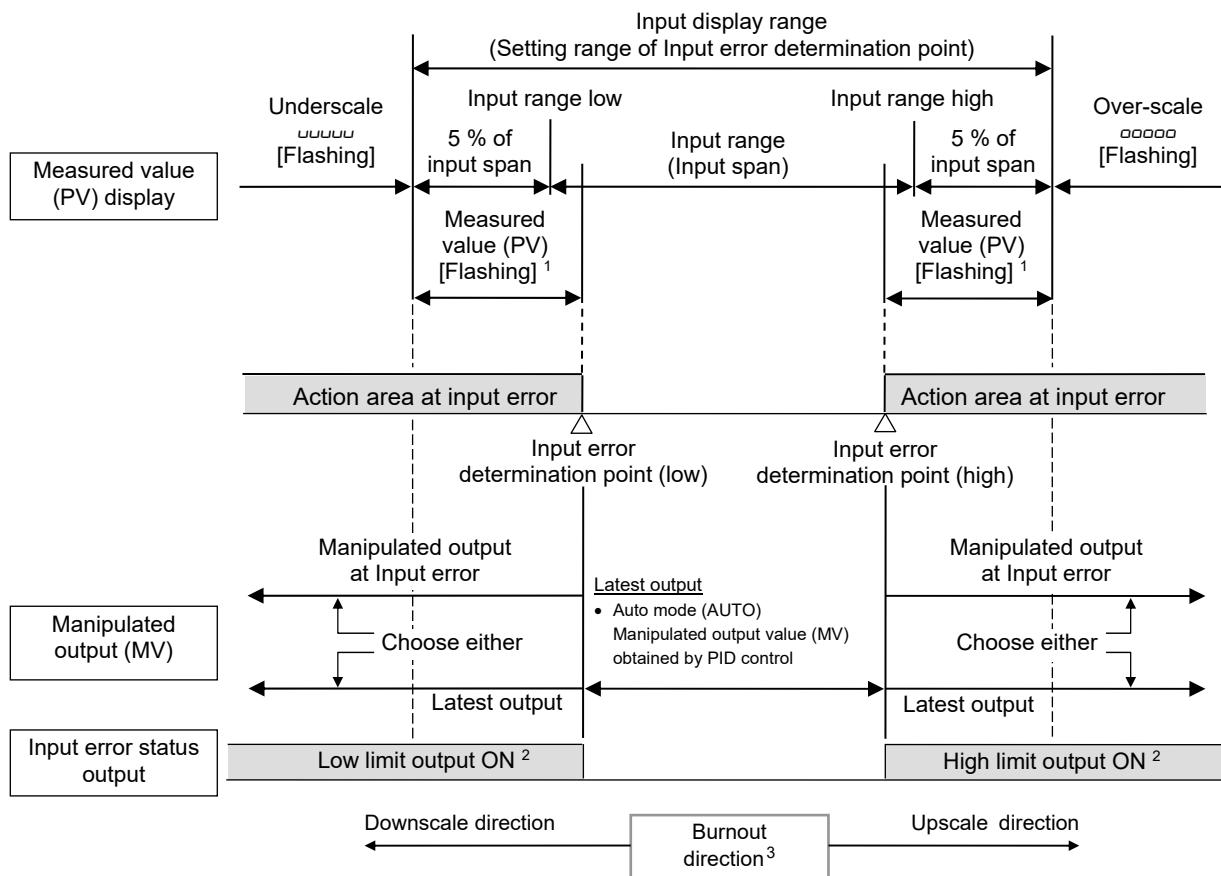
■ Description of function

If the measured value (PV) exceeds the Input error determination point (high or low), the action predefined at “Action (high and low) input error” will be taken. Input error status signal can be output from OUT1 to OUT3 and DO1 to DO4.



In manual mode and control stop mode, action and output will not be taken for input errors.

- Input error determination point is set within the input range



¹ Flashing can be suppressed by setting "PV flashing display at input error" (Function block No. 10 in the Engineering mode).

² For Input error status output, see ● Details of OUT1 to 3 as well as DO1 to 4 logic calculation selection (P. 6-4).

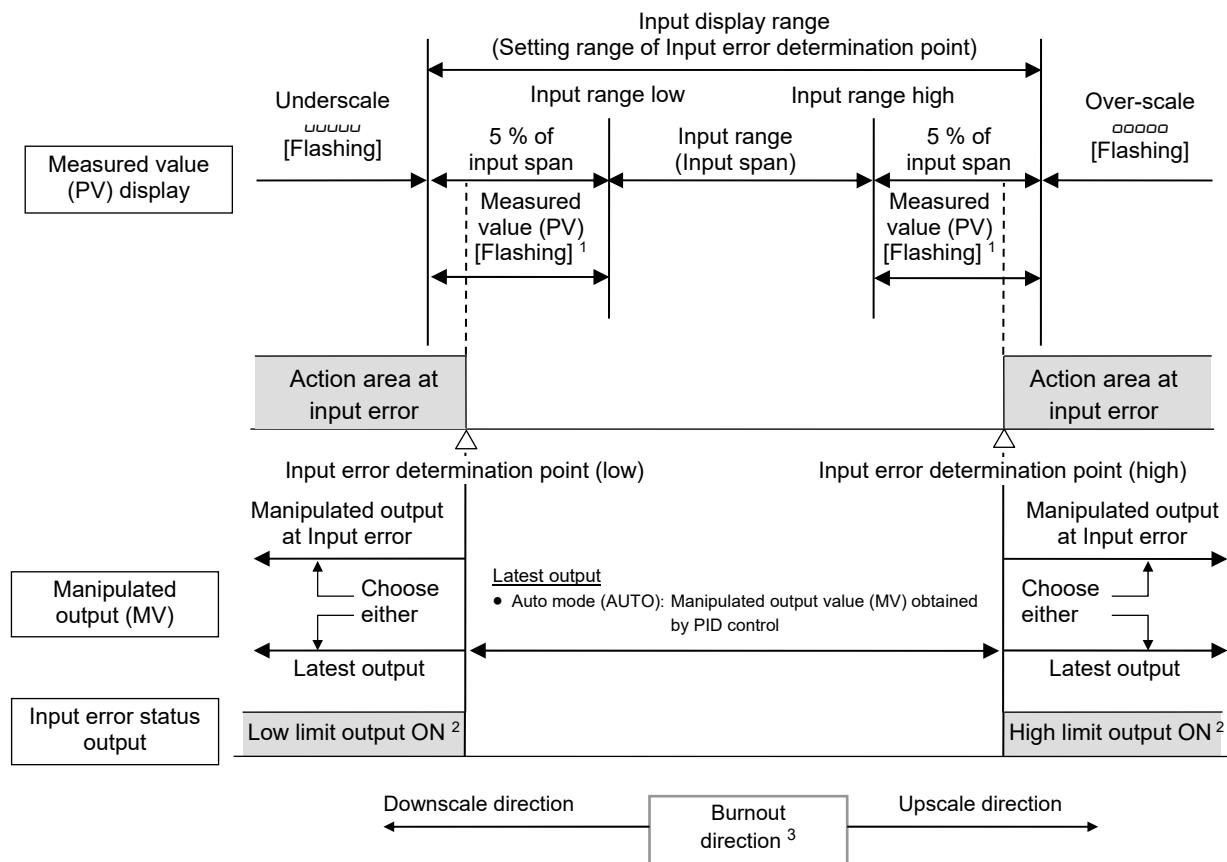
³ Setting Burnout direction is valid for thermocouple input and low voltage input (0 to 10 mV DC, 0 to 100 mV DC). Actions of other input types are fixed as follows.

Actions of other input types are fixed as follows:
RTD input: Upscale
High voltage/Current inputs:Downscale (Indicates value near

 See the **Input range table** (P. 5-11) for the input range of each input.

 For details of Input error status output, see [6.1 Changing Output Assignment \(P. 6-2\)](#).

- Input error determination point is set outside the input range



¹ Flashing can be suppressed by setting "PV flashing display at input error" (Function block No. 10 in the Engineering mode).

² For Input error status output, see ● Details of OUT1 to 3 as well as DO1 to 4 logic calculation selection (P. 6-4).

³ Setting Burnout direction is valid for thermocouple input and low voltage input (0 to 10 mV DC, 0 to 100 mV DC). Actions of other input types are fixed as follows.

RTD input: Upscale

High voltage/Current inputs:Downscale (Indicates value near 0)



See the **Input range table (P. 5-11)** for the input range of each input.



For details of Input error status output, see **6.1 Changing Output Assignment (P. 6-2)**.



In the case of control with dual inputs, the action at input error is conducted independently on each of Input 1 and Input 2. However, exceptional cases are shown below in which Action at input error may be slightly different.

● 2-loop control/Differential temperature control

	Input 1 is abnormal	Input 2 is abnormal
Input error determination	Input 1 is determined at Input 1_Input error determination point.	Input 2 is determined at Input 2_Input error determination point.
Action at input error	Action selected for Input 1_Action input error.	Input 1 side: "Input 1_Manipulated output value at input error" is output [fixed] Input 2 side: Action selected for Input 2_Action input error.
Manipulated output value at input error	Input 1_Manipulated output value at input error	Input 1_Manipulated output value at input error Input 2_Manipulated output value at input error

● Input circuit error alarm

	Input 1 is abnormal	Input 2 is abnormal
Input error determination	Input 1 is determined at Input 1_Input error determination point.	Input 2 is determined at Input 2_Input error determination point.
Action at input error	Action selected for Input 1_Action input error.	
Manipulated output value at input error	Input 1_Manipulated output value at input error	Even if Input 2 is in input error, Action at input error will not be taken. *

* If (Input 2 – Input 1) exceeds the Input circuit error alarm set value, Action at input error is the action defined in Input 1_Action input error.

● Control with PV select

	Input 1 is abnormal	Input 2 is abnormal
Input error determination	Input 1 is determined at Input 1_Input error determination point.	Input 2 is determined at Input 2_Input error determination point.
Action at input error	When the Input 1 is used: Action selected for Input 1_Action input error. When the Input 2 is used: No Action at input error	When the Input 1 is used: No Action at input error When the Input 2 is used: Action selected for Input 1_Action input error.
Manipulated output value at input error	Input 1_Manipulated output value at input error	Input 1_Manipulated output value at input error

■ Parameter setting

● PV flashing display at input error

[Engineering mode: Function block No. 10 (Fn 10)]

Parameter symbol	Data range	Factory set value
<i>d5oP</i>	0: Flashing display 1: Non-flashing display	0

● Input 1_Input error determination point (high)

[Engineering mode: Function block No. 21 (Fn 21)]

Parameter symbol	Data range	Factory set value
<i>I. Pov</i>	Input 1_Input error determination point (low) to Input 1_Input range high + (Input 1_5 % of input span) Varies with the setting of the Decimal point position.	Input 1_Input range high + (Input 1_5 % of input span)

● **Input 1_Input error determination point (low)**
[Engineering mode: Function block No. 21 (Fn21)]

Parameter symbol	Data range	Factory set value
<i>I. PUN</i>	Input 1_Input range low – (Input 1_5 % of input span) * to Input 1_Input error determination point (high) Varies with the setting of the Decimal point position. * When Input type of Input 1 is RTD, low limit value is about 2 Ohms. (Pt100: -245.5 °C [-409.8 °F], JPt100: -237.6 °C [-395.7 °F])	Input 1_Input range low – (Input 1_5 % of input span)

● **Input 2_Input error determination point (high)**
[Engineering mode: Function block No. 22 (Fn22)]

Parameter symbol	Data range	Factory set value
<i>2. Pov</i>	Input 2_Input error determination point (low) to Input 2_Input range high + (Input 2_5 % of input span) Varies with the setting of the Decimal point position.	Input 2_Input range high + (Input 2_5 % of input span)

-  To show the “Input 2_Input error determination point (high),” “Measured input 2” must be specified at the time of order.
-  Not displayed when “No function” or “Remote setting input” is selected in “Select function for input 2” (Function block No. 58 in Engineering mode).

● **Input 2_Input error determination point (low)**
[Engineering mode: Function block No. 22 (Fn22)]

Parameter symbol	Data range	Factory set value
<i>2. PUN</i>	Input 2_Input range low – (Input 2_5 % of input span) * to Input 2_Input error determination point (high) Varies with the setting of the Decimal point position. * When Input type of Input 2 is RTD, low limit value is about 2 Ohms. (Pt100: -245.5 °C [-409.8 °F], JPt100: -237.6 °C [-395.7 °F])	Input 2_Input range low – (Input 2_5 % of input span)

-  To show the “Input 2_Input error determination point (low),” “Measured input 2” must be specified at the time of order.
-  Not displayed when “No function” or “Remote setting input” is selected in “Select function for input 2” (Function block No. 58 in Engineering mode).

● **Input 1_Burnout direction**
[Engineering mode: Function block No. 21 (Fn21)]

Parameter symbol	Data range	Factory set value
<i>I. b05</i>	0: Upscale 1: Downscale	0

-  To show “Input 1_Burnout direction,” thermocouple or voltage (low) [0 to 100 mV DC, 0 to 10 mV DC] must be selected at Input 1_Input type in Function block No. 21 in the Engineering mode.

● Input 2_Burnout direction

[Engineering mode: Function block No. 22 (Fn22)]

Parameter symbol	Data range	Factory set value
2. b05	0: Upscale 1: Downscale	0

 To show “Input 2_Burnout direction,” “Measured input 2” must be specified at the time of order and thermocouple or low voltage (0 to 100 mV DC, 0 to 10 mV DC) must be selected at “Input 2_Input type” in Function block No. 22 in the Engineering mode.

 Input 2_Input type is not displayed if “No function” is selected at Select function for input 2 in Function block No. 58 in the Engineering mode.

● Input 1_Action (high) input error

[Engineering mode: Function block No. 51 (Fn51)]

Parameter symbol	Data range	Factory set value
IRoVE	0: Control continues (with the latest output) 1: Manipulated output value at input error (Manual mode) The operation mode is switched to the Manual mode and the Input 1_Manipulated output value at input error is output. 2: Manipulated output value at input error (Auto mode) The operation mode remains in the Auto mode and the Input 1_Manipulated output value at input error of is output. When the error is recovered, the operation mode is switched to the PID control.	2

 When the value is fixed to “Auto mode” at “Fix parameter setting: Auto/Manual transfer” in the Setting lock mode, “1” cannot be set.

● Input 1_Action (low) input error

[Engineering mode: Function block No. 51 (Fn51)]

Parameter symbol	Data range	Factory set value
IRUNE	0: Control continues (with the latest output) 1: Manipulated output value at input error (Manual mode) The operation mode is switched to the Manual mode and the Input 1_Manipulated output value at input error is output. 2: Manipulated output value at input error (Auto mode) The operation mode remains in the Auto mode and the Input 1_Manipulated output value at input error of is output. When the error is recovered, the operation mode is switched to the PID control.	2

 When the value is fixed to “Auto mode” at “Fix parameter setting: Auto/Manual transfer” in the Setting lock mode, “1” cannot be set.

● Input 2_Action (high) input error

[Engineering mode: Function block No. 52 (Fn52)]

Parameter symbol	Data range	Factory set value
2.RoVE	0: Control continues (with the latest output) 1: Manipulated output value at input error (Manual mode) The operation mode is switched to the Manual mode and the Input 1_Manipulated output value at input error is output. 2: Manipulated output value at input error (Auto mode) The operation mode remains in the Auto mode and the Input 1_Manipulated output value at input error of is output. When the error is recovered, the operation mode is switched to the PID control.	2

-  To show “Input 2_Action (high) input error,” “Measured input 2” must be specified at the time of order, and “Select function for input 2” (Function block No. 58 in the Engineering mode) must be set to “2-loop control/Differential temperature input” must be set up.
-  When the value is fixed to “Auto mode” at “Fix parameter setting: Auto/Manual transfer” in the Setting lock mode, “1” cannot be set.

● Input 2_Action (low) input error

[Engineering mode: Function block No. 52 (Fn52)]

Parameter symbol	Data range	Factory set value
2.RUNE	0: Control continues (with the latest output) 1: Manipulated output value at input error (Manual mode) The operation mode is switched to the Manual mode and the Input 1_Manipulated output value at input error is output. 2: Manipulated output value at input error (Auto mode) The operation mode remains in the Auto mode and the Input 1_Manipulated output value at input error of is output. When the error is recovered, the operation mode is switched to the PID control.	2

-  To show “Input 2_Action (low) input error,” “Measured input 2” must be specified at the time of order, and “Select function for input 2” (Function block No. 58 in the Engineering mode) must be set to “2-loop control/Differential temperature input” must be set up.
-  When the value is fixed to “Auto mode” at “Fix parameter setting: Auto/Manual transfer” in the Setting lock mode, “1” cannot be set.

● Input 1_Manipulated output value at input error

[Engineering mode: Function block No. 51 (Fn51)]

Parameter symbol	Data range	Factory set value
I. PSM	PID control: -5.0 to +105.0 % Heat/Cool PID control: -105.0 to +105.0 %	PID control: -5.0 Heat/Cool PID control: 0.0

-  For Heat/Cool PID control, output is produced from the heat side if the setting is positive (+) and output is produced from the cool side if the setting is negative (-).

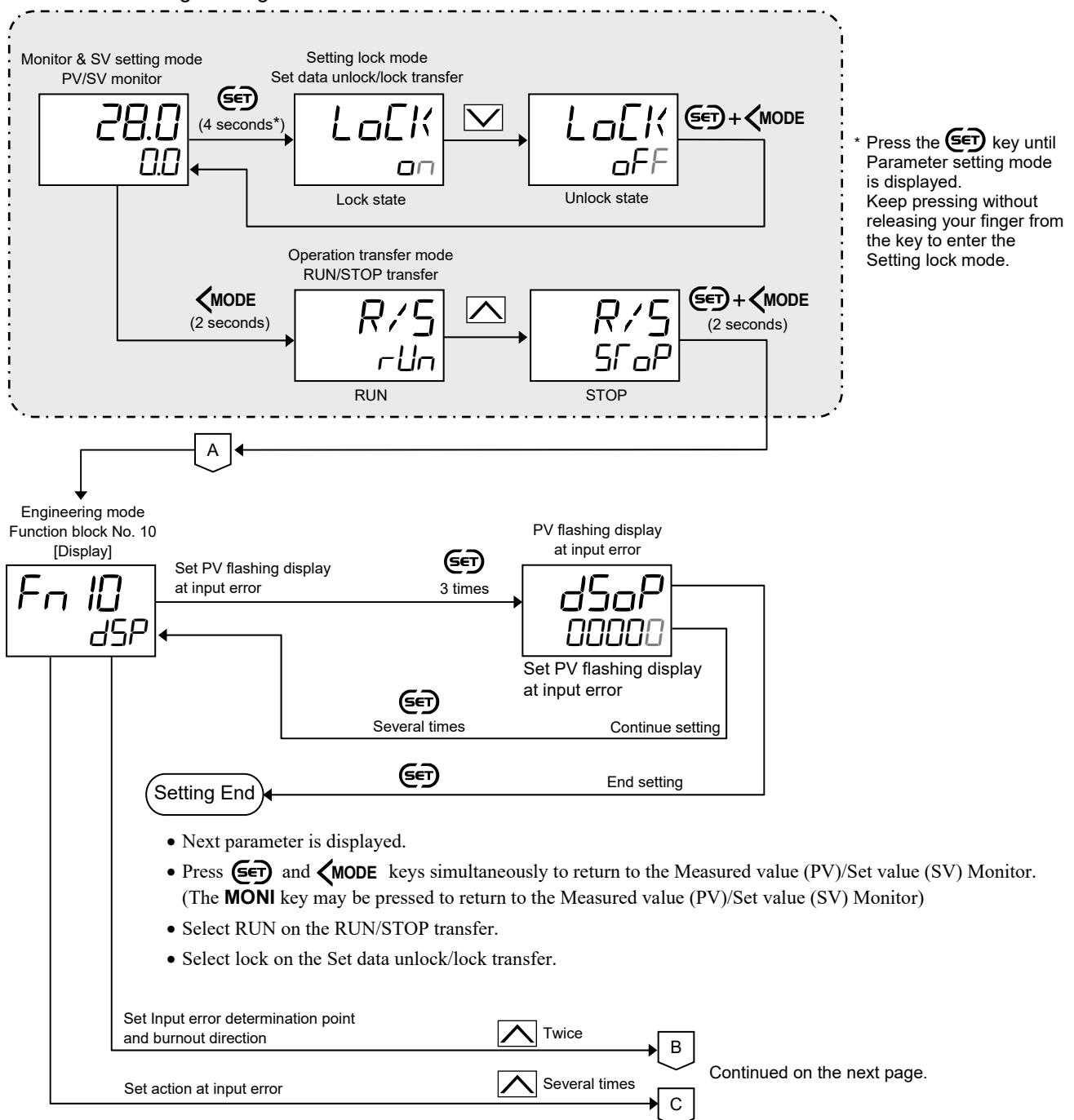
● **Input 2_Manipulated output value at input error**
[Engineering mode: Function block No. 52 (Fn52)]

Parameter symbol	Data range	Factory set value
2. PSM	-5.0 to +105.0 %	-5.0

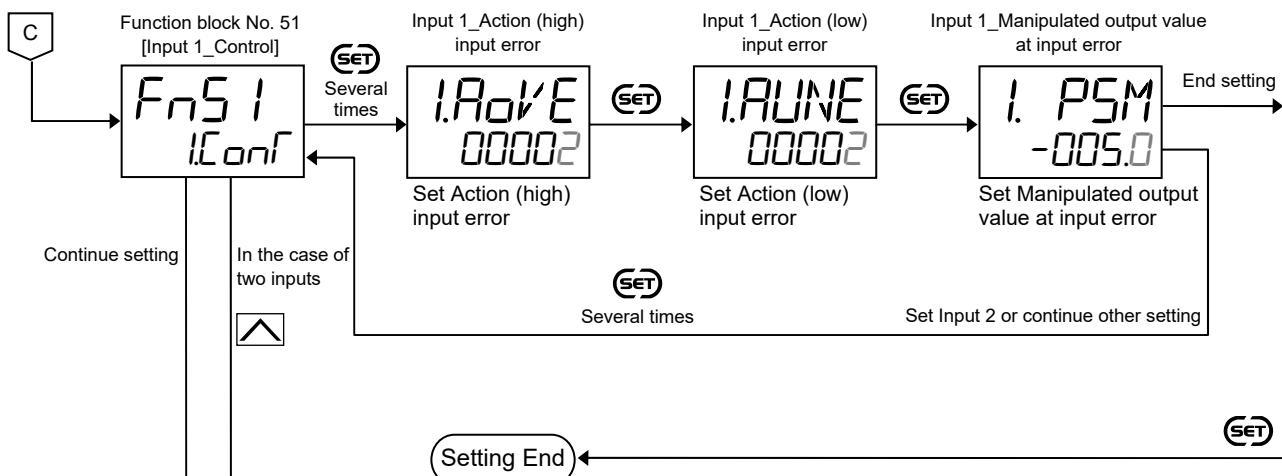
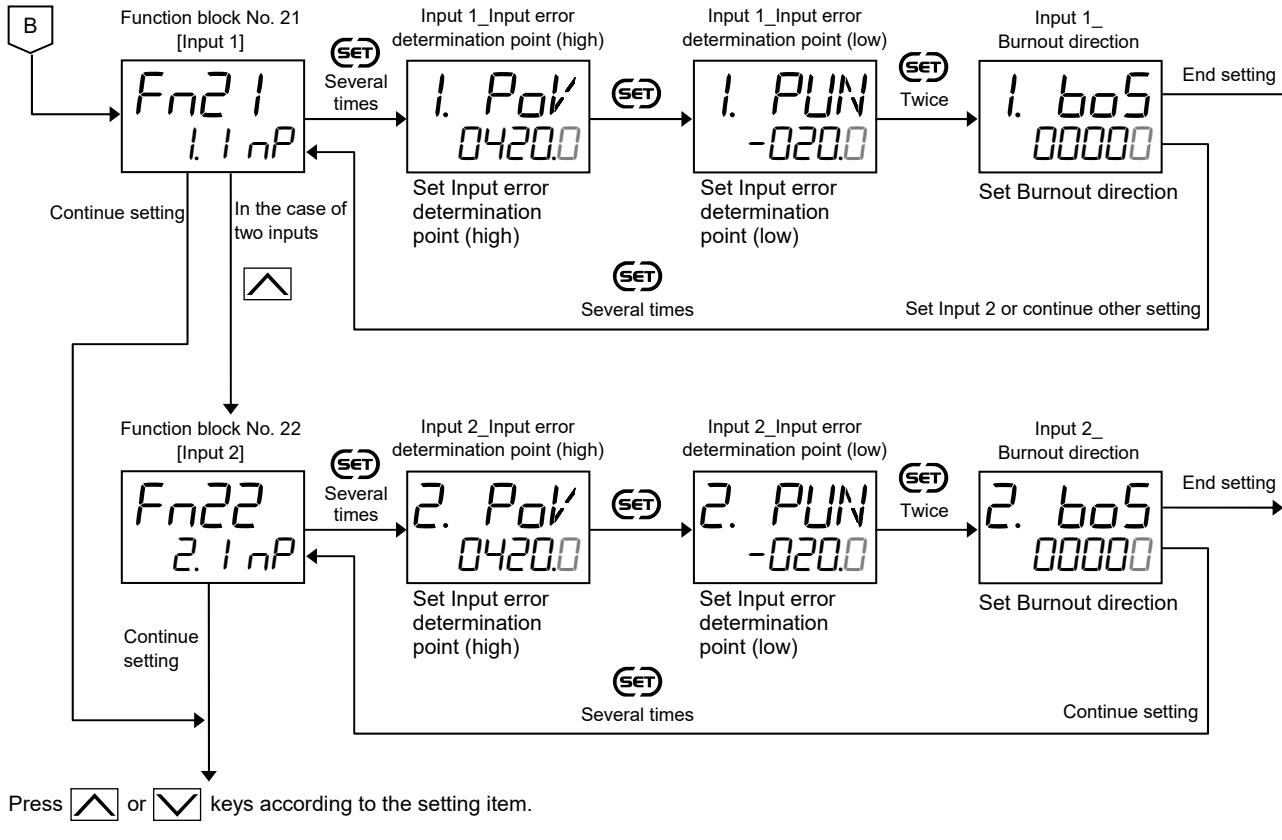
 To show “Input 2_Manipulated output value at input error,” “Measured input 2” must be specified at the time of order, and “Select function for input 2” (Function block No. 58 in the Engineering mode) must be set to “2-loop control/Differential temperature input” must be set up.

■ Setting procedure

To enter the Engineering mode



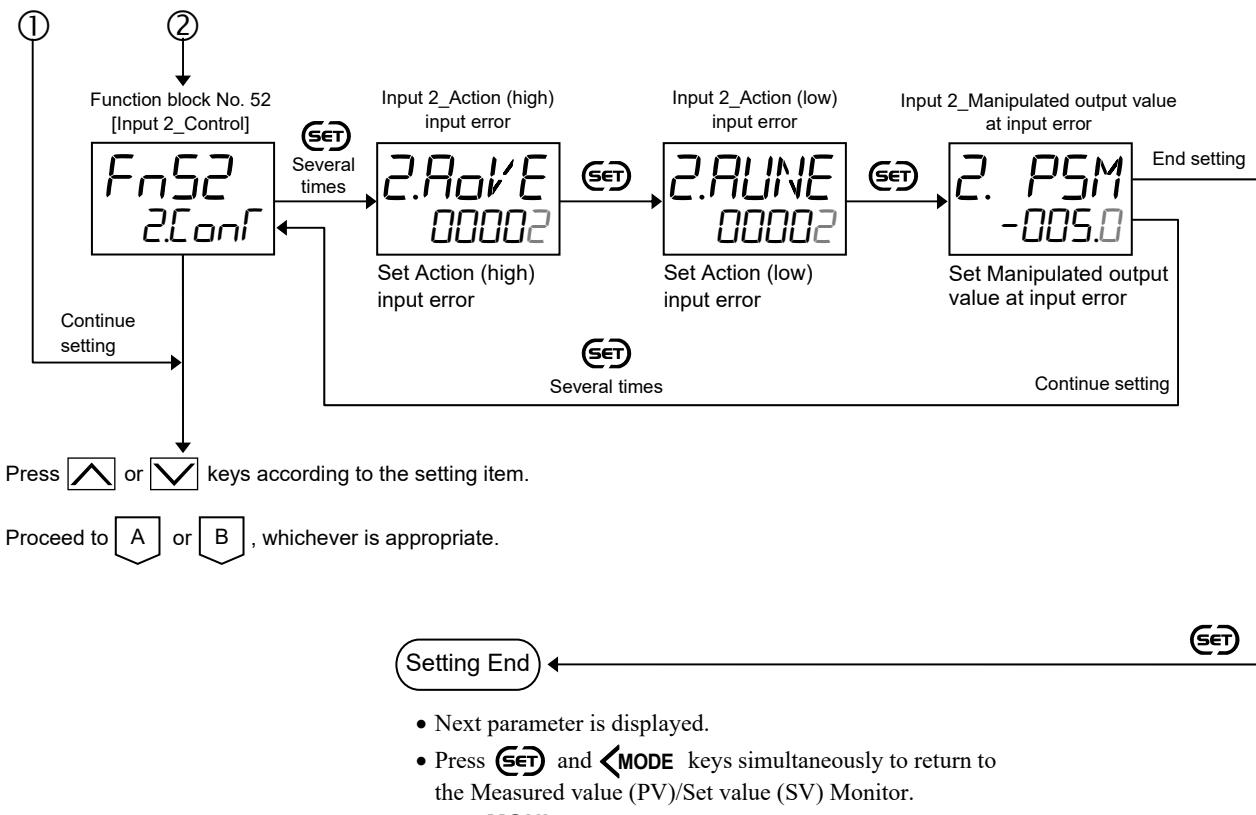
5. INPUT FUNCTION



- Next parameter is displayed.
- Press SET and MODE keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The MONI key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

Continued on the next page.

Continued from the previous page.



5.8 Using Dual Input Function

This instrument has an optional dual input function which can be configured as follows.

- **Remote setting input function**

The instrument uses an input signal from Input 2 as a remote signal and sets it to the Input 1_Set value (SV). To have this function, “Remote setting input” must be specified at the time of order.

 See **8.9 Using Remote Setting Input (P. 8-49)** for more details.

- **2-loop control function**

The instrument performs two independent control using Input 1 and 2. To have this function, “Measured input 2” must be specified at the time of order.

The 2-loop control can be configured to Differential temperature control, and vice versa.

 See **8.10 Executing 2-Loop Control (P. 8-55)** for more details of 2-loop control.

- **Differential temperature control function**

With this function, temperature control of Input 1 is performed by setting a temperature difference between Input 2 and Input 1. To have this function, “Measured input 2” must be specified at the time of order.

The 2-loop control can be configured to Differential temperature control, and vice versa.

 See **8.11 Executing Differential Temperature Control (P. 8-58)** for details.

- **Control with PV select**

This function uses two inputs and allows the sensors to be switched from one to another depending on the temperature of the controlled object (high or low temperatures). To have this function, “Measured input 2” must be specified at the time of order.

 For Control with PV select, see **8.12 Executing Control with PV Select (P. 8-63)**.

- **Input circuit error alarm function**

The instrument uses two inputs to detect an error from the difference in input between the two. To have this function, “Measured input 2” must be specified at the time of order.

 For more details, see **7.7 Preventing Control with Input Errors (Input Circuit Error Alarm) (P. 7-46)**.

■ Parameter setting

● Select function for input 2

[Engineering mode: Function block No. 58 (*Fn58*)]

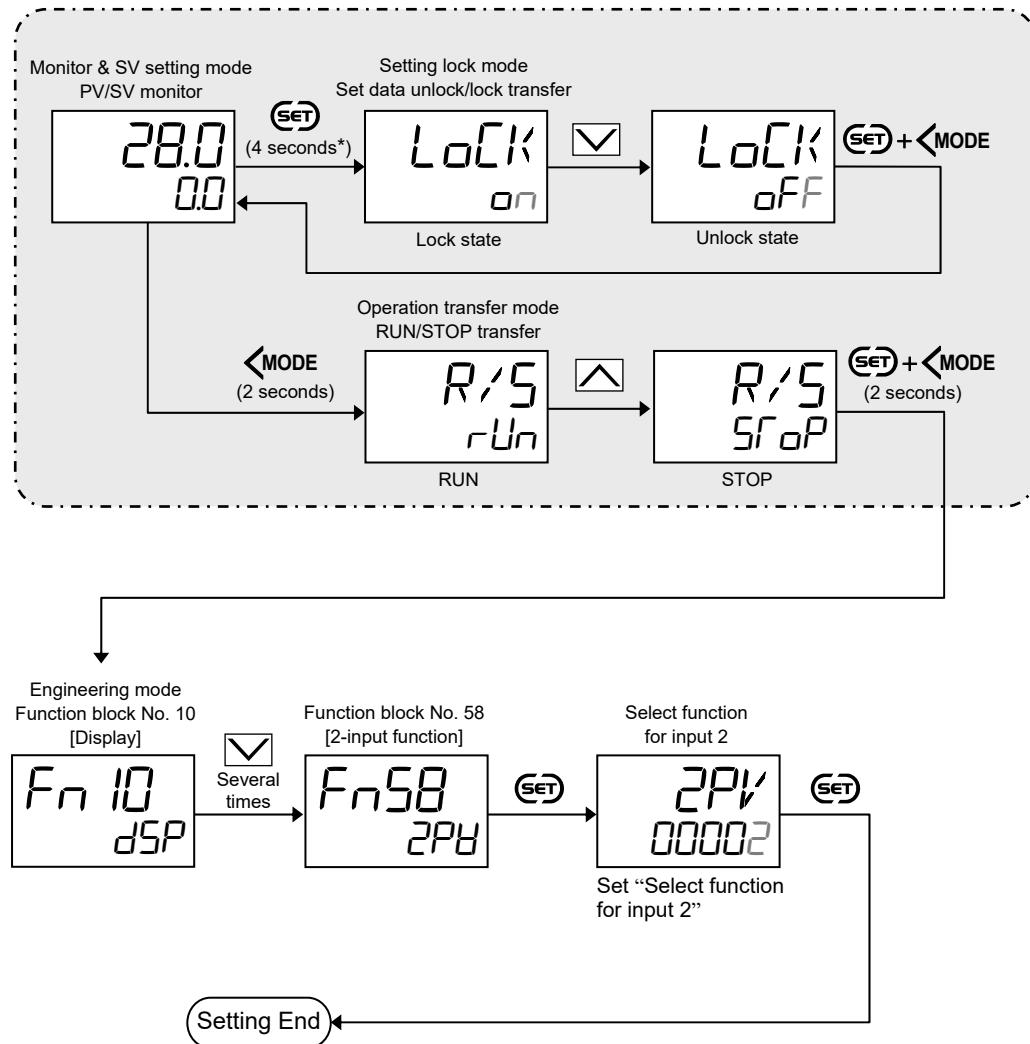
Parameter symbol	Data range	Factory set value
<i>2PV</i>	0: No function 1: Remote setting input 2: 2-loop control/Differential temperature control * 3: Control with PV select 6: Input circuit error alarm <small>* This parameter cannot be specified if the instrument is a Heat/Cool PID type.</small> <ul style="list-style-type: none"> • When Measured input 2 is selected at the time of order: 0 to 3, 6 • When the Remote setting input is selected: 0 to 1 	Based on Model code

 To display “Select function for input 2,” “Remote setting input” or “Measured input 2” must be specified at the time of order.

 See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are initialized or changed when the Select function for input 2 is changed.

■ Setting procedure

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.

5.9 Changing Power Supply Frequency

Power supply frequency to this instrument can be switched between 50 Hz and 60 Hz. Select a power supply frequency of your power supply.

NOTE

To prevent malfunction and instrument failure, setting Power supply frequency (50/60Hz) is required. Before starting the control, make sure you set the power supply frequency of the power supply to be supplied to this instrument.

■ Parameter setting

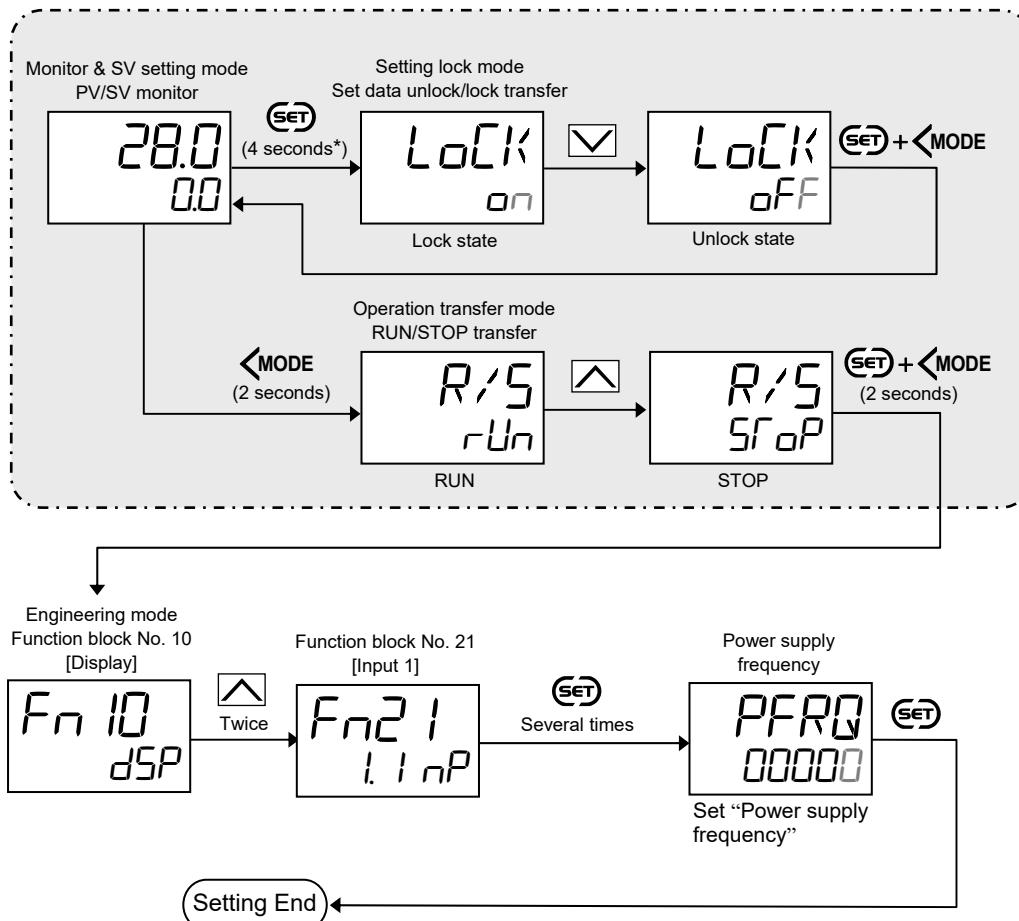
● Power supply frequency

[Engineering mode: Function block No. 21 (*Fn21*)]

Parameter symbol	Data range	Factory set value
<i>PFRQ</i>	0: 50 Hz 1: 60 Hz	0

■ Setting procedure

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.

- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

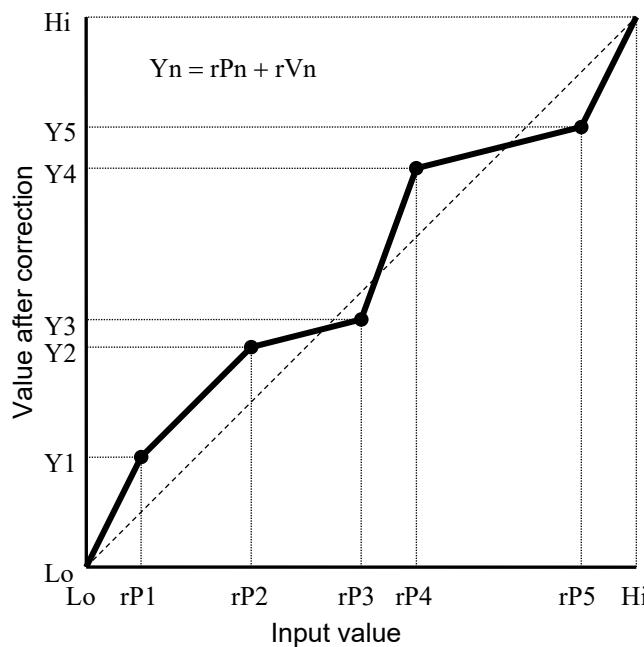
5.10 Making Corrections at Multiple Points (Input Knee Point Correction)

The Input knee point correction function is a function to provide input correction at many temperature points in the process where there are temperature differences between the measured values on heater surface and the set values. Example may include semiconductor related processing machines such as a flip-chip bonding machine.

Input knee point correction can be set independently for input 1 and input 2. Both input 1 and 2 can have up to 16 settings (5 knee points per setting) with the use of memory area.

■ Description of function

Example: In case setting method of knee point correction value is “Deviation setting”



Setting example

Knee point input value		Knee point correction value	
Lo	-200		
rP1	-100	rV1	50
rP2	100	rV2	50
rP3	300	rV3	-20
rP4	400	rV4	60
rP5	700	rV5	-50
Hi	800		

Lo: Input range low

rP1 to rP5: Knee point input value 1 to Knee point input value 5

rV1 to rV5: Knee point correction value 1 to Knee point correction value 5

Hi: Input range high

Equation of correction:

$$\text{Lo} \leq \text{Input value} < \text{rP1} \quad (\text{Value after correction}) = \frac{Y_1 - Lo}{rP1 - Lo} (\text{Input value} - Lo) + Lo$$

$$\text{rP1} \leq \text{Input value} < \text{rP2} \quad (\text{Value after correction}) = \frac{Y_2 - Y_1}{rP2 - rP1} (\text{Input value} - rP1) + Y_1$$

$$\text{rP}_{n-1} \leq \text{Input value} < \text{rP}_n \quad (\text{Value after correction}) = \frac{Y_n - Y_{n-1}}{rP_n - rP_{n-1}} (\text{Input value} - rP_{n-1}) + Y_{n-1}$$

$$\text{rP}_{max} \leq \text{Input value} \leq \text{Hi} \quad (\text{Value after correction}) = \frac{Hi - Y_{max}}{Hi - rP_{max}} (\text{Input value} - rP_{max}) + Y_{max}$$

Lo: Input range low

Hi: Input range high

rP_n: Knee point input value

rV_n: Knee point correction value

Y_n: Value after correction

Deviation setting: Y_n = rP_n + rV_n

Direct setting: Y_n = rV_n

max: Number of knee points

n: 1 to 5

● Setting for irregular setting

NOTE

To avoid an exceptional setting, make sure that the values for Knee point input values 1 to 5 and Knee point correction values 1 to 5 satisfy the following conditions.

Knee point input value 1 to 5

Knee point input value 1 < Knee point input value 2 < Knee point input value 3 <
Knee point input value 4 < Knee point input value 5

Knee point correction value 1 to 5

Value after correction

For deviation setting:

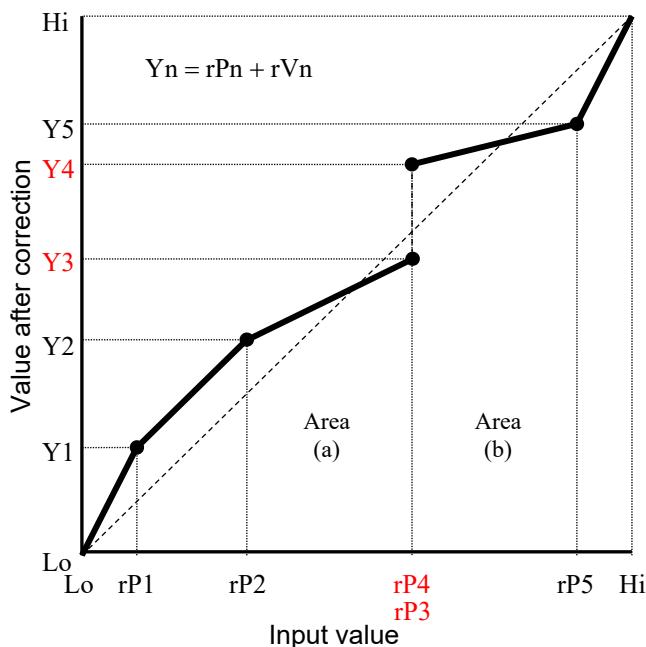
Knee point input value 1+ Knee point correction value 1 <
Knee point input value 2+ Knee point correction value 2 <
Knee point input value 3+ Knee point correction value 3 <
Knee point input value 4+ Knee point correction value 4 <
Knee point input value 5+ Knee point correction value 5

For direct setting:

Knee point correction value 1 < Knee point correction value 2 <
Knee point correction value 3 < Knee point correction value 4 <
Knee point correction value 5

The resultant action may be as follows in case of irregular setting.

Example 1: When knee point input values overlap each other



Setting example

Knee point input value		Knee point correction value	
Lo	-200		
rP ₁	-100	rV ₁	50
rP ₂	100	rV ₂	50
rP ₃	400	rV ₃	-20
rP ₄	400	rV ₄	60
rP ₅	700	rV ₅	-50
Hi	800		

Lo: Input range low

rP₁ to rP₅: Knee point input value 1 to Knee point input value 5

rV₁ to rV₅: Knee point correction value 1 to Knee point correction value 5

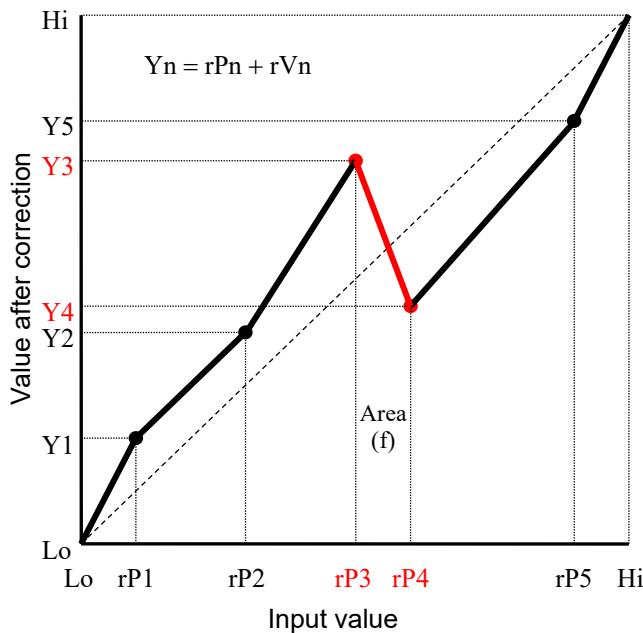
Hi: Input range high

In area (a), correction value is calculated between "Y₂" and "Y₃."

In area (b), correction value is calculated between "Y₄" and "Y₅."

As a result, at the border of area (a) and (b), the value after the calculation may jump.

Example 2: In case value after the correction is reversed



Setting example

Knee point input value		Knee point correction value	
Lo	-200		
rP1	-100	rV1	50
rP2	100	rV2	50
rP3	300	rV3	160
rP4	400	rV4	-120
rP5	700	rV5	-50
Hi	800		

Lo: Input range low

rP1 to rP5: Knee point input value 1 to Knee point input value 5

rV1 to rV5: Knee point correction value 1 to Knee point correction value 5

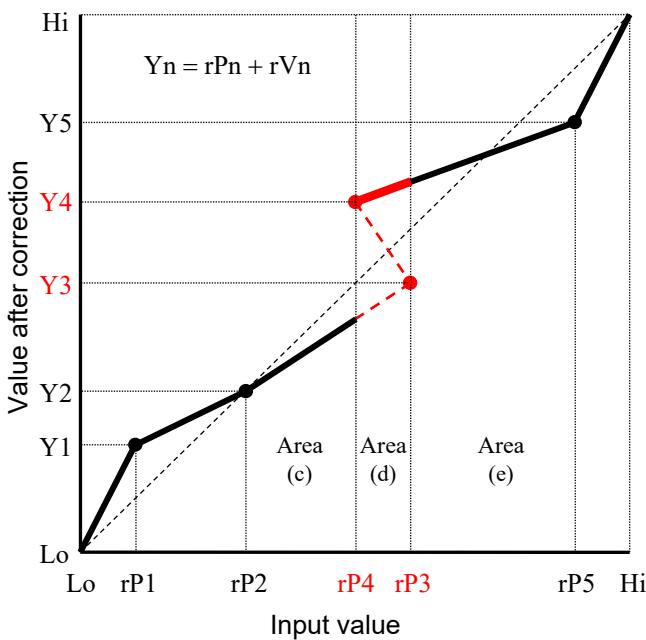
Hi: Input range high

In area (f), the value after the correction is reversed as Y₃ > Y₄.

Accordingly the calculation result decreases as the input increases.

This may cause unstable control.

Example 3: In case knee point input value is reversed



Setting example

Knee point input value		Knee point correction value	
Lo	-200		
rP1	-100	rV1	50
rP2	100	rV2	0
rP3	400	rV3	-50
rP4	300	rV4	50
rP5	700	rV5	-50
Hi	800		

Lo: Input range low

rP1 to rP5: Knee point input value 1 to Knee point input value 5

rV1 to rV5: Knee point correction value 1 to Knee point correction value 5

Hi: Input range high

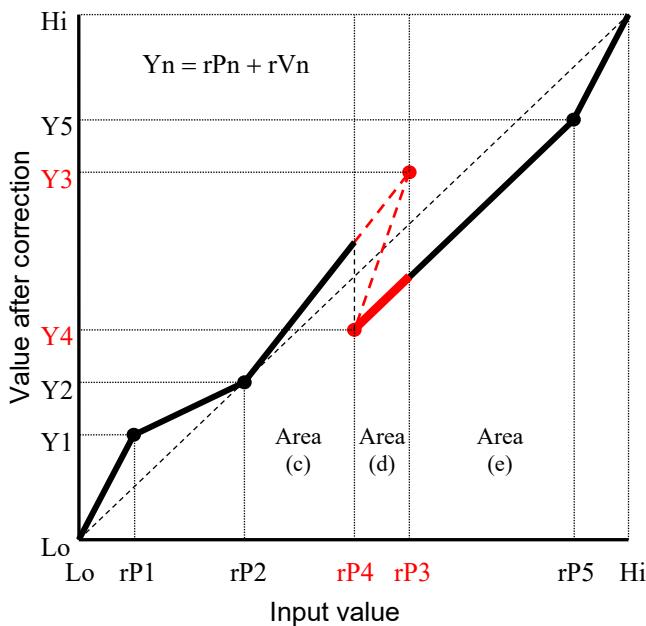
In area (c), correction value is calculated between "Y₂" and "Y₃."

In area (e), correction value is calculated between "Y₄" and "Y₅."

In area (d), as "rP4" which is larger in the identification number of knee point input values becomes effective, correction value is calculated between "Y₄" and "Y₅."

As a result, at the border of area (c) and (d), the value after the calculation may jump.

Example 4: In case both knee point input value and value after correction are reversed



Setting example

Knee point input value		Knee point correction value	
Lo	-200		
rP1	-100	rV1	50
rP2	100	rV2	0
rP3	400	rV3	50
rP4	300	rV4	-50
rP5	700	rV5	-50
Hi	800		

Lo: Input range low

rP1 to rP5: Knee point input value 1 to Knee point input value 5

rV1 to rV5: Knee point correction value 1 to Knee point correction value 5

Hi: Input range high

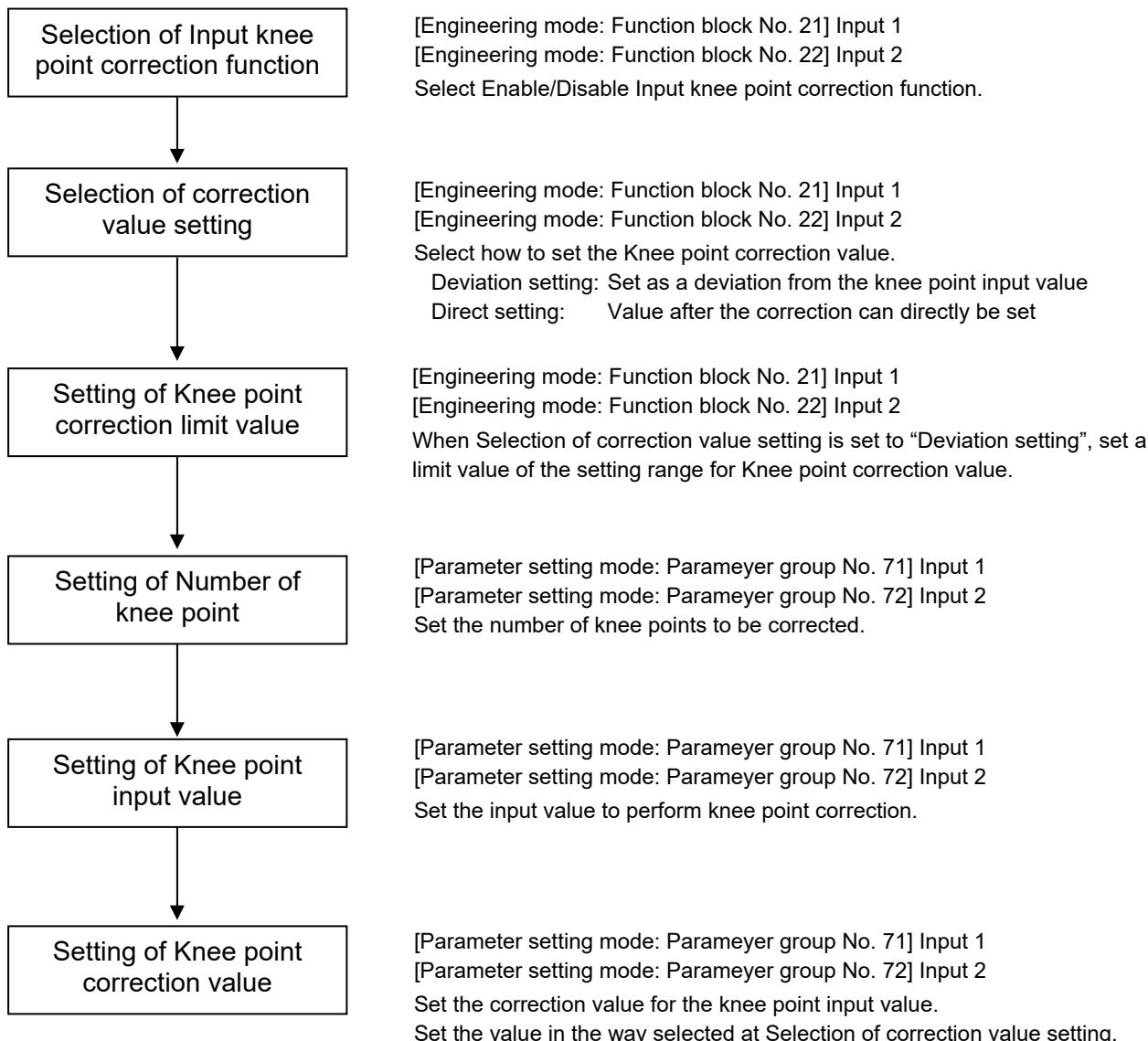
In area (c), correction value is calculated between "Y2" and "Y3."

In area (e), correction value is calculated between "Y4" and "Y5."

In area (d), as "rP4" which is larger in the identification number of knee point input values becomes effective, correction value is calculated between "Y4" and "Y5."

As a result, at the border of area (c) and (d), the value after the calculation may jump.

■ Setting procedure



■ Parameter setting

- **Input 1_Selection of knee point function**
[Engineering mode: Function block No. 21 (F_{n21})]

Parameter symbol	Data range	Factory set value
$I.rV5L$	0: Disable input knee point correction function 1: Enable input knee point correction function	0

- **Input 2_Selection of knee point function**
[Engineering mode: Function block No. 22 (F_{n22})]

Parameter symbol	Data range	Factory set value
$2.rV5L$	0: Disable input knee point correction function 1: Enable input knee point correction function	0

-  To display Input 2_Selection of knee point function, “Measured input 2” or “Remote setting input” must be specified at the time of order.
-  Input 2_Selection of knee point function is not displayed if “No function” is selected at Select function for input 2 in Function block No. 58 in the Engineering mode.

- **Input 1_Selection of correction value setting**
[Engineering mode: Function block No. 21 (F_{n21})]

Parameter symbol	Data range	Factory set value
$I.rV5$	0: Deviation setting (set as a deviation from the knee point input value) 1: Direct setting (value after the correction can directly be set)	0

-  See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the Selection of correction value setting is changed.

- **Input 2_Selection of correction value setting**
[Engineering mode: Function block No. 22 (F_{n22})]

Parameter symbol	Data range	Factory set value
$2.rV5$	0: Deviation setting (set as a deviation from the knee point input value) 1: Direct setting (value after the correction can directly be set)	0

-  To display Input 2_Selection of correction value setting, “Measured input 2” or “Remote setting input” must be specified at the time of order.
-  Input 2_Selection of correction value setting is not displayed if “No function” is selected at Select function for input 2 in Function block No. 58 in the Engineering mode.
-  See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the Selection of correction value setting is changed.

● **Input 1_Knee point correction limit value**
[Engineering Mode: Function block No. 21 (Fn21)]

Parameter symbol	Data range	Factory set value
I_{rVLM}	0 to Input 1_Input span Varies with the setting of the Decimal point position.	10

-  See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are automatically converted when the Knee point correction limit value is changed.

● **Input 2_Knee point correction limit value**
[Engineering Mode: Function block No. No. 22 (Fn22)]

Parameter symbol	Data range	Factory set value
Z_{rVLM}	0 to Input 2_Input span Varies with the setting of the Decimal point position.	10

-  To display Input 2_Knee point correction limit value, “Measured input 2” or “Remote setting input” must be specified at the time of order.
-  Input 2_Knee point correction limit value is not displayed if “No function” is selected at Select function for input 2 in Function block No. 58 in the Engineering mode.
-  See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are automatically converted when the Knee point correction limit value is changed.

● **Input 1_Number of knee point**
[Parameter Setting Mode: Parameter group No. 71 (Pn71)]

Parameter symbol	Data range	Factory set value
I_{norP}	0 to 5 0: Input knee point correction function is disabled	5

-  To show “Input 1_Number of knee point,” Enable input knee point correction function must be selected at Input 1_Selection of knee point function in Function block No. 21 in the Engineering mode.

● **Input 2_Number of knee point**
[Parameter Setting Mode: Parameter group No. 72 (Pn72)]

Parameter symbol	Data range	Factory set value
Z_{norP}	0 to 5 0: Input knee point correction function is disabled	5

-  To show “Input 2_Number of knee point,” “Measured input 2” or “Remote setting input” must be specified at the time of order and Enable input knee point correction function must be selected at Input 2_Selection of knee point function in Function block No. 22 in the Engineering mode.
-  Input 2_Number of knee point is not displayed if “No function” is selected at Select function for input 2 in Function block No. 58 in the Engineering mode.

● **Input 1_Knee point input value 1 to Input 1_Knee point input value 5**
[Parameter Setting Mode: Parameter group No. 71 (Pn71)]

Parameter symbol	Data range	Factory set value
I. rP1	Input 1_Input range low to Input 1_Input range high Varies with the setting of the Decimal point position.	Input 1_Input range high
I. rP2	To avoid an exceptional setting, make sure that the values for Input 1_Knee point input values 1 to 5 satisfy the following conditions. Input 1_Knee point input value 1 < Input 1_Knee point input value 2 < Input 1_Knee point input value 3 < Input 1_Knee point input value 4 < Input 1_Knee point input value 5	
I. rP3		
I. rP4		
I. rP5	Setting of Input 1_Knee point input value depends on the number set at Input 1_Number of knee point.	

- ─ To show “Input 1_Knee point input value 1 to Input 1_Knee point input value 5,” Enable input knee point correction function must be selected at Input 1_Selection of knee point function in Function block No. 21 in the Engineering mode.

● **Input 2_Knee point input value 1 to Input 2_Knee point input value 5**
[Parameter Setting Mode: Parameter group No. 72 (Pn72)]

Parameter symbol	Data range	Factory set value
2. rP1	Input 2_Input range low to Input 2_Input range high Varies with the setting of the Decimal point position.	Input 2_Input range high
2. rP2	To avoid an exceptional setting, make sure that the values for Input 2_Knee point input values 1 to 5 satisfy the following conditions. Input 2_Knee point input value 1 < Input 2_Knee point input value 2 < Input 2_Knee point input value 3 < Input 2_Knee point input value 4 < Input 2_Knee point input value 5	
2. rP3		
2. rP4		
2. rP5	Setting of Input 2_Knee point input value depends on the number set at Input 2_Number of knee point.	

- ─ To show “Input 2_Knee point input value 1 to Input 2_Knee point input value 5,” “Measured input 2” or “Remote setting input” must be specified at the time of order and Enable input knee point correction function must be selected at Input 2_Selection of knee point function in Function block No. 21 in the Engineering mode.
- ─ Input 2_Knee point input value 1 to Input 2_Knee point input value 5 are not displayed if “No function” is selected at Select function for input 2 in Function block No. 58 in the Engineering mode.

● **Input 1_Knee point correction value 1 to Input 1_Knee point correction value 5**
[Parameter Setting Mode: Parameter group No. 71 (Pn71)]

Parameter symbol	Data range	Factory set value
I. rV1	Deviation setting: -(Input 1_Knee point correction limit value) to +(Input 1_Knee point correction limit value) Direct setting: Input 1_Input range low to Input 1_Input range high	Deviation setting: 0 Direct setting: Input 1_Input range high
I. rV2	Varies with the setting of the Decimal point position.	
I. rV3	To avoid an exceptional setting, make sure that the values for Input 1_Knee point correction values 1 to 5 satisfy the following conditions. Value after correction For deviation setting: Input 1_Knee point input value 1 < + Input 1_Knee point correction value 1 < Input 1_Knee point input value 2 < + Input 1_Knee point correction value 2 < Input 1_Knee point input value 3 < + Input 1_Knee point correction value 3 < Input 1_Knee point input value 4 < + Input 1_Knee point correction value 4 < Input 1_Knee point input value 5 < + Input 1_Knee point correction value 5	
I. rV4	For direct setting: Input 1_Knee point correction value 1 < Input 1_Knee point correction value 2 < Input 1_Knee point correction value 3 < Input 1_Knee point correction value 4 < Input 1_Knee point correction value 5	
I. rV5	Setting of Input 1_Knee point correction value depends on the number set at Input 1_Number of knee point.	



To show “Input 1_Knee point correction value 1 to Input 1_Knee point correction value 5,” Enable input knee point correction function must be selected at Input 1_Selection of knee point function in Function block No. 21 in the Engineering mode.

● **Input 2_Knee point correction value 1 to Input 2_Knee point correction value 5**
[Parameter Setting Mode: Parameter group No. 72 (Pn72)]

Parameter symbol	Data range	Factory set value
2. rV1	Deviation setting: -(Input 2_Knee point correction limit value) to +(Input 2_Knee point correction limit value) Direct setting: Input 2_Input range low to Input 2_Input range high	Deviation setting: 0 Direct setting: Input 2_Input range high
2. rV2	Varies with the setting of the Decimal point position.	
2. rV3	To avoid an exceptional setting, make sure that the values for Input 2_Knee point correction values 1 to 5 satisfy the following conditions. Value after correction For deviation setting: Input 2_Knee point input value 1 < + Input 2_Knee point correction value 1 < Input 2_Knee point input value 2 < + Input 2_Knee point correction value 2 < Input 2_Knee point input value 3 < + Input 2_Knee point correction value 3 < Input 2_Knee point input value 4 < + Input 2_Knee point correction value 4 < Input 2_Knee point input value 5 < + Input 2_Knee point correction value 5 <	
2. rV4	For direct setting: Input 2_Knee point correction value 1 < Input 2_Knee point correction value 2 < Input 2_Knee point correction value 3 < Input 2_Knee point correction value 4 < Input 2_Knee point correction value 5 <	
2. rV5	Setting of Input 2_Knee point correction value depends on the number set at Input 2_Number of knee point.	

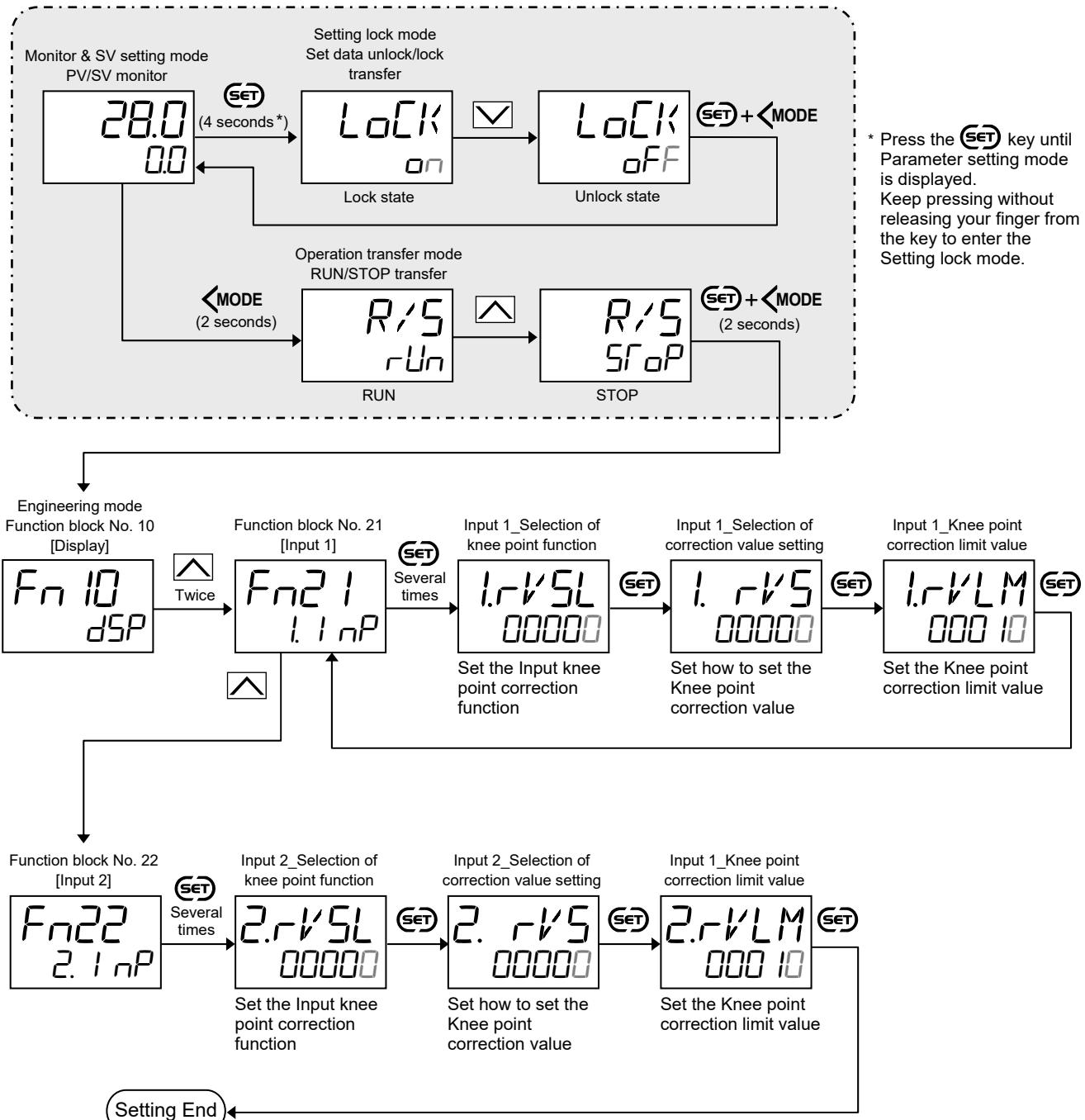
 To show “Input 2_Knee point correction value 1 to Input 2_Knee point correction value 5,” “Measured input 2” or “Remote setting input” must be specified at the time of order and Enable input knee point correction function must be selected at Input 2_Selection of knee point function in Function block No. 21 in the Engineering mode.

 Input 2_Knee point correction value 1 to Input 2_Knee point correction value 5 are not displayed if “No function” is selected at Select function for input 2 in Function block No. 58 in the Engineering mode.

■ Setting procedure

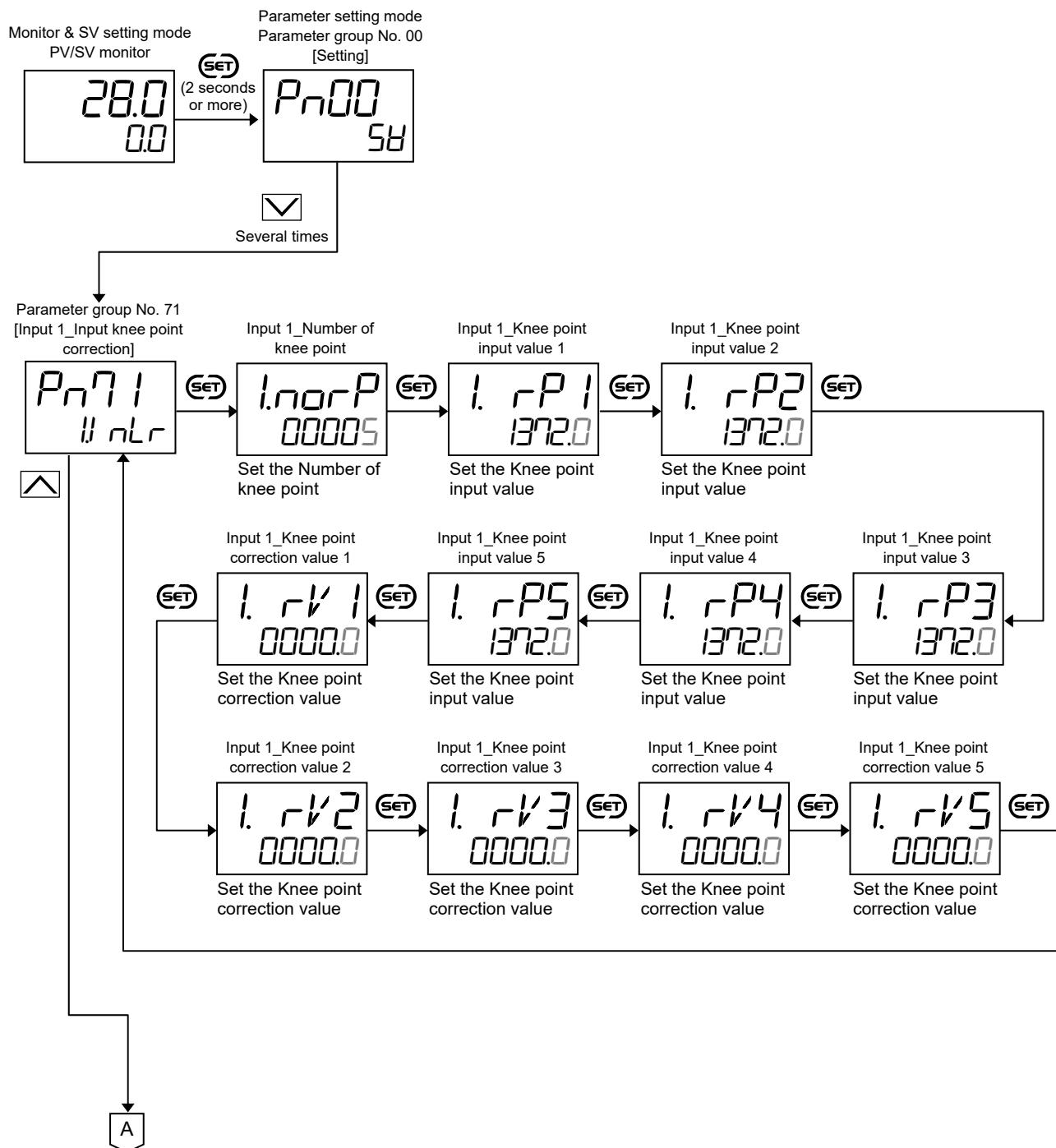
- Setting “Selection of knee point function,” “Selection of correction value setting” and “Knee point correction limit value”

To enter the Engineering mode



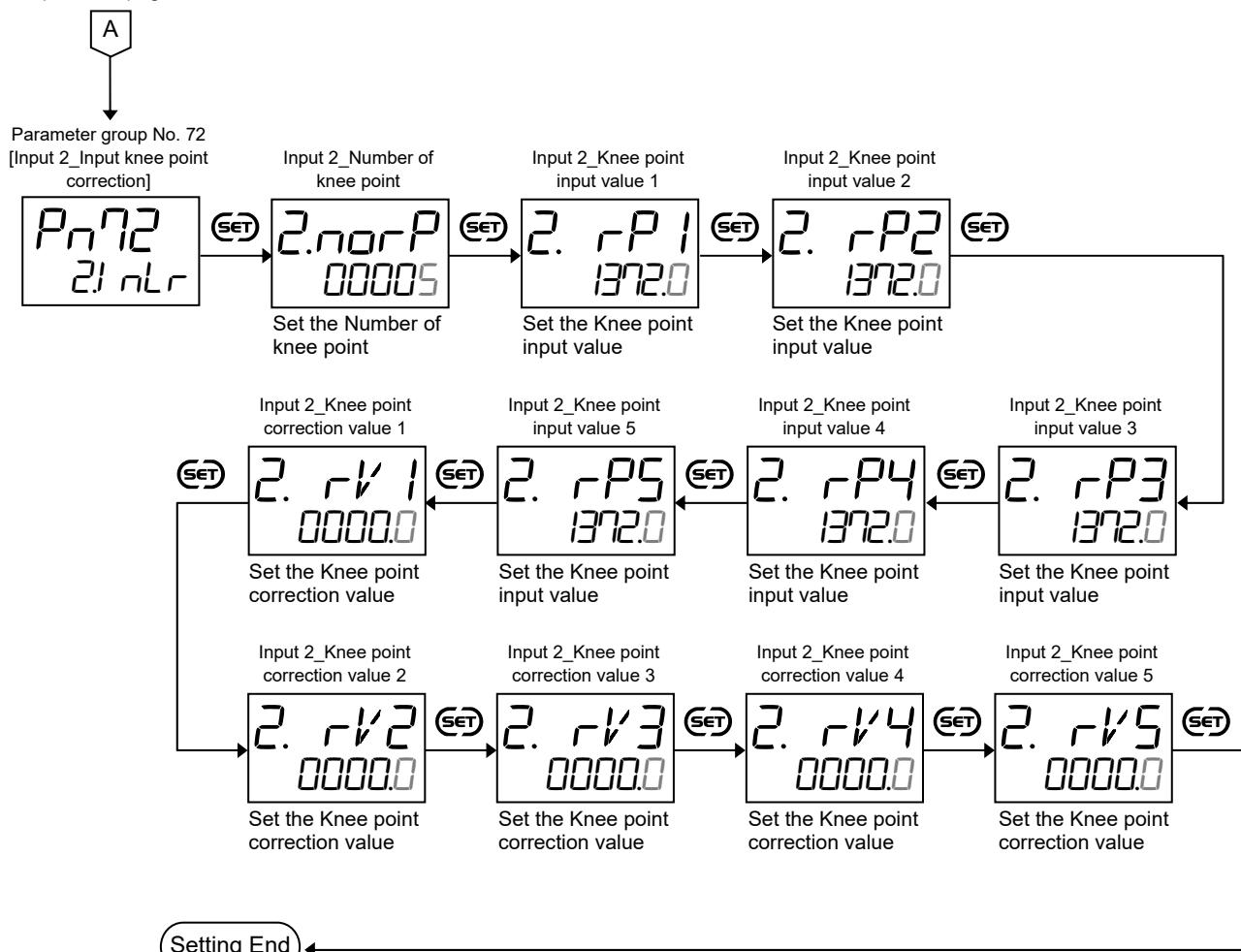
- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

● Setting “Number of knee point,” “Knee point input value” and “Knee point correction value”



Continued on the next page.

Continued from the previous page.



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

6

OUTPUT FUNCTION

This chapter describes output related functions, setting contents and setting procedure based on the key words related to outputs.

6.1	Changing Output Assignment [Control Output, Retransmission Output, Logic Calculation (Event) Output, Instrument Status Output].....	6-2
6.2	Changing Output Type of OUT3	6-12
6.3	Using Retransmission Output	6-14
6.4	Changing Proportional Cycle Time	6-20
6.5	Changing Energizing/De-energizing Output	6-24
6.6	Limiting Output.....	6-26
6.7	Suppressing Sudden Change in Output (Output Change Rate Limiter).....	6-29
6.8	Suppressing Sudden Change in Output (Balanceless Bumpless)	6-33
6.9	Changing the Output Action While in Control Stop Mode	6-39
6.10	Monitoring Manipulated Output Value	6-42

6.1 Changing Output Assignment [Control Output, Retransmission Output, Logic Calculation (Event) Output, Instrument Status Output]

GZ400/900 has such hardware outputs as shown below.

- OUT1 to 3 (max. 3)
- DO1 to 4 (max. 4)

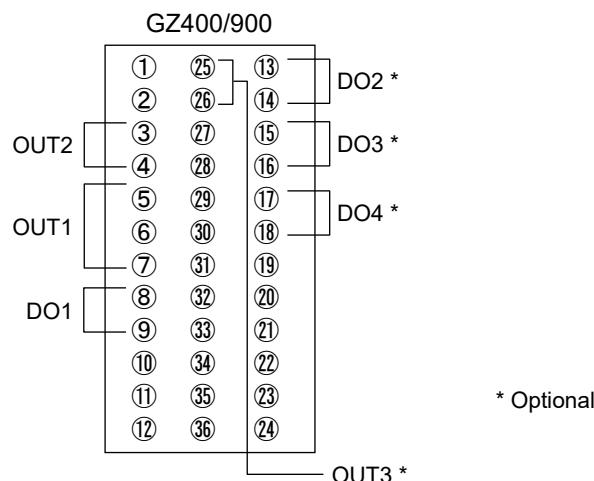
The following output signals are assigned to each output terminal.

- Control output (Settable only between OUT1 and OUT3)
- Retransmission output (Settable only between OUT1 and OUT3)
- Logic calculation output
[Event, Heater break alarm (HBA), Control loop break alarm (LBA), Input error status]
- Instrument Status Output
[RUN, Manual mode, Remote mode, Autotuning (AT), While Set value (SV) is changing, Communication monitoring result, FAIL]

■ Description of function

Output signals [Control output, Retransmission output, Logic calculation output, or Instrument status output] are assigned to the output terminals (OUT1 to 3, DO1 to 4).

● Position of output terminals



● Details of functions assigned to OUT1 to 3

Set value	Assigned functions
0	No assignment
1	Input 1_Control output [heat-side]
2	Input 1_Control output [cool-side]
3	Input 2_Control output
4	Retransmission output
5	Logic calculation output [Event, HBA, LBA, Input error status]
6	RUN state output
7	Input 1_Manual mode state output
8	Input 2_Manual mode state output
9	Remote mode state output (Output of differential temperature control state, Input 2 state output of Control with PV select)
10	Input 1_Autotuning (AT) state output
11	Input 2_Autotuning (AT) state output
12	Output while Set value of Input 1 is changing
13	Output while Set value of Input 2 is changing
14	Output of the communication monitoring result
15	FAIL output

Continued on the next page.

[Explanation of the setting]

- **Input 1_Control output [heat-side]:**
Assignable to Input 1. If Heat/Cool PID control is selected for Input 1, this output is used as heating output.
- **Input 1_Control output [cool-side]:**
This output is available if Heat/Cool PID control is selected for Input 1.
If Heat/Cool PID control is selected, this output is used as a cooling output.
- **Input 2_Control output**
Assignable to Input 2. This output is available if 2-loop control (including Differential temperature control) is selected for Select function for Input 2.
- **Retransmission output:**
Retransmission output type needs to be specified later. Retransmission output scaling is also available.
 For more details of Retransmission output, see **6.3 Using Retransmission Output (P. 6-14)**.
- **Logic calculation output [Event, HBA, LBA, Input error status]:**
Logic calculation needs to be specified separately. Multiple outputs can be output from a single output terminal as logical *OR* relation.
 See the next page (P. 6-4) for Logic calculation selection.
- **RUN state output:**
Output turns on while the instrument is in RUN mode.
- **Input 1_Manual mode state output:**
Output turns on while the Input 1 is in Manual mode.
- **Input 2_Manual mode state output:**
Output turns on while the Input 2 is in Manual mode.
- **Remote mode state output (Output of differential temperature control state, Input 2 state output of Control with PV select)**
Output turns on while the instrument is in the remote mode, differential temperature control, or when Input 2 of Control with PV select is used.
- **Input 1_Autotuning (AT) state output:**
Output turns on while the Input 1 is in the Autotuning (AT).
- **Input 2_Autotuning (AT) state output:**
Output turns on while the Input 2 is in the Autotuning (AT).
- **Output while Set value of Input 1 is changing:**
Output turns on while the Input 1_Set value (SV) is changing due to Setting change rate limiter.
- **Output while Set value of Input 2 is changing:**
Output turns on while the Input 2_Set value (SV) is changing due to Setting change rate limiter.
- **Output of the communication monitoring result:**
Valid only when the communication function is supplied. Output turns on if improper communication continues for 10 seconds.
- **FAIL output:**
Output turns on when the instrument is in FAIL state.
When FAIL is selected, the output terminal is fixed to de-energizing, and the previous setting of energizing and de-energizing gets invalid.

- Details of functions assigned to DO1 to 4

Set value	Assigned functions
0	No assignment
1	Logic calculation output [Event, HBA, LBA, Input error status]
2	RUN state output
3	Input 1_Manual mode state output
4	Input 2_Manual mode state output
5	Remote mode state output (Output of differential temperature control state, Input 2 state output of Control with PV select)
6	Input 1_Autotuning (AT) state output
7	Input 2_Autotuning (AT) state output
8	Output while Set value of Input 1 is changing
9	Output while Set value of Input 2 is changing
10	Output of the communication monitoring result
11	FAIL output

[Explanation of the setting]

See [Explanation of the setting] for OUT1 to 3

- Details of OUT1 to 3 as well as DO1 to 4 logic calculation selection

Multiple functions can be selected in the logic operation. The selected functions are *OR*-output.
To select multiple functions, add the numbers of the desired functions.

Set value	Assigned functions
0	No assignment
1	Event 1
2	Event 2
4	Event 3
8	Event 4
16	Heater break alarm 1 (HBA1)
32	Heater break alarm 2 (HBA2)
64	Control loop break alarm 1 (LBA1)
128	Control loop break alarm 2 (LBA2)
256	Input 1_Input error high
512	Input 1_Input error low
1024	Input 2_Input error high
2048	Input 2_Input error low

[Explanation of the setting]

- Event: Output turns on when the instrument is in the event state.
You also need to set Event assignment, Event type, Event hold action, Event differential gap, Event timer, and Event set value.

 For details of Event, see **7.1 Using Event Function (P. 7-2)**.

- Heater break alarm (HBA):
Output turns on when the instrument is in Heater break alarm (HBA) state.
You also need to set CT assignment, HBA set value, and HBA delay time.

 For details of Heater break alarm (HBA), see **7.2 Using Heater Break Alarm (HBA) (P. 7-24)**.

- Control loop break alarm (LBA):
Output turns on when the instrument is in Control loop break alarm (LBA) state.
You also need to set LBA time and LBA deadband.

 For details of Control loop break alarm (LBA), see **7.3 Using Control loop break alarm (LBA) (P. 7-36)**.

- Input error high:
Output turns on when the Measured value (PV) exceeds the Input error determination point (high).
Under the conditions of a valid Input circuit error alarm, when the Measured value of Input 2 goes over the Set value of the Input circuit error alarm and the measured value of Input 1, the Input error high alarm of Input 1 will turn on.

- Input error low:
Output turns on when the Measured value (PV) exceeds the Input error determination point (low).
Under the conditions of a valid Input circuit error alarm, when the Measured value of Input 2 falls below over the Set value of the Input circuit error alarm and the measured value of Input 1, the Input error low alarm of Input 1 will turn on.

Example

To select Event 1 output, Heater break alarm 1 (HBA1) output and Input 1_Input error output high, set as follows.

- Event 1 = 1
- Heater break alarm 1 (HBA1) = 16
- Input 1_Input error high = 256

$$1 + 16 + 256 = 273$$

So, set 273

■ Setting example

To provide Event 1 to Event 4 from DO1 as a logic OR output.

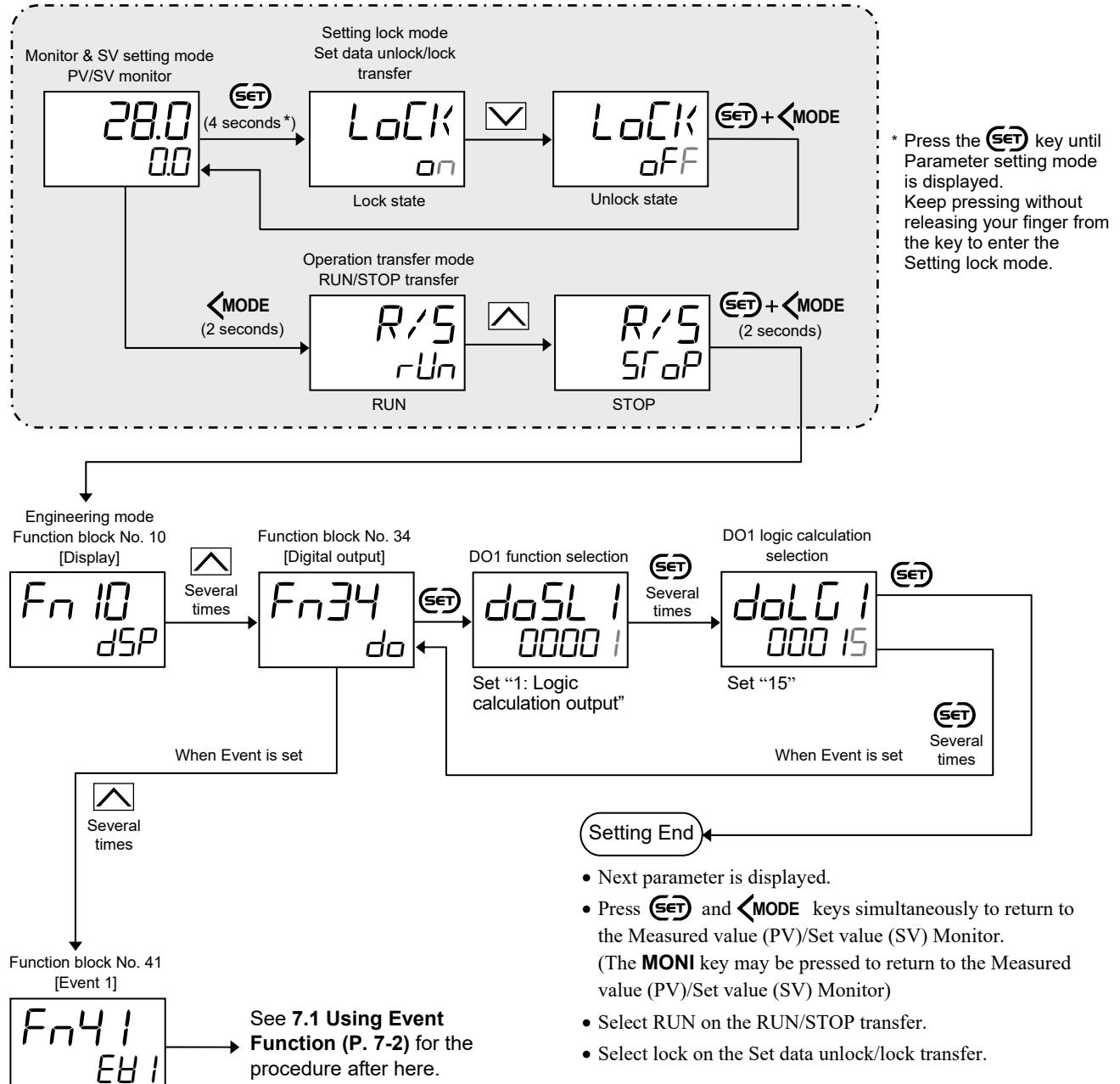
1. Select “1: Logic calculation output” in DO1 assignment.

2. Set “15” for DO1_logic calculation selection.

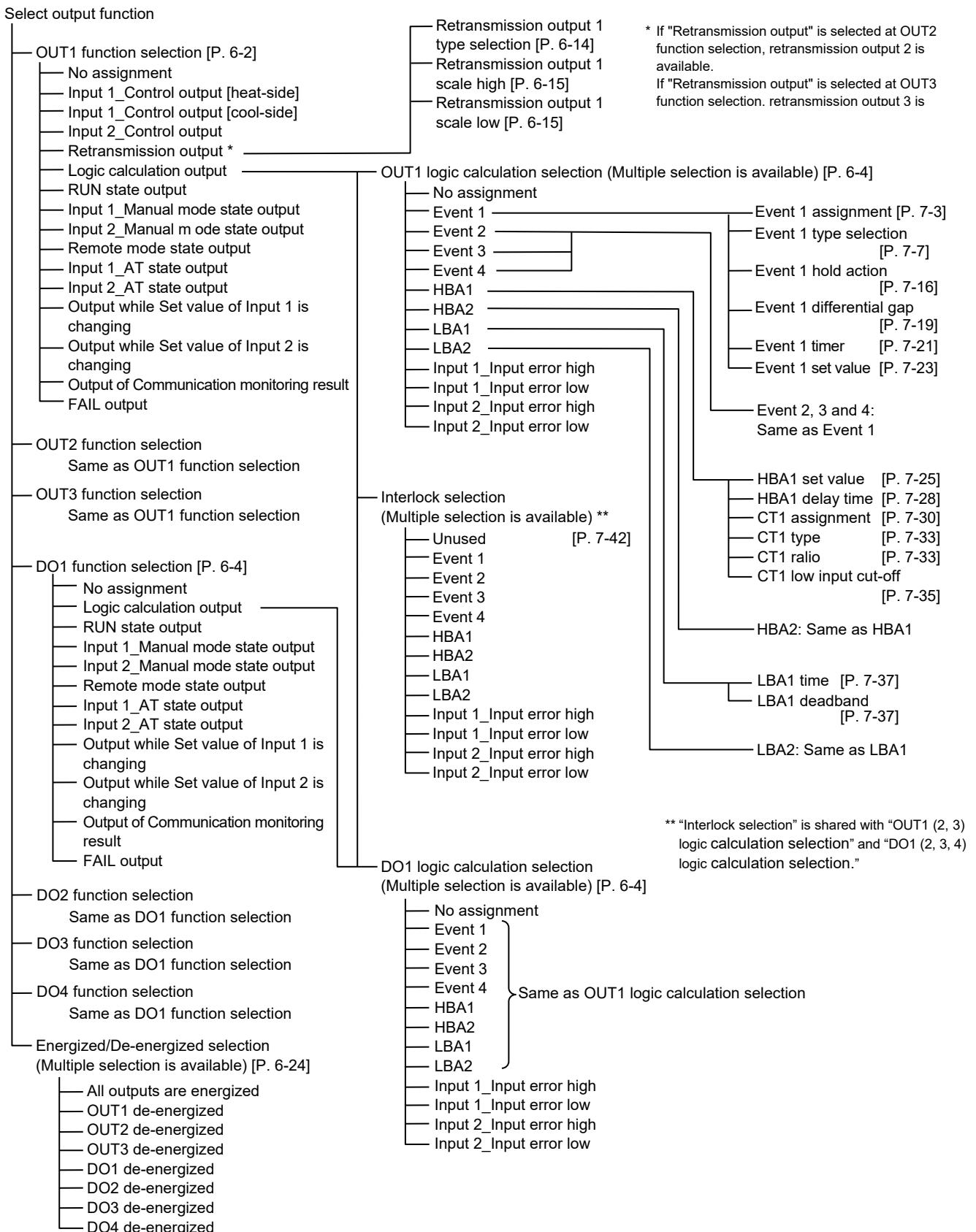
Enter “1” to output Event 1, “2” for Event 2, “4” for Event 3, and “8” for Event 4. Add the sum of these numbers (15), then the outputs of Event 1 to 4 are produced as a logical *OR*.

[Setup procedures]

To enter the Engineering mode



● Output function map



- Retransmission output 1 type selection [P. 6-14]
- Retransmission output 1 scale high [P. 6-15]
- Retransmission output 1 scale low [P. 6-15]

* If "Retransmission output" is selected at OUT2 function selection, retransmission output 2 is available.
If "Retransmission output" is selected at OUT3 function selection, retransmission output 3 is

OUT1 logic calculation selection (Multiple selection is available) [P. 6-4]

- No assignment
- Event 1
- Event 2
- Event 3
- Event 4
- HBA1
- HBA2
- LBA1
- LBA2
- Input 1_Input error high
- Input 1_Input error low
- Input 2_Input error high
- Input 2_Input error low

- Event 1 assignment [P. 7-3]
- Event 1 type selection [P. 7-7]
- Event 1 hold action [P. 7-16]
- Event 1 differential gap [P. 7-19]
- Event 1 timer [P. 7-21]
- Event 1 set value [P. 7-23]

Event 2, 3 and 4:
Same as Event 1

- HBA1 set value [P. 7-25]
- HBA1 delay time [P. 7-28]
- CT1 assignment [P. 7-30]
- CT1 type [P. 7-33]
- CT1 ratio [P. 7-33]
- CT1 low input cut-off [P. 7-35]

- HBA2: Same as HBA1
- LBA1 time [P. 7-37]
- LBA1 deadband [P. 7-37]
- LBA2: Same as LBA1

Interlock selection (Multiple selection is available) **

- Unused [P. 7-42]
- Event 1
- Event 2
- Event 3
- Event 4
- HBA1
- HBA2
- LBA1
- LBA2
- Input 1_Input error high
- Input 1_Input error low
- Input 2_Input error high
- Input 2_Input error low

** "Interlock selection" is shared with "OUT1 (2, 3) logic calculation selection" and "DO1 (2, 3, 4) logic calculation selection."

DO1 logic calculation selection (Multiple selection is available) [P. 6-4]

- No assignment
- Event 1
- Event 2
- Event 3
- Event 4
- HBA1
- HBA2
- LBA1
- LBA2
- Input 1_Input error high
- Input 1_Input error low
- Input 2_Input error high
- Input 2_Input error low

Same as OUT1 logic calculation selection

■ Parameter setting

● OUT1 function selection

[Engineering Mode: Function block No. 30 (Fn30)]

Parameter symbol	Data range	Factory set value
oSL1	<ul style="list-style-type: none"> 0: No assignment 1: Input 1_Control output [heat-side] 2: Input 1_Control output [cool-side] 3: Input 2_Control output 4: Retransmission output 5: Logic calculation output (Event, HBA, LBA, Input error) 6: RUN state output 7: Input 1_Manual mode state output 8: Input 2_Manual mode state output 9: Remote mode state output (Output of differential temperature control state, Input 2 state output of Control with PV select) 10: Input 1_Autotuning (AT) state output 11: Input 2_Autotuning (AT) state output 12: Output while Set value of Input 1 is changing 13: Output while Set value of Input 2 is changing 14: Output of the communication monitoring result 15: FAIL output 	Based on Model code

 To display “OUT1 function selection,” you need to specify the output type other than “None” at Output 1 (OUT1) at the time of order.

 See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are initialized when the OUT1 function selection is changed.

● OUT2 function selection

[Engineering Mode: Function block No. 30 (Fn30)]

Parameter symbol	Data range	Factory set value
oSL2	Same as OUT1 function selection	Based on Model code

 To display “OUT2 function selection,” you need to specify the output type other than “None” at Output 2 (OUT2) at the time of order.

 See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are initialized when the OUT2 function selection is changed.

● OUT3 function selection

[Engineering Mode: Function block No. 30 (Fn30)]

Parameter symbol	Data range	Factory set value
oSL3	Same as OUT1 function selection	4

 To display “OUT3 function selection,” you need to specify the output type OUT3 at the time of order.

 See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the OUT3 function selection is changed.

● DO1 function selection

[Engineering Mode: Function block No. 34 (Fn34)]

Parameter symbol	Data range	Factory set value
doSL1	0: No assignment 1: Logic calculation output (Event, HBA, LBA, Input error) 2: RUN state output 3: Input 1_Manual mode state output 4: Input 2_Manual mode state output 5: Remote mode state output (Output of differential temperature control state, Input 2 state output of Control with PV select) 6: Input 1_Autotuning (AT) state output 7: Input 2_Autotuning (AT) state output 8: Output while Set value of Input 1 is changing 9: Output while Set value of Input 2 is changing 10: Output of the communication monitoring result 11: FAIL output	Based on Model code

● DO2 function selection

[Engineering Mode: Function block No. 34 (Fn34)]

Parameter symbol	Data range	Factory set value
doSL2	Same as DO1 function selection	Based on Model code

 To display “DO2 function selection,” you have to specify 4 digital outputs (DO) at the time of order.

● DO3 function selection

[Engineering Mode: Function block No. 34 (Fn34)]

Parameter symbol	Data range	Factory set value
doSL3	Same as DO1 function selection	Based on Model code

 To display “DO3 function selection,” you have to specify 4 digital outputs (DO) at the time of order.

● DO4 function selection

[Engineering Mode: Function block No. 34 (Fn34)]

Parameter symbol	Data range	Factory set value
do5L4	Same as DO1 function selection	Based on Model code



To display “DO4 function selection,” you have to specify 4 digital outputs (DO) at the time of order.

