Module Type Controller SRV

Temperature Control Module for Ethernet

V-TIO-P/V-TIO-Q **Instruction Manual**

IMS01P08-E5

Thank you for purchasing this RKC product. In order to achieve maximum performance and ensure proper operation of your new instrument, carefully read all the instructions in this manual. Please place the manual in a convenient location for easy reference.

SYMBOLS

WARNING: This mark indicates precautions that must be taken if there is danger of electric shock, fire, etc., which could result in loss of life or injury.



This mark indicates that if these precautions and operating procedures are not taken, damage to the instrument may result.



This mark indicates that all precautions should be taken for safe usage.



This mark indicates important information on installation, handling and operating procedures.



This mark indicates supplemental information on installation, handling and operating procedures.



This mark indicates where additional information may be located.

/! WARNING

- To prevent injury to persons, damage to instrument and equipment, a suitable external protection device shall be required.
- All wiring must be completed before power is turned on to prevent electric shock, fire or damage to instrument and equipment.
- This instrument must be used in accordance with the specifications to prevent fire or damage to instrument and equipment.
- This instrument is not intended for use in locations subject to flammable or explosive gases.
- Do not touch high-voltage connections such as power supply terminals, etc. to avoid electric shock.
- RKC is not responsible if this instrument is repaired, disassembled modified or by other factory-approved personnel. Malfunction can occur and warranty is void under these conditions.

CAUTION

- This product is intended for use with industrial machines, test and measuring equipment. (It is not designed for use with medical equipment and nuclear energy.)
- This is a Class A instrument. In a domestic environment, this instrument may cause radio interference, in which case the user may be required to take additional measures.
- This instrument is protected from electric shock by reinforced insulation. Provide reinforced insulation between the wire for the input signal and the wires for instrument power supply, source of power and loads.

- Be sure to provide an appropriate surge control circuit respectively for the following:
- If input/output or signal lines within the building are longer than 30 meters.
- If input/output or signal lines leave the building, regardless the length.
- This instrument is designed for installation in an enclosed instrumentation panel. All high-voltage connections such as power supply terminals must be enclosed in the instrumentation panel to avoid electric shock by operating personnel.
- All precautions described in this manual should be taken to avoid damage to the instrument or equipment.
- All wiring must be in accordance with local codes and regulations.
- All wiring must be completed before power is turned on to prevent electric shock, instrument failure, or incorrect action. The power must be turned off before repairing work for input break and output failure including replacement of sensor, contactor or SSR, and all wiring must be completed before power is turned on again.
- To prevent instrument damage as a result of failure, protect the power line and the input/output lines from high currents with a suitable overcurrent protection device with adequate breaking capacity such as fuse, circuit breaker, etc.
- Prevent metal fragments or lead wire scraps from falling inside instrument case to avoid electric shock, fire or malfunction.
- Tighten each terminal screw to the specified torque found in the manual to avoid electric shock, fire or malfunction.
- For proper operation of this instrument, provide adequate ventilation for heat dispensation.
- Do not connect wires to unused terminals as this will interfere with proper operation of the instrument.
- Turn off the power supply before cleaning the instrument.
- Do not use a volatile solvent such as paint thinner to clean the instrument. Deformation or discoloration will occur. Use a soft, dry cloth to remove stains from the instrument.
- To avoid damage to instrument display, do not rub with an abrasive material or push front panel with a hard object.
- When high alarm with hold action/re-hold action is used for Event function, alarm does not turn on while hold action is in operation. Take measures to prevent overheating which may occur if the control device fails.

NOTICE

- This manual assumes that the reader has a fundamental knowledge of the principles of electricity, process control, computer technology and communications.
- The figures, diagrams and numeric values used in this manual are only for purpose of illustration.
- RKC is not responsible for any damage or injury that is caused as a result of using this instrument, instrument failure or indirect damage.
- RKC is not responsible for any damage and/or injury resulting from the use of instruments made by imitating this instrument.
- Periodic maintenance is required for safe and proper operation of this instrument. Some components have a limited service life, or characteristics that change over time.
- Every effort has been made to ensure accuracy of all information contained herein. RKC makes no warranty expressed or implied, with respect to the accuracy of the information. The information in this manual is subject to change without prior notice.
- No portion of this document may be reprinted, modified, copied, transmitted, digitized, stored, processed or retrieved through any mechanical, electronic, optical or other means without prior written approval from RKC.

