



*Ethernet Modbus/TCP
Communication Converter*

COM-ME-1
[For SRZ]

Instruction Manual

NOTICE

- This manual assumes that the reader has a fundamental knowledge of the principles of electricity, process control, computer technology and communications.
- The figures, diagrams and numeric values used in this manual are only for explanation purpose.
- RKC is not responsible for any damage or injury that is caused as a result of using this instrument, instrument failure or indirect damage.
- RKC is not responsible for any damage and/or injury resulting from the use of instruments made by imitating this instrument.
- Periodic maintenance is required for safe and proper operation of this instrument. Some components have a limited service life, or characteristics that change over time.
- Every effort has been made to ensure accuracy of all information contained herein. RKC makes no warranty, expressed or implied, with respect to the accuracy of the information. The information in this manual is subject to change without prior notice.
- No portion of this document may be reprinted, modified, copied, transmitted, digitized, stored, processed or retrieved through any mechanical, electronic, optical or other means without prior written approval from RKC.

- Modbus is a registered trademark of Schneider Electric.
- The name of each programmable controller (PLC) means the products of each manufacturer.
- Company names and product names used in this manual are the trademarks or registered trademarks of the respective companies.

Safety Precautions

■ Pictorial Symbols (safety symbols)

Various pictorial symbols are used in this manual to ensure safe use of the product, to protect you and other people from harm, and to prevent damage to property. The symbols are described below.

Be sure you thoroughly understand the meaning of the symbols before reading this manual.



WARNING

: This mark indicates precautions that must be taken if there is danger of electric shock, fire, etc., which could result in loss of life or injury.



CAUTION

: This mark indicates that if these precautions and operating procedures are not taken, damage to the instrument may result.



: This mark indicates that all precautions should be taken for safe usage.



WARNING

- To prevent injury to persons, damage to the instrument and the equipment, a suitable external protection device shall be required.
- All wiring must be completed before power is turned on to prevent electric shock, fire or damage to the instrument and the equipment.
- This instrument must be used in accordance with the specifications to prevent fire or damage to the instrument and the equipment.
- This instrument is not intended for use in locations subject to flammable or explosive gases.
- Do not touch high-voltage connections such as power supply terminals, etc. to avoid electric shock.
- RKC is not responsible if this instrument is repaired, modified or disassembled by other than factory-approved personnel. Malfunction may occur and warranty is void under these conditions.

CAUTION

- This product is intended for use with industrial machines, test and measuring equipment. (It is not designed for use with medical equipment and nuclear energy plant.)
- In a domestic environment, this instrument may cause radio interference, in which case the user may be required to take additional measures.
- Provide reinforced insulation between the wire for the input signal and the wires for instrument power supply, source of power and loads.
- Be sure to provide an appropriate surge control circuit respectively for the following:
 - If input/output or signal lines within the building are longer than 30 meters.
 - If input/output or signal lines leave the building, regardless the length.
- This instrument is designed for installation in an enclosed instrumentation panel. All high-voltage connections such as power supply terminals must be enclosed in the instrumentation panel to avoid electric shock to operating personnel.
- All precautions described in this manual should be taken to avoid damage to the instrument or equipment.
- If the equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.
- All wiring must be in accordance with local codes and regulations.
- To prevent instrument damage as a result of failure, protect the power line and the input/output lines from high currents with a suitable overcurrent protection device with adequate breaking capacity such as a fuse, circuit breaker, etc.
- A malfunction in this product may occasionally make control operations impossible or prevent alarm outputs, resulting in a possible hazard. Take appropriate measures in the end use to prevent hazards in the event of malfunction.
- Prevent metal fragments or lead wire scraps from falling inside instrument case to avoid electric shock, fire or malfunction.
- Tighten each terminal screw to the specified torque found in the manual to avoid electric shock, fire or malfunction.
- For proper operation of this instrument, provide adequate ventilation for heat dissipation.
- Do not connect wires to unused terminals as this will interfere with proper operation of the instrument.
- Turn off the power supply before cleaning the instrument.
- Do not use a volatile solvent such as paint thinner to clean the instrument. Deformation or discoloration may occur. Use a soft, dry cloth to remove stains from the instrument.
- Do not connect modular connectors to telephone line.

For Proper Disposal

When disposing of each part used for this instrument, always follows the procedure for disposing of industrial wastes stipulated by the respective local community.

Symbols

■ Pictorial Symbols (safety symbols)



NOTE : This mark indicates important information on installation, handling and operating procedures.



: This mark indicates supplemental information on installation, handling and operating procedures.



: This mark indicates where additional information may be located.

■ Abbreviation symbols

These abbreviations are used in this manual:

Abbreviation symbols	Name	Abbreviation symbols	Name
PV	Measured value	TC (input)	Thermocouple (input)
SV	Set value	RTD (input)	Resistance temperature detector (input)
MV	Manipulated output value	V (input)	Voltage (input)
AT	Autotuning	I (input)	Current (input)
ST	Startup tuning	HBA	Heater break alarm
OUT	Output	CT	Current transformer
DI	Digital input	LBA	Control loop break alarm
DO	Digital output	LBD	LBA deadband

About This Manual

There are three manuals pertaining to this product. Please be sure to read all manuals specific to your application requirements.