● OUT1 logic calculation selection

[Engineering Mode: Function block No. 30 (Fn30)]

Parameter symbol	Data range	Factory set value
oLG1	0 to 4095 0: OFF +1: Event 1 +2: Event 2 +4: Event 3 +8: Event 4 +16: Heater break alarm 1 (HBA1) +32: Heater break alarm 2 (HBA2) +64: Control loop break alarm 1 (LBA1) +128: Control loop break alarm 2 (LBA2) +256: Input 1_Input error high +512: Input 1_Input error low +1024: Input 2_Input error high +2048: Input 2_Input error low To select two or more functions, sum each value.	0



To display “OUT1 logic calculation selection,” you need to specify the output type other than “None” at Output 1 (OUT1) at the time of order.

● OUT2 logic calculation selection

[Engineering Mode: Function block No. 30 (Fn30)]

Parameter symbol	Data range	Factory set value
oLG2	Same as OUT1 logic calculation selection	Based on Model code



To display “OUT2 logic calculation selection,” you need to specify the output type other than “None” at Output 2 (OUT2) at the time of order.

● OUT3 logic calculation selection

[Engineering Mode: Function block No. 30 (Fn30)]

Parameter symbol	Data range	Factory set value
oLG3	Same as OUT1 logic calculation selection	0



To display “OUT3 logic calculation selection,” you need to specify the output type OUT3 at the time of order.

● **DO1 logic calculation selection**

[Engineering Mode: Function block No. 34 (Fn34)]

Parameter symbol	Data range	Factory set value
<i>doLG1</i>	Same as OUT1 logic calculation selection (P. 6-9)	Based on Model code

● **DO2 logic calculation selection**

[Engineering Mode: Function block No. 34 (Fn34)]

Parameter symbol	Data range	Factory set value
<i>doLG2</i>	Same as OUT1 logic calculation selection (P. 6-9)	Based on Model code



To display “DO2 logic calculation selection,” you have to specify 4 digital outputs (DO) at the time of order.

● **DO3 logic calculation selection**

[Engineering Mode: Function block No. 34 (Fn34)]

Parameter symbol	Data range	Factory set value
<i>doLG3</i>	Same as OUT1 logic calculation selection (P. 6-9)	Based on Model code



To display “DO3 logic calculation selection,” you have to specify 4 digital outputs (DO) at the time of order.

● **DO4 logic calculation selection**

[Engineering Mode: Function block No. 34 (Fn34)]

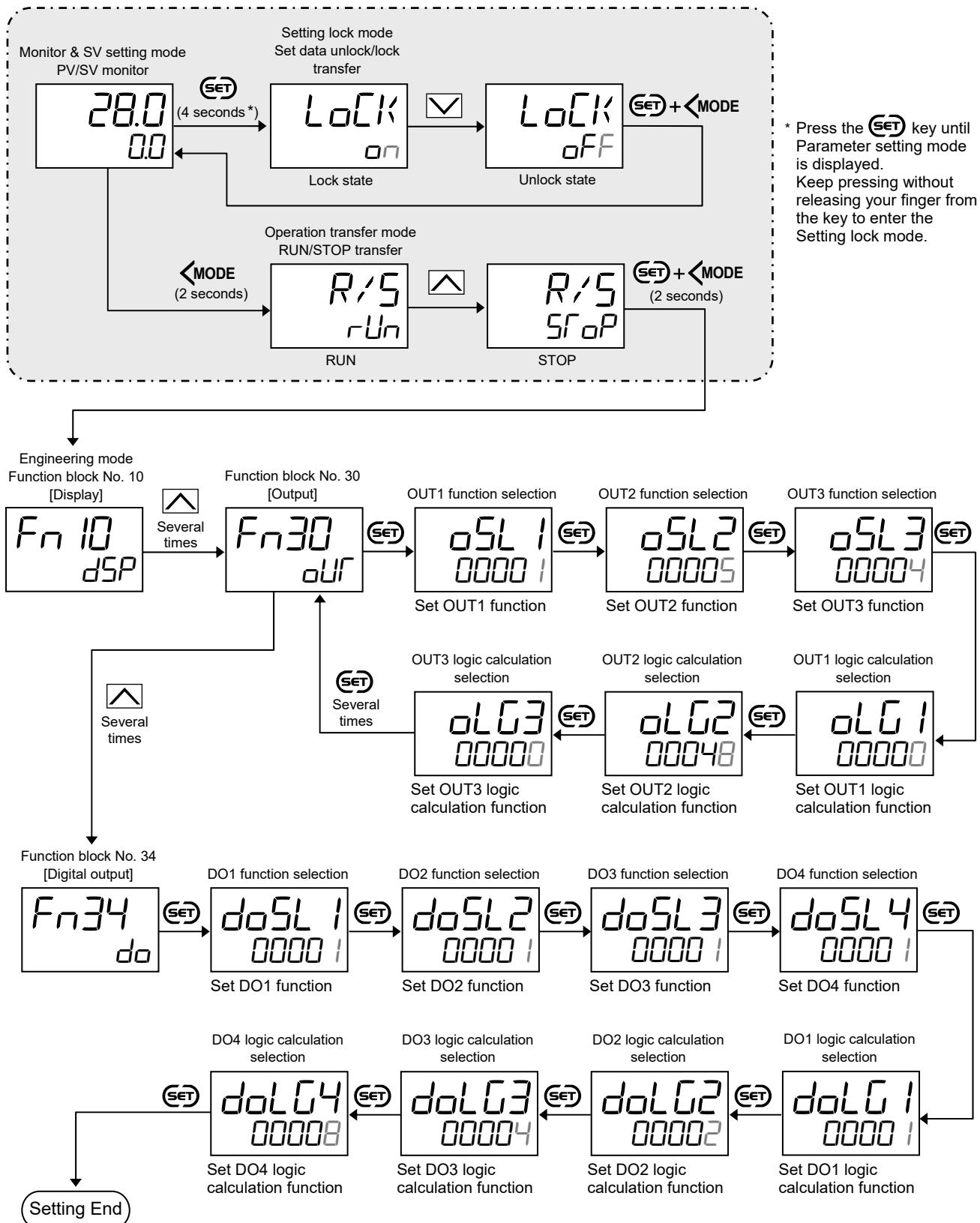
Parameter symbol	Data range	Factory set value
<i>doLG4</i>	Same as OUT1 logic calculation selection (P. 6-9)	Based on Model code



To display “DO4 logic calculation selection,” you have to specify 4 digital outputs (DO) at the time of order.

■ Setting procedure

To enter the Engineering mode



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

6.2 Changing Output Type of OUT3

OUT3 (optional) is available as a universal output. Output type can be changed even after the purchase.

■ Description of function

Output 3 (optional) may be selected from the following three types. The output can be modified without changing the hardware.

- Voltage pulse output (0/14 V DC)
- Current output (4 to 20 mA DC)
- Current output (0 to 20 mA DC)

■ Parameter setting

● Universal output type selection (OUT3) [Engineering Mode: Function block No. 30 (*Fn30*)]

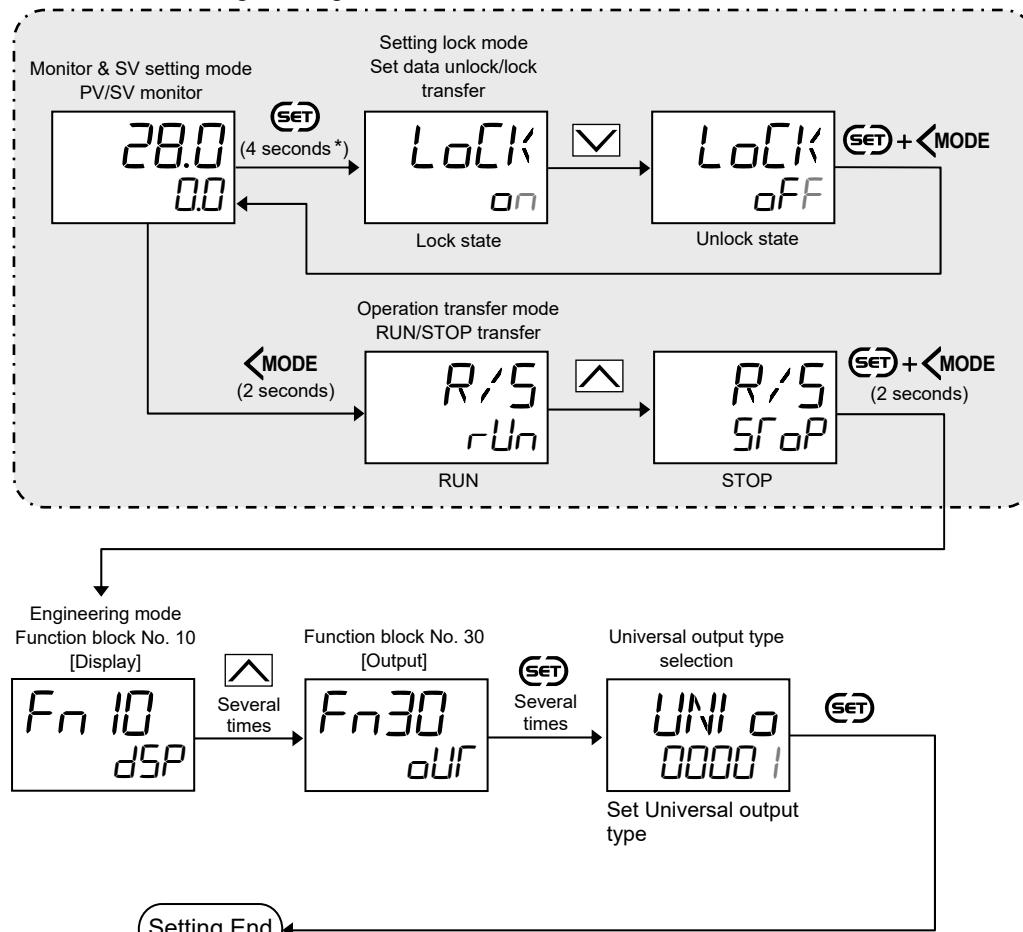
Parameter symbol	Data range	Factory set value
<i>UNI</i>	0: Voltage pulse output 1: Current output (4 to 20 mA DC) 2: Current output (0 to 20 mA DC)	1

To display “Universal output type selection (OUT3),” you need to specify the output type OUT3 at the time of order.

See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are initialized when the Universal output type selection (OUT3) is changed.

■ Setting procedure

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.

- Next parameter is displayed.

- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

6.3 Using Retransmission Output

Retransmission output can be provided from OUT1 to 3. To use the Retransmission output, the output type must be current or continuous voltage output.

■ Description of function

To use the Retransmission output, select Retransmission output at OUT1 to 3 function selection.

If Retransmission output is selected at the OUT1 function selection, the output is provided as Retransmission output 1.

If Retransmission output is selected at the OUT2 function selection, the output is provided as Retransmission output 2.

If Retransmission output is selected at the OUT3 function selection, the output is provided as Retransmission output 3.

 For details OUT1 to 3 function selection, see **6.1 Changing Output Assignment [Control Output, Retransmission Output, Logic Calculation (Event) Output, Instrument Status Output] (P. 6-2)**.

● Details of Retransmission output type

Set value	Assigned functions
0	No retransmission output
1	Input 1_Measured value (PV) Input 1_Measured value (PV) is output.
2	Input 1_Local SV Input 1_Set value (SV) is output. The local SV is the SV set. If the set value is changed, irrespective of the Setting change rate limiter whether or not it is set, the new set value will be used as soon as the value is changed.
3	Input 1_SV monitor value Input 1_Set value (SV) is output. The SV monitor value is the monitored value of the set value (SV). If a Setting change rate limiter is set, the set value starts changing according to the setting when the setting is changed.
4	Input 1_Deviation [Input 1_Measured value (PV) – Input 1_Set value (SV)] is output.
5	Input 1_Manipulated output value [heat-side] Input 1_Manipulated output value [heat-side] is output.
6	Input 1_Manipulated output value [cool-side] Input 1_Manipulated output value [cool-side] is output.
7	Input 2_Measured value (PV) ¹ Input 2_Measured value (PV) is output.
8	Input 2_Local SV ^{1,2} Input 2_Set value (SV) is output. The local SV is the SV set. If the set value is changed, irrespective of the Setting change rate limiter whether or not it is set, the new set value will be used as soon as the value is changed.
9	Input 2_SV monitor value ^{1,2} Input 2_Set value (SV) is output. The SV monitor value is the monitored value of the set value (SV). If a Setting change rate limiter is set, the set value starts changing according to the setting when the setting is changed.
10	Input 2_Deviation ^{1,2} [Input 2_Measured value (PV) – Input 2_Set value (SV)] is output.
11	Input 2_Manipulated output value ^{1,2} Input 2_Manipulated output value [heat-side] is output.
12	Remote setting input value ³ Remote setting input value is output.
13	Current transformer 1 (CT1) input value ⁴ Current transformer 1 (CT1) input value is output.
14	Current transformer 2 (CT2) input value ⁵ Current transformer 2 (CT2) input value is output.
15	Measured value (PV) of differential temperature input ¹ Measured value (PV) of Differential temperature input [Input 1_Measured value (PV) – Input 2_Measured value (PV)] is output.

¹ Valid if “Measured input 2” is specified at the time of order.

² Disabled when “Control with PV select” selected at “Select function for Input 2.”

³ Valid when “Remote setting input” is selected at Select function for input 2.

⁴ Valid if Current transformer (CT) input is supplied.

⁵ Valid if two Current transformer (CT) input are supplied.

 The output will be 0 % when the Retransmission output type not provided on the instrument is set.

- Scaling the Retransmission output

Set high and low limits for the Retransmission output. The scale range depends on the type of the selected Retransmission output.

No retransmission output, Input 1_Measured value (PV), Input 1_Local SV, Input 1_SV monitor value, and Remote setting input value:

Input 1_Input range low to Input 1_Input range high
(When Control with PV select: PV select input range low to PV select input range high)
[Varies with the setting of the Decimal point position.]

Input 1_Deviation:

-(Input 1_Input span) to +(Input 1_Input span)
[Varies with the setting of the Decimal point position.]

Input 2_Measured value (PV), Input 2_Local SV, and Input 2_SV monitor value:

Input 2_Input range low to Input 2_Input range high
[Varies with the setting of the Decimal point position.]

Input 2_Deviation:

-(Input 2_Input span) to +(Input 2_Input span)
[Varies with the setting of the Decimal point position.]

Manipulated output value:

-5.0 to +105.0 %
Current transformer (CT) input value:
0.0 to 100.0 %

Measured value (PV) of differential temperature input:

-(Input 1_Input span) to +(Input 1_Input span)
[Varies with the setting of the Decimal point position.]



In the case of Control with PV select, the measured value used for setting values “1” and “4” for Retransmission output type is the Measured value (PV) of the PV select. When the set value is “7”, the Input 2_Measured value (PV) is used.

■ Parameter setting

● Retransmission output 1 type

[Engineering Mode: Function block No. 31 (Fn31)]

Parameter symbol	Data range		Factory set value
<i>Ro1</i>	0: No retransmission output 1: Input 1_Measured value (PV) 2: Input 1_Local SV 3: Input 1_SV monitor value 4: Input 1_Deviation 5: Input 1_Manipulated output value [heat-side] 6: Input 1_Manipulated output value [cool-side] 7: Input 2_Measured value (PV) 8: Input 2_Local SV	9: Input 2_SV monitor value 10: Input 2_Deviation 11: Input 2_Manipulated output value 12: Remote setting input value 13: Current transformer 1 (CT1) input value 14: Current transformer 2 (CT2) input value 15: Measured value (PV) of differential temperature input	0

 To display “Retransmission output 1 type,” Output type on OUT1 must be specified as Current output or Continuous voltage output at the time of order.

 See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are initialized when the Retransmission output 1 type is changed.

● Retransmission output 1 scale high

[Engineering Mode: Function block No. 31 (Fn31)]

Parameter symbol	Data range	Factory set value
<i>RHS1</i>	No retransmission output, Input 1_Measured value (PV), Input 1_Local SV, Input 1_SV monitor value, and Remote setting input value: Input 1_Input range low to Input 1_Input range high When Control with PV select: PV select input range low to PV select input range high [Varies with the setting of the Decimal point position.] Input 1_Deviation: -(Input 1_Input span) to +(Input 1_Input span) [Varies with the setting of the Decimal point position.] Input 2_Measured value (PV), Input 2_Local SV, and Input 2_SV monitor value: Input 2_Input range low to Input 2_Input range high [Varies with the setting of the Decimal point position.] Input 2_Deviation: -(Input 2_Input span) to +(Input 2_Input span) [Varies with the setting of the Decimal point position.] Manipulated output value: -5.0 to +105.0 % Current transformer (CT) input value: 0.0 to 100.0 % Measured value (PV) of differential temperature input: -(Input 1_Input span) to +(Input 1_Input span) [Varies with the setting of the Decimal point position.]	No retransmission output, Input 1_Measured value (PV), Input 1_Local SV, Input 1_SV monitor value, and Remote setting input value: Input 1_Input range high Control with PV select: PV select input range high Input 1_Deviation: +(Input 1_Input span) Input 2_Measured value (PV), Input 2_Local SV, and Input 2_SV monitor value: Input 2_Input range high Input 2_Deviation: +(Input 2_Input span) Manipulated output value, and Current transformer (CT) input value: 100.0 Measured value (PV) of differential temperature input: 100

 To display “Retransmission output 1 scale high,” Output type on OUT1 must be specified as Current output or Continuous voltage output at the time of order.

● Retransmission output 1 scale low

[Engineering Mode: Function block No. 31 (Fn31)]

Parameter symbol	Data range	Factory set value
RLS1	Same as Retransmission output 1 scale high (P. 6-16)	No retransmission output, Input 1_Measured value (PV), Input 1_Local SV, Input 1_SV monitor value, and Remote setting input value: Input 1_Input range low Control with PV select: PV select input range low Input 1_Deviation: -(Input 1_Input span) Input 2_Measured value (PV), Input 2_Local SV, and Input 2_SV monitor value: Input 2_Input range low Input 2_Deviation: -(Input 2_Input span) Manipulated output value, and Current transformer (CT) input value: 0.0 Measured value (PV) of differential temperature input: -100



To display “Retransmission output 1 scale low,” Output type on OUT1 must be specified as Current output or Continuous voltage output at the time of order.

● Retransmission output 2 type

[Engineering Mode: Function block No. 32 (Fn32)]

Parameter symbol	Data range	Factory set value
R02	Same as Retransmission output 1 (P. 6-16)	0



To display “Retransmission output 2 type,” Output type on OUT2 must be specified as Current output or Continuous voltage output at the time of order.



See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the Retransmission output 2 type is changed.

● Retransmission output 2 scale high

[Engineering Mode: Function block No. 32 (Fn32)]

Parameter symbol	Data range	Factory set value
RHS2	Same as Retransmission output 1 scale high (P. 6-16)	Same as Retransmission output 1 scale high



To display “Retransmission output 2 scale high,” Output type on OUT2 must be specified as Current output or Continuous voltage output at the time of order.

● **Retransmission output 2 scale low**
[Engineering Mode: Function block No. 32 (Fn32)]

Parameter symbol	Data range	Factory set value
AL52	Same as Retransmission output 1 scale low (P. 6-17)	Same as Retransmission output 1 scale low

-  To display “Retransmission output 2 scale low,” Output type on OUT2 must be specified as Current output or Continuous voltage output at the time of order.

● **Retransmission output 3 type**
[Engineering Mode: Function block No. 33 (Fn33)]

Parameter symbol	Data range	Factory set value
Ro3	Same as Retransmission output 1 (P. 6-16)	1

-  To display “Retransmission output 3 type,” OUT3 must be specified at the time of order, and Current output must be set up in “Universal output type selection” in Function block No. 30 in Engineering mode.
-  See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are initialized when the Retransmission output 3 type is changed.

● **Retransmission output 3 scale high**
[Engineering Mode: Function block No. 33 (Fn33)]

Parameter symbol	Data range	Factory set value
RH53	Same as Retransmission output 1 scale high (P. 6-16)	Same as Retransmission output 1 scale high

-  To display “Retransmission output 3 scale high,” OUT3 must be specified at the time of order, and Current output must be set up in “Universal output type selection” in Function block No. 30 in Engineering mode.

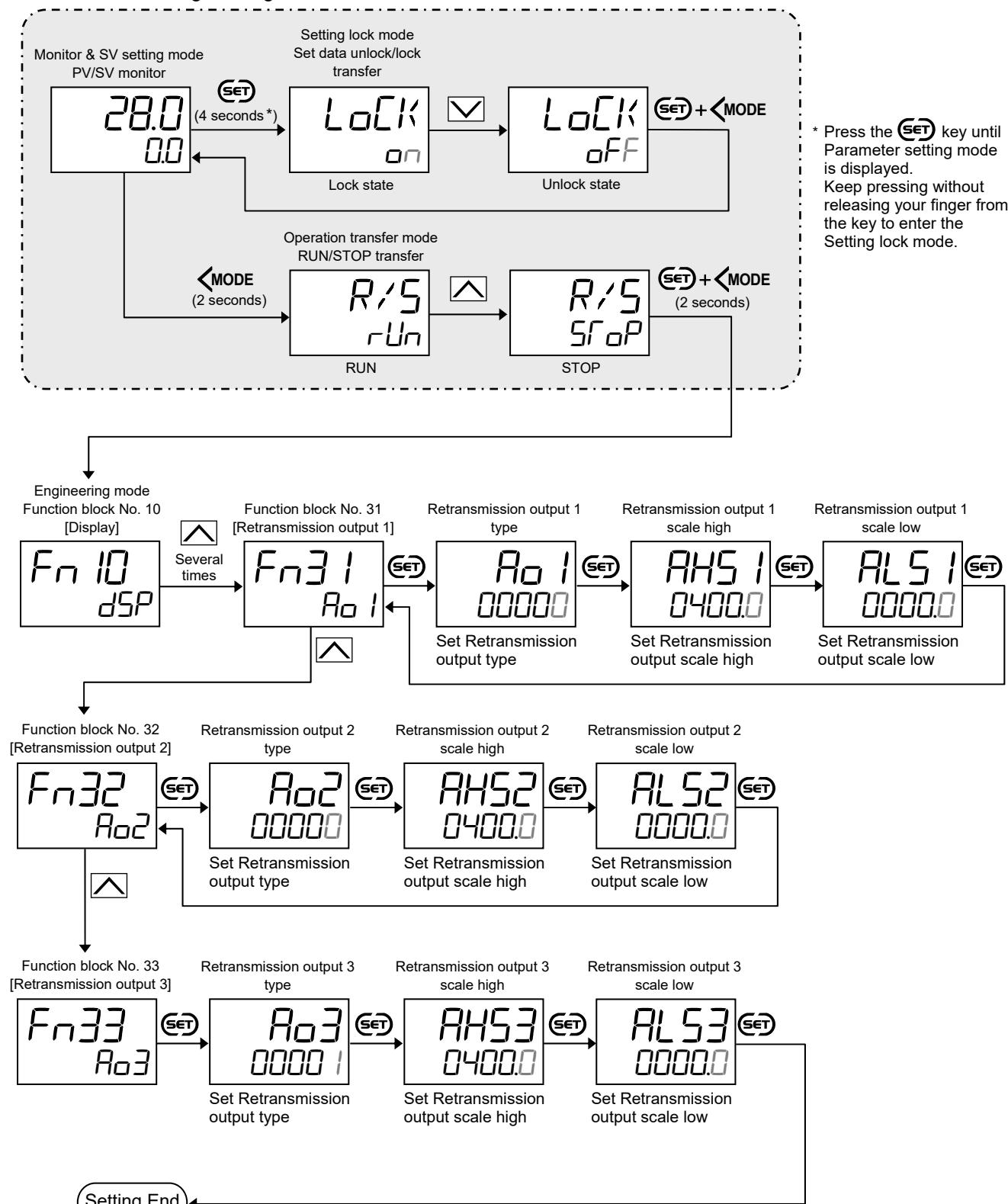
● **Retransmission output 3 scale low**
[Engineering Mode: Function block No. 33 (Fn33)]

Parameter symbol	Data range	Factory set value
AL53	Same as Retransmission output 1 scale low (P. 6-17)	Same as Retransmission output 1 scale low

-  To display “Retransmission output 3 scale low,” OUT3 must be specified at the time of order, and Current output must be set up in “Universal output type selection” in Function block No. 30 in Engineering mode.

■ Setting procedure

To enter the Engineering mode



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

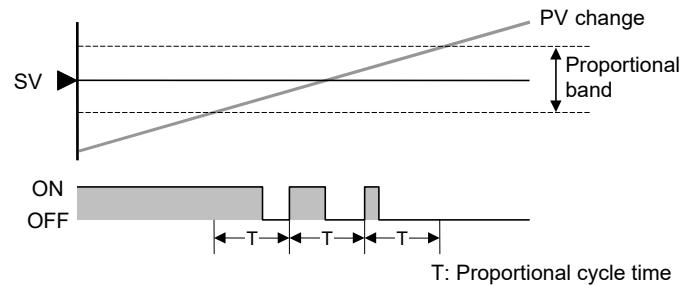
6.4 Changing Proportional Cycle Time

When time proportioning output (relay output, voltage pulse output or transistor output) is specified at the time of ordering, Proportional cycle time and Minimum ON/OFF time of proportional cycle can be changed.

■ Description of function

● Proportional cycle time

Manipulated output value turns ON and OFF in a certain cycle (Proportional cycle time) when the Measured value (PV) reaches within the Proportional band at Time proportioning action. More precise control can be achieved by shortening Proportional cycle time, however, the life of operating unit (Relay etc.) can be shortened based on the feature of the specific controlled object



● Minimum ON/OFF time of proportioning cycle

Minimum ON/OFF time of proportioning cycle can be used to compensate relay life by acquiring the minimum ON/OFF time.

Minimum ON time of proportioning cycle:

Manipulated output does not turn ON when the duration of the computed ON output is shorter than the Minimum ON time of proportioning cycle being set.

Manipulated output remains ON the same amount of time as the computed ON output when the computed ON output is longer than the Minimum ON time of proportioning cycle being set.

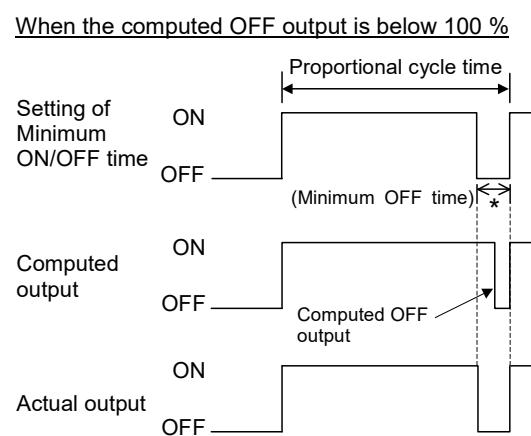
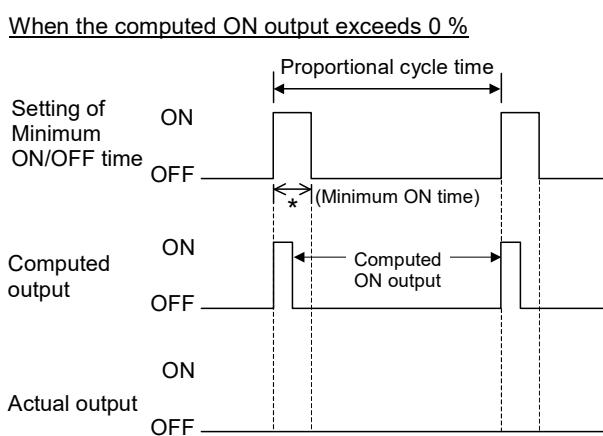
(Minimum ON time of proportioning cycle is valid when the computed ON output exceeds 0 %.)

Minimum OFF time of proportioning cycle:

Manipulated output remains OFF the same amount of time as the Minimum OFF time set when the computed OFF output is shorter than the Minimum OFF time being set.

Manipulated output remains OFF the same amount of time as the computed OFF output when the computed OFF output is longer than the Minimum OFF time being set.

(Minimum OFF time of proportioning cycle is valid when the computed OFF output is below 100 %.)



* When a long minimum ON/OFF time is required for the relay, set a time longer than that time.



Minimum ON/OFF time of proportioning cycle is not operative if the Proportioning cycle is set shorter than the Minimum ON/OFF time of proportioning cycle (Proportioning cycle < Minimum ON/OFF proportioning time).

■ Parameter setting

● OUT1 proportional cycle time

[Setup Setting Mode: Setting group No. 30 (5n30)]

Parameter symbol	Data range	Factory set value
F_1	0.1 to 100.0 seconds	Relay contact output: 20.0 Voltage pulse output, Transistor output: Note

Note: In case OUT1 function selection is “Input 1_Control output [cool-side]” AND Input 1_Control action is “Heat/Cool PID control [air cooling] or [water cooling]”: 20.0, Other cases: 2.0

- (book) To display “OUT1 proportional cycle time,” Output type on OUT1 must be specified at the time of order as Relay contact output, Voltage pulse output, or Transistor output.

● OUT2 proportional cycle time

[Setup Setting Mode: Setting group No. 30 (5n30)]

Parameter symbol	Data range	Factory set value
F_2	0.1 to 100.0 seconds	Relay contact output: 20.0 Voltage pulse output, Transistor output: Note

Note: In case OUT2 function selection is “Input 1_Control output [cool-side]” AND Input 1_Control action is “Heat/Cool PID control [air cooling] or [water cooling]”: 20.0, Other cases: 2.0

- (book) To display “OUT2 proportional cycle time,” Output type on OUT2 must be specified at the time of order as Relay contact output, Voltage pulse output, or Transistor output.

● OUT3 proportional cycle time

[Setup Setting Mode: Setting group No. 30 (5n30)]

Parameter symbol	Data range	Factory set value
F_3	0.1 to 100.0 seconds	Voltage pulse output: Note

Note: In case OUT3 function selection is “Input 1_Control output [cool-side]” AND Input 1_Control action is “Heat/Cool PID control [air cooling] or [water cooling]”: 20.0, Other cases: 2.0

- (book) To display “OUT3 proportional cycle time,” OUT3 must be specified at the time of order, and Voltage pulse output must be set up in “Universal output type selection” in Function block No. 30 in Engineering mode.

● OUT1 minimum ON/OFF time of proportional cycle

[Setup Setting Mode: Setting group No. 30 (5n30)]

Parameter symbol	Data range	Factory set value
MF_1	0 to 1000 ms	0

- (book) To display “OUT1 minimum ON/OFF time of proportional cycle,” Output type on OUT1 must be specified at the time of order as Relay contact output, Voltage pulse output, or Transistor output.

● OUT2 minimum ON/OFF time of proportional cycle

[Setup Setting Mode: Setting group No. 30 (S_n30)]

Parameter symbol	Data range	Factory set value
M _F 2	0 to 1000 ms	0



To display “OUT2 minimum ON/OFF time of proportional cycle,” Output type on OUT2 must be specified at the time of order as Relay contact output, Voltage pulse output, or Transistor output.

● OUT3 minimum ON/OFF time of proportional cycle

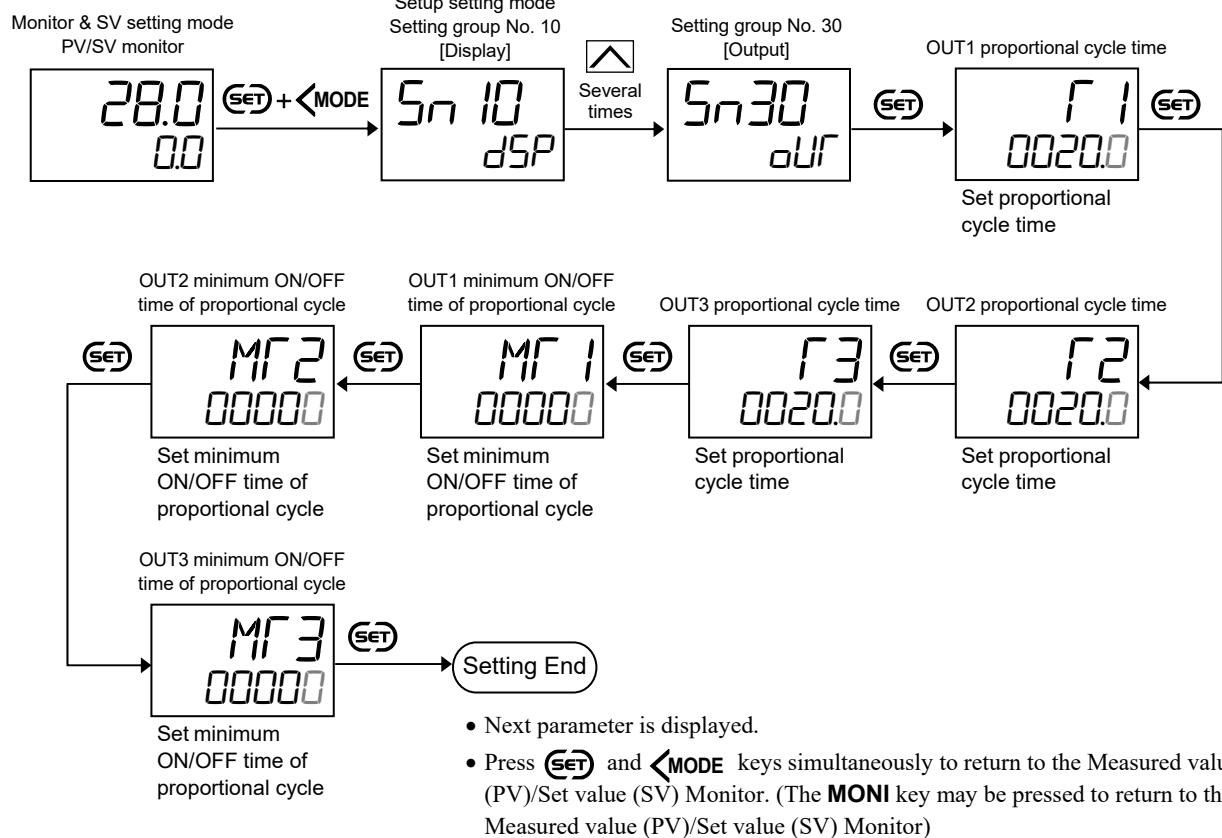
[Setup Setting Mode: Setting group No. 30 (S_n30)]

Parameter symbol	Data range	Factory set value
M _F 3	0 to 1000 ms	0



To display “OUT3 minimum ON/OFF time of proportional cycle,” OUT3 must be specified at the time of order, and Voltage pulse output must be set up in “Universal output type selection” in Function block No. 30 in Engineering mode.

■ Setting procedure



6.5 Changing Energizing/De-energizing Output

Each output (OUT 1 to 3, DO1 to 4) can be individually set to energize or de-energize.

- Setting energize/de-energize at Control output, Retransmission output, or Output terminal to which FAIL is assigned is ignored. (FAIL is fixed as de-energize)

■ Description of function

● Outputs selectable to energize or de-energize

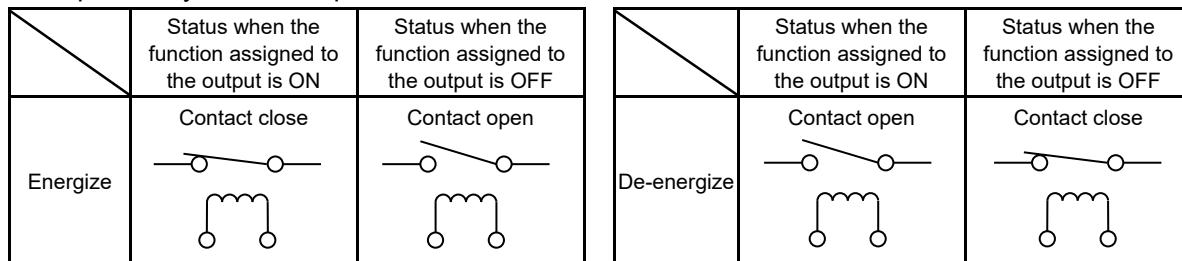
Logic calculation output: Event, Heater break alarm (HBA), Control loop break alarm (LBA), Input error status

Instrument Status Output: RUN, Manual mode, Remote mode, Autotuning (AT), While Set value (SV) is changing, Communication monitoring result

● Explanation of energizing and de-energizing outputs

Output type		Output state	
		Status when the function assigned to the output is ON	Status when the function assigned to the output is OFF
Relay contact output	Energize	Contact close	Contact open
	De-energize	Contact open	Contact close
Voltage pulse output	Energize	ON	OFF
	De-energize	OFF	ON
Current output	Energize	Outputs the maximum output current (100 %)	Outputs the minimum output current (0 %)
	De-energize	Outputs the minimum output current (0 %)	Outputs the maximum output current (100 %)
Continuous voltage output	Energize	Outputs the maximum output current (100 %)	Outputs the minimum output current (0 %)
	De-energize	Outputs the minimum output current (0 %)	Outputs the maximum output current (100 %)
Transistor output	Energize	ON	OFF
	De-energize	OFF	ON

Example: Relay contact output



● Output state at STOP

Irrespective of setting Energize/De-energize, the output state at STOP is as follows.

If “Output action at control stop” (Function block No. 30 in Engineering mode) is set to continue the action, setting of Energize/De-energize remains valid.

Output type	Output state
Relay contact output	Contact open
Voltage pulse output	OFF
Current output	Outputs the minimum output current (0 %)
Continuous voltage output	Outputs the minimum output current (0 %)
Transistor output	OFF

■ Parameter setting

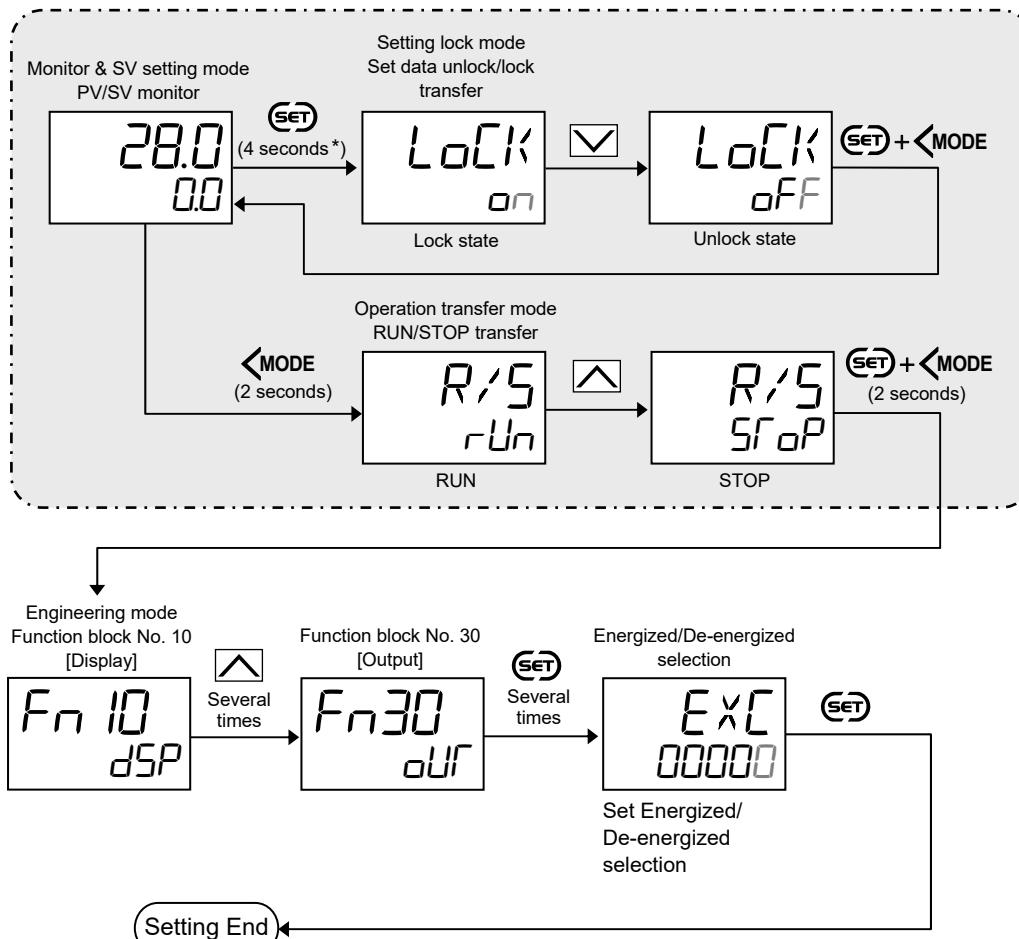
● Energized/De-energized selection

[Engineering Mode: Function block No. 30 (Fn30)]

Parameter symbol	Data range	Factory set value
EXC	0 to 127 0: All outputs are energized +1: OUT1 de-energized +2: OUT2 de-energized +4: OUT3 de-energized +8: DO1 de-energized +16: DO2 de-energized +32: DO3 de-energized +64: DO4 de-energized To select two or more functions, sum each value.	0

■ Setting procedure

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.

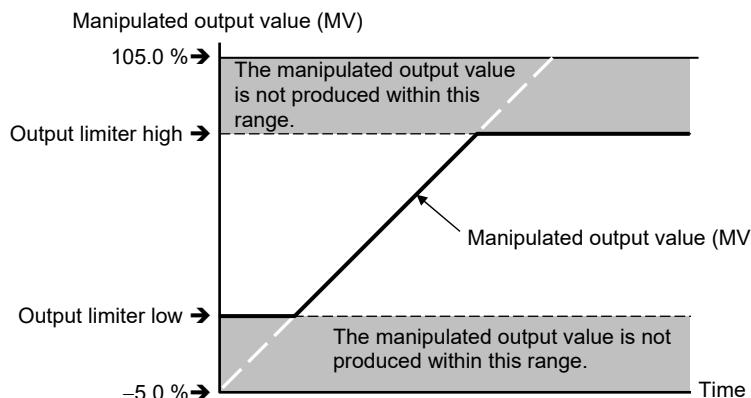
- Next parameter is displayed.
- Press **SET** and **MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

6.6 Limiting Output

Use output limiter to limit the output.

■ Description of function

This is the function which restricts the high and low limits of Manipulated output values (MV).



Output limiter is also effective in ON/OFF control.

■ Parameter setting

- **Input 1_Output limiter high [heat-side]**
[Parameter Setting Mode: Parameter group No. 51 ($P_{n5\ 1}$)]

Parameter symbol	Data range	Factory set value
I_{OLH}	Input 1_Output limiter low [heat-side] to 105.0 %	105.0

See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are automatically converted when the Input 1_Output limiter high [heat-side] is changed.

- **Input 1_Output limiter low [heat-side]**
[Parameter Setting Mode: Parameter group No. 51 ($P_{n5\ 1}$)]

Parameter symbol	Data range	Factory set value
I_{OLL}	-5.0 % to Input 1_Output limiter high [heat-side]	-5.0

See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are automatically converted when the Input 1_Output limiter low [heat-side] is changed.

● Input 2_Output limiter high

[Parameter Setting Mode: Parameter group No. 52 (P_{n52})]

Parameter symbol	Data range	Factory set value
2. oLH	Input 2_Output limiter low to 105.0 %	105.0

 To display “Input 2_Output limiter high,” specify “Measured input 2” at the time of order, AND “Select function for Input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

 See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are automatically converted when the Input 2_Output limiter high is changed.

● Input 2_Output limiter low

[Parameter Setting Mode: Parameter group No. 52 (P_{n52})]

Parameter symbol	Data range	Factory set value
2. oLL	-5.0 % to Input 2_Output limiter high	-5.0

 To display “Input 2_Output limiter low,” specify “Measured input 2” at the time of order, AND “Select function for Input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

 See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are automatically converted when the Input 2_Output limiter low is changed.

● Input 1_Output limiter high [cool-side]

[Parameter Setting Mode: Parameter group No. 56 (P_{n56})]

Parameter symbol	Data range	Factory set value
1.oLHC	Input 1_Output limiter low [cool-side] to 105.0 %	105.0

 To display “Input 1_Output limiter high [cool-side],” specify Heat/Cool PID control at the time of order, or select Heat/Cool PID control at “Input 1_Control action” (Function block No. 51 in Engineering mode).

 See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are automatically converted when the Input 1_Output limiter high [cool-side] is changed.

● Input 1_Output limiter low [cool-side]

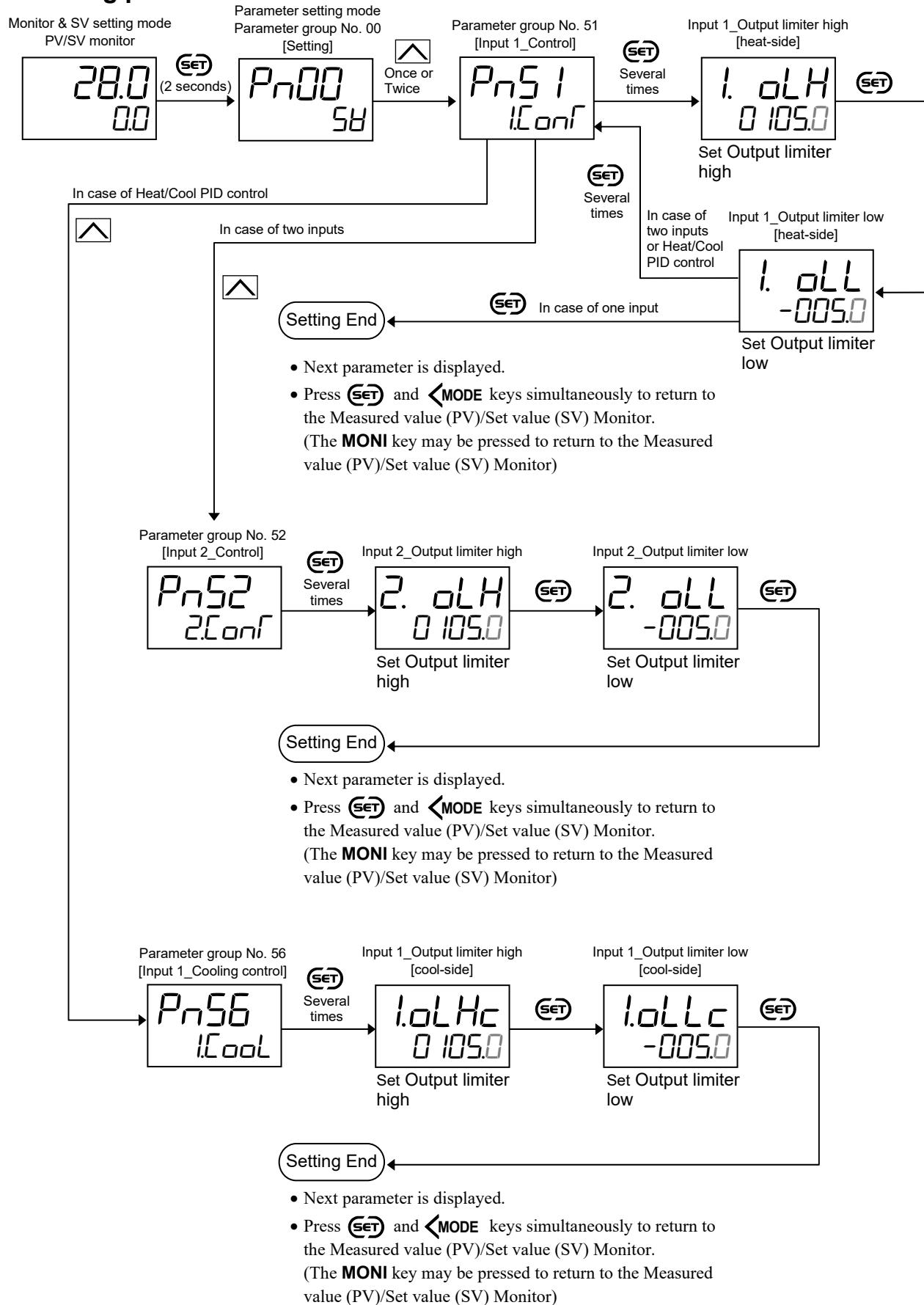
[Parameter Setting Mode: Parameter group No. 56 (P_{n56})]

Parameter symbol	Data range	Factory set value
1.oLLC	-5.0 % to Input 1_Output limiter high [cool-side]	-5.0

 To display “Input 1_Output limiter low [cool-side],” specify Heat/Cool PID control at the time of order, or select Heat/Cool PID control at “Input 1_Control action” (Function block No. 51 in Engineering mode).

 See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are automatically converted when the Input 1_Output limiter low [cool-side] is changed.

■ Setting procedure



6.7 Suppressing Sudden Change in Output (Output Change Rate Limiter)

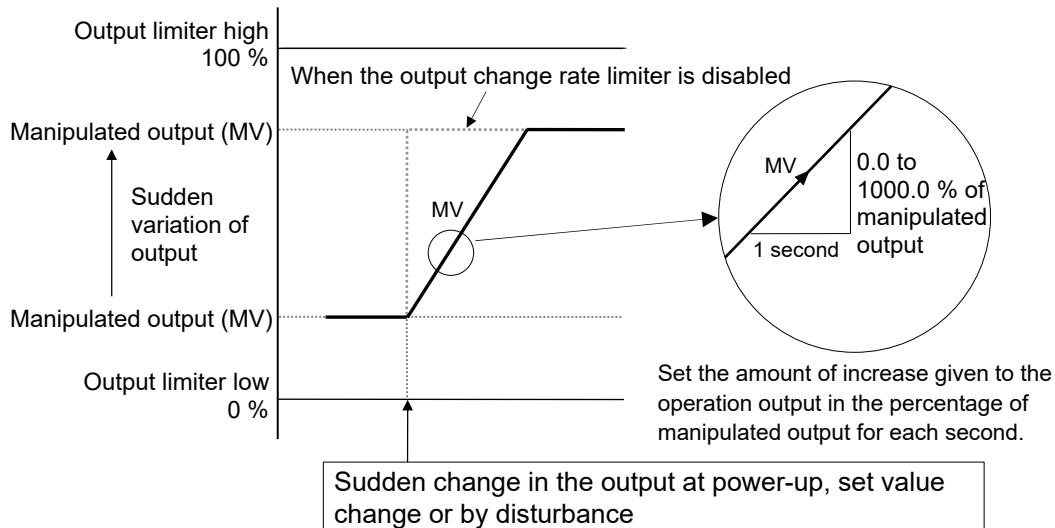
Output change rate limiter may be used to suppress sudden change in output at power on or at the time of set value change.

■ Description of function

The Output change rate limiter limits the variation of Manipulated output (MV) per second. This function is suitable for an application in which a sudden MV change is not acceptable.

Example: The Output change rate limiter is effective.

- The MV reaches 100 % when the power is turned on to the controller and such a sudden output change is not acceptable in the application.
- A sudden output change occurs at the SV change and it is not acceptable in the application.



The output changes at specific rates set by Output change rate limiter (up) even under the situations where a sudden output change would occur without Output change rate limiter function. There is also independent Output change rate limiter (down).

- BOOK If the output change rate is set smaller, it will cause slow control response and affect Derivative action.
- BOOK When the Output change rate limiter is used, you may not be able to obtain appropriate PID constants by Autotuning.
- BOOK The Output change rate limiter is particularly effective when a sudden MV change may create uncontrollable situation cause a large current flow. Also, it is very effective current output or voltage output is used as control output.
- BOOK Output change rate limiter may be also effective in Manual mode (including communication). Output change rate limiter also functions when output changes suddenly due to manipulated manual output at input error.
- BOOK When the instrument recovers from power failure in Hot start 1, the Output change rate limiter starts from the value before the power failure.
- BOOK The Output change rate limiter is deactivated when control is stopped (at STOP), and when control action is an ON/OFF control.

■ Parameter setting

- **Input 1_Output change rate limiter (up) [heat-side]
[Engineering Mode: Function block No. 51 (Fn51)]**

Parameter symbol	Data range	Factory set value
1. ΔR_U	0.0 to 1000.0 %/seconds of manipulated output 0.0: OFF	0.0

- **Input 1_Output change rate limiter (down) [heat-side]
[Engineering Mode: Function block No. 51 (Fn51)]**

Parameter symbol	Data range	Factory set value
1. ΔR_d	0.0 to 1000.0 %/seconds of manipulated output 0.0: OFF	0.0

- **Input 2_Output change rate limiter (up)
[Engineering Mode: Function block No. 52 (Fn52)]**

Parameter symbol	Data range	Factory set value
2. ΔR_U	0.0 to 1000.0 %/seconds of manipulated output 0.0: OFF	0.0

 To display “Input 2_Output change rate limiter (up),” specify “Measured input 2” at the time of order, AND “Select function for Input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

- **Input 2_Output change rate limiter (down)
[Engineering Mode: Function block No. 52 (Fn52)]**

Parameter symbol	Data range	Factory set value
2. ΔR_d	0.0 to 1000.0 %/seconds of manipulated output 0.0: OFF	0.0

 To display “Input 2_Output change rate limiter (down),” specify “Measured input 2” at the time of order, AND “Select function for Input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

● **Input 1_Output change rate limiter (up) [cool-side]
[Engineering Mode: Function block No. 56 (Fn56)]**

Parameter symbol	Data range	Factory set value
I_{oRUC}	0.0 to 1000.0 %/seconds of manipulated output 0.0: OFF	0.0

 To display “Input 1_Output change rate limiter (up) [cool-side],” specify Heat/Cool PID control at the time of order, or select Heat/Cool PID control at “Input 1_Control action” (Function block No. 51 in Engineering mode).

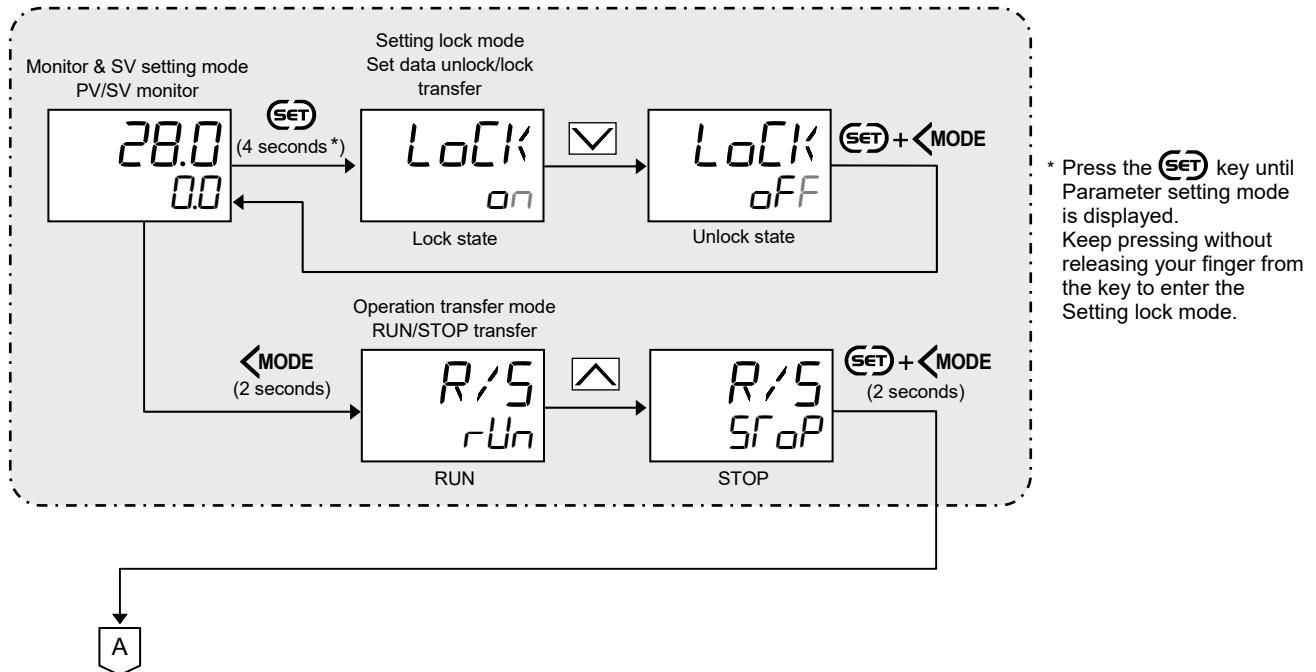
● **Input 1_Output change rate limiter (down) [cool-side]
[Engineering Mode: Function block No. 56 (Fn56)]**

Parameter symbol	Data range	Factory set value
I_{oRdc}	0.0 to 1000.0 %/seconds of manipulated output 0.0: OFF	0.0

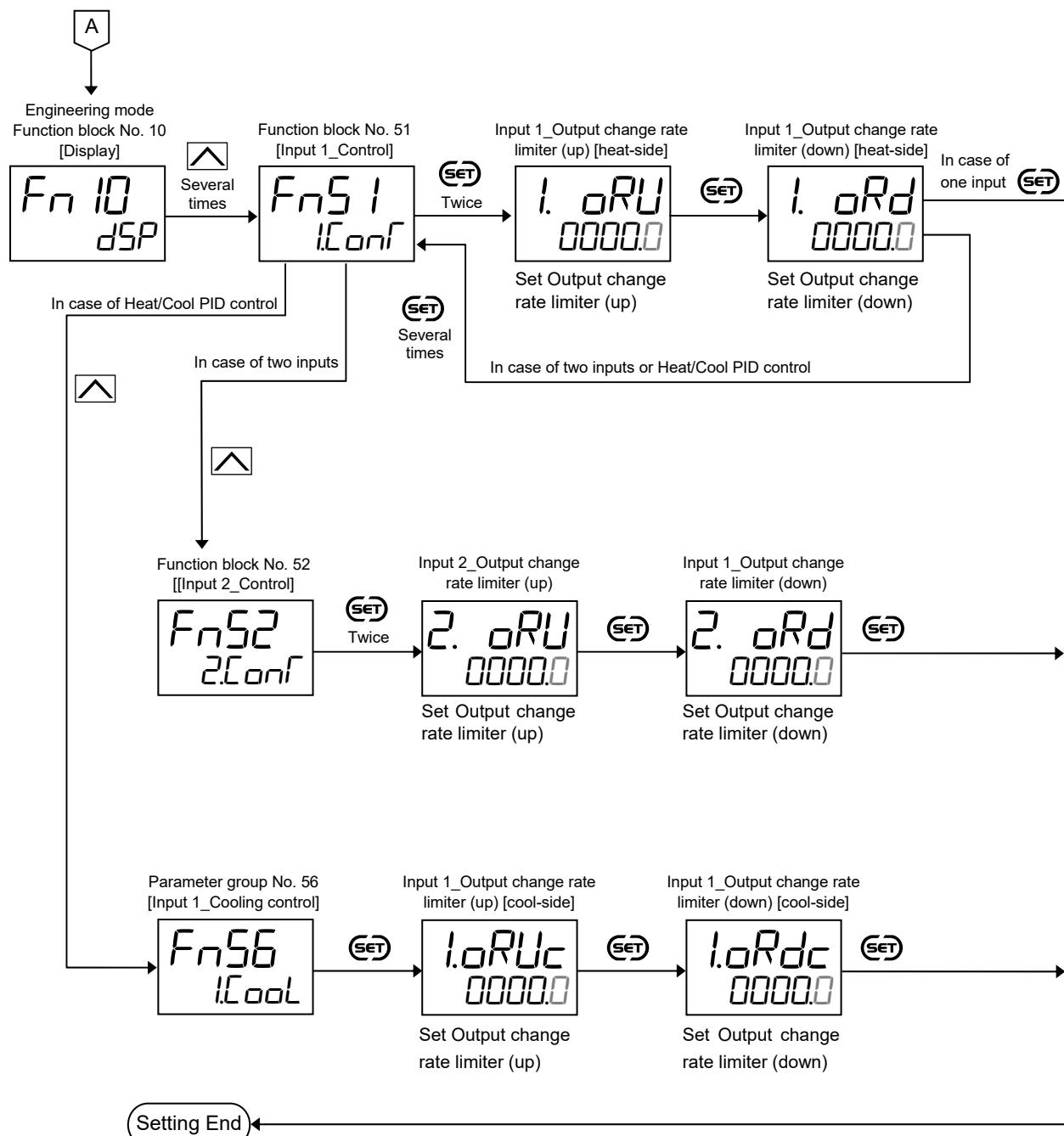
 To display “Input 1_Output change rate limiter (down) [cool-side],” specify Heat/Cool PID control at the time of order, or select Heat/Cool PID control at “Input 1_Control action” (Function block No. 51 in Engineering mode).

■ Setting procedure

To enter the Engineering mode



Continued from the previous page.



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

6.8 Suppressing Sudden Change in Output (Balanceless Bumpless)

Balanceless bumpless may be used to suppress sudden output change when the control is transferred from Auto mode to Manual mode (or Manual mode to Auto mode).

■ Description of function

Manipulated output value, when transferred from Auto mode to Manual mode, depends on the setting of “Manual manipulated output value selection.” Selection of “Use the most recent manipulated output value” (balanceless bumpless function) or “Use the Manual manipulated output value **” (bump action) can be selected in “Manual manipulated output value selection.”

* The Manual manipulated output value is the last manipulated output value in Manual mode before the mode is transferred from Auto mode to Manual mode.

Note that the Manual manipulated output value can be preset in advance in the Setup setting mode before the mode is transferred to Manual mode.

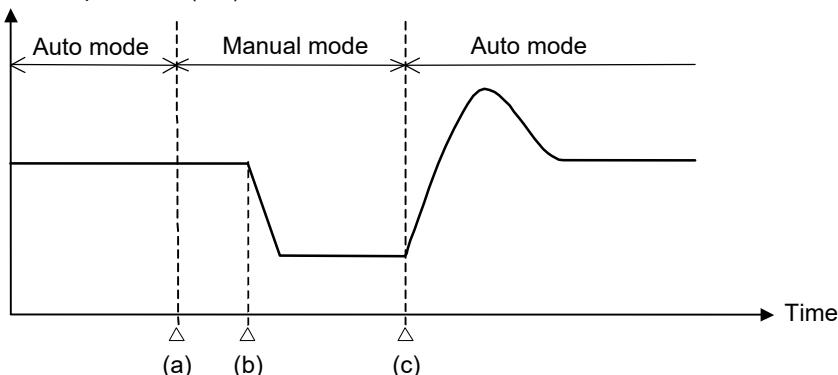


When the mode is transferred from Manual mode to Auto mode, the balanceless bumpless function is always activated.

● Balanceless bumpless function

This function is used to prevent overload caused by the Manipulated output value (MV) suddenly changing when Auto mode is transferred to Manual mode and vice versa.

Manipulated output value (MV)



- (a) Transfer from Auto mode to Manual mode.

However, when the mode is transferred to Manual mode, the Manipulated output value used in Auto mode will be used as the manual output value in Manual mode.

- (b) The manipulated output value is changed (Manual mode function)

- (c) Transfer from Manual mode to Auto mode.

When the mode is transferred to Auto mode, the controller starts PID control based on the MV used in Manual mode.

- Bumpless action associated with Auto/Manual transfer at the time of memory area selection

This instrument allows Auto/Manual transfer at the time of Memory area selection. Selection of balanceless bumpless action and bump action can be made at the time of Auto/Manual transfer.

[Parameters to set up]

- Auto/Manual transfer selection (Area)

This setting is used to select whether the mode should be transferred to Auto mode or Manual mode at the time of Memory area selection. This setting is also used to select balanceless bumpless action or bump action at the time of Auto/Manual transfer.

- Manipulated output value (Area)

This setting is used to set a manipulated output value when Bump action is selected at the time of Auto/Manual selection (area). This setting is used in Auto mode and Manual mode in common.



There are several ways to select a memory area.

Concerning the selection by key operation, see **10.3 Storing the Control Related Settings (Memory Area Function) (P. 10-10)** or **GZ400/GZ900 Quick Operation Manual (IMR03D02-E)**.

Concerning the selection by Digital input (DI), see **5.2 Switching Functions Using Digital Inputs (DI) (P. 5-16)**.

Concerning the selection by Memory area soak time, see **10.5 Executing Simple Program Operation (P. 10-18)** or **10.6 Executing Simple Sequence Operation (P. 10-26)**.



Bumpless/Bump action by “Auto/Manual transfer selection (Area)” has a priority over the Bumpless/Bump action by “Manual manipulated output value selection.”

■ Parameter setting

- **Manual manipulated output value selection**
[Engineering Mode: Function block No. 50 (Fn50)]

Parameter symbol	Data range	Factory set value
MVFS	0: The last manipulated output value (Balanceless bumpless function) 1: Manual manipulated output value	0

- **Input 1_Manual manipulated output value**
[Setup Setting Mode: Setting group No. 51 (S51)]

Parameter symbol	Data range	Factory set value
I. MMIV	PID control: Input 1_Output limiter low [heat-side] to Input 1_Output limiter high [heat-side] Heat/Cool PID control: -(Input 1_Output limiter high [cool-side]) to +(Input 1_Output limiter high [heat-side])	PID control: -5.0 Heat/Cool PID control: 0.0

* Heat/Cool PID control has exceptional conditions as follows for the data range.

- (1) Input 1_Output limiter high [cool-side] is $\leq 0.0\%$
 - Input 1_Output limiter low [heat-side] is $\leq 0.0\%:$ 0.0 % to +(Input 1_Output limiter high [heat-side])
 - Input 1_Output limiter low [heat-side] is $> 0.0\%:$ Input 1_Output limiter low [heat-side]
to Input 1_Output limiter high [heat-side]
- (2) Input 1_Output limiter high [heat-side] is $\leq 0.0\%$
 - Input 1_Output limiter low [cool-side] is $\leq 0.0\%:$ -(Input 1_Output limiter high [cool-side]) to 0.0 %
 - Input 1_Output limiter low [cool-side] is $> 0.0\%:$ -(Input 1_Output limiter high [cool-side])
to -(Input 1_Output limiter low [cool-side])
- (3) Fixed at 0.0% in the following cases:
Input 1_Output limiter high [cool-side] $\leq 0.0\%$, AND Input 1_Output limiter high [heat-side] $\leq 0.0\%$

- **Input 2_Manual manipulated output value**
[Setup Setting Mode: Setting group No. 52 (S52)]

Parameter symbol	Data range	Factory set value
I2. MMIV	Input 2_Output limiter low to Input 2_Output limiter high	-5.0



To display “Input 2_Manual manipulated output value,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

- **Input 1_Auto/Manual transfer selection (Area)**
[Parameter Setting Mode: Parameter group No. 70 (Pn70)]

Parameter symbol	Data range	Factory set value
IR / MR	0: No transfer 1: Auto mode (bumpless) 2: Auto mode (bump) 3: Manual mode (bumpless) 4: Manual mode (bump)	0



When the value is set and fixed to Auto mode at “Fix parameter setting: Auto/Manual transfer” in the Setting lock mode, data 3 and 4 in the above table cannot be set.

● **Input 1_Manipulated output value (Area)**
[Parameter Setting Mode: Parameter group No. 70 (P_{n70})]

Parameter symbol	Data range	Factory set value
$I. MV.R$	PID control: –5.0 to +105.0 % Heat/Cool PID control: –105.0 to +105.0 %	PID control: –5.0 Heat/Cool PID control:0.0

● **Input 2_Auto/Manual transfer selection (Area)**
[Parameter Setting Mode: Parameter group No. 70 (P_{n70})]

Parameter symbol	Data range	Factory set value
$2.R / M.R$	0: No transfer 1: Auto mode (bumpless) 2: Auto mode (bump) 3: Manual mode (bumpless) 4: Manual mode (bump)	0

-  To display “Input 2_Auto/Manual transfer selection (Area),” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.
-  When the value is set and fixed to Auto mode at “Fix parameter setting: Auto/Manual transfer” in the Setting lock mode, data 3 and 4 in the above table cannot be set.

● **Input 2_Manipulated output value (Area)**
[Parameter Setting Mode: Parameter group No. 70 (P_{n70})]

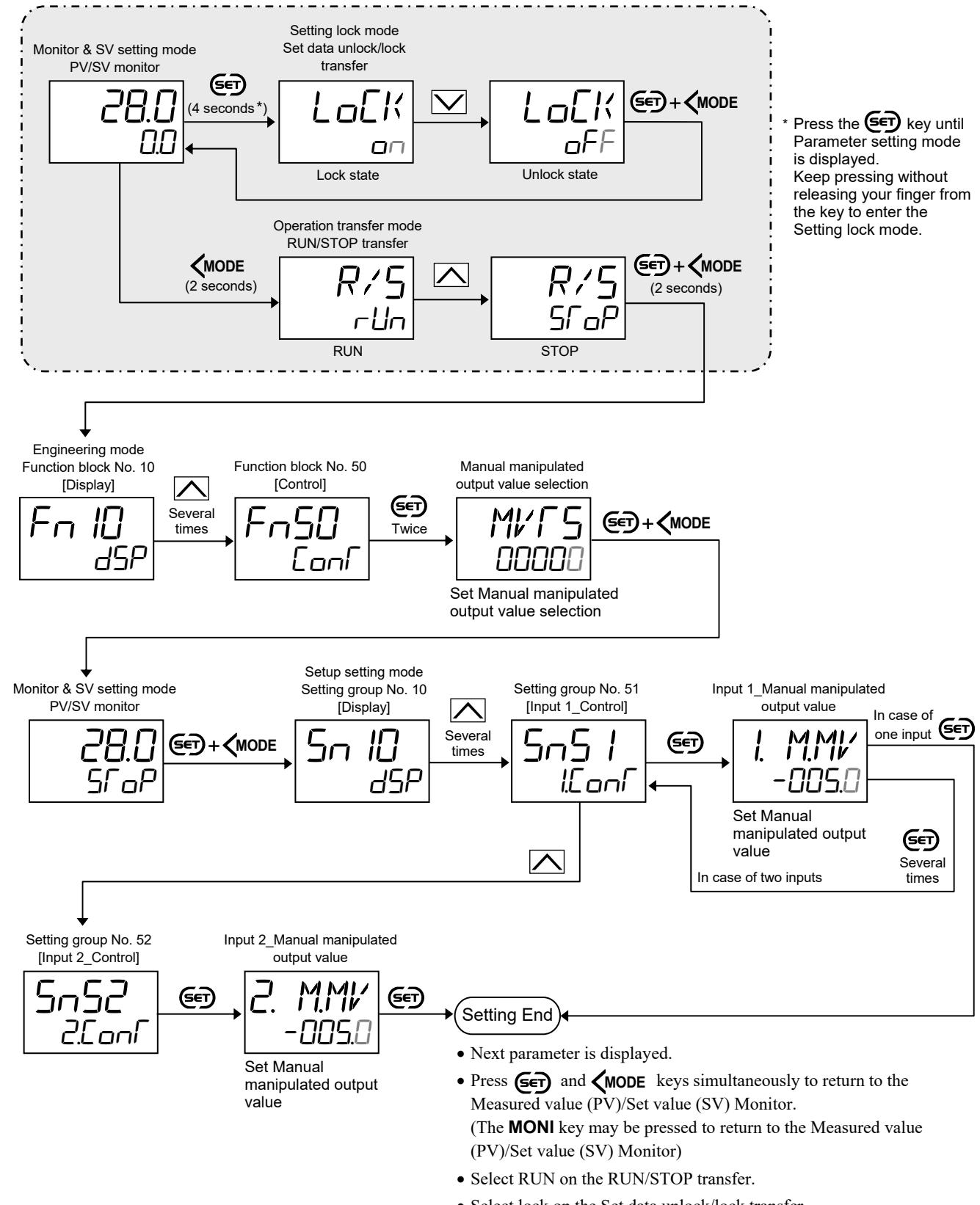
Parameter symbol	Data range	Factory set value
$2. MV.R$	–5.0 to +105.0 %	–5.0

-  To display “Input 2_Manipulated output value (Area),” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

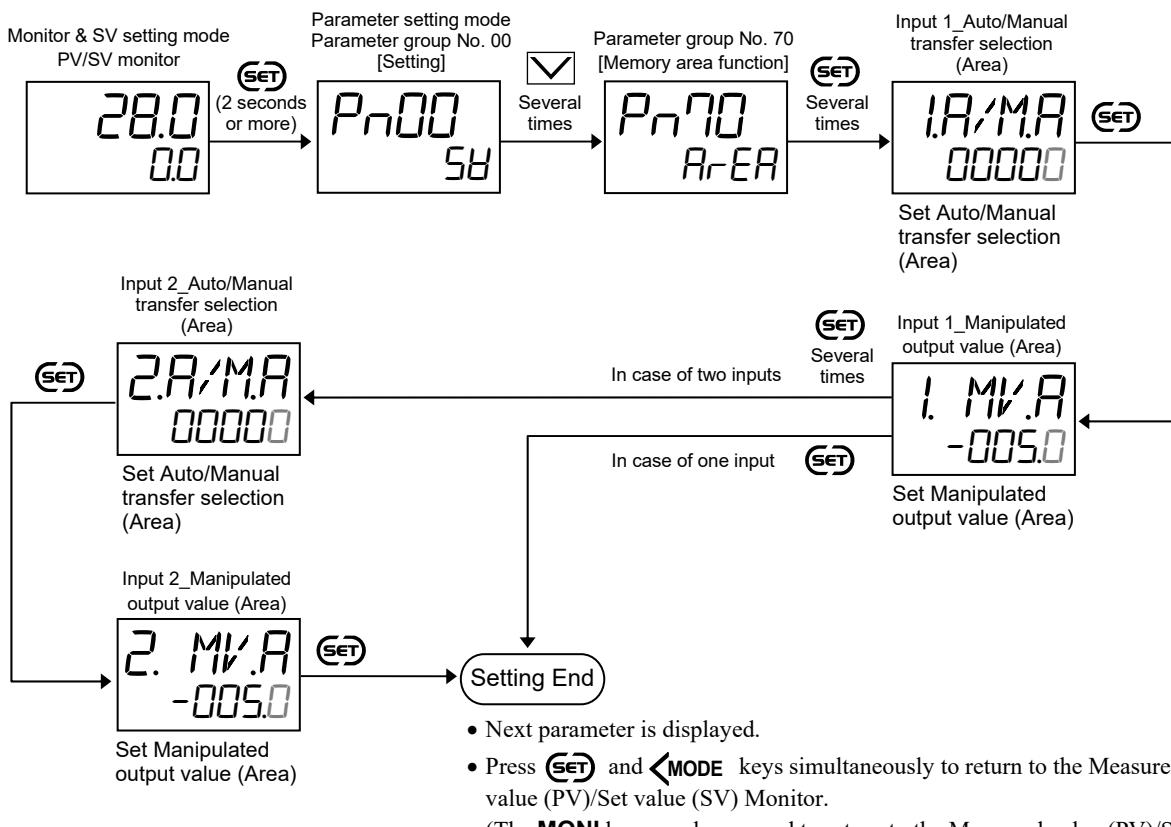
■ Setting procedure

- Setting “Manual manipulated output value selection” and “Manual manipulated output value”

To enter the Engineering mode



● Setting “Auto/Manual transfer selection (Area)” and “Manipulated output value (Area)”



- Next parameter is displayed.
- Press **SET** and **◀ MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

6.9 Changing the Output Action While in Control Stop Mode

This instrument can continue supplying Retransmission output and Event outputs, or output Manipulated output value, even while Control is stopped.

■ Description of function

The following three types can be continued to output even while in control stop mode. Multi types can be selected.

- Retransmission output
- Logic calculation output [Event, Heater break alarm (HBA), Input error status]
- Instrument Status Output [Manual mode, Remote mode, While Set value (SV) is changing, Communication monitoring result]



Continued output types while in Control stop cannot be selected by the output.

For example, this combination is not available:

Event 1: Continue to output even while in Control stop. Event 2: Output to be stopped.

Selection can be made in the unit of Retransmission output, Logic operation output, and Instrument status output.



Selecting “Logic calculation output: Action continues” as “Output action at control stop” will not include Control loop break alarm (LBA).

● Manipulated output value at STOP

Manipulated output value at STOP is a function to produce the preset manipulated output value at Control STOP. In the case of Heat/Cool PID control, Manipulated output value can be set on both sides of heating and cooling. Likewise, in case of a dual output type, manipulated output value can be set on both sides of Control output 1 and 2.

■ Parameter setting

● Output action at control stop

[Engineering Mode: Function block No. 30 (*Fn30*)]

Parameter symbol	Data range	Factory set value
55	0 to 7 0: OFF +1: Logic calculation output: Action continues +2: Retransmission output: Action continues +4: Instrument status output: Action continues To select two or more functions, sum each value.	0

● Input 1_Manipulated output value at STOP [heat-side]

[Engineering Mode: Function block No. 51 (*Fn51*)]

Parameter symbol	Data range	Factory set value
I. RMV	-5.0 to +105.0 %	-5.0

● **Input 2_Manipulated output value at STOP**
[Engineering Mode: Function block No. 52 (Fn52)]

Parameter symbol	Data range	Factory set value
2. RMV	-5.0 to +105.0 %	-5.0

 To display “Input 2_Manipulated output value at STOP,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

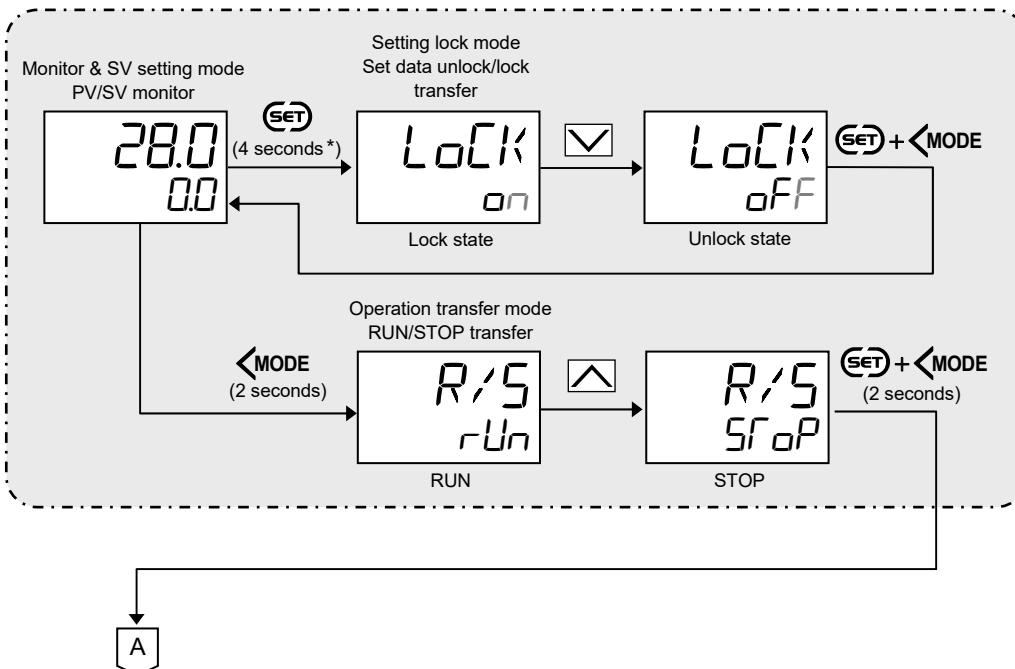
● **Input 1_Manipulated output value at STOP [cool-side]**
[Engineering Mode: Function block No. 56 (Fn56)]

Parameter symbol	Data range	Factory set value
1RMV_C	-5.0 to +105.0 %	-5.0

 To display “Input 1_Manipulated output value at STOP [cool-side],” specify Heat/Cool PID control at the time of order, or select Heat/Cool PID control at “Input 1_Control action” (Function block No. 51 in Engineering mode).

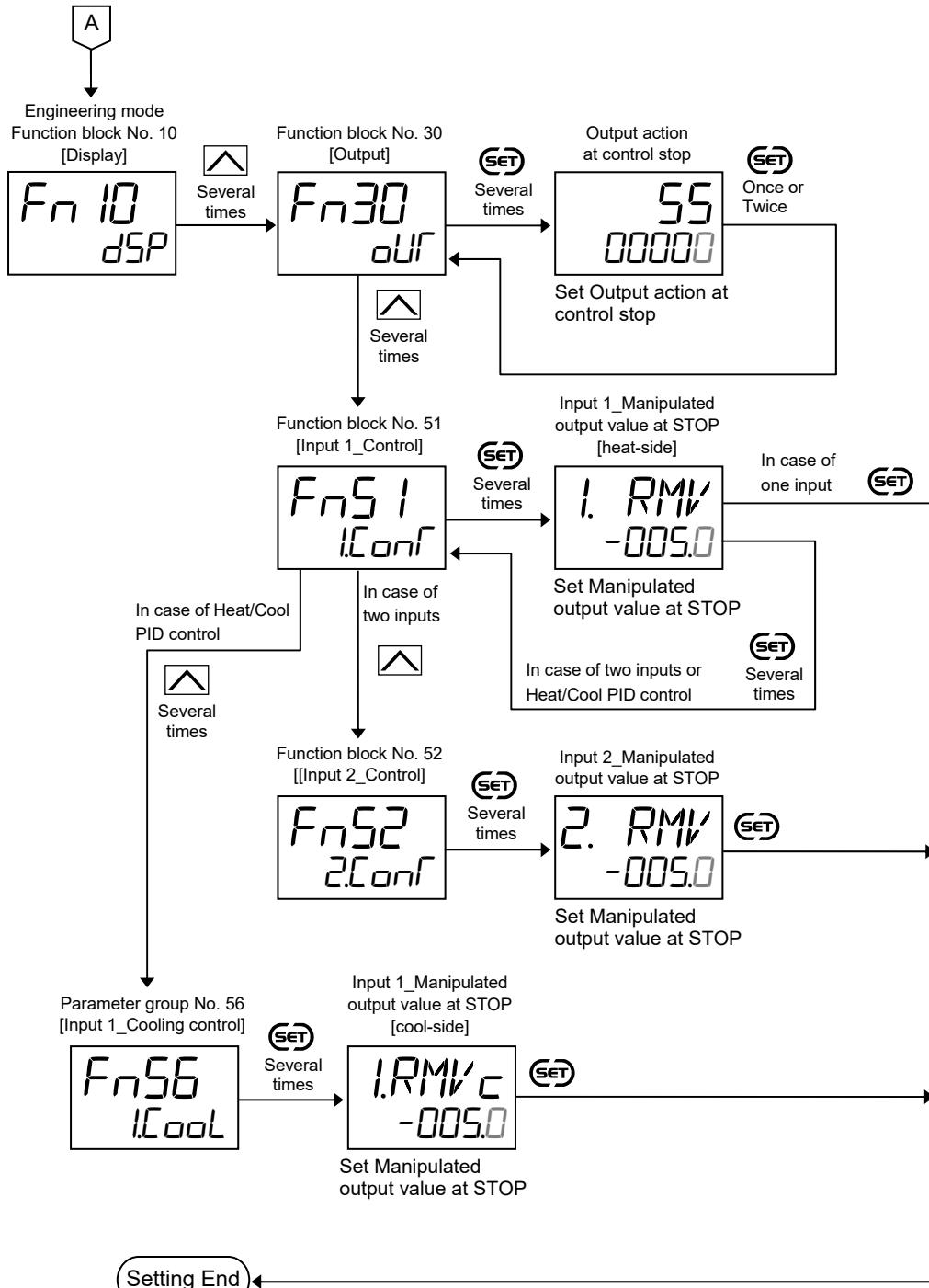
■ Setting procedure

To enter the Engineering mode



Continued on the next page.

Continued from the previous page.



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

6.10 Monitoring Manipulated Output Value

Manipulated output value can be monitored on this instrument.

■ Display contents

- **Input 1_Manipulated output value monitor [heat-side]
[Monitor & SV Setting Mode]**

Parameter symbol	Data range	Factory set value
I. MV	-5.0 to +105.0 %	

- **Input 1_Manipulated output value monitor [cool-side]
[Monitor & SV Setting Mode]**

Parameter symbol	Data range	Factory set value
I. MV_C	-5.0 to +105.0 %	



To display “Input 1_Manipulated output value monitor [cool-side],” specify Heat/Cool PID control at the time of order, or select Heat/Cool PID control at “Input 1_Control action” (Function block No. 51 in Engineering mode).

- **Input 2_Manipulated output value monitor
[Monitor & SV Setting Mode]**

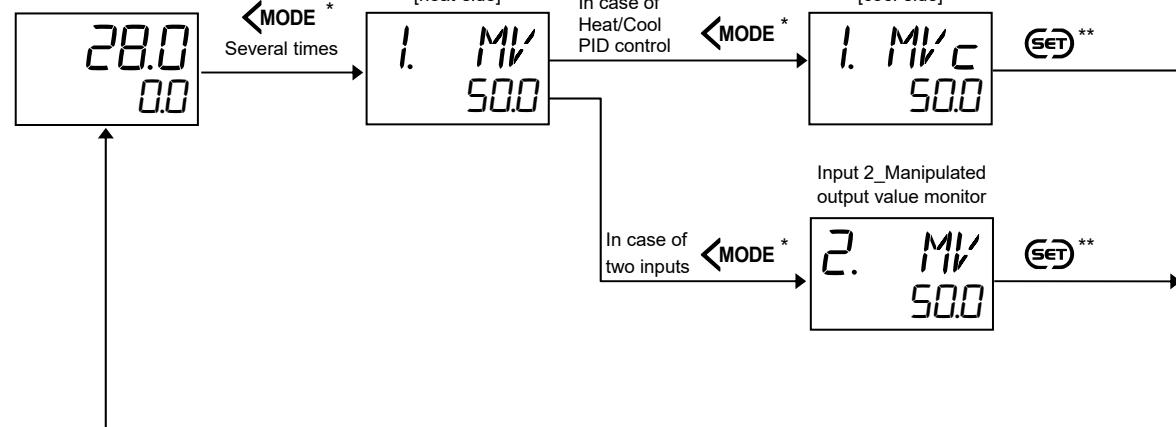
Parameter symbol	Data range	Factory set value
2. MV	-5.0 to +105.0 %	



To display “Input 2_Manipulated output value monitor,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

■ Display operation

Monitor & SV setting mode
PV/SV monitor



* MONI key may be used instead.

** R.SET key may be used to return.

MEMO

7

EVENT FUNCTION

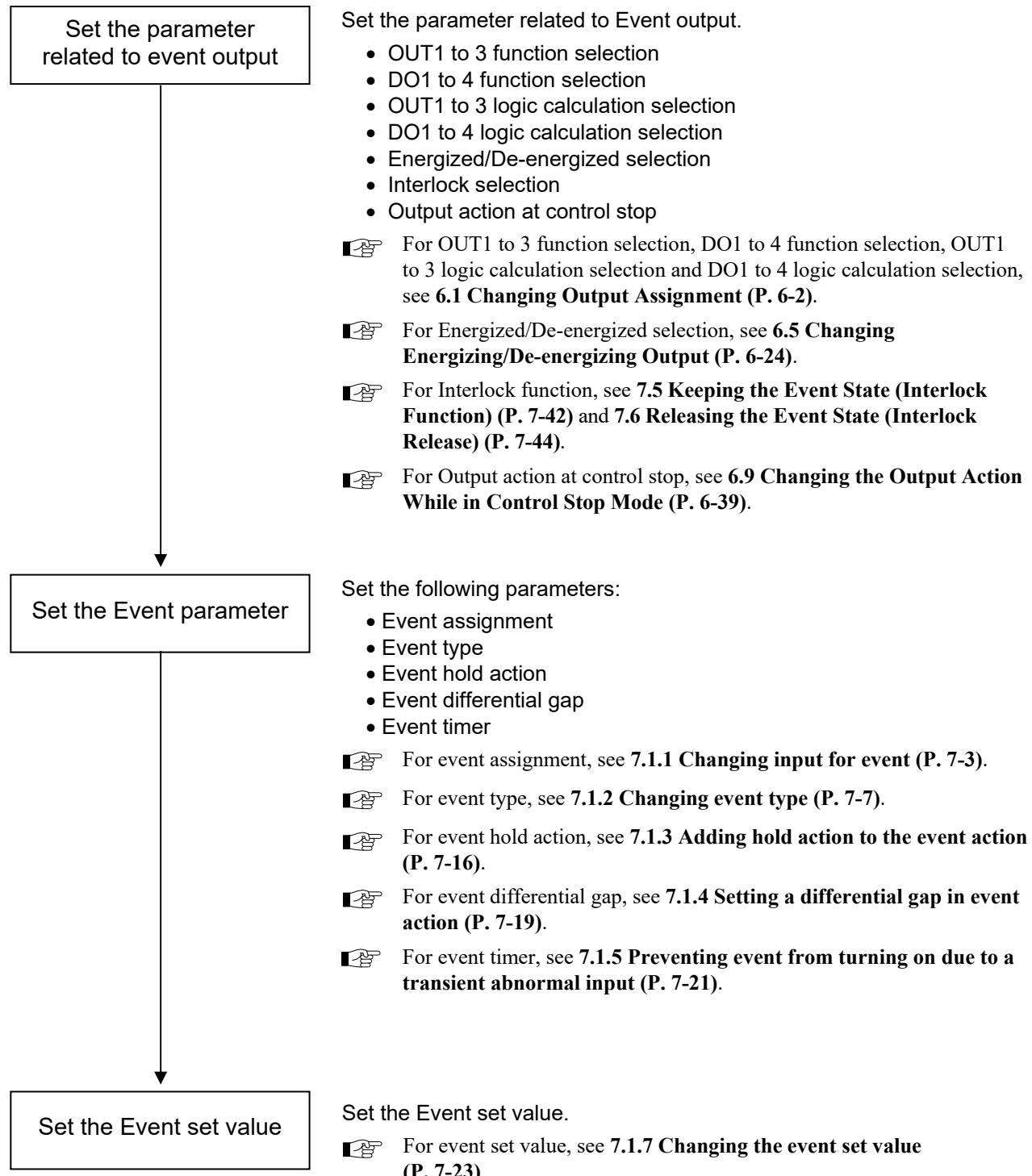
This chapter describes event related functions, setting contents and setting procedure based on the key words related to events.

7.1 Using Event Function	7-2
7.1.1 Changing input for event	7-3
7.1.2 Changing event type.....	7-7
7.1.3 Adding hold action to the event action.....	7-16
7.1.4 Setting a differential gap in event action.....	7-19
7.1.5 Preventing event from turning on due to a transient abnormal input.....	7-21
7.1.6 Changing event output assignment.....	7-23
7.1.7 Changing the event set value	7-23
7.2 Using Heater Break Alarm (HBA).....	7-24
7.2.1 Setting the Heater break alarm (HBA) set value	7-25
7.2.2 Preventing Heater break alarm (HBA) from turning on due to a transient abnormal input.....	7-28
7.2.3 Changing the output monitored by the Heater break alarm (HBA)....	7-30
7.2.4 Changing the Current transformer (CT) type	7-33
7.2.5 Forcing the CT input value to 0.0 A when the heater is OFF	7-35
7.3 Using Control Loop Break Alarm (LBA)	7-36
7.4 Checking Event ON State	7-40
7.5 Keeping the Event State (Interlock Function).....	7-42
7.6 Releasing the Event State (Interlock Release).....	7-44
7.7 Preventing Control with Input Errors (Input Circuit Error Alarm)....	7-46

7.1 Using Event Function

■ Setting procedure for event function

Set event as follows:



7.1.1 Changing input for event

On this instrument input signal can be individually set for each event.

- Input 1
- Input 2
- Differential temperature input

■ Description of function

There are four action available for event; Deviation action, Input value action, Set value action, and Manipulated output value action.

Each event uses its own value.

● Deviation action

For Input 1: Deviation = Input 1_Measured value (PV) – Input 1_Set value (SV)

For Input 2: Deviation = Input 2_Measured value (PV) – Input 2_Set value (SV)

For Differential temperature input: Deviation = Measured value (PV) of differential temperature input – Set value (SV) of differential temperature input

● Input value action

For Input 1: Input value = Input 1_Measured value (PV)

For Input 2: Input value = Input 2_Measured value (PV)

For Differential temperature input: Input value = Measured value (PV) of differential temperature input

● Set value action

For Input 1: Set value = Input 1_Set value (SV)

For Input 2: Set value = Input 2_Set value (SV)

For Differential temperature input: Set value = Set value (SV) of differential temperature input

● Manipulated output value action

For Input 1: Manipulated output value = Input 1_Manipulated output value (MV)

For Input 2: Manipulated output value = Input 2_Manipulated output value (MV)

For Differential temperature input: Manipulated output value = Input 1_Manipulated output value (MV)



In the case of Control with PV select, the event target is only “for Input 1” in any of the above actions. (The Event 1 to 4 assignment screens are not displayed)

The data used at this time are the Measured value (PV) of the PV select, Input 1_Set value (SV), and Input 1_Manipulated output value (MV).

■ Parameter setting

● Event 1 assignment

[Engineering Mode: Function block No. 41 (Fn4 I)]

Parameter symbol	Data range	Factory set value
EVA1	1: Input 1 2: Input 2 3: Differential temperature input	1



To display “Event 1 assignment,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.



See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the Event 1 assignment is changed.

● Event 2 assignment

[Engineering Mode: Function block No. 42 (Fn42)]

Parameter symbol	Data range	Factory set value
EVRA2	1: Input 1 2: Input 2 3: Differential temperature input	1

 To display “Event 2 assignment,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

 See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the Event 2 assignment is changed.

● Event 3 assignment

[Engineering Mode: Function block No. 43 (Fn43)]

Parameter symbol	Data range	Factory set value
EVRA3	1: Input 1 2: Input 2 3: Differential temperature input	1

 To display “Event 3 assignment,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

 See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the Event 3 assignment is changed.

● Event 4 assignment

[Engineering Mode: Function block No. 44 (Fn44)]

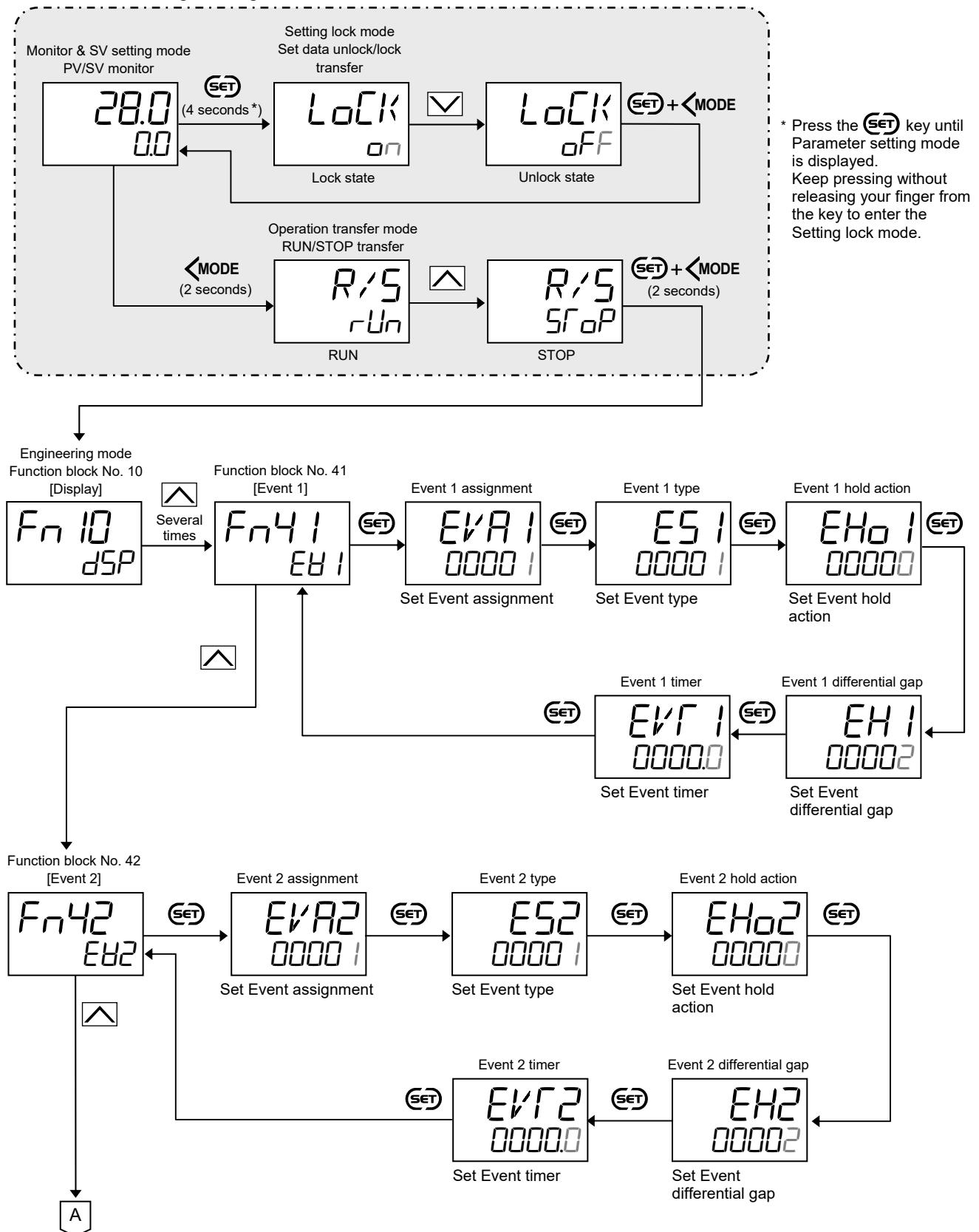
Parameter symbol	Data range	Factory set value
EVRA4	1: Input 1 2: Input 2 3: Differential temperature input	1

 To display “Event 4 assignment,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

 See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the Event 4 assignment is changed.