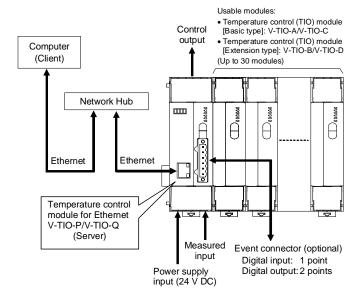
1. OUTLINE

The temperature control module for Ethernet V-TIO-P/V-TIO-Q has one modular connector (RJ-45) for connection to Ethernet. This module conforms to Modbus/TCP (Modbus protocol) operating on TCP/IP of Ethernet.

One this module enables temperature control corresponding to two channels. It has power supply terminals in addition to temperature control input and output terminals.

In addition, one digital input (DI) point and two digital output (DO) points can be optionally added.

All data are set by communication.



The data request side is called "client" (such as computer) and the data response (supply) side is called "server" (SRV).

Basically, one client corresponds to one server (SRV) (i.e. one to one). However, one client can communicate with two or more servers depending on the program on the client side, but two or more clients cannot communicate with one server.

For details of Ethernet communication, refer to the Module Type Controller SRV Ethernet [Modbus/TCP] Communication Instruction Manual (IMS01P09-EII).

2. PRODUCT CHECK

Before using this product, check each of the following:

- Model code
- Check that all of the accessories delivered are complete.
- Check that there are no scratch or breakage in external appearance (case, front panel, or terminal, etc).

(1) Type

- P: Module for Ethernet, Heat control
- Q: Module for Ethernet, Heat/Cool control

(2) Control action

[For Heat control]

- F: PID action with autotuning (AT) (reverse action)
- D: PID action with autotuning (AT) (direct action)

[For H eat/Cool control]

- B: Heat/Cool PID action with autotuning (AT) (air cooling)
- W: Heat/Cool PID action with autotuning (AT) (water cooling)

(3) Input range (Each channel common code)

[Thermocouple input]

[memocoupic input]				
Type	Code	Range Code Range		Range
K	K02	0 to 400 °C KB9 32 to 75		32 to 752 °F
	K04	0 to 800 °C	KB8	32 to 1472 °F
	K16	−200 to +1372 °C	KB7	-328 to +2501 °F
	K09	0.0 to 400.0 °C	KC2	32.0 to 752.0 °F
	K35	-200.0 to +400.0 °C	KC1	-328.0 to +752.0 °F
J	J02	0 to 400 °C	JC2	32 to 752 °F
	J04	0 to 800 °C	JC1	32 to 1472 °F
	J15	-200 to +1200 °C	JB9	-328 to +2192 °F
	J09	0.0 to 400.0 °C	JC4	32.0 to 752.0 °F
	J27	-200.0 to +400.0 °C	JC3	-328.0 to +752.0 °F
Т	T08	0 to 400 °C	TB9	32 to 752 °F
	T09	0 to 200 °C	TC1	32 to 392 °F
	T16	−200 to +400 °C	TB8	-328 to +752 °F
	T06	0.0 to 400.0 °C	TC3	32.0 to 752.0 °F
	T19	-200.0 to +400.0 °C	TC2	-328.0 to +752.0 °F
E	E01	0 to 800 °C	EA8	32 to 1472 °F
	E02	0 to 1000 °C	EA7	32 to 1832 °F
S	S05	0 to 1768 °C	SA6	32 to 3214 °F
R	R06	0 to 1768 °C	RA6	32 to 3214 °F
N	N02	0 to 1300 °C	NA6	32 to 2372 °F
В	B03	0 to 1800 °C	BB1	32 to 3272 °F
PLⅡ	A02	0 to 1390 °C	AA6	32 to 2534 °F
W5Re/ W26Re	W03	0 to 2300 °C	WA9	32 to 4172 °F