The following manuals can be downloaded from the official RKC website:

<https://www.rkcinst.co.jp/english/download-center/>

Manual	Manual Number	Remarks
COM-ME [For SRZ] Installation Manual	IMR02E29-E□	This manual is enclosed with instrument. This manual explains the mounting and wiring.
COM-ME-1 [For SRZ] Host Communication Data List	IMR02E30-E□	This manual is enclosed with instrument. This list is a compilation of the host communication data items.
COM-ME-1 [For SRZ] Instruction Manual	IMR02E31-E2	This manual you are reading now. This manual describes mounting, wiring, communication setting, protocol, communication data, troubleshooting and product specification.



Read this manual carefully before operating the instrument. Please place the manual in a convenient location for easy reference.

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MEMO

1. OUTLINE

Ethernet Modbus/TCP communication converter COM-ME-1 [For SRZ] (hereafter called COM-ME) is communication converter to connect the RKC module type controller SRZ to the Ethernet [Modbus/TCP].

This chapter describes features, package contents, model code, system configuration, etc.

- Ethernet [Modbus/TCP]

Modbus/TCP is an open field network provided with the Modbus protocol on the TCP/IP protocol of Ethernet. The data request side is called “client” (such as computer) and the data response (supply) side is called “server” (COM-ME).

- Host communication

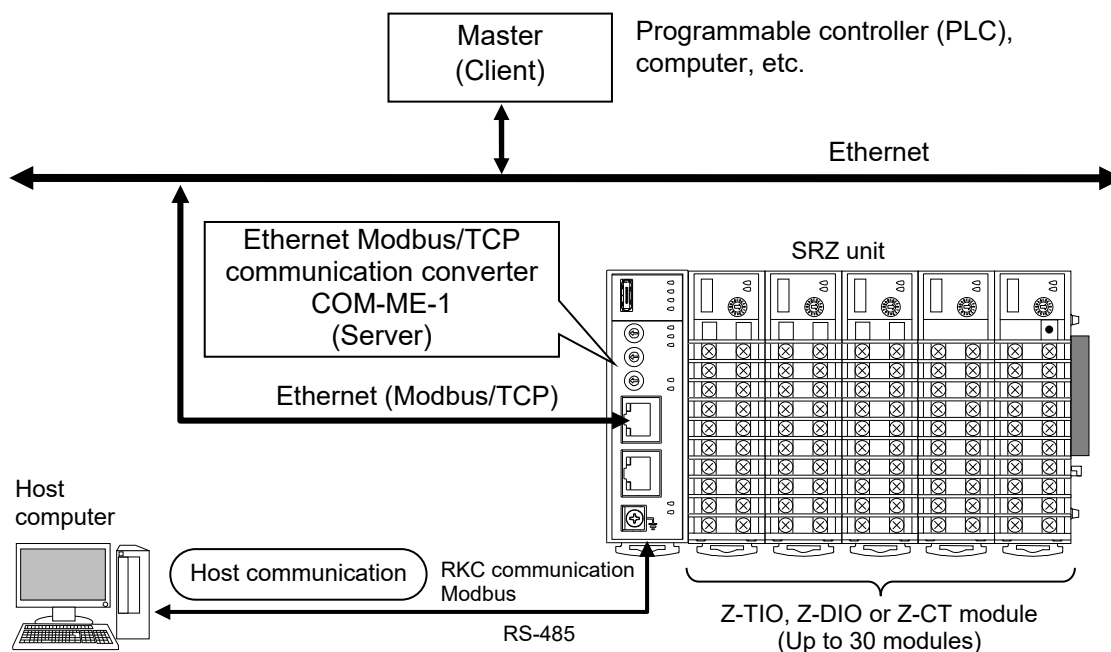
Data send/receive is possible between the converter and the host computer through RKC communication (ANSI X3.28-1976 subcategories 2.5 and B1) or Modbus.

- Function modules

Multi-zone temperature control system can be easily achieved by connecting functional modules (Z-TIO, Z-DIO and Z-CT modules) of SRZ to COM-ME. The combination of COM-ME and functional module of SRZ is called an SRZ unit.

Up to 30 function modules can be connected to one COM-ME.

(Connectable module: Z-TIO-A/B, Z-DIO-A and Z-CT-A)



1.1 Checking the Product

Before using this product, check each of the following:

- Model code
- Check that there are no scratches or breakages in external appearance (case, front panel, or terminal, etc.)
- Check that all of the items delivered are complete. (See below)

Name	Q'TY	Remarks
<input type="checkbox"/> COM-ME [For SRZ] Installation Manual (IMR02E29-E□)	1	Enclosed with instrument
<input type="checkbox"/> COM-ME-1 [For SRZ] Host Communication Data List (IMR02E30-E□)	1	Enclosed with instrument
<input type="checkbox"/> Joint connector cover KSRZ-517A	2	Enclosed with instrument
<input type="checkbox"/> Power terminal cover KSRZ-518A	1	Enclosed with instrument
<input type="checkbox"/> COM-ME-1 [For SRZ] Instruction Manual (IMR02E31-E2)	1	This manual (sold separately) This manual can be downloaded from the official RKC website.