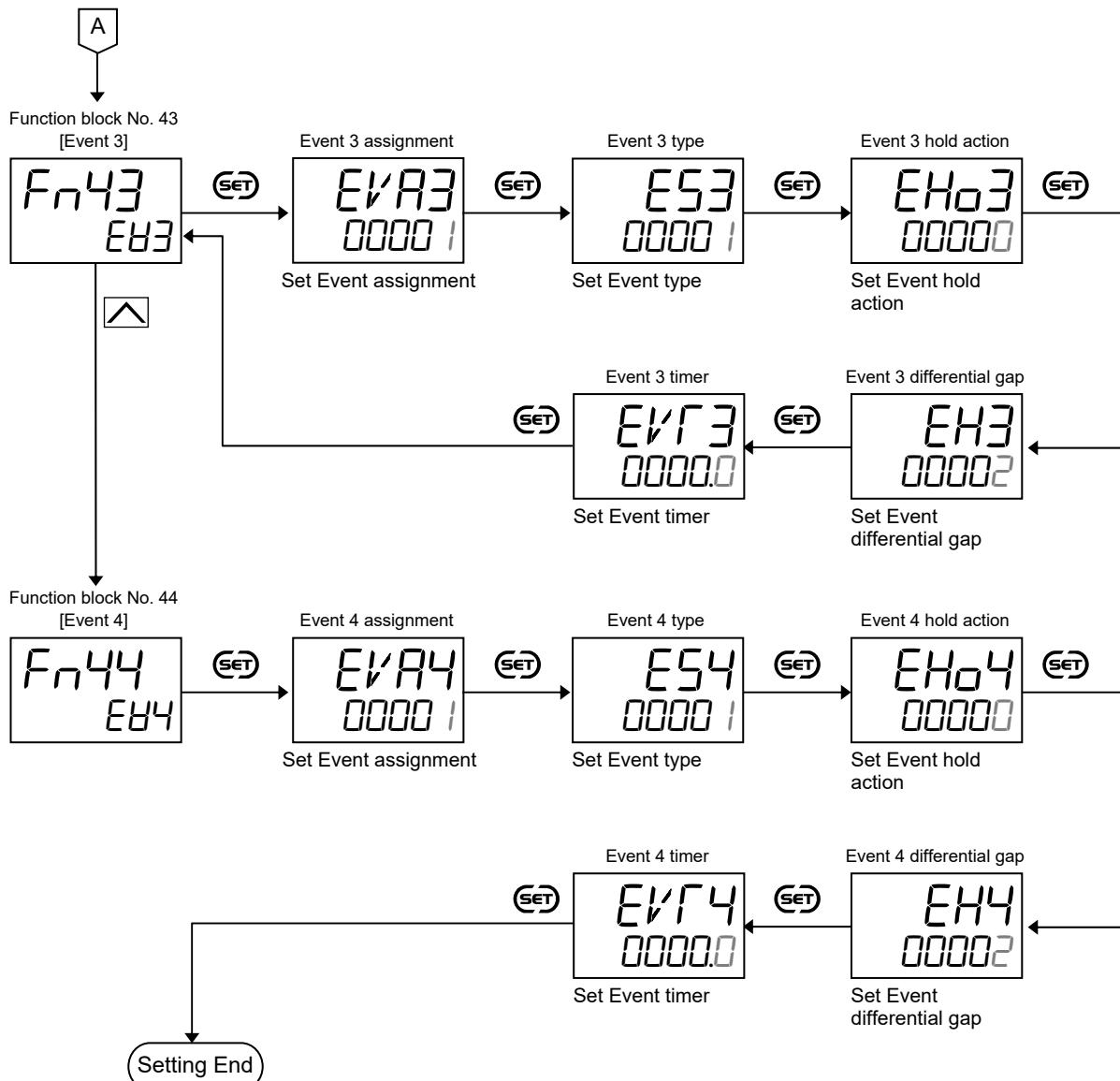
■ Setting procedure

To enter the Engineering mode



Continued on the next page.

Continued from the previous page.



- Next parameter is displayed.
 - Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
 - Select RUN on the RUN/STOP transfer.
 - Select lock on the Set data unlock/lock transfer.

7.1.2 Changing event type

There are 24 types of event in total.

- Event type

Set value	Event type	Initial setting code
0	None	N
1	Deviation high (using SV monitor value) ¹	A, E (with hold action), Q (with re-hold action)
2	Deviation low (using SV monitor value) ¹	B, F (with hold action), R (with re-hold action)
3	Deviation high/low (using SV monitor value) ¹	C, G (with hold action), T (with re-hold action)
4	Band (using SV monitor value) ¹	D
5	Deviation high/low (using SV monitor value) [High/Low individual setting] ¹	X, Y (with hold action), Z (with re-hold action)
6	Band (using SV monitor value) [High/Low individual setting] ¹	U
7	SV high (using SV monitor value)	V
8	SV low (using SV monitor value)	W
9	Process high ²	H, K (with hold action)
10	Process low ²	J, L (with hold action)
11	Deviation high (using local SV) ¹	—
12	Deviation low (using local SV) ¹	—
13	Deviation high/low (using local SV) ¹	—
14	Band (using local SV) ¹	—
15	Deviation high/low (using local SV) [High/Low individual setting] ¹	—
16	Band (using local SV) [High/Low individual setting] ¹	—
17	SV high (using local SV)	—
18	SV low (using local SV)	—
19	MV high [heat-side] ²	1
20	MV low [heat-side] ²	2
21	MV high [cool-side] ²	3
22	MV low [cool-side] ²	4
23	Process high/low [High/Low individual setting] ²	—
24	Process band [High/Low individual setting] ²	—

¹ Event hold and re-hold action is available.

² Event hold action is available.

■ Description of function

● Deviation action

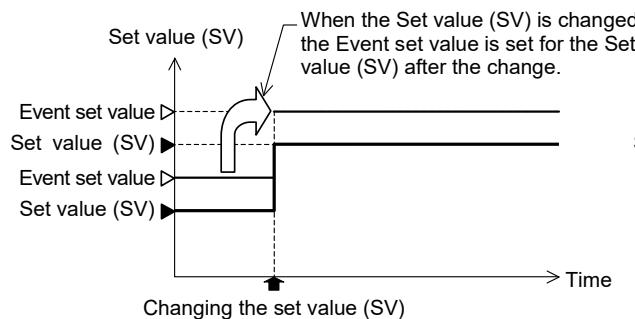
When the deviation (PV – SV) reaches the Event set value, event ON occurs.

SV monitor value type and local SV value type are available for Deviation action.

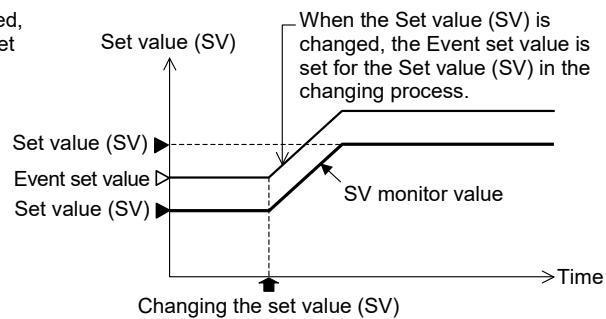
SV monitor value type	<p>The Event set value is set for the SV monitor value. Setting change rate limiter adjusts the Event set value to follow the same change rate of SV monitor value.</p> <p>SV monitor value: SV monitor value is displayed in the Measured value (PV)/Set value (SV) monitor screen (Monitor & SV setting mode). When Setting change rate limiter is set, the Set value (SV) in the changing process is displayed.</p>
Local SV type	<p>The Event set value is set for the Set value (SV) [Local SV].</p> <p>Local SV: Local SV is displayed in the Measured value (PV)/Set value (SV) screen (Monitor & SV setting mode).</p>

SV monitor value type

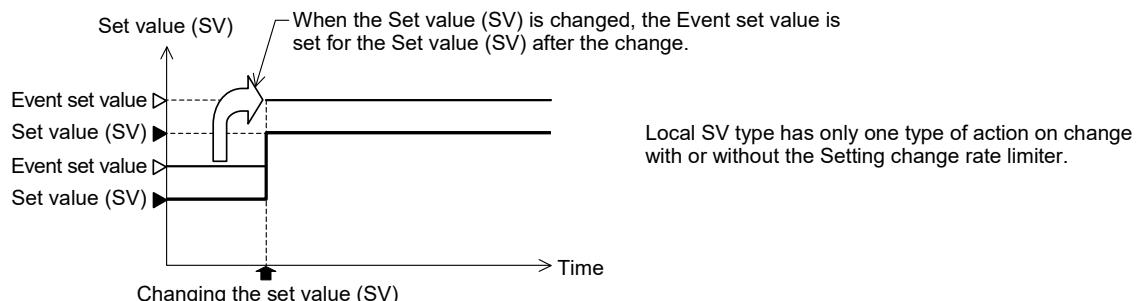
[When setting change rate limiter is not set.]



[When setting change rate limiter is set.]



Local SV type



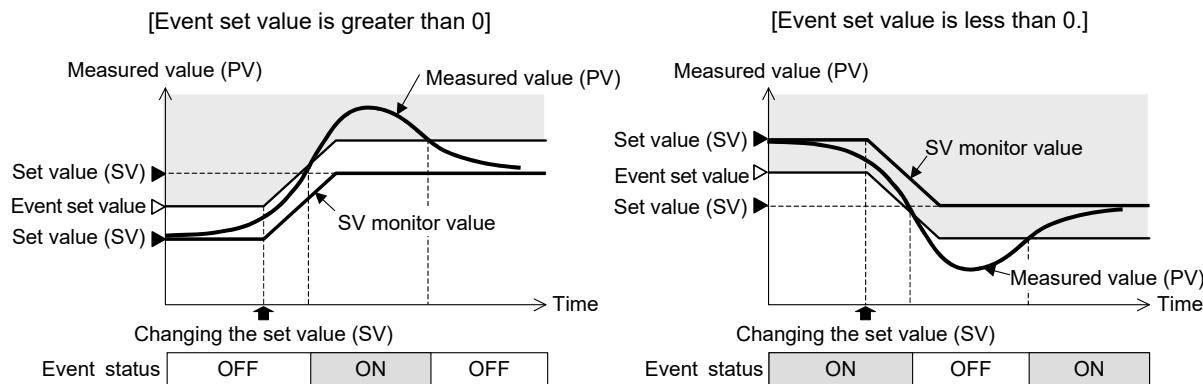
For the Setting change rate limiter, see **10.2 Eliminating a Sudden Set Value Change (Setting Change Rate Limiter) (P. 10-6)**.

Some examples of Deviation high are described in the following:

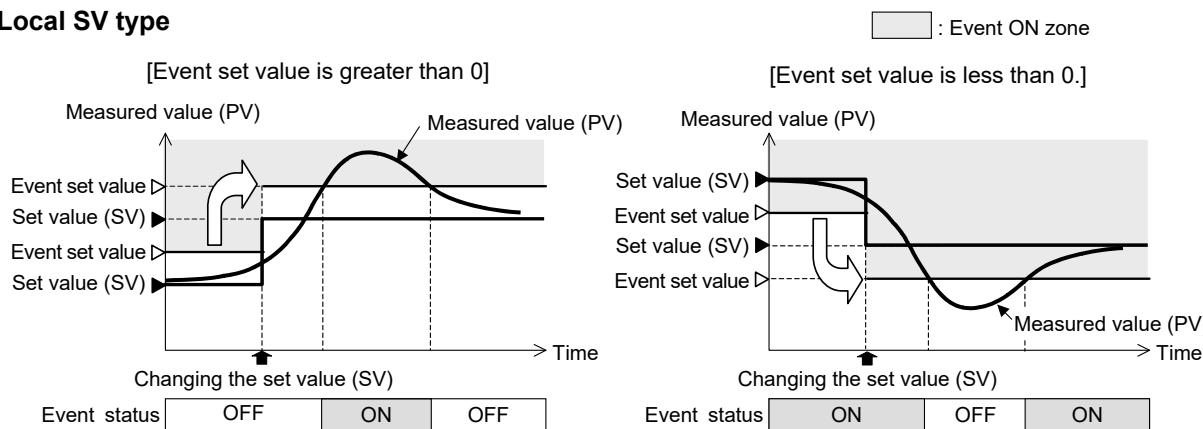
Deviation high: When the deviation ($PV - SV$) is more than the Event set value, the event ON occurs.

SV monitor value type

(Example: When setting change rate limiter is set.)



Local SV type



- ☞ Event turns ON or OFF in accordance with the differential gap setting. For Event differential gap, see **7.1.4 Setting a differential gap in event action (P. 7-19)**.

Diagrams of the Deviation action type are shown in the following:

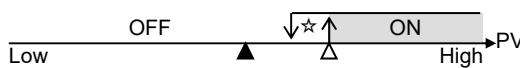
ON: Event action turned on

OFF: Event action turned off (▲: Set value (SV) △: Event set value ☆: Event differential gap)

Deviation high

When the deviation ($PV - SV$) is more than the Event set value, the event ON occurs.

(Event set value is greater than 0.)



(Event set value is less than 0.)



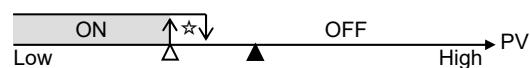
Deviation low

When the deviation ($PV - SV$) is less than the Event set value, the event ON occurs.

(Event set value is greater than 0.)



(Event set value is less than 0.)



Deviation high/low

Two types of Deviation high/low action are available.

Without high/low individual setting:

When the absolute deviation $|PV - SV|$ is more/less than the Event set value, the event ON occurs.

With high/low individual setting:

High action: When the deviation ($PV - SV$) is more than the Event set value [high], the event ON occurs.

Low action: When the deviation ($PV - SV$) is less than the Event set value [low], the event ON occurs.

(Without High/Low individual setting)



(With High/Low individual setting)



Band

Two types of Band action are available.

Without high/low individual setting:

When the absolute deviation $|PV - SV|$ is within the Event set value, the event ON occurs.

With high/low individual setting:

High action: When the deviation ($PV - SV$) is less than the Event set value [high], the event ON occurs.

Low action: When the deviation ($PV - SV$) is more than the Event set value [low], the event ON occurs.

(Without High/Low individual setting)



(With High/Low individual setting)



● Set value action

When the Set value (SV) reaches the Event set value, event ON occurs.

SV monitor value type and local SV value type are available for Set value action.

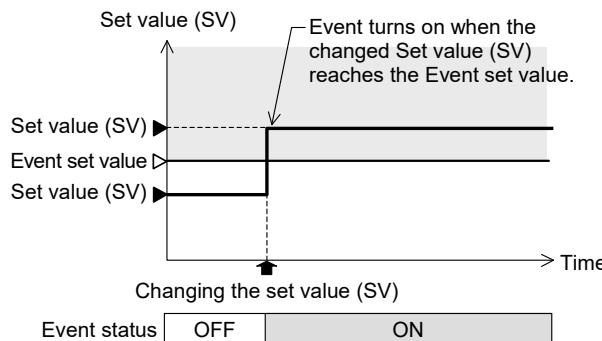
SV monitor value type	<p>Event turns on when SV monitor value reaches Event set value. Setting change rate limiter turns on the event when the Set value (SV) in the changing process reaches Event set value.</p> <p>SV monitor value: SV monitor value is displayed in the Measured value (PV)/Set value (SV) monitor screen (Monitor display mode). When Setting change rate limiter is set, the Set value (SV) in the changing process is displayed.</p>
Local SV type	<p>Event turns on when Set value (SV) [Local SV] reaches Event set value.</p> <p>Local SV: Local SV is displayed in the Measured value (PV)/Set value (SV) screen (SV setting mode).</p>

Some examples of SV high are described in the following:

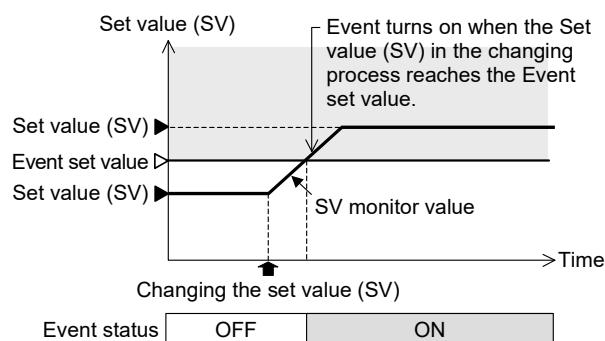
SV high: When the Set value (SV) is more than the Event set value, the event ON occurs.

SV monitor value type

[When setting change rate limiter is not set.]

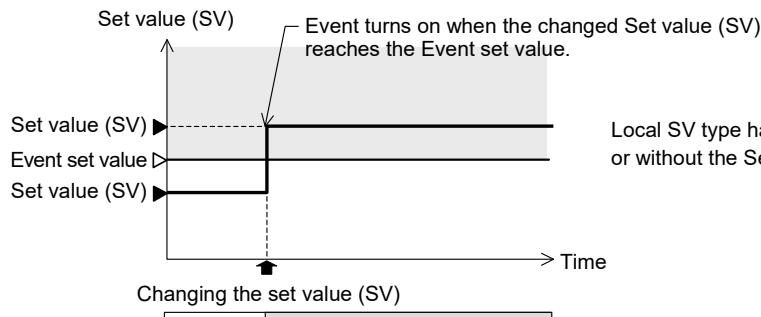


[When setting change rate limiter is set.]



Local SV type

: Event ON zone



Local SV type has only one type of action on a change with or without the Setting change rate limiter.

- ☞ Event turns ON or OFF in accordance with the differential gap setting. For Event differential gap, see **7.1.4 Setting a differential gap in event action (P. 7-19)**.

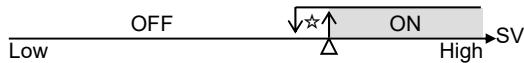
Diagrams of the Set value action type are shown in the following:

ON: Event action turned on

OFF: Event action turned off (Δ: Event set value ☆: Event differential gap)

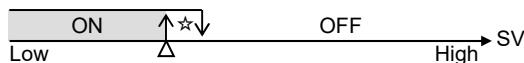
SV high

When the Set value (SV) is more than the Event set value, the event ON occurs.



SV low

When the Set value (SV) is less than the Event set value, the event ON occurs.



● Input value action

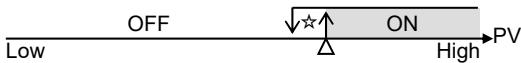
When the Measured value (PV) reaches the Event set value, event ON occurs.

ON: Event action turned on

OFF: Event action turned off (Δ: Event set value ☆: Event differential gap)

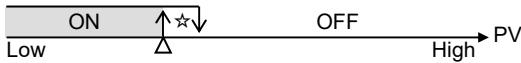
Process high

When the Measured value (PV) is more than the Event set value, the event ON occurs.



Process low

When the Measured value (PV) is less than the Event set value, the event ON occurs.



Process high/low

Process high/low action can be modified to high and low individual setting.

High action: When the Measured value (PV) is more than the Event set value [high], the event ON occurs.

Low action: When the Measured value (PV) is less than the Event set value [low], the event ON occurs.

(With High/Low individual setting)



Process band

Process band action can be modified to high and low individual setting.

High action: When the Measured value (PV) is less than the Event set value [high], the event ON occurs.

Low action: When the Measured value (PV) is more than the Event set value [low], the event ON occurs.

(With High/Low individual setting)



● Manipulated output value action

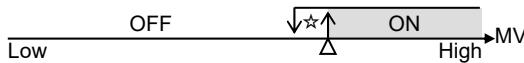
When a Manipulated output value (MV) reaches the Event set value, the event ON occurs.

ON: Event action turned on

OFF: Event action turned off (Δ: Event set value ☆: Event differential gap)

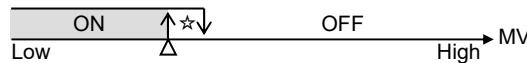
MV high

When the Manipulated output value (MV) is more than the Event set value, the event ON occurs.



MV high

When the Manipulated output value (MV) is less than the Event set value, the event ON occurs.



■ Parameter setting

● Event 1 type

[Engineering Mode: Function block No. 41 (Fn41)]

Parameter symbol	Data range	Factory set value
<i>E51</i>	0: None 1: Deviation high (Using SV monitor value) ^a 2: Deviation low (Using SV monitor value) ^a 3: Deviation high/low (Using SV monitor value) ^a 4: Band (Using SV monitor value) ^a 5: Deviation high/low (Using SV monitor value) [High/Low individual setting] ^a 6: Band (Using SV monitor value) [High/Low individual setting] ^a 7: SV high (Using SV monitor value) 8: SV low (Using SV monitor value) 9: Process high ^b 10: Process low ^b 11: Deviation high (Using local SV) ^a 12: Deviation low (Using local SV) ^a 13: Deviation high/low (Using local SV) ^a 14: Band (Using local SV) ^a 15: Deviation high/low (Using local SV) [High/Low individual setting] ^a 16: Band (Using local SV) [High/Low individual setting] ^a 17: SV high (Using local SV) 18: SV low (Using local SV) 19: MV high [heat-side] ^b 20: MV low [heat-side] ^b 21: MV high [cool-side] ^b 22: MV low [cool-side] ^b 23: Process high/low [High/Low individual setting] ^b 24: Process band [High/Low individual setting] ^b	If the Event type is specified by the initial setting code when ordering, that Event type will be the factory set value. If the Event type is not specified: 1

^a Event hold and re-hold action is available.

^b Event hold action is available.



See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the Event 1 type is changed.

● Event 2 type

[Engineering Mode: Function block No. 42 (Fn42)]

Parameter symbol	Data range	Factory set value
E52	Same as Event 1 type (P. 7-14)	If the Event type is specified by the initial setting code when ordering, that Event type will be the factory set value. If the Event type is not specified: 1



See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the Event 2 type is changed.

● Event 3 type

[Engineering Mode: Function block No. 43 (Fn43)]

Parameter symbol	Data range	Factory set value
E53	Same as Event 1 type (P. 7-14)	If the Event type is specified by the initial setting code when ordering, that Event type will be the factory set value. If the Event type is not specified: 1



See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the Event 3 type is changed.

● Event 4 type

[Engineering Mode: Function block No. 44 (Fn44)]

Parameter symbol	Data range	Factory set value
E54	Same as Event 1 type (P. 7-14)	If the Event type is specified by the initial setting code when ordering, that Event type will be the factory set value. If the Event type is not specified: 1



See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the Event 4 type is changed.

■ Setting procedure

See the operation on P. 7-5.

7.1.3 Adding hold action to the event action

On this instrument hold action or re-hold action can be added to the Event action.



Some event actions may not be available with hold and re-hold actions. Setting hold or re-hold action on the event that is not available with hold and re-hold actions will just be ignored.



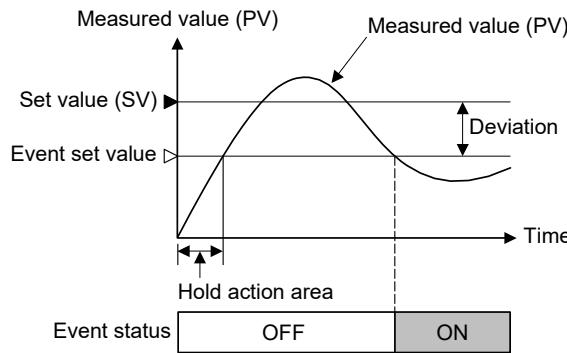
See Setting of Event types (P.7-14) for those events that are available with hold or re-hold action.

■ Description of function

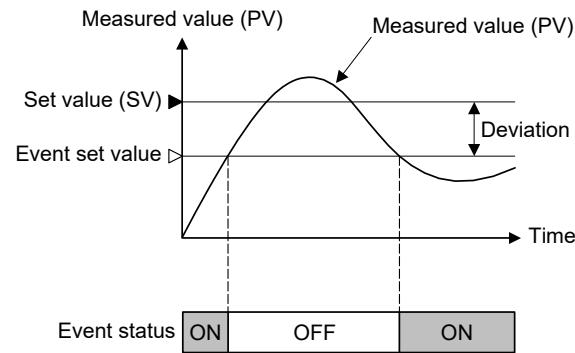
● Hold action

When hold action is ON, the event action is suppressed at start-up or STOP to RUN until the measured value has entered the non-event range.

[With hold action]



[Without hold action]



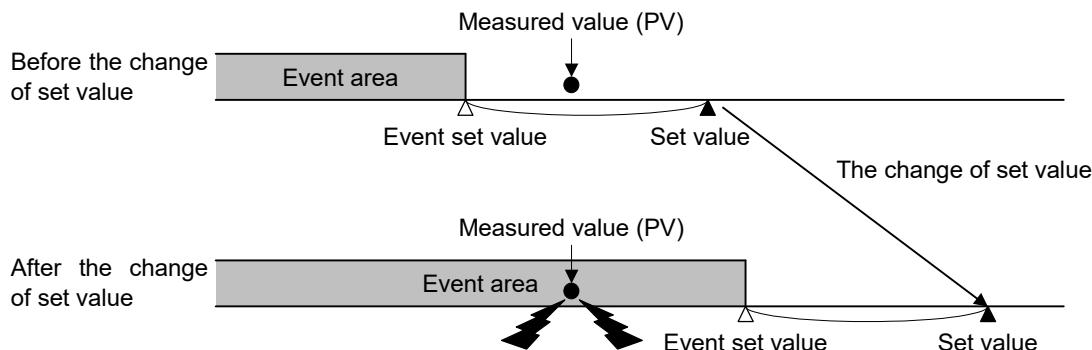
● Re-hold action

When Re-hold action is ON, the event action is also suppressed at the Set value (SV) change until the Measured value (PV) has entered the non-event range.

Action condition	Hold action	Re-hold action
When the power is turned on	Works	Works
When transferred from STOP (control STOP) to RUN (control RUN)	Works	Works
When the Set value (SV) is changed	Does not work	Works

[Example] When Event 1 type is the deviation low:

When re-hold action is OFF and event output type is deviation, the event output is produced due to the Set value (SV) change. The re-hold action suppresses the alarm output until the measured value has entered the non-event range again.



NOTE
When high alarm with hold action/re-hold action is used for Event function, alarm does not turn on while hold action is in operation. Take measures to prevent overheating which may occur if the control device fails.



The re-hold action is invalid for any of the following.

- Setting of Setting change rate limiter is other than “0 (no function)”
- Remote mode
- Differential temperature control

■ Parameter setting

● Event 1 hold action

[Engineering Mode: Function block No. 41 (Fn41)]

Parameter symbol	Data range	Factory set value
EHo1	0: Hold action OFF 1: Hold action ON 2: Re-hold action ON Setting hold or re-hold action on the event that is not available with hold and re-hold actions will just be ignored.	If the Event type is specified by the initial setting code when ordering, the factory set value of Event hold action differs depending on the Event type. If the Event type is not specified: 0

● Event 2 hold action

[Engineering Mode: Function block No. 42 (Fn42)]

Parameter symbol	Data range	Factory set value
$EHo2$	0: Hold action OFF 1: Hold action ON 2: Re-hold action ON Setting hold or re-hold action on the event that is not available with hold and re-hold actions will just be ignored.	If the Event type is specified by the initial setting code when ordering, the factory set value of Event hold action differs depending on the Event type. If the Event type is not specified: 0

● Event 3 hold action

[Engineering Mode: Function block No. 43 (Fn43)]

Parameter symbol	Data range	Factory set value
$EHo3$	0: Hold action OFF 1: Hold action ON 2: Re-hold action ON Setting hold or re-hold action on the event that is not available with hold and re-hold actions will just be ignored.	If the Event type is specified by the initial setting code when ordering, the factory set value of Event hold action differs depending on the Event type. If the Event type is not specified: 0

● Event 4 hold action

[Engineering Mode: Function block No. 44 (Fn44)]

Parameter symbol	Data range	Factory set value
$EHo4$	0: Hold action OFF 1: Hold action ON 2: Re-hold action ON Setting hold or re-hold action on the event that is not available with hold and re-hold actions will just be ignored.	If the Event type is specified by the initial setting code when ordering, the factory set value of Event hold action differs depending on the Event type. If the Event type is not specified: 0

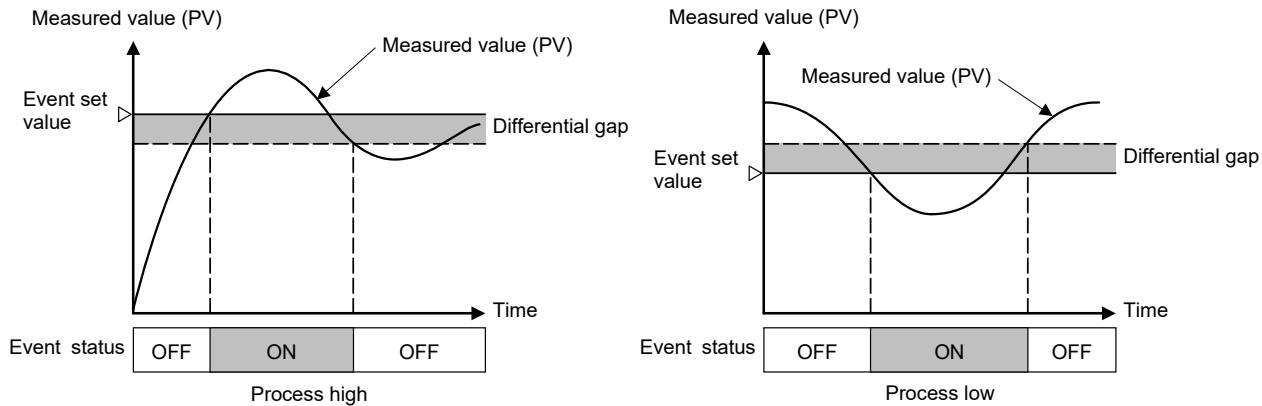
■ Setting procedure

See the operation on P. 7-5.

7.1.4 Setting a differential gap in event action

■ Description of function

It prevents chattering of event output due to the measured value fluctuation around the Event set value.



■ Parameter setting

● Event 1 differential gap

[Engineering Mode: Function block No. 41 (Fn41)]

Parameter symbol	Data range	Factory set value
$EH1$	Deviation, Process and SV: <ul style="list-style-type: none"> If event assignment is either Input 1 or Differential temperature. 0 to Input 1_Input span (When Control with PV select: 0 to PV select input span) If event assignment is Input 2 0 to Input 2_Input span [Varies with the setting of the Decimal point position.] MV: 0.0 to 110.0 % 	Deviation, Process and SV: TC/RTD inputs: 2 V/I inputs: 0.2 % of input span MV: 0.2

● Event 2 differential gap

[Engineering Mode: Function block No. 42 (Fn42)]

Parameter symbol	Data range	Factory set value
$EH2$	Same as Event 1 differential gap (P. 7-19)	Deviation, Process and SV: TC/RTD inputs: 2 V/I inputs: 0.2 % of input span MV: 0.2

● Event 3 differential gap

[Engineering Mode: Function block No. 43 (F_{n43})]

Parameter symbol	Data range	Factory set value
EH3	Same as Event 1 differential gap (P. 7-19)	Deviation, Process and SV: TC/RTD inputs: 2 V/I inputs: 0.2 % of input span MV: 0.2

● Event 4 differential gap

[Engineering Mode: Function block No. 44 (F_{n44})]

Parameter symbol	Data range	Factory set value
EH4	Same as Event 1 differential gap (P. 7-19)	Deviation, Process and SV: TC/RTD inputs: 2 V/I inputs: 0.2 % of input span MV: 0.2

■ Setting procedure

See the operation on P. 7-5.

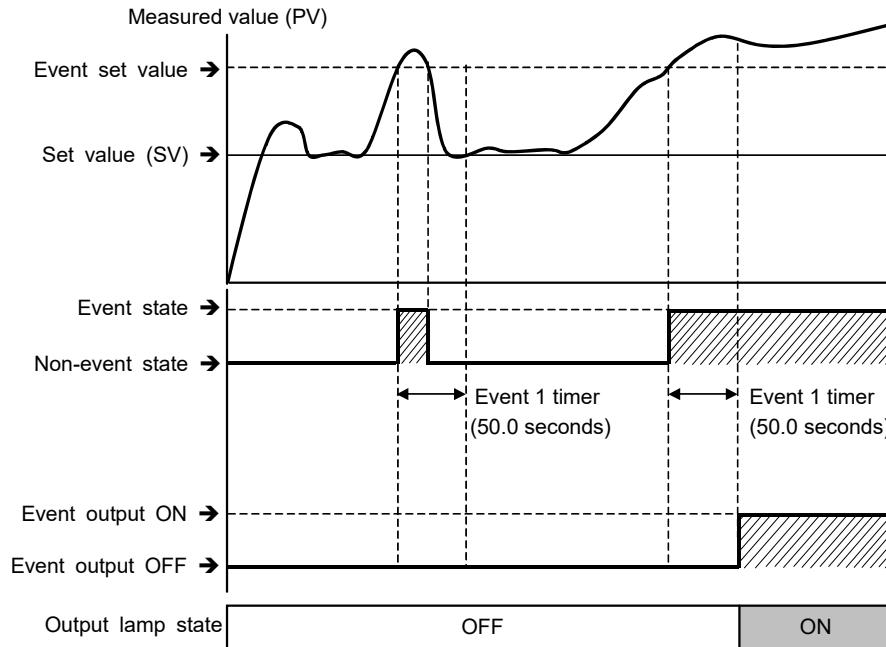
7.1.5 Preventing event from turning on due to a transient abnormal input

Event timer can be used to prevent event from turning on for the event state shorter than the set time.

■ Description of function

When an event condition becomes ON, the output is suppressed until the Event timer set time elapses. If the event output is still ON after time is up, the output will resume.

Example: When the setting of Event 1 timer is 50.0 seconds



The Event timer is also activated for the following reasons:

- When set to the event state simultaneously with power turned on
- When set to the event state simultaneously with control changed to RUN (control start) from STOP (control stop).



In the event wait state, no event output is turned on even after the Event timer preset time has elapsed.



The Event timer is reset for the following reasons:

- When power failure occurs while the Event timer is being activated
- When control is changed to STOP (control stop) from RUN (control start) while the Event timer is being activated *
- Cancellation of Event state

* Event timer will not be reset by switching to the STOP (control stop) when logical operation output (OUT1 to OUT3 logic calculation selection) is selected for an Event and "logic calculation output: Action continues" is set for the Output action in Reset mode.

■ Parameter setting

● Event 1 timer

[Engineering Mode: Function block No. 41 (F_{n41})]

Parameter symbol	Data range	Factory set value
$EVR1$	0.0 to 600.0 seconds	0.0

● Event 2 timer

[Engineering Mode: Function block No. 42 (F_{n42})]

Parameter symbol	Data range	Factory set value
$EVR2$	0.0 to 600.0 seconds	0.0

● Event 3 timer

[Engineering Mode: Function block No. 43 (F_{n43})]

Parameter symbol	Data range	Factory set value
$EVR3$	0.0 to 600.0 seconds	0.0

● Event 4 timer

[Engineering Mode: Function block No. 44 (F_{n44})]

Parameter symbol	Data range	Factory set value
$EVR4$	0.0 to 600.0 seconds	0.0

■ Setting procedure

See the operation on P. 7-5.

7.1.6 Changing event output assignment

Event output assignment can be changed through OUT1 to 3 function selection, DO1 to 4 function selection, OUT1 to 3 logic calculation selection, and DO1 to 4 logic calculation selection.

Depending on the ordered specifications, there may be some restrictions in the event output assignment.

-  For Event output assignment, see **6.1 Changing Output Assignment [Control Output, Retransmission Output, Logic Calculation (Event) Output, Instrument Status Output] (P. 6-2)**.

7.1.7 Changing the event set value

The Event set value can be set in Parameter group No. 40 in the Parameter setting mode.

Since the Set value for Event 1 to 4 are included in the Memory area, up to 16 data can be stored per parameter.

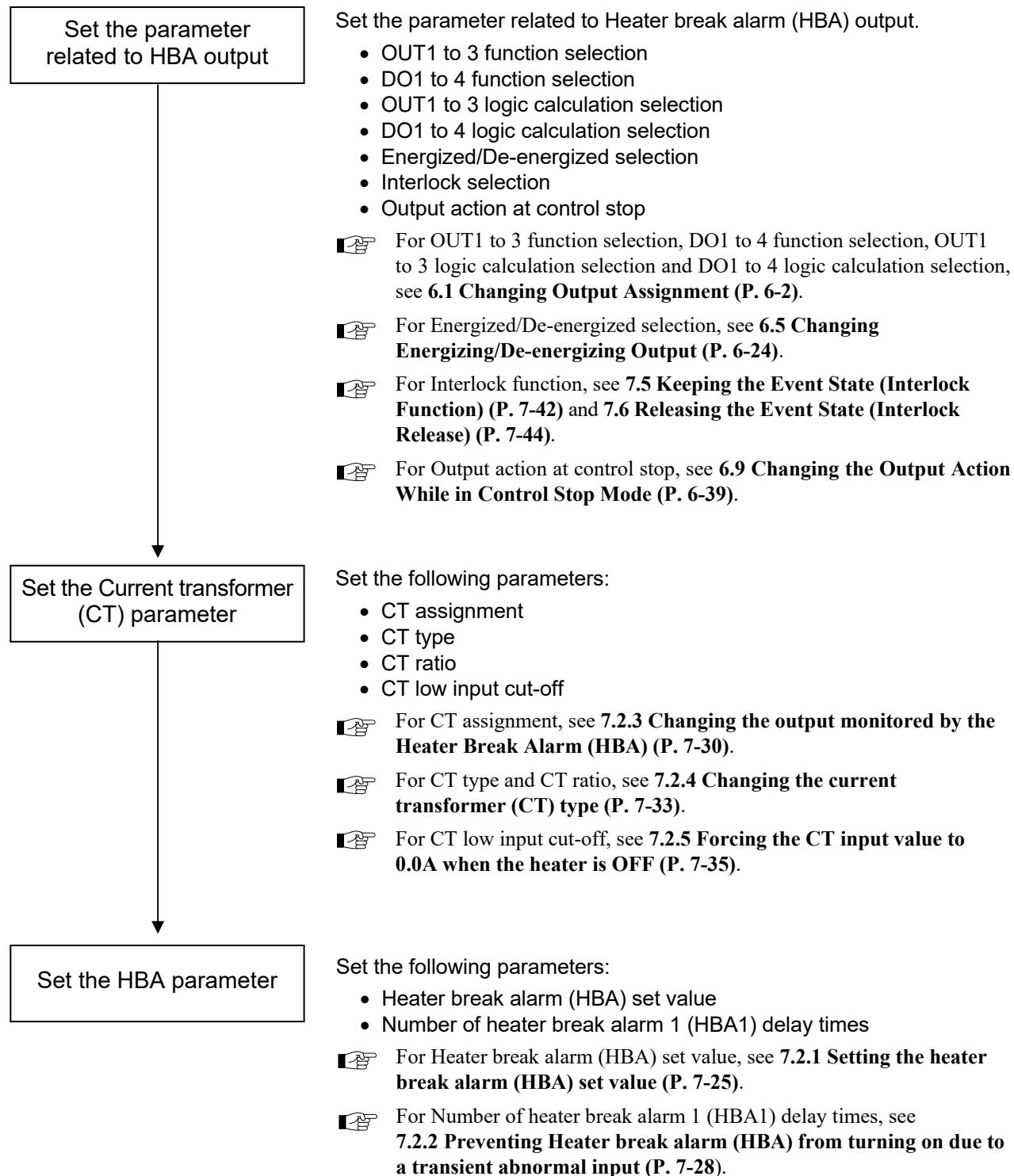
-  For detailed operation on how to set Event set values, refer to **GZ400/GZ900 Quick operation manual (IMR03D02-E)** or **GZ400/GZ900 Instruction Manual [Part 1: Hardware] (IMR03D04-E)**.

Details of Memory area transfer can be found in **10.3 Storing the control related set values (Memory Area function) (P. 10-10)**.

7.2 Using Heater Break Alarm (HBA)

■ Setting procedure for Heater break alarm (HBA)

Set Heater break alarm (HBA) as follows:



7.2.1 Setting the Heater break alarm (HBA) set value

■ Description of function

● Heater break alarm (HBA)

Heater break alarm (HBA) can only be used with time-proportional control output (relay or voltage pulse output).

The Heater break alarm (HBA) function monitors the current flowing through the load by a dedicated current transformer (CT), then compares the measured value with the Heater break alarm (HBA) set values, and detects a fault in the heating circuit.

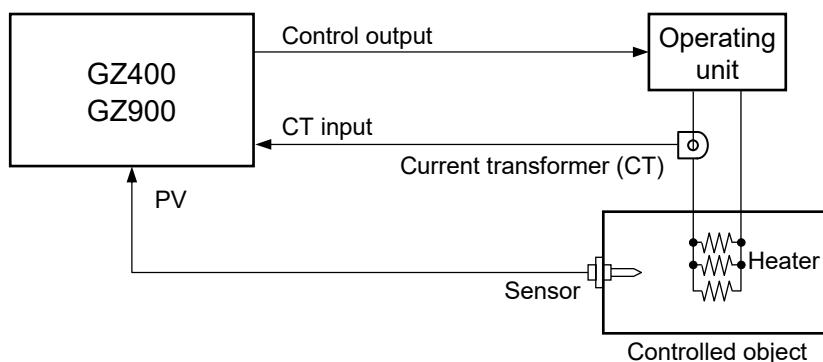
The Heater break alarm (HBA) function is activated for the following cases:

- ① Low or No current flow (Heater break, malfunction of the control device, etc.):

When the control output is ON and the CT input value is equal to or less than the heater break determination point for the preset number of consecutive sampling cycles, an alarm is activated.

- ② Over current or short-circuit:

When the control output is OFF and the CT input value is equal to or greater than the heater break determination point for the preset number of consecutive sampling cycles, an alarm is activated.



[Setting Heater Break Alarm]

Set the HBA set value to approximately 85 % of the maximum reading of the CT input.

Set the HBA set value to a slightly smaller value to prevent a false alarm if the power supply becomes unstable. When more than one heater is connected in parallel, the HBA set value may need to be increased to detect a single heater failure.

When a set value of Heater Break Alarm (HBA) is set, the CT input value is displayed on the MV display and it may be helpful to set an alarm value.

[Display example]

PV display	Hba 1	Parameter of Heater break alarm 1 (HBA1) set value
SV display	64.0	Heater break alarm 1 (HBA1) set value
MV display	75.3	Current transformer 1 (CT1) input value

- BOOK When Heater break alarm 1 (HBA1) is set, the display shows the input value of the Current transformer 1 (CT1). When Heater break alarm 2 (HBA2) is set, the display shows the input value of the Current transformer 2 (CT2).
- BOOK The data to be displayed on the MV display can be selected at “Show/Hide MV” in Function block 10 in Engineering mode. When the Heater break alarm (HBA) is displayed, the MV display shows the Current transformer (CT) input value.

■ Parameter setting

● Heater break alarm 1 (HBA1) set value

[Setup Setting Mode: Setting group No. 45 (5n45)]

Parameter symbol	Data range	Factory set value
HbA1	0.0 to 100.0 A 0.0: HBA function OFF	0.0

-  To display “Heater break alarm 1 (HBA1) set value,” “CT input” must be specified at the time of order.
-  This parameter is not displayed if “no assignment” is set at “CT1 assignment” in Function block 45 in Engineering mode. If the output type assigned at “CT1 assignment” is Current output or Continuous voltage output, this parameter will not be displayed.

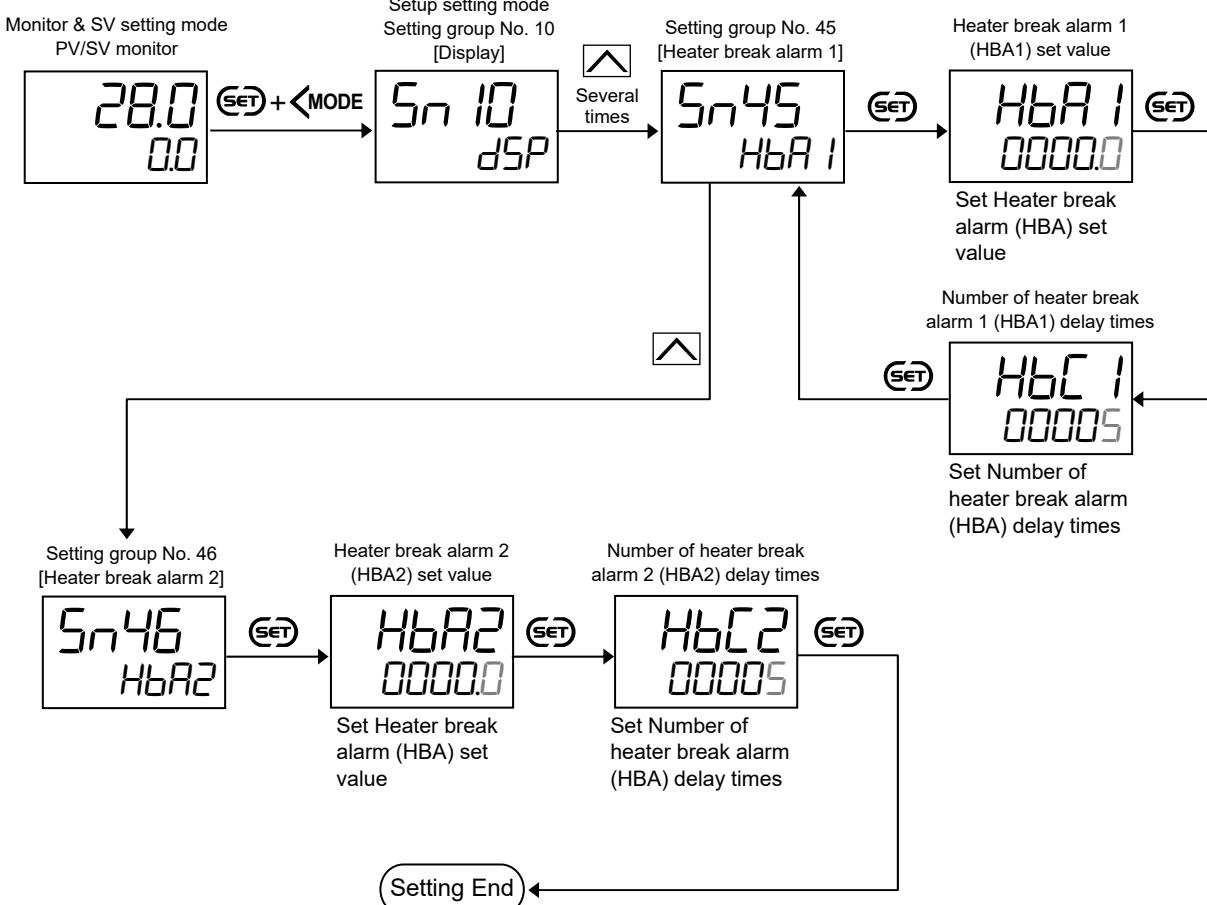
● Heater break alarm 2 (HBA2) set value

[Setup Setting Mode: Setting group No. 46 (5n46)]

Parameter symbol	Data range	Factory set value
HbA2	0.0 to 100.0 A 0.0: HBA function OFF	0.0

-  To display “Heater break alarm 2 (HBA2) set value,” “CT input” must be specified at the time of order. (When CT input is specified, two CT inputs are supplied.)
-  This parameter is not displayed if “no assignment” is set at “CT2 assignment” in Function block 46 in Engineering mode. If the output type assigned at “CT2 assignment” is Current output or Continuous voltage output, this parameter will not be displayed.

■ Setting procedure



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

7.2.2 Preventing Heater break alarm (HBA) from turning on due to a transient abnormal input

There is a function called HBA delay time which suppresses the alarm when the Heater break alarm (HBA) state is less than the setting (the number of sampling).

■ Description of function

● Number of HBA delay times

This is a function to allow the Heater break alarm (HBA) to turn on if the Heater break alarm (HBA) ON condition continues beyond the setting (the number of sampling).

Heater break alarm (HBA) delay times = Number of HBA delay times × Sampling time *

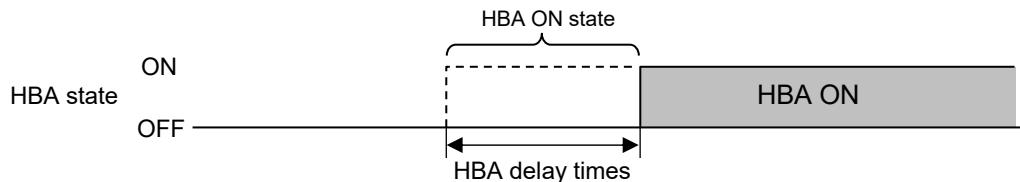
*The sampling cycle time is the shortest. It varies with the load factor (Output ON or OFF time).

Example:

Sampling cycle: 0.5 seconds

Number of HBA delay times: 5 times (Factory set value)

$$\text{HBA delay times} = 5 \text{ times} \times 0.5 \text{ seconds} = 2.5 \text{ seconds}$$



■ Parameter setting

● Number of heater break alarm 1 (HBA1) delay times [Setup Setting Mode: Setting group No. 45 (5n45)]

Parameter symbol	Data range	Factory set value
HbC1	0 to 255 times	5

-  To display “Number of heater break alarm 1 (HBA1) delay times,” “CT input” must be specified at the time of order.
-  This parameter is not displayed if “no assignment” is set at “CT1 assignment” in Function block 45 in Engineering mode. If the output type assigned at “CT1 assignment” is Current output or Continuous voltage output, this parameter will not be displayed.

● Number of heater break alarm 2 (HBA2) delay times

[Setup Setting Mode: Setting group No. 46 (5n46)]

Parameter symbol	Data range	Factory set value
HbC2	0 to 255 times	5

-  To display “Number of heater break alarm 2 (HBA2) delay times,” “CT input” must be specified at the time of order. (When CT input is specified, two CT inputs are supplied.)
-  This parameter is not displayed if “no assignment” is set at “CT2 assignment” in Function block 46 in Engineering mode. If the output type assigned at “CT2 assignment” is Current output or Continuous voltage output, this parameter will not be displayed.

■ Setting procedure

See the operation on P. 7-27.

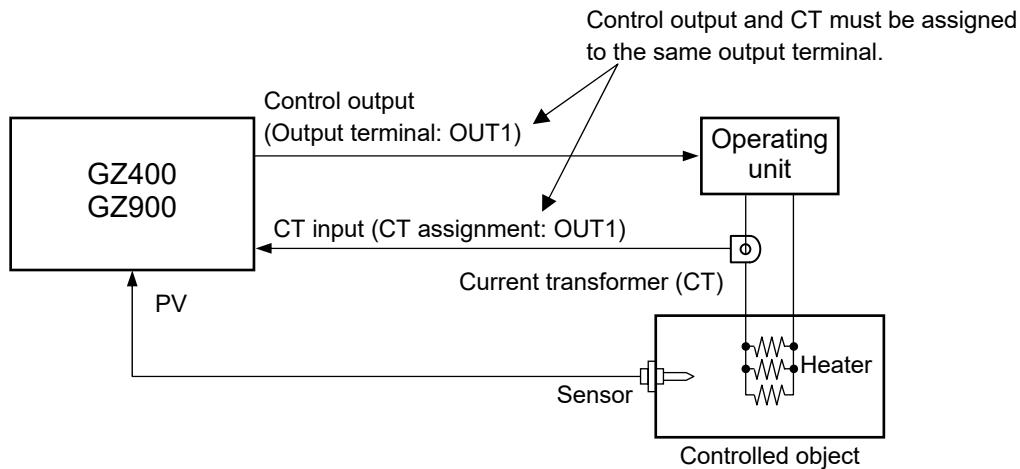
7.2.3 Changing the output monitored by the Heater break alarm (HBA)

Assignment of control output monitored by Current transformer (CT) used with Heater break alarm (HBA) can be changed.

■ Description of function

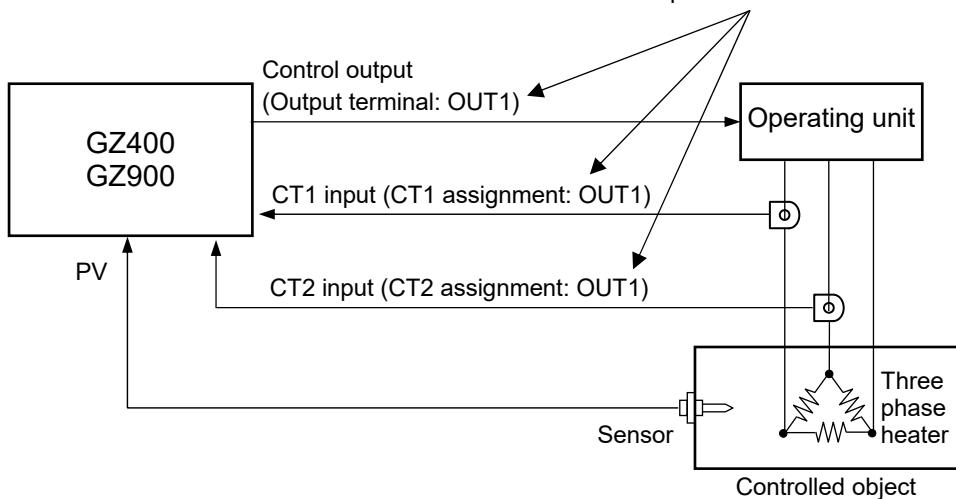
● CT assignment

The Current transformer (CT) input used by the Heater break alarm (HBA) monitors the output from the output device controlled by the control output from the controller. If the output terminal of the control output from the instrument is changed, assignment of the CT needs to be changed accordingly.



When there are two CT inputs, to detect a break in three phase heater, CT1 and CT2 must be assigned to the same terminal.

CT1 and CT2 must be assigned to the same output terminal.



■ Parameter setting

● CT1 assignment

[Engineering Mode: Function block No. 45 (Fn45)]

Parameter symbol	Data range	Factory set value
CFR1	0: None 1: OUT1 2: OUT2 3: OUT3	1



To display “CT1 assignment,” “CT input” must be specified at the time of order.

● CT2 assignment

[Engineering Mode: Function block No. 46 (Fn46)]

Parameter symbol	Data range	Factory set value
CFR2	0: None 1: OUT1 2: OUT2 3: OUT3	Based on Model code

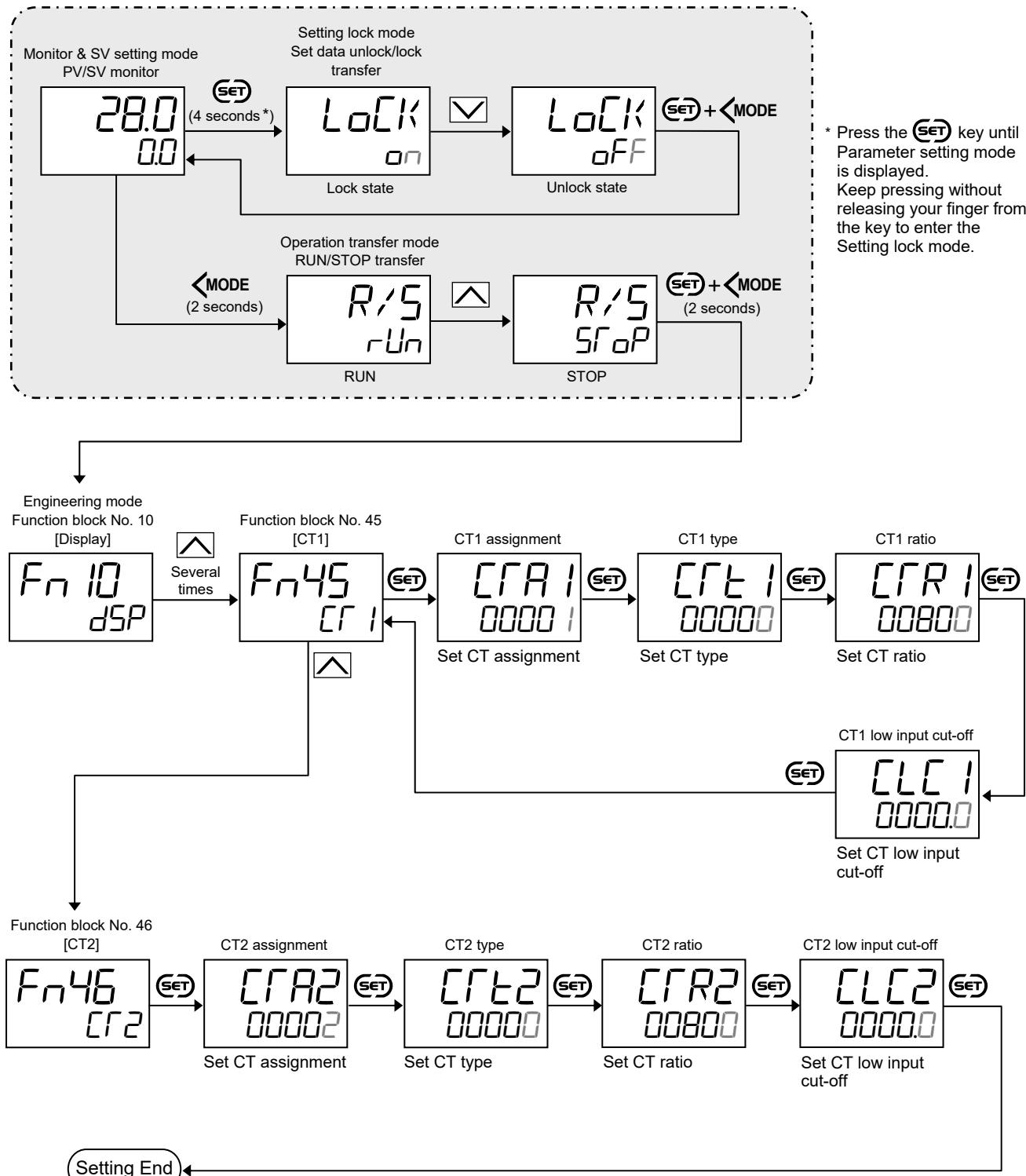


To display “CT2 assignment,” “CT input” must be specified at the time of order.

(When CT input is specified, two CT inputs are supplied.)

■ Setting procedure

To enter the Engineering mode



- Next parameter is displayed.
- Press **SET** and **MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

7.2.4 Changing the Current transformer (CT) type

When a Current transformer (CT) type is changed, change the CT type on the instrument.

Input range of Current transformer (CT)

- CTL-6-P-N: 0 to 30 A
- CTL-12-S56-10L-N: 0 to 100A
- CTL-6-P-Z: 0 to 10 A

■ Parameter setting

● CT1 type

[Engineering Mode: Function block No. 45 (Fn45)]

Parameter symbol	Data range	Factory set value
	0: CTL-6-P-N 1: CTL-12-S56-10L-N 2: CTL-6-P-Z	Based on Model code

-  To display “CT1 type,” “CT input” must be specified at the time of order.
-  After “CT1 type” is changed, the value of “CT1 ratio” is initialized and set to an appropriate CT type.
CT ratio value
 - CTL-6-P-N: 800
 - CTL-12-S56-10L-N: 1000
 - CTL-6-P-Z: 800
-  See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the CT1 type is changed.

● CT1 ratio

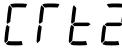
[Engineering Mode: Function block No. 45 (Fn45)]

Parameter symbol	Data range	Factory set value
	0 to 9999 When the CT type is changed, the following value will be automatically set. CTL-6-P-N: 800 CTL-12-S56-10L-N: 1000 CTL-6-P-Z: 800	If CTL-6-P-N or CTL-6-P-Z is specified for the Current transformer (CT) type: 800 If CTL-12-S56-10L-N is specified for the Current transformer (CT) type: 1000

-  To display “CT1 ratio,” “CT input” must be specified at the time of order.

● CT2 type

[Engineering Mode: Function block No. 46 (Fn46)]

Parameter symbol	Data range	Factory set value
	0: CTL-6-P-N 1: CTL-12-S56-10L-N 2: CTL-6-P-Z	Based on Model code

-  To display “CT2 type,” “CT input” must be specified at the time of order.
(When CT input is specified, two CT inputs are supplied.)
-  After “CT2 type” is changed, the value of “CT2 ratio” is initialized and set to an appropriate CT type.
CT ratio value • CTL-6-P-N: 800
• CTL-12-S56-10L-N: 1000
• CTL-6-P-Z: 800
-  See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the CT2 type is changed.

● CT2 ratio

[Engineering Mode: Function block No. 46 (Fn46)]

Parameter symbol	Data range	Factory set value
	0 to 9999 When the CT type is changed, the following value will be automatically set. CTL-6-P-N: 800 CTL-12-S56-10L-N: 1000 CTL-6-P-Z: 800	If CTL-6-P-N or CTL-6-P-Z is specified for the Current transformer (CT) type: 800 If CTL-12-S56-10L-N is specified for the Current transformer (CT) type: 1000

-  To display “CT2 ratio,” “CT input” must be specified at the time of order.
(When CT input is specified, two CT inputs are supplied.)

■ Setting procedure

See the operation on P. 7-32.

7.2.5 Forcing the CT input value to 0.0 A when the heater is OFF

If the Current transformer (CT) input value exceeds 0.0 A while the heater is off, the input value of the Current transformer (CT) can be forced to 0.0 A.

■ Description of function

● CT low input cut-off

The CT input value may exceed 0.0 A while the heater is OFF (control output is OFF). In such a case CT low input cut-off may be used. This is a function to force the CT input which is below the set value to 0.0 A.

-  Note that Heater break alarm (HBA) may not work properly if setting such as follows is made when the CT low input cut-off function is used.

CT low input cut-off set value > Heater break alarm (HBA) set value

[Example] CT low input cut-off set value: 1.0 A and Heater break alarm (HBA) set value: 0.5 A

- If the CT input value is 0.8 A when the control output is ON, the CT input value becomes 0.0 A, causing the Heater break alarm (HBA) to turn on.
→ Actually the CT input value is larger than the HBA set value and the HBA is OFF.
- If the CT input value is 0.8 A when the control output is OFF, the CT input value becomes 0.0 A, causing the Heater break alarm (HBA) to turn off.
→ Actually the CT input value is larger than the HBA set value and the HBA is ON.

If current larger than the CT low input cut-off set value is given, HBA functions properly.

■ Parameter setting

● CT1 low input cut-off

[Engineering Mode: Function block No. 45 (Fn45)]

Parameter symbol	Data range	Factory set value
CLC1	0.0 to 1.0 A	0.0

-  To display “CT1 low input cut-off,” “CT input” must be specified at the time of order.

● CT2 low input cut-off

[Engineering Mode: Function block No. 46 (Fn46)]

Parameter symbol	Data range	Factory set value
CLC2	0.0 to 1.0 A	0.0

-  To display “CT2 low input cut-off,” “CT input” must be specified at the time of order.
(When CT input is specified, two CT inputs are supplied.)

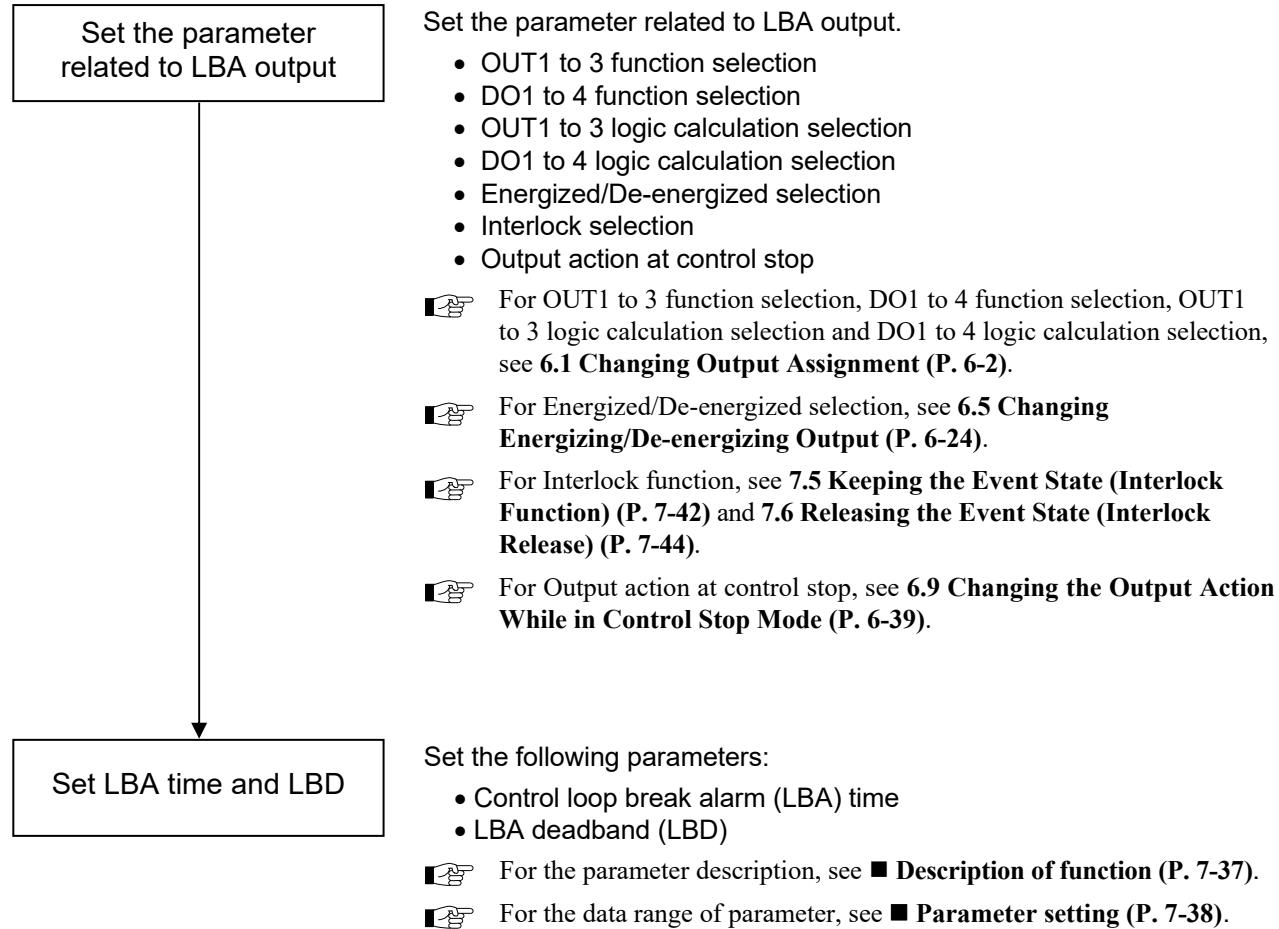
■ Setting procedure

See the operation on P. 7-32.

7.3 Using Control Loop Break Alarm (LBA)

■ Setting procedure for Control loop break alarm (LBA)

Set Control loop break alarm (LBA) as follows:



■ Description of function

The Control loop break alarm (LBA) function is used to detect a load (heater) break or a failure in the external actuator (power controller, magnet relay, etc.), or a failure in the control loop caused by an input (sensor) break. The LBA function is activated when control output reaches 0 % (low limit with output limit function) or 100 % (high limit with output limit function). LBA monitors variation of the Measured value (PV) for the length of LBA time. When the LBA time has elapsed and the PV is still within the alarm determination range, the LBA will be ON.

[Alarm action]

LBA determination range: TC/RTD input: 2 °C [°F] (fixed)
Voltage /Current input: 0.2 % of input span (fixed)

● Heating control

		When the output reaches 0 % (low limit with output limit function)	When the output exceeds 100 % (high limit with output limit function)
LBA occurring condition	For reverse action	When the LBA time has passed and the Measured value (PV) has not fallen below the alarm determination range, the alarm will be turned on.	When the LBA time has passed and the Measured value (PV) has not risen beyond the alarm determination range, the alarm will be turned on.
	For direct action	When the LBA time has passed and the Measured value (PV) has not risen beyond the alarm determination range, the alarm will be turned on.	When the LBA time has passed and the Measured value (PV) has not fallen below the alarm determination range, the alarm will be turned on.

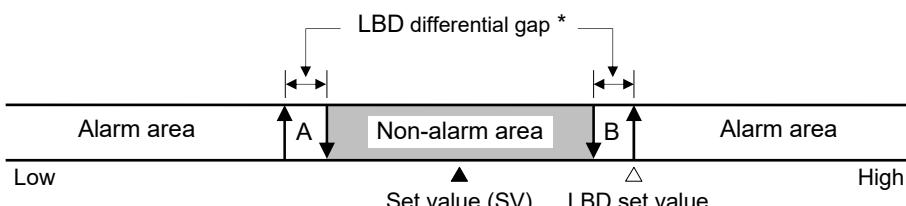
● Heat/Cool control

		When the heat-side output exceeds 100 % (high limit with heat-side output limit function) and the cool-side output reaches 0 % (A) *	When the heat-side output reaches 0 % and the cool-side output exceeds 100 % (high limit with cool-side output limit function) (B) *
LBA occurring condition	When the LBA time has passed and the Measured value (PV) has not risen beyond the alarm determination range, the alarm will be turned on.	When the LBA time has passed and the Measured value (PV) has not fallen below the alarm determination range, the alarm will be turned on.	
	When the LBA time has passed and the Measured value (PV) has not risen beyond the alarm determination range, the alarm will be turned on.		

* If conditions of (A) and (B) are both met, priority is given to (A).

● LBA deadband (LBD)

The Control loop break alarm (LBA) may malfunction due to external disturbances. To prevent malfunction due to external disturbance, LBA deadband (LBD) sets a neutral zone in which Control loop break alarm (LBA) is not activated. When the Measured value (PV) is within the LBA deadband (LBD) area, Control loop break alarm (LBA) will not be activated. If the LBA deadband (LBD) setting is not correct, the LBA will not work correctly.



* TC/RTD input: 0.8 °C [°F] (fixed)
Voltage/Current input: 0.8 % of input span (fixed)

- A: During temperature rise: Alarm area During temperature fall: Non-alarm area
B: During temperature rise: Non-alarm area During temperature fall: Alarm area

-  LBA function is not available:
 - when displaying Input type and Input range after turning ON the power.
 - during Autotuning (AT).
 - in the STOP mode.
 - when Control loop break alarm (LBA) time is “0.”
-  If the Control loop break alarm (LBA) setting time does not match the controlled object requirements, the Control loop break alarm (LBA) setting time should be lengthened. If setting time is not correct, the Control loop break alarm (LBA) will malfunction by turning on or off at inappropriate times or not turning on at all.
-  While the LBA is ON (under alarm status), the following conditions cancel the alarm status and LBA will be OFF.
 - The Measured value (PV) rises beyond (or falls below) the LBA determination range within the LBA time.
 - The Measured value (PV) enters within the LBA deadband (LBD).
-  If the Autotuning (AT) is used, the Control loop break alarm (LBA) time is automatically set twice as large as the integral time. The Control loop break alarm (LBA) time will not change even if the integral time is changed. If the Control loop break alarm (LBA) time is “0” and Autotuning (AT) is executed, the Control loop break alarm (LBA) time will not be set.
-  If the Control loop break alarm (LBA) function detects an error occurring in the control loop, but cannot specify the location, the control loop should be checked. The Control loop break alarm (LBA) function does not detect the location which causes alarm status. If Control loop break alarm (LBA) is ON, check each device or wiring in the control loop.

■ Parameter setting

● Input 1_Control loop break alarm (LBA) time

[Parameter Setting Mode: Parameter group No. 51 (P_{n51})]

Parameter symbol	Data range	Factory set value
$I_1.Lba$	0 to 7200 seconds 0: No function	Output assignment is entered in the initial setting code: <ul style="list-style-type: none"> • The assigned output has LBA output: 480 • The assigned output has no LBA output: 0 Output assignment is not entered in the initial setting code: 0

● Input 2_Control loop break alarm (LBA) time

[Parameter Setting Mode: Parameter group No. 52 (P_{n52})]

Parameter symbol	Data range	Factory set value
$I_2.Lba$	0 to 7200 seconds 0: No function	Output assignment is entered in the initial setting code: <ul style="list-style-type: none"> • The assigned output has LBA output: 480 • The assigned output has no LBA output: 0 Output assignment is not entered in the initial setting code: 0

-  To display “Input 2_Control loop break alarm (LBA) time,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

● Input 1_LBA deadband (LBD)

[Parameter Setting Mode: Parameter group No. 51 (P_{n51})]

Parameter symbol	Data range	Factory set value
$I. Lbd$	0 to Input 1_Input span (When Control with PV select: 0 to PV select input span) [Varies with the setting of the Decimal point position.]	0

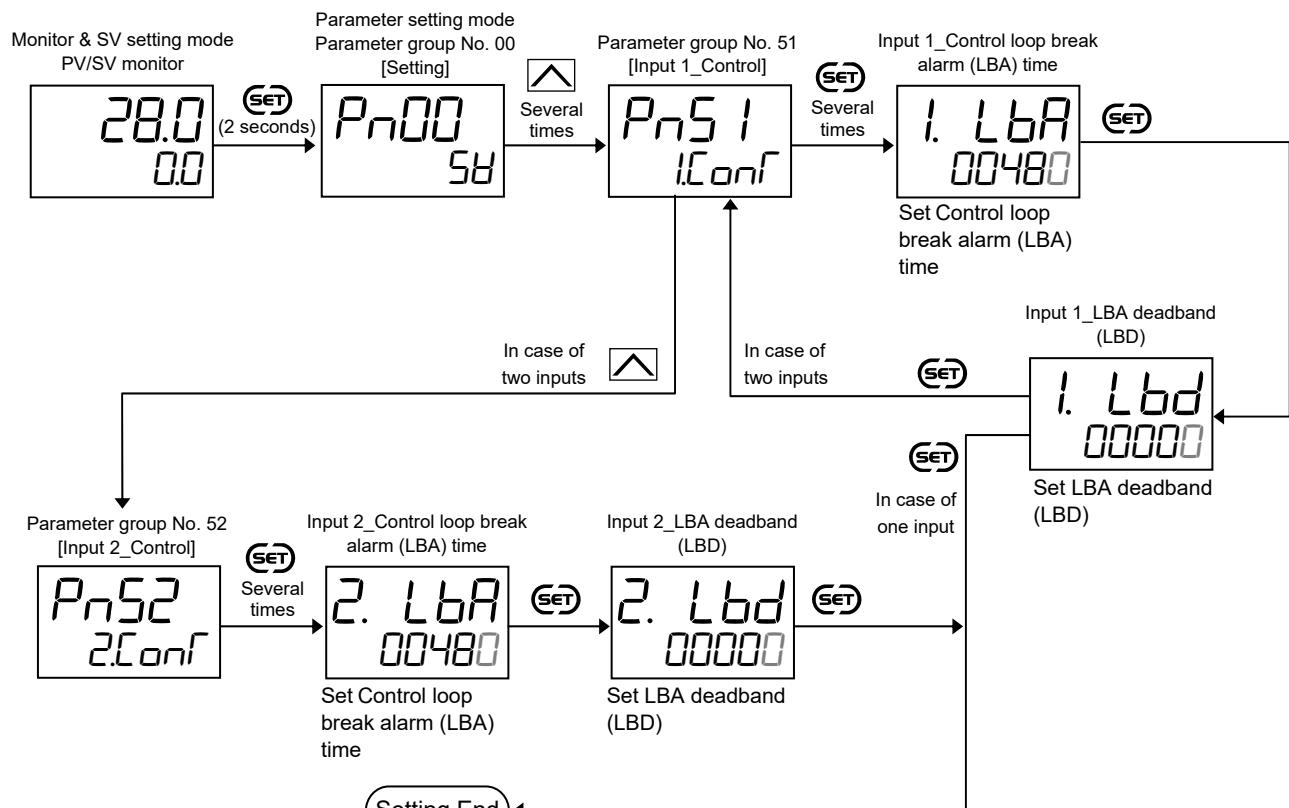
● Input 2_LBA deadband (LBD)

[Parameter Setting Mode: Parameter group No. 52 (P_{n52})]

Parameter symbol	Data range	Factory set value
$2. Lbd$	0 to Input 2_Input span [Varies with the setting of the Decimal point position.]	0

-  To display “Input 2_LBA deadband (LBD),” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

■ Setting procedure



- Next parameter is displayed.
- Press  and  keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

7.4 Checking Event ON State

The event ON state can be checked with the ALM lamp or on the Comprehensive event state screen in the Monitor & SV setting mode.

■ Display contents

● ALM lamp

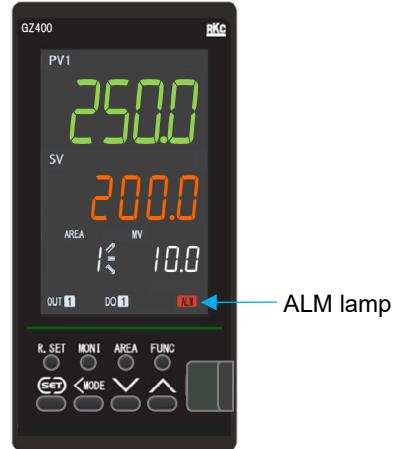
When the event is in the ON state, the ALM lamp turns on. However, the instrument has only one ALM lamp which is turned on using the *OR* relation of the related functions. Combination of the states can be freely available.

The setting can be done at ALM lamp lighting condition (Function block 10 in Engineering mode)

[Events that illuminate the lamp]

- Event 1
- Event 2
- Event 3
- Event 4
- Heater break alarm 1 (HBA1)
- Heater break alarm 2 (HBA2)
- Control loop break alarm 1 (LBA1)
- Control loop break alarm 2 (LBA2)
- Input 1_Input error high
- Input 1_Input error low
- Input 2_Input error high
- Input 2_Input error low

Display example



● ALM lamp lighting condition

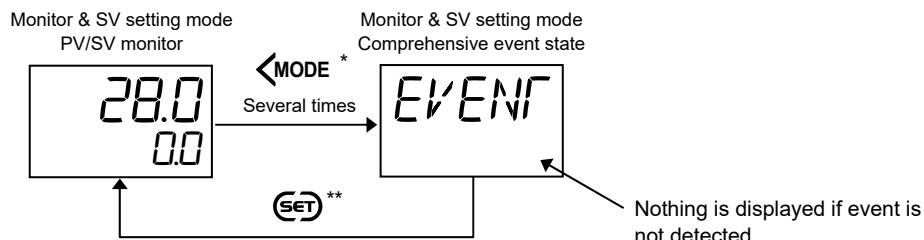
[Engineering Mode: Function block No. 10 ($F_{n \text{ I/O}}$)]

Parameter symbol	Data range	Factory set value
ALM	0 to 4095 0: OFF +1: Event 1 +2: Event 2 +4: Event 3 +8: Event 4 +16: Heater break alarm 1 (HBA1) +32: Heater break alarm 2 (HBA2) +64: Control loop break alarm 1 (LBA1) +128: Control loop break alarm 2 (LBA2) +256: Input 1_Input error high +512: Input 1_Input error low +1024: Input 2_Input error high +2048: Input 2_Input error low To select two or more functions, sum each value.	255

● **Comprehensive event state**
[Monitor & SV Setting Mode]

Parameter symbol	Data range	Factory set value
<i>EVENT</i>	<p>When an event occurs, the character of the occurring event is displayed on the Set value (SV) display unit. If two or more events occur at the same time, the relevant characters are displayed alternately every 0.5 seconds.</p> <p><i>EVR1</i>: Event 1 <i>EVR2</i>: Event 2 <i>EVR3</i>: Event 3 <i>EVR4</i>: Event 4 <i>HbR1</i>: Heater break alarm 1 (HBA1) <i>HbR2</i>: Heater break alarm 2 (HBA2) <i>LbR1</i>: Control loop break alarm 1 (LBA1) <i>LbR2</i>: Control loop break alarm 2 (LBA2) <i>I n I.UP</i>: Input 1_Input error high <i>I n I.dn</i>: Input 1_Input error low <i>I n2.UP</i>: Input 2_Input error high <i>I n2.dn</i>: Input 2_Input error low</p>	—

■ **Display operation**



* MONI key may be used instead.

** R.SET key may be used to return.

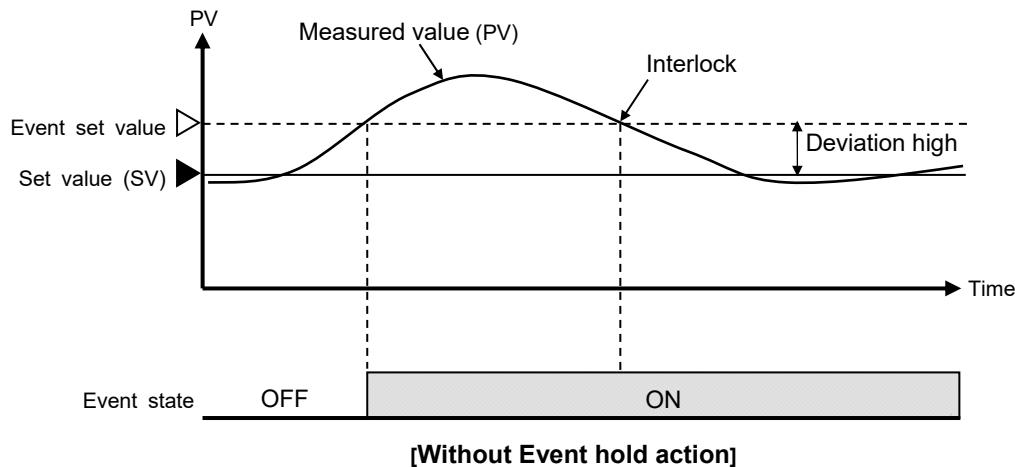
7.5 Keeping the Event State (Interlock Function)

■ Description of function

The Event interlock function holds the event state (including the HBA, the LBA and the input error) even if the Measured value (PV) is out of the event zone after it enters the event zone once.

Interlock can be set for the Event, Heater break alarm (HBA), Control loop break alarm (LBA) and Input error.

Example: When the Event interlock function is used for Deviation high



For the interlock release, see **7.6 Releasing the Event State (Interlock Release) (P. 7-44)**.

■ Parameter setting

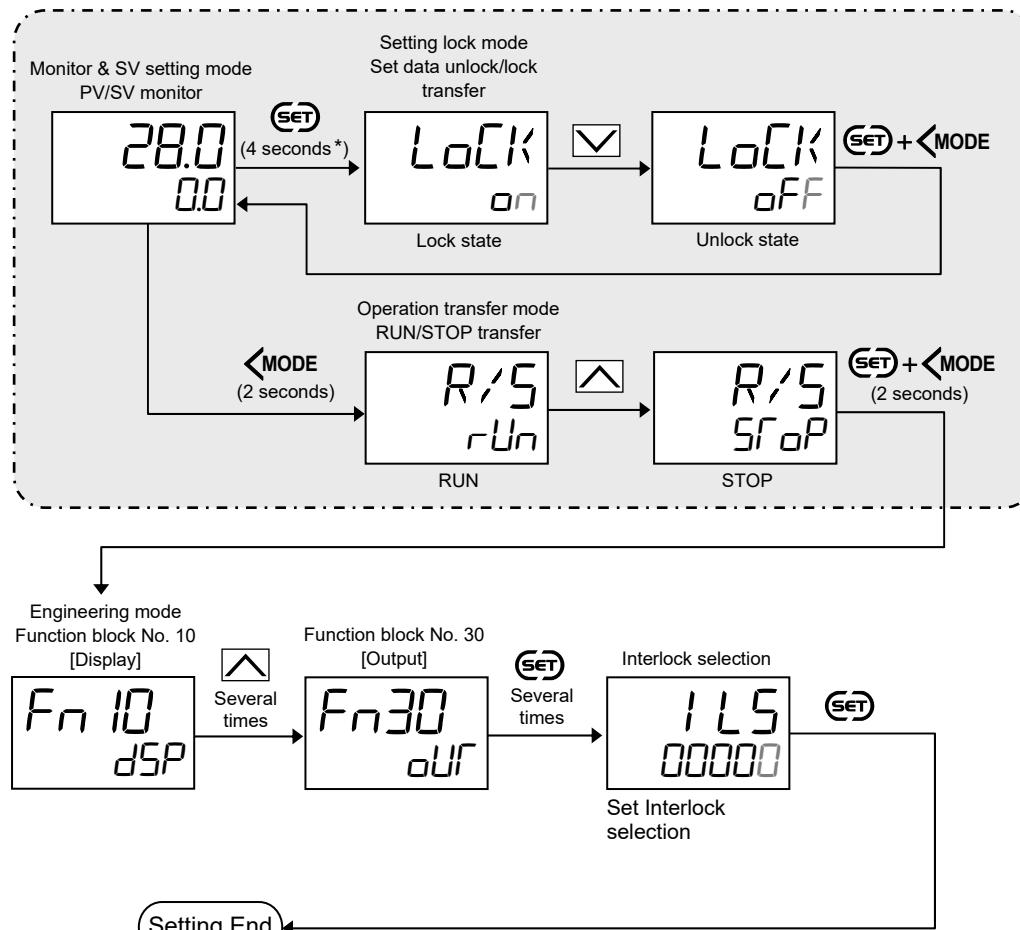
● Interlock selection

[Engineering Mode: Function block No. 30 (Fn30)]

Parameter symbol	Data range	Factory set value
I LS	0 to 4095 0: Unused +1: Event 1 +2: Event 2 +4: Event 3 +8: Event 4 +16: Heater break alarm 1 (HBA1) +32: Heater break alarm 2 (HBA2) +64: Control loop break alarm 1 (LBA1) +128: Control loop break alarm 2 (LBA2) +256: Input 1_Input error high +512: Input 1_Input error low +1024: Input 2_Input error high +2048: Input 2_Input error low To select two or more functions, sum each value.	0

■ Setting procedure

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.

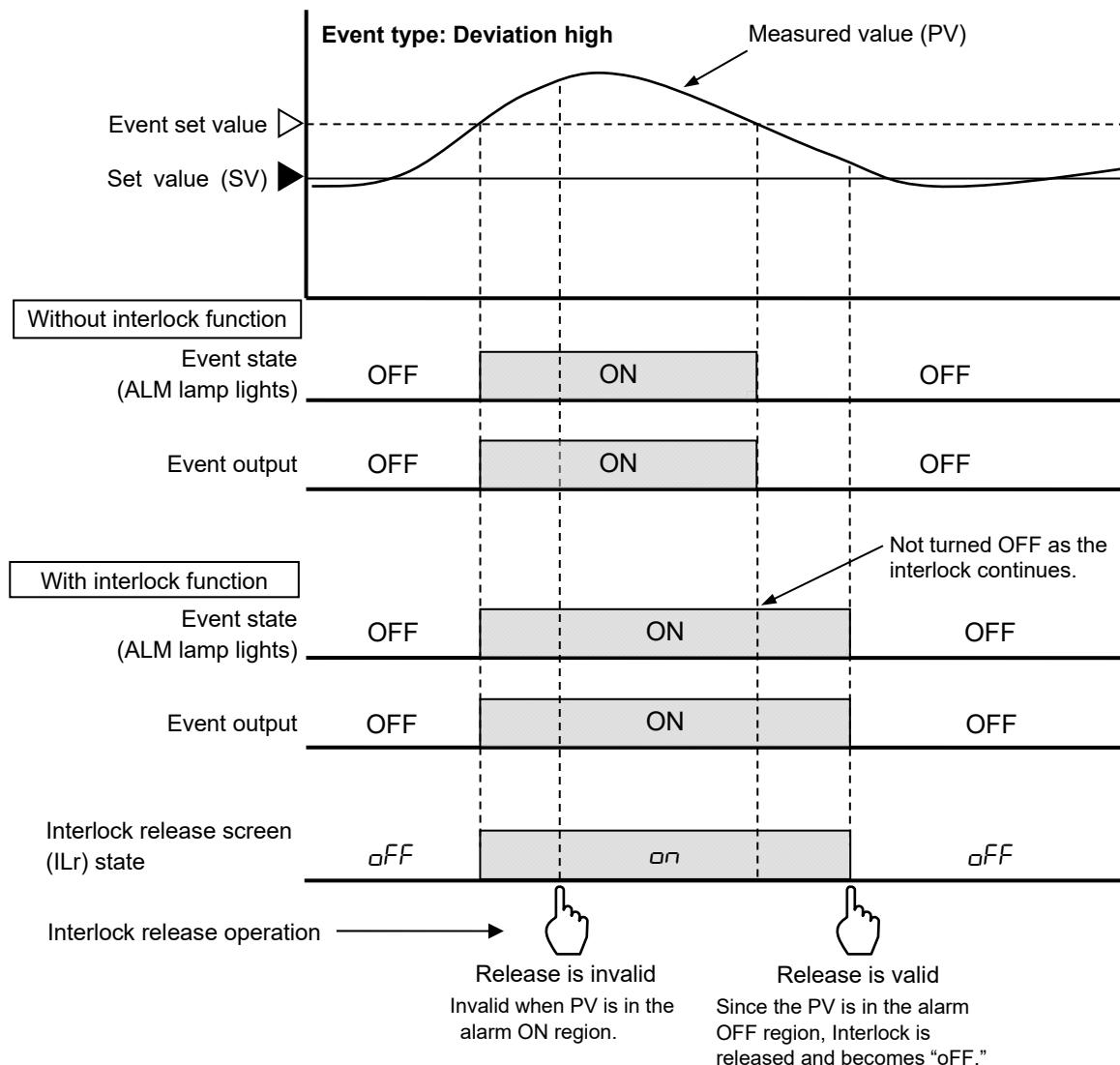
7.6 Releasing the Event State (Interlock Release)

■ Description of function

The Event interlock function holds the event state (including the HBA, the LBA and the input error) even if the Measured value (PV) is out of the event zone after it enters the event zone once.

The Interlock may be released by Digital input (DI) and Communication (optional) as well as key operation.

The following picture shows how to release the interlock.



- The Interlock release has an influence to all events, Heater break alarm (HBA), Control loop break alarm (LBA) and input error that are in the interlock state and releases such events at one time whose interlock release conditions are met.
- For Interlock release through Digital input (DI), see **5.2 Switching Functions Using Digital Inputs (DI) (P. 5-16)**.
- For Interlock release through Communication, refer to **GZ400/GZ900 Instruction Manual [Host Communication] (IMR03D07-E2)**.

■ Parameter setting

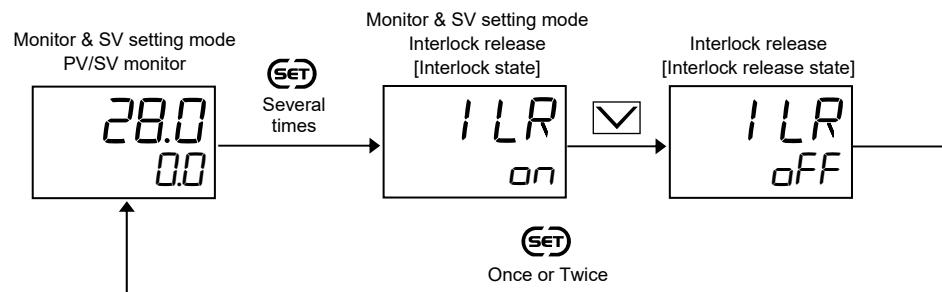
- **Interlock release**
[Monitor & SV Setting Mode]

Parameter symbol	Data range	Factory set value
<i>I LR</i>	<i>oFF</i> : Interlock release <i>on</i> : Interlock state	<i>oFF</i>

 To display “Interlock release,” the Interlock selection must be set (Function block No. 30 in Engineering mode) other than “Unused.”

■ Setting procedure

After the Interlock is set, the Interlock release screen shows “*on*” automatically.

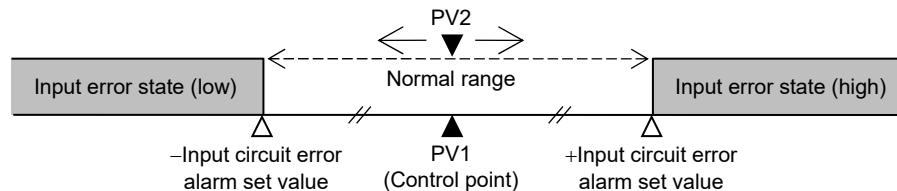


7.7 Preventing Control with Input Errors (Input Circuit Error Alarm)

■ Description of function

Input circuit error alarm uses two inputs (dual input function) and detects errors in the input circuit from the difference between two inputs.

When the difference between Input 1_Measured input (PV1) and Input 2_Measured input (PV2 – PV1) exceeds Input circuit error alarm set value, it is considered to be an input error and “Input error state” starts.

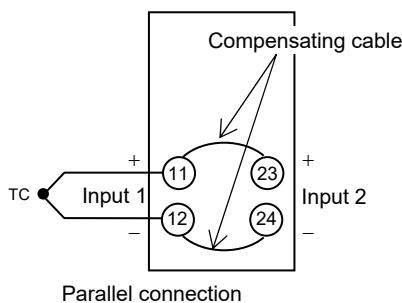


Determination of input errors

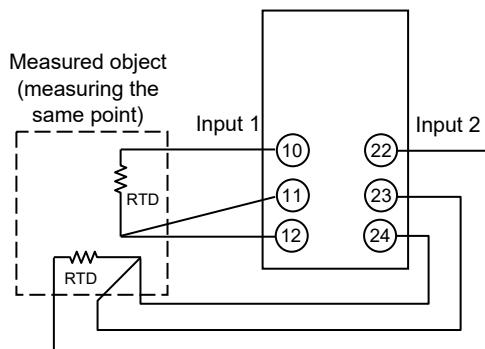
- $(PV1 + \text{Input circuit error alarm set value}) < PV2 \cdots \text{Input error of Input 1 (high)}$
- $(PV1 - \text{Input circuit error alarm set value}) > PV2 \cdots \text{Input error of Input 1 (low)}$

[Wiring example]

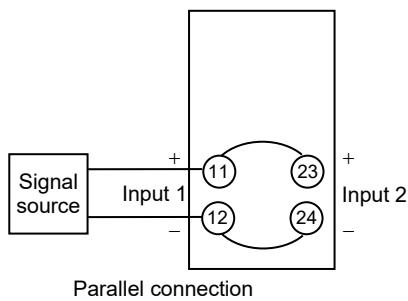
- TC input



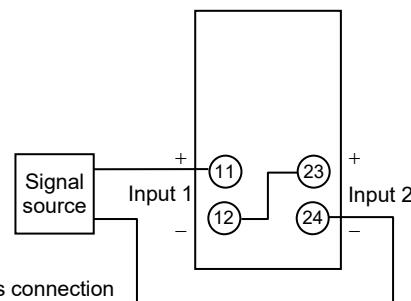
- RTD input



- Voltage input



- Current input



Different input type can be specified for Input 1 and Input 2. Note that action may be different on each input.

-  To output “Input 1_Input error high/low,” output assignment must be set in advance. For details of output assignment, see **6.1 Changing Output Assignment [Control Output, Retransmission Output, Logic Calculation (Event) Output, Instrument Status Output] (P. 6-2)**.
-  Irrespective of Input circuit error alarm setting, “Input 1_Input error high/low” conducts normal Input error alarm action. For detailed operation at Input error action, see **5.7 Changing Error Handling at Input Error (P. 5-39)**.
-  Before using the Input circuit error alarm, check for errors in measured values between Input 1 and Input 2 which should be removed in advance using PV bias.
-  The Input circuit error alarm function uses two inputs, but control using Input 2 is not available. However, lighting the ALM lamp and providing state output from Digital output (DO) are possible.

■ Parameter setting

● Select function for input 2

[Engineering Mode: Function block No. 58 (Fn58)]

Parameter symbol	Data range	Factory set value
$2PV$	0: No function 1: Remote setting input 2: 2-loop control/Differential temperature control * 3: Control with PV select 6: Input circuit error alarm <small>* This parameter cannot be specified if the instrument is a Heat/Cool PID type.</small> • When Measured input 2 is selected at the time of order: 0 to 3, 6 • When the Remote setting input is selected: 0 to 1	Based on Model code

-  To select “Input circuit error alarm” in “Select function for input 2,” “Measured input 2” must be ordered.
-  See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are initialized when the Select function for input 2 is changed.

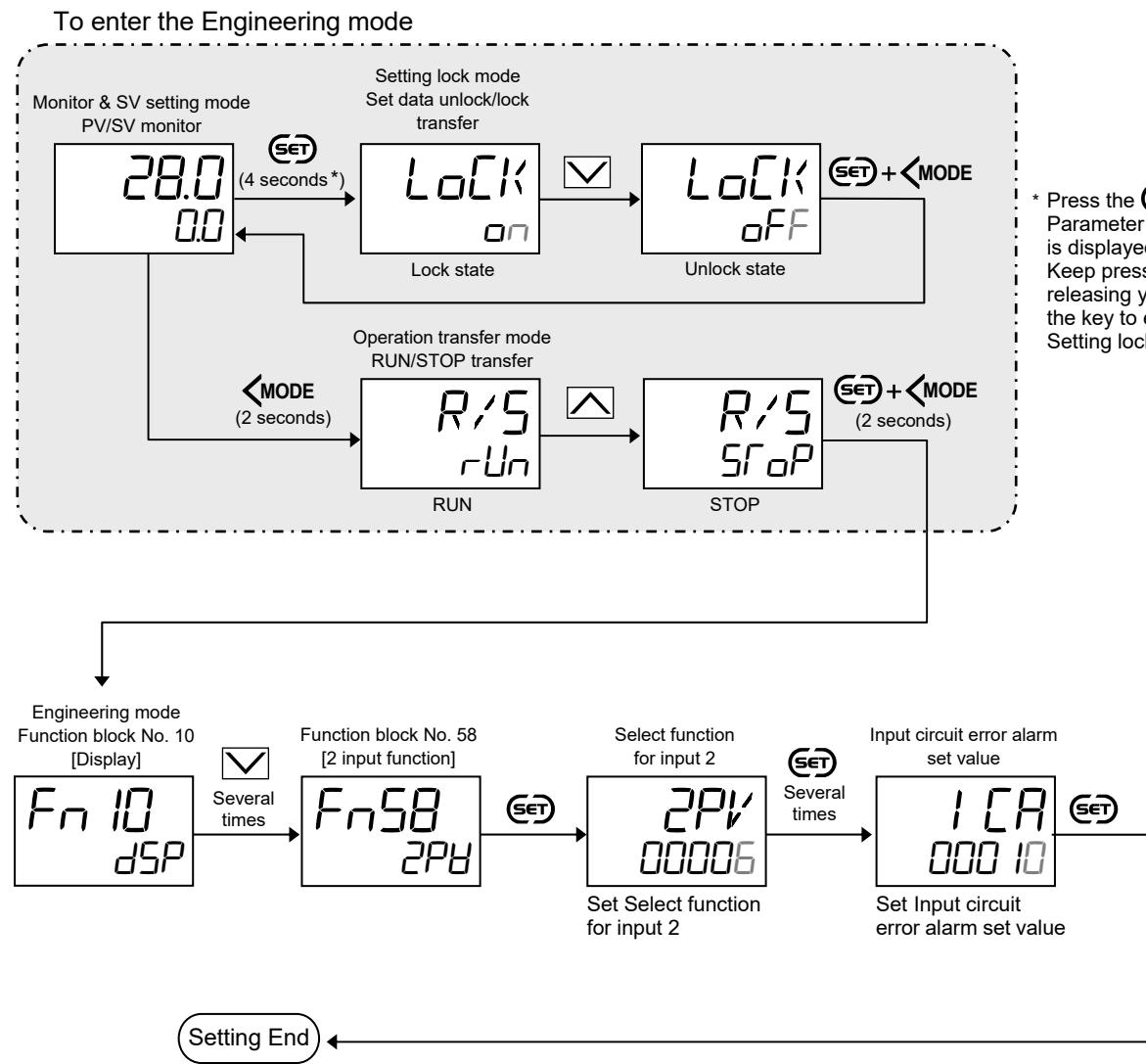
● Input circuit error alarm set value

[Engineering Mode: Function block No. 58 (Fn58)]

Parameter symbol	Data range	Factory set value
I_{CAR}	0 to Input 1_Input span 0: No function <small>[Varies with the setting of the Decimal point position.]</small>	TC/RTD inputs: 10 <small>V/I inputs:</small> 5 % of Input 1_Input span

-  To display “Input circuit error alarm set value,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to Input circuit error alarm.