[RTD input]

<u></u>	free mbed					
Type	Code	Range	Code	Range		
Pt100	D17	0 to 400 °C	DC5	32 to 752 °F		
	D33	0 to 850 °C	DC4	32 to 1562 °F		
	D16	0.0 to 400.0 °C	DC7	32.0 to 752.0 °F		
	D28	-200.0 to +400.0 °C	DC6	-328.0 to +752.0 °F		
JPt100	P17	0 to 400 °C	PC5	32 to 752 °F		
	P23	0 to 600 °C	PC4	32 to 1112 °F		
	P16	0.0 to 400.0 °C	PC7	32.0 to 752.0 °F		
	P28	-200.0 to +400.0 °C	PC6	-328.0 to +752.0 °F		

[Voltage/Current input]

		<u> </u>		
	Code	Type	Code	Type
Voltage		0 to 100 mV DC		0 to 5 V DC
_	501	0 to 10 V DC	601	1 to 5 V DC
Current	701	0 to 20 mA DC	801	4 to 20 mA DC

(4) Control output (CH1), (5) Control output (CH2)

M: Relay contact output V: Voltage pulse output 0/12 V DC 4: 0 to 5 V DC 5: 0 to 10 V DC 6: 1 to 5 V DC

7: 0 to 20 mA DC 8: 4 to 20 mA DC

(6) Event input (DI) [Optional]

N: None

1: Control RUN/STOP

2: Event interlock release

(7) (8) Event output 1 (DO1) [Optional] * (9) (10) Event output 2 (DO2) [Optional] *

[Code of (7)]

N: None 1: Channel 1

[Code of (9)]

N: None 2: Channel 2

[Code of (8) and (10)]

N: None A: Deviation high B: Deviation low C: Deviation high/low D: Band

E: Deviation high with hold action F: Deviation low with hold action

G: Deviation high/low with hold action H: Process high

J: Process low K: Process high with hold action

L: Process low with hold action

Q: Deviation high with re-hold action

R: Deviation low with re-hold action

T: Deviation high/low with re-hold action

P: Heater break alarm (HBA) 1: Control loop break alarm (LBA)

2: Burnout 3: Temperature rise completion

* When "N" is selected in (7) or (9), (8) or (10) becomes "N."

(11) CT type (Each channel common code)

P: CTL-6-P-N S: CTL-12-S56-10L-N

(12) Communication protocol

1: Modbus/TCP

2 IMS01P08-E5

(13) Version symbol

No code: For Japanese domestic market
/Y: For International market



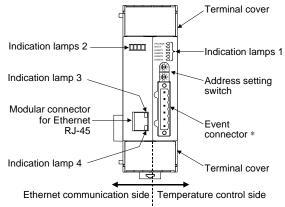
- For Heat/Cool PID control (V-TIO-Q), input channel 2 becomes unused.
- For Heat/Cool PID control (V-TIO-Q), Control output 1 corresponds to the heating output and Control output 2 corresponds to the cooling output.
- Heater break alarm (HBA) function cannot be used when control output is Voltage/Current output.
- Control loop break alarm (LBA) function cannot be used when control type is Heat/Cool PID control (V-TIO-Q).

■ Accessories	
End Plate	2
Joint connector cover	2
V-TIO-P/V-TIO-Q Instruction Manual (IMS01P08-E5)	1

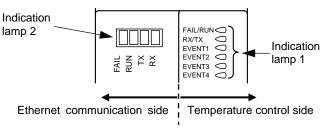


If any of the products are missing, damaged, or if your manual is incomplete, please contact RKC sales office or the agent.

3. PARTS DESCRIPTION



* Installed when provided with the event input or output (optional).



[Indication lamps 1]

• FAIL/RUN (for temperature control)

When normally: Green lamp: ON (RUN)
When abnormally: Red lamp: ON (FAIL)
During self-diagnostic error: Green lamp: flashing

RX/TX (for internal communication)

During data send and receive: Green lamp: ON

EVENT 1 to 4

Display various states by setting.