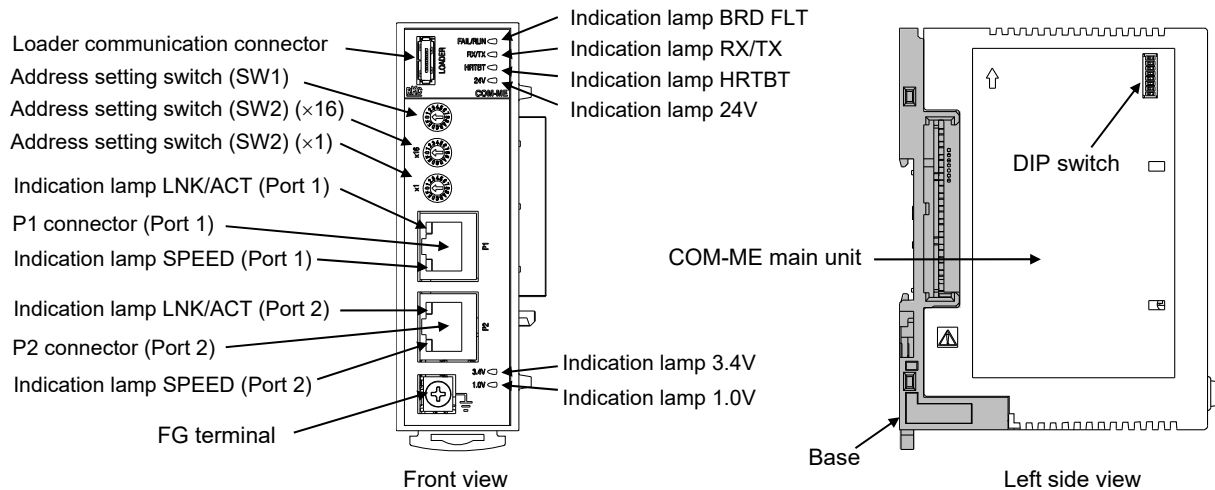
If any of the products are missing, damaged, or if your manual is incomplete, please contact RKC sales office or the agent.

■ Accessories (sold separately)

Name	Q'TY	Remarks
<input type="checkbox"/> End plate DEP-01	2	Secures the SRZ on the DIN rail
<input type="checkbox"/> Communication converter COM-KG-1N	1	For loader communication
<input type="checkbox"/> Communication converter COM-K2-1	1	(Option: with loader communication cable)

1.3 Parts Description

■ COM-ME main unit



● Indication lamps

FAIL/ RUN	[Green or Red]	<ul style="list-style-type: none"> When normal: During setting of IP address: Self-diagnostic error (Recoverable fault): Self-diagnostic error (Major fault): 	Green lamp turns on Green lamp blinks Green lamp blinks Red lamp turns on
RX/TX	[Green]	During host communication data send and receive:	Green lamp turns on
HRTBT	[Green]	While software is properly running:	Green lamp blinks
24V	[Green]	While 24 V power is supplied:	Green lamp turns on
3.4V	[Green]	While 3.4 V power is supplied:	Green lamp turns on
1.0V	[Green]	While 1.0 V power is supplied:	Green lamp turns on
LNK/ACT (Port 1/Port 2)	[Green]	<ul style="list-style-type: none"> No link or No power: Link is being established or in data communication: 	Turns off Green lamp turns on
SPEED (Port1/Port2)	[Yellow]	<ul style="list-style-type: none"> When connected at 100 Mbps or when not in communication: When connected at 10 Mbps: 	Turns off Yellow lamp turns on

● Communication connector

Loader communication connector	Used to connect the communication converter and personal computer when loader communication is performed.
P1 connector (Port 1) P2 connector (Port 2)	Used to connect the network communication (Modbus/TCP).

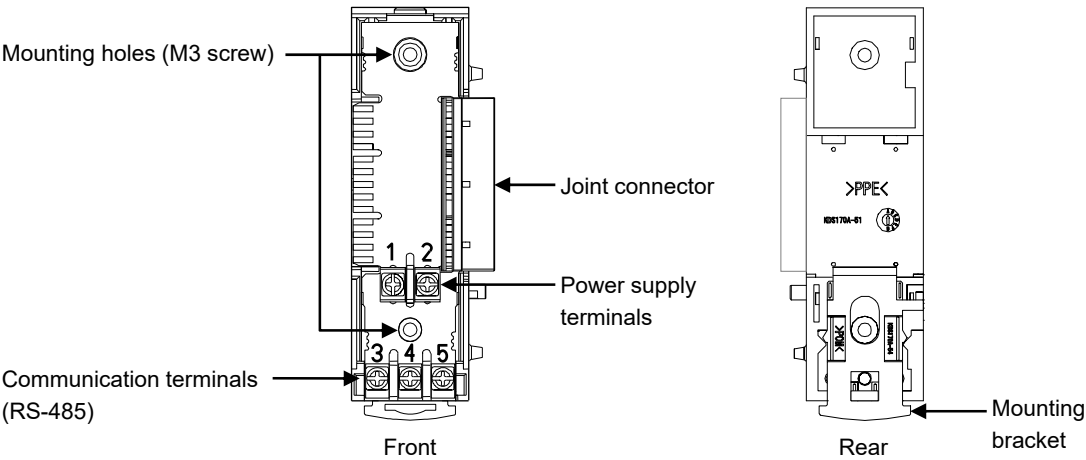
● Switch

Address setting switch (SW1)	<ul style="list-style-type: none"> Used to set the IP address.
Address setting switch (SW2) (×16) Address setting switch (SW3) (×1)	<ul style="list-style-type: none"> Sets the host communication address in hexadecimal during the operation. Sets the IP address in hexadecimal during the IP address setting.
DIP switch	<ul style="list-style-type: none"> Sets the communication speed and communication protocol corresponding to host communication. Sets DIP switch setting validity/invalidity. Used to set the IP address setting and how it works.