■ Setting procedure



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

8

CONTROL FUNCTION

This chapter describes control related functions, setting contents and setting procedure based on the key words related to controls.

8.1 Running/Stopping Control (RUN/STOP Transfer)	8-2
8.2 Changing Control Action.....	8-5
8.3 Setting PID Values Automatically (Autotuning)	8-11
8.4 Setting PID Values Automatically (Startup tuning).....	8-18
8.5 Setting PID Values Manually.....	8-24
8.6 Controlling with ON/OFF Action.....	8-31
8.7 Controlling with Heat/Cool Control.....	8-36
8.8 Controlling with Manual Control.....	8-44
8.9 Using Remote Setting Input.....	8-49
8.10 Executing 2-Loop Control.....	8-55
8.11 Executing Differential Temperature Control	8-58
8.12 Executing Control with PV Select.....	8-63
8.13 Controlling with Level PID	8-72
8.14 Eliminating Offset Inherent to Proportioning Control (Manual Reset)	8-83
8.15 Continuing Stable Control after the Operation Transfer (SV Tracking)	8-85
8.16 Suppressing Overshoot.....	8-90
8.17 Changing the Action at Power ON (Hot/Cold Start).....	8-98

8.1 Running/Stopping Control (RUN/STOP Transfer)

The RUN/STOP transfer can be made by Digital input (DI) or Communication (optional) other than the key operation.

The factory set value is RUN. As soon as the controller is powered on, control is started.

● State of this instrument when set to STOP mode

STOP display		Displays the STOP symbol “ $S\bar{f} \square P$ ” on the SV, PV or MV * displays. (Factory set value: SV displays)
Control output	PID control	“Input 1_Manipulated output value at STOP [heat-side]” is output. (Factory set value: -5.0 %) “Input 2_Manipulated output value at STOP” * is output. (Factory set value: -5.0 %) * In the case of 2-loop control/Differential temperature control
	Heat/Cool PID control	Heat-side: “Input 1_Manipulated output value at STOP [heat-side]” is output. (Factory set value: -5.0 %) Cool-side: “Input 1_Manipulated output value at STOP [cool-side]” is output. (Factory set value: -5.0 %)
Logic calculation output		According to the setting contents of Output action at STOP
Retransmission output		(Factory set value: OFF)
Instrument status output		
Autotuning or Startup tuning		AT canceled (PID constants are not updated.)

- ☞ For STOP display selection, see **9.4 Changing the Display Position of STOP during the Control Stop (P. 9-17)**.
- ☞ For Action selection at STOP mode, see **6.9 Changing the Output Action While in Control Stop Mode (P. 10-46)**.

● State of this instrument when set to RUN mode

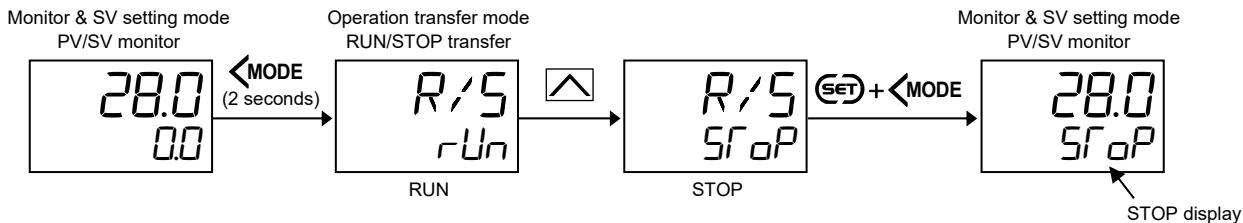
Operation when transferred to RUN from STOP is in accordance with the Hot/Cold start selection setting.

- ☞ For the Hot/Cold start, see **8.17 Changing the Action at Power ON (Hot/Cold Start) (P. 8-98)**.
- ☞ For the details of the RUN/STOP switching by communication (optional), refer to the **GZ400/GZ900 Instruction Manual [Host communication] (IMR03D07-E)**.

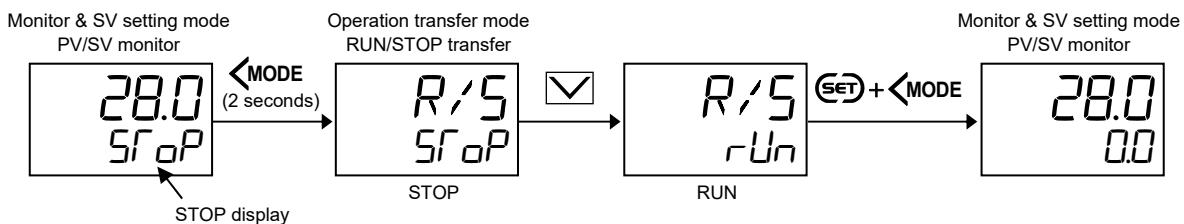
■ Setting procedure

● Selection by front key operation

Changing the mode from RUN to STOP



Changing the mode from STOP to RUN

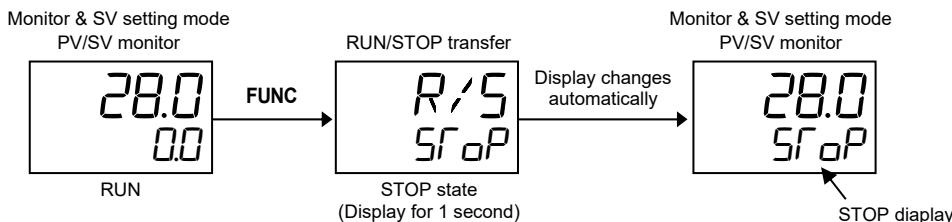


● Changing the mode with the direct key

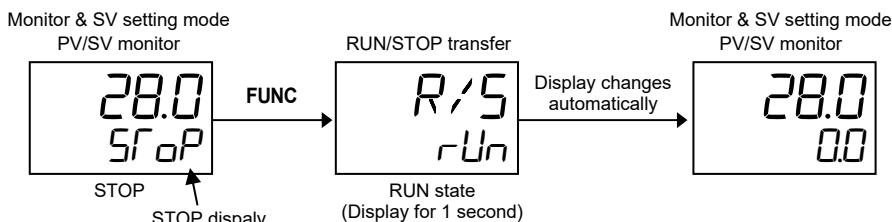
Assigning the “RUN/STOP transfer” function to the FUNC key facilitates the RUN/STOP switching. RUN/STOP transfer function is assigned to the FUNC key at the time of shipment for immediate use. Each time FUNC key is pressed, RUN and STOP are toggled.

For the “FUNC key assignment,” see **10.8 Accessing Some Functions Directly (FUNC key) (P. 10-35)**.

Changing the mode from RUN to STOP



Changing the mode from STOP to RUN



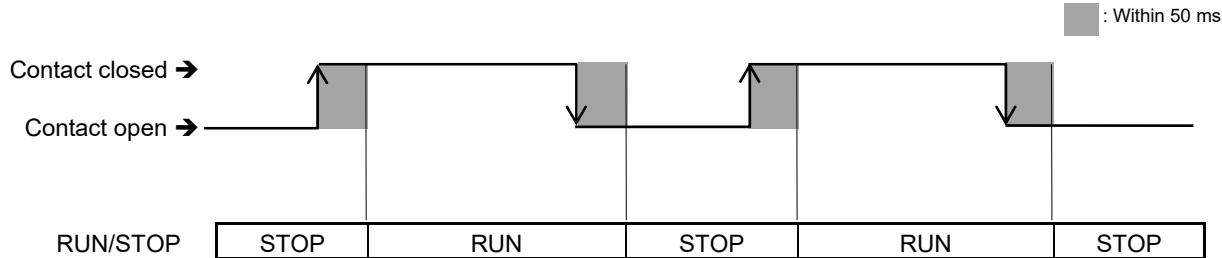
Selection of key action is possible from “Press once” and “Press and hold” to enable the switching. For details, see **10.8 Accessing Some Functions Directly (FUNC key) (P. 10-35)**.

● Switching the mode with Digital Input (DI)

To switch the RUN/STOP using the Digital Input (DI), use “DI function selection” (Function block No. 23 in the Engineering mode).

- For the Digital input (DI) assignment, see **5.2 Switching Functions Using Digital Inputs (DI) (P. 5-16)**.

Transfer timing of RUN/STOP



NOTE

After the contact is transferred, it takes “Within 50 ms” until the action of this instrument is actually selected.

- The above switching action can be inverted (The functions at contact close and contact open can be swapped). This setting can be done at “DI logic invert.” For details, see **5.2 Switching Functions Using Digital Inputs (DI) (P. 5-16)**.

● RUN/STOP transfer state

The table below shows the actual RUN/STOP modes and displays under different combinations of settings by Key operation, Communication, and Digital input (DI).

Setting via front keys or through communication	Setting via Digital Input (DI)	Instrument status	STOP display
RUN	RUN	RUN	—
	STOP		dSfP
STOP	RUN	STOP	UfP
	STOP		SfP *

Priority to STOP

* The instrument without RUN/STOP switching by DI will have the same display.

STOP character display

Monitor & SV setting mode PV/SV monitor	Monitor & SV setting mode PV/SV monitor	Monitor & SV setting mode PV/SV monitor
STOP with the key (No RUN/STOP transfer by DI)	STOP with the key RUN/STOP transfer by DI: RUN	STOP with the DI RUN/STOP transfer by key: RUN

- The display position of STOP can be changed. For details, see **9.4 Changing the Display Position of STOP during the Control Stop (P. 9-17)**.

8.2 Changing Control Action

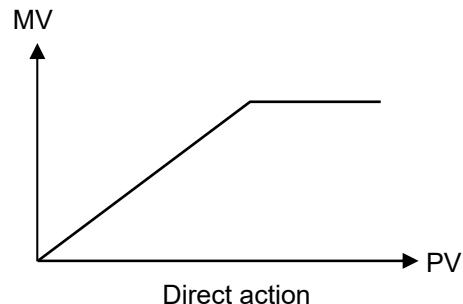
See the following 6 types of control action:

- PID control (direct action)
- PID control (reverse action)
- ON/OFF action
- Heat/Cool PID control (water cooling)
- Heat/Cool PID control (air cooling)
- Heat/Cool PID control (Cooling linear type)

■ PID control (direct action)

The Manipulated output value (MV) increases as the Measured value (PV) increases.

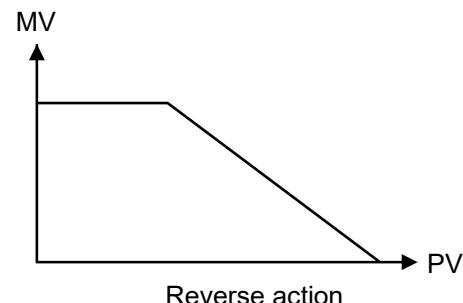
This action is used generally for cooling control.



■ PID control (reverse action)

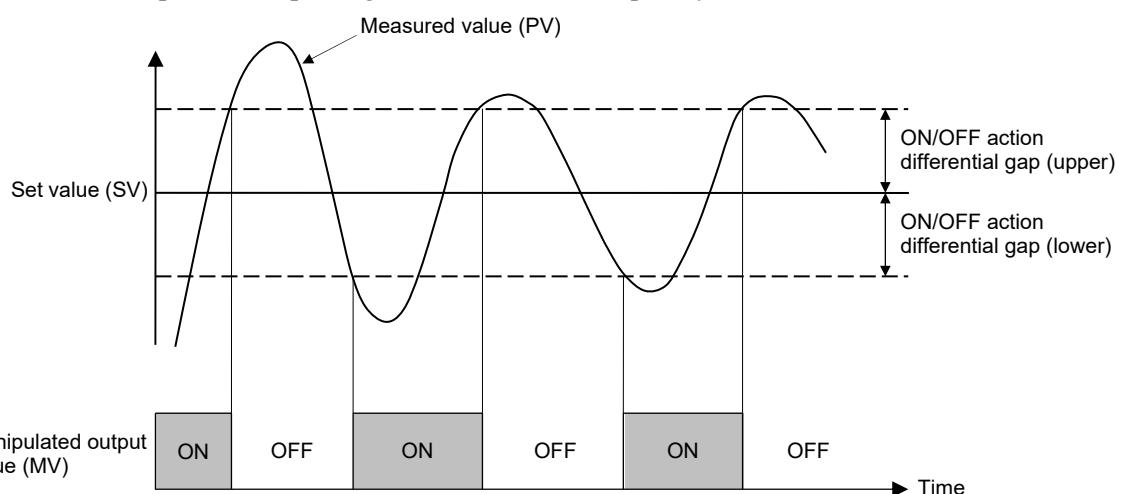
The Manipulated output value (MV) decreases as the Measured value (PV) increases.

This action is used generally for heating control.



■ ON/OFF action

ON/OFF control is possible when the Proportional band [heat-side] is set to 0. In ON/OFF control with Reverse action, when the Measured value (PV) is smaller than the Set value (SV), the Manipulated output (MV) is 100 % or ON. When the PV is higher than the SV, the MV is 0 % or OFF. Differential gap setting prevents control output from repeating ON and OFF too frequently.



For ON/OFF action, see 8.6 Controlling with ON/OFF Action (P. 8-31).

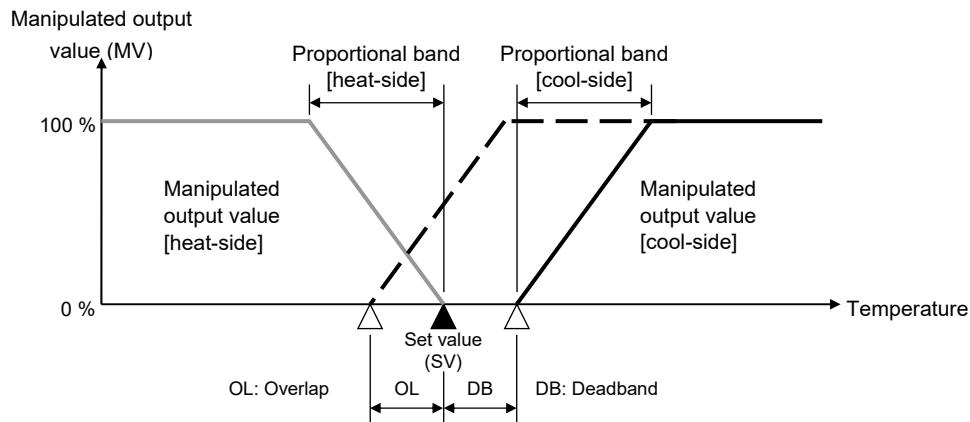
■ Heat/Cool PID control

In Heat/Cool control, heating and cooling control can be achieved with a single controller.

Water cooling/Air cooling: The algorithm intended for Heat/Cool control on the plastic extruders is employed.

Even in equipment provided with a cooling mechanism having nonlinear characteristics, it responds quickly to attain the characteristic responding to the set value with small overshooting.

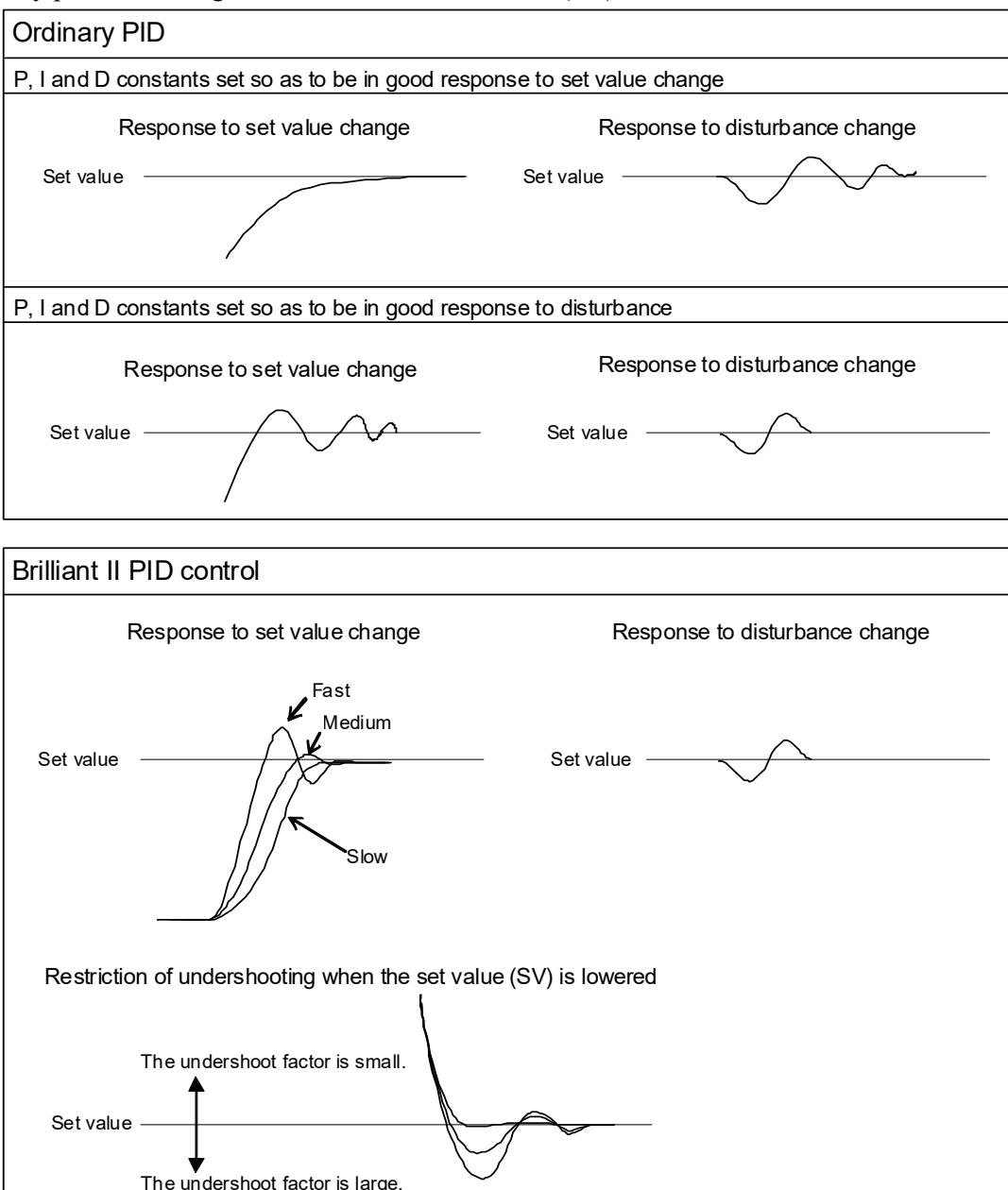
Cooling linear type: The algorithm intended for applications without nonlinear cooling capability is employed.



For Heat/Cool PID control, see **8.7 Controlling with Heat/Cool Control (P. 8-36)**.

■ Brilliant II PID control

PID control is a control method of achieving stabilized control result by setting P (Proportional band), I (Integral time) and D (Derivative time) constants, and is widely used. However, with this PID control, if P, I and D values are set to focus on “better response to control set value change,” “response to external disturbance” deteriorates. In contrast, if PID values are set to focus on “better response to external disturbance,” “response to control set value change” deteriorates. In brilliant II PID control a form of “Response to setting” can be selected from among **Fast**, **Medium** and **Slow** with PID constants remaining unchanged so as to be in good “Response to disturbances.” In addition, the controller is provided with the function which restricts the amount of undershooting caused by the cooling nonlinear characteristic possessed by plastic molding machines when the Set value (SV) is lowered in Heat/Cool PID control.



■ Parameter setting

● Input 1_Control action

[Engineering Mode: Function block No. 51 (Fn51)]

Parameter symbol	Data range	Factory set value
I. 05	0: Brilliant II PID control (direct action) 1: Brilliant II PID control (reverse action) 2: Brilliant II Heat/Cool PID control [water cooling] 3: Brilliant II Heat/Cool PID control [air cooling] 4: Brilliant II Heat/Cool PID control [Cooling linear type] For 2-loop control/Differential temperature control, only 0 or 1 is selectable.	Control action specified at the time of order.



See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the Input 1_Control action is changed.

● Input 2_Control action

[Engineering Mode: Function block No. 52 (Fn52)]

Parameter symbol	Data range	Factory set value
2. 05	0: Brilliant II PID control (direct action) 1: Brilliant II PID control (reverse action)	Same as Input 1_Control action



To display “Input 2_Control action,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

● Input 1_Control response parameter

[Parameter Setting Mode: Parameter group No. 51 (Pn51)]

Parameter symbol	Data range	Factory set value
I. RPF	0: Slow 1: Medium 2: Fast [When the P or PD action is selected, this setting becomes invalid]	PID control: 0 Heat/Cool PID control: 2



When this parameter is set and fixed to Slow at “Fix parameter setting: Control response parameter” in the Setting lock mode, the setting is fixed to 0.

● Input 2_Control response parameter

[Parameter Setting Mode: Parameter group No. 52 (Pn52)]

Parameter symbol	Data range	Factory set value
2. RPF	0: Slow 1: Medium 2: Fast [When the P or PD action is selected, this setting becomes invalid]	0



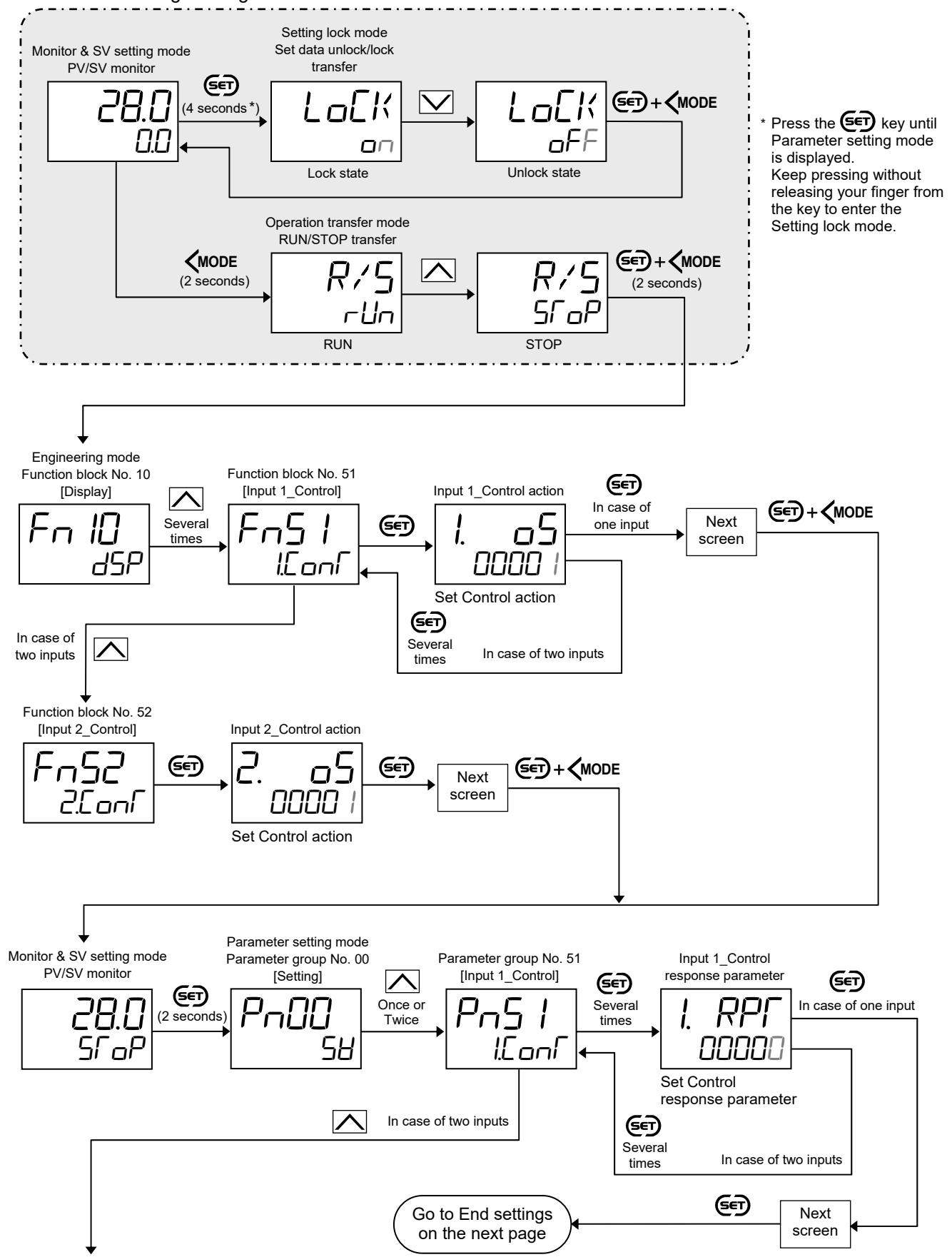
To display “Input 2_Control response parameter,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.



When this parameter is set and fixed to Slow at “Fix parameter setting: Control response parameter” in the Setting lock mode, the setting is fixed to 0.

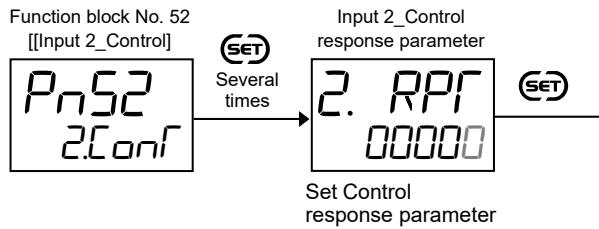
■ Setting procedure

To enter the Engineering mode



Continued on the next page.

Continued from the previous page.



Setting End ←

- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

8.3 Setting PID Values Automatically (Autotuning)

The Autotuning (AT) automatically measures, computes and sets the optimum PID values. The Autotuning (AT) can be used for PID control (Direct action/Reverse action) and Heat/Cool PID control.

■ Description of function

● Parameters computed by Input 1_Autotuning (AT)

- Input 1_Proportional band [heat-side]
- Input 1_Integral time [heat-side]
- Input 1_Derivative time [heat-side]
- Input 1_Proportional band [cool-side] (Only for Heat/Cool PID control)
- Input 1_Integral time [cool-side] (Only for Heat/Cool PID control)
- Input 1_Derivative time [cool-side] (Only for Heat/Cool PID control)
- Input 1_Control loop break alarm (LBA) time * (The LBA time is automatically set to twice the value of the Integral time)

* When the Control break alarm (LBA) time is set to 0, the time will not be automatically obtained through the AT.

● Parameters computed by Input 2_Autotuning (AT)

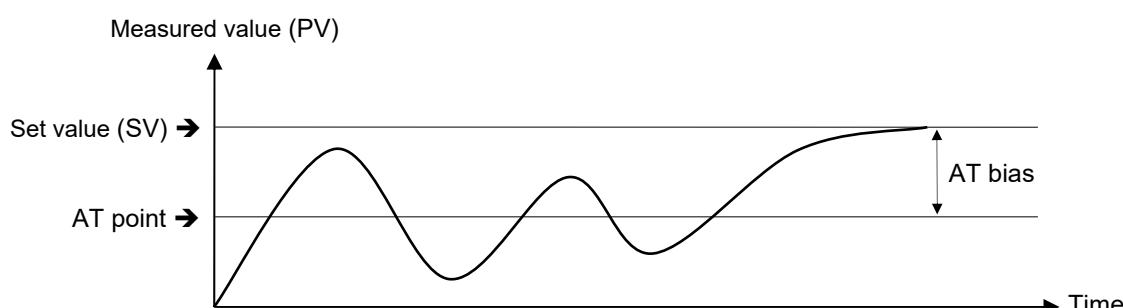
- Input 2_Proportional band
- Input 2_Integral time
- Input 2_Derivative time
- Input 2_Control loop break alarm (LBA) time * (The LBA time is automatically set to twice the value of the Integral time)

* When the Control break alarm (LBA) time is set to 0, the time will not be automatically obtained through the AT.

● AT bias

The AT bias is used to prevent overshoot during the Autotuning in the application which does not allow overshoot even during the Autotuning. RKC Autotuning method uses ON/OFF control at the set value to compute the PID values. However, if overshoot is a concern during the Autotuning, the desired AT bias should be set to lower the set point during Autotuning so that overshoot is prevented.

[Example] When AT bias is set to the minus (-) side.

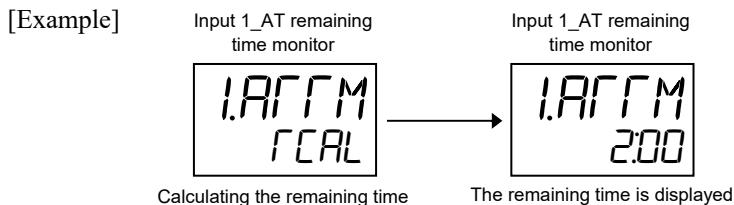


● AT remaining time monitor

Displays the remaining time until the Autotuning (AT) is completed.

(Display range: 0 hours 00 minutes to 48 hours 00 minutes)

The SV display shows “*ATRL*” from the start of Autotuning (AT) till the display of the remaining time. Once the remaining time is displayed, the time is reduced every minute.



The “AT remaining time monitor” is a predictive value and may not be accurate.

● AT/ST status monitor

Displays the execution status of the Autotuning (AT).

- Displays “1” during the Autotuning (AT).
- Displays “0” when the Autotuning (AT) is completed.
- When the Autotuning (AT) is aborted, the display shows –1 up to –4 depending on the reason of the abort.
 - 1: Aborted. Setting changed.
 - When the set value (SV) is changed.
 - When the AT bias is changed.
 - When the PV bias, PV ratio, or PV digital filter is changed.
 - When the Output limiter high or low is changed.
 - When the Autotuning (AT) is changed to PID control.
 - When the instrument is switched to STOP by RUN/STOP transfer.
 - When the instrument is switched to Manual mode using Auto/Manual transfer.
 - When the instrument is switched to Remote mode using Remote/Local transfer.
 - When the memory area is changed.
 - Number of knee point, Knee point input value or Knee point correction value is changed.
 - 2: Aborted. Abnormal input.
 - When the Measured value (PV) has entered the Input error range.

[Input error range: Input error determination point high ≥ Measured value (PV),
 Input error determination point low ≤ Measured value (PV)]
 - 3: Aborted. Timeout.
Output state has not been changed (ON to OFF, OFF to ON) for more than two hours.
 - 4: Aborted. Abnormal calculated values.
Error in the calculation of the values in Control with PV select.

● Caution for using the Autotuning (AT)

- When a temperature change (UP and/or Down) is 1 °C or less per minute during the Autotuning (AT), the Autotuning (AT) may not be finished normally. In that case, adjust the PID values manually. Manual setting of PID values may also be necessary if the set value is around the ambient temperature or is close to the maximum temperature achieved by the load.
- When the Output change rate limiter is used, you may not be able to obtain appropriate PID constants by Autotuning (AT).



For the manual setting of PID values, see **8.5 Setting PID Values Manually (P. 8-24)**.

● Requirements for Autotuning (AT) start

Start the Autotuning (AT) when all following conditions are satisfied:

To start Autotuning (AT), go to Operation transfer mode.

Operation state	RUN/STOP transfer	RUN
	Auto/Manual transfer	Auto mode
	Remote/Local transfer	Local mode
	Autotuning (AT) setting	PID control (State before starting AT)
Parameter setting	PID control of Input 1	Input 1_Output limiter high [heat-side] > 0 % Input 1_Output limiter low [heat-side] < 100 %
	PID control of Input 2	Input 2_Output limiter high > 0 % Input 2_Output limiter low < 100 %
	Heat/Cool PID control	Input 1_Output limiter high [heat-side] > 0 % Input 1_Output limiter low [heat-side] < 100 % Input 1_Output limiter high [cool-side] > 0 % Input 1_Output limiter low [cool-side] < 100 %
Input value state	The Measured value (PV) is not inside the Input error range. [Input error range: Input error determination point (high) ≥ Measured value (PV), Input error determination point (low) ≤ Measured value (PV)]	

● Requirements for Autotuning (AT) cancellation

The Autotuning (AT) is immediately aborted and PID control starts when an error is detected in “AT/ST status monitor.” The PID values will be the same as before the Autotuning (AT) was activated.



For details, see “AT/ST status monitor” on the previous page.

The Autotuning (AT) may be aborted in the following cases except for the conditions in “AT/ST status monitor.”

- When the instrument is in FAIL state.
- When the power supply is disconnected.

■ Parameter setting

● Input 1_Autotunning (AT) [Operation Transfer Mode]

Parameter symbol	Data range	Factory set value
1. $A\Gamma U$	<p><i>oFF</i>: PID control <i>on</i>: Start Autotuning When the Autotuning (AT) is finished, the control will automatically return to “<i>oFF</i>.”</p>	<i>oFF</i>

-  This parameter is not displayed when this parameter is fixed to “Fix parameter setting: Auto/Manual transfer” in the Setting lock mode.

● Input 2_Autotunning (AT) [Operation Transfer Mode]

Parameter symbol	Data range	Factory set value
2. $A\Gamma U$	<p><i>oFF</i>: PID control <i>on</i>: Start Autotuning When the Autotuning (AT) is finished, the control will automatically return to “<i>oFF</i>.”</p>	<i>oFF</i>

-  To display “Input 2_Autotunning (AT),” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.
-  This parameter is not displayed when this parameter is fixed to “Fix parameter setting: Auto/Manual transfer” in the Setting lock mode.

● Input 1_AT bias

[Setup Setting Mode: Setting group No. 53 (5n53)]

Parameter symbol	Data range	Factory set value
1. $A\Gamma b$	<p>–(Input 1_Input span) to +(Input 1_Input span)</p> <p>〔When Control with PV select: –(PV select input span) to +(PV select input span)〕</p> <p>[Varies with the setting of the Decimal point position.]</p>	0

● Input 1_AT bias

[Setup Setting Mode: Setting group No. 54 (5n54)]

Parameter symbol	Data range	Factory set value
2. $A\Gamma b$	<p>–(Input 2_Input span) to +(Input 2_Input span)</p> <p>[Varies with the setting of the Decimal point position.]</p>	0

-  To display “Input 2_AT bias,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

● **Input 1_AT remaining time monitor**
[Setup Setting Mode: Setting group No. 53 (5n53)]

Parameter symbol	Data range	Factory set value
1.RTGM	0 hours 00 minutes to 48 hours 00 minutes	—

● **Input 2_AT remaining time monitor**
[Setup Setting Mode: Setting group No. 54 (5n54)]

Parameter symbol	Data range	Factory set value
2.RTGM	0 hours 00 minutes to 48 hours 00 minutes	—

 To display “Input 2_AT remaining time monitor,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

● **Input 1_AT/ST status monitor**
[Setup Setting Mode: Setting group No. 53 (5n53)]

Parameter symbol	Data range	Factory set value
1.RUNE	0: AT/ST complete 1: AT running now 2: ST running now -1: Aborted. Setting changed. -2: Aborted. Abnormal input. -3: Aborted. Timeout. -4: Aborted. Abnormal calculated values.	—

● **Input 2_AT/ST status monitor**
[Setup Setting Mode: Setting group No. 54 (5n54)]

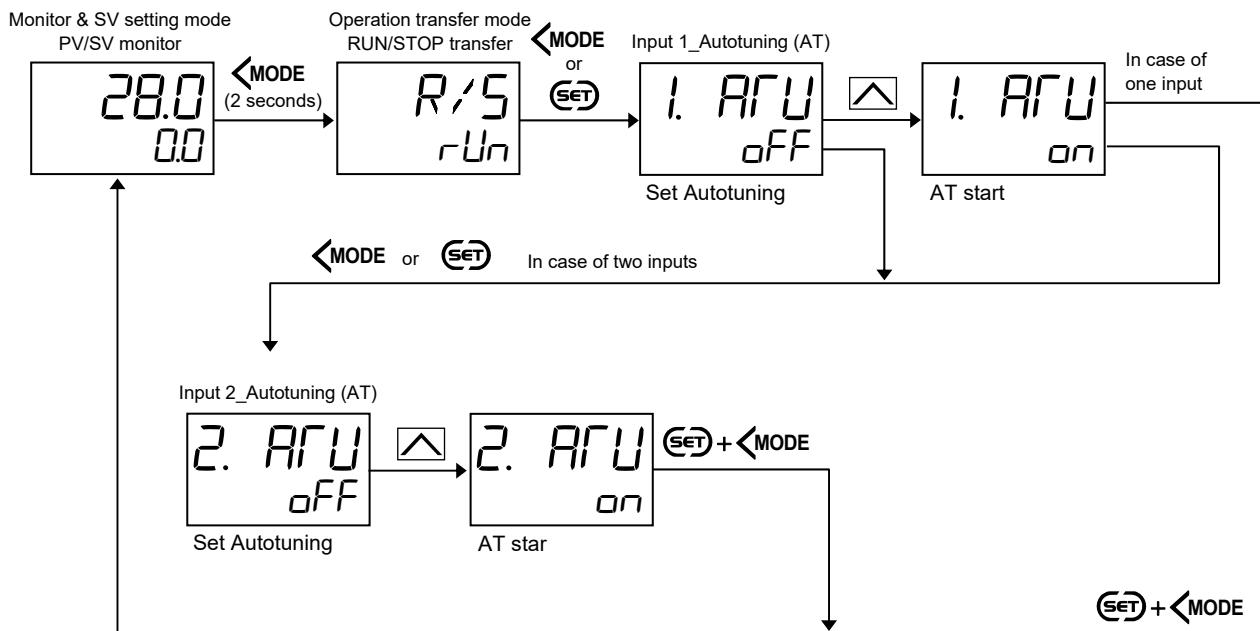
Parameter symbol	Data range	Factory set value
2.RUNE	0: AT/ST complete 1: AT running now 2: ST running now -1: Aborted. Setting changed. -2: Aborted. Abnormal input. -3: Aborted. Timeout. -4: Aborted. Abnormal calculated values.	—

 To display “Input 2_AT/ST status monitor,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

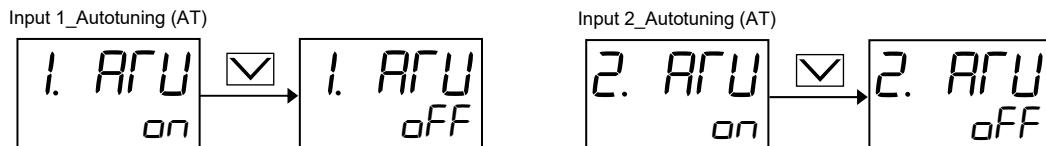
■ Setting procedure

● Start the Autotuning (AT)

Before starting the AT, see ● Requirements for Autotuning (AT) start (P. 8-13). Make sure that all required conditions to start the AT are satisfied.



Aborting the Autotuning (AT)



During the Autotuning (AT), the AT lamp blinks.



When the Autotuning (AT) is finished, the control will automatically return to “*off*: PID control” and the AT lamp turns off.

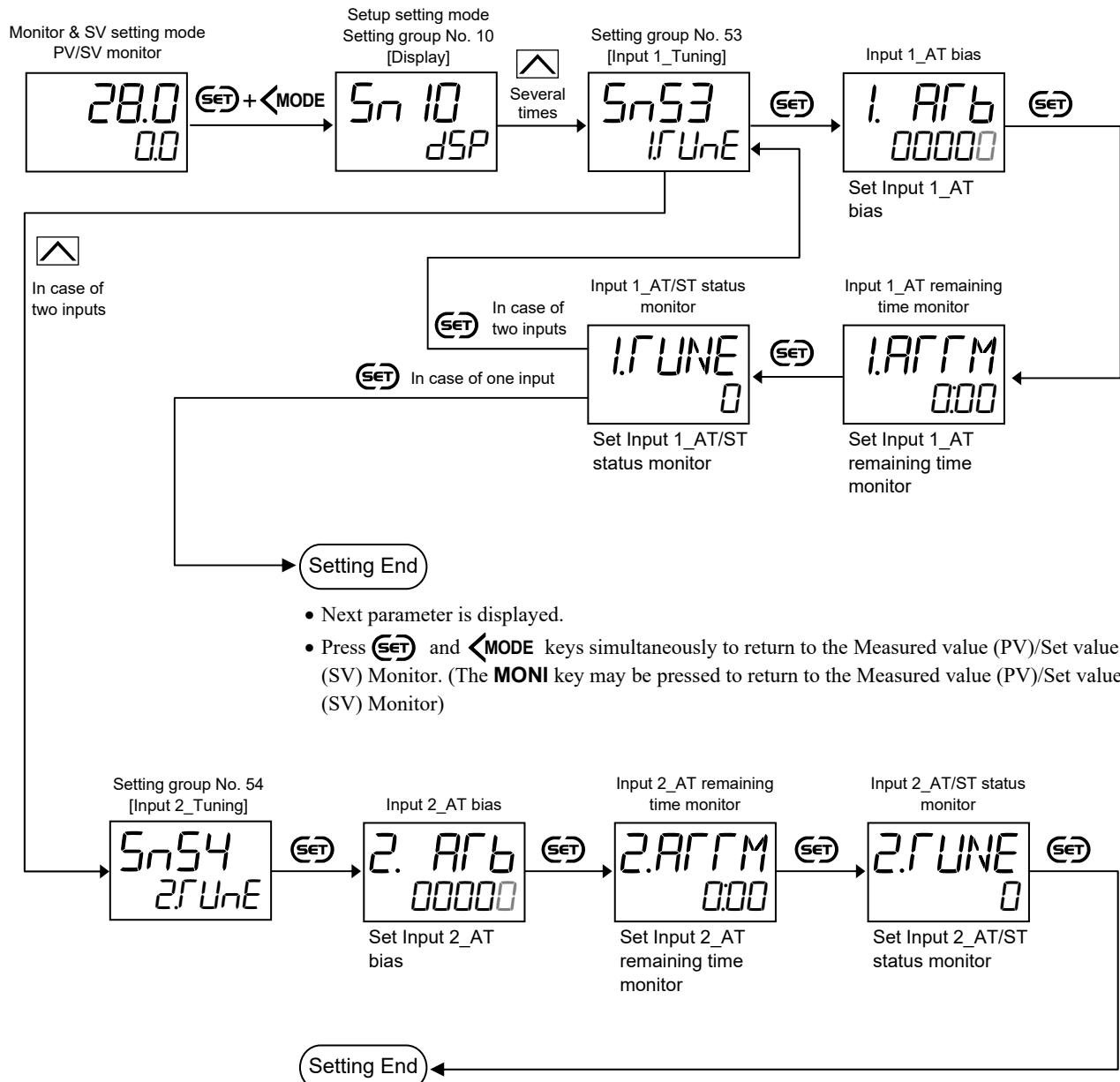


The Autotuning (AT) can be started by Digital input (DI). See “**5.2 Switching Functions Using Digital Inputs (DI) (P. 5-16)**” for more information on assigning Digital input (DI).



The Autotuning (AT) can be started by a key operation of the direct key (FUNC key). For details, see **10.8 Accessing Some Functions Directly (FUNC key) (P. 10-35)**.

● Setting AT bias, Check the AT remaining time and AT/ST status.



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

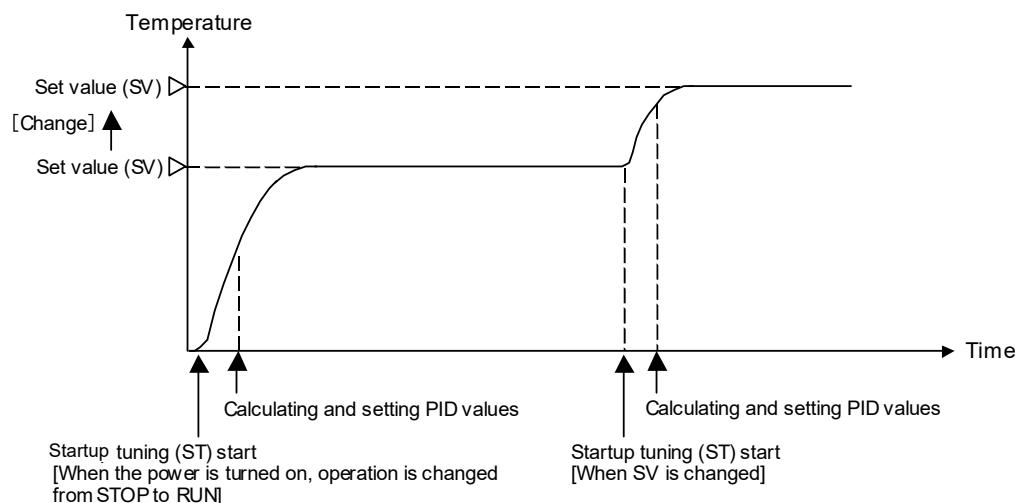
- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

8.4 Setting PID Values Automatically (Startup tuning)

Startup tuning (ST) is a function which automatically computes and sets the PID values and Control loop break alarm (LBA) time from the response characteristics of the controlled system at power ON, transfer from STOP to RUN, and Set value (SV) change.

■ Description of function

- As simple autotuning, the PID values can be obtained in a short time without disturbing controllability for controlled systems with slow response at power ON. At the same time, Control loop break alarm (LBA) time * is calculated (about twice of the Integral time).
- * When the Control break alarm (LBA) time is set to 0, the time will not be automatically obtained through the ST.
- For controlled systems which require different PID values for each temperature setting, the PID values can be obtained for each Set value (SV) change.



- The setting items related to the Startup tuning (ST) are shown below. Set them according to the application used.

Setting item	Details		Setting mode
Start condition	0 (Factory set value)	When the power is turned on, operation is changed from STOP to RUN, or the Set value (SV) is changed.	Engineering mode
	1	When the power is turned on or operation is changed from STOP to RUN.	
	2	When the Set value (SV) is changed.	
Execution method	<i>off</i> (Factory set value)	ST unused	Operation transfer mode
	<i>on 1</i>	Execute once	
	<i>on2</i>	Execute always	

- When the Startup tuning (ST) function is activated in Heat/Cool PID control, only heat-side PID values are calculated and changed. The Startup tuning (ST) is not available when the temperature is downward. (PID values for cooling cannot be calculated)
- If the Startup tuning (ST) is started when the ST start condition is at power on or switching from STOP to RUN, the control will start with Hot start 2 even if the setting is Hot start 1. For Hot/Cold start setting, see **8.17 Changing the Action at Power ON (Hot/Cold Start) (P. 8-98)**.

● AT/ST status monitor

Displays the execution status of the Startup tuning (ST).

- Displays “2” during the Startup tuning (ST).
- Displays “0” when the Startup tuning (ST) is completed.
- When the Startup tuning (ST) is aborted, the display shows –1 up to –4 depending on the reason of the abort.
 - 1: Aborted. Setting changed.
 - When the Startup tuning (ST) is disabled (*oFF*: ST unused).
 - When the PV bias, PV ratio, or PV digital filter is changed.
 - When the Output limiter high or low is changed.
 - When the instrument is switched to STOP by RUN/STOP transfer.
 - When the instrument is switched to Manual mode using Auto/Manual transfer.
 - When the instrument is switched to Remote mode using Remote/Local transfer.
 - When the setting of the Level PID action selection is “2: Switching by the Measured value (PV).”
 - Number of knee point, Knee point input value or Knee point correction value is changed.
 - 2: Aborted. Abnormal input.
When the Measured value (PV) has entered the Input error range.
[Input error range: Input error determination point high \geq Measured value (PV),
Input error determination point low \leq Measured value (PV)]
 - 3: Aborted. Timeout.
When the Startup tuning (ST) will not end approximately 100 minutes after it has been started.
 - 4: Aborted. Abnormal calculated values.
 - When the input was switched by Control with PV select.
 - Internal error of the Startup tuning (ST), etc.

● Caution for using the Startup tuning (ST)

- For the Startup tuning (ST) at power ON or transfer from STOP to RUN, always set the heater power to ON simultaneously with the start of tuning or before the start of tuning.
- Start the Startup tuning (ST) in the state in which the temperature differential between the Measured value (PV) and the Set value (SV) at the start of the Startup tuning (ST) is twice the Proportional band, or greater.
- If in the Heat/Cool PID control, start activating the Startup tuning (ST) function under the condition of “Set value (SV) > Measured value (PV).” Only the PID values on the heat-side are automatically calculated but no PID values on the cool-side are changed. The PID values on the cooling side can be obtained by the Autotuning (AT).
- When the Manipulated output value may be limited by the Output limiter setting, the optimum PID values may not be calculated by the Startup tuning (ST).
- When setting the Output change rate limiter, the optimum PID values may not be computed by Startup tuning (ST).
- When setting the Setting change rate limiter, the optimum PID values are not obtained even when Startup tuning (ST) is executed at Set value (SV) change.
- When the Startup tuning (ST) is started at power on, priority is given to the Startup tuning (ST) and the Proactive function will not start.

● Requirements for Startup tuning (ST) start

Start the Startup tuning (ST) when all following conditions are satisfied:

Operation state	RUN/STOP transfer	RUN
	Auto/Manual transfer	Auto mode
	Remote/Local transfer	Local mode
	Autotuning (AT) setting	PID control
Parameter setting	Startup tuning (ST) is set to ON (Execute once, Execute always)	
	Output limiter high $\geq 0.1\%$, Output limiter low $\leq 99.9\%$ [Heat/Cool PID control type: Output limiter high (heat-side) $\geq 0.1\%$]	
	The Level PID action selection is done by other than “Switching by the Measured value (PV).”	
Input value state	The Measured value (PV) is not underscale or over-scale.	
	Input error determination point (high) \geq Input value \geq Input error determination point (low)	
	At Startup tuning (ST) at Set value (SV) change, the Measured value (PV) shall be stabilized.	
Output value state	Set value (SV) $>$ Measured value (PV) [Heat/Cool PID control]	
Output value state	At startup, output is changed and saturated at the Output limiter high or the Output limiter low [Heat/Cool PID control type: Output limiter high (heat-side)].	

● Requirements for Startup tuning (ST) cancellation

The Startup tuning (ST) will be immediately aborted if any in the cancel condition in the AT/ST status monitor is met. The PID values will be the same as before the Startup tuning (ST) was activated.



For details, see “AT/ST status monitor” on the previous page.

The Startup tuning (ST) may be aborted in the following cases except for the conditions in “AT/ST status monitor.”

- Autotuning (AT) has been started.
- When the instrument is in FAIL state.
- When the power supply is disconnected.

■ Parameter setting

● Input 1_Startup tuning (ST) [Operation Transfer Mode]

Parameter symbol	Data range	Factory set value
I. STU	OFF: ST unused on 1: Execute once * on2 Execute always * When the ST is finished, the control will automatically return to “OFF.”	OFF

● **Input 2_Startup tuning (ST)
[Operation Transfer Mode]**

Parameter symbol	Data range	Factory set value
2. SFU	<p>oFF: ST unused on 1: Execute once * on2 Execute always * When the ST is finished, the control will automatically return to “oFF.”</p>	oFF

 To display “Input 2_Startup tuning (ST),” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

● **Input 1_AT/ST status monitor
[Setup Setting Mode: Setting group No. 53 (5n53)]**

Parameter symbol	Data range	Factory set value
IFUNE	<p>0: AT/ST complete 1: AT running now 2: ST running now -1: Aborted. Setting changed. -2: Aborted. Abnormal input. -3: Aborted. Timeout. -4: Aborted. Abnormal calculated values.</p>	—

● **Input 2_AT/ST status monitor
[Setup Setting Mode: Setting group No. 54 (5n54)]**

Parameter symbol	Data range	Factory set value
2FUNE	<p>0: AT/ST complete 1: AT running now 2: ST running now -1: Aborted. Setting changed. -2: Aborted. Abnormal input. -3: Aborted. Timeout. -4: Aborted. Abnormal calculated values.</p>	—

 To display “Input 2_AT/ST status monitor,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

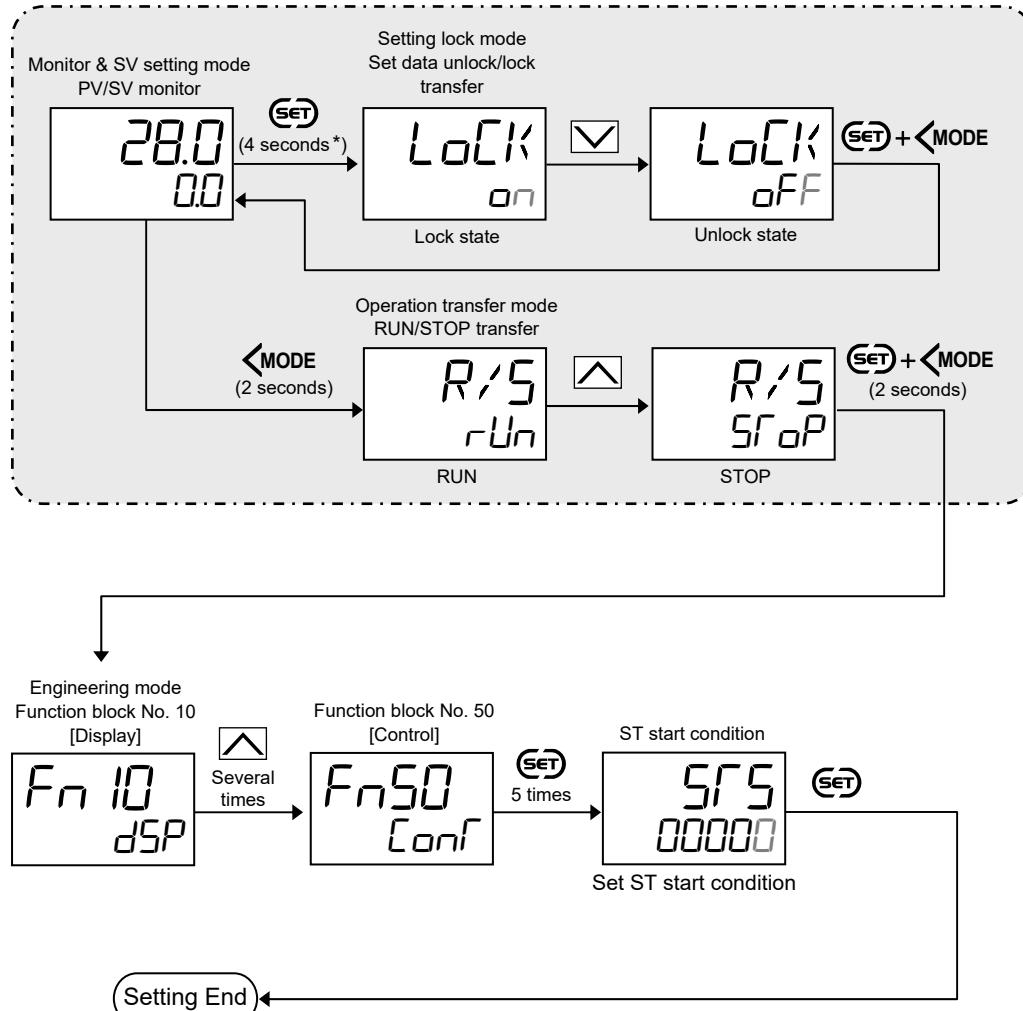
● **ST start condition
[Engineering Mode: Function block No. 50 (Fn50)]**

Parameter symbol	Data range	Factory set value
SFS	<p>0: Activate the Startup tuning (ST) function when the power is turned on; when transferred from STOP to RUN; or when the Set value (SV) is changed. 1: Activate the Startup tuning (ST) function when the power is turned on; or when transferred from STOP to RUN. 2: Activate the Startup tuning (ST) function when the Set value (SV) is changed.</p>	0

■ Setting procedure

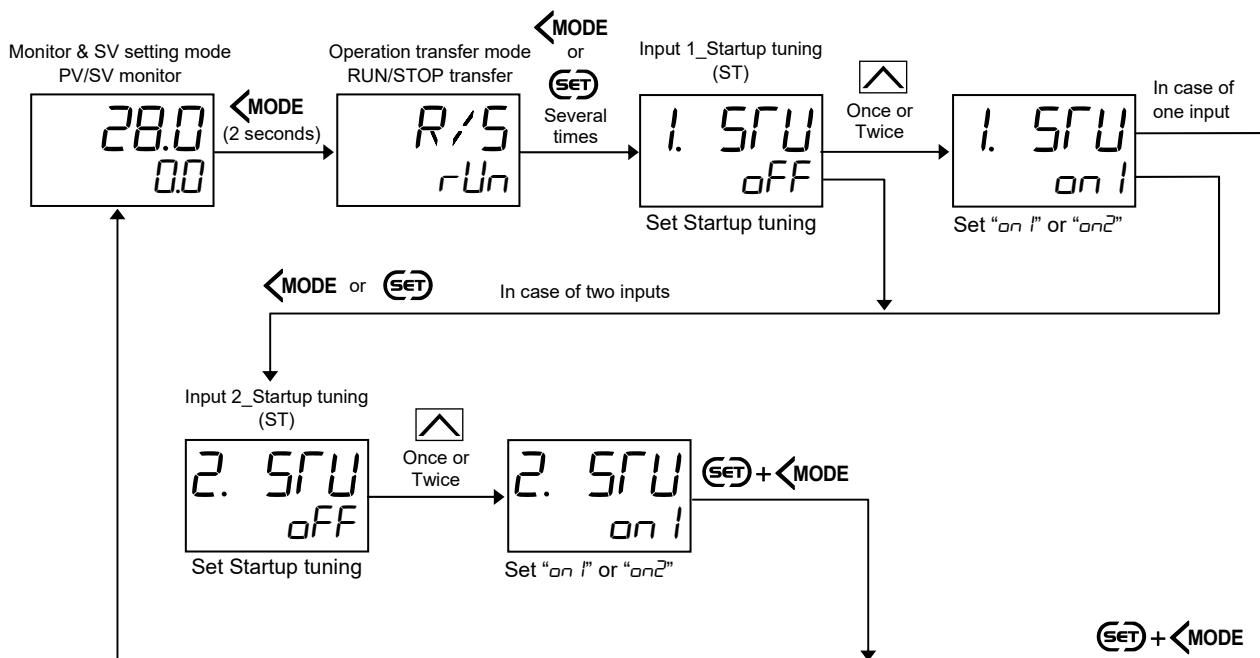
● Set the ST start condition

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.

● Set the Startup tuning (ST)



● Start the Startup tuning (ST)

Before starting the ST, see **● Requirements for Startup tuning (AT) start (P. 8-20)**. Make sure that all required conditions to start the ST are satisfied.

Startup tuning can be started in the following manner. (started in the manner that satisfies the starting condition)

- Power off the controller once and power on again.
- Stop the control once (STOP) and start the control again (RUN).
- Change the Set value (SV).



The AT lamp lights during the Startup tuning (ST).



After completion of the Startup tuning (ST), the AT lamp goes off.

When the Startup tuning setting is “on I: Execute once,” the setting will go back to “off: ST unused” automatically.

8.5 Setting PID Values Manually

To perform PID control, PID parameters shown below need to be set up. These PID parameters can be automatically set using Autotuning (AT) or Startup tuning (ST). Manual adjustment is also available.

- Proportional band (P)
- Integral time (I)
- Derivative time (D)

 For Autotuning (AT) function, see **8.3 Setting PID Values Automatically (Autotuning) (P. 8-11)**.
For Startup tuning (ST) function, see **8.4 Setting PID Values Automatically (Startup tuning) (P. 8-18)**.

■ Description of function

Critical parameters of PID control such as Proportional action (Proportional band: P), Integral action (Integral time: I), and Derivative action (Derivative time: D) are explained below.

Note that this explanation is based on the reverse action (heating control). With the direct action (cooling control), the output increases as the measured value increases.

● Proportional action

In the ON/OFF control action, the manipulated output is turned on and off repeatedly, resulting in oscillatory control.

To eliminate this oscillation, control is performed by producing Manipulated output value (MV) proportional to the deviation between the Set value (SV) and the Measured value (PV).

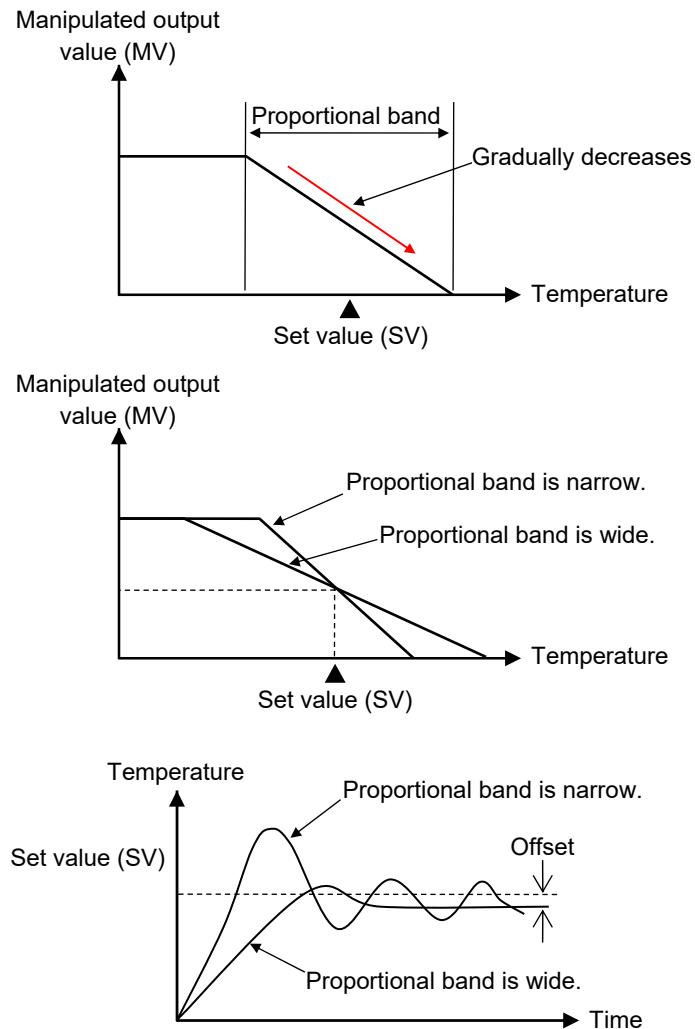
Technically a zone called “Proportional band” is established around the Set value (SV) and when the Measured value (PV) enters the proportional band, the Manipulated output value (MV) is gradually reduced.

The Measured value (PV) stabilizes within the Proportional band at the equilibrium point, but in many cases the stabilized temperature does not match the Set value (SV).

This deviation between the Set value (SV) and the stabilized temperature is called “Offset.”

With a narrower proportional band the control result becomes closer to that of the ON/OFF control (oscillatory).

With a wider proportional band the output is gradually reduced to stabilize quicker, however, often with a larger offset.



 For ON/OFF action,
see **8.6 Controlling with ON/OFF
Action (P. 8-31)**.

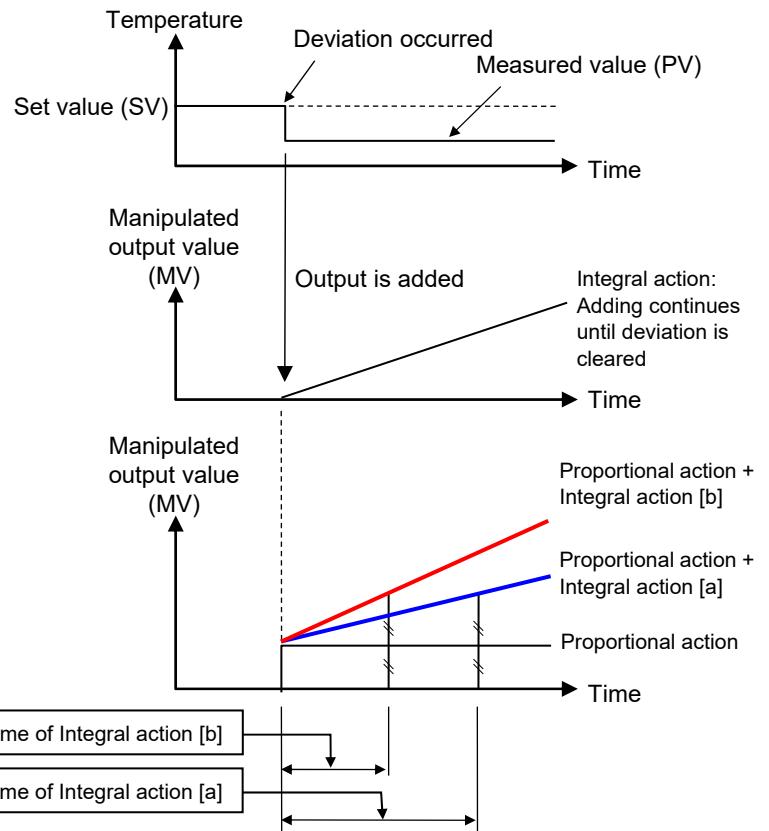
● Integral action

Proportional action provides more stable control than ON/OFF control, but causes offset. This offset can be automatically corrected by Integral action.

As long as deviation exists between the Set value (SV) and the Measured value (PV), the Manipulated output value (MV) is added according to the size of the deviation until no deviation exists.

The strength of the Integral action is expressed by the Integral time. The Integral time is the time till the Manipulated output value (MV) by the Integral action gets equal to that by the Proportional action.

The shorter the Integral time, the stronger the integral effect is, and the longer the weaker.

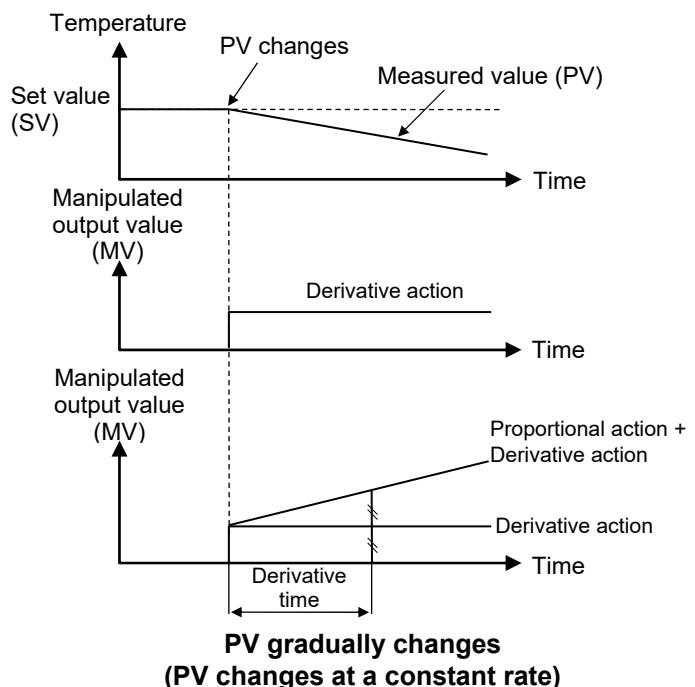
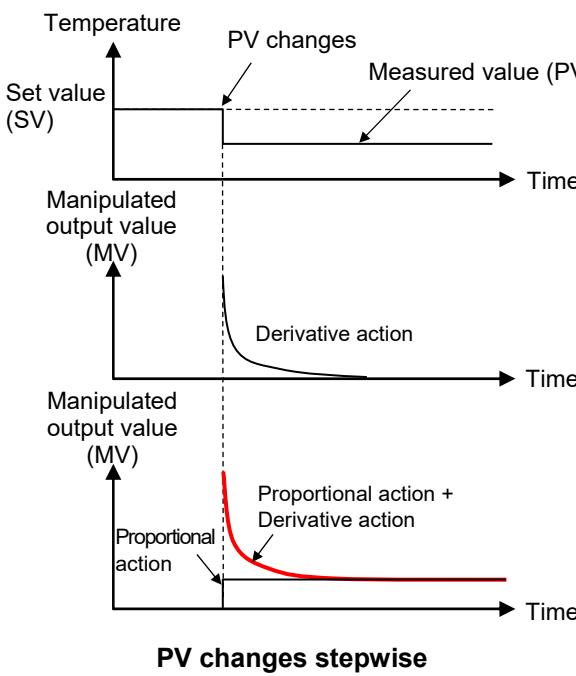


● Derivative action

The Derivative action allows the Manipulated output value (MV) proportional to the changing rate (speed) of the Measured value (PV) to be produced to prevent a fluctuation of the Measured value (PV) before it happens. The strength of the Derivative action is expressed in the Derivative time. The Derivative time is the time until the Manipulated output value (MV) by the Proportional action gets equal to the Manipulated output value (MV) by the Derivative action when the Measured value (PV) changes at a constant rate.

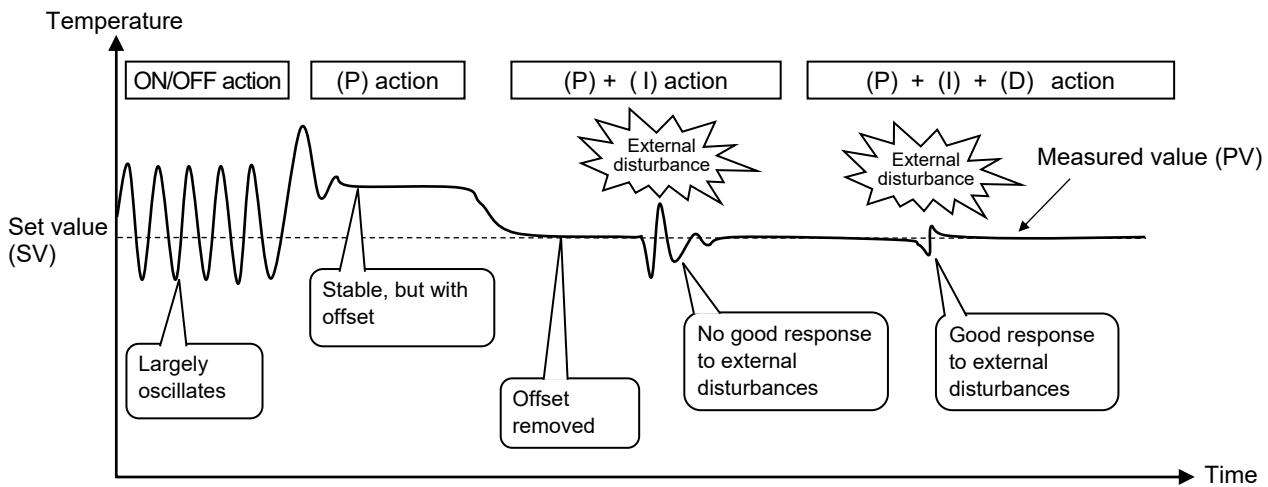
The longer the Derivative time is, the stronger the Derivative effect is, and the shorter the weaker.

The Derivative effect, if set too strong, produces large Manipulated output (MV) against a small change of the Measured value (PV), thus causing hunting and resulting in unstable control.



● Outline of effect of PID

The following figure shows control behaviors under various control actions; ON/OFF control, proportional control (P), Proportional + Integral action (PI action), and Proportional + Integral + Derivative actions (PID control).



● Adjusting PID parameters (Applications controlled with PID control)

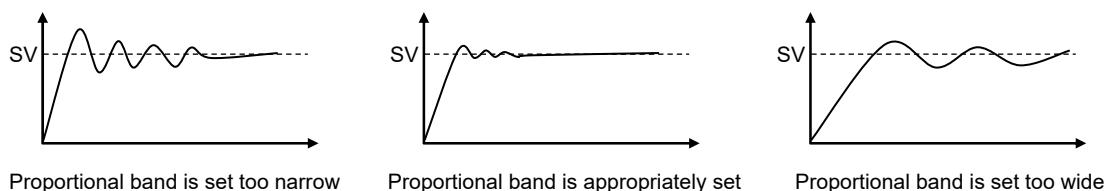
In some applications PID values calculated and obtained through Autotuning (AT) and Startup tuning (ST) may not be appropriate. In such a case the PID values need to be adjusted manually.

Attempt this adjustment referring to the following.

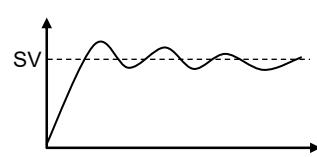
The sample here shows a general tendency. Control results depend on the controlled object and combinations of control constants.

[Adjustment of Proportional band (P)]

Setting the proportional band as small as possible enables the Set value (SV) to be reached faster without overshoot. However, if the proportional band is set too narrow, it will cause hunting and the manipulated output (MV) will become oscillating.



[Adjustment of Integral time (I) and Derivative time (D)]

Made larger (wider, longer)	Made smaller (narrower, shorter)
<p>Overshoot, undershoot and hunting are suppressed.</p> <p>Setting the value too long may need longer time till the Set value (SV) is reached.</p> 	<p>Starts up quickly.</p> <p>Setting the value too short may cause overshoot, undershoot or hunting.</p> 

■ Parameter setting

- **Input 1_Proportional band [heat-side]**
[Parameter Setting Mode: Parameter group No. 51 (P_{n51})]

Parameter symbol	Data range	Factory set value
1. P	TC/RTD inputs: 0 (0.0, 0.00) to Input 1_Input span (Unit: °C [°F]) (When Control with PV select: 0 to PV select input span) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.0 to 1000.0 % of Input 1_Input span (When Control with PV select: 0.0 to 1000.0 % of PV select input span) 0 (0.0, 0.00): ON/OFF action	TC/RTD inputs: 30 V/I inputs: 3.0

- **Input 2_Proportional band**
[Parameter Setting Mode: Parameter group No. 52 (P_{n52})]

Parameter symbol	Data range	Factory set value
2. P	TC/RTD inputs: 0 (0.0, 0.00) to Input 2_Input span (Unit: °C [°F]) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.0 to 1000.0 % of Input 2_Input span 0 (0.0, 0.00): ON/OFF action	TC/RTD inputs: 30 V/I inputs: 3.0

 To display “Input 2_Proportional band,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

- **Input 1_Proportional band [cool-side]**
[Parameter Setting Mode: Parameter group No. 56 (P_{n56})]

Parameter symbol	Data range	Factory set value
1. P_C	TC/RTD inputs: 1 (0.1, 0.01) to Input 1_Input span (Unit: °C [°F]) (When Control with PV select: 1 to PV select input span) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.1 to 1000.0 % of Input 1_Input span (When Control with PV select: 0.1 to 1000.0 % of PV select input span)	TC/RTD inputs: 30 V/I inputs: 3.0

 To display “Input 1_Proportional band [cool-side],” you need to specify “Heat/Cool PID control” at the time of order, AND to enter a value other than 0 in the Input 1_Proportional band [heat-side] in the same memory area.

● Input 1_Integral time [heat-side]

[Parameter Setting Mode: Parameter group No. 51 ($P_{n5} \text{ I}$)]

Parameter symbol	Data range	Factory set value
I_1	PID control or Heat/Cool PID control: 0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds 0 (0.0, 0.00, 0.000): PD action [Varies with the setting of the Integral/Derivative time decimal point position.]	240.00



To display “Input 1_Integral time [heat-side],” you need to enter a value other than 0 in the Input 1_Proportional band [heat-side] in the same memory area.

● Input 2_Integral time

[Parameter Setting Mode: Parameter group No. 52 (P_{n52})]

Parameter symbol	Data range	Factory set value
I_2	0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds 0 (0.0, 0.00, 0.000): PD action [Varies with the setting of the Integral/Derivative time decimal point position.]	240.00



To display “Input 2_Integral time,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control. Additionally, you also need to enter a value other than 0 in the Input 2_Proportional band in the same memory area.

● Input 1_Integral time [cool-side]

[Parameter Setting Mode: Parameter group No. 56 (P_{n56})]

Parameter symbol	Data range	Factory set value
$I_1 \text{ C}$	0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds 0 (0.0, 0.00, 0.000): PD action [Varies with the setting of the Integral/Derivative time decimal point position.]	240.00



To display “Input 1_Integral time [cool-side],” you need to specify “Heat/Cool PID control” at the time of order, AND to enter a value other than 0 in the Input 1_Proportional band [heat-side] in the same memory area.

● Input 1_Derivative time [heat-side]

[Parameter Setting Mode: Parameter group No. 51 ($P_{n5} \text{ I}$)]

Parameter symbol	Data range	Factory set value
D_1	0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds 0 (0.0, 0.00, 0.000): PI action [Varies with the setting of the Integral/Derivative time decimal point position.]	60.00



To display “Input 1_Derivative time [heat-side],” you need to enter a value other than 0 in the Input 1_Proportional band [heat-side] in the same memory area.

● Input 2_Derivative time

[Parameter Setting Mode: Parameter group No. 52 (P_{n52})]

Parameter symbol	Data range	Factory set value
2. d	0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds 0 (0.0, 0.00, 0.000): PI action [Varies with the setting of the Integral/Derivative time decimal point position.]	60.00



To display “Input 2_Derivative time,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control. Additionally, you also need to enter a value other than 0 in the Input 2_Proportional band in the same memory area.

● Input 1_Derivative time [cool-side]

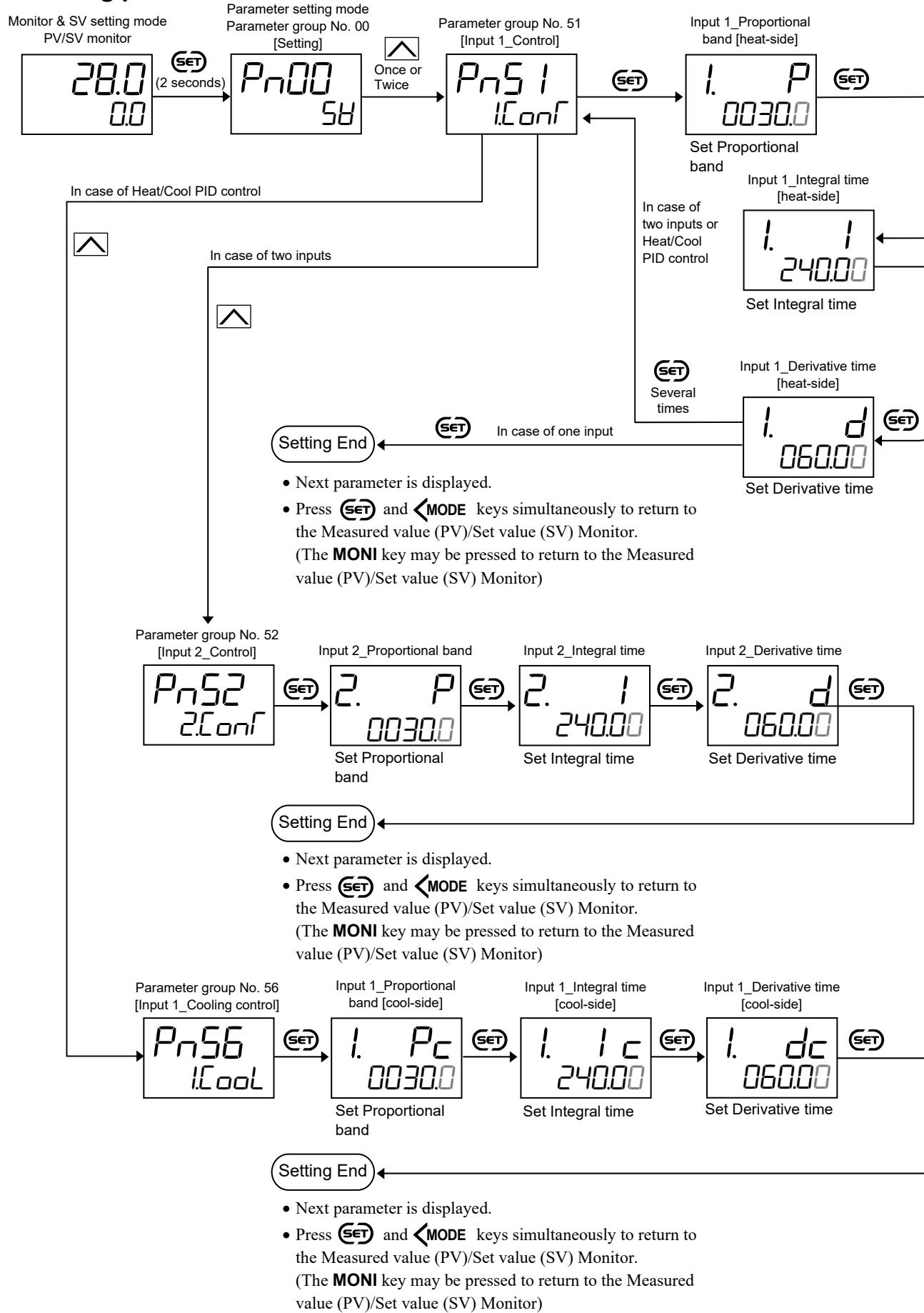
[Parameter Setting Mode: Parameter group No. 56 (P_{n56})]

Parameter symbol	Data range	Factory set value
1. dc	0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds 0 (0.0, 0.00, 0.000): PI action [Varies with the setting of the Integral/Derivative time decimal point position.]	60.00



To display “Input 1_Derivative time [cool-side],” you need to specify “Heat/Cool PID control” at the time of order, AND to enter a value other than 0 in the Input 1_Proportional band [heat-side] in the same memory area.

■ Setting procedure



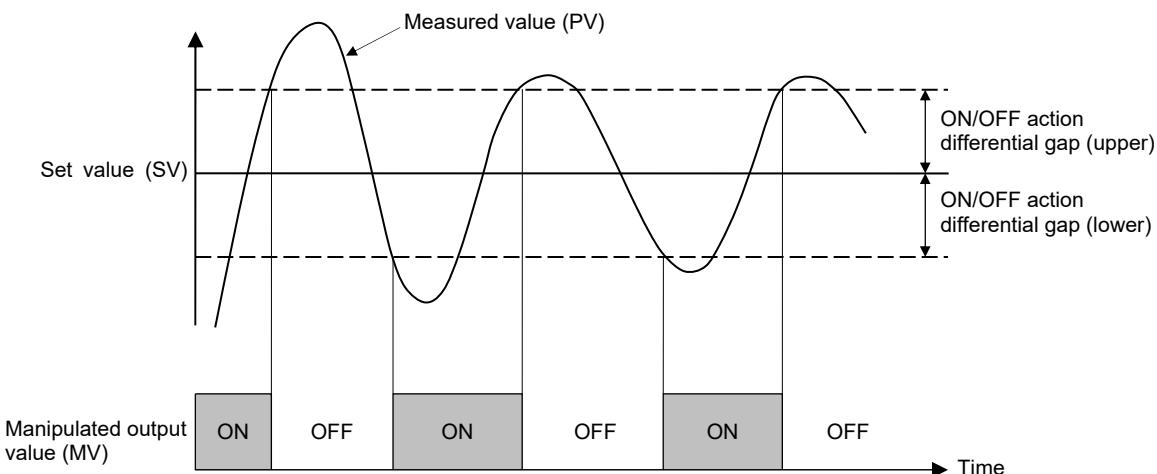
8.6 Controlling with ON/OFF Action

In ON/OFF control, the Manipulated output value (MV) is turned on or off depending on the Measured value (PV) whether it is above or below the Set value (SV).

■ Description of function

When the Measured value (PV) is above the Set value (SV), the Manipulated output value (MV) is turned OFF, and when the Measured value (PV) is below the Set value (SV), the Manipulated output value (MV) is turned ON. **To use the ON/OFF control, set the Proportional band [heat-side] to “0.”**

In the ON/OFF control the output is turned on and off around the Set value (SV) and the output may be turned on and off too frequently for a small change of temperature. This is called “chattering” and may reduce the life of the output relay. To prevent this, ON/OFF differential gap should be properly set.



This explanation applies to “Reverse action” (heating control).



The value of the ON/OFF action differential gap is a deviation from the Set value (SV). This gap can be set individually above and below the Set value (SV). For example, in case of a Reverse action (heating control), assuming that the Set value (SV) is 100 °C with a ON/OFF action differential gap (upper) of 5 °C, the Manipulated output value (MV) turns off at 105 °C.



In case of ON/OFF action, the Output changing rate limiter is deactivated.

● Cooling control with ON/OFF action

The process of Input 1 can be controlled with the ON/OFF action for the Cooling side (direct action) by setting zero to the Input 1_Proportional band [heat-side] after “0: PID control (direct action)” is set at “Input 1_Control action” in Function block No. 51 in the Engineering mode.

The process of Input 2 can be controlled with the ON/OFF action for the Cooling side (direct action) by setting zero to the Input 2_Proportional band after “0: PID control (direct action)” is set at “Input 2_Control action” in Function block No. 52 in the Engineering mode.

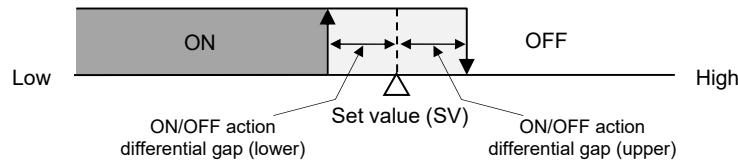
The action is the same as above, but the ON/OFF position of the Manipulated output value (MV) becomes opposite. The ON/OFF action differential gap can be set similarly.

● Heat/Cool control with ON/OFF action

Go to “Input 1_Control action,” Function block No.51 in the Engineering mode.

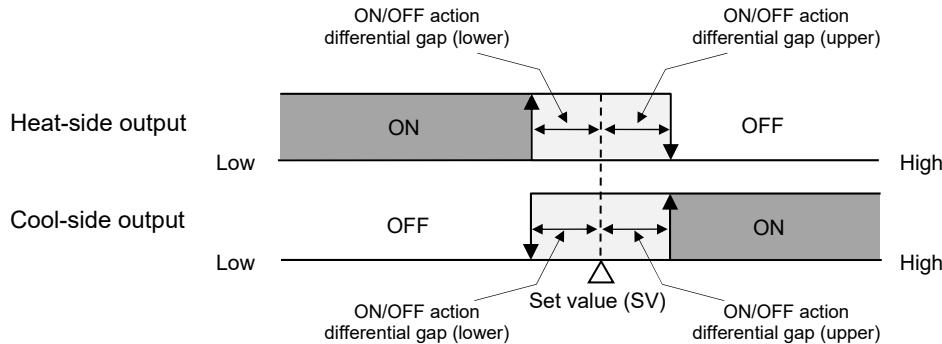
Select any one from “2: Heat/Cool PID control [water cooling],” “3: Heat/Cool PID control [air cooling],” or “4: Heat/Cool PID control [Cooling linear type]” and set “0” at the Input 1_Proportional band [heat-side]. Then, the controller starts Heat/Cool control with ON/OFF action.

Manipulated output for ON/OFF action [at Heating control]

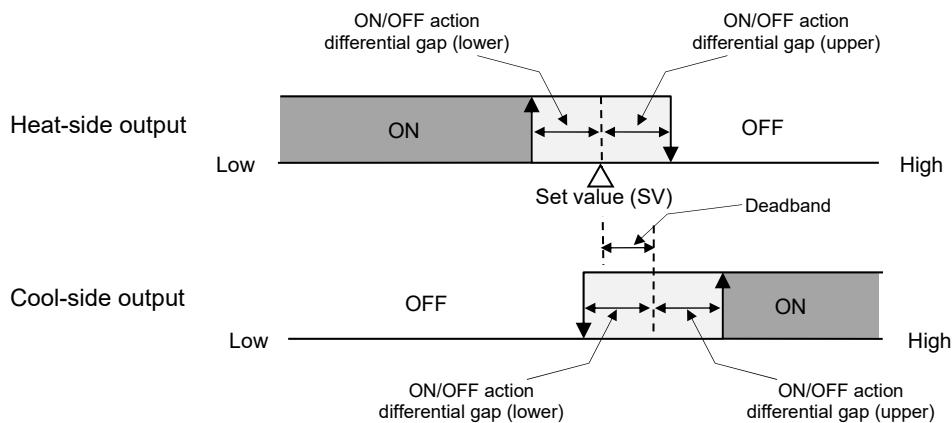


Manipulated output for ON/OFF action [at Heat/Cool control]

● Overlap/Deadband = 0



● Overlap/Deadband > 0



■ Parameter setting

- **Input 1_Proportional band [heat-side]**
[Parameter Setting Mode: Parameter group No. 51 ($P_{n5\ 1}$)]

Parameter symbol	Data range	Factory set value
1. P	TC/RTD inputs: 0 (0.0, 0.00) to Input 1_Input span (Unit: °C [°F]) (When Control with PV select: 0 to PV select input span) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.0 to 1000.0 % of Input 1_Input span (When Control with PV select: 0.0 to 1000.0 % of PV select input span) 0 (0.0, 0.00): ON/OFF action	TC/RTD inputs: 30 V/I inputs: 3.0

- **Input 2_Proportional band**
[Parameter Setting Mode: Parameter group No. 52 (P_{n52})]

Parameter symbol	Data range	Factory set value
2. P	TC/RTD inputs: 0 (0.0, 0.00) to Input 2_Input span (Unit: °C [°F]) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.0 to 1000.0 % of Input 2_Input span 0 (0.0, 0.00): ON/OFF action	TC/RTD inputs: 30 V/I inputs: 3.0

 To display “Input 2_Proportional band,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

- **Input 1_ON/OFF action differential gap (upper)**
[Parameter Setting Mode: Parameter group No. 51 ($P_{n5\ 1}$)]

Parameter symbol	Data range	Factory set value
1. ΔHH	TC/RTD inputs: 0 (0.0, 0.00) to Input 1_Input span (Unit: °C [°F]) (When Control with PV select: 0 to PV select input span) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.0 to 100.0 % of Input 1_Input span (When Control with PV select: 0.0 to 100.0 % of PV select input span)	TC/RTD inputs: 1 V/I inputs: 0.1

 To display “Input 1_ON/OFF action differential gap (upper),” zero (“0”) must be entered at Input 1_Proportional band [heat-side].”

● **Input 1_ON/OFF action differential gap (lower)**
[Parameter Setting Mode: Parameter group No. 51 (Pn51)]

Parameter symbol	Data range	Factory set value
1. ΔHL	TC/RTD inputs: 0 (0.0, 0.00) to Input 1_Input span (Unit: °C [°F]) (When Control with PV select: 0 to PV select input span) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.0 to 100.0 % of Input 1_Input span (When Control with PV select: 0.0 to 100.0 % of PV select input span)	TC/RTD inputs: 1 V/I inputs: 0.1

-  To display “Input 1_ON/OFF action differential gap (lower),” zero (“0”) must be entered at Input 1_Proportional band [heat-side].”

● **Input 2_ON/OFF action differential gap (upper)**
[Parameter Setting Mode: Parameter group No. 52 (Pn52)]

Parameter symbol	Data range	Factory set value
2. ΔHH	TC/RTD inputs: 0 (0.0, 0.00) to Input 2_Input span (Unit: °C [°F]) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.0 to 100.0 % of Input 2_Input span	TC/RTD inputs: 1 V/I inputs: 0.1

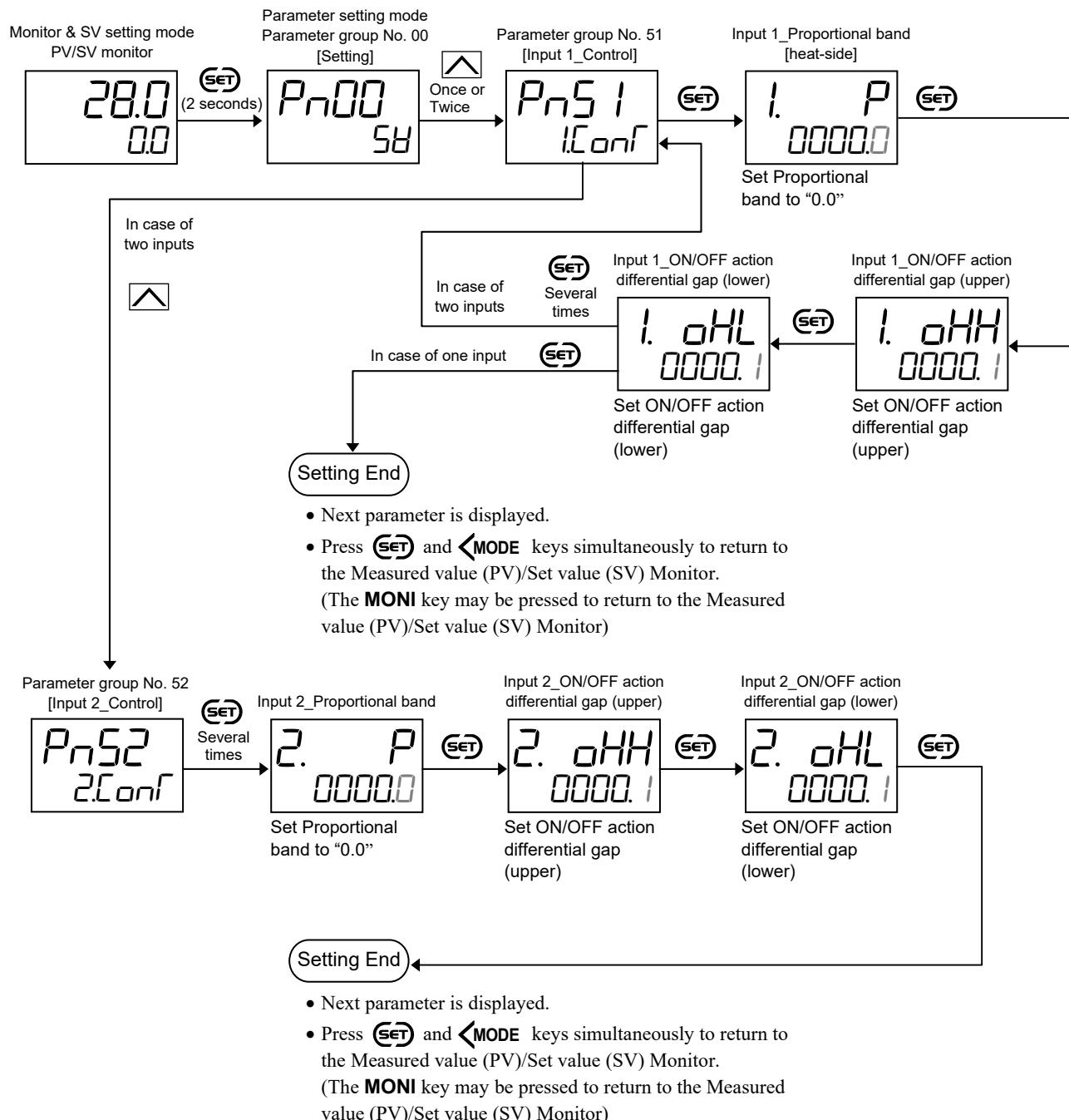
-  To display “Input 2_ON/OFF action differential gap (upper),” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control. You also need to enter zero (“0”) at the Input 2_Proportional band.

● **Input 2_ON/OFF action differential gap (lower)**
[Parameter Setting Mode: Parameter group No. 52 (Pn52)]

Parameter symbol	Data range	Factory set value
2. ΔHL	TC/RTD inputs: 0 (0.0, 0.00) to Input 2_Input span (Unit: °C [°F]) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.0 to 100.0 % of Input 2_Input span	TC/RTD inputs: 1 V/I inputs: 0.1

-  To display “Input 2_ON/OFF action differential gap (lower),” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control. You also need to enter zero (“0”) at the Input 2_Proportional band.

■ Setting procedure



8.7 Controlling with Heat/Cool Control

With Heat/Cool PID control method, heat-side and cool-side can be controlled by a controller. For example, this is effective when cooling control is required in extruder cylinder temperature control.

■ Description of function

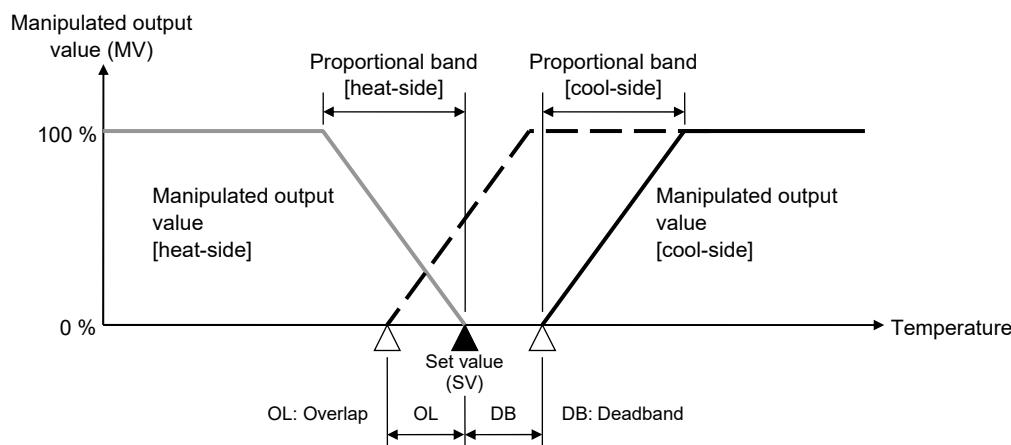
● Cool control type

The control on the heat-side is the same as the standard PID control. The control on the cool-side can be selected from a few types according to the controlled object.