During ON state: A green lamp turns on

Display contents

Event 1 state, Event 2 state, Comprehensive event state, Output state, and Control state

[Indication lamps 2]

• FAIL (for Ethernet communication)

When normally: Red lamp: OFF When abnormally: Red lamp: ON

RUN (for Ethernet communication)

When normally: Green lamp: ON

When abnormally [Module configuration error, input error]:

Green lamp: slow flashing

Data collection just after the power is turned on:

Green lamp: rapid flashing

TX

During data send: Green lamp: flashing

RX

During data receive: Green lamp: flashing

[Indication lamps 3]

Link

10BASE-T link: Amber lamp: ON 100BASE-TX link: Green lamp: ON

[Indication lamps 4]

Activity

Half-duplex; activity: Amber lamp: Momentary ON Full-duplex; activity: Green lamp: Momentary ON

4. COMMUNICATION SETTING

Set communication setting before mounting and wiring of SRV.

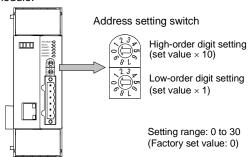
CAUTION

Do not separate the module mainframe from the terminal base with the power turned on. If separated, adjusted data may be destroyed; control be stopped, and no return can be made.

4.1 Module Address Setting

Set a module address. For this setting, use a small slotted screwdriver.

When using two or more modules, set the desired address to each module.



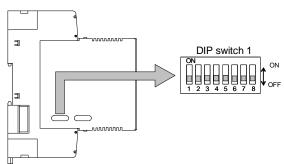


To avoid problems or malfunction, do not duplicate an address on the same communication line.

4.2 Internal Communication Setting

■ Ethernet communication side setting

Set the communication speed for internal communication by using the DIP switch 1.



Left side view (Ethernet communication side)

1	2	Communication speed
OFF	OFF	38400 bps
ON	OFF	9600 bps
OFF	ON	19200 bps
ON	ON	38400 bps

Factory set value: 38400 bps



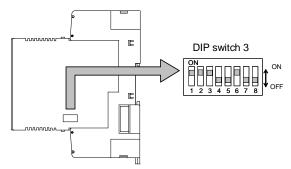
• Switch No. 3 to 8: OFF fixed

(Do not change this one)

 The communication speed sets the same value as a temperature control side (DIP switch 3) setting.

■ Temperature control side setting

Set the communication speed and data bit configuration for internal communication by using the DIP switch 3.



Right side view (temperature control side)

1	2	Communication speed	
OFF	OFF	Do not set this one	
ON	OFF	9600 bps	
OFF	ON	19200 bps	
ON	ON	38400 bps	

Factory set value: 38400 bps

3	4	5	Data bit configuration	
OFF	OFF	OFF		
OFF	OFF	ON	Do not set this one	
OFF	ON	OFF	Do not set this one	
OFF	ON	ON		
ON	OFF	OFF	Data 8-bit, Without parity, Stop 1-bit	
ON	OFF	ON		
ON	ON	OFF	Do not set this one	
ON	ON	ON		

Factory set value (Fixed): Data 8-bit, without parity, Stop 1-bit



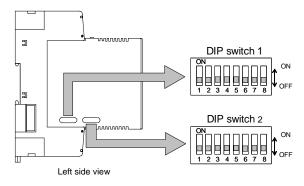
• Switch No. 6: ON fixed (Do not change this one) Switch No. 7 and 8:

OFF fixed (Do not change this one)

 When connecting two or more modules (V-TIO-A, V-TIO-B, V-TIO-C or V-TIO-D) to the V-TIO-P/V-TIO-Q module, match all of their communication speed and data bit configuration settings with the internal settings of the V-TIO-P/V-TIO-Q module.

4.3 Other Setting

It is possible to set the IP address using DIP switch 1 and DIP switch 2.



For details of IP address setting by switch, refer to the Module Type Controller SRV Ethernet [Modbus/TCP] Communication Instruction Manual (IMS01P09-E□).