● Terminal

FG terminal	Terminal for grounding
-------------	------------------------

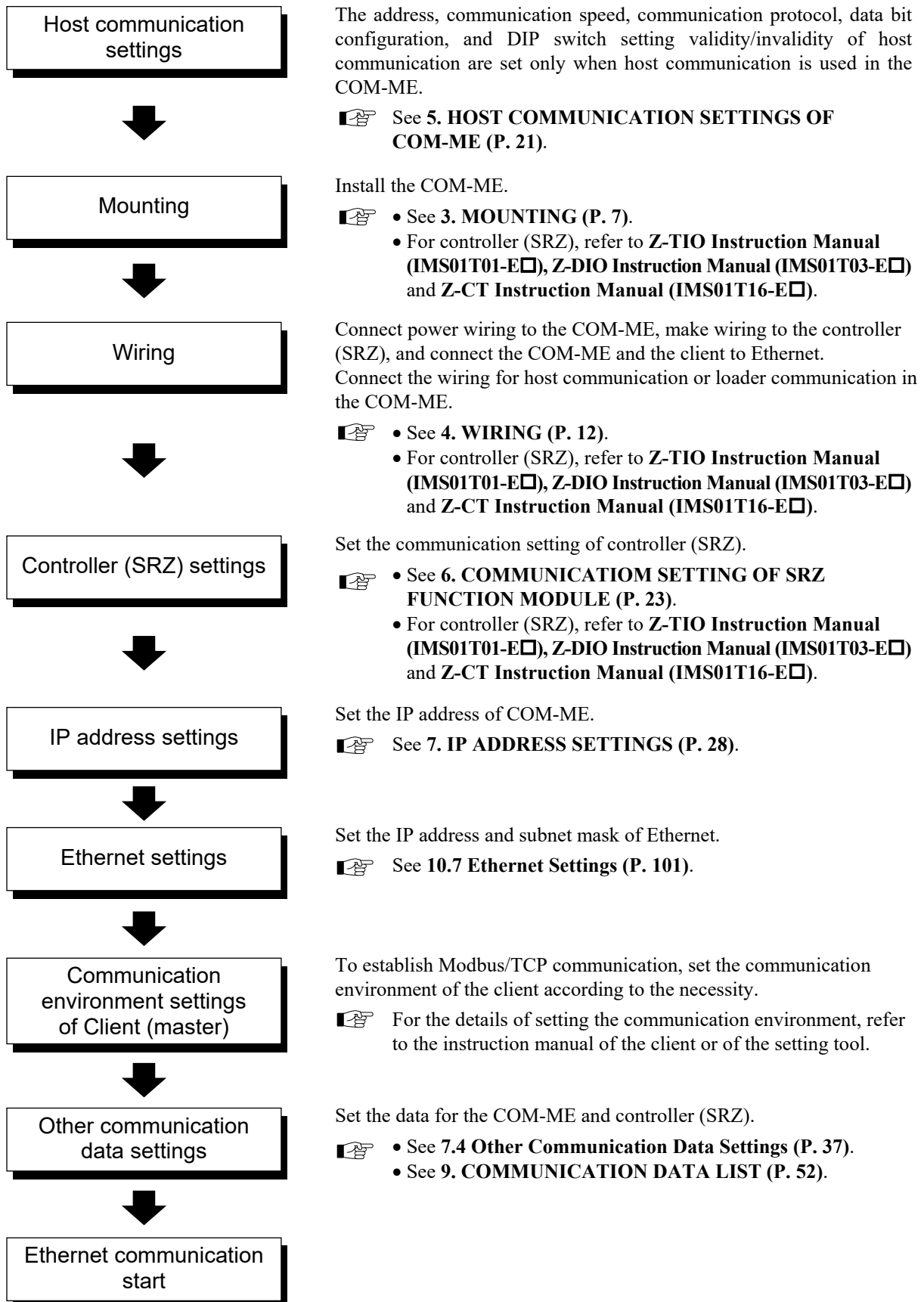
■ Base



Mounting holes (M3 screw)	Holes for screws to fix the base to a panel, etc. Customer must provide the M3 screws.								
Joint connector	Used to mechanically and electrically connect each function module.								
Power supply terminals	These are terminals to supply power to the COM-ME and joined function modules. <table border="1"> <thead> <tr> <th>Terminal number</th><th>Signal name</th></tr> </thead> <tbody> <tr> <td>1</td><td>24 V DC (+)</td></tr> <tr> <td>2</td><td>24 V DC (-)</td></tr> </tbody> </table>	Terminal number	Signal name	1	24 V DC (+)	2	24 V DC (-)		
Terminal number	Signal name								
1	24 V DC (+)								
2	24 V DC (-)								
Communication terminals (RS-485)	These terminals are used to connect to a host computer or an operation panel. <table border="1"> <thead> <tr> <th>Terminal number</th><th>Signal name</th></tr> </thead> <tbody> <tr> <td>3</td><td>T/R (A)</td></tr> <tr> <td>4</td><td>T/R (B)</td></tr> <tr> <td>5</td><td>SG</td></tr> </tbody> </table>	Terminal number	Signal name	3	T/R (A)	4	T/R (B)	5	SG
Terminal number	Signal name								
3	T/R (A)								
4	T/R (B)								
5	SG								
Mounting bracket	Used to fix the COM-ME on DIN rails and also to fix each module joined together.								

2. HANDLING PROCEDURES

Conduct necessary setting before operation according to the procedure described below.



3. MOUNTING

This chapter describes installation environment, mounting cautions, dimensions and mounting procedures.