- Water cooling/Air cooling: The algorithm assuming plastic molding machine Heat/Cool control is employed. Even in equipment provided with a cooling mechanism having nonlinear characteristics, it responds quickly to attain the characteristic responding to the set value with small overshooting.
- Cooling linear type: The algorithm assuming applications without nonlinear cooling capability is employed.

● Overlap/Deadband

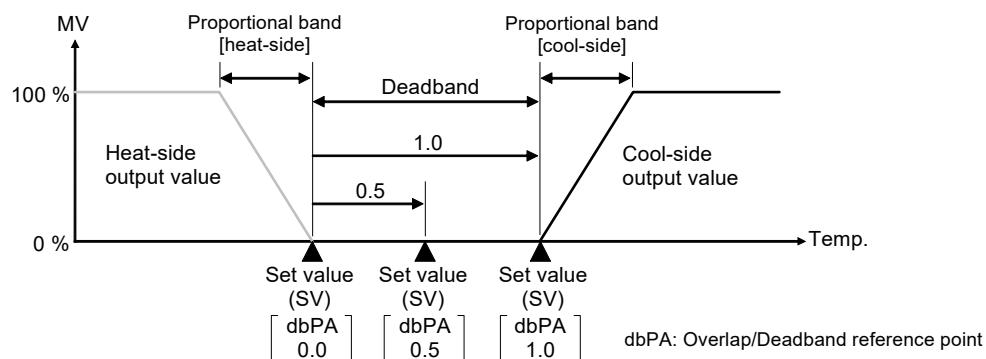
Heat/Cool PID control has a proportional band individually on each side of the heating and the cooling. With the Set value (SV) as a reference point, setting the Overlap/Deadband below the Set value (SV) [setting on the negative side] generates an overlap of the heating and the cooling proportional bands. Setting this parameter above the Set value (SV) [setting on the positive side] generates a deadband.



[Overlap/Deadband reference point]

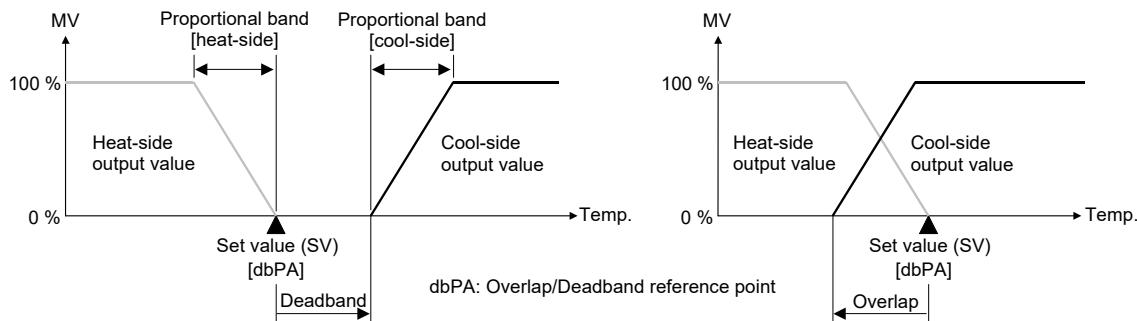
Each Set value (SV) for the Heat/Cool PID control becomes the Overlap/Deadband reference point.

- When setting 0.0, Overlap/Deadband reference point is at 0 % of the output at Proportional band [heat-side].
- When setting 0.5, Overlap/Deadband reference point is at the midpoint of the Overlap/Deadband.
- When setting 1.0, Overlap/Deadband reference point is at 0 % of the output at Proportional band [cool-side].

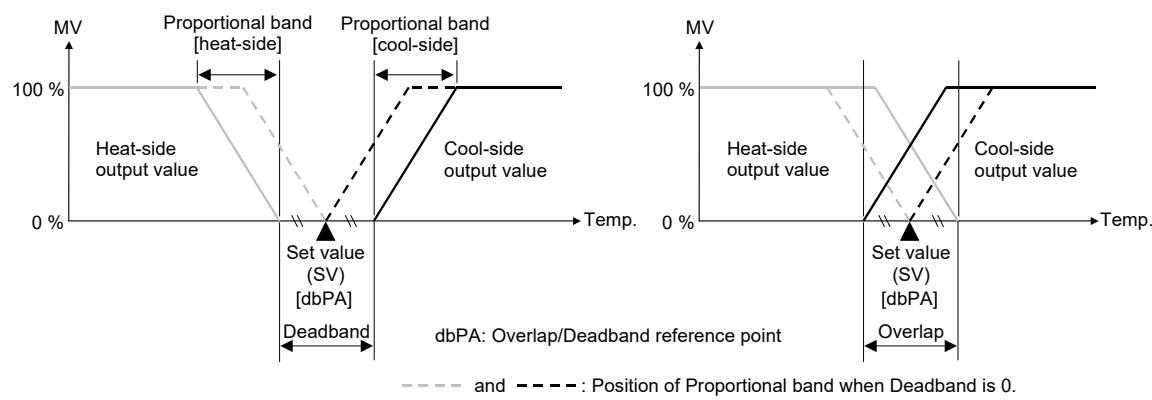


Example: Difference in Overlap/Deadband reference point

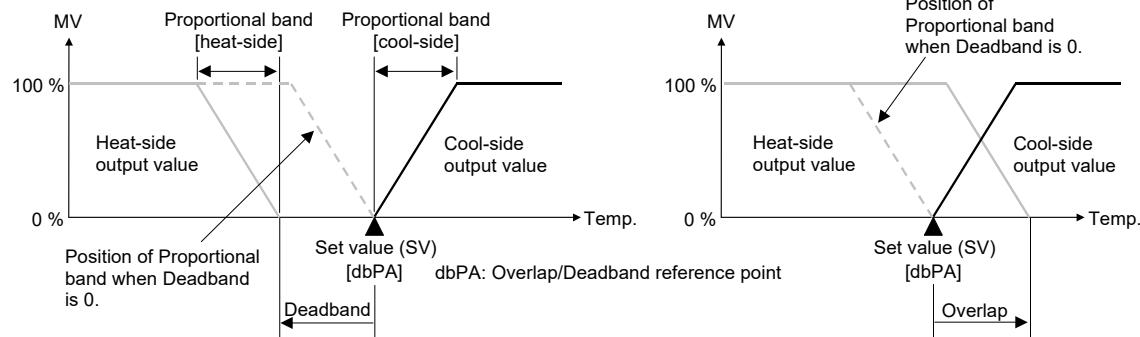
[Overlap/Deadband reference point: 0.0]



[Overlap/Deadband reference point: 0.5]



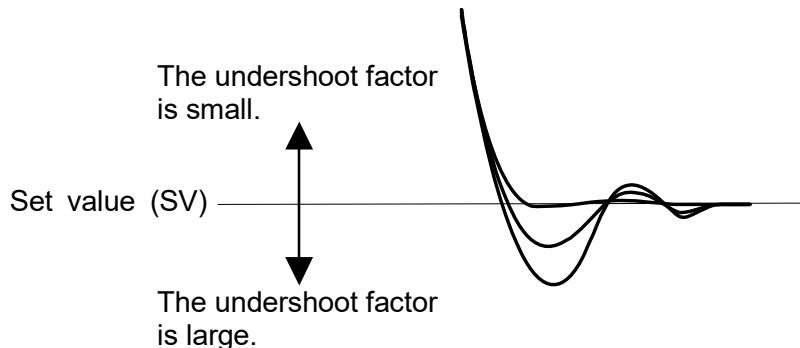
[Overlap/Deadband reference point: 1.0]



- To change Deadband when the Overlap/Deadband reference point is 0.5, the Proportional band on heat-side and cool-side shift equidistantly to the midpoint of the Overlap/Deadband.

● Undershoot suppression factor

The Undershoot suppression function suppresses the undershoot that occurs when the Set value (SV) is lowered due to the special cooling characteristic (cooling nonlinear characteristic) of plastic molding machines. The undershoot suppression effect increases as a smaller value is set for the Undershoot suppression factor.



NOTE

If the Undershoot suppression factor is set too small, the undershoot function acts excessively and prevents the Measured value (PV) from reaching the Set value (SV). As a result, the PV stabilizes at an offset or approaches the set value very slowly, preventing normal control. In this event, change the setting for the Undershoot suppression factor to a slightly higher value.

■ Parameter setting

● Input 1_Proportional band [heat-side]

[Parameter Setting Mode: Parameter group No. 51 ($P_{n5} I$)]

Parameter symbol	Data range	Factory set value
$I_1 P$	TC/RTD inputs: 0 (0.0, 0.00) to Input 1_Input span (Unit: °C [°F]) (When Control with PV select: 0 to PV select input span) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.0 to 1000.0 % of Input 1_Input span (When Control with PV select: 0.0 to 1000.0 % of PV select input span) 0 (0.0, 0.00): ON/OFF action	TC/RTD inputs: 30 V/I inputs: 3.0

● **Input 1_Proportional band [cool-side]**
[Parameter Setting Mode: Parameter group No. 56 (Pn56)]

Parameter symbol	Data range	Factory set value
$I.$ P_C	TC/RTD inputs: 1 (0.1, 0.01) to Input 1_Input span (Unit: °C [°F]) (When Control with PV select: 1 to PV select input span) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: 0.1 to 1000.0 % of Input 1_Input span (When Control with PV select: 0.1 to 1000.0 % of PV select input span)	TC/RTD inputs: 30 V/I inputs: 3.0

-  To display “Input 1_Proportional band [cool-side],” you need to specify “Heat/Cool PID control” at the time of order, AND to enter a value other than 0 in the Input 1_Proportional band [heat-side] in the same memory area.

● **Input 1_Integral time [heat-side]**
[Parameter Setting Mode: Parameter group No. 51 (Pn51)]

Parameter symbol	Data range	Factory set value
$I.$ I	PID control or Heat/Cool PID control: 0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds 0 (0.0, 0.00, 0.000): PD action [Varies with the setting of the Integral/Derivative time decimal point position.]	240.00

-  To display “Input 1_Integral time [heat-side],” you need to enter a value other than 0 in the Input 1_Proportional band [heat-side] in the same memory area.

● **Input 1_Integral time [cool-side]**
[Parameter Setting Mode: Parameter group No. 56 (Pn56)]

Parameter symbol	Data range	Factory set value
$I.$ I_C	0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds 0 (0.0, 0.00, 0.000): PD action [Varies with the setting of the Integral/Derivative time decimal point position.]	240.00

-  To display “Input 1_Integral time [cool-side],” you need to specify “Heat/Cool PID control” at the time of order, AND to enter a value other than 0 in the Input 1_Proportional band [heat-side] in the same memory area.

● **Input 1_Derivative time [heat-side]**
[Parameter Setting Mode: Parameter group No. 51 (Pn51)]

Parameter symbol	Data range	Factory set value
<i>I.</i> <i>d</i>	0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds 0 (0.0, 0.00, 0.000): PI action [Varies with the setting of the Integral/Derivative time decimal point position.]	60.00

-  To display “Input 1_Derivative time [heat-side],” you need to enter a value other than 0 in the Input 1_Proportional band [heat-side] in the same memory area.

● **Input 1_Derivative time [cool-side]**
[Parameter Setting Mode: Parameter group No. 56 (Pn56)]

Parameter symbol	Data range	Factory set value
<i>I.</i> <i>dc</i>	0 to 3600 seconds, 0.0 to 3600.0 seconds, 0.00 to 360.00 seconds or 0.000 to 36.000 seconds 0 (0.0, 0.00, 0.000): PI action [Varies with the setting of the Integral/Derivative time decimal point position.]	60.00

-  To display “Input 1_Derivative time [cool-side],” you need to specify “Heat/Cool PID control” at the time of order, AND to enter a value other than 0 in the Input 1_Proportional band [heat-side] in the same memory area.

● **Input 1_Overlap/Deadband**
[Parameter Setting Mode: Parameter group No. 56 (Pn56)]

Parameter symbol	Data range	Factory set value
<i>I.</i> <i>db</i>	TC/RTD inputs: -(Input 1_Input span)to +(Input 1_Input span) When Control with PV select: -(PV select input span) to +(PV select input span) (Unit: °C [°F]) [Varies with the setting of the Decimal point position.] Voltage (V)/Current (I) inputs: -100.0 to +100.0 % of Input 1_Input span When Control with PV select: -100.0 to +100.0 % of PV select input span Minus (-) setting results in Overlap. However, the overlapping range is within the proportional range.	TC/RTD inputs: 0 V/I inputs: 0.0

-  To display “Input 1_Overlap/Deadband,” you need to specify “Heat/Cool PID control” at the time of order, or “Input 1_Control action” (Function block No. 51 in Engineering mode) must be set to Heat/Cool PID control.

● Input 1_Control action

[Engineering Mode: Function block No. 51 (Fn51)]

Parameter symbol	Data range	Factory set value
I. OS	0: Brilliant II PID control (direct action) 1: Brilliant II PID control (reverse action) 2: Brilliant II Heat/Cool PID control [water cooling] 3: Brilliant II Heat/Cool PID control [air cooling] 4: Brilliant II Heat/Cool PID control [Cooling linear type] <small>For 2-loop control/Differential temperature control, only 0 or 1 is selectable.</small>	Control action specified at the time of order.

-  See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are initialized when the Input 1_Control action is changed.

● Undershoot suppression factor

[Engineering Mode: Function block No. 56 (Fn56)]

Parameter symbol	Data range	Factory set value
US	0.000 to 1.000	Water cooling: 0.100 Air cooling: 0.250 Cooling linear: 1.000

-  To display “Undershoot suppression factor,” you need to specify “Heat/Cool PID control” at the time of order, or “Input 1_Control action” (Function block No. 51 in Engineering mode) must be set to Heat/Cool PID control.

● Overlap/Deadband reference point

[Engineering Mode: Function block No. 56 (Fn56)]

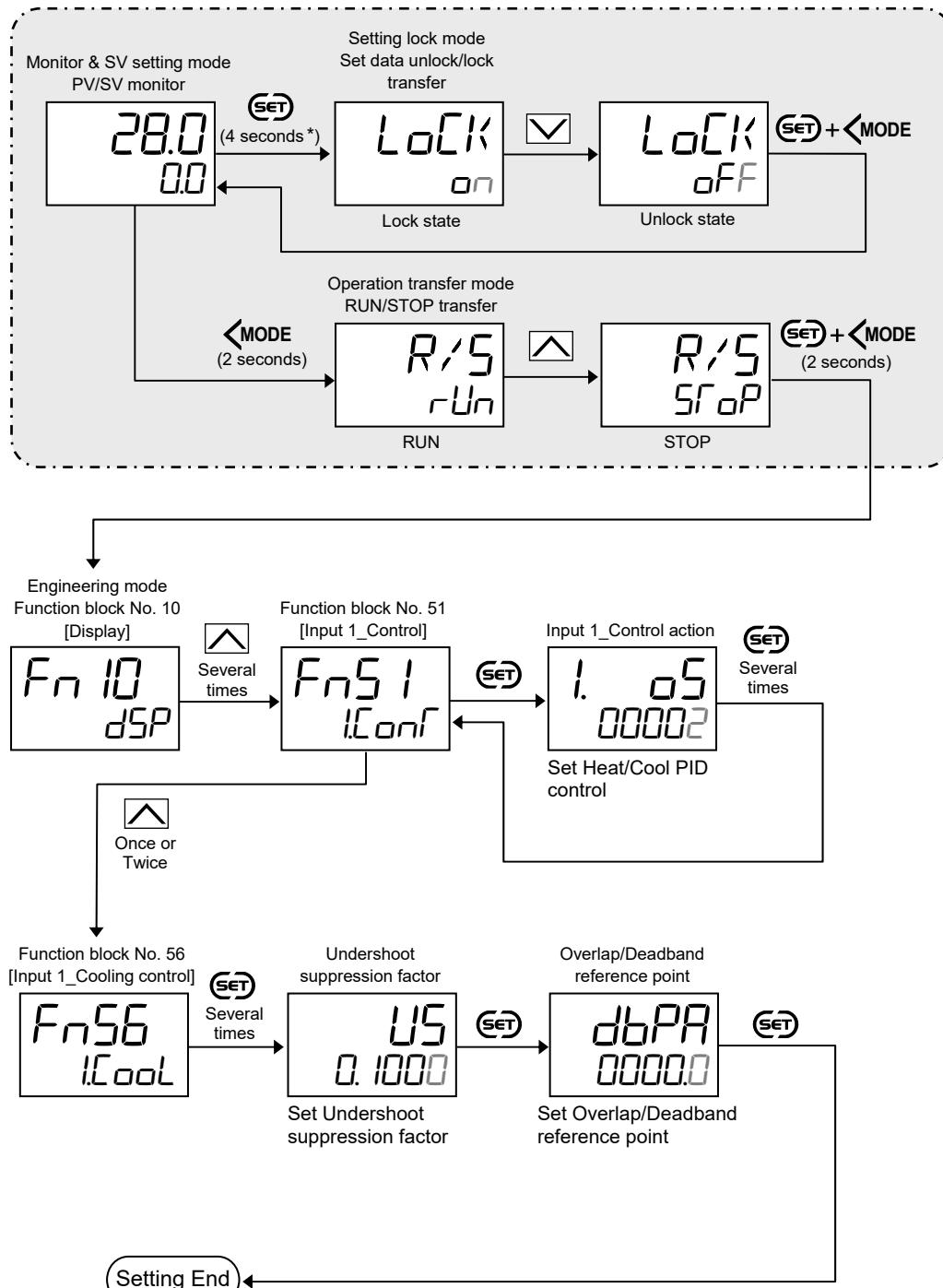
Parameter symbol	Data range	Factory set value
dbPR	0.0 to 1.0	0.0

-  To display “Overlap/Deadband reference point,” you need to specify “Heat/Cool PID control” at the time of order, or “Input 1_Control action” (Function block No. 51 in Engineering mode) must be set to Heat/Cool PID control.

■ Setting procedure

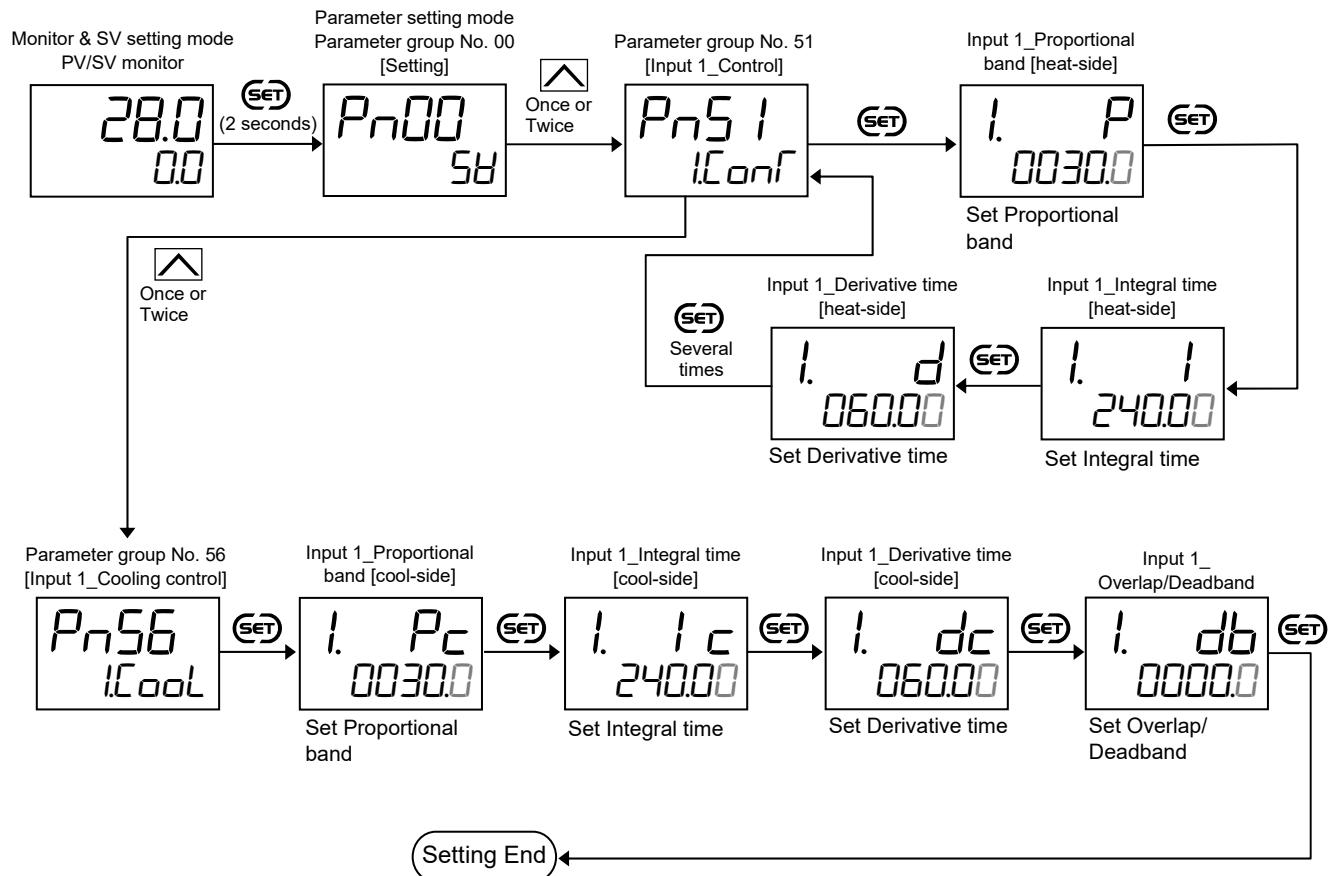
● Selecting Heat/Cool PID control

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.

● Setting parameters for Heat/Cool PID control



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)



The Parameters in Heat/Cool PID control can be calculated also in Autotuning (AT).

(Overlap/Deadband is excluded)

For Autotuning (AT), see **8.3 Setting PID Values Automatically (Autotuning) (P. 8-11)**.

8.8 Controlling with Manual Control

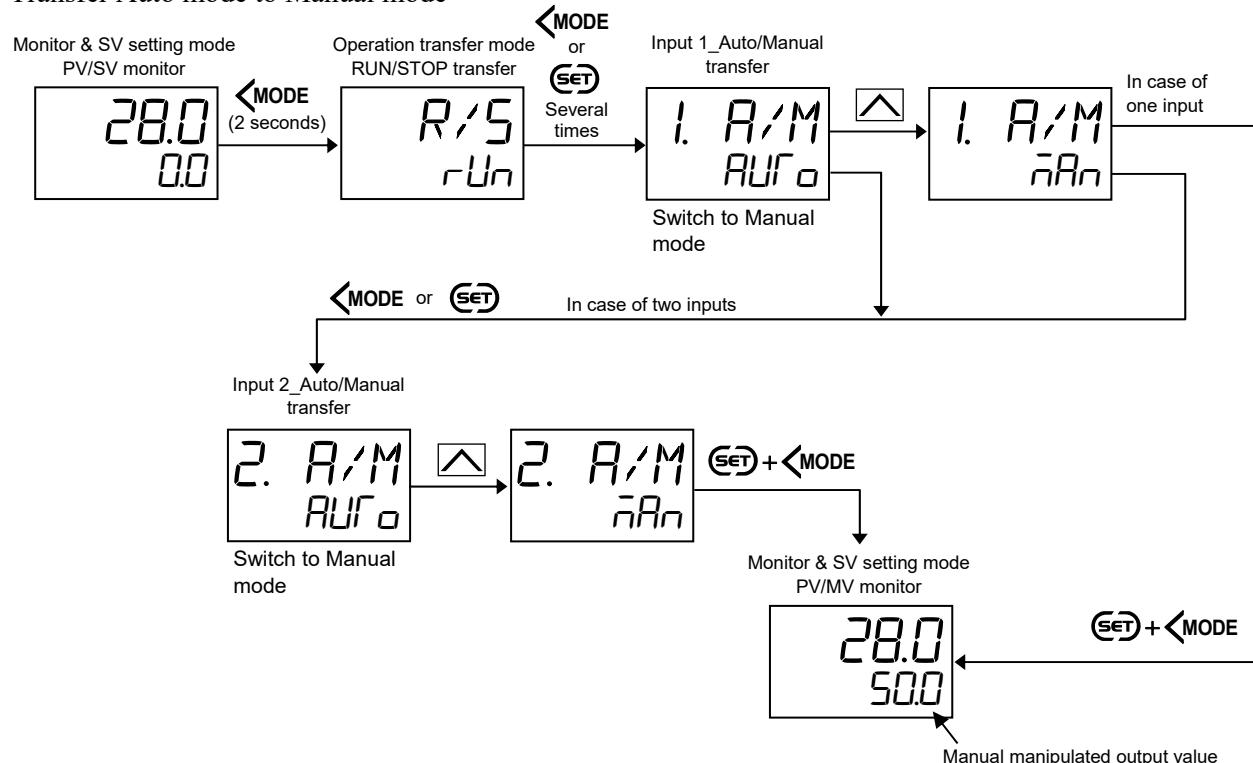
To conduct the Manual control, you need to select the Manual mode using the Auto/Manual transfer. The Auto/Manual transfer can be made by a key operation, Digital input (DI) or communication (optional).

- ☞ For the detail of the Auto/Manual transfer through communication, refer to **GZ400/GZ900 Instruction Manual [Host communication] (IMR02D07-E)**.
- ☞ For the detail of the Manipulated output value (balanceless bumpless) associated with the Auto/Manual transfer, see **6.8 Suppressing Sudden Change in Output (Balanceless Bumpless) (P. 6-33)**.

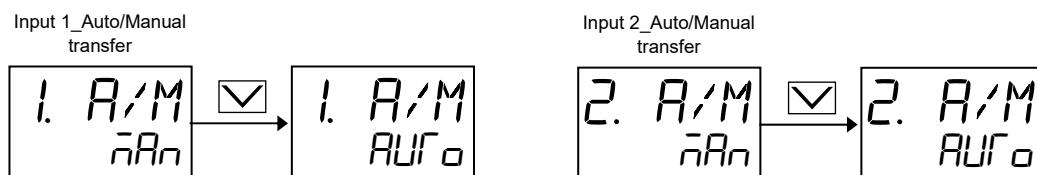
■ Setting procedure

● Selection by front key operation

Transfer Auto mode to Manual mode



- ☞ Transfer Manual mode to Auto mode



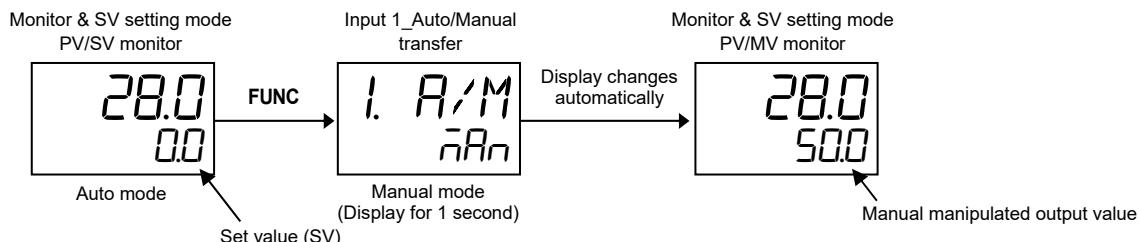
- ☞ During the manual mode, the Manual (MAN) mode lamp is lit.
See P. 8-47 for the Display position of the lamp.

● Changing the mode with the direct key

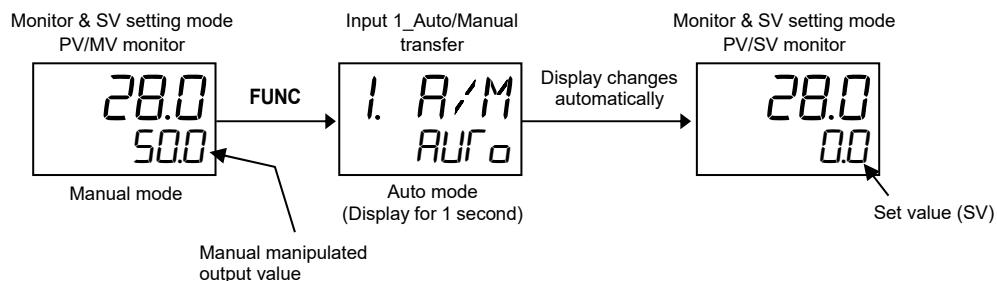
Assigning the “Auto/Manual transfer” function to the FUNC key facilitates the Auto/Manual switching. Each time FUNC key is pressed, Auto mode and Manual mode are toggled.

-  For the “FUNC key assignment,” see **10.8 Accessing Some Functions Directly (FUNC key) (P. 10-35)**.

Transfer Auto mode to Manual mode (Input 1_Auto/Manual transfer)



Transfer Manual mode to Autol mode (Input 1_Auto/Manual transfer)



-  Selection of key action is possible from “Press once” and “Press and hold” to enable the switching. For details, see **10.8 Accessing Some Functions Directly (FUNC key) (P. 10-35)**.

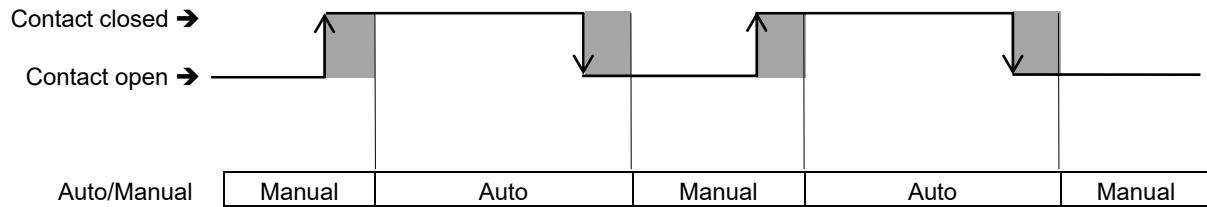
● Switching the mode with Digital Input (DI)

To switch the Auto/Manual using the Digital Input (DI), use “DI function selection” (Function block No. 23 in the Engineering mode).

-  For the Digital input (DI) assignment, see **5.2 Switching Functions Using Digital Inputs (DI) (P. 5-16)**.

Transfer timing of Auto/Manual

 : Within 50 ms



NOTE

After the contact is transferred, it takes “Within 50 ms” until the action of this instrument is actually selected.

-  The above switching action can be inverted (The functions at contact close and contact open can be swapped). This setting can be done at “DI logic invert.” For details, see **5.2 Switching Functions Using Digital Inputs (DI) (P. 5-16)**.

● Auto/Manual transfer state

The table below shows the actual Auto/Manual modes and displays under different combinations of settings by Key operation, Communication, and Digital input (DI).

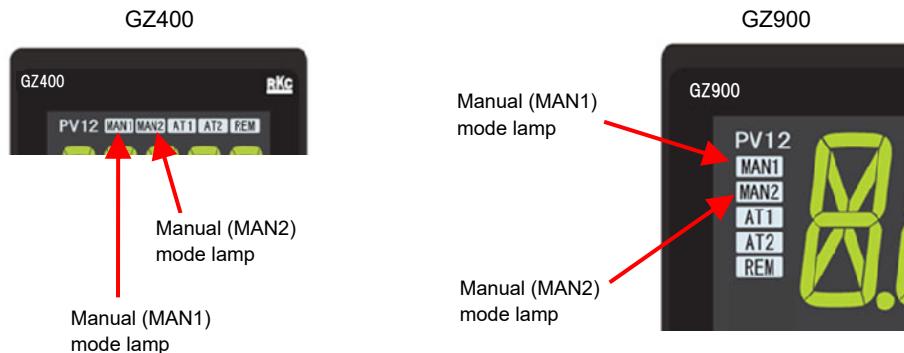
Setting via front keys or through communication	Setting via Digital Input (DI)	Instrument status
Auto mode	Auto mode	Auto mode
	Manual mode	Manual mode
Manual mode	Auto mode	
	Manual mode	Priority to Manual mode

● Setting Manipulated output value in Manual mode

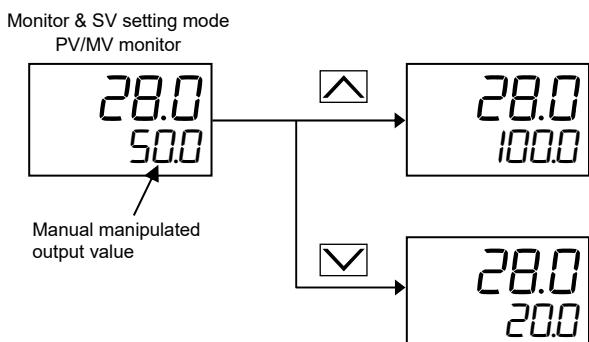
In the Manual mode, the Manipulated output value (MV) can be manually set.

Make sure the Manual mode lamp is on (the instrument is in the manual mode) before starting the operation.

[Position of the Manual mode lamp]



[Adjusting the output]



- key: Increase the Manipulated output value (MV).
- key: Decrease the Manipulated output value (MV).
- Press and hold the key or key makes numeric value change faster.

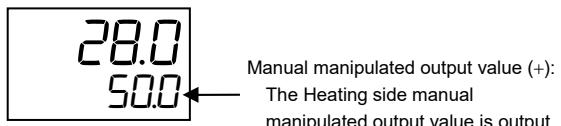


For Heat/Cool PID control:

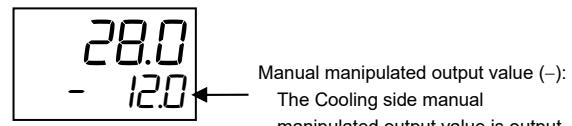
When the Manual manipulated output is positive (+), the Heating side manual manipulated output value is output. When the Manual manipulated output is negative (-), the Cooling side manual manipulated output value is output.

When the Overlap is set on the instrument, the internally calculated value is output in the overlap range.

Monitor & SV setting mode
PV/MV monitor



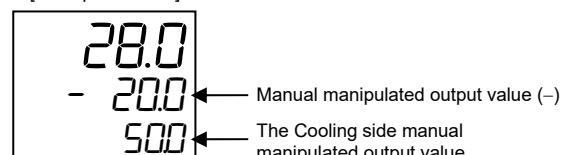
Monitor & SV setting mode
PV/MV monitor



When the Manipulated output value is selected, priority is given to the display of the Heating side manual manipulated output value.

When the Manual manipulated output value enters the negative range, the output is transferred to the Cooling side manual manipulated output value.

[Example: GZ400]



**For ON/OFF action:**

Either Output limiter high or Output limiter low will be output.

[Condition for output]

- The Output limiter low will be output when the Manual manipulated output value \leq the Output limiter low (or 0.0 %.)
- The Output limiter high will be output when the Manual manipulated output value $>$ the Output limiter low (or 0.0 %.)

■ Parameter setting

● Input 1_Auto/Manual transfer [Operation Transfer Mode]

Parameter symbol	Data range	Factory set value
1. A/M	RUF _a : Auto mode nRn: Manual mode	RUF _a



This parameter is not displayed when this parameter is fixed to “Fix parameter setting: Auto/Manual transfer” in the Setting lock mode.

● Input 2_Auto/Manual transfer [Operation Transfer Mode]

Parameter symbol	Data range	Factory set value
2. A/M	RUF _a : Auto mode nRn: Manual mode	RUF _a



To display “Auto/Manual transfer,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.



This parameter is not displayed when this parameter is fixed to “Fix parameter setting: Auto/Manual transfer” in the Setting lock mode.

8.9 Using Remote Setting Input

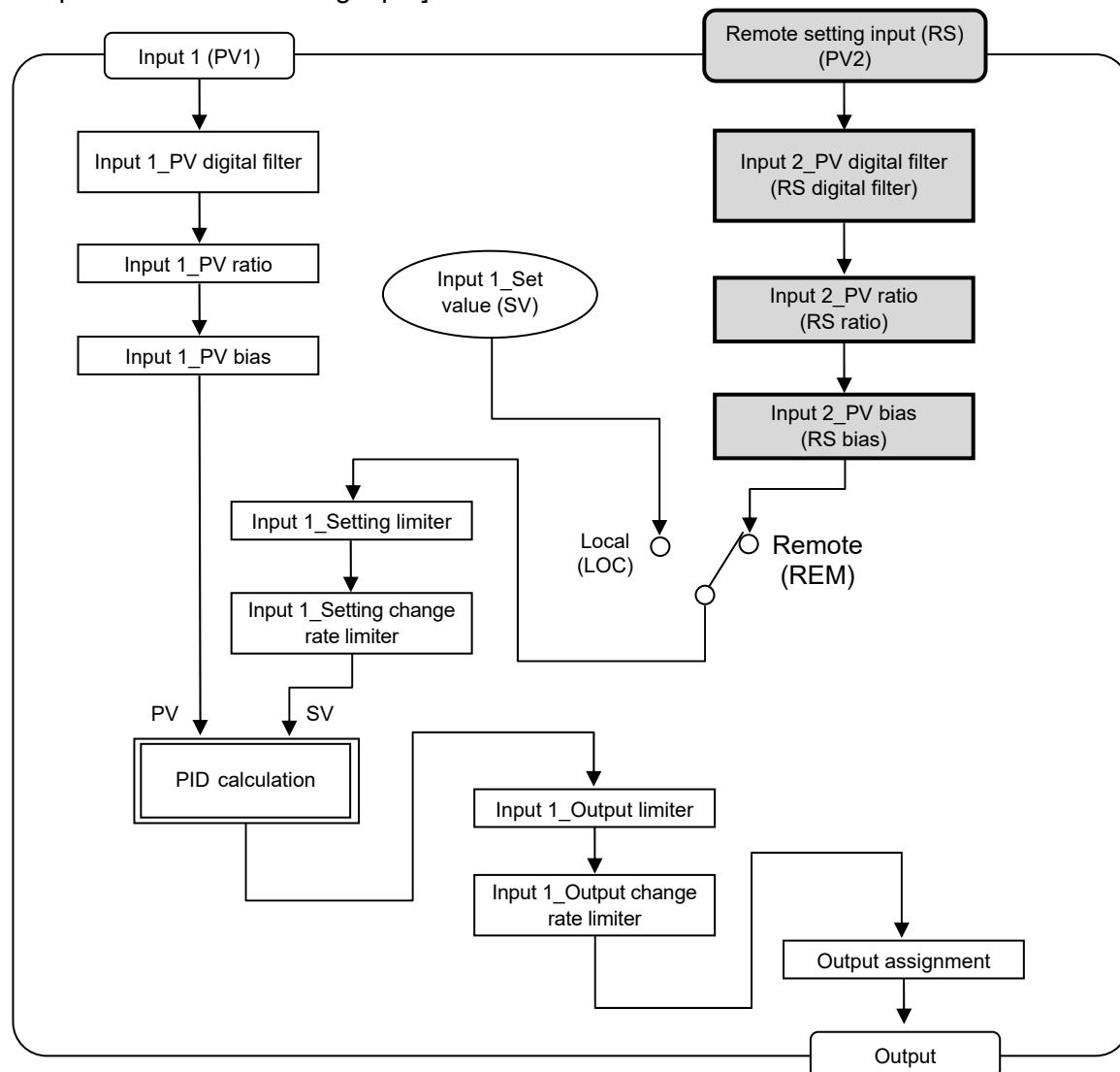
The Remote setting input uses the external signal (Input 2) as the Input 1_set value (SV).

To use the Remote setting input, the mode must be switched to the Remote mode with the Remote/Local transfer. The Remote/Local transfer can be made by a key operation, Digital input (DI) or Communication (optional).

-  To use the Remote setting input function, you need to specify the “Remote setting input” at the time of order, or configure the “Measured input 2” (that must be also specified at the time order) to the Remote setting input at “Select function for input 2” in Function block No. 58 in the Engineering mode.
-  The signal type of the Remote setting input can be set at “Input 2_Input type” in Function block No. 22 in the Engineering mode.
-  For the detail of the Remote/Local transfer through communication, refer to **GZ400/GZ900 Instruction Manual [Host communication] (IMR02D07-E)**.

■ Description of function

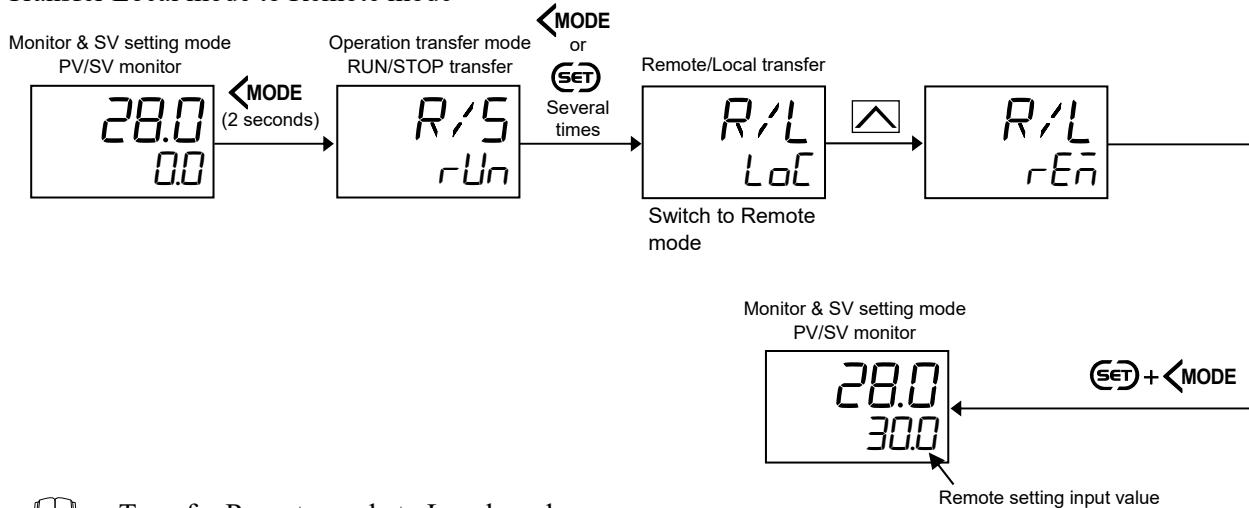
[Description of Remote setting input]



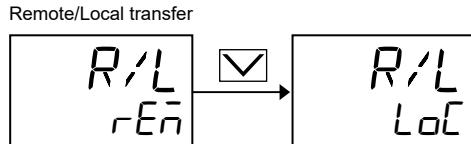
■ Mode transfer

● Selection by front key operation

Transfer Local mode to Remote mode



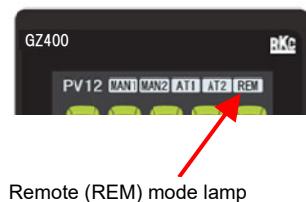
Transfer Remote mode to Local mode



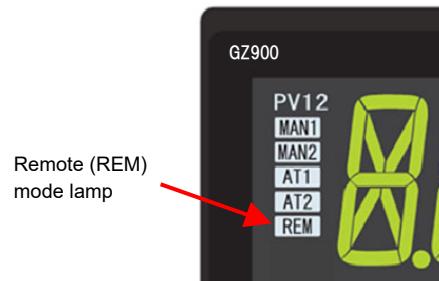
During the Remote mode, the Remote (REM) mode lamp lights on.

[Position of the Remote mode lamp]

GZ400



GZ900



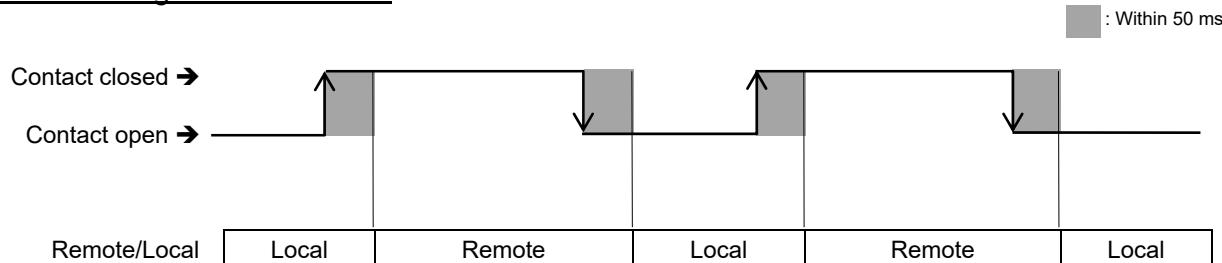
The FUNC key may be configured to switch between Remote and Local.
For details, see 10.8 Accessing Some Functions Directly (FUNC key) (P. 10-35).

● Switching the mode with Digital Input (DI)

To switch the Remote/Local using the Digital Input (DI), use “DI function selection” (Function block No. 23 in the Engineering mode).

-  For the Digital input (DI) assignment, see **5.2 Switching Functions Using Digital Inputs (DI) (P. 5-16)**.

Transfer timing of Remote/Local



NOTE

After the contact is transferred, it takes “Within 50 ms” until the action of this instrument is actually selected.

-  The above switching action can be inverted (The functions at contact close and contact open can be swapped). This setting can be done at “DI logic invert.” For details, see **5.2 Switching Functions Using Digital Inputs (DI) (P. 5-16)**.

● Remote/Local transfer state

The table below shows the actual Remote/Local modes and displays under different combinations of settings by Key operation, Communication, and Digital input (DI).

Setting via front keys or through communication	Setting via Digital Input (DI)	Instrument status
Remote mode	Remote mode	Remote mode
	Local mode	Local mode
Local mode	Remote mode	
	Local mode	Priority to Local mode

■ Parameter setting

● Remote/Local transfer [Operation Transfer Mode]

Parameter symbol	Data range	Factory set value
R/L	When “Remote setting input” is selected at Select function for input 2 Loc: Local mode Ren: Remote mode	Loc

-  To display “Remote/Local transfer”, you need to specify the “Remote setting input” at the time of order, or configure the “Measured input 2” (that must be also specified at the time order) to the Remote setting input at “Select function for input 2” in Function block No. 58 in the Engineering mode.
-  This parameter is not displayed when this parameter is fixed to “Fix parameter setting: Remote/Local transfer” in the Setting lock mode.

● Input 2_Input type

[Engineering Mode: Function block No. 22 (Fn22)]

Parameter symbol	Data range	Factory set value
2. I NP	0: TC input K 1: TC input J 2: TC input R 3: TC input S 4: TC input B 5: TC input E 6: TC input N 7: TC input T 8: TC input W5Re/W26Re 9: TC input PL II 10: TC input U 11: TC input L 12: TC input PR40-20 13: RTD input Pt100 14: RTD input JPt100 ● When Measured input 2 is selected: 0 to 24 * ● When Remote setting input is selected: 15 to 24	Same as Input 1_Input type When Remote setting input is specified at the time of order, but the input type is not specified: 17

* When the “Measured input 2” is specified at the time of order, the Remote setting input type is selectable from TC and RTD by selecting the Remote setting input at “Select function for input 2.” **When the Remote setting input is set to TC or RTD, set “1: Downscale” at the “Input 2_Burnout direction” in Function block No. 22 in the Engineering mode for safety reason.**

-  To display Input 2_Input type, “Measured input 2” or “Remote setting input” must be specified at the time of order.
-  Input 2_Input type is not displayed if “No function” is selected at Select function for input 2 in Function block No. 58 in the Engineering mode.
-  See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are initialized or changed when the input type is changed.

● Select function for input 2

[Engineering mode: Function block No. 58 (Fn58)]

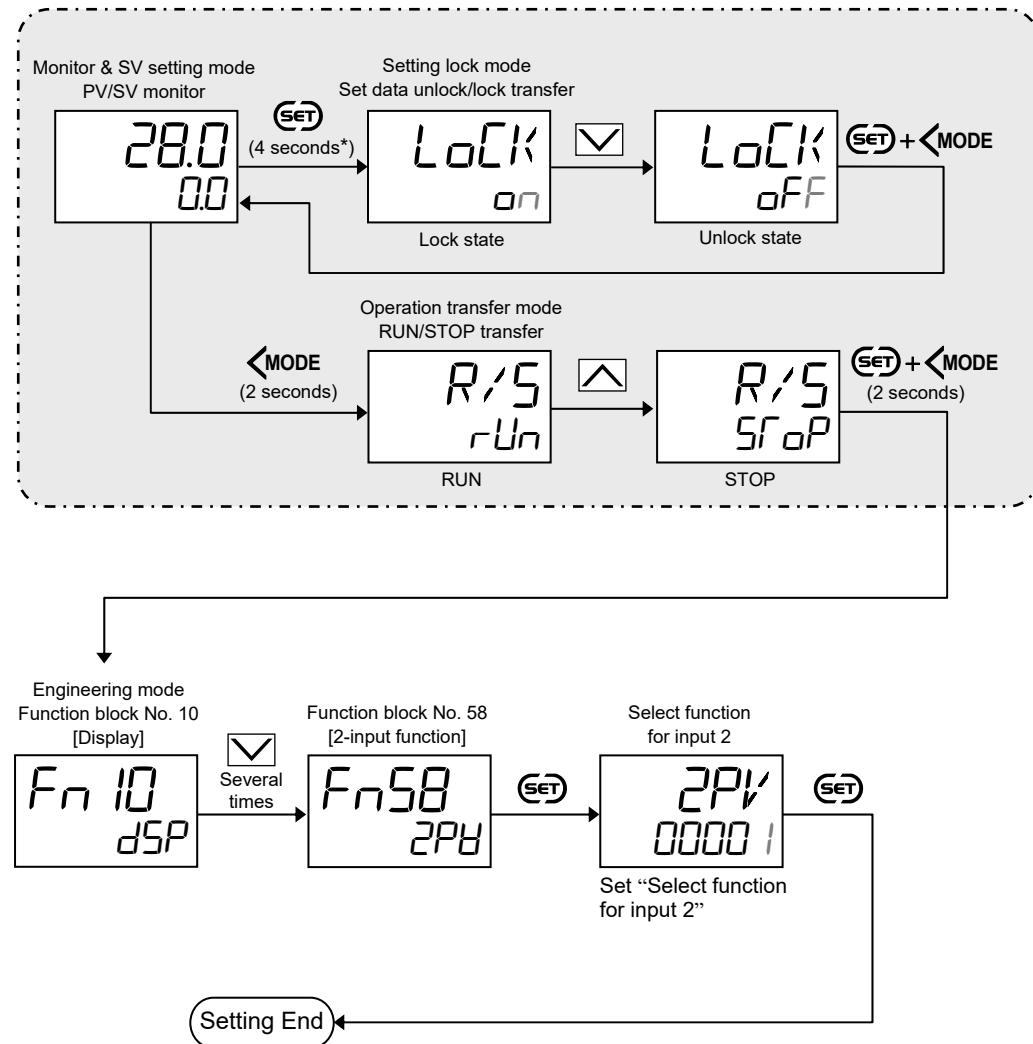
Parameter symbol	Data range	Factory set value
2PV	0: No function 1: Remote setting input 2: 2-loop control/Differential temperature control * 3: Control with PV select 6: Input circuit error alarm *This parameter cannot be specified if the instrument is a Heat/Cool PID type. <ul style="list-style-type: none"> • When Measured input 2 is selected at the time of order: 0 to 3, 6 • When the Remote setting input is selected: 0 to 1 	Based on Model code

 To display “Select function for input 2,” “Remote setting input” or “Measured input 2” must be specified at the time of order.

 See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are initialized or changed when the Select function for input 2 is changed.

■ Setting procedure

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.

8.10 Executing 2-Loop Control

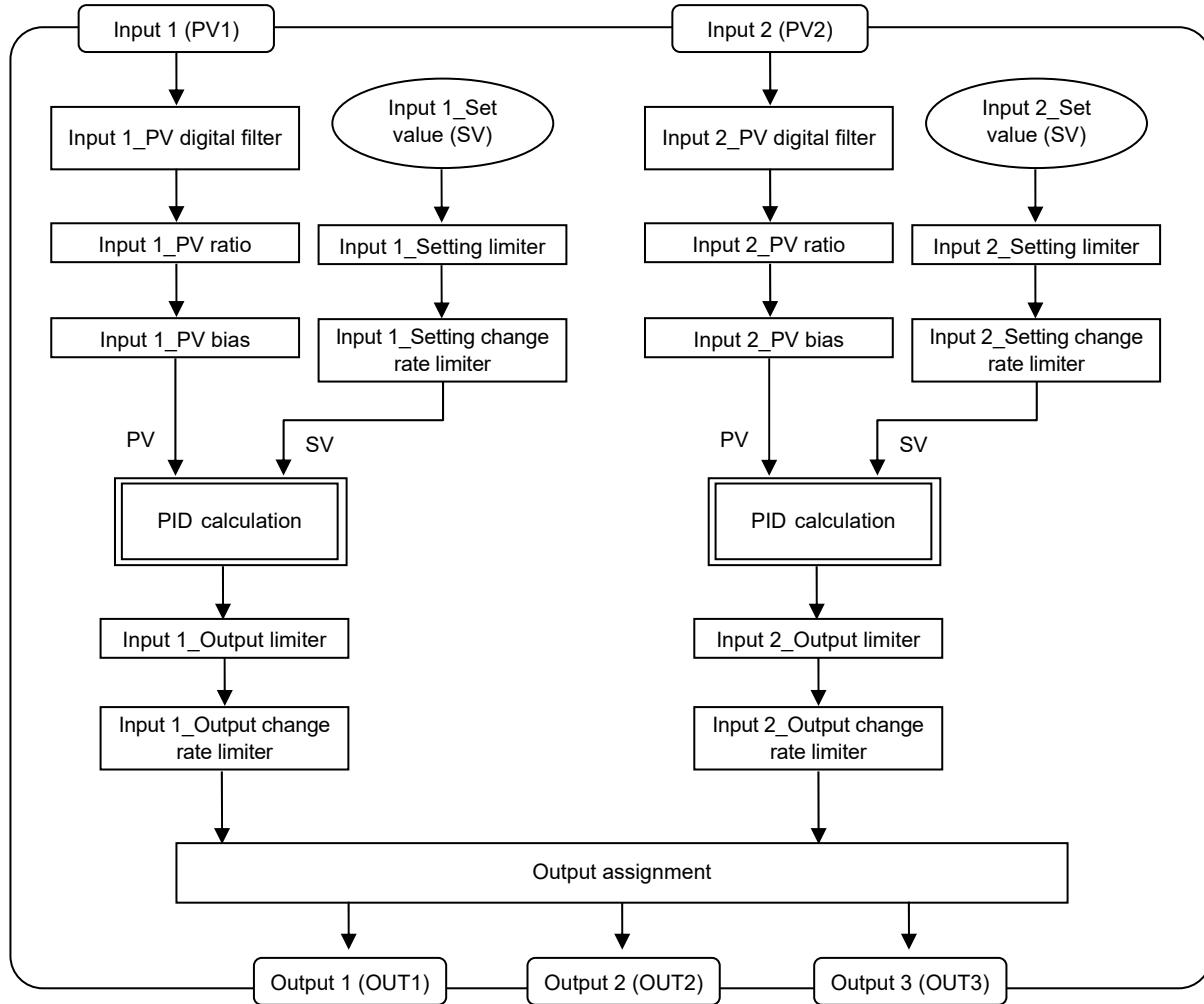
When two inputs are supplied, independent dual loop control can be performed on Input 1 and Input 2.

■ Description of function

The 2-loop control enables two single loop control on a single instrument.

Input 1 and Input 2 are independent from each other and setting must be done separately on each channel.

[Description of 2-loop control]

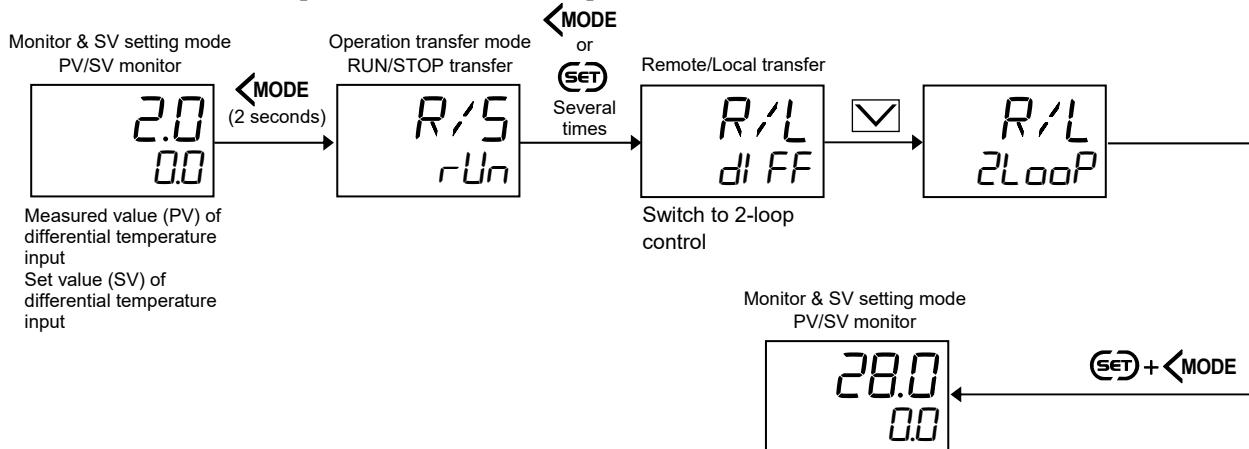


The 2-loop control and the Differential temperature control are switchable. For the detail of the Differential temperature control, see **8.11 Executing Differential Temperature Control (P. 8-58)**.

■ Mode transfer

● Selection by front key operation

Transfer Differential temperature control to 2-loop control

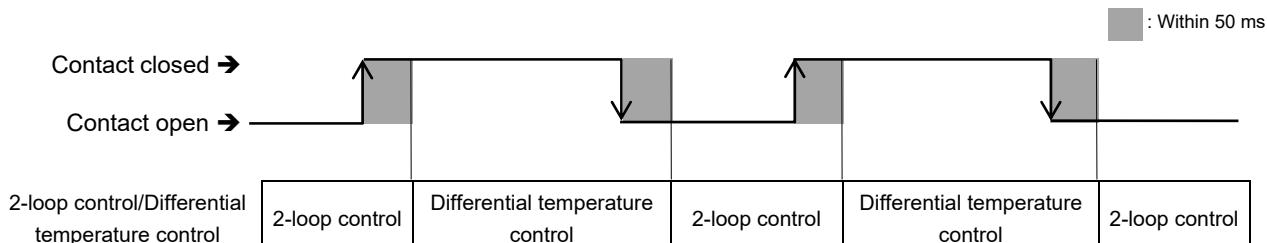


● Switching the mode with Digital Input (DI)

To switch the Remote/Local (2-loop control/ Differential temperature control) using the Digital Input (DI), use “DI function selection” (Function block No. 23 in the Engineering mode).

- For the Digital input (DI) assignment, see **5.2 Switching Functions Using Digital Inputs (DI) (P. 5-16)**.

Transfer timing of Remote/Local(2-loop control/ Differential temperature control)



NOTE
After the contact is transferred, it takes “Within 50 ms” until the action of this instrument is actually selected.



The above switching action can be inverted (The functions at contact close and contact open can be swapped). This setting can be done at “DI logic invert.” For details, see **5.2 Switching Functions Using Digital Inputs (DI) (P. 5-16)**.

● Remote/Local transfer (2-loop control/ Differential temperature control) state

The table below shows the actual 2-loop control/ Differential temperature control status and displays under different combinations of settings by Key operation, Communication, and Digital input (DI).

Setting via front keys or through communication	Setting via Digital Input (DI)	Instrument status
Differential temperature control	Differential temperature control	Differential temperature control
	2-loop control	2-loop control
2-loop control	Differential temperature control	
	2-loop control	Priority to 2-loop control

■ Parameter setting

● Remote/Local transfer (2-loop control/ Differential temperature control) [Operation Transfer Mode]

Parameter symbol	Data range	Factory set value
R/L	When “2-loop control/Differential temperature control” is selected at Select function for input 2 $2Loop$: 2-loop control dFF : Differential temperature control	$2Loop$

-  To display “Remote/Local transfer” (2-loop control/Differential temperature control), specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.
-  This parameter is not displayed when this parameter is fixed to “Fix parameter setting: Remote/Local transfer” in the Setting lock mode.

● Select function for input 2

[Engineering mode: Function block No. 58 (Fn58)]

Parameter symbol	Data range	Factory set value
$2PV$	0: No function 1: Remote setting input 2: 2-loop control/Differential temperature control * 3: Control with PV select 6: Input circuit error alarm * This parameter cannot be specified if the instrument is a Heat/Cool PID type. • When Measured input 2 is selected at the time of order: 0 to 3, 6 • When the Remote setting input is selected: 0 to 1	Based on Model code

-  To display “Select function for input 2,” “Remote setting input” or “Measured input 2” must be specified at the time of order.
-  See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are initialized or changed when the Select function for input 2 is changed.
-  For the detail of Select function for input 2, see P. 8-54.

8.11 Executing Differential Temperature Control

Input 1 is controlled by setting a temperature difference between Input 1 and Input 2.

■ Description of function

Differential temperature control is conducted, while Input 1 is used as Control temperature and Input 2 is used as Reference temperature.

Temperature difference is set on Input 1 against Input 2, and the Input 1 is controlled so that the set temperature difference could be obtained. As the input 2 can also be controlled, the differential temperature control is possible while keeping the reference temperature constant.



In case of Differential temperature control, the Input 1_Set value (SV) is not used for control.

The Input 1_Monitor Set value (SV)* of is used in actual control.

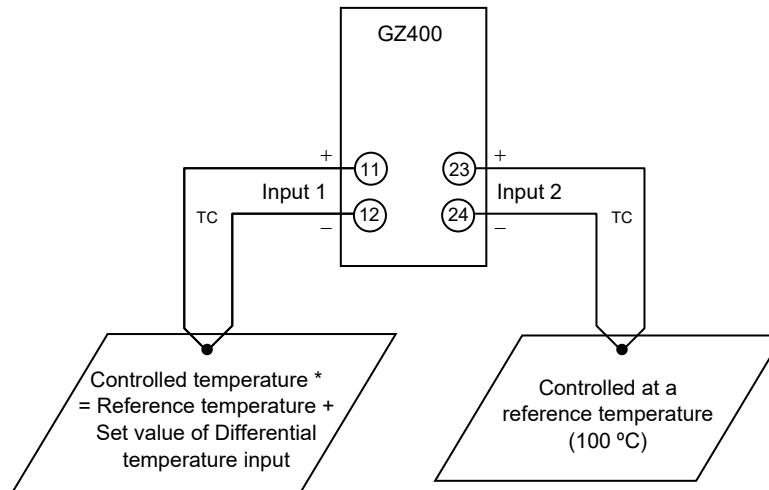
* Input 1_Monitor Set value (SV) = Controlled temperature

= Input 2_Measured value (PV) [Reference temperature] + Set value of Differential temperature input

[Example] Control is done with the Reference temperature (PV of Input 2) at 100 °C, and the Input 1 is controlled by the Differential temperature.

* Example of Controlled temperature when the set value of Differential temperature input is set as follows.

Set value of Differential temperature input	Controlled temperature
-50 °C	50 °C
0 °C	100 °C
100 °C	200 °C



The sensor type used on Input 1 and Input 2 can be different respectively.

[Setting items]

- Remote/Local transfer (2-loop control/ Differential temperature control) [Operation transfer mode]
Transfer to Differential temperature control
- Input 2_Set value (SV) [Parameter setting mode: Parameter group No. 00]:
Setting Reference temperature
- Set value of Differential temperature input [Parameter setting mode: Parameter group No. 00]:
Setting Differential temperature
- Select function for input 2 [Engineering mode: Function block No. 58]:
Select 2-loop control/Differential temperature control
- Other items required for controlling Input 1 and Input 2 (e.g. setting PID values)



The 2-loop control and the Differential temperature control are switchable. For the detail of the 2-loop control, see **8.10 Executing 2-Loop Control (P. 8-55)**.

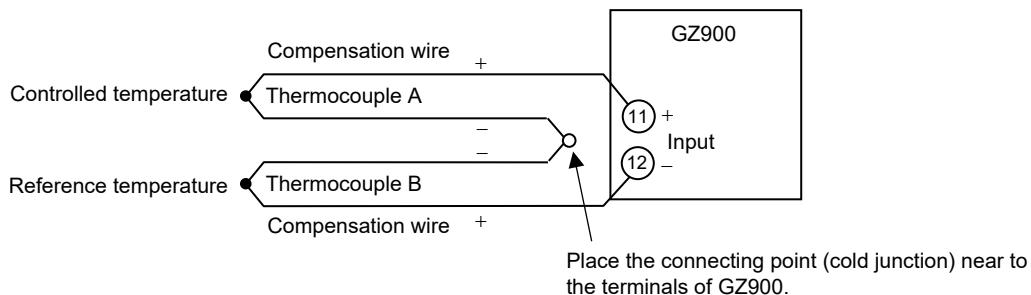


Differential temperature control can be conducted even if the instrument has only one input.

Wiring as follows may be an example of Differential temperature control. In this case, Reference temperature cannot be controlled. Prepare a sample (another controller) if the Reference temperature also needs to be controlled.

In case of the Differential temperature control with this wiring, such a setting as Remote/Local transfer (2-loop control/Differential temperature control) is not required. Control is conducted by a single loop.

[Wiring example]



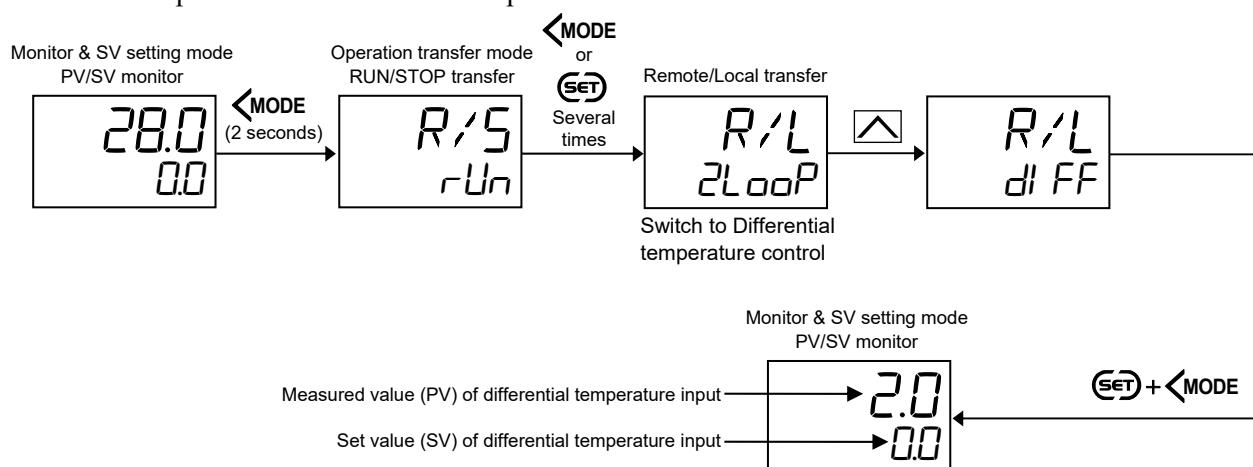
Prerequisites for control

- Both thermocouples must be of the same type.
- Setting of Temperature compensation calculation should be “0: No Temperature compensation calculation”
In the above example, the setting of “Input 1_Temperature compensation calculation” (Function block No. 21 in the Engineering mode) should be “0: No Temperature compensation calculation”

■ Mode transfer

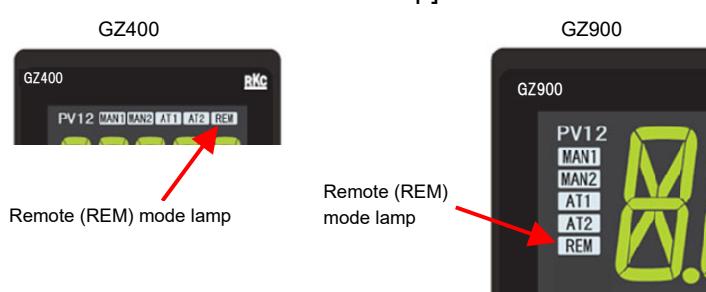
● Selection by front key operation

Transfer 2-loop control to Differential temperature control



During the Differential temperature control, the Remote (REM) mode lamp lights on.

[Position of the Remote mode lamp]





The FUNC key may be configured to switch between 2-loop control and Differential temperature control. For details, see **10.8 Accessing Some Functions Directly (FUNC key) (P. 10-35)**.



Mode transfer by other than the front key should be referred **8.10 Executing 2-Loop Control (P. 8-55)**.

■ Parameter setting

● Remote/Local transfer (2-loop control/ Differential temperature control) [Operation Transfer Mode]

Parameter symbol	Data range	Factory set value
R/L	When “2-loop control/Differential temperature control” is selected at Select function for input 2 2Loop: 2-loop control dFF: Differential temperature control	2Loop



To display “Remote/Local transfer” (2-loop control/Differential temperature control), specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.



This parameter is not displayed when this parameter is fixed to “Fix parameter setting: Remote/Local transfer” in the Setting lock mode.

● Input 2_Set value (SV)

[Parameter Setting Mode: Parameter group No. 00 (Pn00)]

Parameter symbol	Data range	Factory set value
I. SV	Input 2_Setting limiter low to Input 2_Setting limiter high [Varies with the setting of the Decimal point position.]	0



To display “Input 2_Set value (SV),” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

● Set value (SV) of differential temperature input

[Parameter Setting Mode: Parameter group No. 00 (Pn00)]

Parameter symbol	Data range	Factory set value
dSV	-(Input 1_Input span) to +(Input 1_Input span) [Varies with the setting of the Decimal point position.]	0



To display “Set value (SV) of differential temperature input,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control, and Remote/Local transfer must be select Differential temperature control.

● **Select function for input 2**

[Engineering mode: Function block No. 58 (Fn58)]

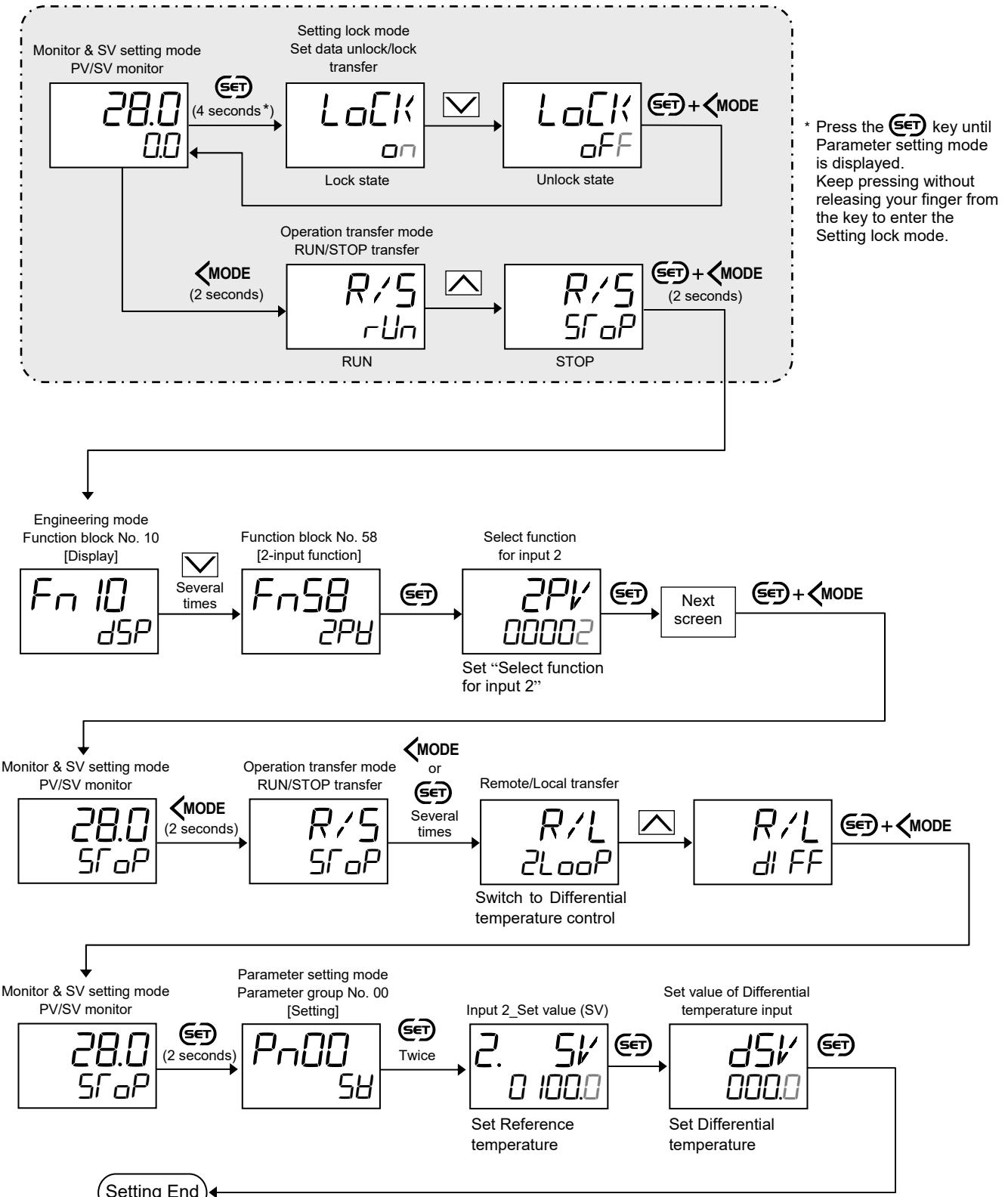
Parameter symbol	Data range	Factory set value
2PV	0: No function 1: Remote setting input 2: 2-loop control/Differential temperature control * 3: Control with PV select 6: Input circuit error alarm *This parameter cannot be specified if the instrument is a Heat/Cool PID type. <ul style="list-style-type: none"> • When Measured input 2 is selected at the time of order: 0 to 3, 6 • When the Remote setting input is selected: 0 to 1 	Based on Model code

 To display “Select function for input 2,” “Remote setting input” or “Measured input 2” must be specified at the time of order.

 See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are initialized or changed when the Select function for input 2 is changed.

■ Setting procedure

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.

Setting End

- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

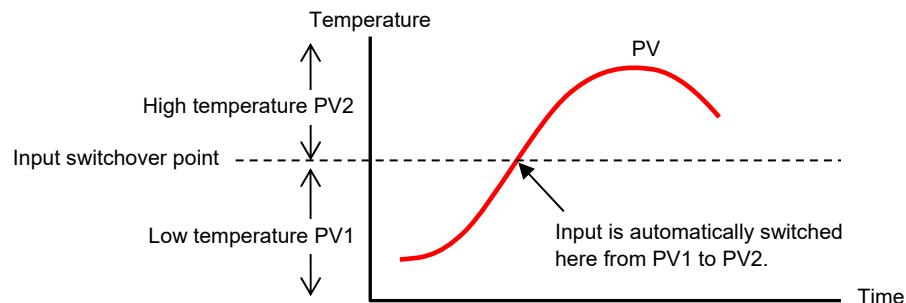
8.12 Executing Control with PV Select

The Control with PV select is a function to control by switching between two inputs for high and low temperature ranges when two different sensors are used in the single controlled object.

■ Description of function

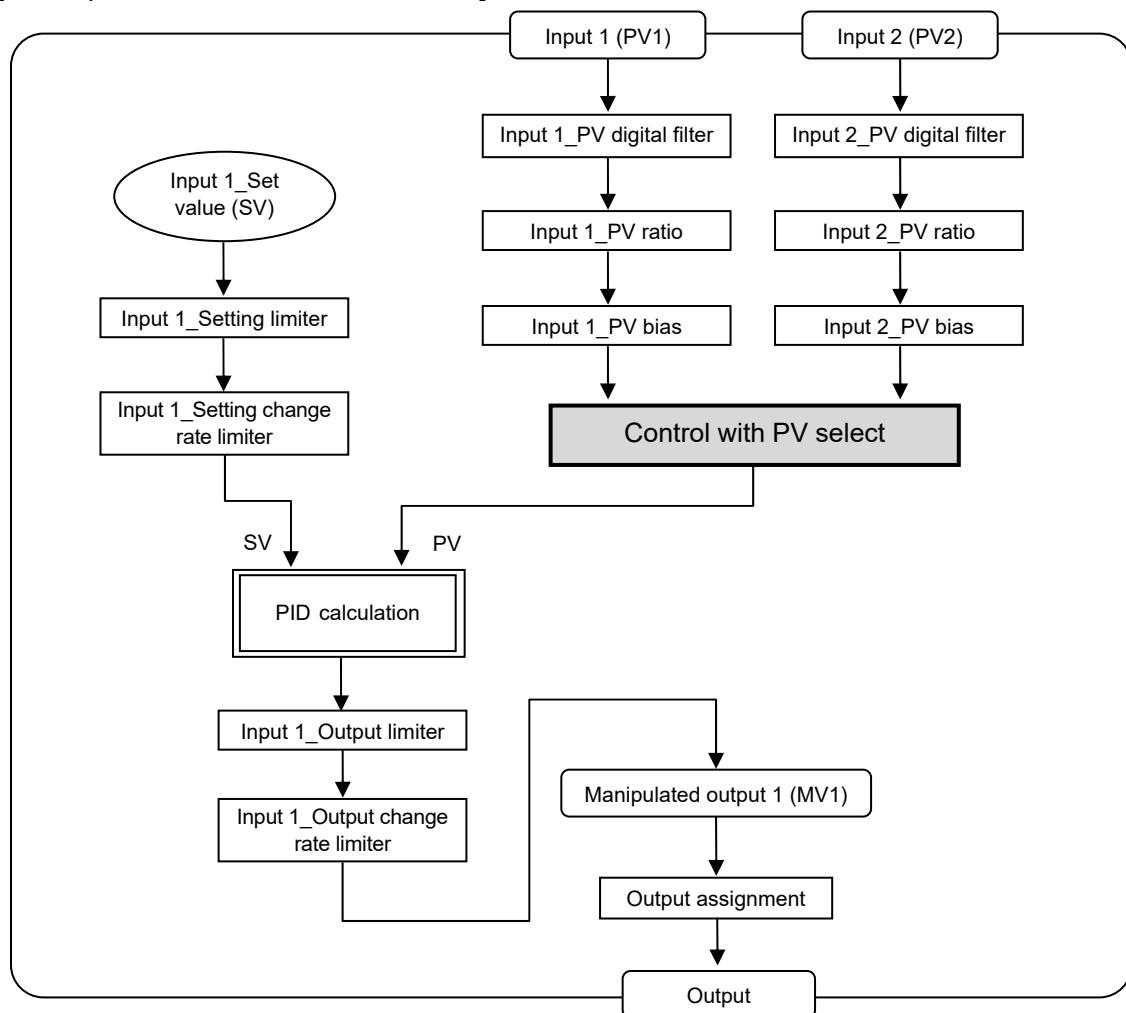
In the Control with PV select, two inputs are used by switching between them: Input 1 (for low temperature range as PV1) and Input 2 (for high temperature range as PV2). Parameters on the Input 1 are used for control computation. Output is also provided on the Input 1 side as Manipulated output 1 (MV1).

[Pictorial explanation of Input switchover]



There are two ways to switch between Input 1 (PV1) and Input 2 (PV2): Switch using the set value and switch by using signal (key operation, digital input, and communication).

[Description of Control with PV select]



● Switching by Set value

The set value (PV select transfer level) is set and used as a trigger for switching between Input 1 (PV1) and Input 2 (PV2). When this set value is exceeded, the present input is transferred to the other.

When the PV select transfer time is set, the transfer action takes place in the set period correcting the input.

[Direction of input switchover]

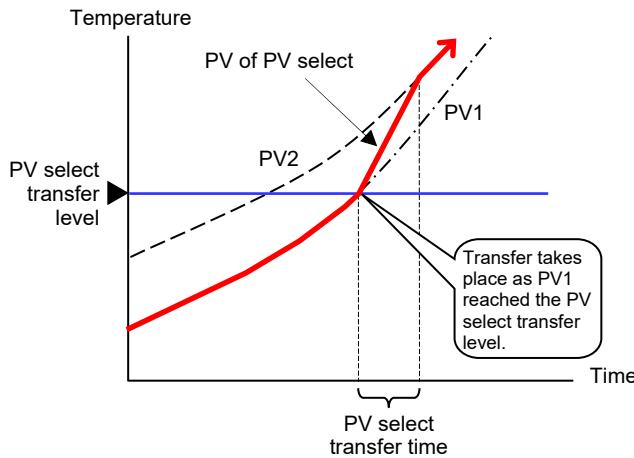
At temperature rise: PV1 to PV2

At temperature fall: PV2 to PV1

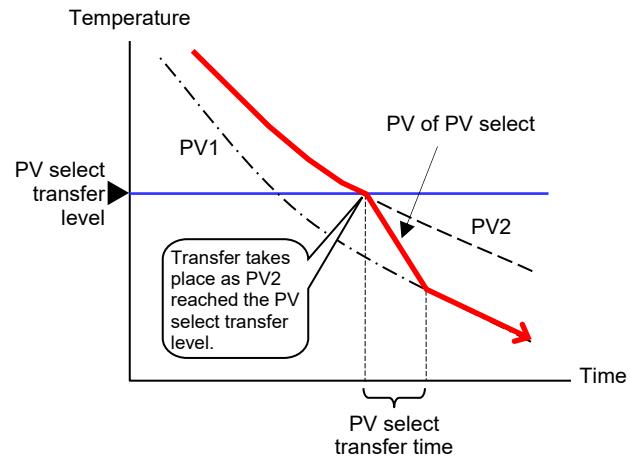
• When PV1 < PV2

When the PV select transfer time is set

<At temperature rise>



<At temperature fall>

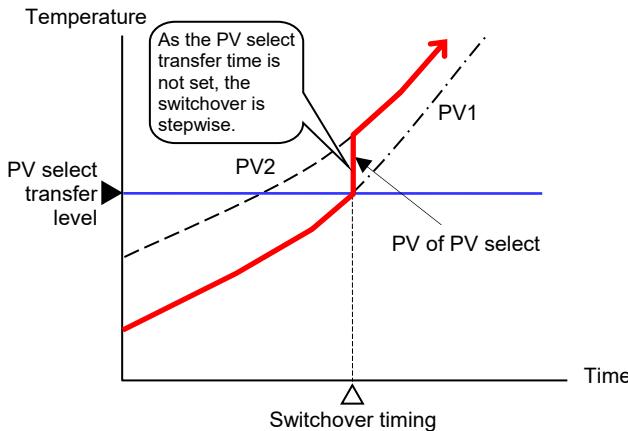


Legend

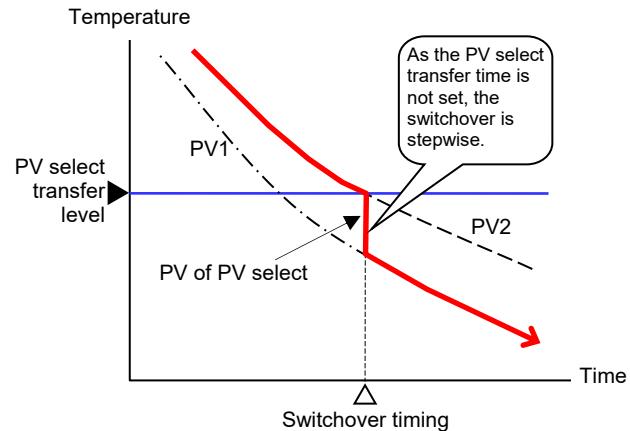
- : Input 1 (PV1)
- - - : Input 2 (PV2)
- : PV select Measured value (PV)

When the PV select transfer time is not set (Set value: 0.0)

<At temperature rise>



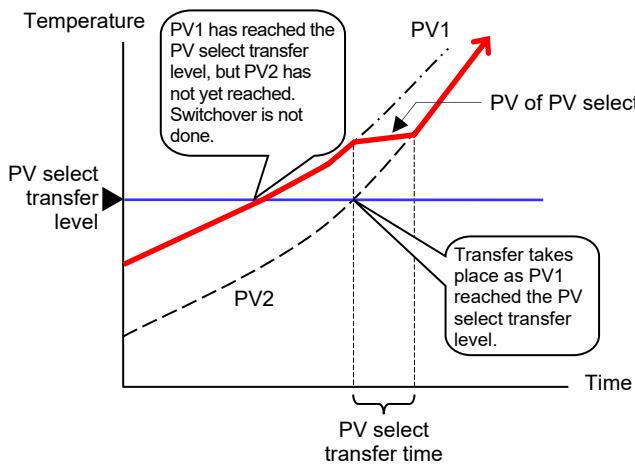
<At temperature fall>



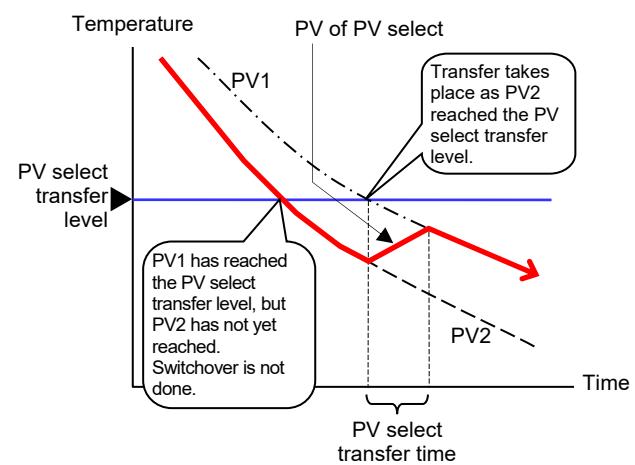
- When $PV1 > PV2$

When the PV select transfer time is set

<At temperature rise>

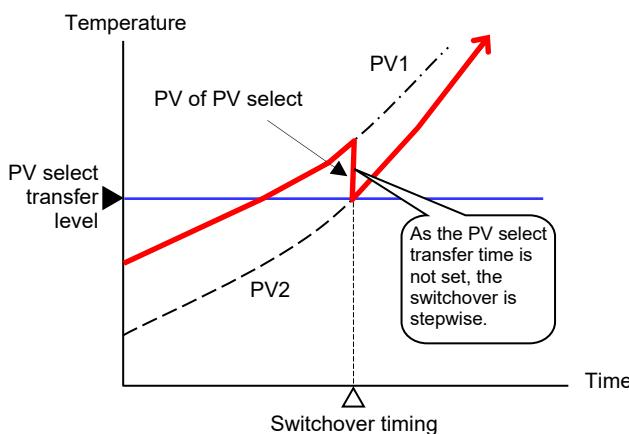


<At temperature fall>

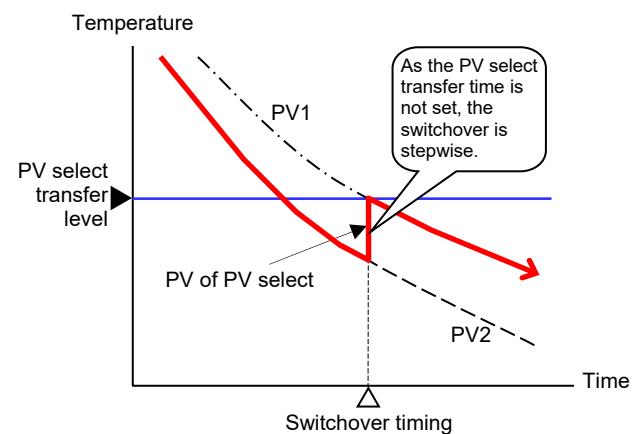


When the PV select transfer time is not set (Set value: 0.0)

<At temperature rise>



<At temperature fall>



● Switchover by signal (key operation, digital input, and communication)

The switchover between Input 1 (PV1) and Input 2 (PV2) is done by using key operation, digital input or communication.

When the PV select transfer time is set, the transfer action takes place in the set period correcting the input.

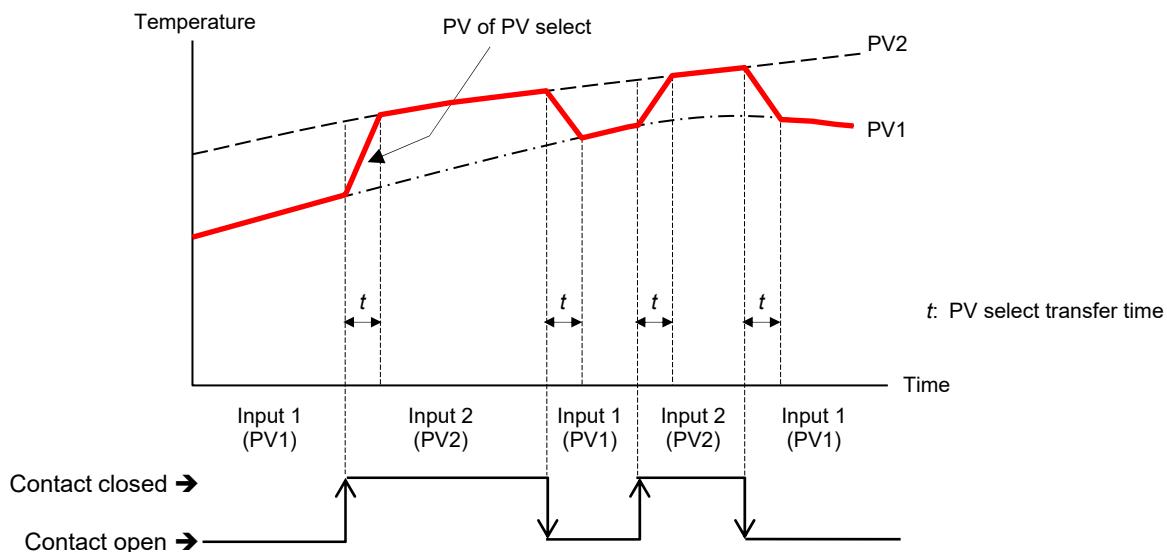
-  In the case of switchover by the signal (key operation, digital input, or communication), there are no restrictions on the switchover direction of the inputs whether the temperature is on the rise or on the decline.
-  For the detail of the input switchover through communication, refer to **GZ400/GZ900 Instruction Manual [Host communication] (IMR02D07-E)**.

• Switching the input with Digital Input (DI)

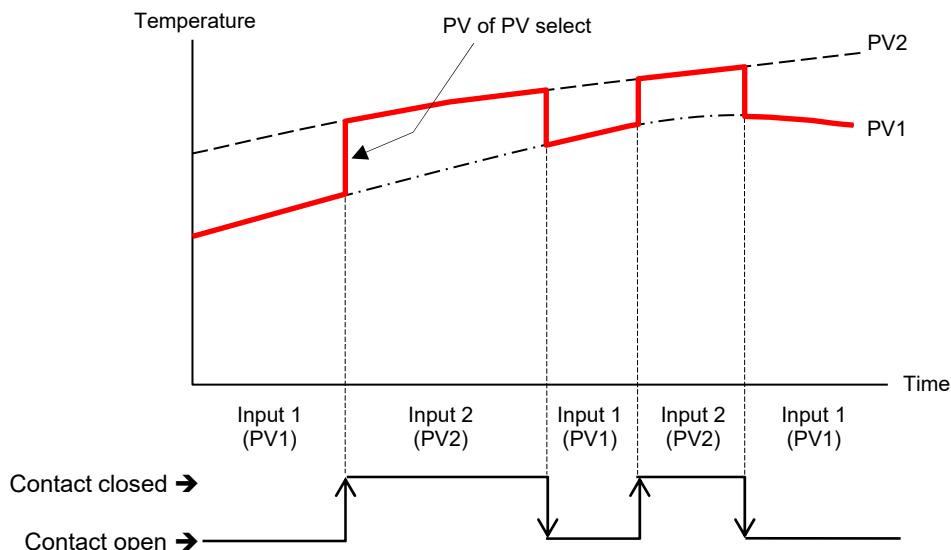
When the PV select transfer time is set

Legend

---	Input 1 (PV1)
- - -	Input 2 (PV2)
—	PV select Measured value (PV)

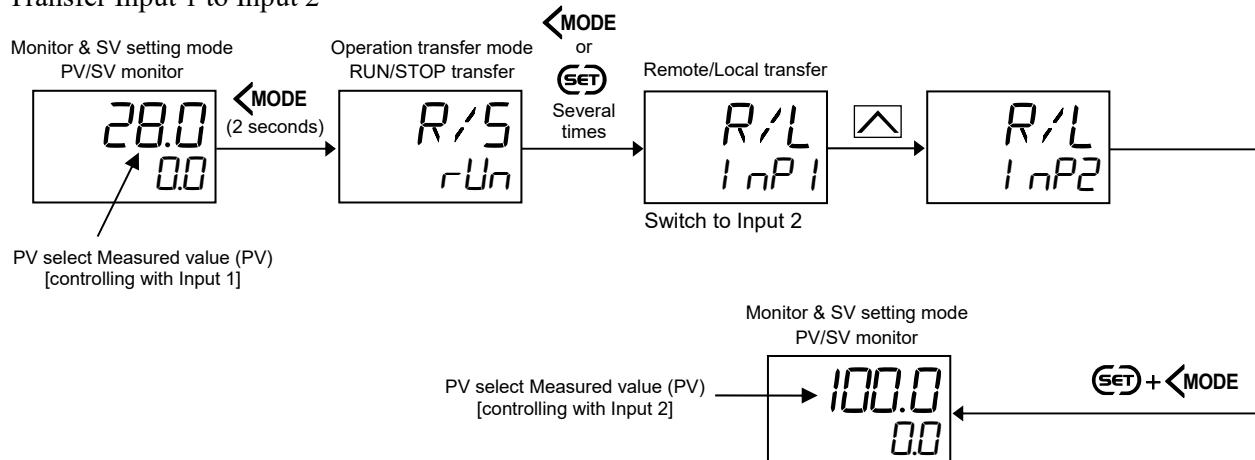


When the PV select transfer time is not set (Set value: 0.0)

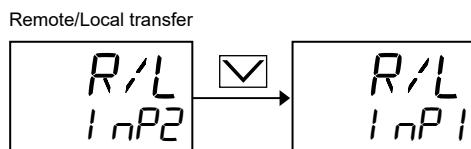


● Selection by front key operation

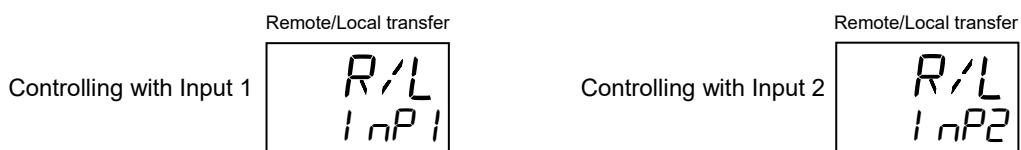
Transfer Input 1 to Input 2



Transfer Input 2 to Input 1

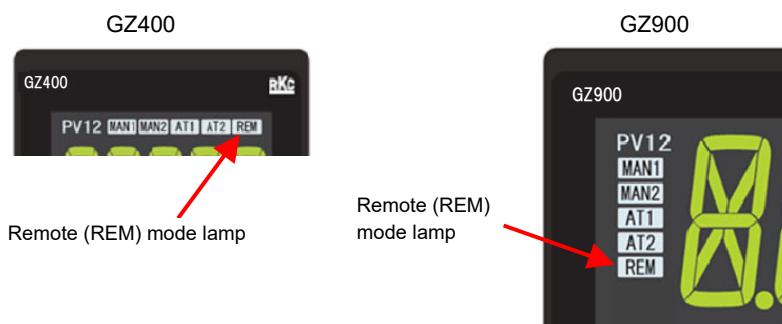


During the switchover by the set value (PV select transfer level), Remote/Local transfer (PV switchover) is not possible, but the transfer status can be checked on the Remote/Local transfer (PV switchover) screen to see if the control is done by Input 1 or Input 2.



The Remote (REM) mode lamp lights on when the “Input 2 is used” as the Measured value (PV) of the PV select and “when Input 1 is switched to Input 2.” When “Input 1 is used” and “when Input 2 is switched to Input 1,” the Remote (REM) mode lamp goes off.

[Position of the Remote mode lamp]



The FUNC key may be configured to switch between Input 1 and Input 2. For details, see **10.8 Accessing Some Functions Directly (FUNC key) (P. 10-35)**.