5. MOUNTING

WARNING

To prevent electric shock or instrument failure, always turn off the power before mounting or removing the instrument.

5.1 Mounting Cautions

- (1) This instrument is intended to be used under the following environmental conditions. (IEC61010-1) [OVERVOLTAGE CATEGORY II, POLLUTION DEGREE 2]
- (2) Use this instrument within the following environment conditions:
- Allowable ambient temperature: -10 to +50 °C
- Allowable ambient humidity: 5 to 95 %RH
- (Absolute humidity: MAX. W. C 29 g/m³ dry air at 101.3 kPa)
- Installation environment conditions: Indoor use

Altitude up to 2000 m

- (3) Avoid the following when selecting the mounting location.
- Rapid changes in ambient temperature, which may cause condensation.
- Corrosive or inflammable gases.
- Direct vibration or shock to the mainframe.
- Water, oil, chemicals, vapor or steam splashes.
- Excessive dust, salt or iron particles.
- Excessive induction noise, static electricity, magnetic fields or noise.
- Direct air flow from an air conditioner.
- Exposure to direct sunlight.
- · Excessive heat accumulation.
- (4) Mount this instrument in the panel considering the following conditions:
- Provide adequate ventilation space so that heat does not build up.
- Do not mount this instrument directly above equipment that generates large amount of heat (heaters, transformers, semi-conductor functional devices, large-wattage resistors.)
- If the ambient temperature rises above 50 °C, cool this instrument with a forced air fan, cooler, etc. Cooled air should not blow directly on this instrument.
- In order to improve safety and the immunity to withstand noise, mount this instrument as far away as possible from high voltage equipment, power lines, and rotating machinery.

High voltage equipment:

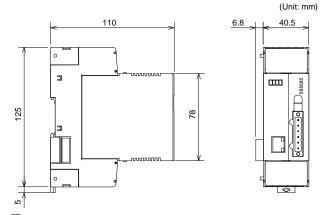
Do not mount within the same panel.

Separate at least 200 mm. Power lines:

Rotating machinery: Separate as far as possible.

- Ensure at least 50 mm space on top and bottom of the control unit for maintenance and environmental reasons.
- (5) In case this instrument is connected to a supply by means of a permanent connection a switch or circuit-breaker shall be included in the installation. This shall be in close proximity to the equipment and within easy reach of the operator. It shall be marked as the disconnecting device for the equipment.

5.2 Dimensions



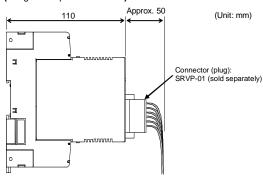
The above figure shows when provided with the event input/output connector, but the same also when not provided with the connector.

4

Depth in connector mounting

Conduct installation in consideration of the sizes of the connector and cable when connector-connected.

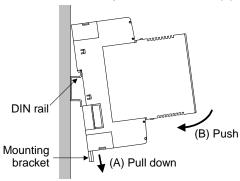
[Usage example of SRVP-01]



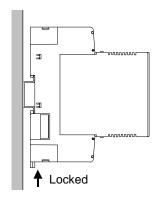
5.3 DIN rail Mounting

■ Mounting procedures

Pull down the mounting bracket at the bottom of the module (A).
 Attach the hooks on the top of the module to the DIN rail and push the lower section into place on the DIN rail (B).

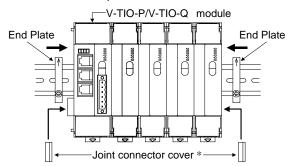


Slide the mounting bracket up to secure the module to the DIN rail.



■ End Plate mounting

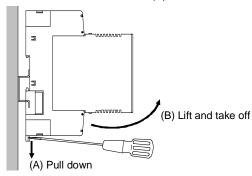
Hold tight both ends of the modules jointed together with the end plates and then fix the end plates with screws. Even if only one V-TIO-P/V-TIO-Q module is used, also hold tight both ends of the module with the end plates.



* For the conservation of the contact of connector, install a joint connector cover in module of both ends.