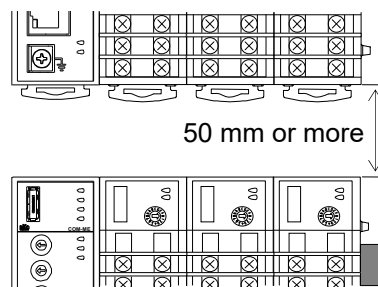
WARNING

To prevent electric shock or instrument failure, always turn off the power before mounting or removing the instrument.

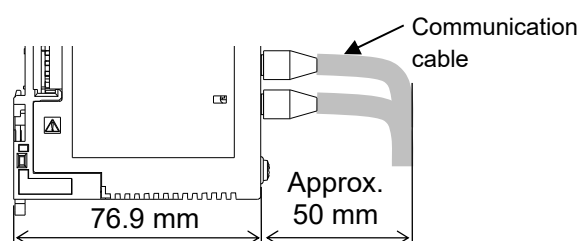
3.1 Mounting Cautions

- (1) This instrument is intended to be used under the following environmental conditions.
(IEC 61010-1) [POLLUTION DEGREE 2]
- (2) Use this instrument within the following environment conditions:
 - Allowable ambient temperature: -10 to $+55$ °C
 - Allowable ambient humidity: 5 to 95 %RH
(Absolute humidity: MAX. W. C 29 g/m³ dry air at 101.3 kPa)
 - Installation environment conditions: Indoor use
Altitude up to 2000 m
- (3) Avoid the following conditions when selecting the mounting location:
 - Rapid changes in ambient temperature which may cause condensation.
 - Corrosive or inflammable gases.
 - Direct vibration or shock to the main unit.
 - Water, oil, chemicals, vapor or steam splashes.
 - Excessive dust, salt or iron particles.
 - Excessive induction noise, static electricity, magnetic fields or noise.
 - Direct air flow from an air conditioner.
 - Exposure to direct sunlight.
 - Excessive heat accumulation.
- (4) Mount this instrument in the panel considering the following conditions:
 - Ensure at least 50 mm space on top and bottom of the instrument for maintenance and environmental reasons.
 - Do not mount this instrument directly above the equipment that generates large amount of heat (heaters, transformers, semi-conductor functional devices, large-wattage resistors.)
 - If the ambient temperature rises above 55 °C, cool this instrument with a forced air fan, cooler, etc. Cooled air should not blow directly on this instrument.
 - In order to improve safety and the immunity to withstand noise, mount this instrument as far away as possible from high voltage equipment, power lines, and rotating machinery.
 - High voltage equipment: Do not mount within the same panel.
 - Power lines: Separate at least 200 mm
 - Rotating machinery: Separate as far as possible
 - For correct functioning mount this instrument in a horizontal position.

- Space required between each module vertically
When the module is mounted on the panel, allow a minimum of 50 mm at the top and bottom of the module to attach the module to the main unit.



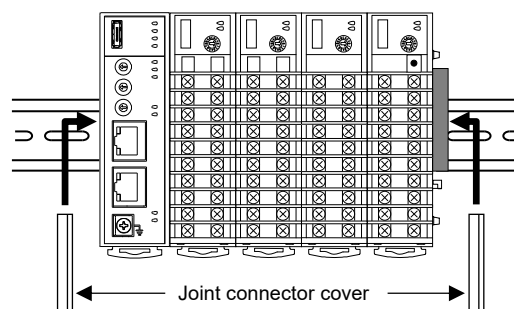
- Depth for modular cables mount type module
Space for modular cables must be considered when installing.



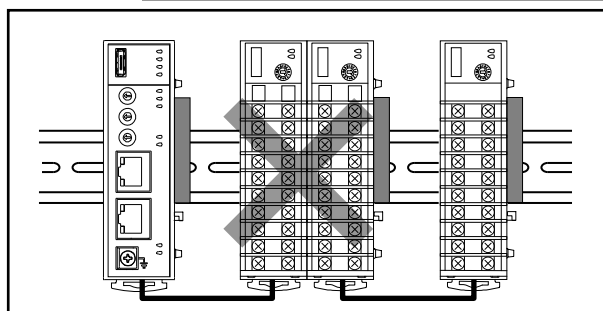
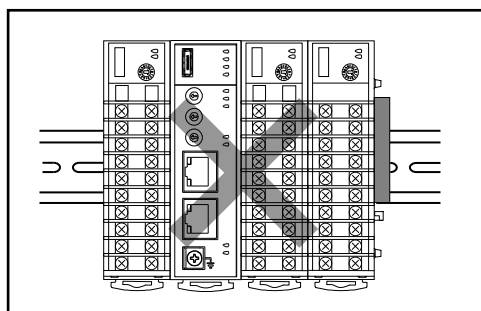
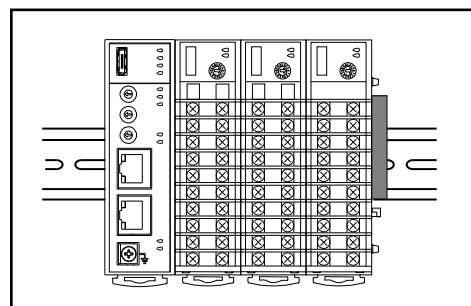
- It is recommended to use a plastic cover on the connector on both sides of the mounted modules for protection of connectors.



When mounting modules, leave space at both ends for covers.