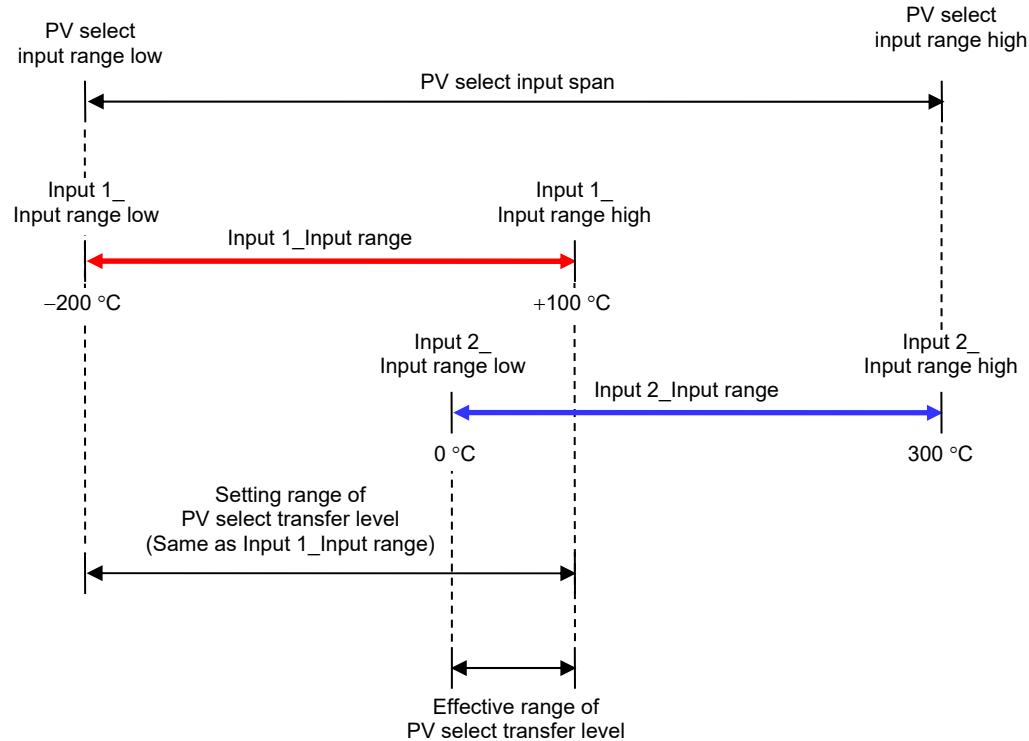
Input range and input span of the PV select

The “PV select input span ,” the “PV select input range high” and the “PV select input range low” mean “Input span,” “Input range high” and “Input range low” at the time of Control with PV select respectively.

The setting range is as follows.

- PV select input range high: Input range high of Input 1 and Input 2, whichever is larger
- PV select input range low: Input range low of Input 1 and Input 2, whichever is smaller
- PV select input span: PV select input range low up to PV select input range high

[Example] When there is a relation as follows between the Input range of Input 1 and Input 2.



In the above example, the effective range of the PV select transfer level is 0 to 100 °C. This means that the action when the PV select transfer level is set somewhere between -200 °C and 0 °C is equal to the action of the 0 °C setting.



When the input is transferred after the start of the Startup tuning (ST), the ST will be aborted. In the case of Autotuning (AT), if the input is transferred after the output has been transferred, the AT will be aborted.



When either one of Input 1 (PV1) or Input 2 (PV2) is disconnected, the PV select transfer time will be invalid.



See below for events and retransmission outputs in the case of Control with PV select.

- **6.3 Using Retransmission Output (P. 6-14)**
- **7.1.1 Changing input for event (P. 7-3)**

■ Parameter setting

● Remote/Local transfer (Control with PV select) [Operation Transfer Mode]

Parameter symbol	Data range	Factory set value
R/L	When “Control with PV select” is selected at Select function for input 2 I_{nP1} : Input 1 I_{nP2} : Input 2	I_{nP1}

-  To display “Remote/Local transfer” (Control with PV select), specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to Control with PV select.
-  When “Switching by level” is selected at “Selection of PV select trigger,” the parameter becomes display only.
-  This parameter is not displayed when this parameter is fixed to “Fix parameter setting: Remote/Local transfer” in the Setting lock mode.

● PV select transfer level

[Setup Setting Mode: Setting group No. 58 (S_nS8)]

Parameter symbol	Data range	Factory set value
$2PV.LV$	Input 1_Input range low to Input 1_Input range high [Varies with the setting of the Decimal point position.]	Input 1_Input range high

-  To display “PV select transfer level,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to Control with PV select.

● PV select transfer time

[Setup Setting Mode: Setting group No. 58 (S_nS8)]

Parameter symbol	Data range	Factory set value
$2PV.TM$	0.0 to 100.0 seconds	0.0

-  To display “PV select transfer time,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to Control with PV select.

● **Select function for input 2**
[Engineering mode: Function block No. 58 (Fn58)]

Parameter symbol	Data range	Factory set value
$2PV$	0: No function 1: Remote setting input 2: 2-loop control/Differential temperature control * 3: Control with PV select 6: Input circuit error alarm *This parameter cannot be specified if the instrument is a Heat/Cool PID type. <ul style="list-style-type: none"> • When Measured input 2 is selected at the time of order: 0 to 3, 6 • When the Remote setting input is selected: 0 to 1 	Based on Model code

 To display “Select function for input 2,” “Remote setting input” or “Measured input 2” must be specified at the time of order.

 See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are initialized or changed when the Select function for input 2 is changed.

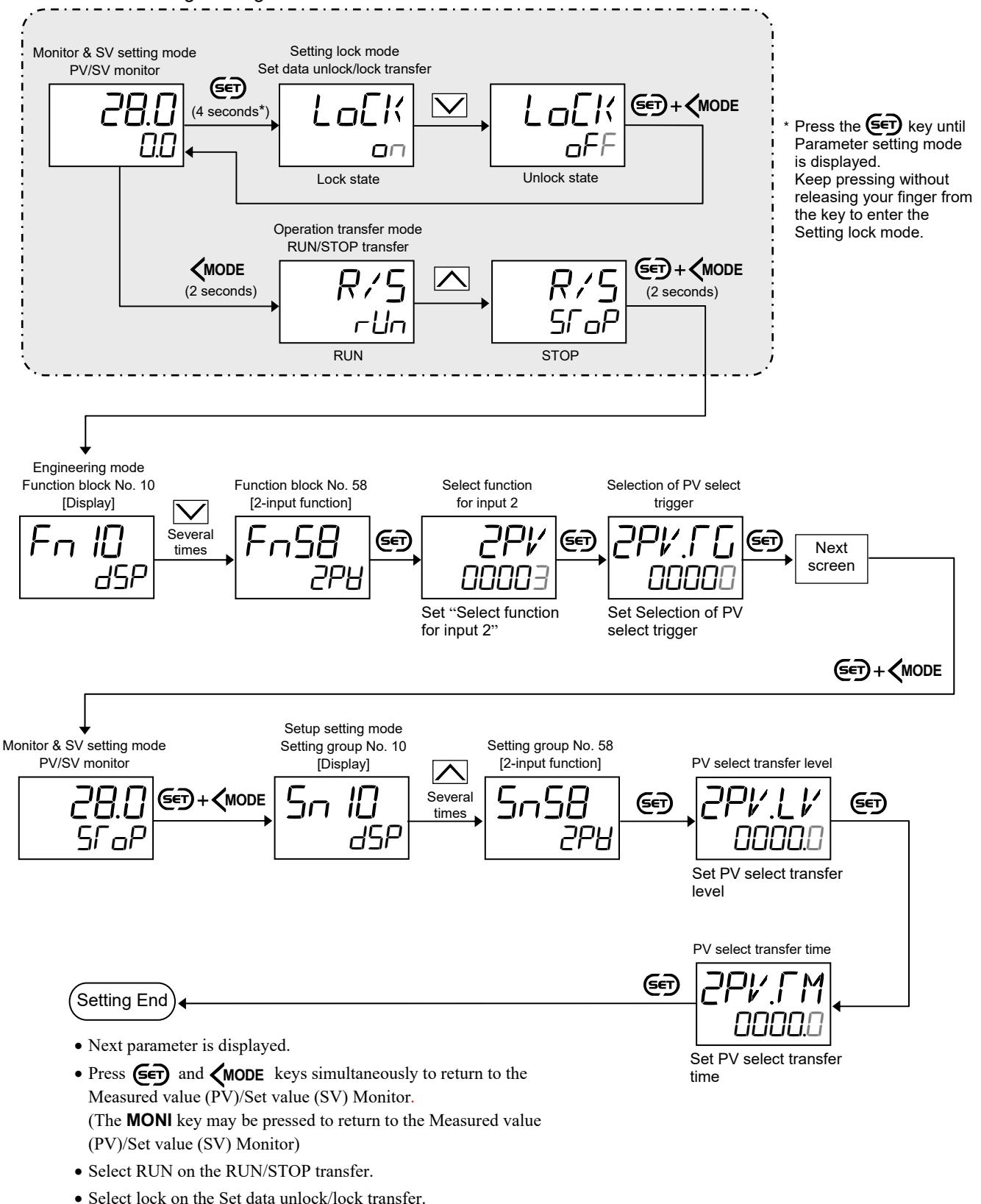
● **Selection of PV select trigger**
[Engineering mode: Function block No. 58 (Fn58)]

Parameter symbol	Data range	Factory set value
$2PV.FG$	0: Switching by level 1: Switching by signal (Key, DI and Communication)	0

 To display “Selection of PV select trigger,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to Control with PV select.

■ Setting procedure

To enter the Engineering mode

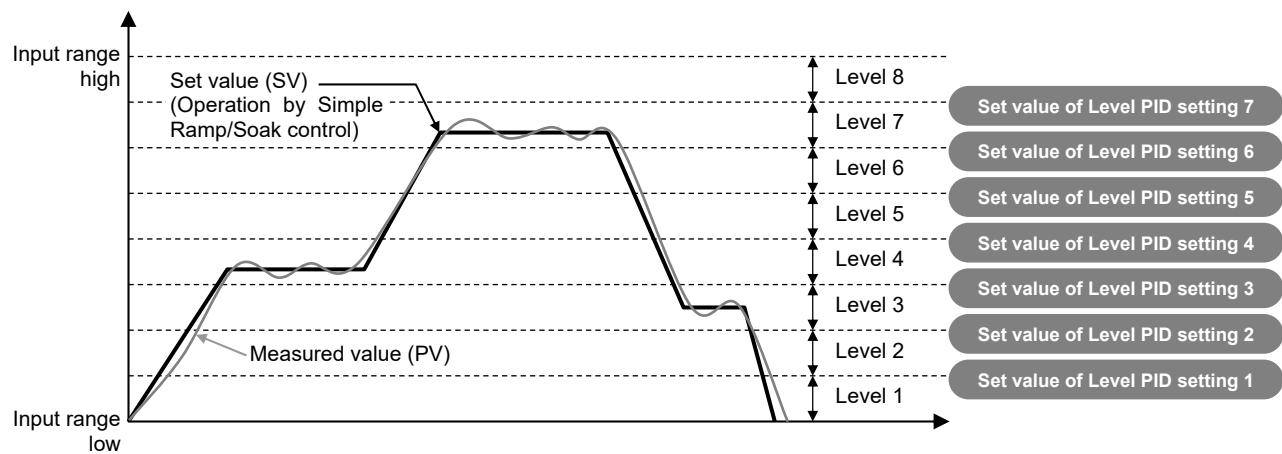


8.13 Controlling with Level PID

Level PID function is used to set the following parameters for control to each divided level of the input range (up to 8 levels): PID values, Control response parameters, Output limiter high/low, Control loop break alarm (LBA) time and LBA deadband.

■ Description of function

- Set the values such as PID values of each level to the Memory area 1 to 8 (PID memory group 1 to 8).
- The input range can be divided based on the setting for the parameters of Level PID setting 1 to Level PID setting 7.
- The value selected in the Level PID action selection [SV or PV] is checked and determined in which level of the PID it is, and the control is done using the PID values from the Memory area appropriate to the level.
- Different levels can be set at Input 1 and Input 2.



● Memory area to be used for level

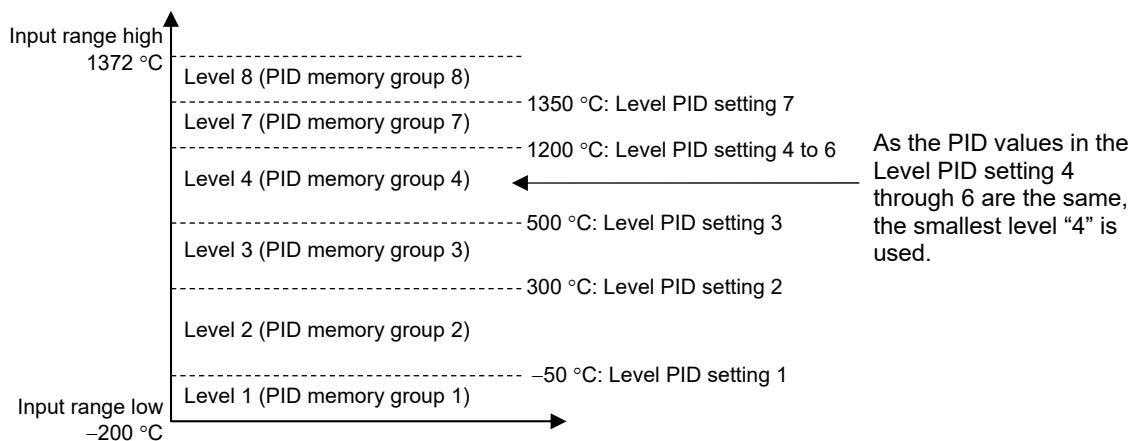
The memory area used at each level will be selected after comparison between the Level PID setting and the value [Set value (SV) or Measured value (PV)] selected in the Level PID action selection

Level	PID memory group	Description	Memory area
Level 8	PID memory group 8	Level PIDsetting 7 < Set value (SV) or Measured value (PV) ≤ Input rang high	Memory area 8
Level 7	PID memory group 7	Level PIDsetting 6 < Set value (SV) or Measured value (PV) ≤ Level PIDsetting 7	Memory area 7
Level 6	PID memory group 6	Level PIDsetting 5 < Set value (SV) or Measured value (PV) ≤ Level PIDsetting 6	Memory area 6
Level 5	PID memory group 5	Level PIDsetting 4 < Set value (SV) or Measured value (PV) ≤ Level PIDsetting 5	Memory area 5
Level 4	PID memory group 4	Level PIDsetting 3 < Set value (SV) or Measured value (PV) ≤ Level PIDsetting 4	Memory area 4
Level 3	PID memory group 3	Level PIDsetting 2 < Set value (SV) or Measured value (PV) ≤ Level PIDsetting 3	Memory area 3
Level 2	PID memory group 2	Level PIDsetting 1 < Set value (SV) or Measured value (PV) ≤ Level PIDsetting 2	Memory area 2
Level 1	PID memory group 1	Input range low ≤ Set value (SV) or Measured value (PV) ≤ Level PIDsetting 1	Memory area 1



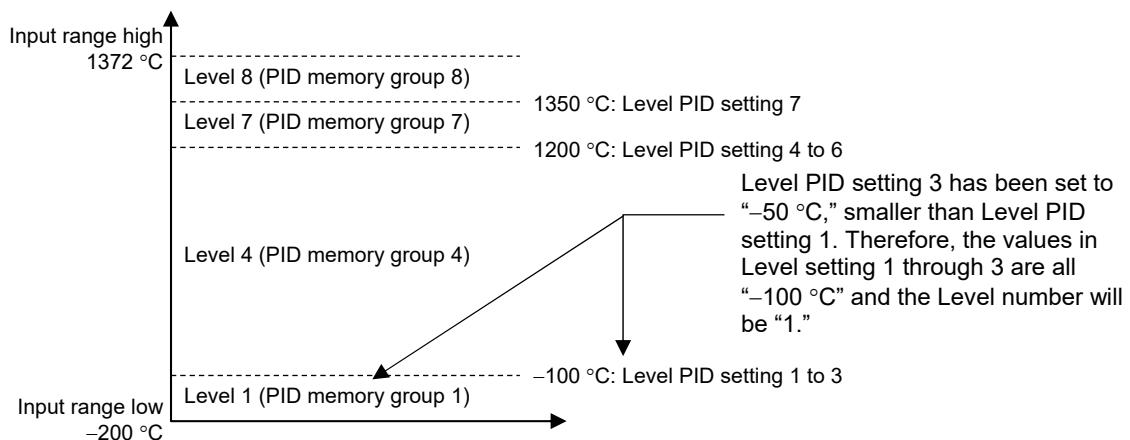
- When two or more levels have the same setting, the values with a smaller level number will be valid and used.

[Example 1] Values in Level PID setting 4 through 6 are the same.



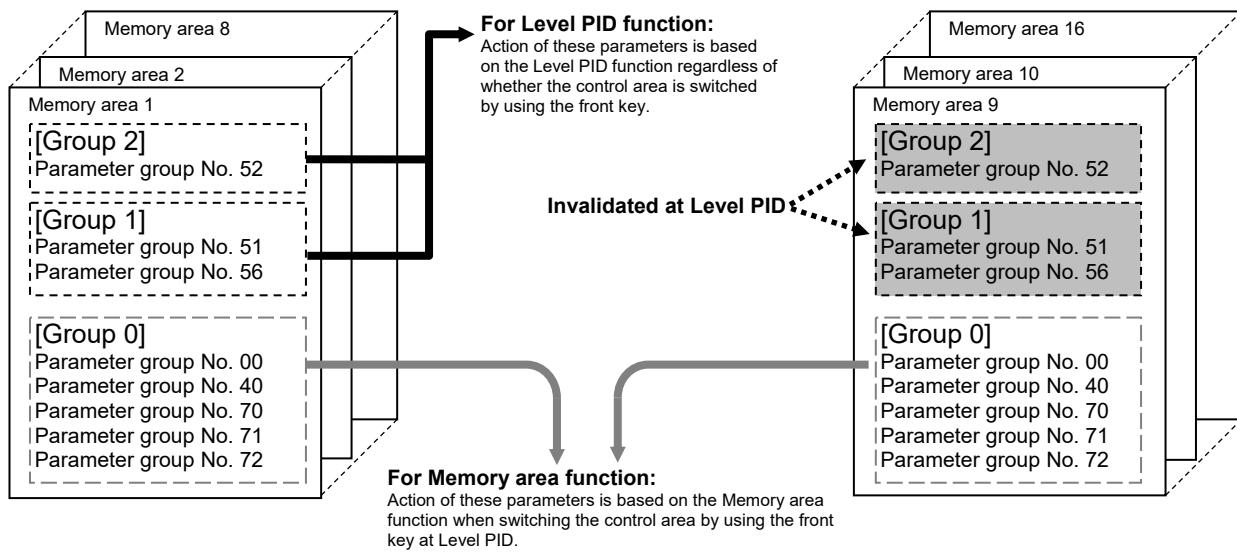
- If the Level PID setting is set ignoring the order of the level Nos., the Level PID values in the set range will be the same and the smallest level number is used. (See Example 2)

[Example 2] Level PID setting 3 in Example 1 has been changed to -100 °C.



● Parameters of Memory area in Level PID

When using Level PID, parameters of Memory area are separated to be used for the Level PID function and the regular Memory area function.



Parameters of Memory area (at Level PID)

Parameters in each group

Parameters for Level PID function (Memory area 1 to 8)

[Group 1] Parameter group No. 51

- Input 1_Proportional band [heat-side]
- Input 1_Integral time [heat-side]
- Input 1_Derivative time [heat-side]
- Input 1_Control response parameter
- Input 1_Proactive intensity
- Input 1_Manual reset
- Input 1_FF amount
- Input 1_Output limiter high [heat-side]
- Input 1_Output limiter low [heat-side]
- Input 1_Control loop break alarm (LBA) time
- Input 1_LBA deadband (LBD)

[Group 2] Parameter group No. 52

- Input 2_Proportional band
- Input 2_Integral time
- Input 2_Derivative time
- Input 2_Control response parameter
- Input 2_Proactive intensity
- Input 2_Manual reset
- Input 2_FF amount
- Input 2_Output limiter high
- Input 2_Output limiter low
- Input 2_Control loop break alarm (LBA) time
- Input 2_LBA deadband (LBD)

Parameter group No. 56

- Input 1_Proportional band [cool-side]
- Input 1_Integral time [cool-side]
- Input 1_Derivative time [cool-side]
- Input 1_Overlap/Deadband
- Input 1_Output limiter high [cool-side]
- Input 1_Output limiter low [cool-side]



During the Level PID, Memory areas 9 through 16 are not used (invalid).



These parameters are all in the Parameter setting mode. However, “ON/OFF action differential gap (upper)” and “ON/OFF action differential gap (lower)” are excluded.

Parameters for Memory area function (Memory area 1 to 16)

[Group 0]

Parameter group No. 00

- Input 1_Set value (SV)
- Input 2_Set value (SV)
- Set value (SV) of differential temperature input

Parameter group No. 40

- Event 1 set value (EV1)
Event 1 set value (EV1) [high]
- Event 1 set value (EV1') [low]
- Event 2 set value (EV2)
Event 2 set value (EV2) [high]
- Event 2 set value (EV2') [low]
- Event 3 set value (EV3)
Event 3 set value (EV3) [high]
- Event 3 set value (EV3') [low]
- Event 4 set value (EV4)
Event 4 set value (EV4) [high]
- Event 4 set value (EV4') [low]

Parameter group No. 70

- Select Trigger type for Memory area transfer
- Area soak time
- Link area number
- Input 1_Setting change rate limiter (up)
- Input 1_Setting change rate limiter (down)
- Input 1_Auto/Manual transfer selection (Area)
- Input 1_Manipulated output value (Area)
- Input 2_Setting change rate limiter (up)
- Input 2_Setting change rate limiter (down)
- Input 2_Auto/Manual transfer selection (Area)
- Input 2_Manipulated output value (Area)
- Remote/Local transfer selection (Area)

Parameter group No. 71

- Input 1_Number of knee point
- Input 1_Knee point input value 1
- Input 1_Knee point input value 2
- Input 1_Knee point input value 3
- Input 1_Knee point input value 4
- Input 1_Knee point input value 5
- Input 1_Knee point correction value 1
- Input 1_Knee point correction value 2
- Input 1_Knee point correction value 3
- Input 1_Knee point correction value 4
- Input 1_Knee point correction value 5

Parameter group No. 72

- Input 2_Number of knee point
- Input 2_Knee point input value 1
- Input 2_Knee point input value 2
- Input 2_Knee point input value 3
- Input 2_Knee point input value 4
- Input 2_Knee point input value 5
- Input 2_Knee point correction value 1
- Input 2_Knee point correction value 2
- Input 2_Knee point correction value 3
- Input 2_Knee point correction value 4
- Input 2_Knee point correction value 5

●Parameters for Level PID function

In Memory areas 1 through 8, the parameters in [Group 1] and [Group 2] are used as parameters for Level PID. Setting in Memory areas 9 through 16 will be ignored.

Memory area number for the control area can be changed by the front key, communication, Digital input (DI), Simple ramp/soak function or Simple sequence function; however, the parameters for Level PID function of the changed Memory area are invalidated.

The value selected in the Level PID action selection [SV or PV] is checked and determined in which level of the PID it is, and the control is done using the PID values from the Memory area appropriate to the level.

 See P. 8-74 for parameters in each group.

To use regular Memory area function

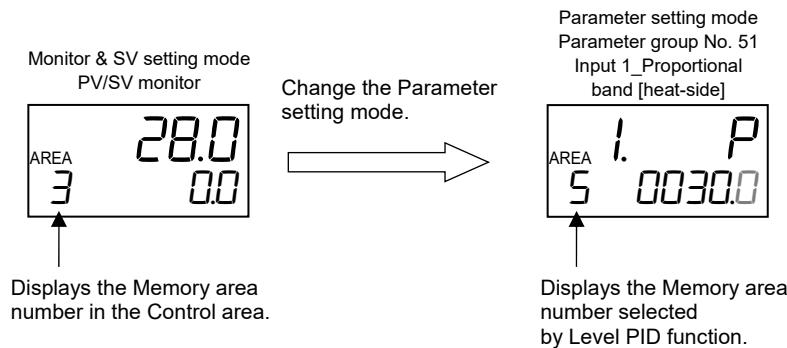
Input 1_Level PID action selection (Function block No. 51 in the Engineering mode) and Input 2_Level PID action selection (Function block No. 52 in the Engineering mode) can be used as a regular Memory area function in the case of “Switching by Memory area number” (Factory set value).

Memory area display at Level PID

PID values used for control are changed by the Level PID, but the control area is not influenced. This means that the Memory area No. on the PV/SV monitor screen in the Monitor & SV setting mode remains unchanged.

To check the Memory area No. actually used by the Level PID, locate the parameter used in the Level PID in the Parameter setting mode. Then, the actual Memory No. will be displayed. (See the example below)

[Example] In this example, Area 3 is displayed on the instrument (as a control area). Parameter “P” is displayed to show the Memory area No. actually used by the Level PID.

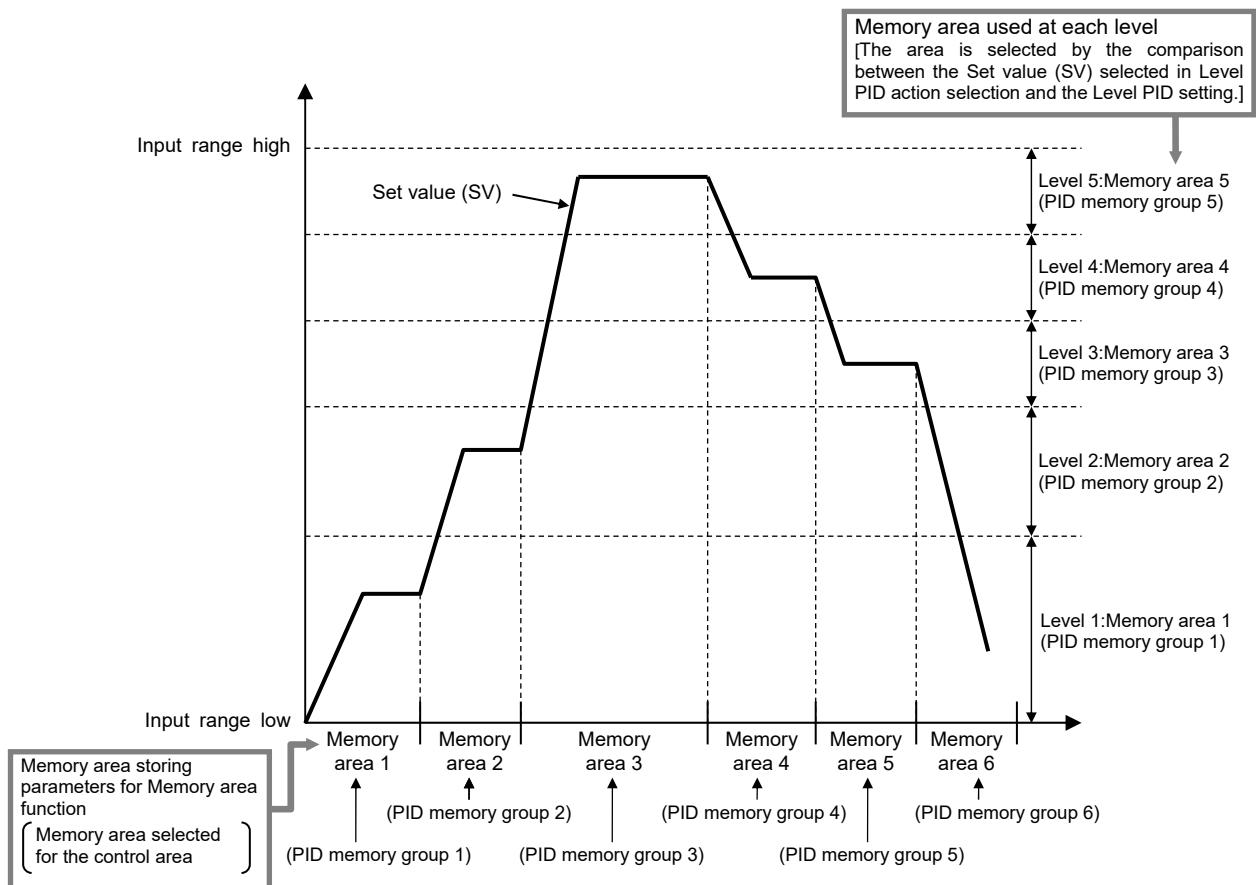


●Parameters for Memory area function

In Memory areas 1 through 16, parameters in [Group 0] can be used for the regular Memory area function. The parameters for the changed Memory area are validated by switching the Memory areas of the control area by the front key, communication, Digital input (DI), Simple ramp/soak function or Simple sequence function.

 For details of the parameters in Group 0, see P. 8-75.

- Example of action of the Memory area when setting simple ramp/soak program at Level PID
[When “1: Switching by Set value (SV) (Level PID action)” is selected in Level PID action selection]



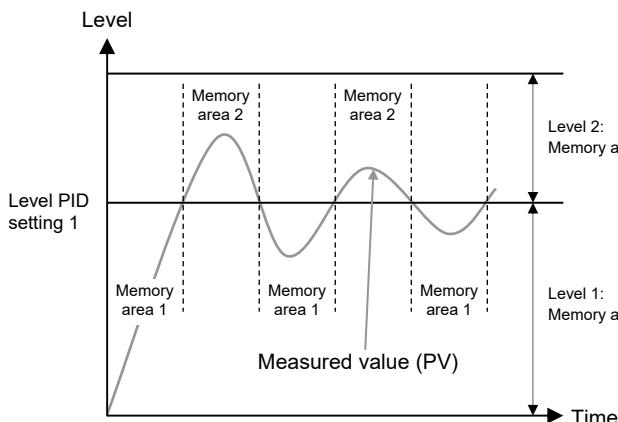
● Level PID differential gap

When setting “Switch by Measured value (PV)” to Level PID action:

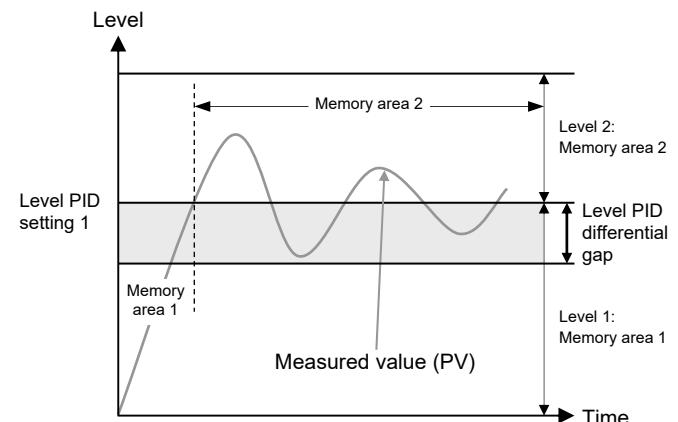
The Memory areas storing the parameters for Level PID function may switch frequently by the fluctuation of the input when the Measured value (PV) is close to the Level PID set value.

Setting Level PID differential gap prevents memory areas from switching too frequently.

When Level PID differential gap is not set



When Level PID differential gap is set



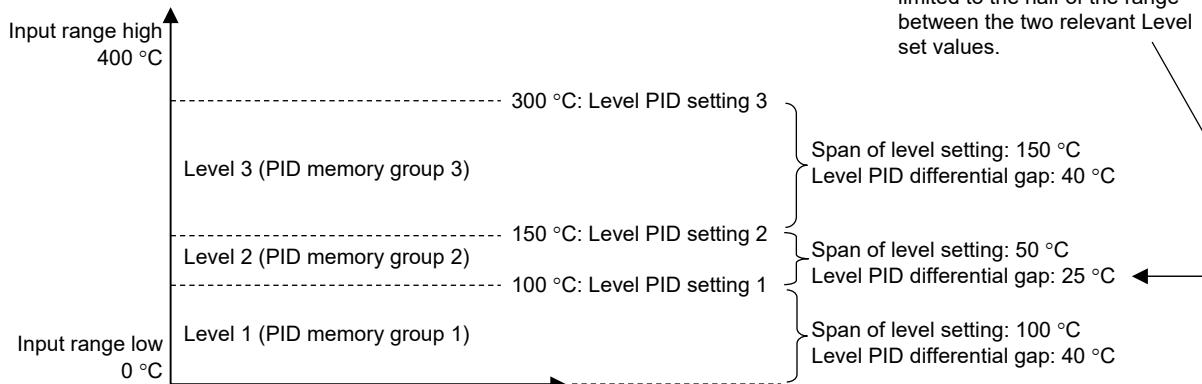
When setting “Switch by Set value (SV)” to Level PID action:

The setting of Level PID differential gap is validated; however, it is recommended to set “0.0” to Level PID differential gap.



When the setting of the Level PID differential gap is set larger than the half of the range between two continuous Level set values, the Level PID differential gap is forcedly limited to the half of the range between the two relevant Level set values.

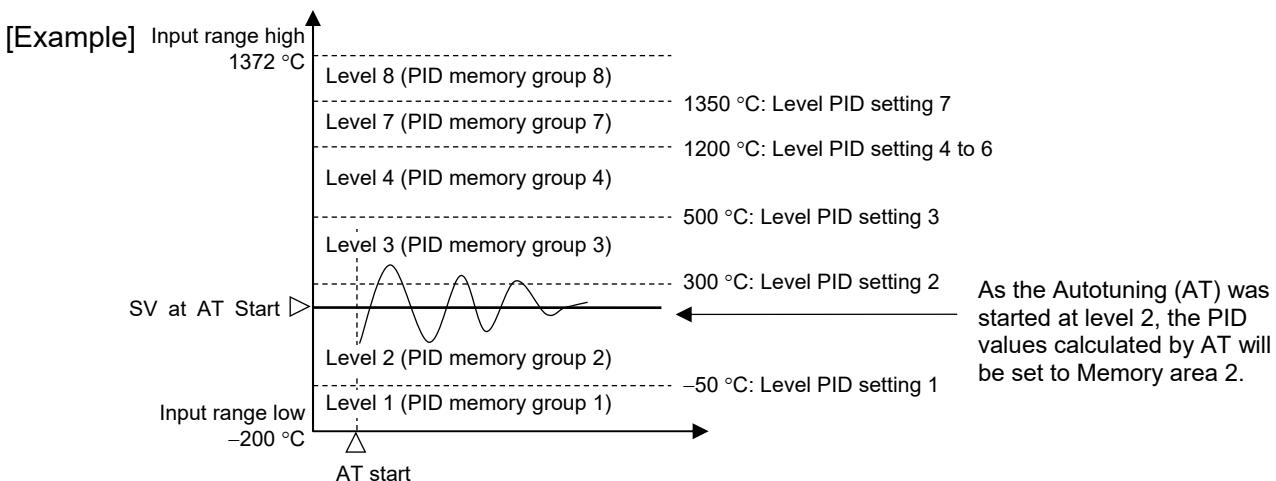
[Example] When Level PID differential gap is “40 °C”



● Autotuning (AT) at Level PID

Autotuning (AT) can be started even while Level PID function is used whether or not the Level PID action selection is “Switching by SV” or “Switching by PV.” Autotuning (AT) will be executed at the Set value (SV) when it is initiated.

The calculated PID values are stored in the memory area which has the Set value (SV) at the time of the Autotuning (AT) start.



● Level PID at Differential temperature control

When the Level PID action selection is “Switching by Set value (SV)”:

Level PID is done at the Input 1_Monitor Set value (SV)*.

* Input 1_Monitor Set value (SV) = Input 2_Measured value (PV) + Set value of Differential temperature input

When the Level PID action selection is “Switching by Measured value (PV)”:

Level PID is done at the Measured value (PV) Input 1.



The Level PID will not work at the Set value (SV) or Measured value (PV) of the Differential temperature input.

■ Parameter setting

- **Input 1_Level PID setting 1 to Input 1_Level PID setting 7**
[Setup Setting Mode: Setting group No. 51 (5n51)]

Parameter symbol	Data range	Factory set value
I.LEV1	Input 1_Input range low to Input 1_Input range high 〔When Control with PV select: PV select input range low to PV select input range high〕 [Varies with the setting of the Decimal point position.]	Input 1_Input range high Control with PV select: PV select input range high
I.LEV2		
I.LEV3		
I.LEV4	Input 1_Level PID settings 1 to 7 always maintain the following relation. (Input 1_Level PID setting 1) ≤ (Input 1_Level PID setting 2) ≤ (Input 1_Level PID setting 3) ≤ (Input 1_Level PID setting 4) ≤ (Input 1_Level PID setting 5) ≤ (Input 1_Level PID setting 6) ≤ (Input 1_Level PID setting 7)	
I.LEV5		
I.LEV6		
I.LEV7		

-  To display the “Input 1_Level PID setting 1 through 7,” set switchover by the Set value (SV) or the Measured value (PV) at “Input 1_Level PID action selection” in Function block No. 51 in the Engineering mode.
-  See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are automatically converted when the Level PID setting is changed.

- **Input 2_Level PID setting 1 to Input 2_Level PID setting 7**
[Setup Setting Mode: Setting group No. 52 (5n52)]

Parameter symbol	Data range	Factory set value
2.LEV1	Input 2_Input range low to Input 2_Input range high 〔Varies with the setting of the Decimal point position.]	Input 2_Input range high
2.LEV2		
2.LEV3		
2.LEV4	Input 2_Level PID settings 1 to 7 always maintain the following relation. (Input 2_Level PID setting 1) ≤ (Input 2_Level PID setting 2) ≤ (Input 2_Level PID setting 3) ≤ (Input 2_Level PID setting 4) ≤ (Input 2_Level PID setting 5) ≤ (Input 2_Level PID setting 6) ≤ (Input 2_Level PID setting 7)	
2.LEV5		
2.LEV6		
2.LEV7		

-  To display “Input 2_Level PID setting 1 to 7,” specify “Measured input 2” at the time of order, AND “Input 2_Level PID action selection” (Function block No. 58 in Engineering mode) select to “Switching by Set value (SV)” or “Switching by Measured value (PV),” AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.
-  See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are automatically converted when the Level PID setting is changed.

● **Input 1_Level PID action selection**
[Engineering mode: Function block No. 51 (Fn51)]

Parameter symbol	Data range	Factory set value
<i>ILPI d</i>	0: Switching by Memory area number 1: Switching by Set value (SV) (Level PID action) 2: Switching by Measured value (PV) (Level PID action)	0

● **Input 2_Level PID action selection**
[Engineering mode: Function block No. 52 (Fn52)]

Parameter symbol	Data range	Factory set value
<i>2LPI d</i>	0: Switching by Memory area number 1: Switching by Set value (SV) (Level PID action) 2: Switching by Measured value (PV) (Level PID action)	0

 To display “Input 2_Level PID action selection,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

● **Input 1_Level PID differential gap**
[Engineering mode: Function block No. 51 (Fn51)]

Parameter symbol	Data range	Factory set value
<i>1. LHS</i>	0 to Input 1_Input span (When Control with PV select: 0 to PV select input span) [Varies with the setting of the Decimal point position.]	TC/RTD inputs: 2 V/I inputs: 0.2 % of Input 1_input span Control with PV select: 0.2 % of PV select input span

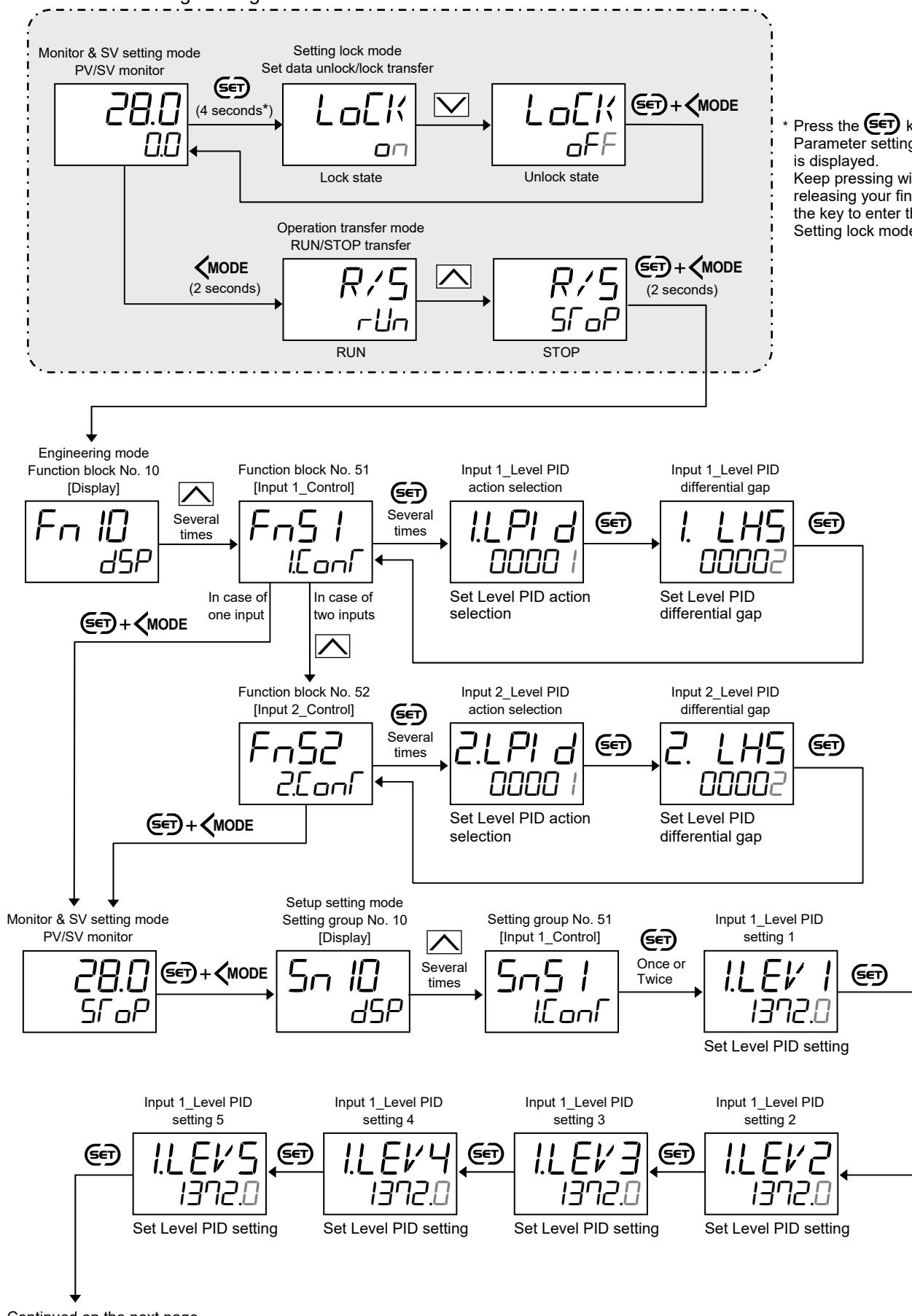
● **Input 2_Level PID differential gap**
[Engineering mode: Function block No. 52 (Fn52)]

Parameter symbol	Data range	Factory set value
<i>2. LHS</i>	0 to Input 2_Input span [Varies with the setting of the Decimal point position.]	TC/RTD inputs: 2 V/I inputs: 0.2 % of Input 2_input span

 To display “Input 2_Level PID differential gap,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

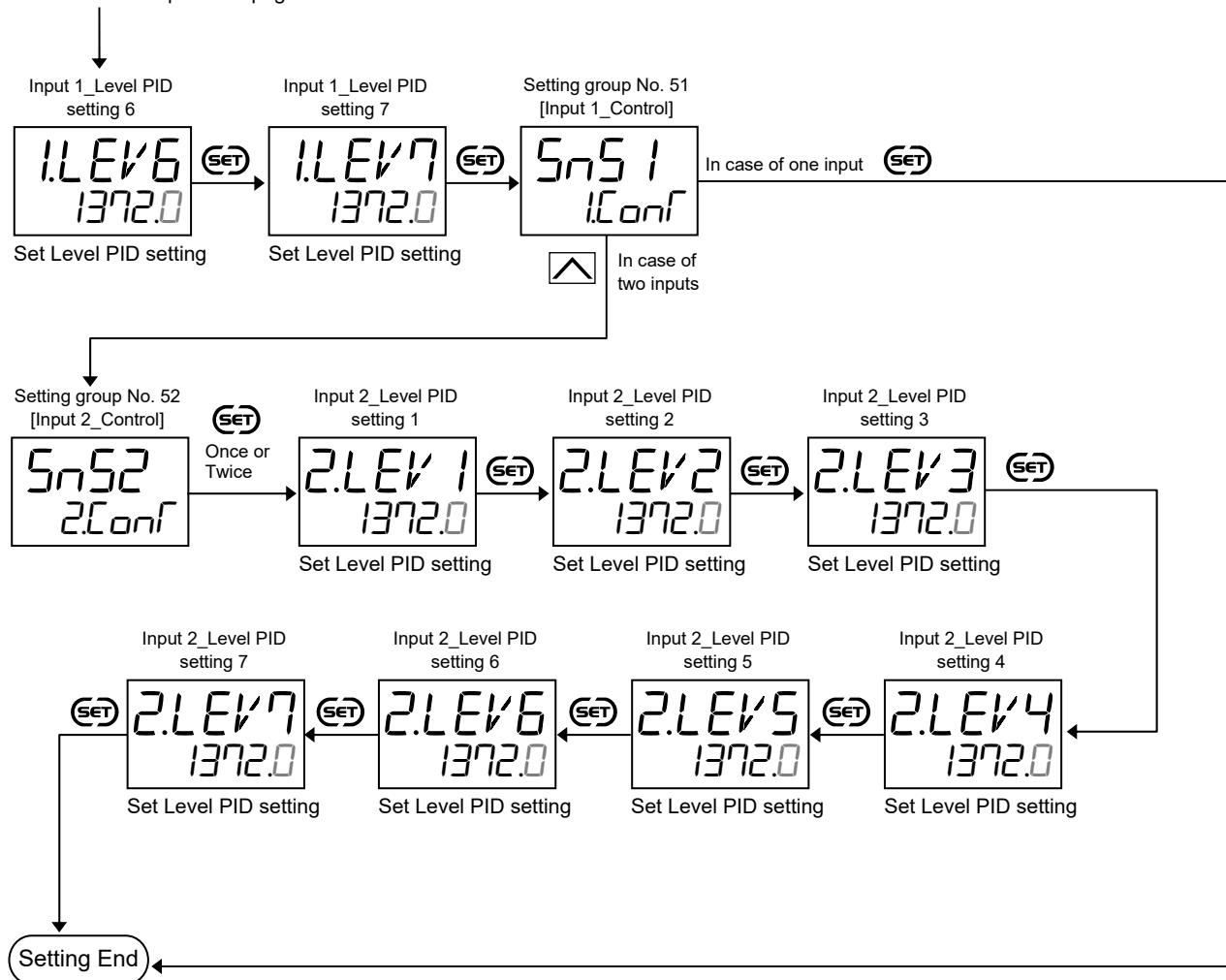
■ Setting procedure

To enter the Engineering mode



Continued on the next page.

Continued from the previous page.



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

8.14 Eliminating Offset Inherent to Proportioning Control (Manual Reset)

In order to eliminate the offset occurring in Proportional (P) control, the Manipulated output value is manually corrected.

■ Description of function

This is the function used to manually correct the offset when in Proportional (P) control or PD control. If the Manual reset value varies, the Manipulated output value also changes.

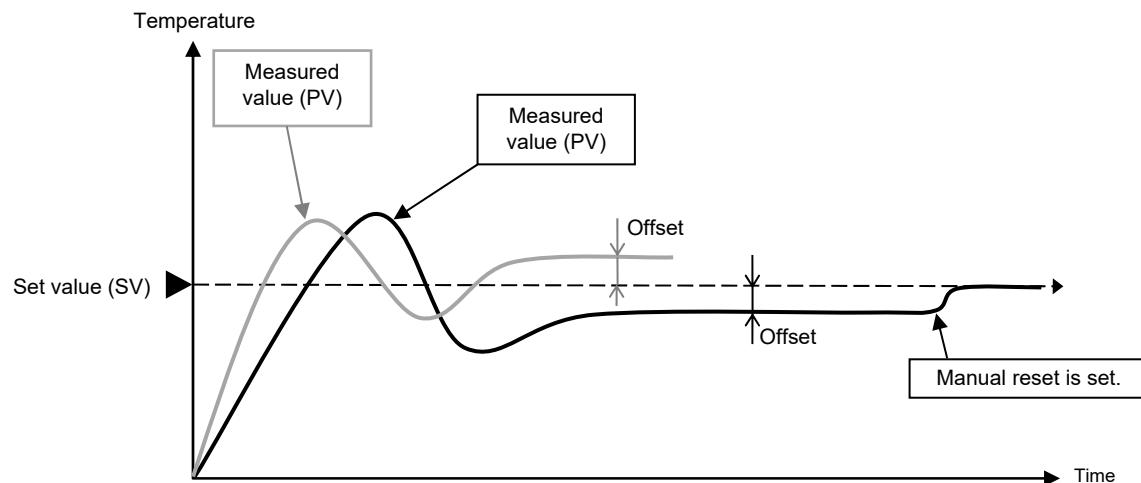
Offset means the deviation of the actual when the Manipulated output value becomes stabilized (stable state).

- When the Manual reset is set to the plus (+) side

The Manipulated output value under the stable condition increases by the Manual reset value.

- When the Manual reset is set to the minus (-) side

The Manipulated output value * under the stable condition decreases by the Manual reset value.



Manual reset is available when the Integral time is 0 (0.0, 0.00 or 0.000).

■ Parameter setting

- Input 1_Manual reset

[Parameter Setting Mode: Parameter group No. 51 ($P_{n5} _I$)]

Parameter symbol	Data range	Factory set value
I. MR	-100.0 to +100.0 %	0.0



To display “Input 1_Manual reset,” set “0” (zero) to the “Input 1_Integral time [heat-side].”

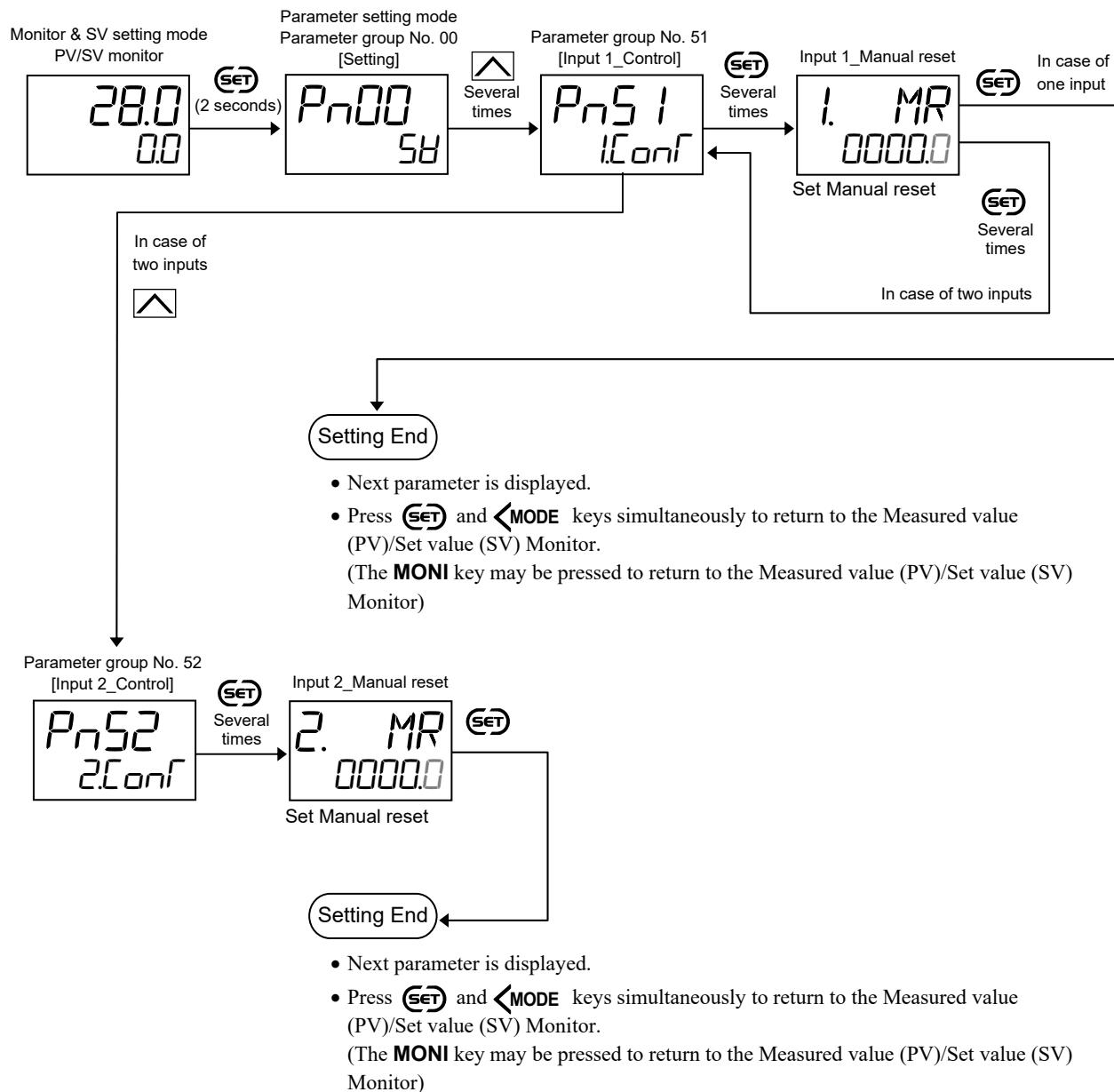
● Input 2_Manual reset

[Parameter Setting Mode: Parameter group No. 52 (Pn52)]

Parameter symbol	Data range	Factory set value
2. MR	-100.0 to +100.0 %	0.0

-  To display “Input 2_Manual reset,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control. Additionally, you also need to set “0” (zero) to the “Input 1_Integral time.”

■ Setting procedure



8.15 Continuing Stable Control after the Operation Transfer (SV Tracking)

This function is used to follow (keep tracking of) the other set value in another mode (control) that was used before the change of the set value. This is useful to suppress a sudden change of the set value when the operation mode is changed.

■ Description of function

The SV tracking can be selected at the time of switching between Remote/Local and Auto/Manual. The functions can be selected independently or together.

● SV tracking at the time of Remote/Local transfer

The SV tracking at the time of Remote/Local transfer may be effective in such switching actions.

- Switching between Remote and Local mode
- Switching between 2-loop control and Differential temperature control

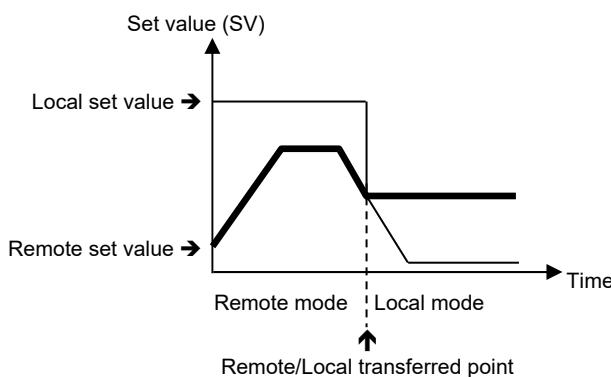
Switching between Remote and Local mode

When the operation mode is switched from Remote to Local mode, the Local set value follows the Remote set value just before the switching (tracking).

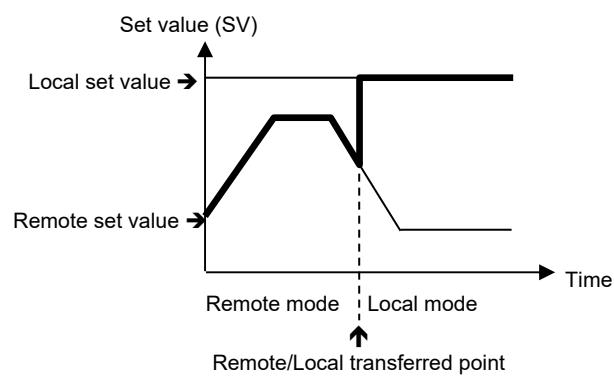
[Change of set values when switched from Remote to Local mode]

Operation mode:	Remote mode	→	Local mode
Set value used	Set value (SV) = Remote set value		Set value (SV) = Local set value
SV tracking used	Local set value ≠ Remote set value		Local set value = Remote set value
SV tracking unused	Local set value ≠ Remote set value		Local set value ≠ Remote set value

< SV tracking used >



< SV tracking unused >



The SV tracking does not function at the time of switching from Local mode to Remote mode.

Switching between 2-loop control and Differential temperature control

When the Differential temperature control is switched to 2-loop control, the Input 1_Set value (SV) follows the Input 1_set value monitor [PV just before the switching + Set value of Differential temperature control]



In case of Differential temperature control, the Input 1_Set value (SV) is not used for control.

The Input 1_Monitor Set value (SV)* of is used in actual control.

* Input 1_Monitor Set value (SV) = Controlled temperature

= Input 2_Measured value (PV) [Reference temperature] + Set value of Differential temperature input

[Change of set values when switched from Differential temperature control to 2-loop control]

Control:	Differential temperature control	2-loop control
Set value used (Input 1)	Input 1_Set value monitor	Input 1_Set value (SV)
SV tracking used	$\text{Input 1_Set value (SV)} = \text{Input 1_Set value (SV)}$ $\text{Input 1_Set value monitor} = \text{Input 2_PV} + \text{Set value of Differential temperature input}$	$\text{Input 1_Set value (SV)} = \text{Input 2_PV just before the switching} + \text{Set value of Differential temperature input}$ $\text{Input 1_Set value monitor} = \text{Input 2_PV} + \text{Set value of Differential temperature input}$
SV tracking unused	$\text{Input 1_Set value (SV)} = \text{Input 1_Set value (SV)}$ $\text{Input 1_Set value monitor} = \text{Input 2_PV} + \text{Set value of Differential temperature input}$	$\text{Input 1_Set value (SV)} = \text{Input 1_Set value (SV)}$ $\text{Input 1_Set value monitor} = \text{Input 1_Set value (SV)}$



The SV tracking does not function at the time of switching from 2-loop control to Differential temperature control.

● SV tracking at the time of Auto/Manual transfer

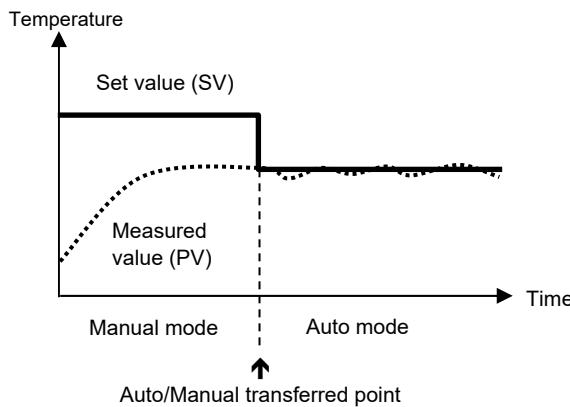
When the Manual mode is switched to the Auto mode, the Set value (SV) follows the Measured value (PV) just before the switching.

[Change of set values when switched from Manual mode to Auto mode]

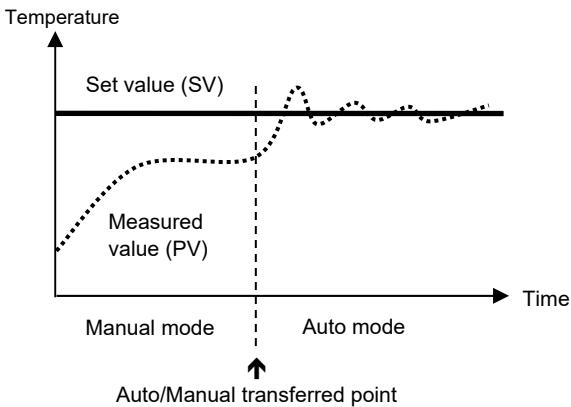
Operation mode:	Manual mode	Auto mode
SV tracking used	Set value (SV) = Set value (SV) Measured value (PV) = Measured value (PV)	Set value (SV) = Measured value (PV) just before the switching Measured value (PV) = Measured value (PV)
SV tracking unused	Set value (SV) = Set value (SV) Measured value (PV) = Measured value (PV)	Set value (SV) = Set value (SV) Measured value (PV) = Measured value (PV)

Input 1 and Input 2 is the same action.

< SV tracking used >



< SV tracking unused >



The SV tracking does not function at the time of switching from Auto mode to Manual mode.



SV tracking does not function at the time of Auto/Manual switching at the Differential temperature control.

■ Parameter setting

● Input 1_Auto/Manual transfer [Operation Transfer Mode]

Parameter symbol	Data range	Factory set value
I. R/M	RUF _o : Auto mode nRn: Manual mode	RUF _o



This parameter is not displayed when this parameter is fixed to “Fix parameter setting: Auto/Manual transfer” in the Setting lock mode.

● **Input 2_Auto/Manual transfer**
[Operation Transfer Mode]

Parameter symbol	Data range	Factory set value
2. $I_{A/M}$	AUf_o : Auto mode $\bar{n}Rn$: Manual mode	AUf_o

- To display “Input 2_Auto/Manual transfer,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.
- This parameter is not displayed when this parameter is fixed to “Fix parameter setting: Auto/Manual transfer” in the Setting lock mode.

● **Remote/Local transfer**
[Operation Transfer Mode]

Parameter symbol	Data range	Factory set value
R/L	When “Remote setting input” is selected at Select function for input 2 LoL : Local mode rEn : Remote mode	LoL
	When “2-loop control/Differential temperature control” is selected at Select function for input 2 $2Loop$: 2-loop control dFF : Differential temperature control	$2Loop$

- To display “Remote/Local transfer”, you need to specify the “Remote setting input” at the time of order, or configure the “Measured input 2” (that must be also specified at the time order) to the Remote setting input at “Select function for input 2” in Function block No. 58 in the Engineering mode.
- This parameter is not displayed when this parameter is fixed to “Fix parameter setting: Remote/Local transfer” in the Setting lock mode.

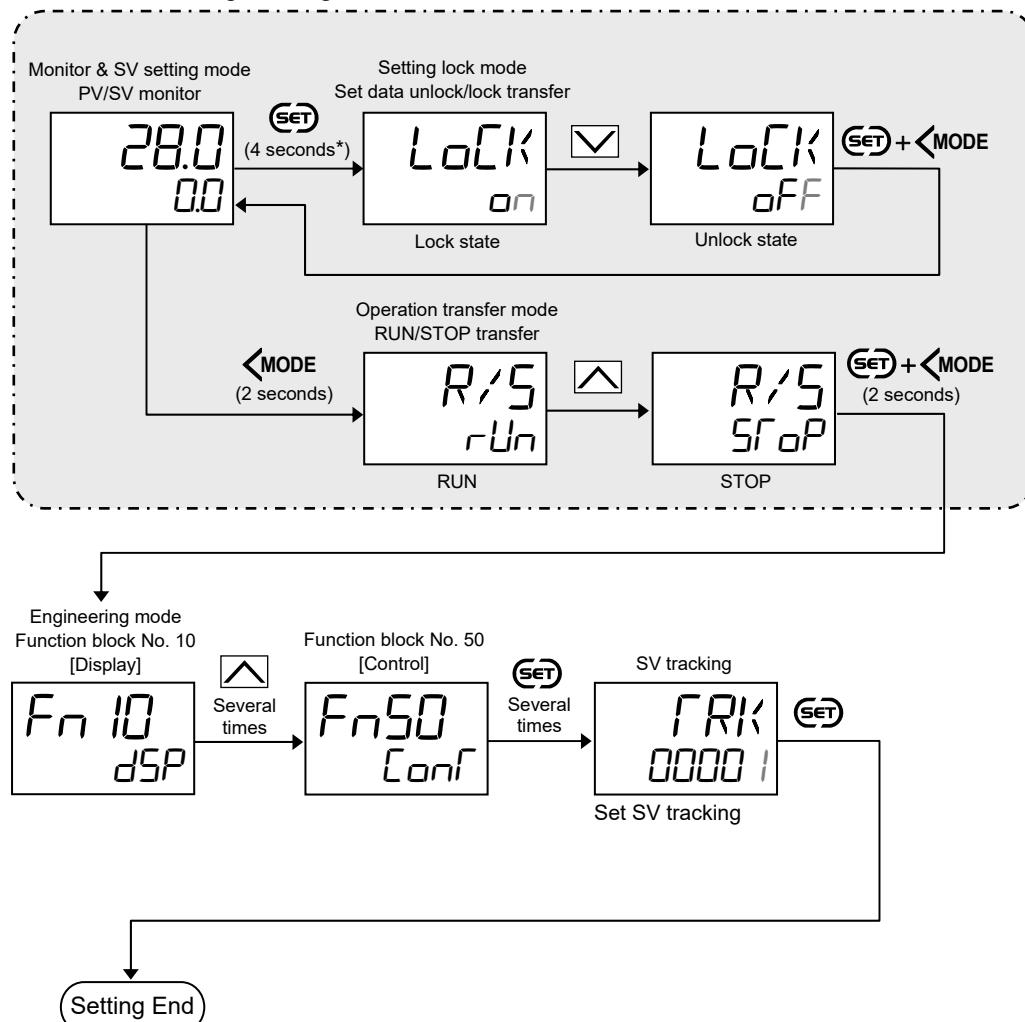
● **SV tracking**
[Engineering Mode: Function block No. 50 (Fn50)]

Parameter symbol	Data range	Factory set value
FRK	0 to 3 0: No SV tracking function +1: SV tracking at transferring Remote/Local * * Including 2-loop control/Differential temperature control transfer +2: SV tracking at transferring Auto/Manual To select two or more functions, sum each value.	1

■ Setting procedure

● SV tracking setting

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.

- Next parameter is displayed.
- Press **SET** and **MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

For detailed operation of Auto/Manual switching, see **8.8 Controlling with Manual Control (P.8-44)**.

For detailed operation of Remote/Local switching, see **8.9 Using Remote Setting Input (P.8-49)**.

8.16 Suppressing Overshoot

Overshoot can be suppressed on this instrument at the time of startup (power on, control stop to start), Set value (SV) change, and external disturbances.

Overshoot during the transition from Ramp to Soak can be prevented, when the Setting change rate limiter is used.

■ Description of function

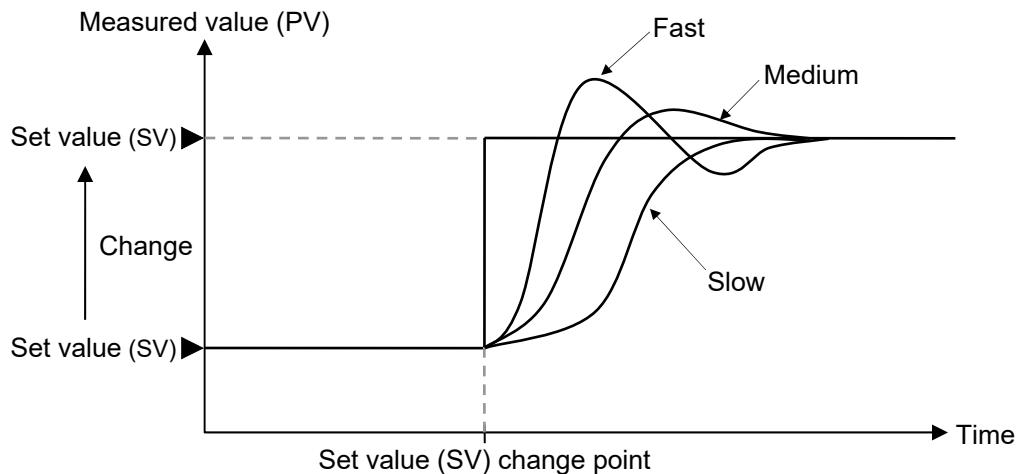
Overshoot suppressing function may include Control response parameter, Proactive intensity, Determination point of external disturbance and Bottom suppression function.

● Control response parameter

A response speed level at changing Set value (SV) at PID control can be selected from three levels (Slow, Medium and Fast) in the Control response parameter.

Select “Fast” to quicken the response of the controlled object to the change in segment level and Set value (SV). When the response speed level is “Fast,” overshoot will occur. To avoid overshoot, select “Slow.”

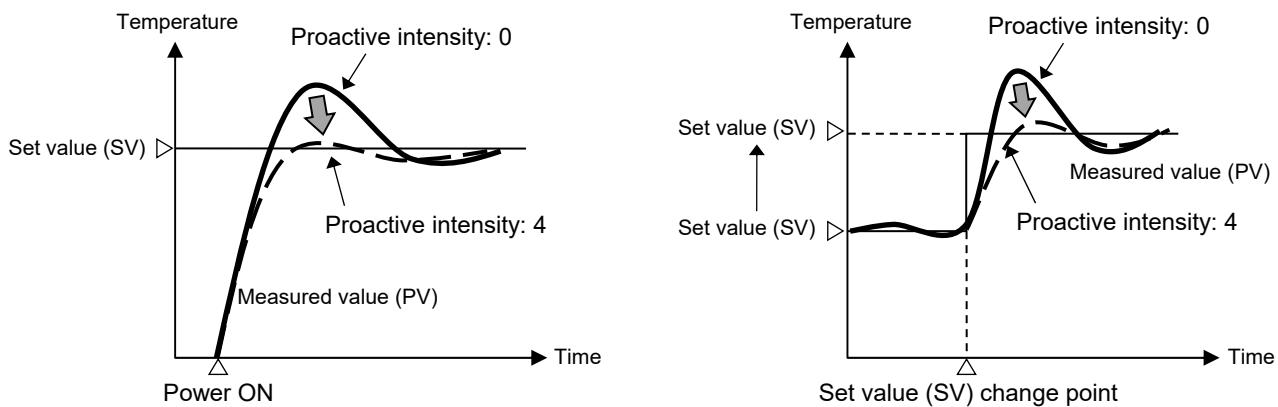
Fast	Selected when rise time needs to be shortened (operation needs to started fast). However in this case, slight overshooting may not be avoided.
Medium	Middle between “Fast” and “Slow.” Overshooting when set to “Medium” becomes less than that when set to “Fast.”
Slow	Selected when no overshooting is allowed. Used when material may be deteriorated if the temperature becomes higher than the set value.



● Proactive intensity, Determination point of external disturbance

Overshoot can be suppressed at startup (power on, control stop to start), Set value (SV) change, and external disturbances. Overshoot during the transition from Ramp to Soak can be prevented. The intensity ranges from 0 to 4 (5 scales).

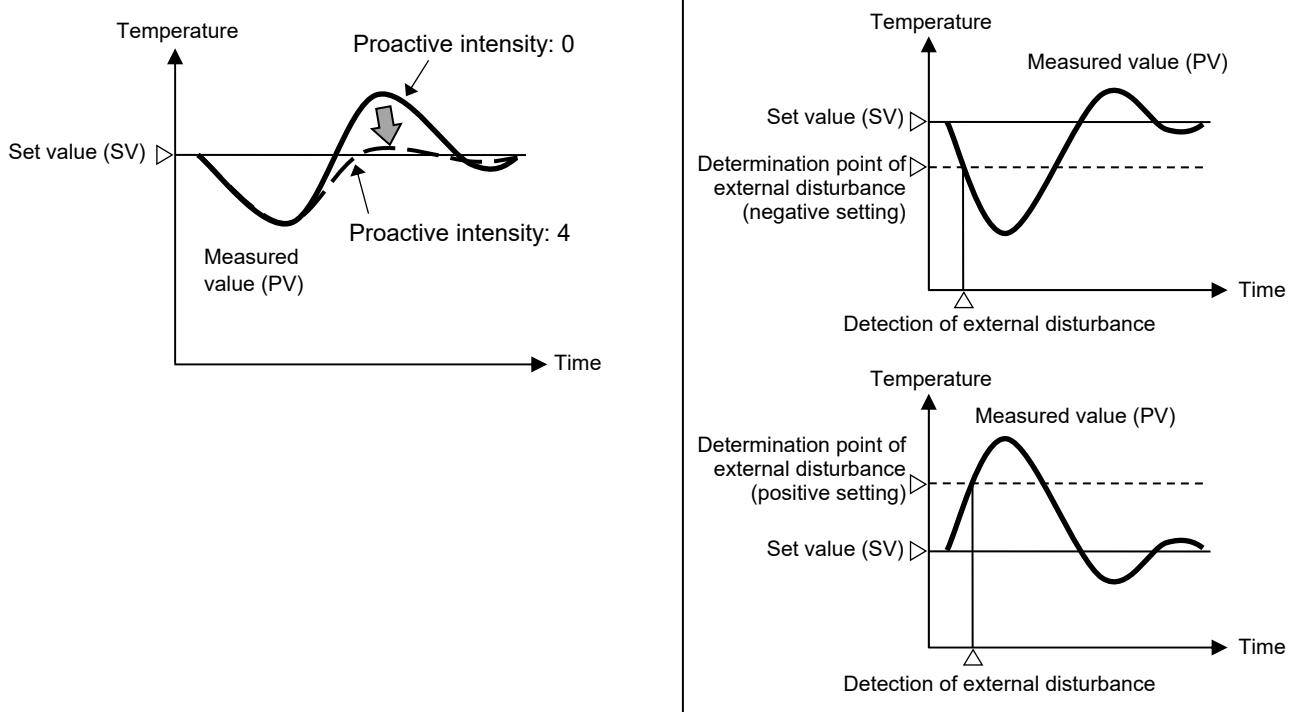
Startup (power on, control stop to start), Set value (SV) change



When external disturbance occurs

Overshoot can be suppressed when external disturbance occurs.

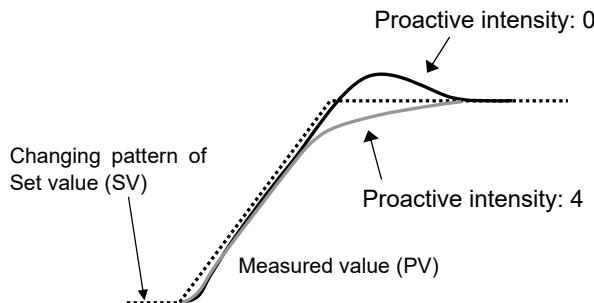
External disturbances are determined by the fluctuation between the stable state and Measured value (PV) of the external disturbance determination point or more which is then used as a trigger.



When Input knee point correction function is enabled, Proactive function is disabled.

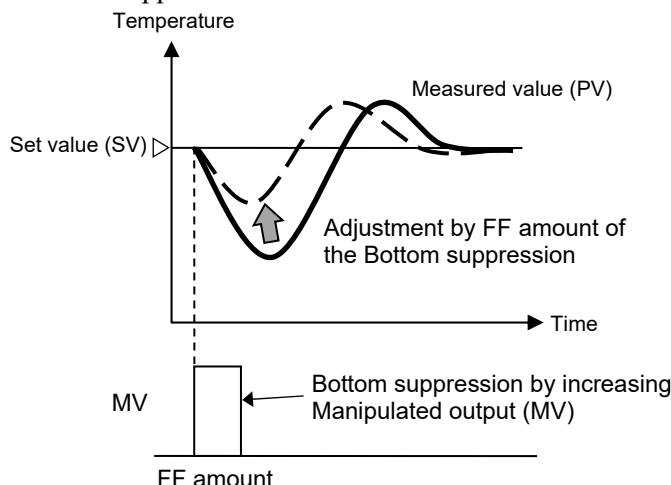
During Ramp control (Change of SV by Setting change rate limiter)

Overshoot can be suppressed when the temperature is in transition from the Ramp state to the Soak state.



● Bottom suppression function

When the input fluctuation by external disturbance is detected, the amount of FF (Feedforward) is added to the output value to suppress the Bottom.



[Setting items]

- FF amount: This can also be obtained automatically by Amount of FF which is added to detect external disturbance and Learning function
- FF amount learning: FF amount can be calculated from external disturbance when detection of external disturbance is executed after selection of "Learn." When setting is completed, the value will automatically return to "0: No learning."
- Bottom suppression function: Used to activate/deactivate the Bottom suppression function as well as a trigger function. There are two types of triggers; when the Determination point of external disturbance (FF amount is added by the level) is exceeded and Forced addition off FF amount. Trigger signal can be input through communication in the case of Forced addition of FF amount.

■ Parameter setting

● Input 1_Control response parameter

[Parameter Setting Mode: Parameter group No. 51 ($Pn5\ 1$)]

Parameter symbol	Data range	Factory set value
$I_1.RPF$	0: Slow 1: Medium 2: Fast [When the P or PD action is selected, this setting becomes invalid]	PID control: 0 Heat/Cool PID control: 2

-  When this parameter is set and fixed to Slow at “Fix parameter setting: Control response parameter” in the Setting lock mode, the setting is fixed to 0.

● Input 2_Control response parameter

[Parameter Setting Mode: Parameter group No. 52 ($Pn52$)]

Parameter symbol	Data range	Factory set value
$I_2.RPF$	0: Slow 1: Medium 2: Fast [When the P or PD action is selected, this setting becomes invalid]	0

-  To display “Input 2_Control response parameter,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.
-  When this parameter is set and fixed to Slow at “Fix parameter setting: Control response parameter” in the Setting lock mode, the setting is fixed to 0.

● Input 1_Proactive intensity

[Parameter Setting Mode: Parameter group No. 51 ($Pn5\ 1$)]

Parameter symbol	Data range	Factory set value
$I.PACT$	0 to 4 0: No function	2

-  To display “Input 1_Proactive intensity,” the Input 1_Proportional band [heat-side] and the Input 1_Integral time [heat-side] in the same memory area must be set to a value other than zero.
-  When Input knee point correction function is enabled, Proactive function is disabled.

● Input 2_Proactive intensity

[Parameter Setting Mode: Parameter group No. 52 (Pn52)]

Parameter symbol	Data range	Factory set value
2.PRACT	0 to 4 0: No function	2

-  To display “Input 2_Proactive intensity,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control. Additionally, you also need to enter a value other than 0 in the Input 2_Proportional band and the Input 2_Integral time in the same memory area.
-  When Input knee point correction function is enabled, Proactive function is disabled.

● Input 1_FF amount

[Parameter Setting Mode: Parameter group No. 51 (Pn51)]

Parameter symbol	Data range	Factory set value
1. FF	-100.0 to +100.0 %	0.0

-  To display “Input 1_FF amount,” 1 or 2 must be set at “Bottom suppression function” at Function block No. 57 in the Engineering mode, and the Input 1_Proportional band [heat-side] and the Input 1_Integral time [heat-side] in the same memory area must be set to a value other than zero.

● Input 2_FF amount

[Parameter Setting Mode: Parameter group No. 52 (Pn52)]

Parameter symbol	Data range	Factory set value
2. FF	-100.0 to +100.0 %	0.0

-  To display “Input 1_FF amount,” 1 or 2 must be set at “Bottom suppression function” at Function block No. 57 in the Engineering mode, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control. Additionally, you also need to enter a value other than 0 in the Input 2_Proportional band and the Input 2_Integral time in the same memory area.

● FF amount learning

[Setup Setting Mode: Setting group No. 57 (S57)]

Parameter symbol	Data range	Factory set value
FFSL	0 to 3 0: No learning +1: Learn Input 1 +2: Learn Input 2 To select two or more functions, sum each value.	0

-  To display “FF amount learning,” 1 or 2 must be set at “Bottom suppression function” at Function block No. 57 in the Engineering mode

● **Input 1_Determination point of external disturbance**
[Setup Setting Mode: Setting group No. 57 (S_nS₇)]

Parameter symbol	Data range	Factory set value
<i>I.E₁Xdu</i>	-(Input 1_Input span) to +(Input 1_Input span) When Control with PV select: -(PV select input span) to +(PV select input span) [Varies with the setting of the Decimal point position.]	-1

● **Input 2_Determination point of external disturbance**
[Setup Setting Mode: Setting group No. 57 (S_nS₇)]

Parameter symbol	Data range	Factory set value
<i>I.E₂Xdu</i>	-(Input 2_Input span) to +(Input 2_Input span) [Varies with the setting of the Decimal point position.]	-1



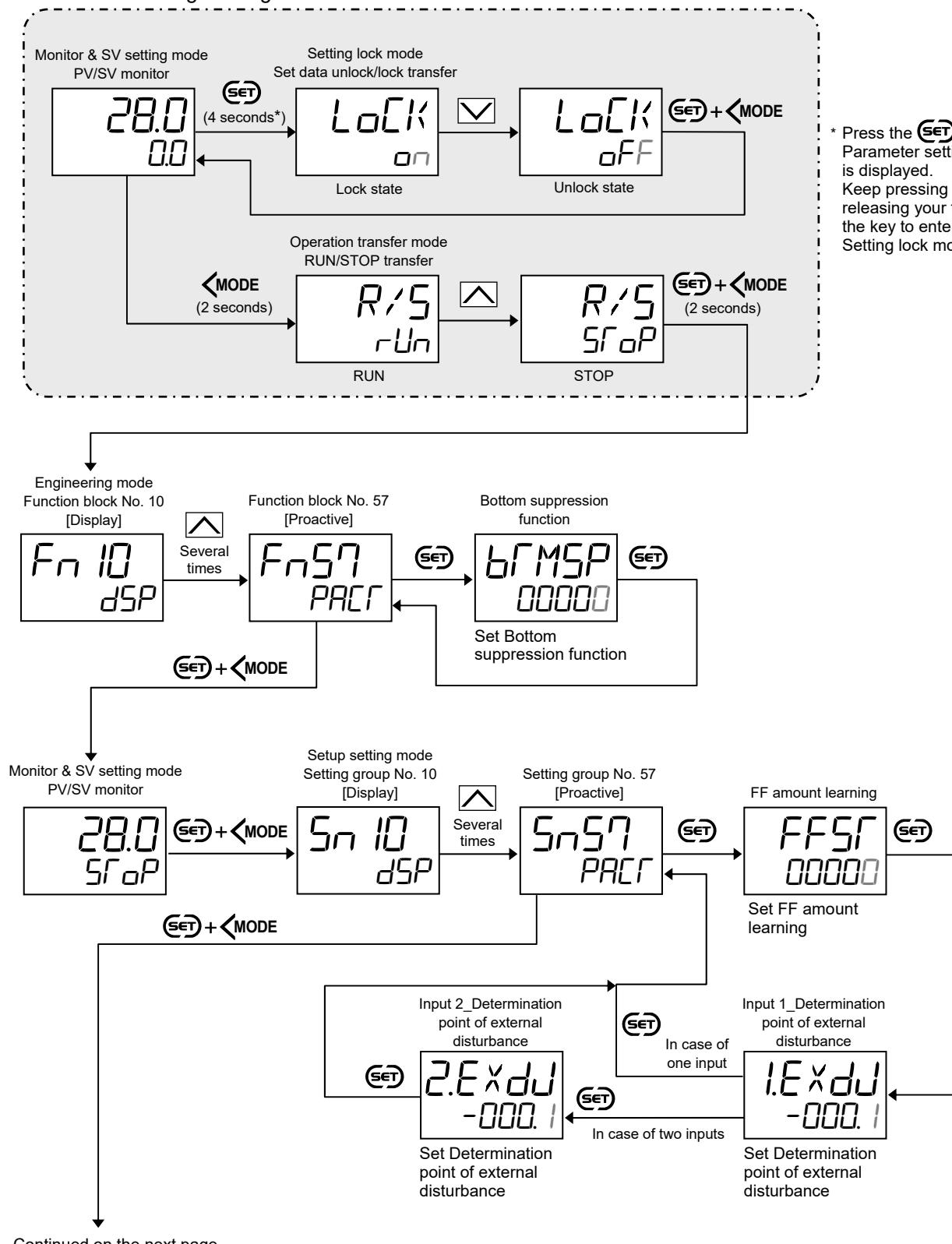
To display “Input 2_Determination point of external disturbance,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

● **Bottom suppression function**
[Engineering Mode: Function block No. 57 (F_nS₇)]

Parameter symbol	Data range	Factory set value
<i>b₁FMS_P</i>	0: No function 1: FF amount is added by level 2: FF amount is forcibly added	0

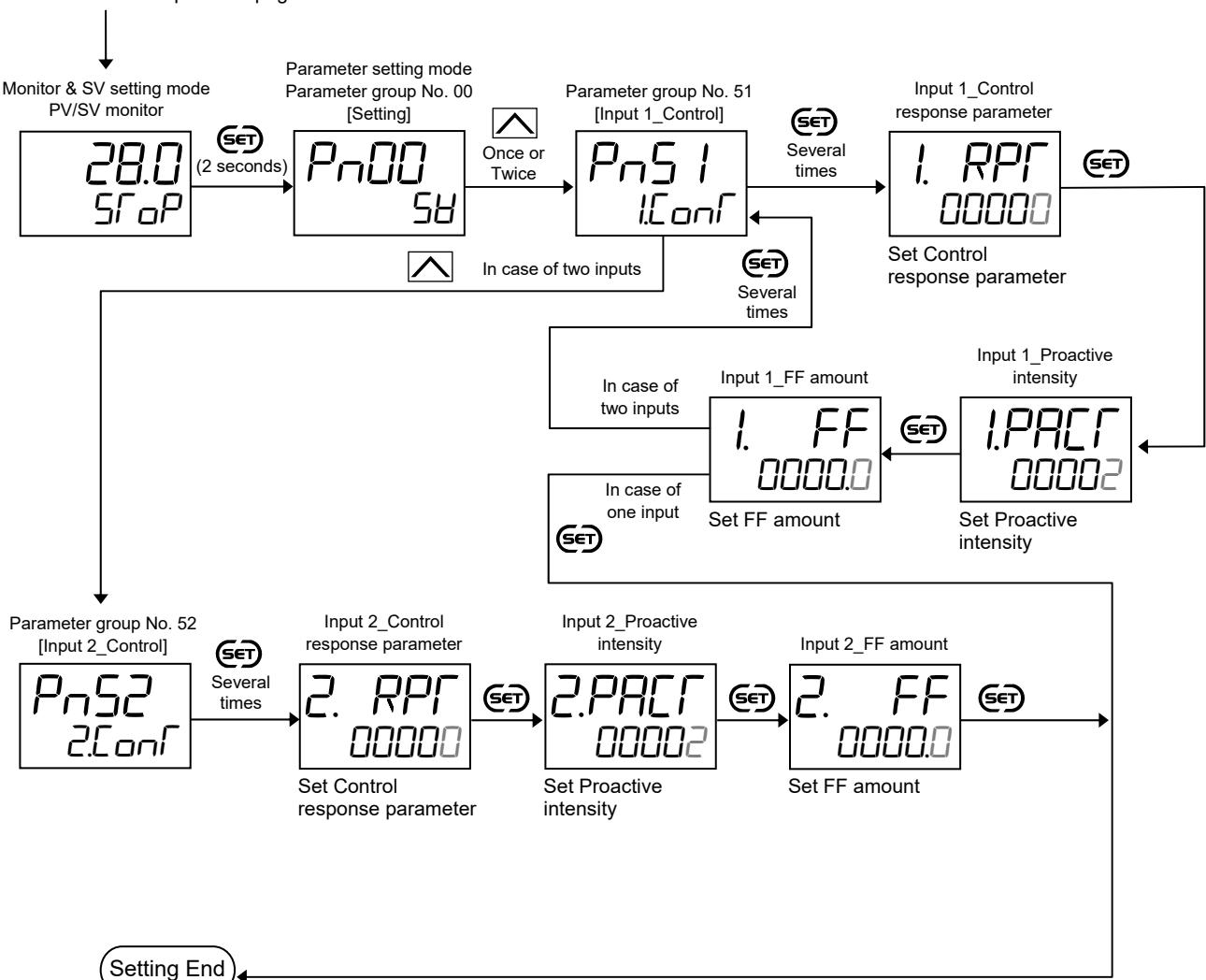
■ Setting procedure

To enter the Engineering mode



Continued on the next page.

Continued from the previous page.



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

8.17 Changing the Action at Power ON (Hot/Cold Start)

When restarting following a power failure (power OFF from ON), the start action can be selected by the following parameters:

- Hot/Cold start
- Start determination point

■ Description of function

● Hot/Cold start

Recovery action from power failure can be selected from the following.

For PID control or Heat/Cool PID control

Action when power failure recovers	Operation mode when power failure recovers	Output value when power failure recovers	
Hot start 1	Same as that before power failure	Near the output value before power failure occurs	
Hot start 2	Same as that before power failure	Auto mode	Computed control output value ²
		Manual mode	Output limiter low
Cold start	Manual control mode	Output limiter low	
STOP start	Started in the Reset mode regardless of the Operation mode before power failure. ¹	Manipulated output value (MV) at STOP	

Factory set value: Hot start 1

¹ If changed to RUN from STOP by RUN/STOP transfer after start, set to the operation mode before power failure occurs.

² The result of control computation varies with the control response parameter.

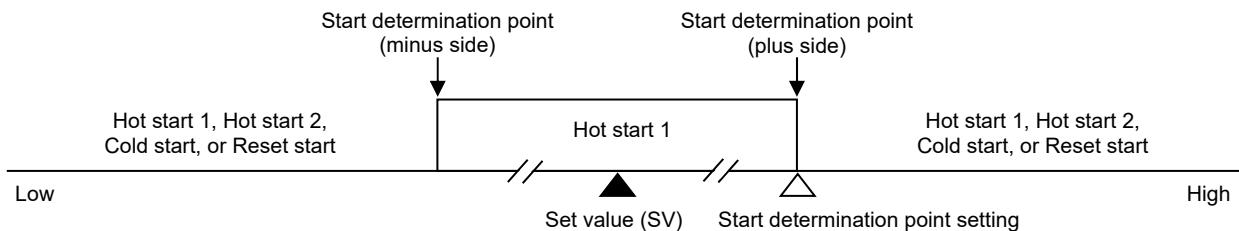


If the Startup tuning (ST) function is executed or an automatic temperature rise is made just when the power is turned on or selection is made from STOP to RUN as one of the startup conditions, control starts at Hot start 2 even if set to Hot start 1 (factory set value).
(It is unavailable at Cold start and STOP start.)

● Start determination point

Separately from Hot start and Cold start, users can set the start range (Start determination point) of Hot start 1 after power recovery. Determination point of start is a deviation setting from the Set value (SV).

- The start state is determined according to the Measured value (PV) level [deviation from set value] at power recovery.
- When a Measured value (PV) is between the determination points on the + (plus) and – (minus) sides, always starts from Hot start 1 when recovered.
- When a Measured value (PV) is out of the determination points or the Start determination point is set at “0,” operation starts from any start state selected by Hot/Cold start.



In the case of Master single control and Slave single control, according to the setting of each input.



Action at power failure for 2-loop control is as follows:

- Hot start 1, Hot start 2, and Cold start
Control is started in a mode according to the determination point of start.
- STOP start
Starts in Hot start 1 when Input 1 or Input 2 stays within the determination point of start.
Starts in STOP start when both of Input 1 and Input 2 are outside the determination point of start.

■ Parameter setting

● Hot/Cold start

[Engineering Mode: Function block No. 50 (Fn50)]

Parameter symbol	Data range	Factory set value
Pd	0: Hot start 1 1: Hot start 2 2: Cold start 3: STOP start	0

-  When this parameter is set and fixed to Hot start 2 at “Fix parameter setting: Hot/Cold start” in the Setting lock mode, the setting is fixed to 1.
-  When the value is set and fixed to Auto mode at “Fix parameter setting: Auto/Manual transfer” in the Setting lock mode, data 2 in the above table cannot be set.

● Input 1_Start determination point

[Engineering Mode: Function block No. 51 (Fn51)]

Parameter symbol	Data range	Factory set value
1. PdR	0 to Input 1_Input span (When Control with PV select: 0 to PV select input span) 0: Operation starts from any start state selected by Hot/Cold start [Varies with the setting of the Decimal point position.]	3 % of Input 1_Input span Control with PV select: 3 % of PV select input span

● Input 2_Start determination point

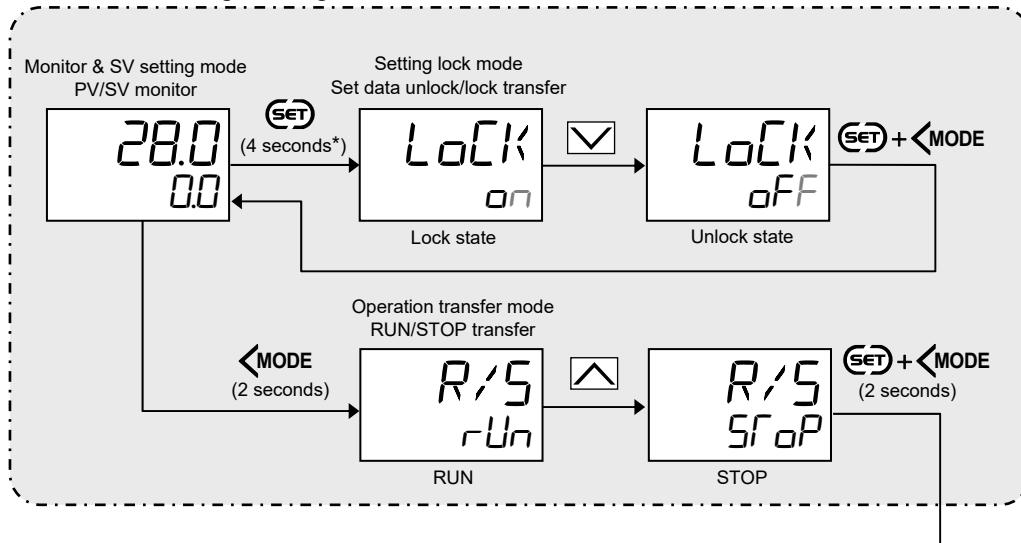
[Engineering Mode: Function block No. 52 (Fn52)]

Parameter symbol	Data range	Factory set value
2. PdR	0 to Input 2_Input span 0: Operation starts from any start state selected by Hot/Cold start [Varies with the setting of the Decimal point position.]	3 % of Input 2_Input span

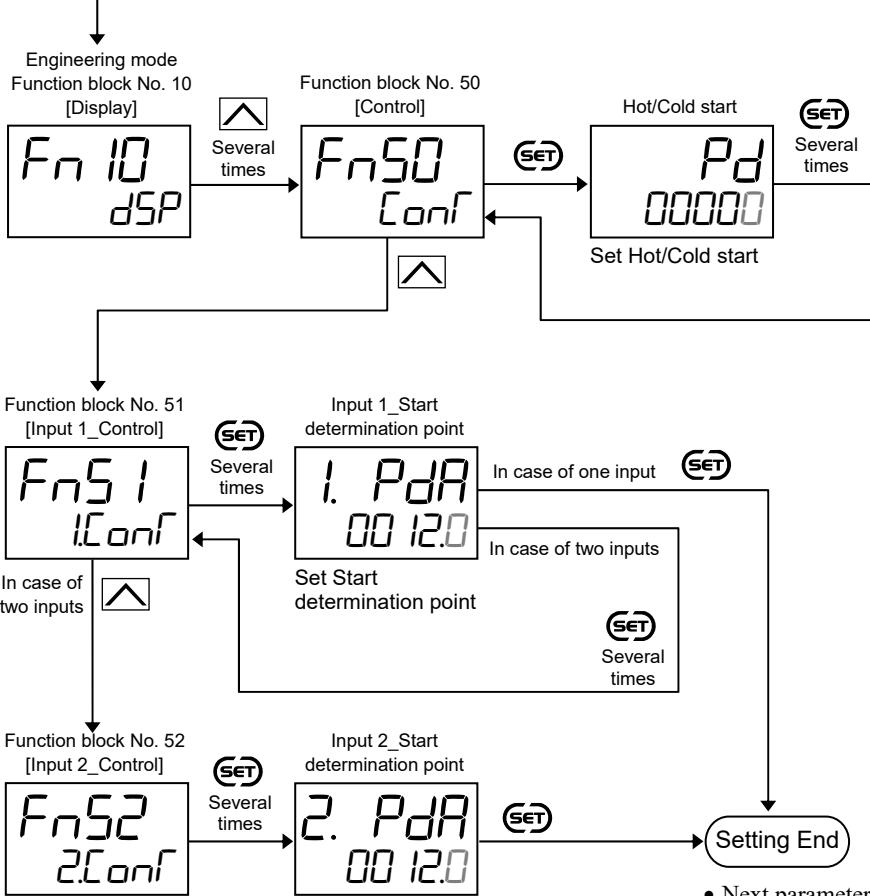
-  To display “Input 2_Start determination point,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

■ Setting procedure

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

MEMO

DISPLAY RELATED FUNCTIONS

9

This chapter describes display related functions, setting contents and setting procedure based on the key words related to Display.

9.1 Grouping Necessary Screens (Parameter Select Function)	9-2
9.2 Hiding Unnecessary Screens.....	9-9
9.3 Hiding the Display of the Set Value (SV)	9-15
9.4 Changing the Display Position of STOP during the Control Stop..	9-17
9.5 Changing the ALM Lamp Lighting Condition	9-19
9.6 Changing the Display Contents of the MV Display	9-21
9.7 Checking Input Peak Value/Bottom Value	9-23
9.8 Suppressing the Display Flickering.....	9-27
9.9 Checking the Instrument Information	9-29

9.1 Grouping Necessary Screens (Parameter Select Function)

This instrument has a function that allows a user to specify desired screens to be displayed. This function is called “Parameter select function.” Up to 16 screens can be grouped together.