■ Removing procedures

Pull down a mounting bracket with a slotted screwdriver (A). Lift the module from bottom, and take it off (B).



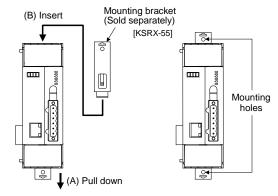
5.4 Panel Mounting

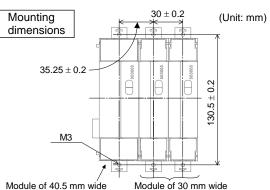
■ Mounting procedures

- Pull down the mounting bracket (A) until locked and that a mounting hole appears.
- Prepare one mounting bracket per module (B) sold separately (KSRX-55) and then insert it in the rear of the terminal board at top of the module until locked but a mounting hole does not disappear.
- Mount each module directly on the panel with screws which are inserted in the mounting holes of the top and bottom mounting brackets.

Recommended tightening torque: 0.3 N·m (3 kgf·cm)

The customer needs to provide the M3 size screws. Select the screw length that matches the mounting panel.





5.5 Jointing Each Module

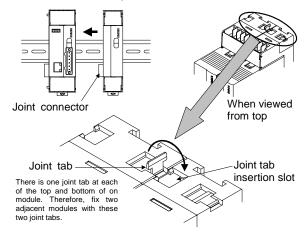
Up to 30 modules (V-TIO-A, V-TIO-B, V-TIO-C or V-TIO-D) can be connected to one module (V-TIO-P or V-TIO-Q). Joint these modules according to the following procedure.

Jointing procedures

- Mount the modules on the DIN rail and then joint these modules together with the joint connector while sliding the relevant module.
- Lift each of the joint tabs located at the top and bottom of the module and then insert it in the slot of the adjacent module to fix these two modules.

IMS01P08-E5 5

For panel mounting, first joint each module and then mount it on the panel.



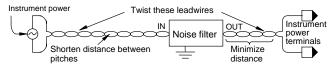
6. WIRING



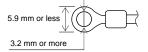
To prevent electric shock or instrument failure, do not turn on the power until all wiring is completed. Make sure that the wiring is correct before applying power to the instrument.

6.1 Wiring Cautions

- For thermocouple input, use the appropriate compensation wire.
- For RTD input, use low resistance lead wire with no difference in resistance between the three lead wires.
- To avoid noise induction, keep input signal wire away from instrument power line, load lines and power lines of other electric equipment.
- Signal connected to Voltage input and Current input shall be low voltage defined as "SELV" circuit per IEC 60950-1.
- If there is electrical noise in the vicinity of the instrument that could affect operation, use a noise filter.
 - Shorten the distance between the twisted power supply wire pitches to achieve the most effective noise reduction.
 - Always install the noise filter on a grounded panel. Minimize the wiring distance between the noise filter output and the instrument power supply terminals to achieve the most effective noise reduction.
 - Do not connect fuses or switches to the noise filter output wiring as this will reduce the effectiveness of the noise filter.

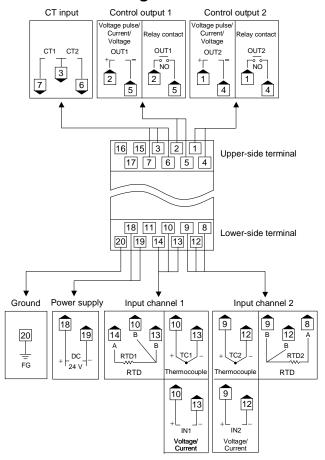


- Power supply wiring must be twisted and have a low voltage drop.
- For an instrument with 24 V power supply input, supply power from "SELV" circuit defined as IEC 60950-1.
- A suitable power supply should be considered in the end-use equipment. The power supply must be in compliance with a limited-energy circuits (maximum available current of 8 A).
- In the maximum configuration (extension up to 31 modules) the 24 V DC supplied equipment may draw up to 4 A. The power supply shall be capable of delivering at least 4 A.
- Use the solderless terminal appropriate to the screw size.
 - Screw size: M3 x 6
 - Recommended tightening torque: 0.4 N·m [4 kgf·cm]
 - Specified solderless terminals: With isolation



 Make sure that during field wiring parts of conductors can not come into contact with adjacent conductive parts.