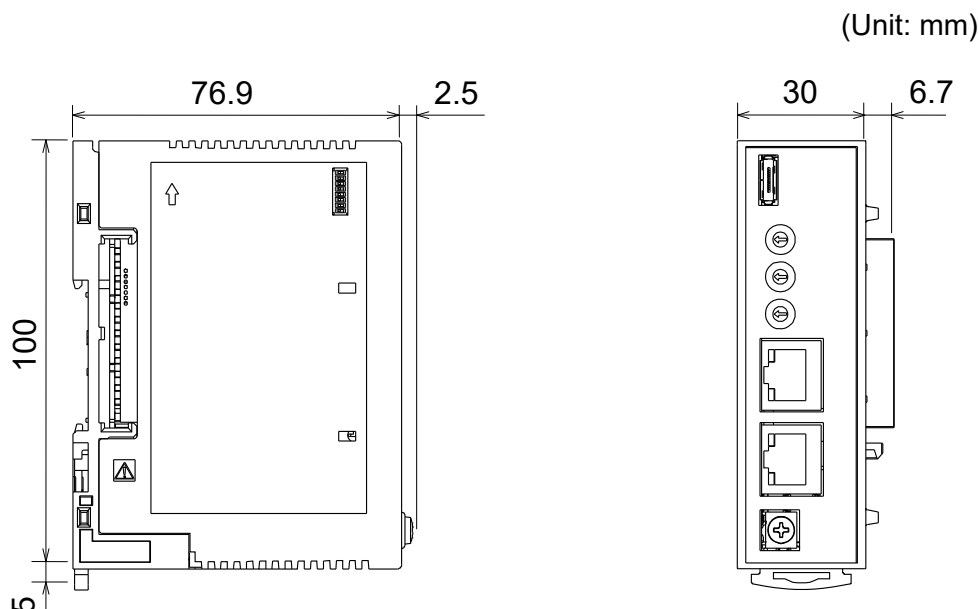


- Be sure the COM-ME and SRZ function modules (Z-TIO, Z-DIO and Z-CT modules) are joined when using them.
Do not connect any SRZ function modules to the left side of the COM-ME.
COM-ML and Z-COM modules cannot be connected to the COM-ME module.



- (5) In case this instrument is connected to a supply by means of a permanent connection, a switch or circuit-breaker shall be included in the installation. This shall be in close proximity to the equipment and within easy reach of the operator. It shall be marked as the disconnecting device for the equipment.

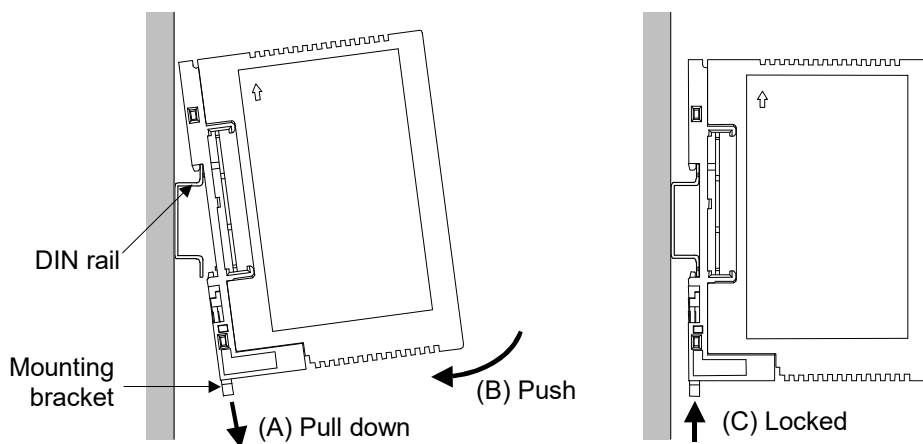
3.2 Dimensions



3.3 DIN Rail Mounting

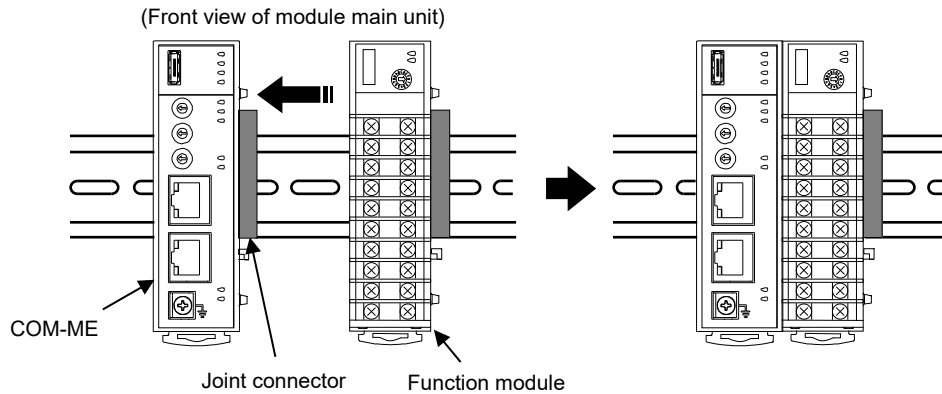
■ Mounting procedures

1. Pull down the mounting bracket at the bottom of the base (A). Attach the hooks on the top of the base to the DIN rail and push the lower section into place on the DIN rail (B).
2. Slide the mounting bracket up to secure the module to the DIN rail (C).



■ Module joining procedures

1. Mount the function modules on the DIN rail. Slide the modules until the modules are closely joined together and the joint connectors are securely connected.