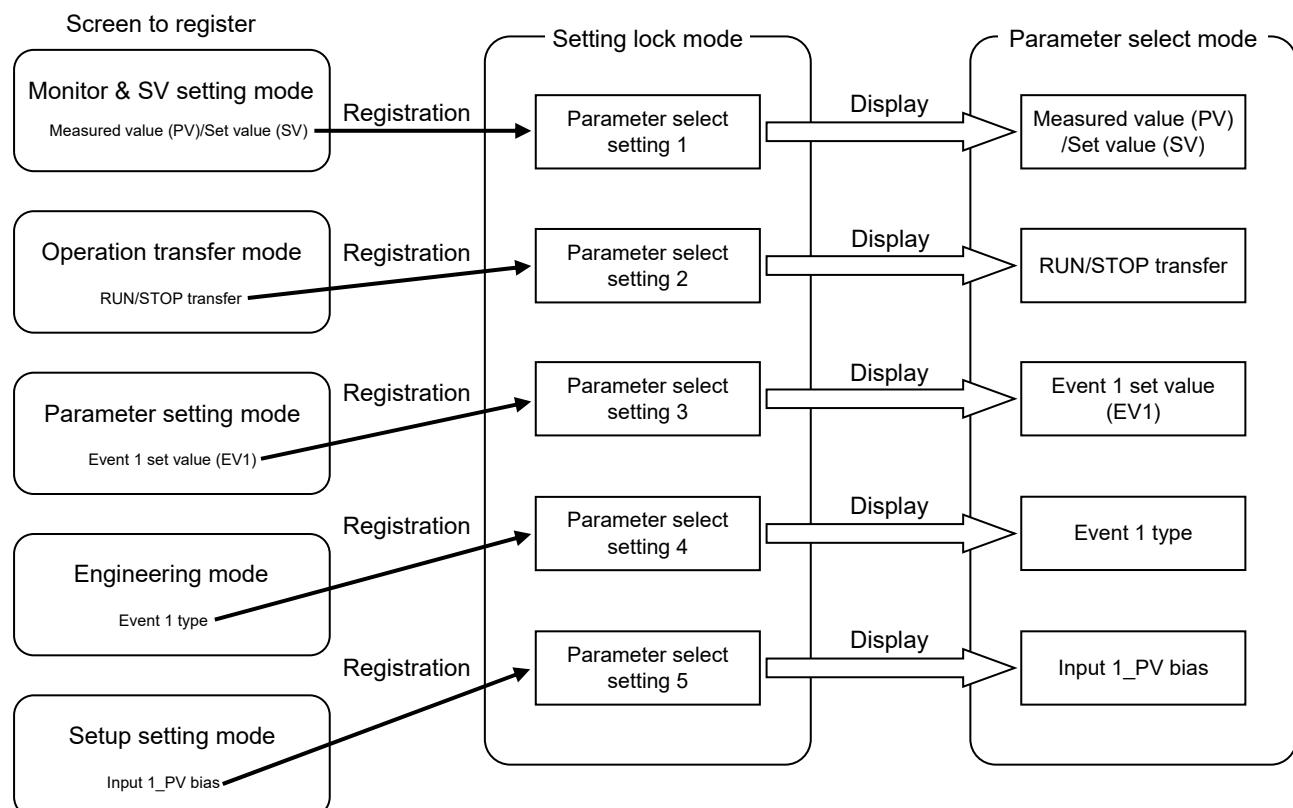
■ Description of function

The Parameter select function allows grouping necessary screens into a single mode for display. Screens registered in the Setting lock mode are displayed in the Parameter select mode.

The screens displayed in this mode can be operated in the same manner as they are in the original mode.

-  With the Parameter select function, the Setting lock mode screen and the Function block No. 91 in the Engineering mode cannot be registered.

[How does Parameter select function work?]



[Example] When “Event 1 set value (EV1)” screen in the Parameter setting mode is registered in the Parameter select setting screen, this screen can be viewed in both the Parameter select mode and the Parameter setting mode.

• Set data lock

This function can be independently activated in each operation mode.

For example, when the parameters in the Parameter setting mode are locked, the same parameters in the Parameter select mode are settable.

There are two ways to register screens.

- Screen number entry: Enter the screen No. on the Parameter select setting screen.
- Direct registration: Display the desired screen and register it through key operations.

● Screen number entry

Enter the predefined screen number on the Parameter select setting screen in the Setting lock mode. The registered screens in the Parameter select mode will be displayed.

 See the **3. PARAMETER LIST (P. 3-1)** for details.

[To register screens]

Check the screen number.

Find the desired screen No. by referring to the
3. PARAMETER LIST (P. 3-1).



Enter the screen number on the Parameter select setting screen.

Display the “Parameter select setting screen” in the Setting lock mode and enter the desired screen number to register.
(A maximum of 16 screens can be registered)



Check the registered screen.

Switch the mode to the Parameter select mode to see that the registered screen is properly displayed.

[Registering screens and display (1)]

There are 16 Parameter select setting screens and these are freely settable. Unregistered screens, if any, will be skipped and screens are displayed in series in the Parameter select mode.

Setting lock mode: Parameter select setting screen (for registration)

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
A	B	C					D	E						F	

 : Registered screens

 : Unregistered screens (Set value = 0)

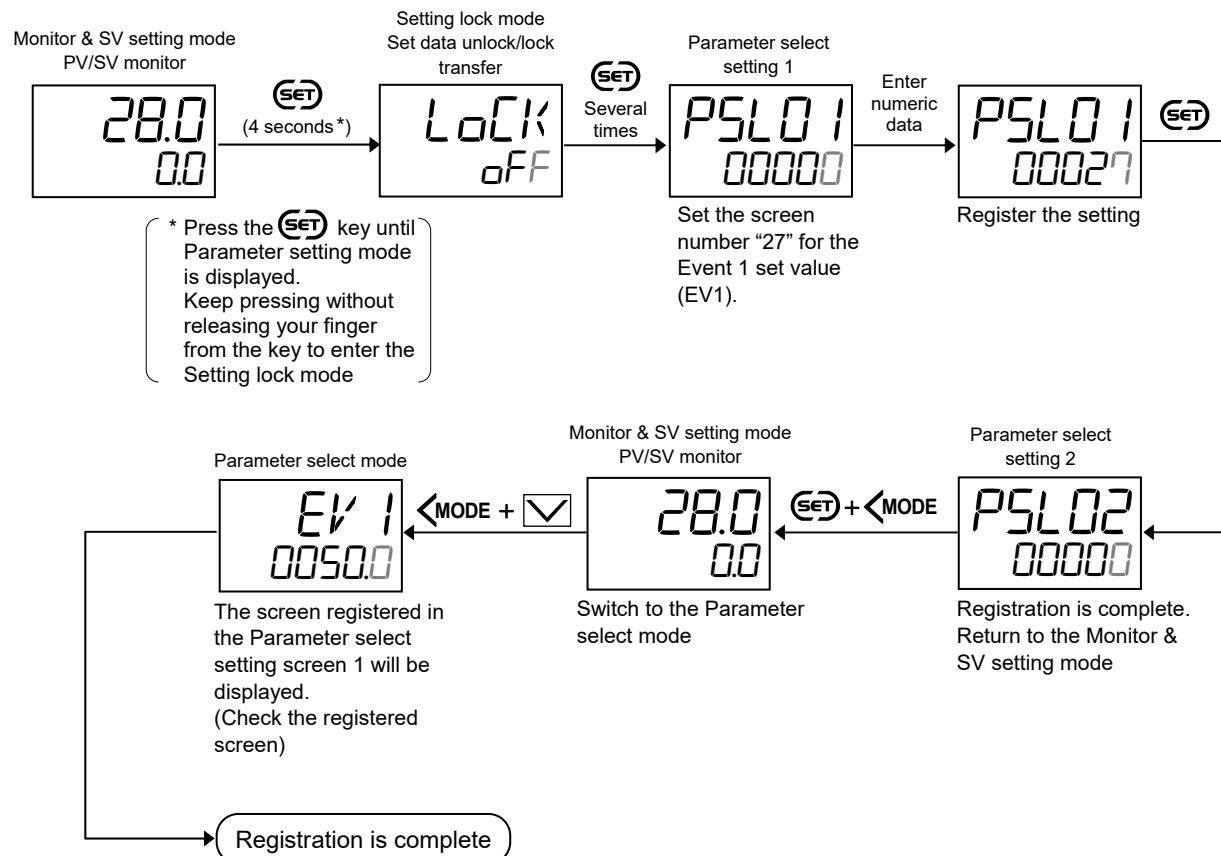
Parameter select mode: Displayed screens

A	B	C	D	E	F
---	---	---	---	---	---

Only registered screens are grouped for display.

[Entering screen No.]

In this example we will register “Event 1 set value (EV1)” in the Parameter setting mode.

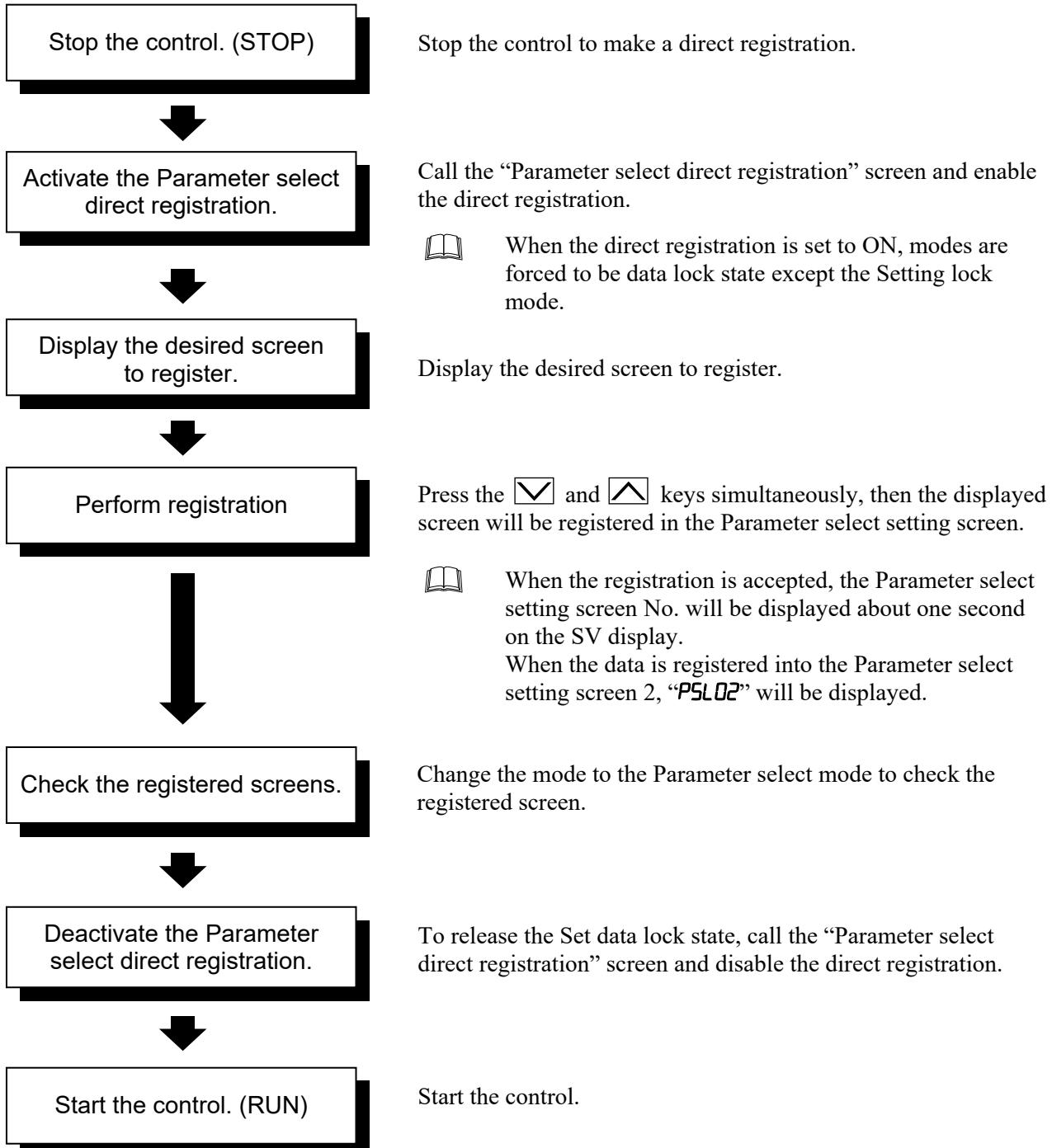


● Direct registration

Activate the direct registration on the Parameter select direct registration screen in the Setting lock mode. Display the screen to register and press the \checkmark and \triangle keys simultaneously. The screen will be registered on the Parameter select setting screen.

-  Control must be stopped before attempting the direct registration.
-  When the direct registration is activated on the Parameter select direct registration screen, all modes except for the Setting lock mode will be locked.

[To register screens]



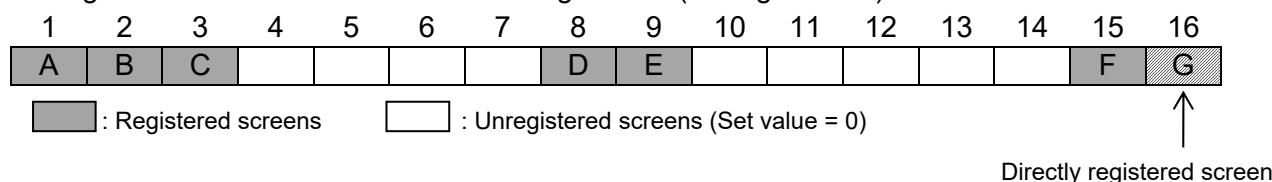
[Registering screens and display (2)]

This example shows the case of the direct registration under the state of the “[Registering screens and display (1)]” (P. 9-3).

• When directly registered

When attempting a direct registration, in case there is a registered screen in the Parameter select setting screen, the new screen will be added to after the registered screen. Even if there are unregistered screens, the new screen will be added to after the screen with the largest screen number of the Parameter select setting screen.

Setting lock mode: Parameter select setting screen (for registration)



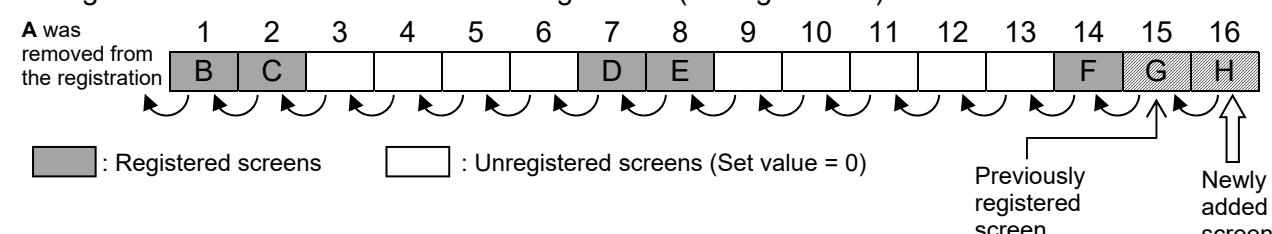
Parameter select mode: Displayed screens



• Registering further screens

When the Parameter select setting 16 screens are registered, the latest direct registration is added to the position of No.16, and the data before that will be moved ahead to toward the direction of the smaller numbers. Consequently, the screen registered at the Parameter select setting 1 will be moved out and removed from the registration.

Setting lock mode: Parameter select setting screen (for registration)

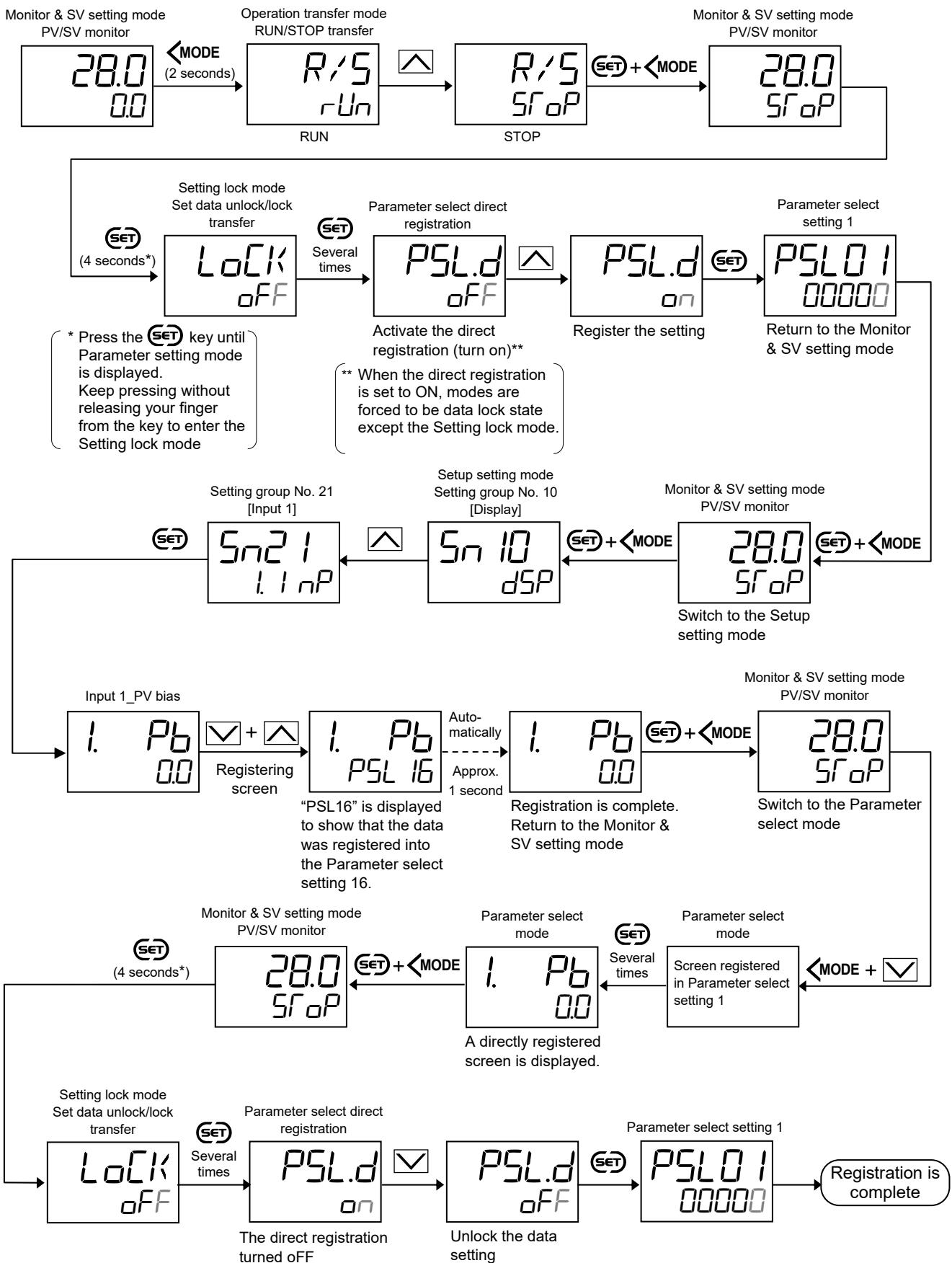


Parameter select mode: Displayed screens



[Example of Direct registration]

This is an example to make a direct registration of “Input 1_PV bias” in the Setting group 21 in the Setup setting mode under the state of the “[Registering screens and display (1)]” (P. 9-3).



■ Parameter setting

● Parameter select direct registration [Setting Lock Mode]

Parameter symbol	Data range	Factory set value
<i>PSL.d</i>	<i>oFF</i> : Direct registration: OFF <i>on</i> : Direct registration: ON	<i>oFF</i>

-  To allow “Parameter select direct registration,” Control must be stopped (STOP).
-  Set “*on*: Direct registration ON” to ON. All except Setting lock mode will be forced to data locked.
After the registration process is over, return the setting to *oFF*.
-  This setting returns to *oFF* when the power is turned off.

● Parameter select setting 1 to 16 [Setting Lock Mode]

Parameter symbol	Data range	Factory set value
<i>PSL01</i>	0: No registration 1 to 313 (Screen No.) For details, see 3. PARAMETER LIST (P. 3-1).	0
<i>PSL16</i>		

9.2 Hiding Unnecessary Screens

On this instrument, a specified range of screens can be hidden.

Below are screens that can be hidden.

- Monitor screen in the Monitor & SV setting mode
- Screens in the Operation transfer mode
- Screens restricted by the Blind function

9.2.1 Hide the monitor screen in the Monitor & SV setting mode

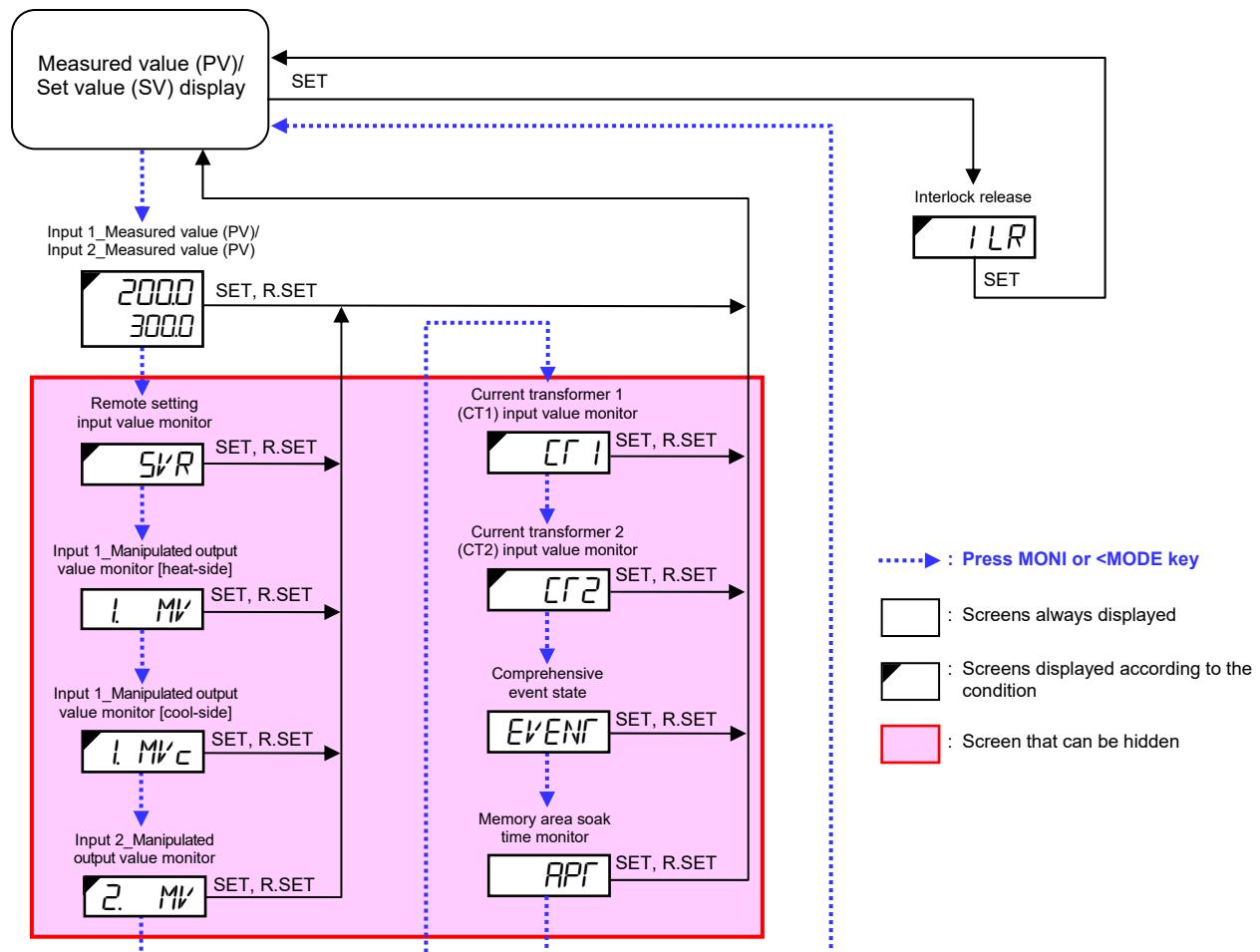
Show/Hide selection of the monitor screens in the Monitor & SV setting mode is available at “Select hide items in Monitor mode” in Function block No. 10 in the Engineering mode.

[Applicable screens]

- Remote setting input value monitor
- Manipulated output value (MV) monitor *:
Input 1_Manipulated output value monitor [heat-side], Input 1_Manipulated output value monitor [cool-side],
Input 2_Manipulated output value monitor
- Current transformer (CT) input value monitor *:
Current transformer 1 (CT1) input value monitor, Current transformer 2 (CT2) input value monitor
- Comprehensive event state
- Memory area soak time

* Setting is done at “Manipulated output value (MV) monitor” and “Current transformer (CT) input value monitor.”

[Operating navigation in the Monitor & SV setting mode]



■ Parameter setting

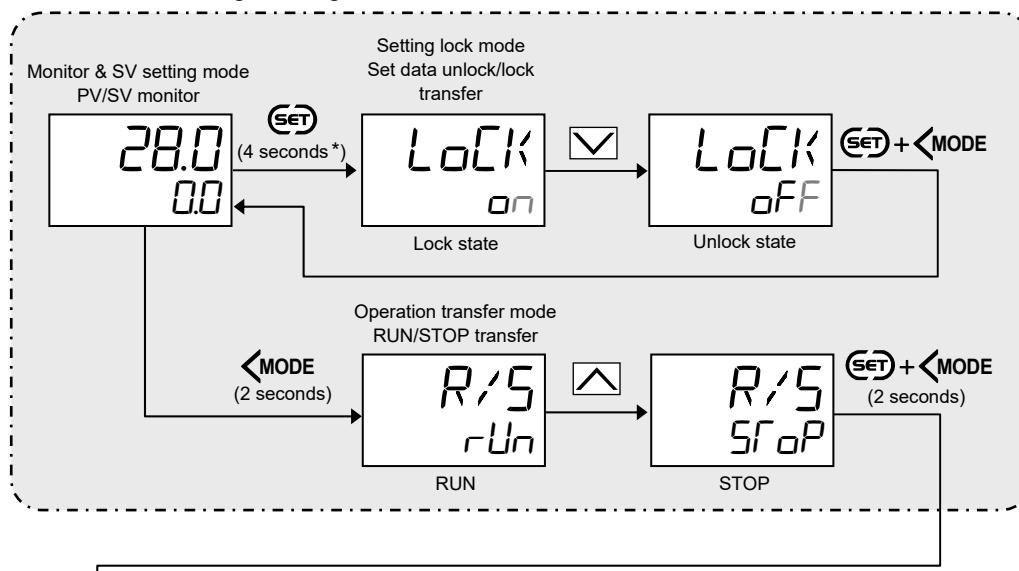
● Select hide items in Monitor mode

[Engineering Mode: Function block No. 10 (Fn 10)]

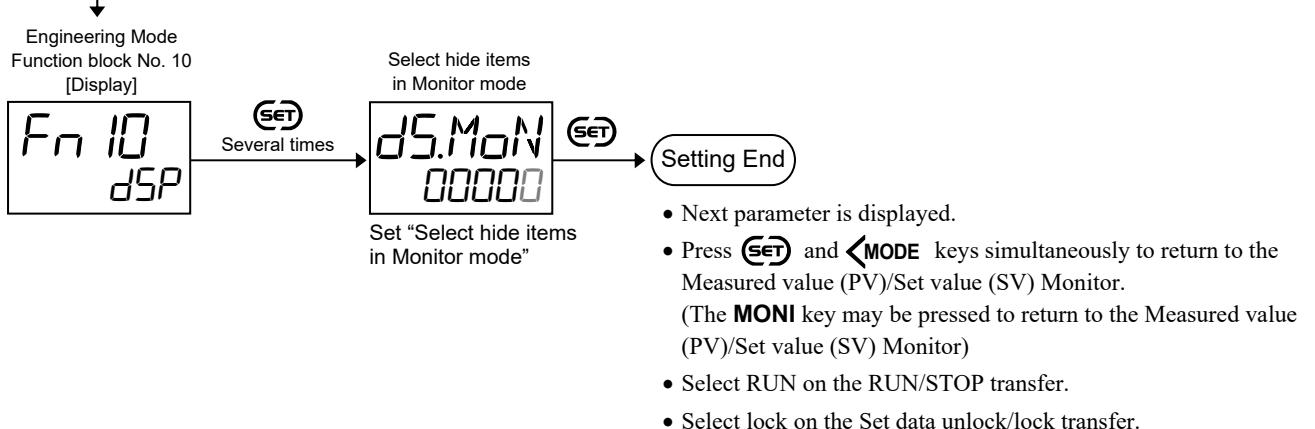
Parameter symbol	Data range	Factory set value
<i>d5.MoN</i>	0 to 31 0: Show all +1: Remote setting input value monitor +2: Manipulated output value (MV) monitor +4: Current transformer (CT) monitor +8: Comprehensive event state +16: Memory area soak time To select two or more functions, sum each value.	0

■ Setting procedure

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed. Keep pressing without releasing your finger from the key to enter the Setting lock mode.



9.2.2 Hiding screens in Operation transfer mode

Show/Hide selection of the screens in the Operation transfer mode is available at “Select hide items in Operation transfer mode” in Function block No. 10 in the Engineering mode.

[Applicable screens]

- RUN/STOP transfer
- Autotuning (AT) *: Input 1_Autotuning (AT), Input 2_Autotuning (AT)
- Startup tuning (ST) *: Input 1_Startup tuning (ST), Input 2_Startup tuning (ST)
- Auto/Manual transfer: Input 1_Auto/Manual transfer, Input 2_Auto/Manual transfer
- Remote/Local transfer
(PV select transfer, 2-loop control/Differential temperature control)
- Control area Local/External transfer

* Setting is done at “Autotuning (AT)” and “Startup tuning (ST).”

■ Parameter setting

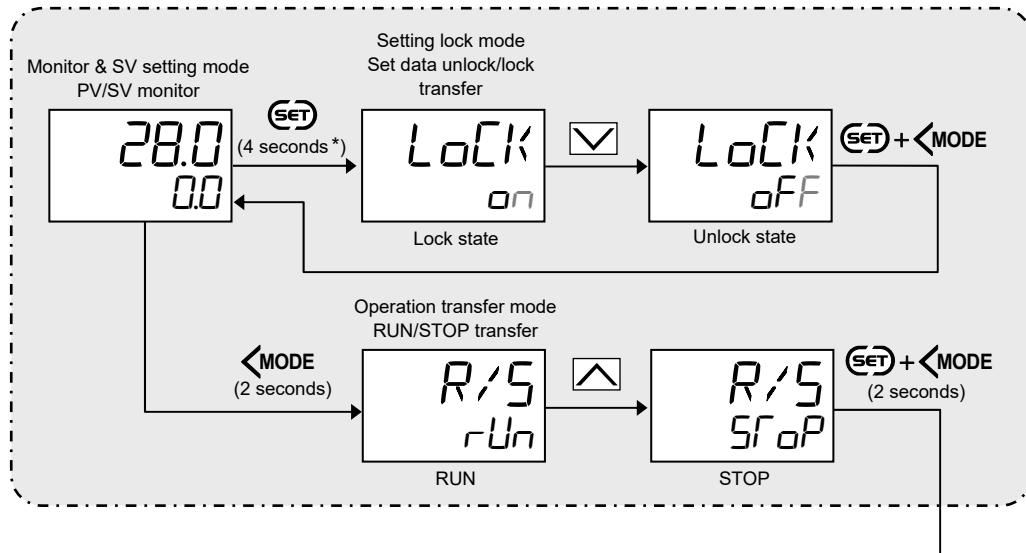
● Select hide items in Operation transfer mode

[Engineering Mode: Function block No. 10 (Fn 10)]

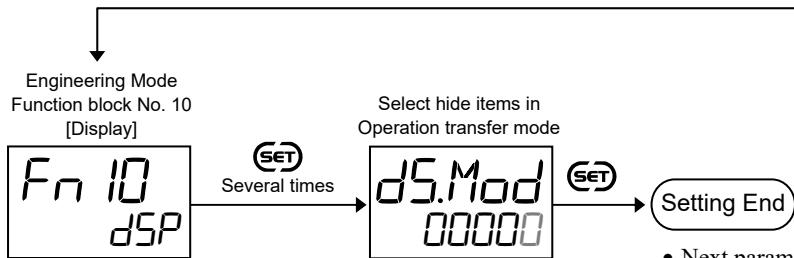
Parameter symbol	Data range	Factory set value
<i>d5Mod</i>	0 to 63 0: Show all +1: RUN/STOP transfer +2: Autotuning (AT) +4: Startup tuning (ST) +8: Auto/Manual transfer +16: Remote/Local transfer (PV select transfer, 2-loop control/Differential temperature control) +32: Control area Local/External transfer To select two or more functions, sum each value.	0

■ Setting procedure

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed. Keep pressing without releasing your finger from the key to enter the Setting lock mode.



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

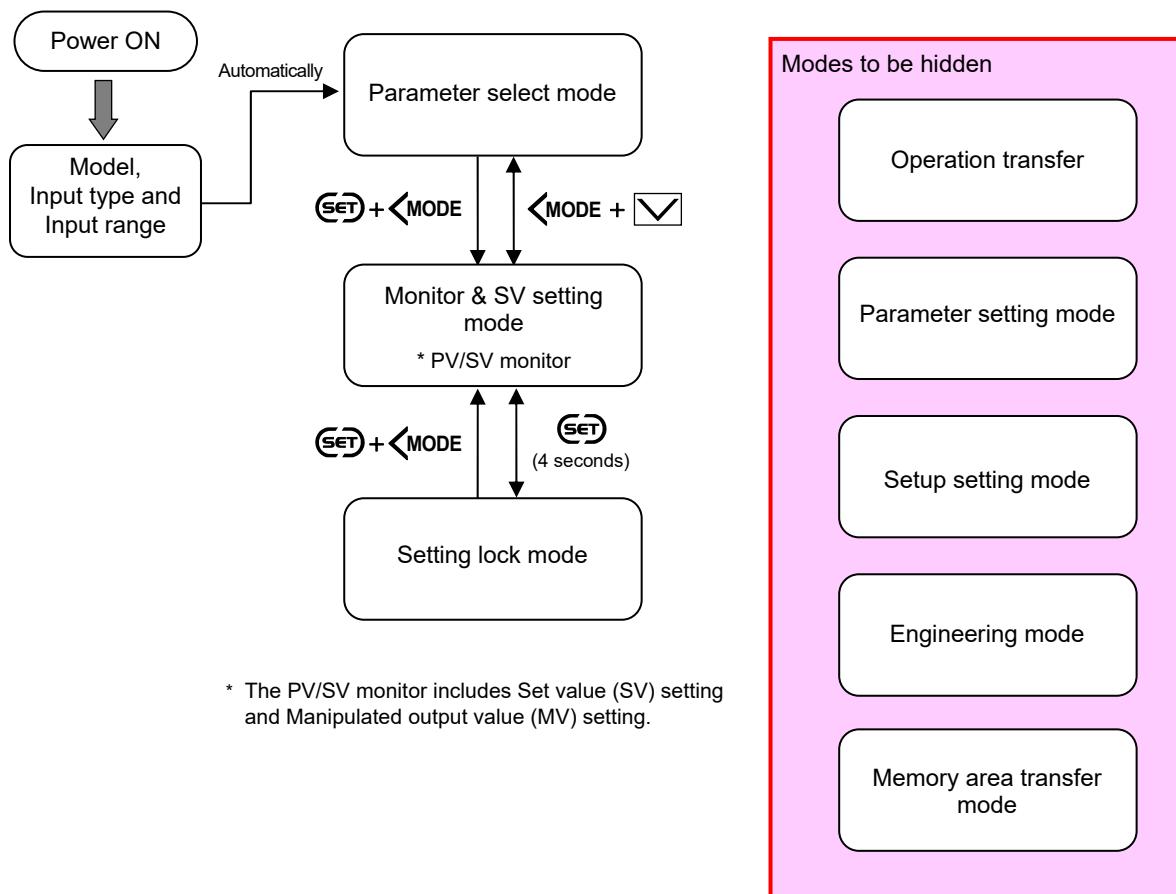
9.2.3 Hiding the screen using the Blind function

The Blind function is used to hide all screens except Parameter select mode, Setting lock mode, and Measured value (PV)/Set value (SV) monitor.

The Blind function can be set in the Setting lock mode.

-  When the Blind function is activated, the instrument displays the Parameter select mode after displaying the model and the input type/range at the time of power-up.
If all of the necessary screens are placed together in the Parameter select mode, there will be no need of switching screens to other modes.
-  Pressing the MONI key somewhere in the Parameter select mode will bring you back to the top screen of the Parameter select mode.

[Operation flow when the Blind function is activated]

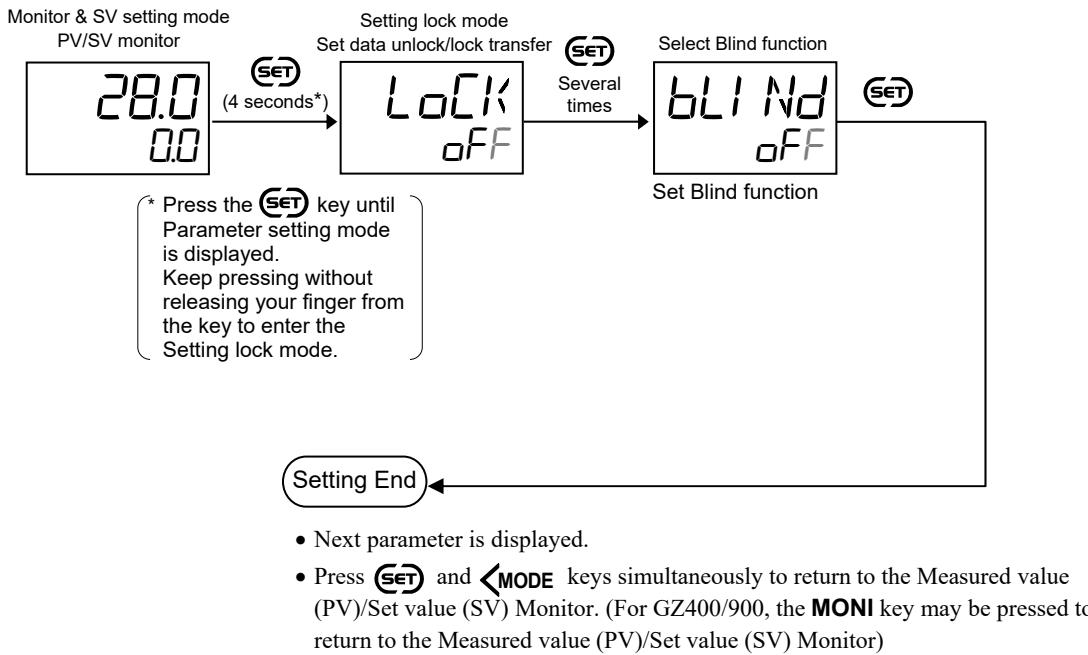


■ Parameter setting

● Select Blind function [Setting Lock Mode]

Parameter symbol	Data range	Factory set value
BLINd	<i>oFF</i> : Blind function: OFF <i>on</i> : Blind function: ON	<i>oFF</i>

■ Setting procedure



9.3 Hiding the Display of the Set Value (SV)

On the normal PV/SV monitor screen, the Set value (SV) is displayed on the set value (SV) display unit. This display can be turned OFF.

■ Description of function

Display of Set value (SV)

With Set value (SV) display



Without Set value (SV) display



In the above figure GZ400 is used for explanation, but the operation is the same for GZ900.

■ Parameter setting

● Show/Hide Input 1_SV

[Engineering Mode: Function block No. 10 ($F_{n \ 10}$)]

Parameter symbol	Data range	Factory set value
$I_{d5.5V}$	0: Hide Input 1_SV 1: Show Input 1_SV	1

● Show/Hide Input 2_SV

[Engineering Mode: Function block No. 10 ($F_{n \ 10}$)]

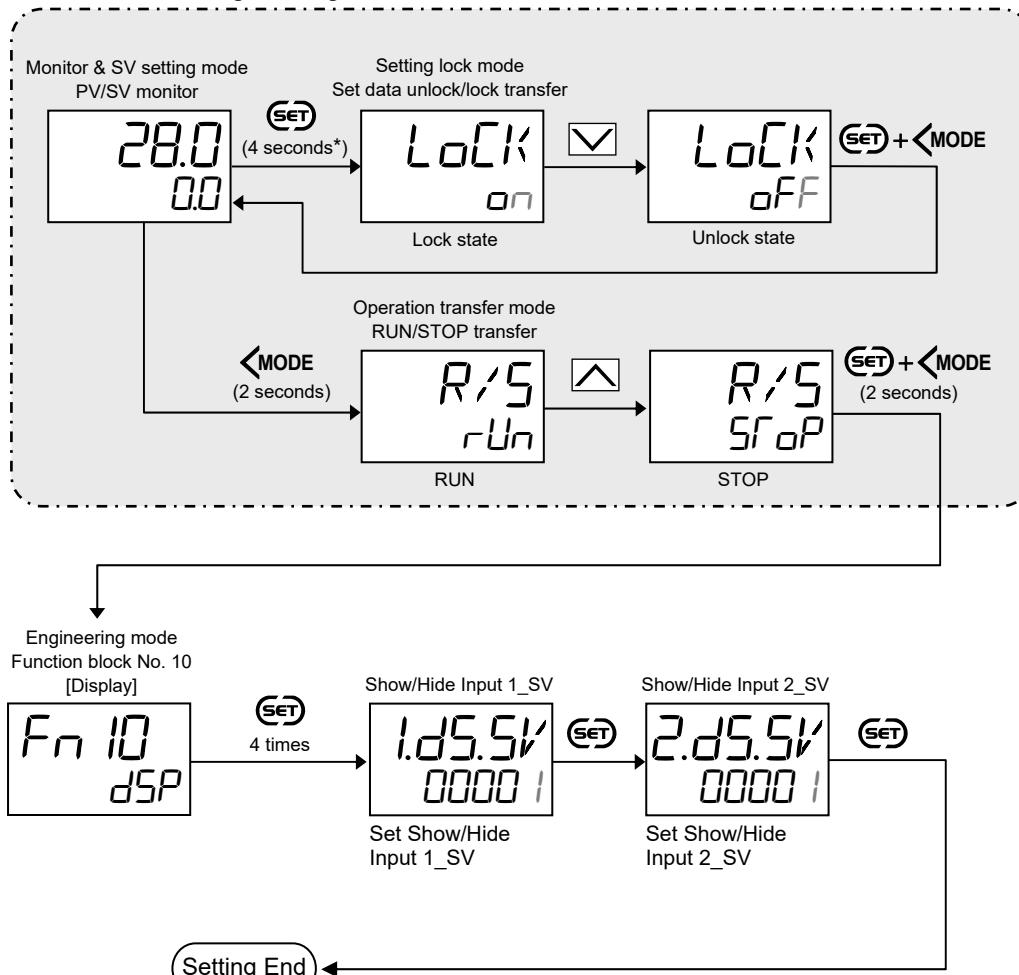
Parameter symbol	Data range	Factory set value
$2_{d5.5V}$	0: Hide Input 2_SV 1: Show Input 2_SV	1



To display "Show/Hide Input 2_SV," specify "Measured input 2" at the time of order, AND "Select function for input 2" (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

■ Setting procedure

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.

9.4 Changing the Display Position of STOP during the Control Stop

The display position of “*Sr oP*” showing the control stop state can be changed.

■ Description of function

The position of the STOP display can be specified; Measured value (PV) display, Set value (SV) display, or Manipulated output value (MV) display.



Displays the STOP
on the SV display
(Factory set value)



Displays the STOP
on the PV display



Displays the STOP on the MV display



In the above figure GZ400 is used for explanation, but the operation is the same for GZ900.

■ Parameter setting

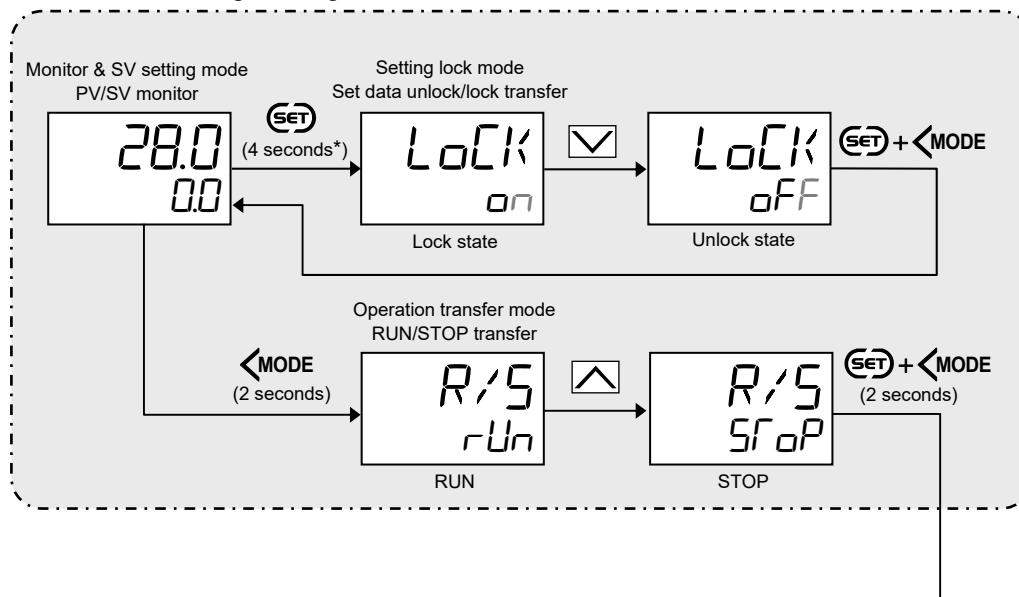
● STOP display selection

[Engineering Mode: Function block No. 10 (*Fn 10*)]

Parameter symbol	Data range	Factory set value
<i>SPCH</i>	0: Stop on PV display 1: Stop on SV display 2: Stop on MV display	1

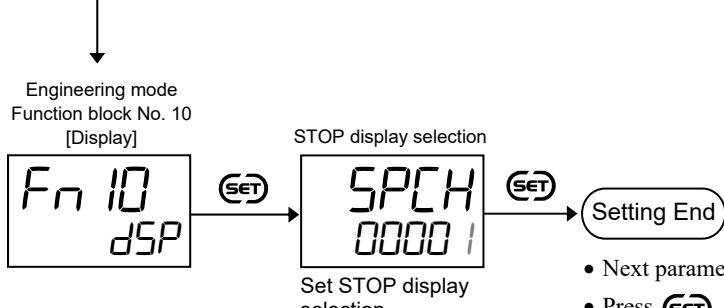
■ Setting procedure

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.

Keep pressing without releasing your finger from the key to enter the Setting lock mode.



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

9.5 Changing the ALM Lamp Lighting Condition

The light condition of the ALM lamp on the front panel can be changed.

■ Description of function

ALM lamps can be configured to light on the occurrence of the following events. These are freely combinable. If any one of selected events or alarms occurs, the ALM lamp will lights on.

- Event 1
- Event 2
- Event 3
- Event 4
- Heater break alarm 1 (HBA1)
- Heater break alarm 2 (HBA2)
- Control loop break alarm 1 (LBA1)
- Control loop break alarm 2 (LBA2)
- Input 1_Input error high
- Input 1_Input error low
- Input 2_Input error high
- Input 2_Input error low

Factory set ranges



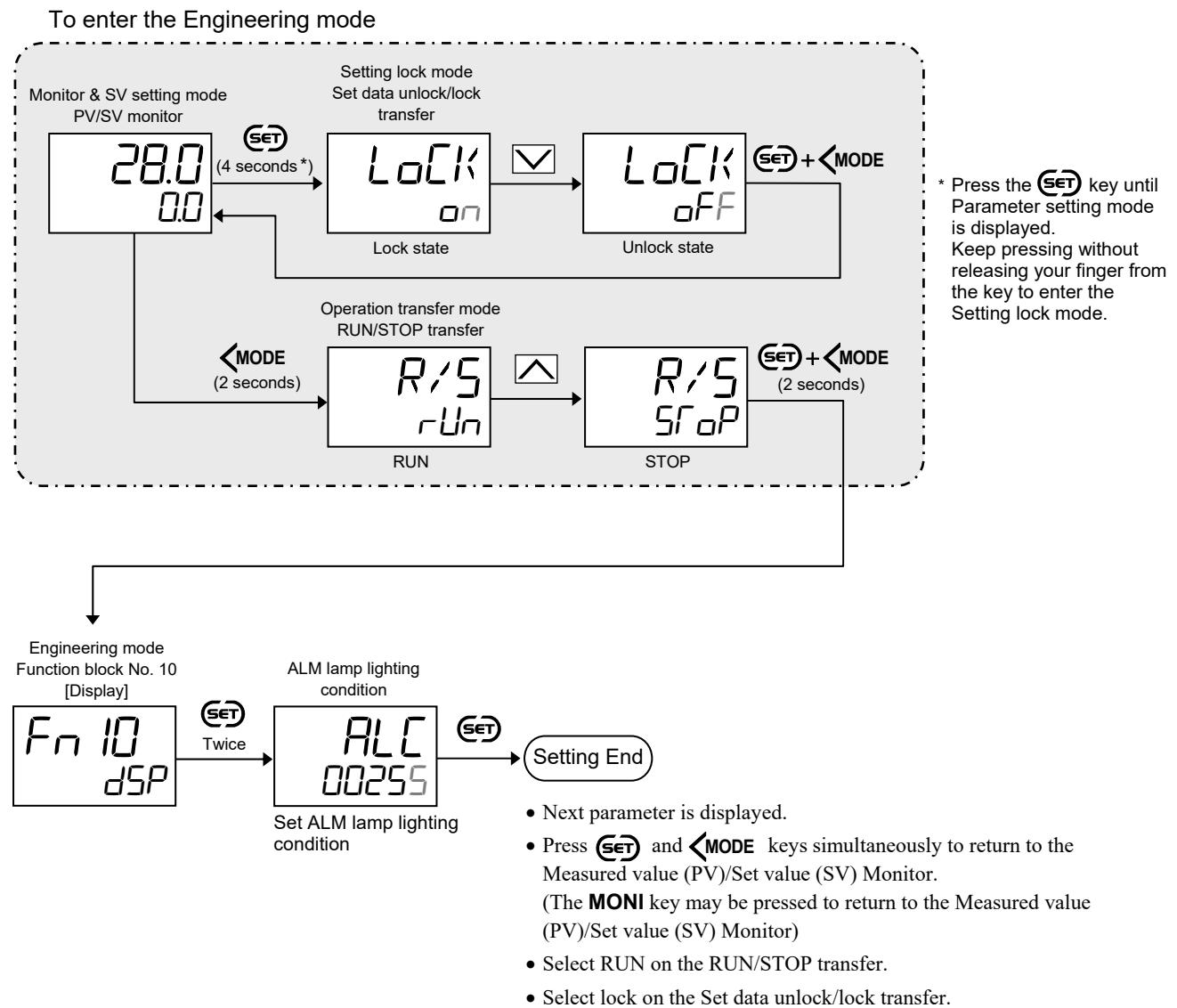
■ Parameter setting

● ALM lamp lighting condition

[Engineering Mode: Function block No. 10 ($F_{n \ 10}$)]

Parameter symbol	Data range	Factory set value
ALC	0 to 4095 0: OFF +1: Event 1 +2: Event 2 +4: Event 3 +8: Event 4 +16: Heater break alarm 1 (HBA1) +32: Heater break alarm 2 (HBA2) +64: Control loop break alarm 1 (LBA1) +128: Control loop break alarm 2 (LBA2) +256: Input 1_Input error high +512: Input 1_Input error low +1024: Input 2_Input error high +2048: Input 2_Input error low To select two or more functions, sum each value.	255

■ Setting procedure



9.6 Changing the Display Contents of the MV Display

While the instrument is monitoring the Measured value (PV) and the Set value (SV), the MV display can be configured to change the display contents.

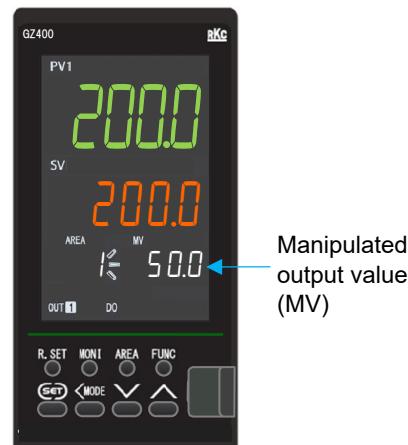
■ Description of function

The MV display on the instrument can display the following data.

- Manipulated output value (MV)
- Memory area soak time
- Current transformer (CT) input value *
- Hide

* If the instrument has no current transformer (CT), the value will not be displayed even if this setting is selected.

Display example



Display of Show Memory area soak time

When the Soak time unit is set to “2,” the time is displayed as follows depending on the time to be displayed.

Time	Time unit	Lamp	Example	
2 hour or more	Hours: Minutes	H:M	H:M	2:06 (2 hours 6 minutes)
1 hour 00 minutes 00 seconds to 1 hour 59 minutes 59 seconds	Hours: Minutes: seconds	H:M:S	H:M:S	1:08:45 (1 hour 8 minutes 45 seconds)
0 minutes 00 seconds to 59 minutes 59 seconds	Minutes: seconds	M:S	M:S	37:09 (37 minutes 9 seconds)

When the Soak time unit is set to “3: 0.00 to 59.99 seconds,” the time is displayed as follows.

Time	Time unit	Lamp	Example	
0.00 seconds to 59.99 seconds	Seconds: 00	:S	:S	58:76 (58.76 seconds)

■ Parameter setting

● Show/Hide Input 1_MV

[Engineering Mode: Function block No. 10 ($F_{n \ 10}$)]

Parameter symbol	Data range	Factory set value
$I_{d5.MV}$	0: Hide 1: Show Input 1_Manipulated output value (MV) 2: Show Memory area soak time * 3: Show Current transformer 1 (CT1) input value 4: Show Current transformer 2 (CT2) input value	1

* The time unit depends on the setting of Soak time unit (Function block No. 70 in the Engineering mode).

● Show/Hide Input 2_MV
[Engineering Mode: Function block No. 10 (Fn 10)]

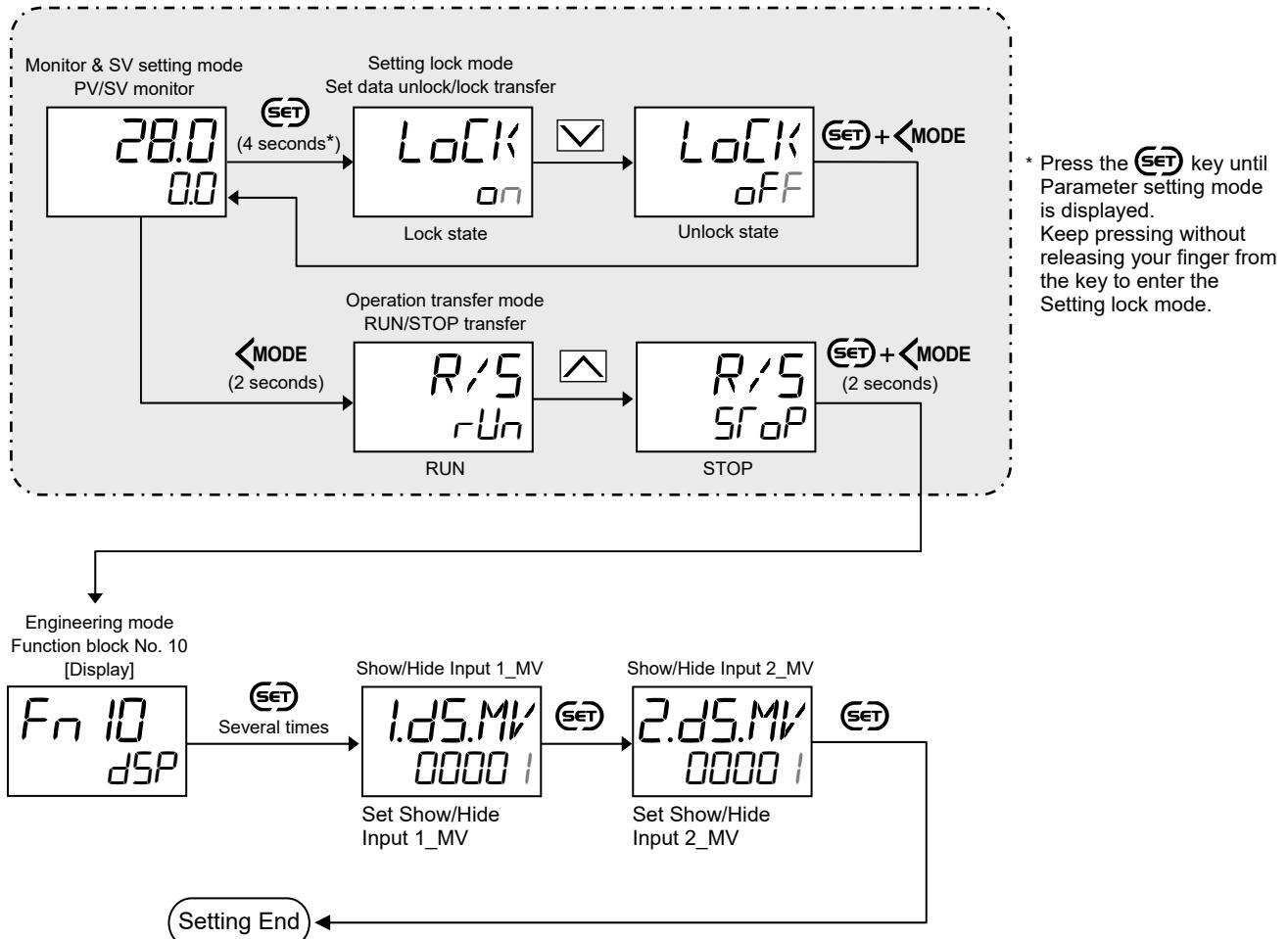
Parameter symbol	Data range	Factory set value
2.d5.MV	0: Hide 1: Show Input 2_Manipulated output value (MV) 2: Show Memory area soak time * 3: Show Current transformer 1 (CT1) input value 4: Show Current transformer 2 (CT2) input value	1

* The time unit depends on the setting of Soak time unit (Function block No. 70 in the Engineering mode).

-  To display “Show/Hide Input 2_MV,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

■ Setting procedure

To enter the Engineering mode



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

9.7 Checking Input Peak Value/Bottom Value

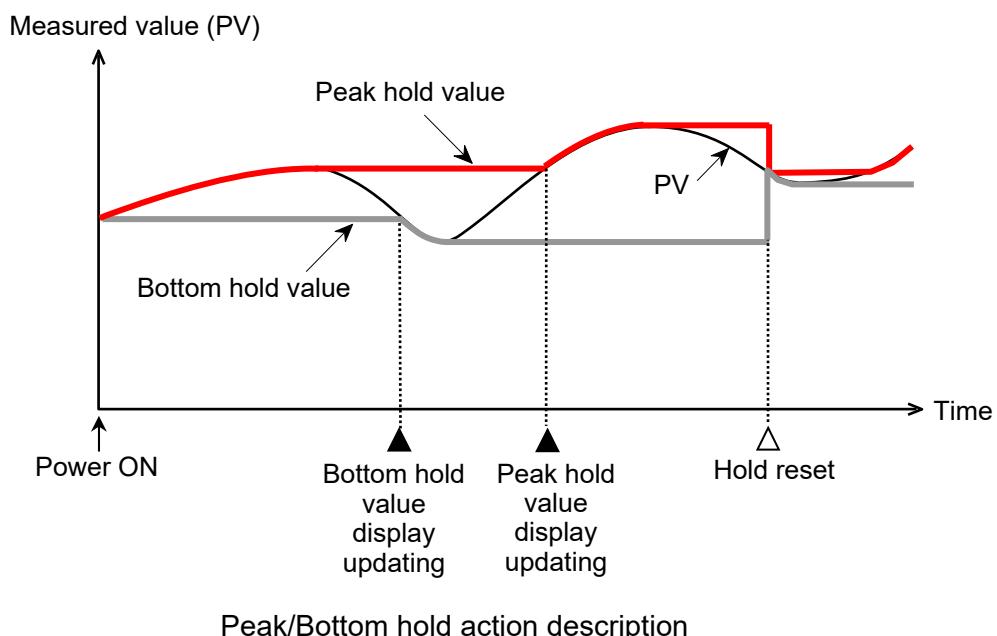
This instrument incorporates as standard the Peak/Bottom hold function which allows storing the peak (max) and the bottom (min) Measured values (PV).

■ Description of function

The peak hold/bottom hold function is used to store (hold) the peak (max) and the bottom (min) Measured values (PV). Each of these values is updated when the measured temperature becomes more (or less) than the value now being held.



The stored peak (max) and bottom (min) values can be reset on the Hold reset screen.



■ Parameter setting

● Input 1_Peak hold monitor

[Setup Setting Mode: Setting group No. 91 (S91)]

Parameter symbol	Data range	Factory set value
I.PHLd	Input 1_Input range low - (Input 1_5 % of input span) to Input 1_Input range high + (Input 1_5 % of input span) Varies with the setting of the Decimal point position.	—

● Input 2_Peak hold monitor

[Setup Setting Mode: Setting group No. 91 (5n9 l)]

Parameter symbol	Data range	Factory set value
<i>2.PHLd</i>	Input 2_Input range low – (Input 2_5 % of input span) to Input 2_Input range high + (Input 2_5 % of input span) Varies with the setting of the Decimal point position.	—



To display “Input 2_Peak hold monitor,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to Control with PV select, 2-loop control/Differential temperature control, or Input circuit error alarm.

● Input 1_Bottom hold monitor

[Setup Setting Mode: Setting group No. 91 (5n9 l)]

Parameter symbol	Data range	Factory set value
<i>1.bHLd</i>	Input 1_Input range low – (Input 1_5 % of input span) to Input 1_Input range high + (Input 1_5 % of input span) Varies with the setting of the Decimal point position.	—

● Input 2_Bottom hold monitor

[Setup Setting Mode: Setting group No. 91 (5n9 l)]

Parameter symbol	Data range	Factory set value
<i>2.bHLd</i>	Input 2_Input range low – (Input 2_5 % of input span) to Input 2_Input range high + (Input 2_5 % of input span) Varies with the setting of the Decimal point position.	—



To display “Input 2_Bottomk hold monitor,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to Control with PV select, 2-loop control/Differential temperature control, or Input circuit error alarm.

● Input 1_Hold reset

[Setup Setting Mode: Setting group No. 91 (5n9 l)]

Parameter symbol	Data range	Factory set value
<i>I.HLdR</i>	<i>HoLD</i> : Hold <i>rESEt</i> : Reset Returns to Hold state automatically after reset.	<i>HoLD</i>



Note that the both of the peak and the bottom hold values are reset at a time by the hold reset operation.

● Input 2_Hold reset

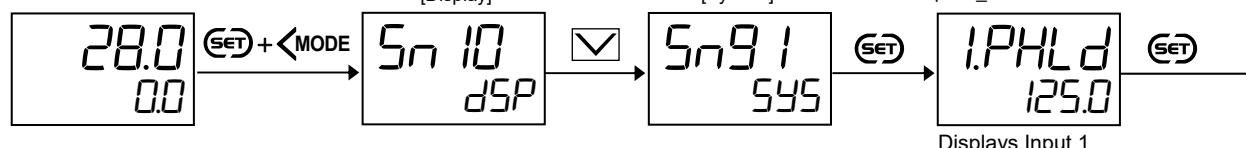
[Setup Setting Mode: Setting group No. 91 (5n9 l)]

Parameter symbol	Data range	Factory set value
<i>2.HLdR</i>	<i>HoLD</i> : Hold <i>rESET</i> : Reset Returns to Hold state automatically after reset.	<i>HoLD</i>

- book To display “Input 2_Hold reset,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to Control with PV select, 2-loop control/Differential temperature control, or Input circuit error alarm.
- book Note that the both of the peak and the bottom hold values are reset at a time by the hold reset operation.

■ Setting procedure

Monitor & SV setting mode
PV/SV monitor



Displays Input 1_Peak hold monitor

Setup setting mode
Setting group No. 10
[Display]

Setting group No. 91
[System]

Input 1_Peak hold monitor

In the case of two inputs
SET

In the case of one input
SET

Input 1_Hold reset

I.HLdR
HoLD

Set Input 1_Hold
reset

Input 1_Bottom hold monitor

I.bHLd
18.0

Displays Input 1_Bottom hold
monitor

Setting End

- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

Input 2_Peak hold monitor

2.PHLd
254.0

Displays Input 2_Peak hold monitor

Input 2_Bottom hold monitor

2.bHLd
38.0

Displays Input 2_Bottom hold monitor

Input 2_Hold reset

2.HLdR
HoLD

Set Input 2_Hold
reset

Setting End

- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

9.8 Suppressing the Display Flickering

The display flickering due to input changes in PV/SV monitor screen can be reduced by extending the display update cycle.

● Applicable screens

The PV/SV monitor screen which comes at the beginning in the Monitor & SV setting mode. When the instrument has two inputs, PV/SV on the Input 2 is also covered.

-  The Manipulated output value (MV) displayed on the Manipulated output value (MV) display is also covered.

[1-loop control]

- Auto mode

Input 1_Measured value (PV)/
Input 1_Set value (SV)



- Manual mode

Input 1_Measured value (PV)/
Input 1_Manual manipulated output value (MV)



[2-loop control]

- Auto mode

Input 1_Measured value (PV)/
Input 1_Set value (SV)



Input 2_Measured value (PV)/
Input 2_Set value (SV)



- Manual mode

Input 1_Measured value (PV)/
Input 1_Manual manipulated output value (MV)



Input 2_Measured value (PV)/
Input 2_Manual manipulated output value (MV)



[Control with PV select]

- Auto mode

PV select Measured value (PV)/
Input 1_Set value (SV)



- Manual mode

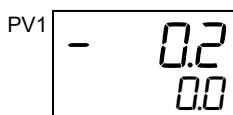
PV select Measured value (PV)/
Input 1_Manual manipulated output value (MV)



[Differential temperature control]

- Auto mode

Measured value (PV) of
differential temperature input/
Set value (SV) of differential
temperature input



Input 1_Measured value (PV)/
Input 1_Set value (SV)



Input 2_Measured value (PV)/
Input 2_Set value (SV)



- Manual mode

Measured value (PV) of differential
temperature input/
Input 1_Manual manipulated output
value (MV)



Input 1_Measured value (PV)/
Input 1_Manual manipulated output value (MV)



Input 2_Measured value (PV)/
Input 2_Manual manipulated output value (MV)



■ Parameter setting

● Display update cycle

[Setup Setting Mode: Setting group No. 10 (Sn 10)]

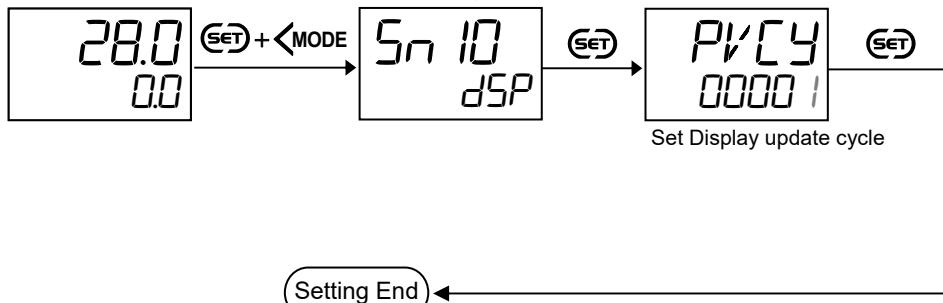
Parameter symbol	Data range	Factory set value
PV CY	1: 50 ms 2: 100 ms 3: 150 ms 4: 200 ms 5: 250 ms 6: 300 ms 7: 350 ms 8: 400 ms 9: 450 ms 10: 500 ms	1

■ Setting procedure

Monitor & SV setting mode
PV/SV monitor

Setup setting mode
Setting group No. 10
[Display]

Display update cycle



- Next parameter is displayed.
- Press **SET** and **MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

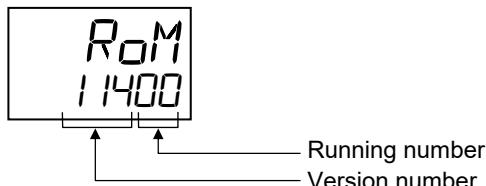
9.9 Checking the Instrument Information

When error occurs and when you contact us, you are requested to provide us with the information on the instrument model code and specification. You can check the ROM version, model code and serial number of the instrument on the instrument display. The Integrated operating time and the maximum ambient temperature (Peak hold monitor of the ambient temperature).

■ How to check

● ROM Version

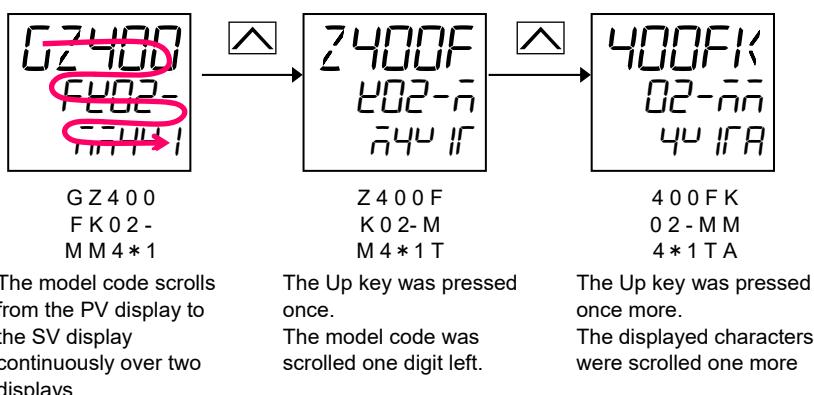
[Example]



● Model code monitor

Displays the model code of the instrument. As the Model code is too long to be displayed on a single screen, it can be scrolled left and right with Δ and ∇ keys.

Example: Model code is GZ400FK02-MM4*1TA2NN/1



● Instrument number monitor

Displays the serial number of the instrument.

- To read the displayed characters, see “Character Symbols” (P. i-2).
- Alternatively, you can check the model code (MODEL), serial number (S/N) and suffix code (CODE) on the label on the side of the instrument if you are unable to check the information on the display.

● Integrated operating time

As soon as the instrument is powered, “1” is added. Thereafter, “1” is accumulated for each hour.

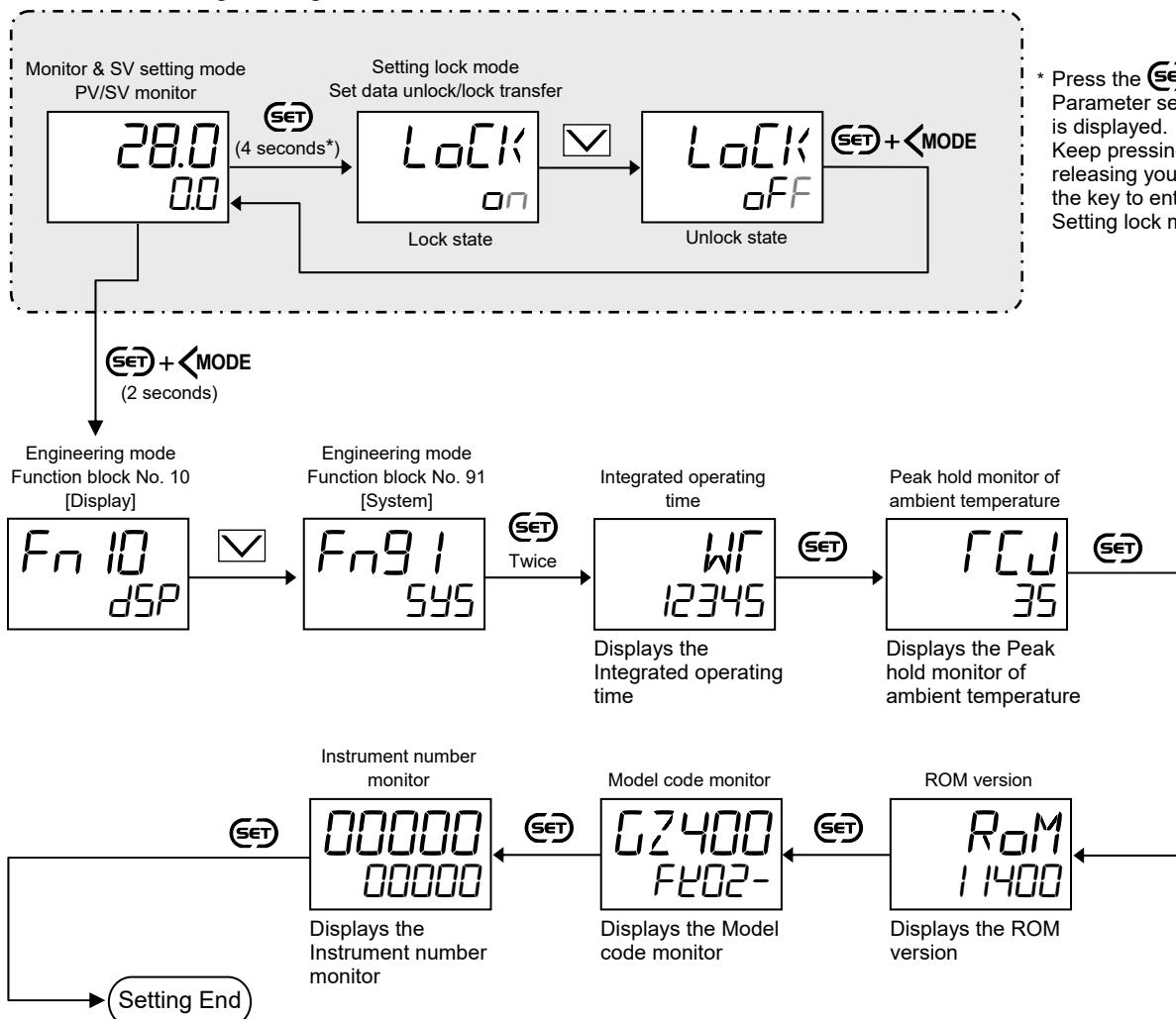
● Peak hold monitor of the ambient temperature

Temperature around the rear terminal is measured and the maximum value is stored.

- The Integrated operating time and the maximum ambient temperature (Peak hold monitor of the ambient temperature) cannot be reset.

■ Operating procedure

To enter the Engineering mode



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.

SETTING AND KEY OPERATION

10

This chapter describes setting and key operation related functions, setting contents and setting procedure based on the keywords related to setting and key operation.

10.1 Limiting the Setting Range of Set Value (SV)	10-2
10.2 Eliminating a Sudden Set Value Change (Setting Change Rate Limiter)	10-6
10.3 Storing the Control Related Set Values (Memory Area Function).....	10-10
10.4 Copying the Data in Memory Area to Set Other Areas	10-16
10.5 Running a Simple Ramp/Soak Operation.....	10-18
10.6 Using a Simple Sequence Operation.....	10-26
10.7 Registering a Set Value (SV) Without Pressing the SET Key....	10-33
10.8 Accessing Some Functions Directly (FUNC Key).....	10-35
10.9 Restricting Key Operation (Set Data Lock).....	10-38
10.10 Fixing the Set Value to a Specified Value (Fix Parameter Setting)	10-41
10.11 Initializing the Set Data.....	10-45

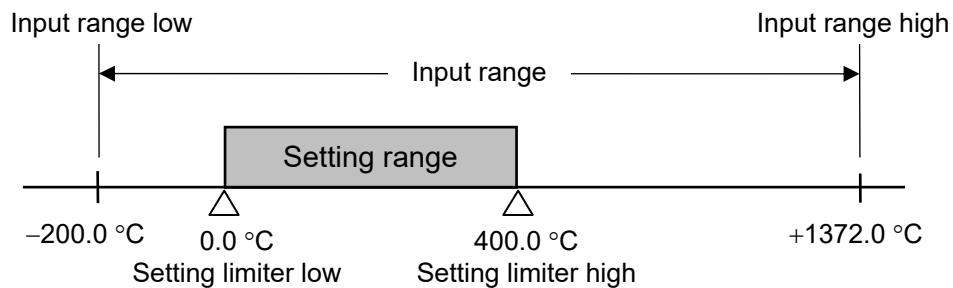
10.1 Limiting the Setting Range of Set Value (SV)

To limit the setting range of the Set value (SV), Setting limiter is used.

■ Description of function

Setting limiter is a function to limit the setting range of the Set value (SV) within the input range.

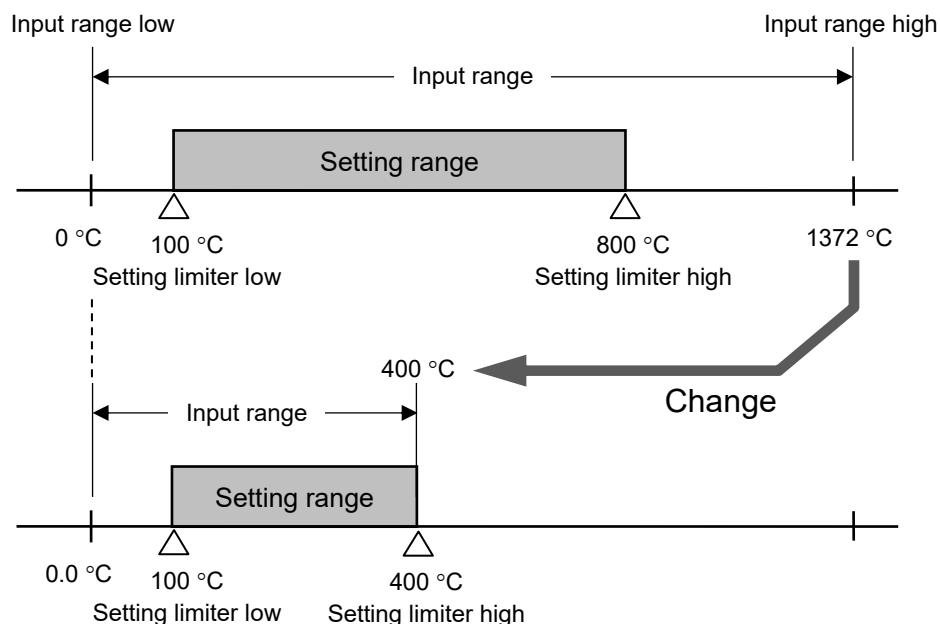
Example: The input range is from -200.0 to $+1372.0$ °C, the Setting limiter high is 400.0 °C, and the Setting limiter low is 0.0 °C.



When the input range is changed, the setting limiter may be also changed according to the changed setting.

[Example 1]

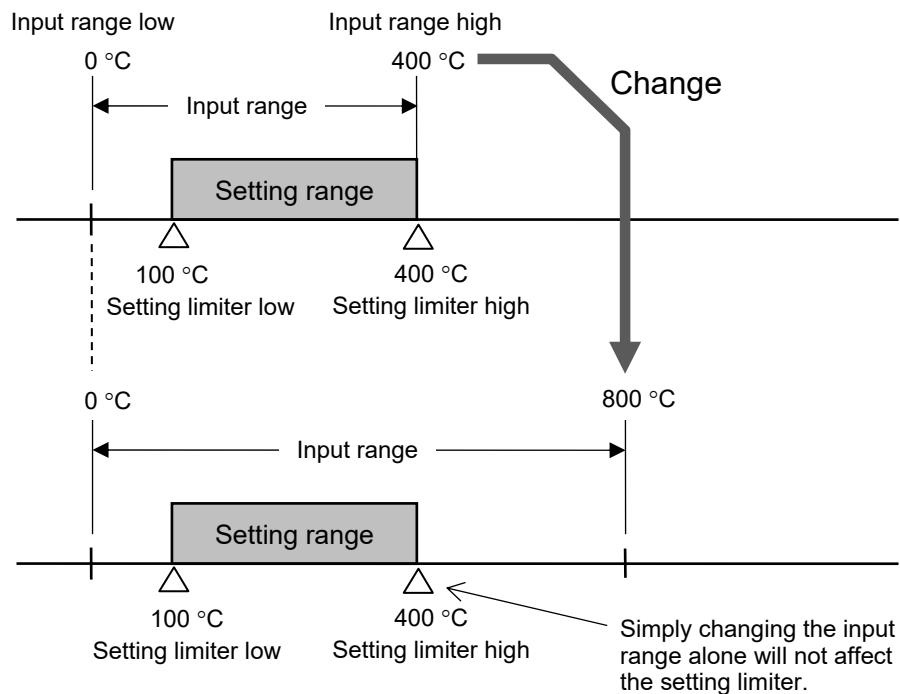
Input 1_Input range is 0 to 1372 °C, Input 1_Setting limiter high is 800 °C. Changing the Input 1_Input range high to 400 °C will change the Setting limiter high to 400 °C accordingly.



[Example 2]

When the Input 1_Input range is 0 to 400 °C and the Input 1_Setting limiter high is 400 °C, changing the Input 1_Input range high to 800 °C will not affect the setting limiter value. In this case the Input 1_Setting limiter high remains 400 °C.

When a wider setting range of the Set value (SV) is required according to the extended input range, change the setting limiter value accordingly.



■ Parameter setting

● Input 1_Setting limiter high

[Engineering Mode: Function block No. 71 (Fn71)]

Parameter symbol	Data range	Factory set value
I. SLH	Input 1_Setting limiter low to Input 1_Input range high (When Control with PV select: Input 1_Setting limiter low to PV select input range high)	Input 1_Input range high (Control with PV select: PV select input range high)

Varies with the setting of the Decimal point position.

- See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are automatically converted when the Input 1_Setting limiter high is changed.

● Input 2_Setting limiter high

[Engineering Mode: Function block No. 72 (Fn72)]

Parameter symbol	Data range	Factory set value
2. SLL	Input 2_Setting limiter low to Input 2_Input range high Varies with the setting of the Decimal point position.	Input 2_Input range high

 To display “Input 2_Setting limiter high,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

 See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are automatically converted when the Input 2_Setting limiter high is changed.

● Input 1_Setting limiter low

[Engineering Mode: Function block No. 71 (Fn71)]

Parameter symbol	Data range	Factory set value
1. SLL	Input 1_Input range low to Input 1_Setting limiter high (When Control with PV select: PV select input range low to Input 1_Setting limiter high) Varies with the setting of the Decimal point position.	Input 1_Input range low (Control with PV select: PV select input range low)

 See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are automatically converted when the Input 1_Setting limiter low is changed.

● Input 2_Setting limiter low

[Engineering Mode: Function block No. 72 (Fn72)]

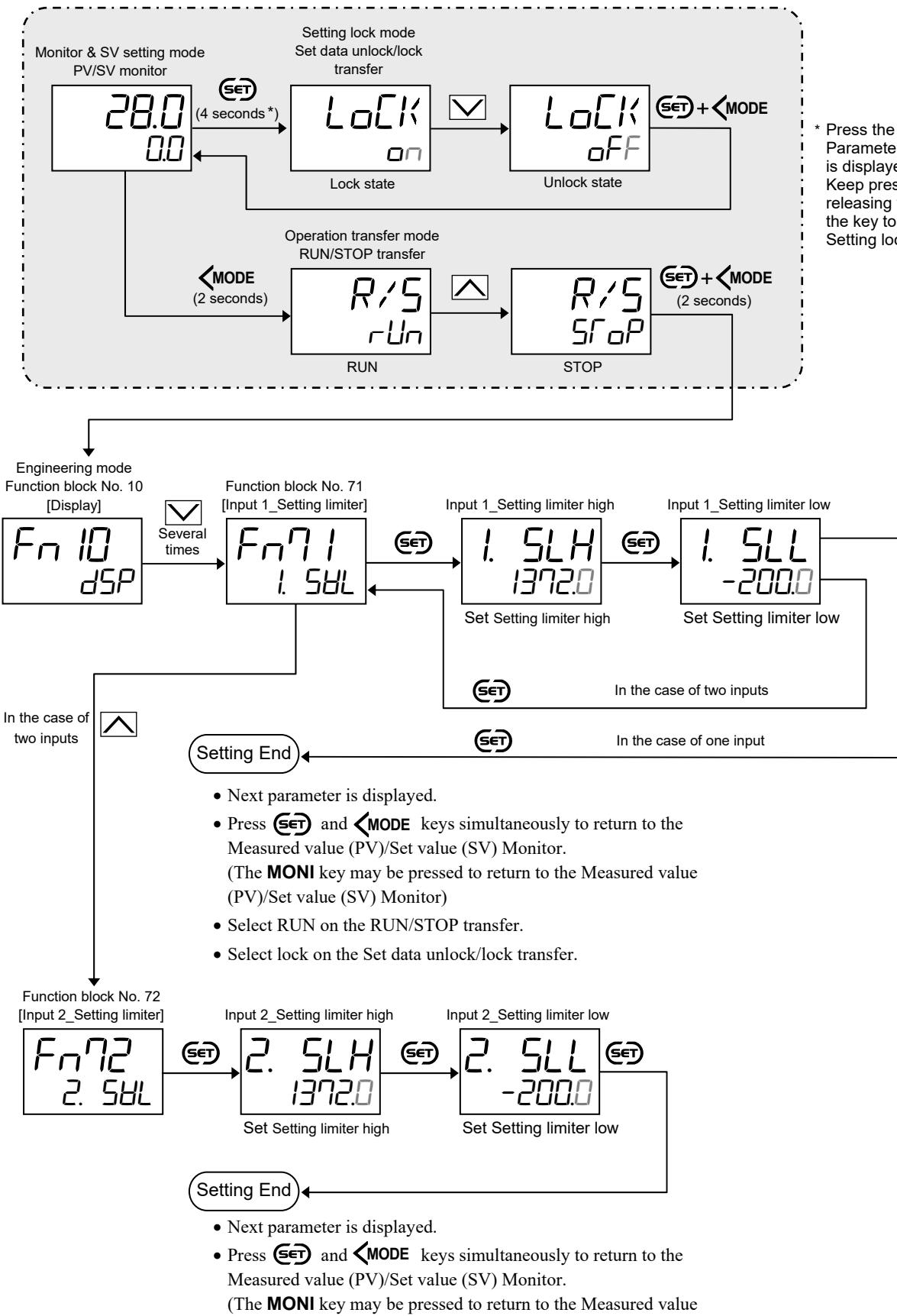
Parameter symbol	Data range	Factory set value
2. SLL	Input 2_Input range low to Input 2_Setting limiter high Varies with the setting of the Decimal point position.	Input 2_Input range low

 To display “Input 2_Setting limiter low,” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

 See “4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)” for the parameters that are automatically converted when the Input 2_Setting limiter low is changed.

■ Setting procedure

To enter the Engineering mode



10.2 Eliminating a Sudden Set Value Change (Setting Change Rate Limiter)

This function allows the Set value (SV) to change gradually, not rapidly or not at a time, when the Set value (SV) is changed.

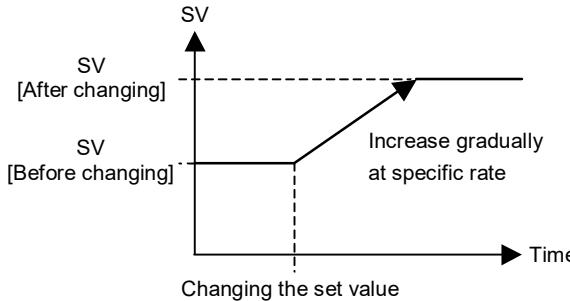
■ Description of function

This function is to allow the Set value (SV) to be automatically changed at specific rates when a new Set value (SV).

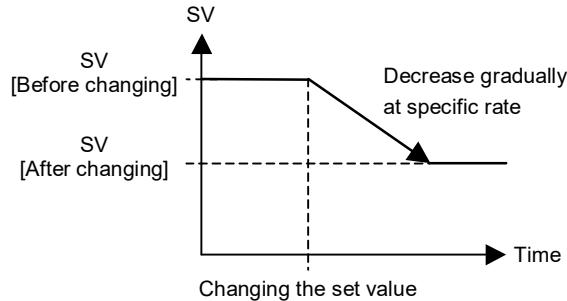
Setting the Setting change rate limiter unit time parameter and the Setting change rate limiter (up and down) will enable setting the changing rate (setting change rate limiter/unit time) of the Setting change rate limiter (up or down).

[Application examples of Setting change rate limiter]

- Increasing the SV to a higher value



- Decreasing the SV to a lower value



- When the Setting change rate limiter is used, the Set value (SV) will also ramp up or ramp down by the function at power-on and operation mode change from STOP to RUN.
- When the Set value (SV) is changed by the Memory area transfer function, the Setting change rate limiter functions from the Set value (SV) before the change (transfer) toward the set value after the change (transfer).
- If the Autotuning (AT) function is activated while the Set value (SV) is ramping up or ramping down by the Setting change rate limiter, the AT will starts after the Set value (SV) finishes ramp-up or ramp-down by the limiter, and the controller is in PID control mode until the AT starts.
- When the value of Setting change rate limiter is changed during normal operation, the ramp-up or ramp-down rate will be changed unless the SV already has finished ramp-up or ramp-down by the function.
- When Setting change rate limiter is set to other than “OFF: No function (disabled)” and when the Event type is set to a SV monitor value, the Event re-hold function by the Set value (SV) change is invalid. However, the event using a local SV will have the Event re-hold function by the Set value (SV) change valid.
- During the Remote mode, the Input 1_Setting change rate limiter will function to Remote setting input value.

■ Parameter setting

● Input 1_Setting change rate limiter (up)

[Parameter Setting Mode: Parameter group No. 70 (P_{n70})]

Parameter symbol	Data range	Factory set value
$ISVRU$	0 to Input 1_Input span (When Control with PV select: 0 to PV select input span) 0: No function Varies with the setting of the Decimal point position.	0

● Input 2_Setting change rate limiter (up)

[Parameter Setting Mode: Parameter groupNo. 70 (P_{n70})]

Parameter symbol	Data range	Factory set value
$2SVRU$	0 to Input 2_Input span 0: No function Varies with the setting of the Decimal point position.	0



To display “Input 2_Setting change rate limiter (up),” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

● Input 1_Setting change rate limiter (down)

[Parameter Setting Mode: Parameter group No. 70 (P_{n70})]

Parameter symbol	Data range	Factory set value
$ISVRd$	0 to Input 1_Input span (When Control with PV select: 0 to PV select input span) 0: No function Varies with the setting of the Decimal point position.	0

● Input 2_Setting change rate limiter (down)

[Parameter Setting Mode: Parameter group No. 70 (P_{n70})]

Parameter symbol	Data range	Factory set value
$2SVRd$	0 to Input 2_Input span 0: No function Varies with the setting of the Decimal point position.	0



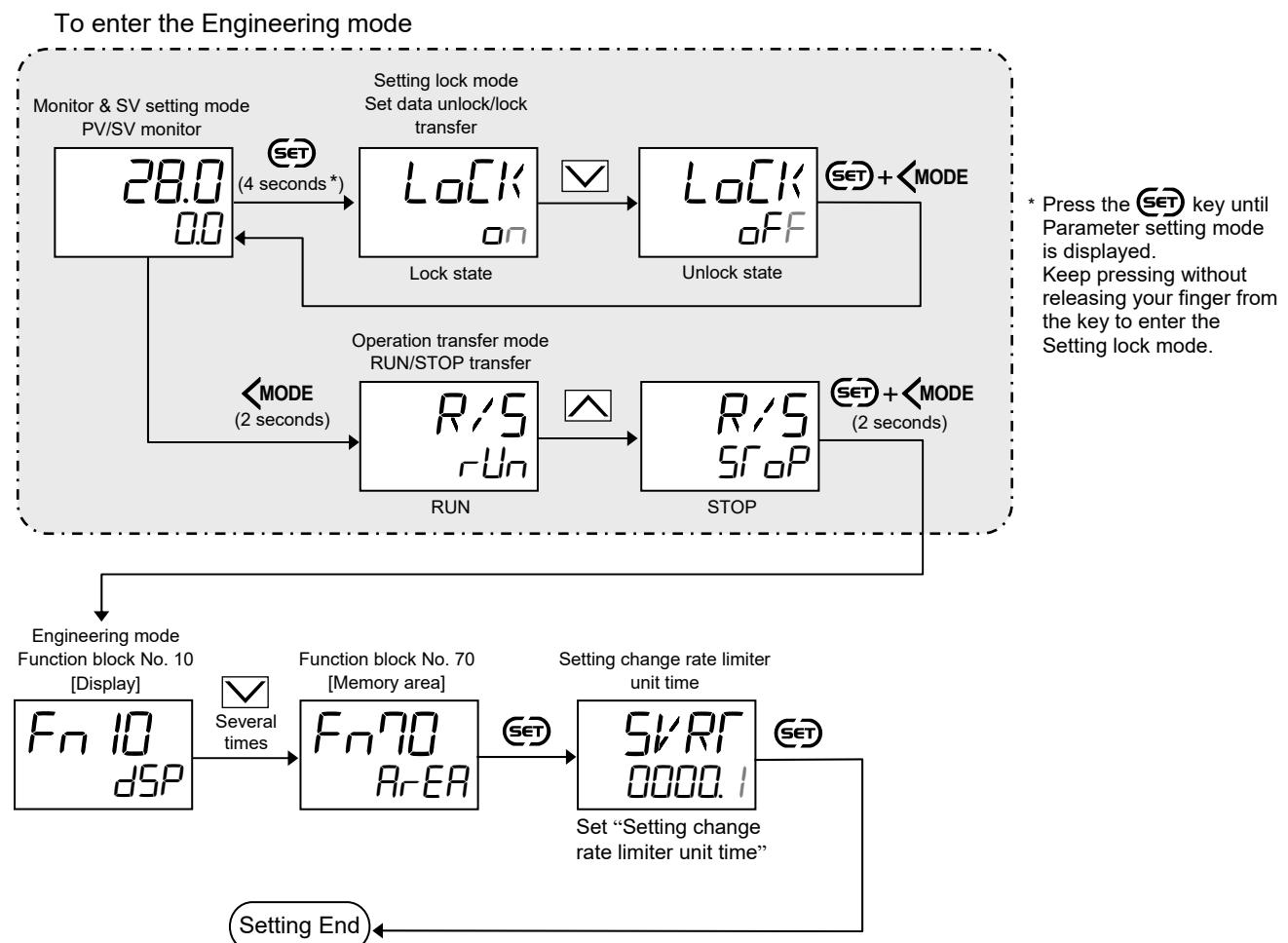
To display “Input 2_Setting change rate limiter (down),” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

● Setting change rate limiter unit time
[Engineering Mode: Function block No. 70 (Fn70)]

Parameter symbol	Data range	Factory set value
SVRF	0.1 to 360.0 seconds	0.1

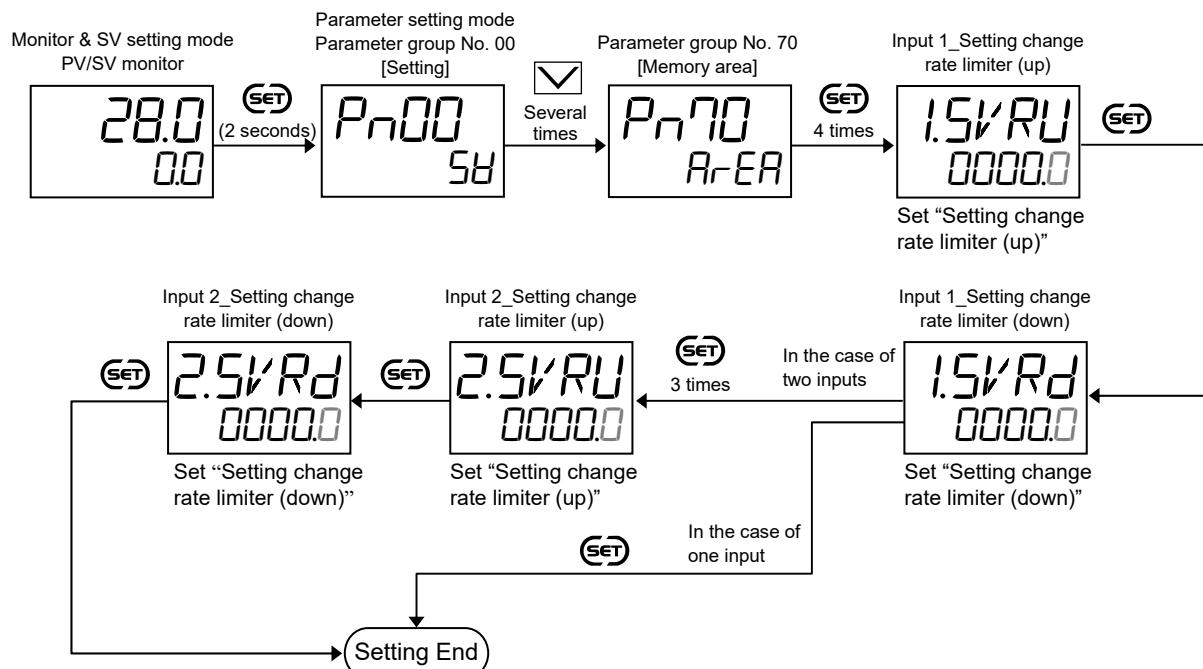
■ Setting procedure

● Set the Setting change rate limiter unit time parameter



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

● Set the Setting change rate limiter (up/down)



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

10.3 Storing the Control Related Set Values (Memory Area Function)

This function allows PID related parameters such as a Set value (SV) to be stored as an area and up to 16 areas.

■ Description of function

The Memory area function is to store up to 16 areas of parameters such as a Set value (SV). Parameters that can be stored in an area are those inside the Parameter setting mode*.

One of the Areas is used for control, and the currently selected area is Control area.

Storing set values according to work processes in a location called “area” allows a necessary set of set values for the work process to be retrieved only by changing the area number.

* ON/OFF action differential gap (upper) and (lower) are excluded.

Parameters inside the Parameter setting mode are categorized into six groups by the setting contents. These parameters are categorized into three groups during the “Level PID” function.