6.2 Terminal Configuration





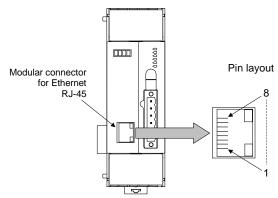
- For Heat/Cool PID control (V-TIO-Q), Input channel 2 becomes unused.
- For Heat/Cool PID control (V-TIO-Q), Control output 1 corresponds to the heating output and Control output 2 corresponds to the cooling output.
- Heater break alarm (HBA) function cannot be used when control output is Voltage/Current output.
- Control loop break alarm (LBA) function cannot be used when control type is Heat/Cool PID control (V-TIO-Q).



Terminal No. 11, 15, 16 and 17 are not used. Do not connect to these terminals.

6.3 Pin Layout of Connector

■ Modular connector for Ethernet



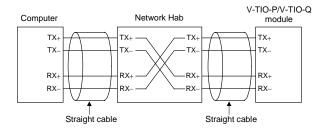
6 IMS01P08-E5

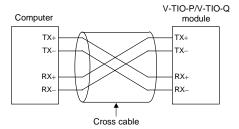
Pin No.	Signal name	Symbol
1	Send data +	TX+
2	Send data -	TX-
3	Receive data +	RX+
4	Unused	_
5	Unused	
6	Receive data –	RX-
7	Unused	
8	Unused	



Customer must provide the Ethernet communication cable. In addition, use straight cables when connected to the network hub, and use a cross cable when directly connected to the computer.

However, cables different from the above cables may be used depending on the connecting device used. Therefore follow the instructions for each connecting device.

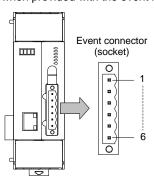




Use the RJ-45 type of modular connector as the connector plugged into the V-TIO-P/V-TIO-Q module.

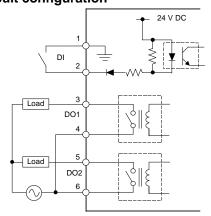
■ Event connector (optional)

This is a connector installed in the V-TIO-P/V-TIO-Q module only when provided with the event input (DI) or the event output (DO).



Pin No.	Description		
1	Digital input (DI) (-)		
2	Digital input (DI) (+)		
3	Digital output (DO) 1		
4	(Relay contact output)		
5	Digital output (DO) 2		
6	(Relay contact output)		

Circuit configuration



Attention in Connector (plug) Wiring

• Use the following connector (plug) as that connected to the event input/output connector. Connector (plug) is sold separately.

SRVP-01 (Front-screw type) SRVP-02 (Side-screw type)

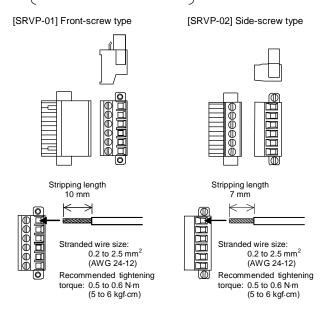
- The lead wires use the stranded wire.
- Use the stranded wire from size 0.2 to 2.5 mm² (AWG 24-12).

Stripping length is as follows.

SRVP-01: 10 mm SRVP-02: 7 mm

• Recommended tightening torque of the lead wire in the connector (plug): 0.5 to 0.6 N·m (5 to 6 kgf·cm)

> Screw size: SRVP-01: M2.5 SRVP-02: M3



7. SPECIFICATIONS

■ Inputs

Number of inputs: 2 points

> Isolated between each channel: Thermocouple input, Voltage (low) input Not isolated between each channel: RTD input, Voltage (high) input,

Current input

Input type:

· Thermocouple: K, J, T, S, R, E, B, N (JIS-C1602-1995)

PLII (NBS)

W5Re/W26Re (ASTM-E988-96)

• RTD: Pt100 (JIS-C1604-1997)