2. Push in the mounting brackets to lock the modules together and fix to the DIN rail.

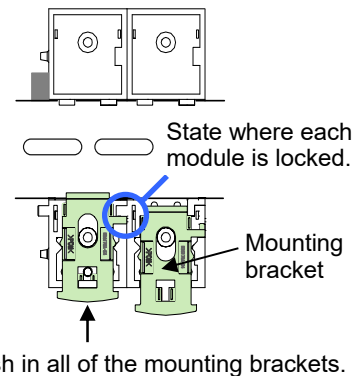


After module joining, install a plastic cover on the connector on both sides of the mounted modules for protection of connectors. (See P. 8)



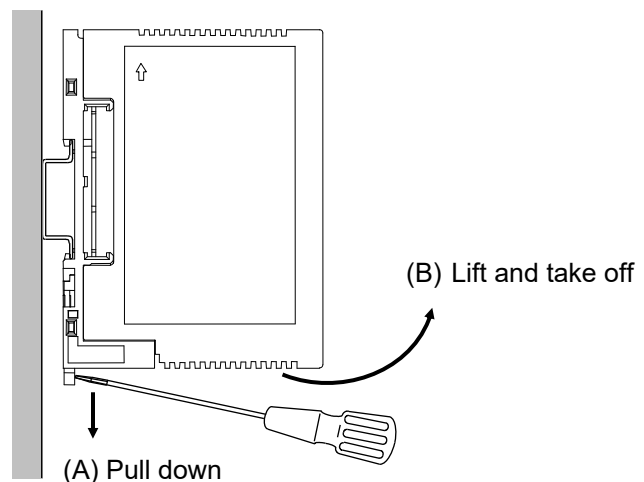
To firmly fix the modules, use end plates (DEP-01) sold separately on both sides of the mounted modules. When mounting modules, leave space at both ends for end plates.

(Rear view of base)



■ Removing procedures

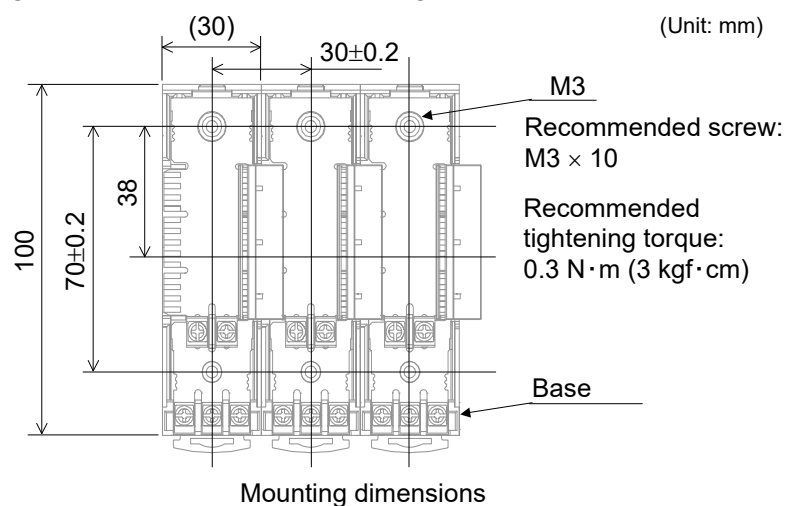
1. Turn the power OFF.
2. Remove the wiring.
3. Pull down a mounting bracket with a slotted screwdriver (A). Lift the module from bottom, and take it off (B).



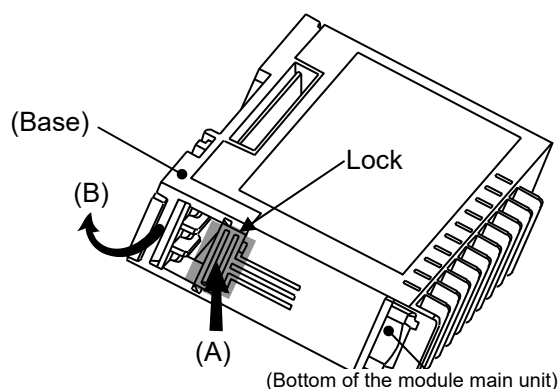
3.4 Panel Mounting

■ Mounting procedures

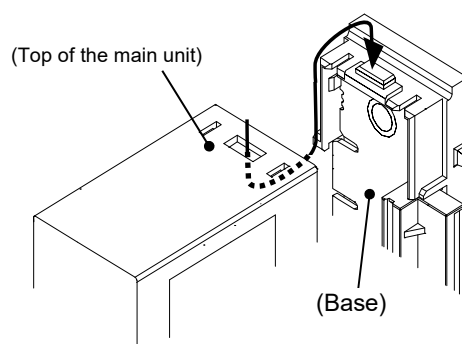
1. See the mounting dimensions below when selecting the location.



2. Remove the base from the main unit (B) while the lock is pressed (A).



3. Join bases. Then, lock them by pushing in the mounting brackets. (See P. 10)
4. Fix the base to its mounting position using M3 screws. Customer must provide the screws.
5. Mount the main unit on the base.



4. WIRING

This chapter describes wiring cautions, terminal configuration and connections.

4.1 Wiring Cautions

WARNING

To prevent electric shock or instrument failure, do not turn on the power until all wiring is completed. Make sure that the wiring is correct before applying power to the instrument.