● Memory area parameters of Parameter group No. 00 (P_{n00}) [Set value (SV)]

Input 1_Set value (SV)

Input 2_Set value (SV)

Set value (SV) of differential temperature input

● Memory area parameters of Parameter group No. 40 (P_{n40}) [Event]

Event 1 set value (EV1) or Event 1 set value (EV1) [high]

Event 1 set value (EV1') [low]

Event 2set value (EV2) or Event 2set value (EV2) [high]

Event 2set value (EV2') [low]

Event 3set value (EV3) or Event 3set value (EV3) [high]

Event 3set value (EV3') [low]

Event 4set value (EV4) or Event 4set value (EV4) [high]

Event 4set value (EV4') [low]

● Memory area parameters of Parameter group No. 51 (P_{n51}) [Input 1_Control]

Input 1_Proportional band [heat-side]

Input 1_FF amount

Input 1_Integral time [heat-side]

Input 1_Output limiter high [heat-side]

Input 1_Derivative time [heat-side]

Input 1_Output limiter low [heat-side]

Input 1_Control response parameter

Input 1_Control loop break alarm (LBA) time

Input 1_Proactive intensity

Input 1_LBA deadband (LBD)

Input 1_Manual reset

● Memory area parameters of Parameter group No. 52 (P_{n52}) [Input 2_Control]

Input 2_Proportional band

Input 2_FF amount

Input 2_Integral time

Input 2_Output limiter high

Input 2_Derivative time

Input 2_Output limiter low

Input 2_Control response parameter

Input 2_Control loop break alarm (LBA) time

Input 2_Proactive intensity

Input 2_LBA deadband (LBD)

Input 2_Manual reset

● Memory area parameters of Parameter group No. 56 (P_{n56}) [Input_1 Cooling control]

Input 1_Proportional band [cool-side]

Input 1_Integral time [cool-side]

Input 1_Derivative time [cool-side]

Input 1_Overlap/Deadband

Input 1_Output limiter high [cool-side]

Input 1_Output limiter low [cool-side]

● Memory area parameters of Parameter group No. 70 (P_{n70}) [Memory area]

Select Trigger type for Memory area transfer

Area soak time

Link area number

Input 1_Setting change rate limiter (up)

Input 1_Setting change rate limiter (down)

Input 1_Auto/Manual transfer selection (Area)

Input 1_Manipulated output value (Area)

Input 2_Setting change rate limiter (up)

Input 2_Setting change rate limiter (down)

Input 2_Auto/Manual transfer selection (Area)

Input 2_Manipulated output value (Area)

Remote/Local transfer selection (Area)

● Memory area parameters of Parameter group No. 71 (P_{n71})

[Input 1_Input knee point correction]

Input 1_Number of knee point

Input 1_Knee point input value 1

Input 1_Knee point input value 2

Input 1_Knee point input value 3

Input 1_Knee point input value 4

Input 1_Knee point input value 5

Input 1_Knee point correction value 1

Input 1_Knee point correction value 2

Input 1_Knee point correction value 3

Input 1_Knee point correction value 4

Input 1_Knee point correction value 5

● Memory area parameters of Parameter group No. 72 (P_{n72})

[Input 2_Input knee point correction]

Input 2_Number of knee point

Input 2_Knee point input value 1

Input 2_Knee point input value 2

Input 2_Knee point input value 3

Input 2_Knee point input value 4

Input 2_Knee point input value 5

Input 2_Knee point correction value 1

Input 2_Knee point correction value 2

Input 2_Knee point correction value 3

Input 2_Knee point correction value 4

Input 2_Knee point correction value 5

[Groups used during the Level PID]

- **Group 0:** Parameter group No. 00, No. 40, No. 70, No. 71, and No. 72

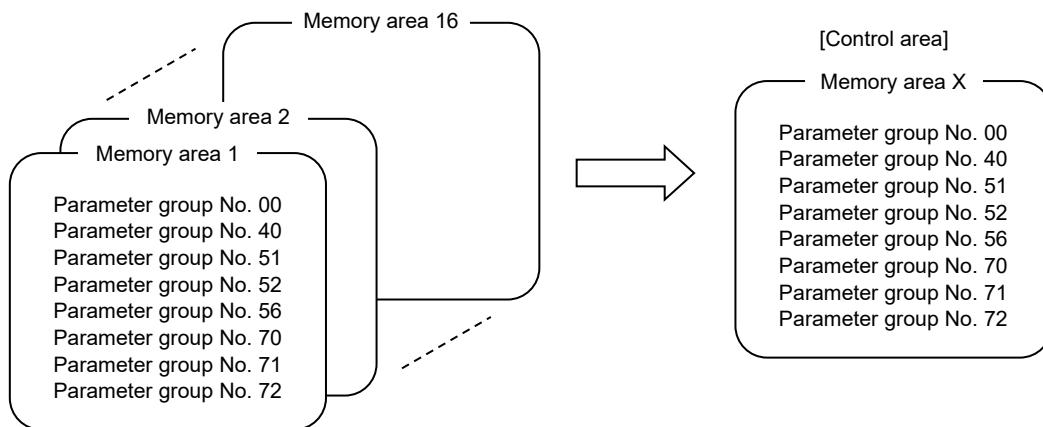
- **Group 1:** Parameter group No. 51 and No. 56

- **Group 2:** Parameter group No. 52



For Level PID function, see **8.13. Controlling with Level PID (P. 8-72)**.

● Structural image of Memory area



The following four parameters are used in common in all Memory areas, and therefore are not included in the Memory area.

Parameter group No. 51: Input 1_ON/OFF action differential gap (upper)
 Input 1_ON/OFF action differential gap (lower)

Parameter group No. 52: Input 2_ON/OFF action differential gap (upper)
 Input 2_ON/OFF action differential gap (lower)

■ Transferring the Control area

The Control area is displayed on the Memory area display during the monitor display state. (See the right picture)

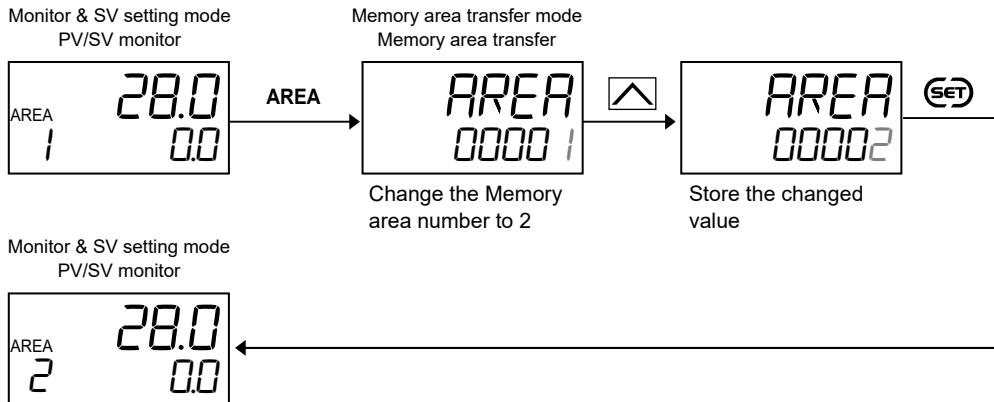
Control area can be transferred by Key operations, Digital input, or communication. Memory area transfer by Memory Area Soak time is also possible.

-  For the communication, refer to the separate **GZ400/GZ900 Instruction Manual [Host communication] (IMR03D07-E)**.



● Selection by front key operation

Changing the Control area from 1 to 2



● Switching the Control area by Digital Input (DI)

To switch the control area by Digital input (DI), the instrument must have an option (Digital input). The memory area transfer must be set at DI1 function selection.

To change the Control area by Digital input (DI), two methods are offered; Transfer using the SET signal input and transfer without the SET signal.

- With a SET signal: After the Memory area has been selected by the DI, close the contact of the SET signal so that the Control area is transferred.
- Without a SET signal input:
After the Memory area has been selected by the DI, the Area will be automatically changed after the time period (1 to 5 seconds) set at “Area switching time (without area set signal)” in Function block No. 23 in the Engineering mode.

-  For details, see **5.2 Switching Functions Using Digital Inputs (DI) (P. 5-16)**.

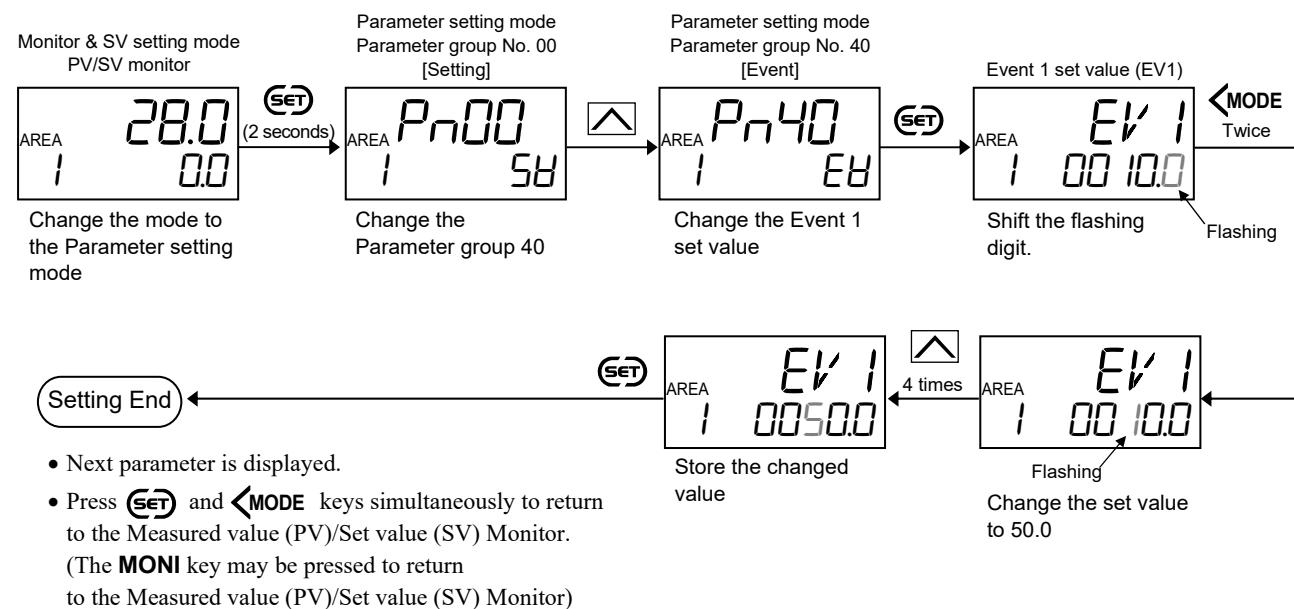
● Switching the Control area by Area soak time

Changing the Memory area by the Memory area soak time will need setting the Memory area No. to which the Memory area is switched.

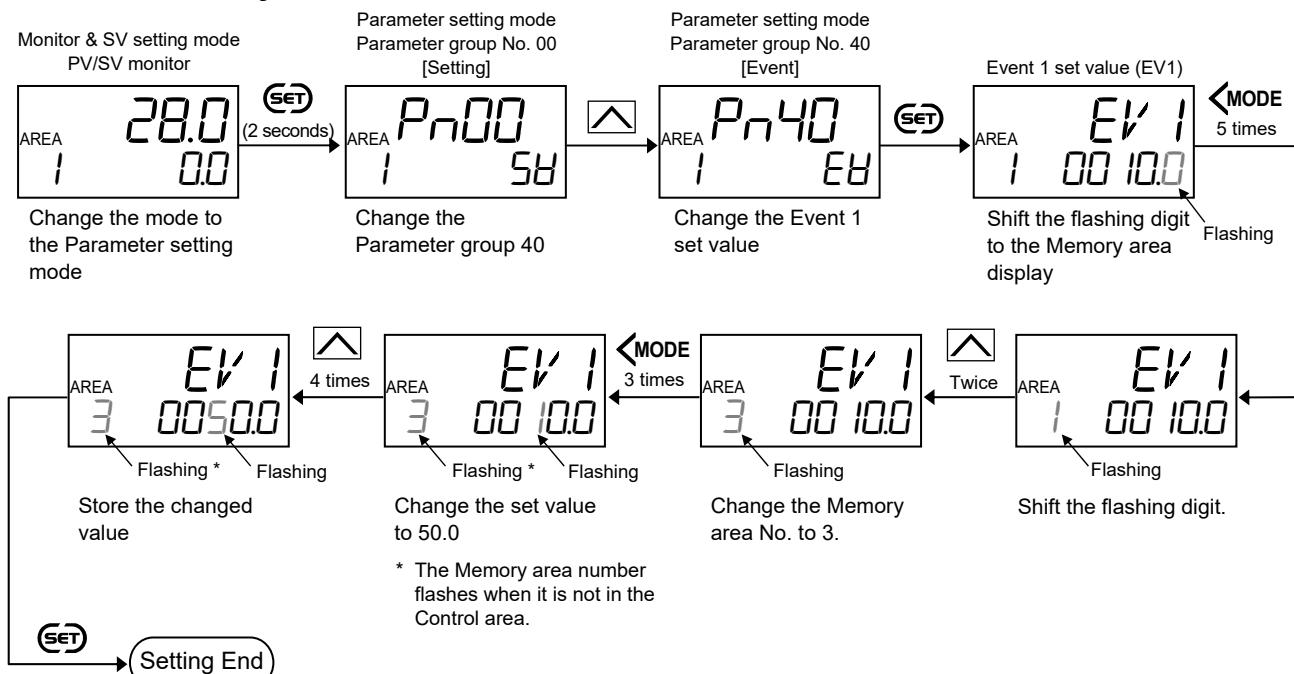
See **10.5 Running a Simple Ramp/Soak Operation (P. 10-18)** or **10.6 Using a Simple Sequence Operation (P. 10-26)** for details.

■ Changing the data in the Memory area

● Change the Event 1 set value in the Control area (Memory area 1) from 10.0 to 50.0



● Change the Event 1 set value from 10.0 to 50.0 in Memory area 3 when the Control area is Memory area 1.



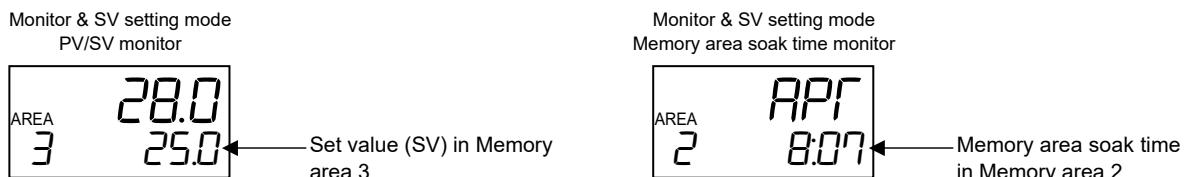
- Next parameter is displayed.
- Press **SET** and **MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

■ Memory area display

During the PV/SV monitor display, the Set value (SV) displayed on the SV display is the Set value (SV) in the Memory area No. now displayed on the Memory area display.

During the Monitor & SV setting mode display, the time displayed on the Memory area soak time is the time of the Memory area No. now displayed on the Memory area display.

[Example]



■ Parameter setting

● Memory area transfer

[Memory Area Transfer Mode]

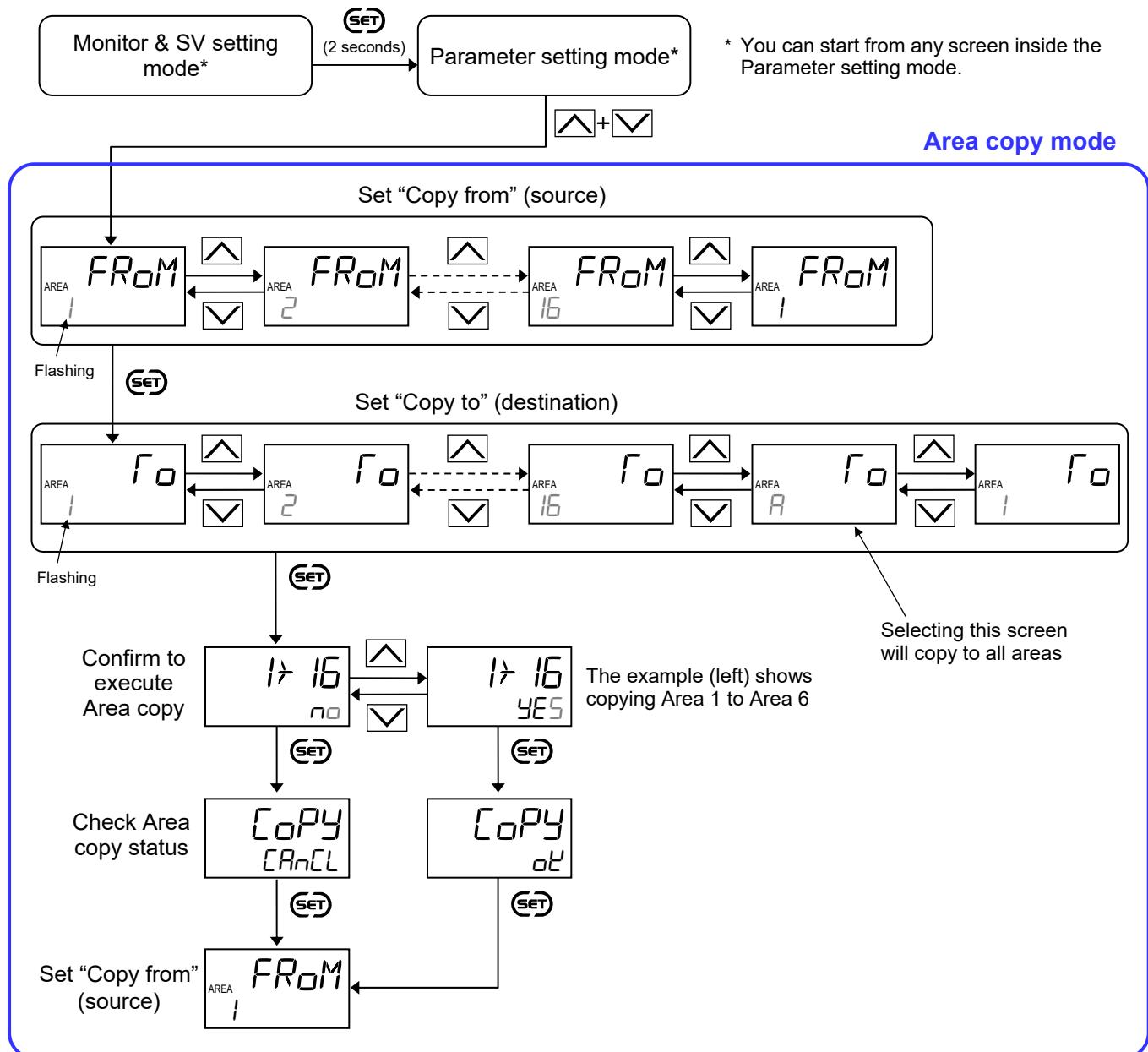
Parameter symbol	Data range	Factory set value
AREAR	1 to 16	1

-  When the “Area lock” setting is “Memory area is not adjustable when the setting data is locked”, this parameter will not be displayed.
-  See “**4. PARAMETERS THAT ARE INITIALIZED/MODIFIED WHEN SETTING IS CHANGED (P. 4-1)**” for the parameters that are automatically converted when the Memory area is changed.

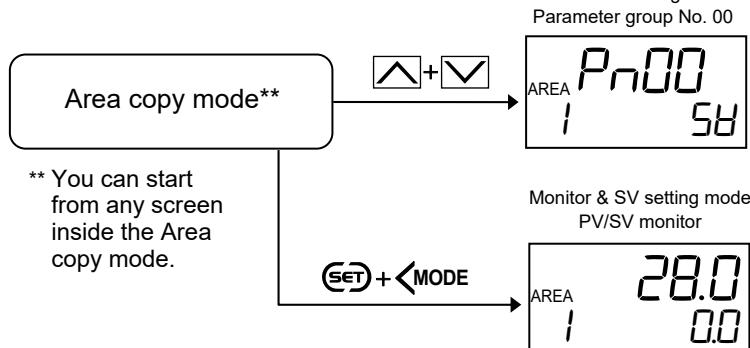
10.4 Copying the Data in Memory Area to Set Other Areas

Up to 16 Memory areas can be set, but it consumes time if Memory areas are set one after another. On this instrument, the data in the Memory area can be copied.

■ Screens for Area copy mode

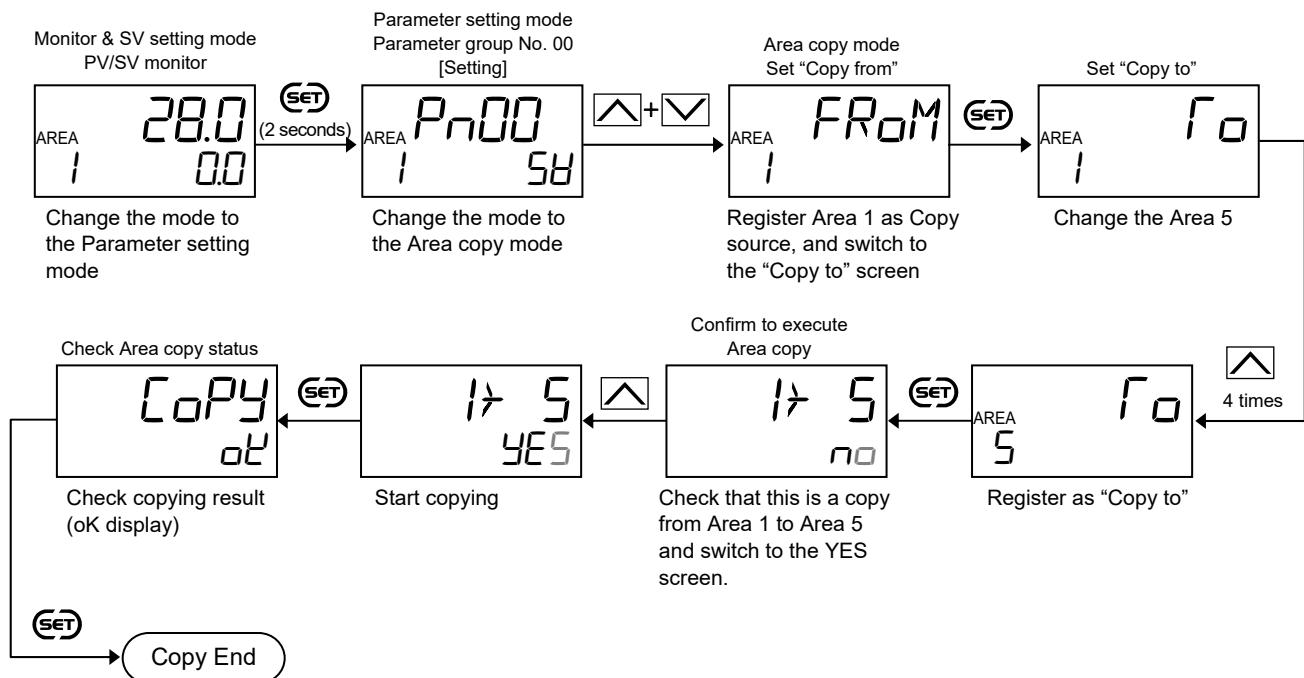


[To exit from Area copy mode]



[Example Area copy]

Copy the data in Memory Area 1 to Memory area 5



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

10.5 Running a Simple Ramp/Soak Operation

On this instrument multiple Memory areas can be linked to run a simple ramp/soak control.

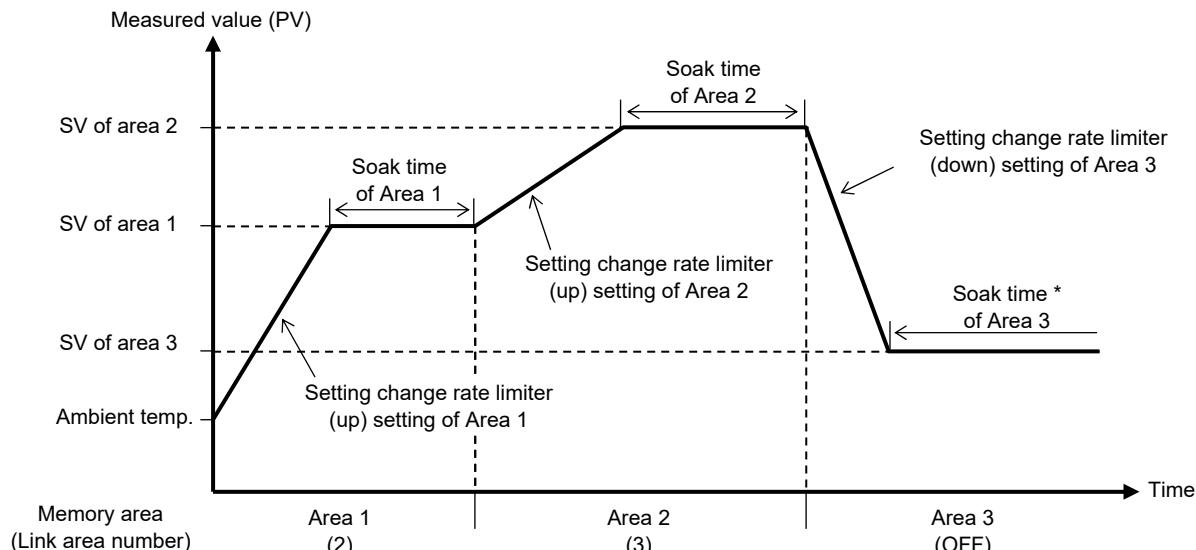
■ Description of function

Simple Ramp/Soak control is possible by setting a Set value (SV), Setting change rate limiter (up/down), Area soak time, and Link area number in each memory area.

- Set value (SV): Sets the fixed set point control (control by fixed set value) desired value of each memory area.
- Setting change rate limiter: Sets the slope of the Set value (SV) which is raised or lowered at each unit time.
- Area soak time: Sets the fixed set point control time of each memory area.
- Link area number: Sets the memory area numbers for linking the corresponding memory areas.

 Besides the above, the Setting change rate limiter unit time and Area soak time unit are set in the Engineering mode.

Example: Ramp/Soak control by linking Memory area 1 to 3

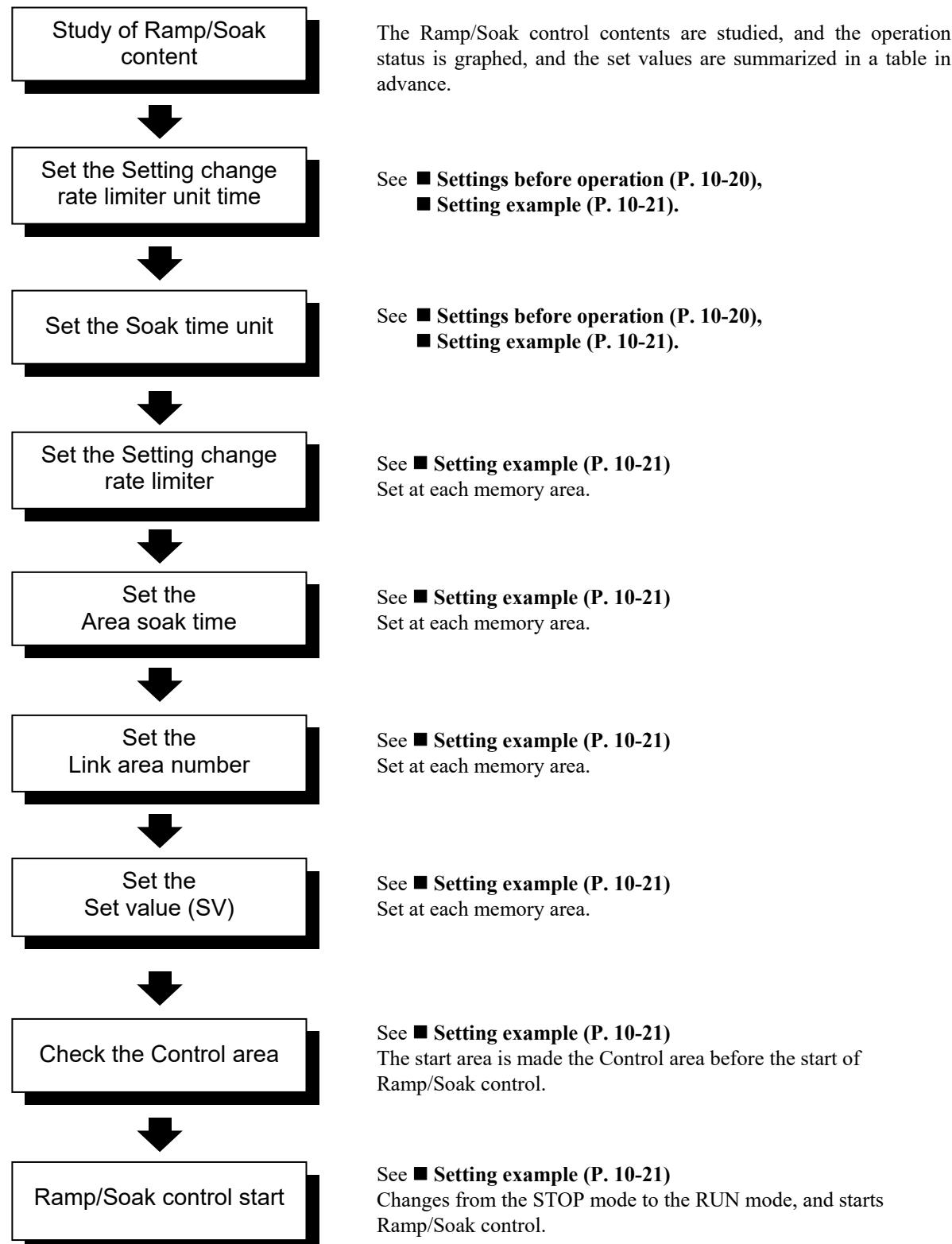


* As the area soak time for memory area linked last becomes invalid, the state of SV3 reached continues.

 To check the elapsed time in each area, see the “Memory area soak time monitor” in the Monitor & SV setting mode.

Memory area soak time can be displayed on the MV display. See **9.6 Changing the Display Contents of the MV Display (P. 9-21)**.

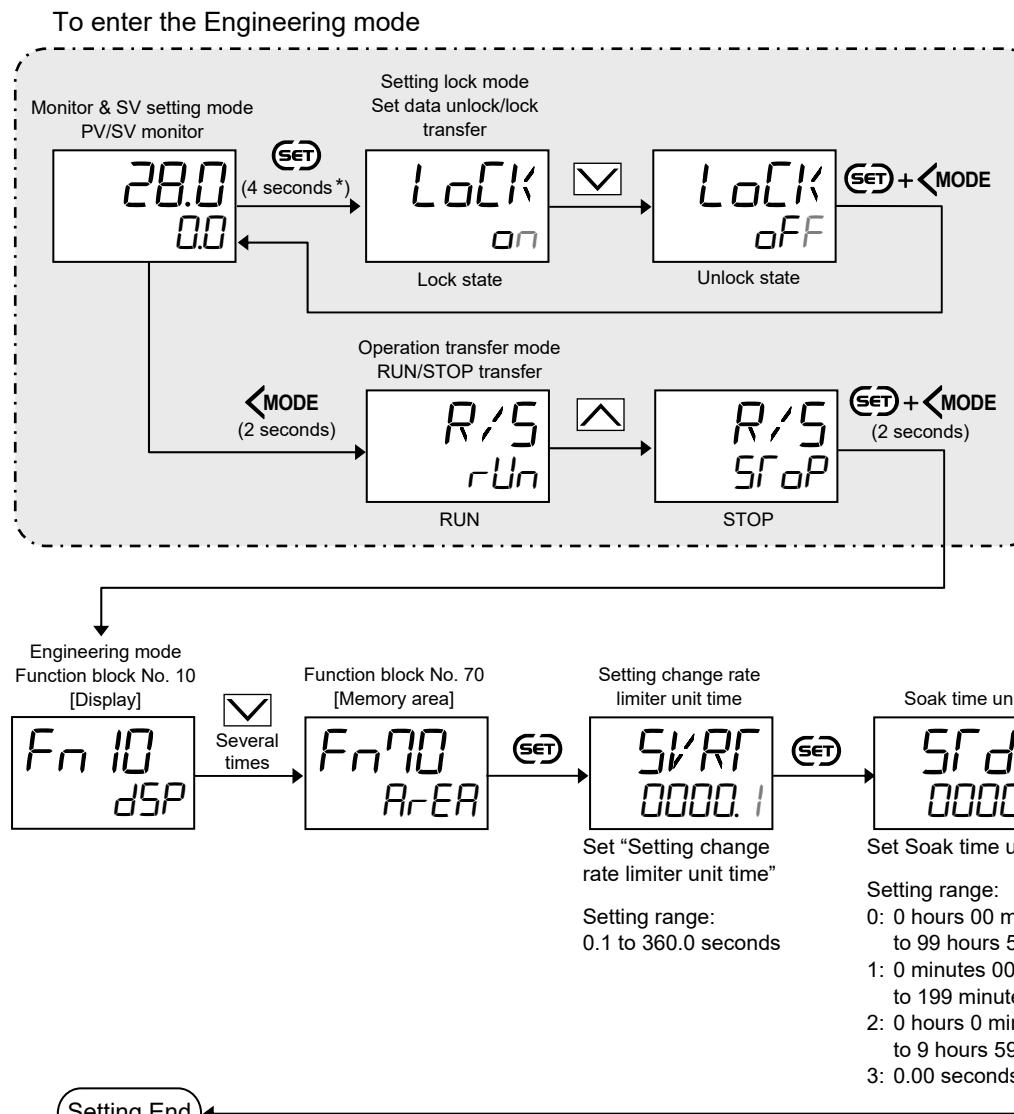
■ Operation flowchart



■ Settings before operation

When implementing Ramp/Soak control, it may be necessary to set the following items in advance.

- Setting change rate limiter unit time [Engineering mode: Function block No. 70 (F_{n70})]
- Soak time unit [Engineering mode: Function block No. 70 (F_{n70})]

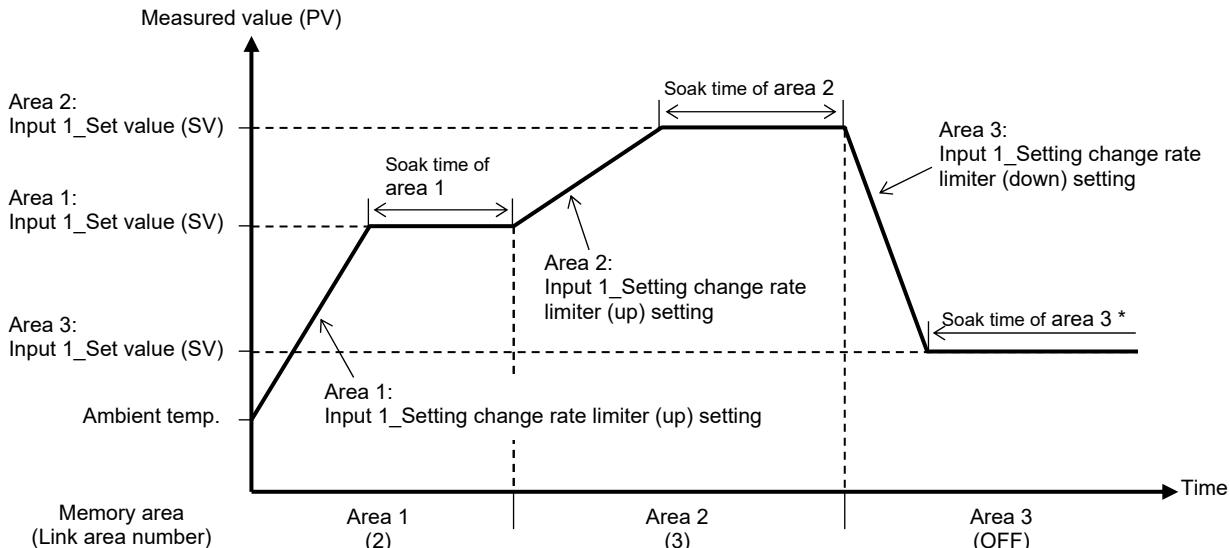


- Next parameter is displayed.
- Press **SET** and **MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

■ Setting example

This section uses the following sample of Ramp/Soak control to describe the setting procedures.

[Example: Ramp/Soak control by linking Memory area 1 to 3]



	Area 1	Area 2	Area 3
Input 1_Set value (SV)	150.0 °C	200.0 °C	50.0 °C
Input 1_Setting change rate limiter (up)	4.0 °C/min. (60.0 sec.)	2.0 °C/min. (60.0 sec.)	OFF
Input 1_Setting change rate limiter (down)	OFF	OFF	9.0 °C/min. (60.0 sec.)
Area soak time	30 minutes	40 minutes	0 minutes *
Link area number	2	3	OFF

* In this example, the Area soak time for memory area 3 is set. However, as the Area soak time for the memory area linked last becomes invalid, the state of SV3 reached continues.

Step 1:
Study the Ramp/Soak control content.

The Ramp/Soak control contents are studied and Ramp/Soak status is graphed and the set values of each memory area are summarized in a table as shown above.

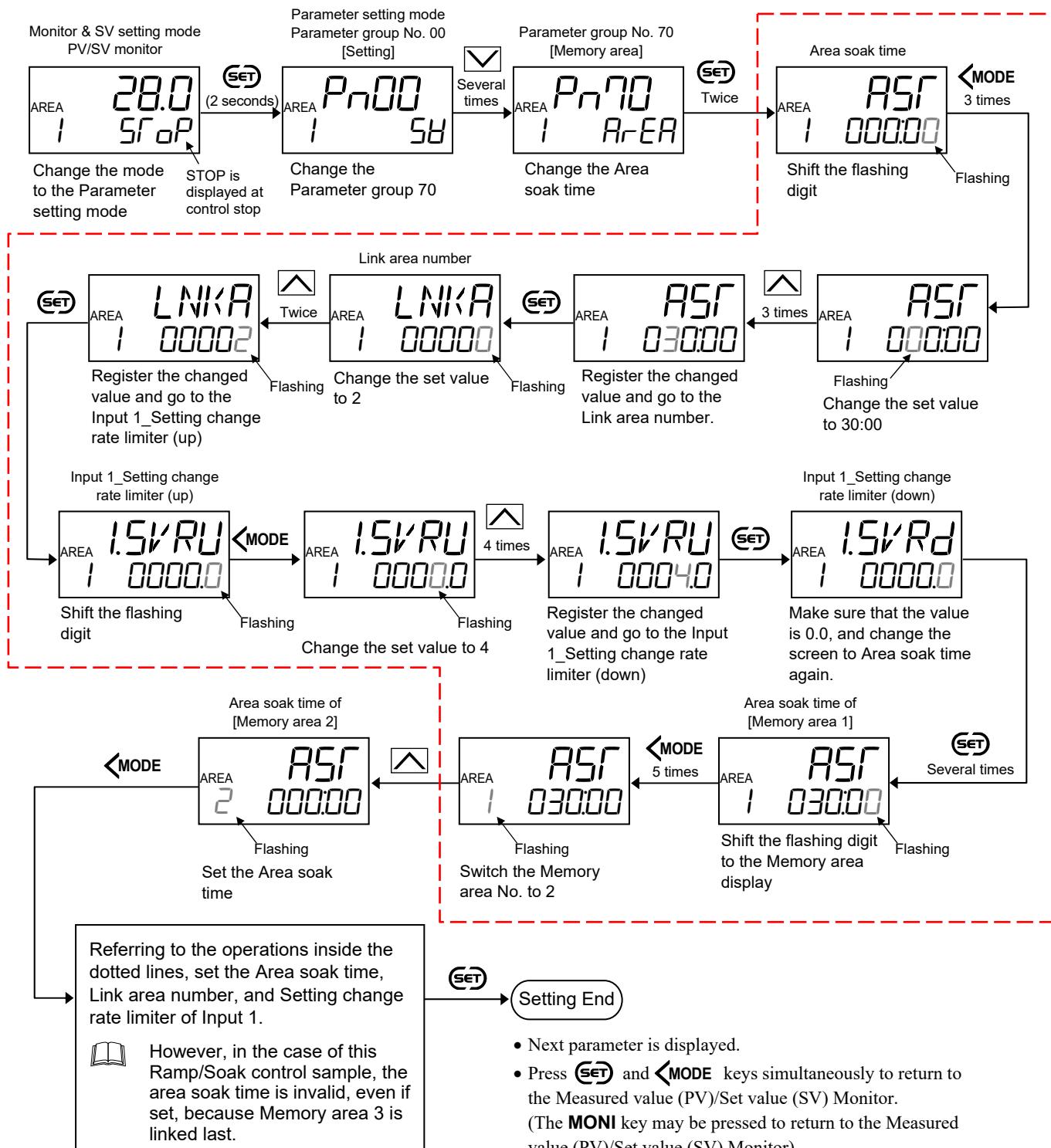
Step 2:
Set the Setting change rate limiter unit time and Soak time unit.

See ■ **Settings before operation (P. 10-20)** and set the Setting change rate limiter unit time and Area soak time. Since control stops (STOP) at this time, go directly to the next step.

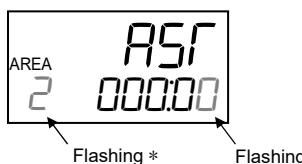
- Setting change rate limiter unit time: 60.0 seconds
- Soak time unit: 1 (0 minutes 00 seconds to 199 minutes 59 seconds)

Step 3:

Set the Setting change rate limiter, Area soak time and Link area number to each of Memory area 1, 2 and 3.

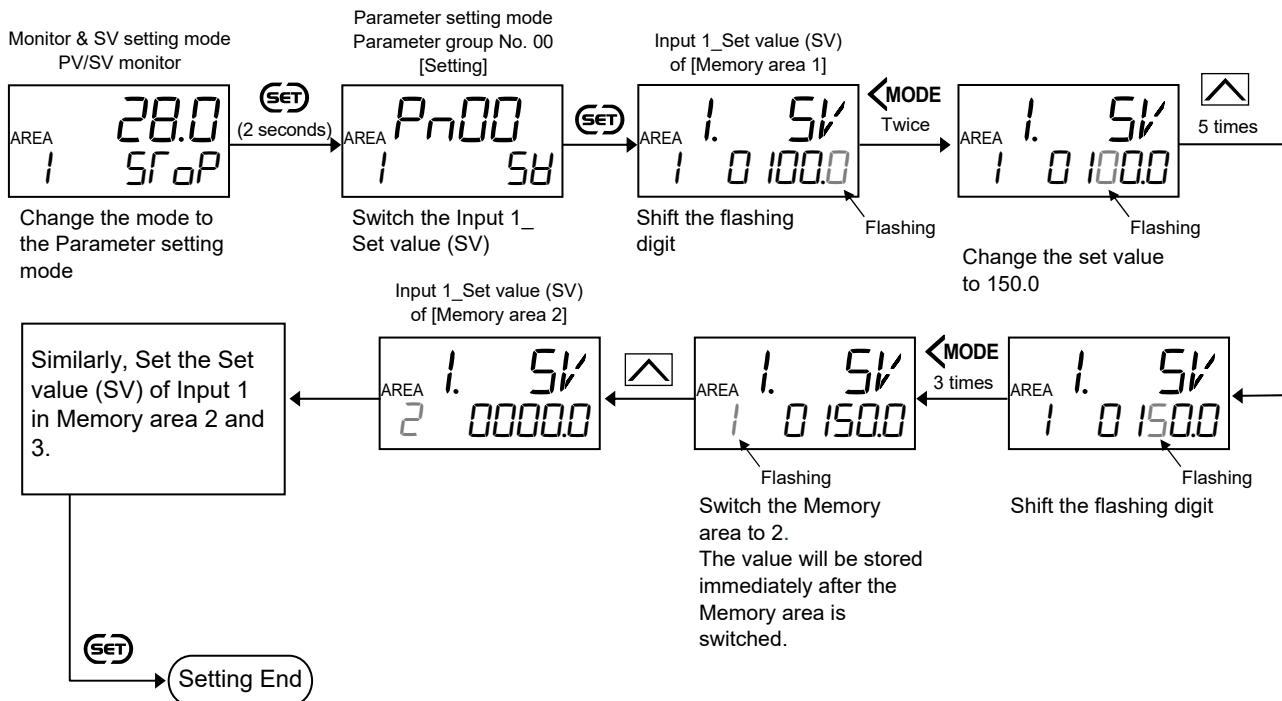


The Memory area number flashes when a Memory area other than that in the Control area is displayed.



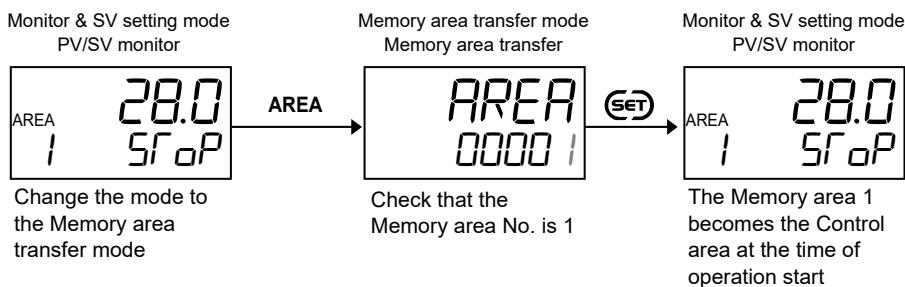
(* Area other than Control area is displayed)

Step 4:
Set the SV to each of Memory area 1, 2 and 3.

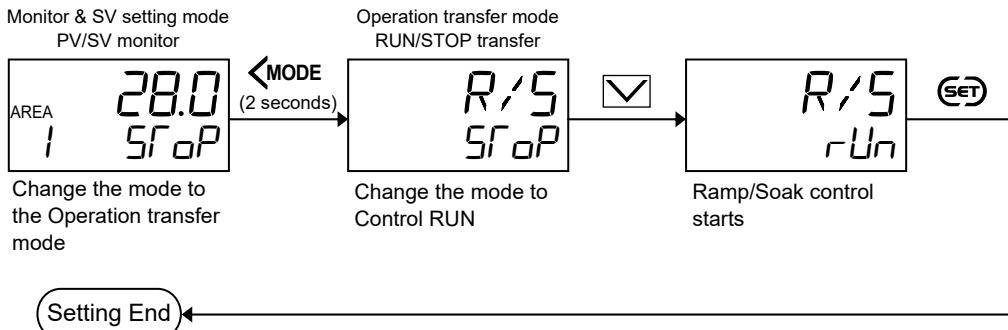


- Next parameter is displayed.
 - Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

Step 5:
Check the control area number.



Step 6:
Change from STOP mode to RUN mode



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

■ Parameter setting

 For Setting change rate limiter (up/down) and Setting change rate limiter unit time, see **10.2 Eliminating a Sudden Set Value Change (Setting Change Rate Limiter) (P. 10-6)**.

● Area soak time

[Parameter Setting Mode: Parameter group No. 70 (P_{n70})]

Parameter symbol	Data range	Factory set value
ASR	0 hours 00 minutes 00 seconds to 9 hours 59 minutes 59 seconds * 0 hours 00 minutes to 99 hours 59 minutes 0 minutes 00 seconds to 199 minutes 59 seconds 0.00 seconds to 59.99 seconds (Calculation is performed every 50ms.) * Settable only when the Input data type is 0 or 2. Data range of Area soak time can be selected on the Soak time unit.	0:00 (0.00 seconds)

 For Input data type, see **5.1 Changing Input (P. 5-2)**.

● Link area number

[Parameter Setting Mode: Parameter group No. 70 (P_{n70})]

Parameter symbol	Data range	Factory set value
$LNKA$	0 to 16 0: No link	0

● Soak time unit

[Engineering Mode: Function block No. 70 (F_{n70})]

Parameter symbol	Data range	Factory set value
SF_{dP}	0: 0 hours 00 minutes to 99 hours 59 minutes 1: 0 minutes 00 seconds to 199 minutes 59 seconds 2: 0 hours 00 minutes 00 seconds 3: 0.00 seconds to 59.99 seconds In case of Input data type 0 or 2: 0 to 3 In case of Input data type 1: 0 to 1, 3	3

 For Input data type, see **5.1 Changing Input (P. 5-2)**.

10.6 Using a Simple Sequence Operation

On this instrument, multiple Memory areas can be linked to run a simple sequence operation in each Memory area.

■ Description of function

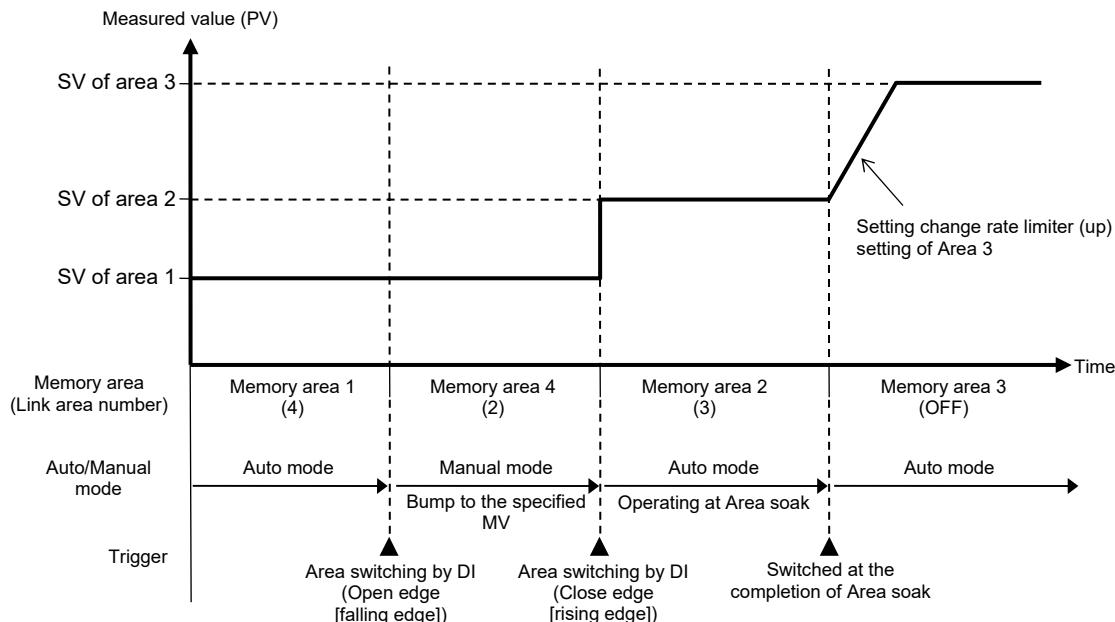
Simple sequence operation is possible by setting a Set value (SV), Setting change rate limiter (up/down), Select Trigger type for Memory area transfer, Area soak time, Link area number, Auto/Manual transfer selection (Area), Manipulated output value (Area), and Remote/Local transfer selection (Area) in each memory area.

- Set value (SV): Sets the fixed set point control (control by fixed set value) desired value of each memory area.
- Setting change rate limiter: Sets the slope of the Set value (SV) which is raised or lowered at each unit time.
- Select Trigger type for Memory area transfer: Select a trigger type to switch the Memory area.
- Area soak time: Sets the fixed set point control time of each memory area.
- Link area number: Sets the memory area numbers for linking the corresponding memory areas. Memory area will be switched by generated events or contact status of Digital input (DI). To use the generated events as a switching method, setting up the event function is required. To use the Digital input (DI) as a switching method, “Area jump” must be preset in the DI function selection.
 -  For the Event function, see **7.1 Using Event Function (P. 7-2)**. For the DI function selection, see **5.2 Switching Functions Using Digital Inputs (DI) (P. 5-16)**.
- Auto/Manual transfer selection (Area): Select the operation mode (Auto mode or Manual mode) at the time of switching the memory area. A selection of “Bump” or “Bumpless” is available both in Auto and Manual modes.
 -  When the SV tracking function is selected at the time of switching from Manual to Auto mode, the Set value (SV) of the Memory area will be ignored.
 -  For more details of Bumpless action at the time of switching between Auto/Manual, see **6.8 Suppressing Sudden Change in Output (Balanceless Bumpless) (P. 6-33)**.
 -  For the SV tracking function, see **8.15 Continuing Stable Control after the Operation Transfer (SV Tracking) (P. 8-85)**.
- Manipulated output value (Area): When either “Auto mode (bump)” or “Manual mode (bump)” is selected in the Auto/Manual transfer selection (Area), the Manipulated output value just after the switching is complete needs to be set here.
- Remote/Local transfer selection (Area): Select the Operation mode at the time of Memory area switching. The operation mode depends on the action selected in Select function for input 2.
 - Remote setting input: Remote mode/Local mode switching
 - Control with PV select: Input 1/Input 2 switching
 - 2-loop control/Differential temperature control:
2-loop control/Differential temperature control switching
 -  When the SV tracking function is selected at the time of the operation mode transfer, the operation mode follows the action set in the SV tracking.
 -  For the SV tracking function, see **8.15 Continuing Stable Control after the Operation Transfer (SV Tracking) (P. 8-85)**.



Besides the above, the Setting change rate limiter unit time and Area soak time unit are set in the Engineering mode

Example: Operating a simple sequence using Memory areas 1 through 4



● Description of operation

1. Memory area 1: Operation mode: Auto mode
Control target: Set value (SV) of Memory area 1
Area soak time: 0:00 (No function)
Link area number: 4
Memory area switching trigger: Open edge (falling edge) of Digital input (DI1)
2. Memory area 4: Operation mode: Switched from Auto mode to Manual mode
Control output: Bumps to the value specified by the Manipulated output value (Area)
Area soak time: 0:00 (No function)
Link area number: 2
Memory area switching trigger: Close edge (rising edge) of Digital input (DI1)
3. Memory area 2: Operation mode: Switched from Manual mode to Auto mode
Control target: Set value (SV) of Memory area 2
Area soak time: 10 minutes
Link area number: 3
Memory area switching trigger: 0 (No assignment)
Area is switched after the completion of the Area soak.
4. Memory area 3: Operation mode: Auto mode continues
Control target: After changing the Set value (SV) by the Setting change rate limiter, control is done using the Set value (SV) in Memory area 3.
Area soak time: In this example, the Area soak time for memory area 3 is set. However, as the Area soak time for the memory area linked last becomes invalid, the state of SV3 reached continues.
Link area number: 0 (No function)
Memory area switching trigger: 0 (No assignment)



When both of Area soak time and Select trigger type for memory area transfer are valid, the switching takes place based on the OR-logic.

■ Parameter setting

 For Setting change rate limiter (up/down) and Setting change rate limiter unit time, see **10.2 Eliminating a Sudden Set Value Change (Setting Change Rate Limiter) (P. 10-6)**.

● Select Trigger type for Memory area transfer

[Parameter Setting Mode: Parameter group No. 70 (*Pn70*)]

Parameter symbol	Data range	Factory set value
<i>TRGA</i>	0 to 63 0: No assignment +1: Event 1 +2: Event 2 +4: Event 3 +8: Event 4 +16: Digital input 1 (DI1) Close edge +32: Digital input 1 (DI1) Open edge To select two or more functions, sum each value.	0

 To use the generated events as a switching method, setting up the event function is required. To use the Digital input (DI) as a switching method, “Area jump” must be preset in the DI function selection. For the Event function, see **7.1 Using Event Function (P. 7-2)**. For the DI function selection, see **5.2 Switching Functions Using Digital Inputs (DI) (P. 5-16)**.

● Area soak time

[Parameter Setting Mode: Parameter group No. 70 (*Pn70*)]

Parameter symbol	Data range	Factory set value
<i>ASR</i>	0 hours 00 minutes 00 seconds to 9 hours 59 minutes 59 seconds * 0 hours 00 minutes to 99 hours 59 minutes 0 minutes 00 seconds to 199 minutes 59 seconds 0.00 seconds to 59.99 seconds (Calculation is performed every 50ms.) * Settable only when the Input data type is 0. Data range of Area soak time can be selected on the Soak time unit.	0:00 (0.00 seconds)

 For Input data type, see **5.1 Changing Input (P. 5-2)**.

● Link area number

[Parameter Setting Mode: Parameter group No. 70 (*Pn70*)]

Parameter symbol	Data range	Factory set value
<i>LNKA</i>	0 to 16 0: No link	0

● Input 1_Auto/Manual transfer selection (Area)

[Parameter Setting Mode: Parameter group No. 70 (P_{n70})]

Parameter symbol	Data range	Factory set value
$I.R / M.R$	0: No transfer 1: Auto mode (bumpless) 2: Auto mode (bump) 3: Manual mode (bumpless) 4: Manual mode (bump)	0



When the value is set and fixed to Auto mode at “Fix parameter setting: Auto/Manual transfer” in the Setting lock mode, data 3 and 4 in the above table cannot be set.

● Input 1_Manipulated output value (Area)

[Parameter Setting Mode: Parameter group No. 70 (P_{n70})]

Parameter symbol	Data range	Factory set value
$I.MV.R$	PID control: -5.0 to +105.0 % Heat/Cool PID control: -105.0 to +105.0 %	PID control: -5.0 Heat/Cool PID control: 0.0

● Input 2_Auto/Manual transfer selection (Area)

[Parameter Setting Mode: Parameter group No. 70 (P_{n70})]

Parameter symbol	Data range	Factory set value
$2.R / M.R$	0: No transfer 1: Auto mode (bumpless) 2: Auto mode (bump) 3: Manual mode (bumpless) 4: Manual mode (bump)	0



To display “Input 2_Auto/Manual transfer selection (Area),” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.



When the value is set and fixed to Auto mode at “Fix parameter setting: Auto/Manual transfer” in the Setting lock mode, data 3 and 4 in the above table cannot be set.

● Input 2_Manipulated output value (Area)

[Parameter Setting Mode: Parameter group No. 70 (P_{n70})]

Parameter symbol	Data range	Factory set value
$2.MV.R$	-5.0 to +105.0 %	-5.0



To display “Input 2_Manipulated output value (Area),” specify “Measured input 2” at the time of order, AND “Select function for input 2” (Function block No. 58 in Engineering mode) must be set to 2-loop control/Differential temperature control.

● Remote/Local transfer selection (Area)
[Parameter Setting Mode: Parameter group No. 70 (Pn70)]

Parameter symbol	Data range	Factory set value
<i>R/L.R</i>	<ul style="list-style-type: none"> When “Remote setting input” is selected at Select function for input 2¹ <ul style="list-style-type: none"> 0: No transfer 1: Local mode 2: Remote mode 	0
	<ul style="list-style-type: none"> When “Control with PV select” is selected at Select function for input 2² <ul style="list-style-type: none"> 0: No transfer 1: Input 1 2: Input 2 	
	<ul style="list-style-type: none"> When “2-loop control/Differential temperature control” is selected at Select function for input 2³ <ul style="list-style-type: none"> 0: No transfer 1: 2-loop control 2: Differential temperature control 	

¹ Displayed when “Remote setting input” is selected in “Select function for input 2.”

² Displayed when “Control with PV select” is selected in “Select function for input 2.”

³ Displayed when “2-loop control/Differential temperature control” is selected in “Select function for input 2.”



To display “Remote/Local transfer selection (Area)”

Specify two inputs at the time of order, set Remote setting input, Control with PV select, or 2-loop control/Differential temperature control at “Select function for input 2” in Function block No. 58 in the Engineering mode.



When the value is set and fixed to Local mode at “Fix parameter setting: Remote/Local transfer” in the Setting lock mode, data 2 in the above table cannot be set.

● Soak time unit

[Engineering Mode: Function block No. 70 (Fn70)]

Parameter symbol	Data range	Factory set value
<i>Sf dP</i>	<ul style="list-style-type: none"> 0: 0 hours 00 minutes to 99 hours 59 minutes 1: 0 minutes 00 seconds to 199 minutes 59 seconds 2: 0 hours 00 minutes 00 seconds to 9 hours 59 minutes 59 seconds 3: 0.00 seconds to 59.99 seconds <p>In case of Input data type 0 or 2: 0 to 3 In case of Input data type 1: 0 to 1, 3</p>	3

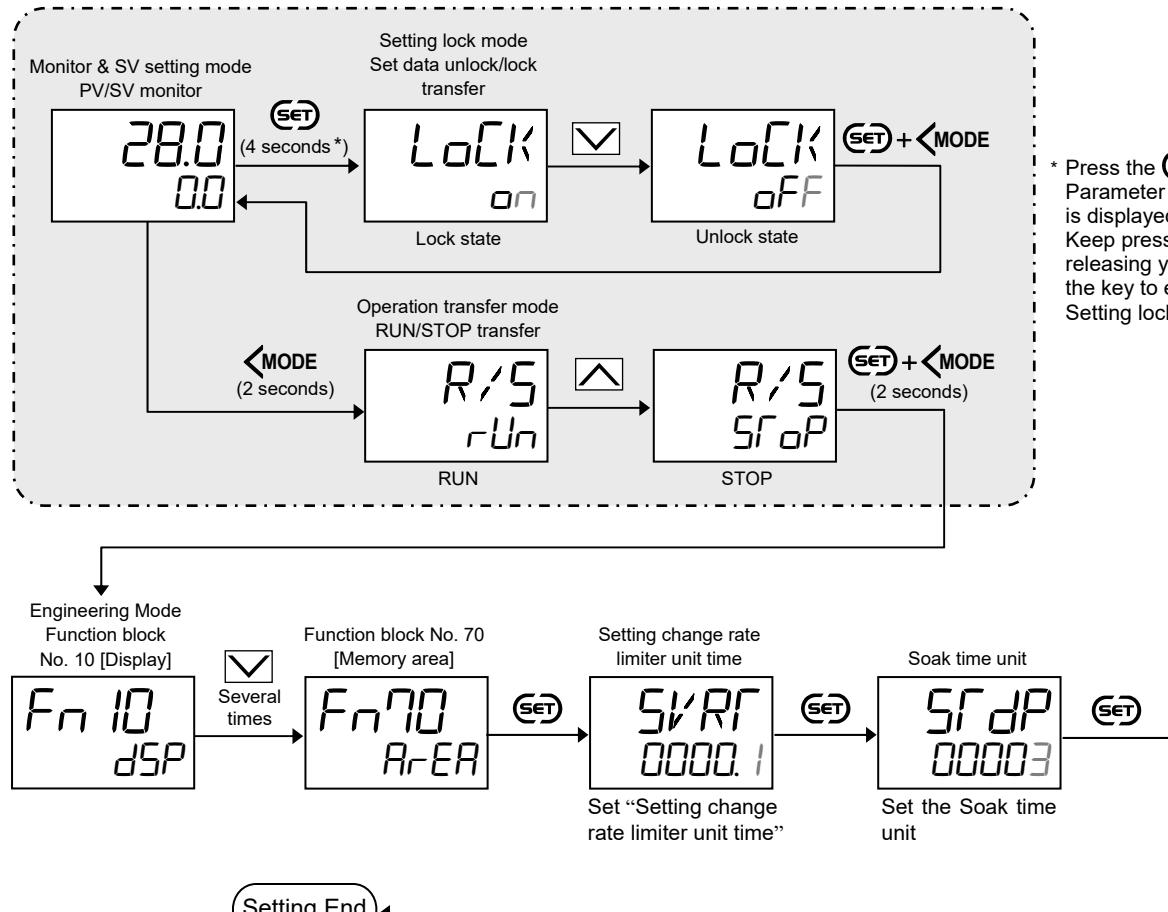


For Input data type, see **5.1 Changing Input (P. 5-2)**.

■ Setting procedure

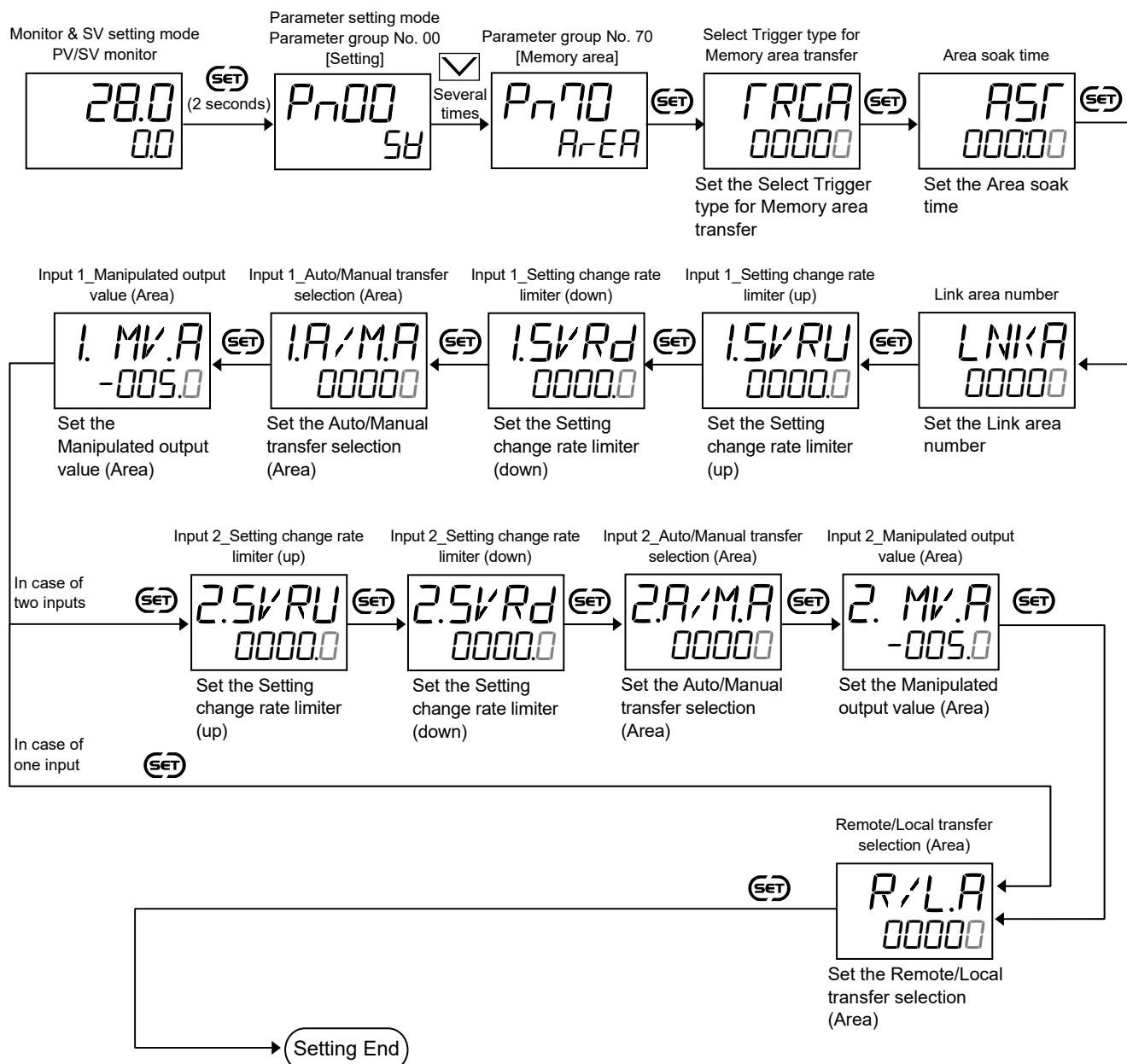
● Set the Setting change rate limiter unit time parameter and Soak time unit

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.

● Set the simple sequence related set items



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

10.7 Registering a Set Value (SV) Without Pressing the SET Key

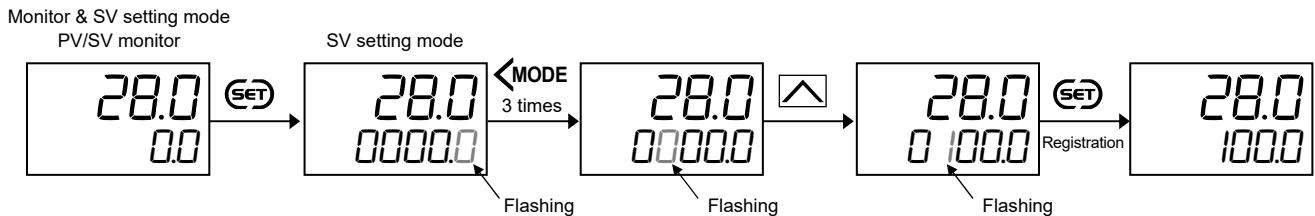
Basically the **SET** key must be pressed to register the data after changing the value of parameters.

There is another way of registering the Set value (SV) which takes in the changed data 2 seconds after the change.

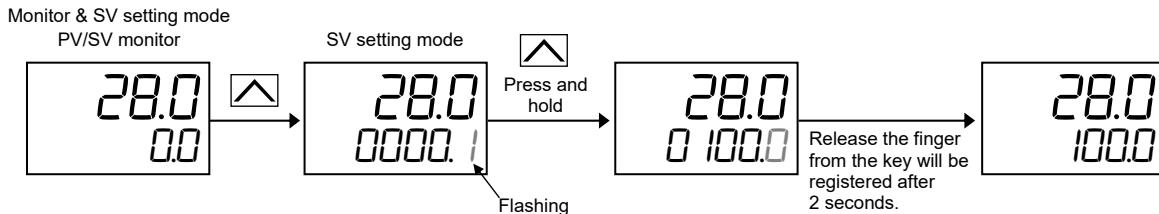
■ Description of function

[Example: Changing the Set value (SV) to 100.0]

- To register the value by pressing the SET key (SET key method)



- To register the value without pressing the SET key (Direct method)



- To set the Set value (SV) in the PV/SV monitor, press the **▲** or **▼** key.
- Keep pressing the **▲** or **▼** key to accelerate the speed of increase/decrease.
- In the above explanation, the value is changed by using the **▲** or **▼** key, but **MODE** key may be used to shift the blinking digit to change the value digit by digit.

- To use a registration method without pressing the **SET** key, go to “Data registration” in Function Block No. 11 in the Engineering mode.
- Registration without pressing the **SET** key is only applicable to the Set value (SV). Other parameters are not available in this method. Available mode is Monitor & SV setting mode only.

■ Parameter setting

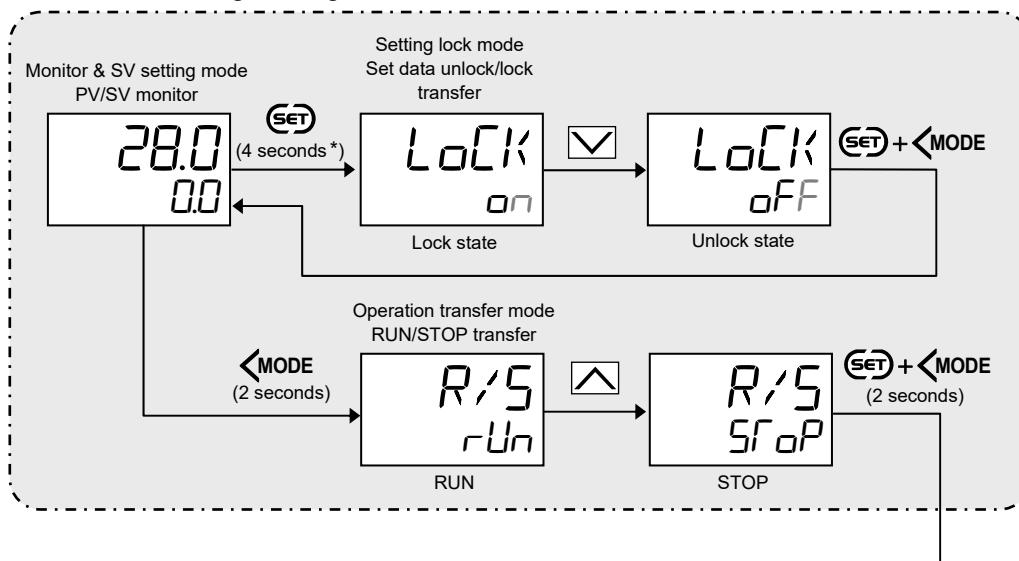
● Data registration

[Engineering Mode: Function block No. 11 (Fn 11)]

Parameter symbol	Data range	Factory set value
SET.KY	0: SET key method Used to register the Set value (SV) using the SET key. 1: Direct registration Used to register the Set value (SV) without pressing the SET key.	0

■ Setting procedure

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.

Keep pressing without releasing your finger from the key to enter the Setting lock mode.

- Next parameter is displayed.
- Press **SET** and **MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor.
(The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)
- Select RUN on the RUN/STOP transfer.
- Select lock on the Set data unlock/lock transfer.

10.8 Accessing Some Functions Directly (FUNC Key)

The instrument has a FUNC key which allows a specified function to be assigned to it.

■ Description of function

Functions assignable to the FUNC key

- RUN/STOP transfer ··· A
- Autotuning (AT) (Common to Input 1 and 2) ··· B
- Input 1_Autotuning (AT) ··· B
- Input 2_Autotuning (AT) ··· B
- Auto/Manual transfer (Common to Input 1 and 2) ··· A
- Input 1_Auto/Manual transfer ··· A
- Input 2_Auto/Manual transfer ··· A
- Remote/Local transfer (PV select transfer, 2-loop control/Differential temperature control) ··· A
- Control area Local/External transfer ··· A
- Interlock release ··· C
- Hold reset (Common to Input 1 and 2) ··· C
- Input 1_Hold reset ··· C
- Input 2_Hold reset ··· C
- Set data unlock/lock transfer ··· A
- Area jump ··· D

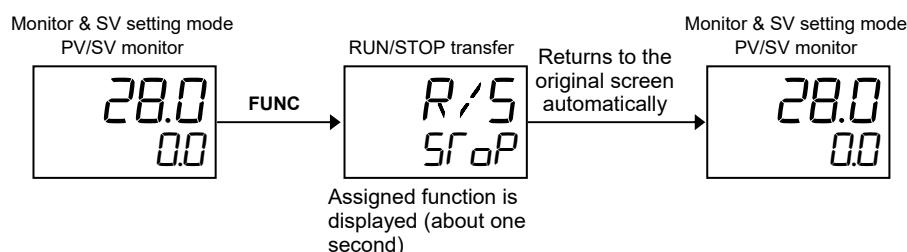
Explanation of key action

- A: Mode is changed for every press of the key.
- B: Function is turned on and off for every press of the key.
- C: Function is released or reset by pressing the key.
- D: Pressing the key switches the memory area to the preset area set in the Link area number in the Parameter setting mode. When the Link area number is not specified, a memory area with the number of the current control area number +1 will be used.

- For details of each function, see **5.2 Switching Functions Using Digital Inputs (DI) (P. 5-16)**.
- Selection of key action is possible from “Press once” and “Press and hold” to enable the switching.
- The function assigned to the FUNC key is accessible even when the Set data lock is used.
- The items set to “Fixed” at Fix Parameter Setting are disabled even if any function is assigned to the FUNC key.

● Displays when switched by the FUNC key

[Example] RUN/STOP switching is assigned to the FUNC key



■ Parameter setting

● FUNC key assignment

[Engineering Mode: Function block No. 11 ($F_{n/l}$)]

Parameter symbol	Data range	Factory set value
$F_{N.KY}$	0: Unused 1: RUN/STOP transfer 2: Autotuning (AT) (Common to Input 1 and 2) 3: Input 1_Autotuning (AT) 4: Input 2_Autotuning (AT) 5: Auto/Manual transfer (Common to Input 1 and 2) 6: Input 1_Auto/Manual transfer 7: Input 2_Auto/Manual transfer 8: Remote/Local transfer (PV select transfer, 2-loop control/Differential temperature control) 9: Control area Local/External transfer 10: Interlock release 11: Hold reset (Common to Input 1 and 2) 12: Input 1_Hold reset 13: Input 2_Hold reset 14: Set data unlock/lock transfer 15: Area jump	1

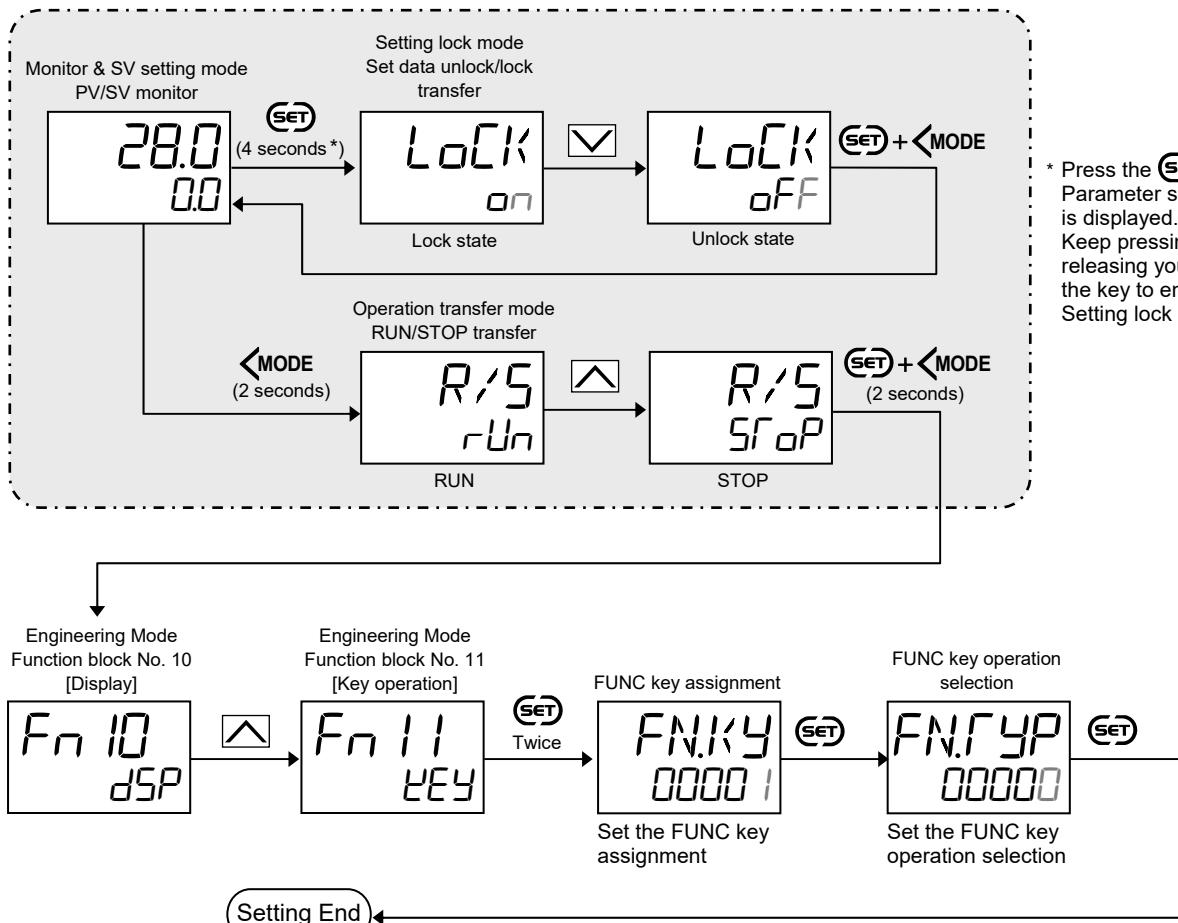
● FUNC key operation selection

[Engineering Mode: Function block No. 11 ($F_{n/l}$)]

Parameter symbol	Data range	Factory set value
$F_{N.FYP}$	0: Press once The function set at "FUNC key assignment" is activated upon a press of the FUNC key. 1: Press and hold The function set at "FUNC key assignment" is activated by holding the FUNC key pressed.	0

■ Setting procedure

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.

10.9 Restricting Key Operation (Set Data Lock)

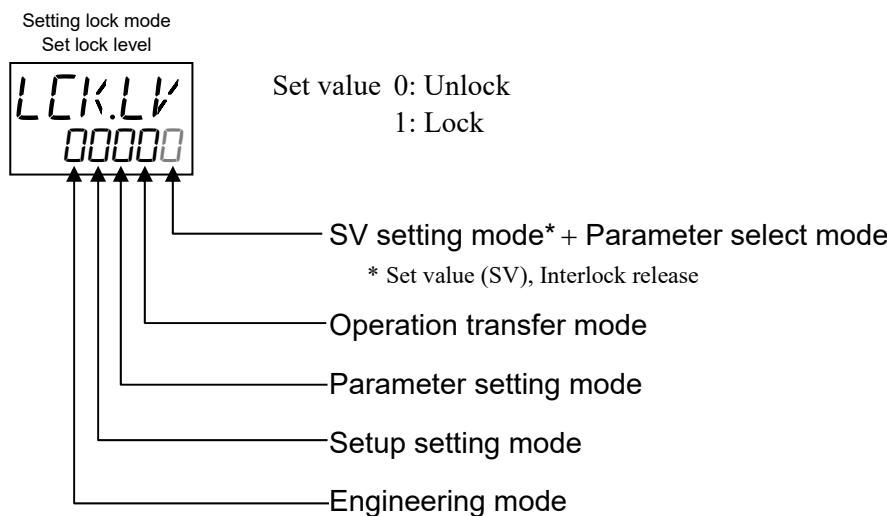
The Set data lock function limits access of unauthorized personnel to the parameters and prevents parameter change by mistake.

■ Description of function

The Set data lock function restricts changing values depending on the parameter mode. The Area lock restricts switching the Memory areas.

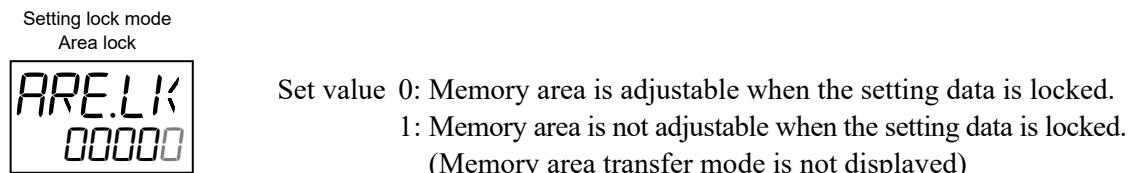
● Set lock level

Select the parameter mode to lock.



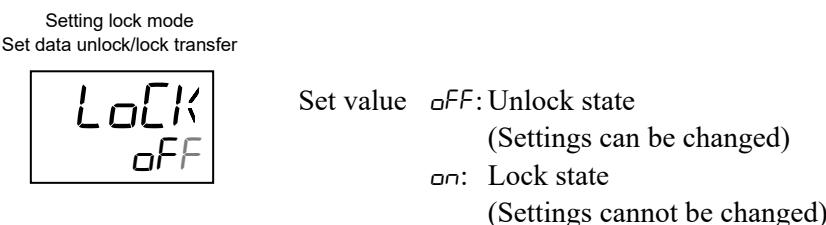
● Area lock

Select enable/disable Memory area switching.

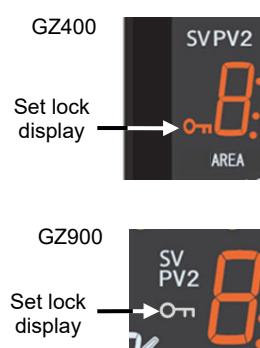


● Set data unlock/lock transfer

The parameter set with Set lock level and Area lock can be locked/unlocked.



The Set lock indicator lights on in the lock state.

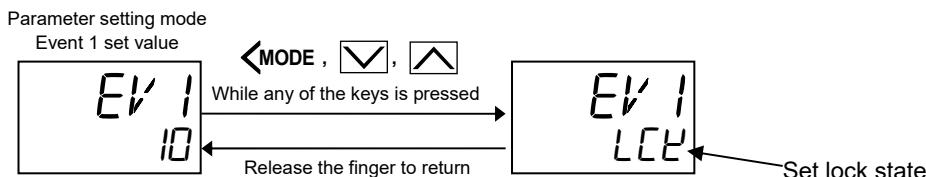


- When the set value was likely to be changed during the Set data lock state

A character will be shown on the Set value (SV) display unit to show the lock mode when any of or key is pressed.

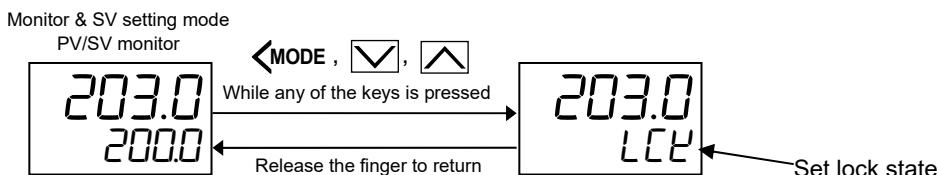
The “” is displayed only while the relevant key is pressed. Releasing the finger from the key will return the display to the original.

Example 1: “Event 1 set value” screen when the Parameter setting mode is locked.



Example 2: “PV/SV monitor” screen when the SV setting mode is locked

(Direct method is selected at Function block No. 11 in the Engineering mode)



Switching the Set data lock is available anytime irrespective of RUN or STOP state.



Parameter switching is available during the Set data lock state for checking the data.

When the SV setting mode is locked, the Set value (SV) setting screen in the SV setting mode will not be displayed.



Even during the Set data lock state, setting through the communication (optional function) and selection of functions by the FUNC key is possible. It should be noted that when the parameters in the Engineering mode are changed, the instrument must be stopped (or stay in the STOP mode).

■ Parameter setting

- Set data unlock/lock transfer
[Setting Lock Mode]

Parameter symbol	Data range	Factory set value
	: Unlock state : Lock state	

● Set lock level

[Setting Lock Mode]

Parameter symbol	Data range	Factory set value
<i>LCK.LV</i>	<p>Set Lock/Unlock at each digit.</p> <p>SV display 0: Unlock 1: Lock</p> <p>SV setting mode * + Parameter select mode * Set value (SV), Interlock release</p> <p>Operation transfer mode</p> <p>Parameter setting mode</p> <p>Setup setting mode</p> <p>Engineering mode</p>	00000

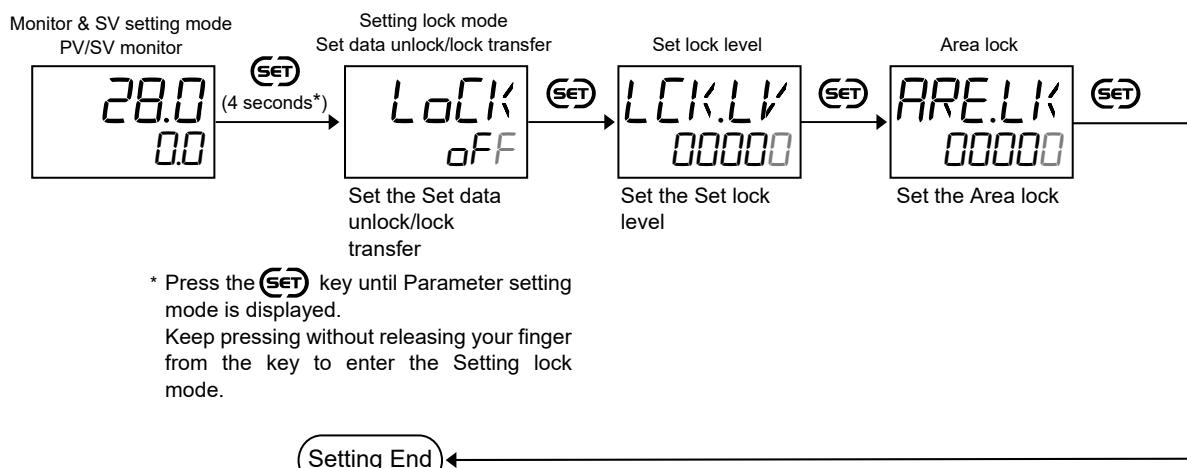
● Area lock

[Setting Lock Mode]

Parameter symbol	Data range	Factory set value
<i>ARE.LK</i>	<p>0: Memory area is adjustable when the setting data is locked. 1: Memory area is not adjustable when the setting data is locked. (Memory area transfer mode is not displayed)</p>	0

■ Setting procedure

Set data lock can be found in the Set data lock mode.



- Next parameter is displayed.
- Press **SET** and **<MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

10.10 Fixing the Set Value to a Specified Value (Fix Parameter Setting)

If excessive output is mistakenly given to the heater, the heater may be damaged. The use of Fix parameter function fixes the set values of the parameters that might cause a damage to the heater to the preset values, thus enabling to avoid operation error.

■ Description of function

The parameters "Fixed" at Fix Parameter Setting cannot be adjusted via the front keypad. In the communication those parameters become RO (Read Only), and adjustment of set values is no longer possible.

● Parameters and contents that can be fixed

- Autotuning (AT)Fixed to PID control
- Auto/Manual transfer.....Fixed to Auto mode
- Remote/Local transferFixed to Local mode
- Control response parameterFixed to Slow
- Hot/Cold startFixed to Hot start 2

● Conditions required to fix the parameter setting

• For Autotuning (AT)

Before setting the items to “Fixed” at Fixed Parameter setting, make sure that all of the following conditions are satisfied. Once you have set the items to “Fixed”, you are no longer able to change the set values except the following setting. Autotuning (AT) screens of Input 1 and Input 2 will not be displayed.

Mode	Items	Conditions required to fix the setting
Operation transfer mode	Input 1_Autotuning (AT) Input 2_Autotuning (AT)	PID control

• **For Auto/Manual transfer**

Before setting the items to “Fixed” at Fixed Parameter setting, make sure that all of the following conditions are satisfied. Once you have set the items to “Fixed”, you are no longer able to change the set values except the following setting. Auto/Manual transfer screens of Input 1 and Input 2 will not be displayed.

Mode		Items	Conditions required to fix the setting
Operation transfer mode		Input 1_Auto/Manual transfer Input 2_Auto/Manual transfer	Auto mode
Parameter Setting Mode	Parameter group No. 70	Input 1_Auto/Manual transfer selection (Area) for each memory area Input 2_Auto/Manual transfer selection (Area) for each memory area	One of the following: 0: No transfer 1: Auto mode (bumpless) 2: Auto mode (bump)
Engineering Mode	Function block No. 51	Input 1_Action (high) input error Input 1_Action (low) input error	One of the following: 0: Control continues (with the latest output) 2: Manipulated output value at input error (Auto mode)
	Function block No. 52	Input 2_Action (high) input error Input 2_Action (low) input error	One of the following: 0: Control continues (with the latest output) 2: Manipulated output value at input error (Auto mode)
	Function block No. 50	Hot/Cold start	One of the following: 0: Hot start 1 1: Hot start 2 3: STOP start

• For Remote/Local transfer

Before setting the items to “Fixed” at Fixed Parameter setting, make sure that all of the following conditions are satisfied. Once you have set the items to “Fixed”, you are no longer able to change the set values except the following setting. Remote/Local transfer screen will not be displayed.

Mode	Items	Conditions required to fix the setting
Operation transfer mode	Remote/Local transfer	When “Remote setting input” is selected at Select function for Input 2 0: Local mode
		When “Control with PV select” is selected at Select function for input 2 0: Input 1
		When “2-loop control/Differential temperature control” is selected at Select function for input 2 0: 2-loop control
Parameter Setting Mode	Parameter group No. 70	When “Remote setting input” is selected at Select function for Input 2 One of the following: 0: No transfer 1: Local mode
		When “Control with PV select” is selected at Select function for input 2 One of the following: 0: No transfer 1: Input 1
		When “2-loop control/Differential temperature control” is selected at Select function for input 2 One of the following: 0: No transfer 1: 2-loop control

• For Control response parameter

Before setting the items to “Fixed” at Fixed Parameter setting, make sure that all of the following conditions are satisfied. Once you have set the items to “Fixed”, you are no longer able to change the set values except the following setting.

Mode	Items	Conditions required to fix the setting
Parameter Setting Mode	Parameter group No. 51	Input 1_Control response parameter for each memory area
	Parameter group No. 52	Input 2_Control response parameter for each memory area

• For Hot/Cold start

Before setting the items to “Fixed” at Fixed Parameter setting, make sure that all of the following conditions are satisfied. Once you have set the items to “Fixed”, you are no longer able to change the set values except the following setting.

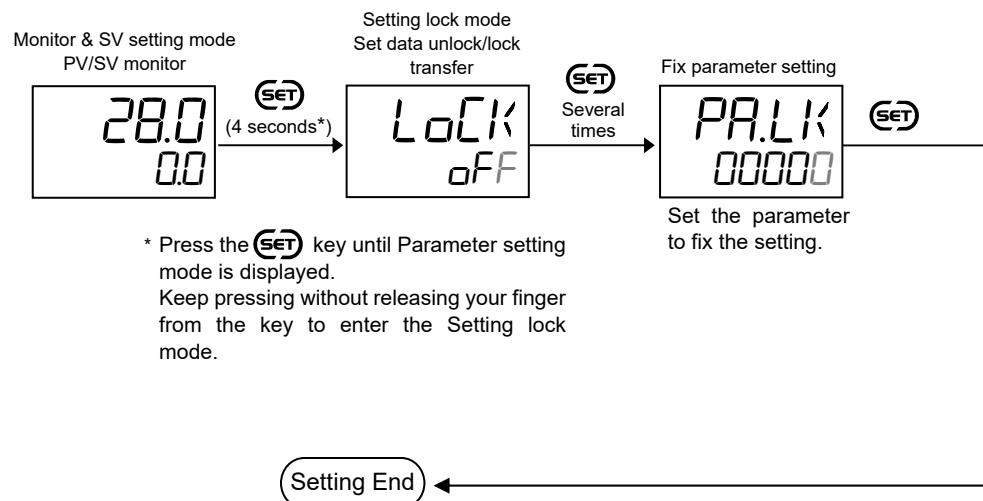
Mode	Items	Conditions required to fix the setting
Engineering Mode	Function block No. 50	1: Hot start 2

■ Parameter setting

● Fix parameter setting [Setting Lock Mode]

Parameter symbol	Data range	Factory set value
PRLK	<p>Set 0 or 1 for each digit.</p>	00000

■ Setting procedure



- Next parameter is displayed.
- Press **SET** and **MODE** keys simultaneously to return to the Measured value (PV)/Set value (SV) Monitor. (The **MONI** key may be pressed to return to the Measured value (PV)/Set value (SV) Monitor)

10.11 Initializing the Set Data

The set values can be initialized when all the set values need to be reset.

■ Description of function

When the pass code is entered on the “Initialize” screen in Function block No. 91 in the Engineering mode, all the set values are initialized and reset to the factory set values.

-  This action initializes and erases all the set values set so far. Record your setting separately if necessary. **3. PARAMETER LIST (P. 3-1)** has a field for user set values which can be used for recording.

■ Parameter setting

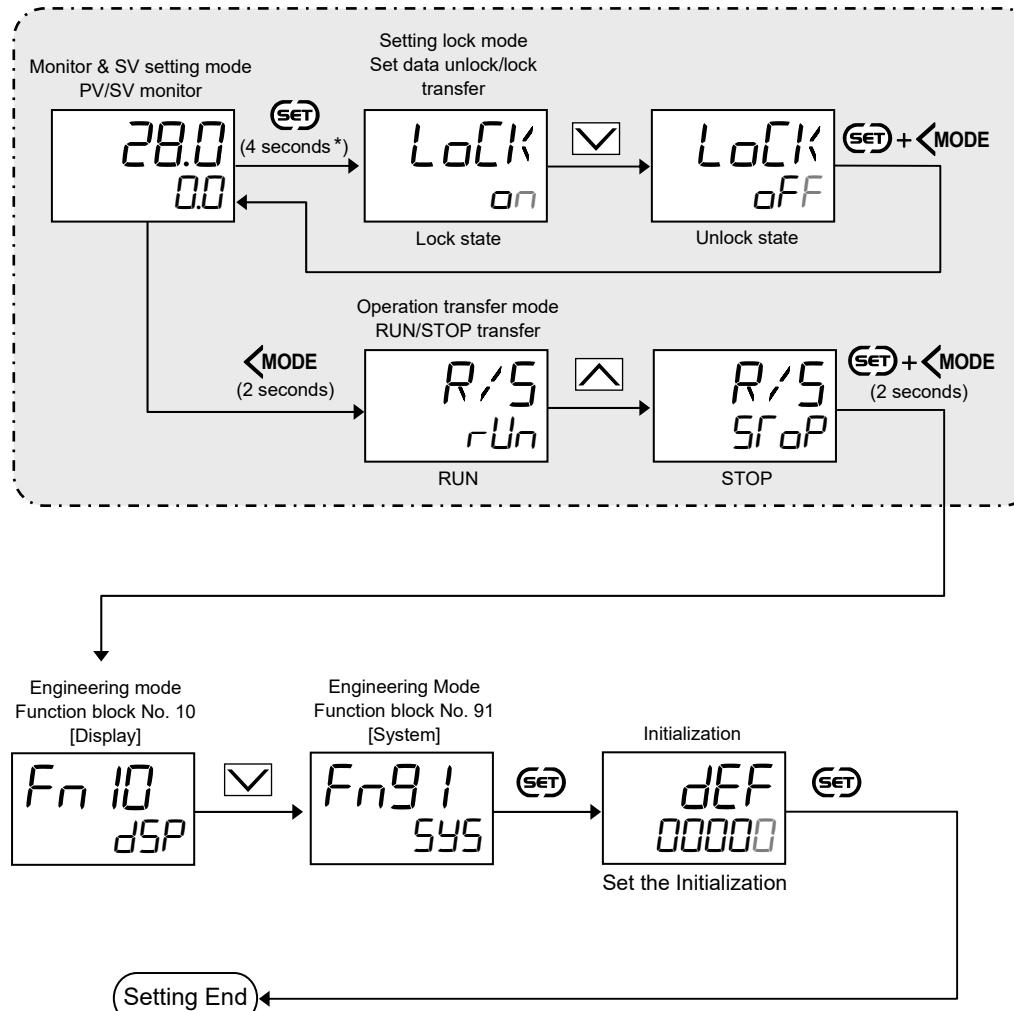
● Initialization

[Engineering Mode: Function block No. 91 (Fn9 !)]

Parameter symbol	Data range	Factory set value
<i>dEF</i>	1225: Start initialization Other values: Set values are maintained After the initialization, this instrument is restarted. This setting will automatically go back to zero.	0

■ Setting procedure

To enter the Engineering mode



* Press the **SET** key until Parameter setting mode is displayed.
Keep pressing without releasing your finger from the key to enter the Setting lock mode.

The first edition: DEC. 2019 [IMQ01]
The second edition: MAY 2023 [IMQ00]



RKC INSTRUMENT INC.

HEADQUARTERS: 16-6, KUGAHARA 5-CHOME, OHTA-KU TOKYO 146-8515 JAPAN

PHONE: 03-3751-9799 (+81 3 3751 9799)

E-mail: info@rkcinst.co.jp

Website: <https://www.rkcinst.co.jp/english/>