JPt100 (JIS-C1604-1989, Pt100 of

JIS-C1604-1981)

• Voltage (low): 0 to 100 mV DC

· Voltage (high): 0 to 5 V DC, 0 to 10 V DC, 1 to 5 V DC

Current: 0 to 20 mA DC, 4 to 20 mA DC

Input impedance: 250 Ω)

Sampling cycle: 500 ms

PV bias: -Input span to +Input span

CT input: 2 points

0.0 to 30.0 A (CTL-6P-N) or

0.0 to 100.0 A (CTL-12-S56-10L-N)

7 IMS01P08-E5

■ Outputs

Number of outputs: 2 points

(Isolated between input and output, and

between output and power supply)

Output type:

• Relay contact: 250 V AC, 3 A (Resistive load)

1a contact

Electrical life: 300,000 times or more

(Rated load)

0/12 V DC · Voltage pulse:

(Load resistance 600 Ω or more) 0 to 20 mA DC, 4 to 20 mA DC

• Current: (Load resistance 600 Ω or less)

Voltage: 0 to 5 V DC, 0 to 10 V DC, 1 to 5 V DC

(Load resistance 1 $k\Omega$ or more)

■ Control action

Number of controls: 2 points

Brilliant PID control Control method:

> Reverse action or direct action is selectable (Specify when ordering) Heat/Cool control is selectable (Specify when ordering)

Additional function: Autotuning function

■ Events

2 points/channel Number of events: Event type: Temperature event:

Deviation high, Deviation low, Deviation high/low, Band, Process high, Process low Heater break alarm (HBA). Control loop break alarm (LBA), Burnout, Temperature rise completion

Optional

Event input (DI)

Number of inputs: 1 point

Input type: Dry contact input 24 V DC (Rated) Input voltage: Approx. 6 mA Input current: Input details: Control RUN/STOP.

> Event interlock release (Specify when ordering)

Event output (DO)

Number of outputs: 2 points

Output type: Relay contact output

250 V AC, 1 A (Resistive load)

1a contact

Electrical life: 300,000 times or more

(Rated load)

Output details: Temperature event, Heater break alarm

(HBA). Control loop break alarm (LBA). Burnout, Temperature rise completion

(Specify when ordering)

■ Ethernet communication

Physical layer: Ethernet

10BASE-T/100BASE-TX automatic

recognition

Modbus/TCP Application layer:

Communication data: Based on Serial communication (Modbus)

map

Connector type: **RJ-45**

Maximum connections:

Up to 30 temperature control modules can be connected to one V-TIO-P/V-TIO-Q

module

■ Others

Power supply voltage: 21.6 to 26.4 V DC

(Including power supply voltage variation)

Rating: 24 V DC

Current consumption: With event input/output:

220 mA max./module

Without event input/output:

200 mA max./module

Rush current: 12 A/module max.

Allowable ambient temperature:

-10 to +50 °C

Allowable ambient humidity:

5 to 95 %RH Absolute humidity:

MAX.W.C 29 g/m3 dry air at 101.3 kPa

With event input/output: Weight:

Approx. 270 g Without event input/output:

Approx. 260 g

■ Standard

Safety standard: UL61010-1

cUL: CAN/CSA-C22.2 No.61010-1

CE marking: LVD: EN61010-1

OVERVOLTAGE CATEGORYII, POLLUTION DEGREE 2,

Class II (Reinforced insulation)

EMC: EN61326-1

RCM: EN55011

Ethernet is a registered trademark of Xerox Corp.

Modbus is a registered trademark of Schneider Electric.

Company names and product names used in this manual are the trademarks or registered trademarks of the respective companies.

The first edition: JUN. 2004 [IMQ00] The fifth edition: FEB. 2016 [IMQ00]



HEADQUARTERS: 16-6, KUGAHARA 5-CHOME, OHTA-KU TOKYO 146-8515 JAPAN E-mail: info@rkcinst.co.jp

Website: http://www.rkcinst.com/ FAX: 03-3751-8585 (+81 3 3751 8585)

FEB. 2016 IMS01P08-E5