- To avoid noise induction, keep communication signal wire away from instrument power line, load lines and power lines of other electric equipment.
- If there is electrical noise in the vicinity of the instrument that could affect operation, use a noise filter.
 - Shorten the distance between the twisted power supply wire pitches to achieve the most effective noise reduction.
 - Always install the noise filter on a grounded panel. Minimize the wiring distance between the noise filter output and the instrument power supply terminals to achieve the most effective noise reduction.
 - Do not connect fuses or switches to the noise filter output wiring as this will reduce the effectiveness of the noise filter.
- Power supply wiring must be twisted and have a low voltage drop.
- For an instrument with 24 V power supply input, supply power from a “SELV” circuit defined as IEC 60950-1.
- A suitable power supply should be considered in end-use equipment. The power supply must be in compliance with a limited-energy circuits (maximum available current of 5.6 A).
- Supply the power to only one of the joined modules or COM-ME. When power is supplied to any one of the joined modules or COM-ME, all of the joined modules and COM-ME will receive power.
- Select the power capacity which is appropriate for the total power consumption of all joined modules (include COM-ME) and the initial current surge when the power is turned on.

Power consumption (at maximum load): 150 mA max. (at 24 V DC)

Rush current: 15 A or less

- When connecting the wiring to the terminals, use the recommended solderless terminals. Only these recommended solderless terminals can be used due to the insulation between the terminals.

Screw Size: Power supply terminals, Communication terminals:

M3 × 7 (with 5.8 × 5.8 square washer)

FG terminal: M3 × 6

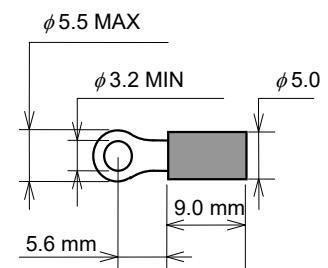
Recommended tightening torque: 0.4 N·m (4 kgf·cm)

Applicable wire: Solid/twisted wire of 0.25 to 1.65 mm²

Recommended solderless terminal:

Manufactured by J.S.T MFG CO., LTD.

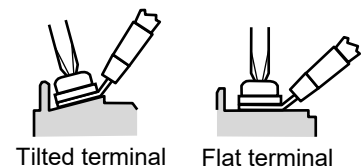
Circular terminal with isolation V1.25–MS3



- Make sure that the any wiring such as solderless terminal is not in contact with the adjoining terminals.



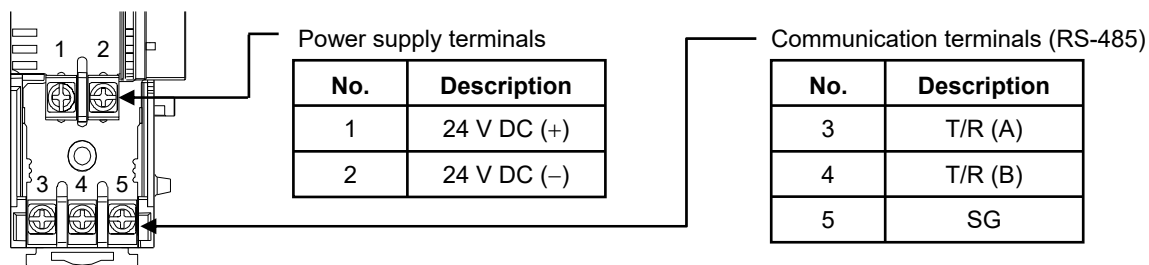
When tightening a screw of the instrument, make sure to fit the screwdriver properly into the screw head mounted tilted or flat as shown in the right figure. Tightening the screw with excessive torque may damage the screw thread. (Only function modules)



4.2 Terminal Configuration

■ Power supply terminals, Communication terminals

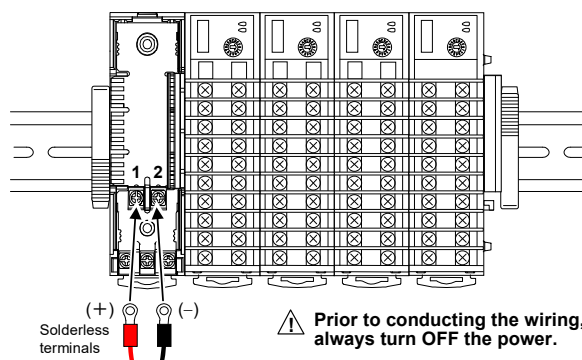
The terminal layout of COM-ME (base) is as follows.



● Wiring method

As an example, the method of connecting to the power terminals (terminal numbers 1 and 2) is shown below.

1. Remove the module main unit to which the power wiring will be connected.
2. Remove the terminal cover.
3. Attach the solderless terminals to the power terminals with a Phillips head screwdriver. When attaching the terminals, make sure that the polarity (+ and -) is correct.

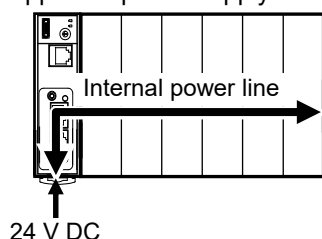


4. Attach the terminal cover on the terminal and return the main unit to the base. This completes the wiring work.

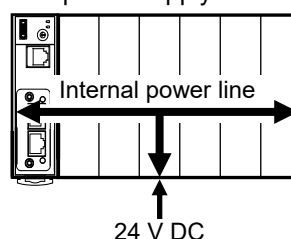
- Connections to the communication terminals (terminal numbers 3 to 5) are made in the same way.
- The communication lines of the modules connected to the COM-ME are mutually interconnected. Make the wiring of the communication terminals between the COM-ME and any one of the modules.
- When using the COM-ME connected to function modules, the power supply wiring is connected to any one of the modules. Power is supplied from the module with the power wiring to the other modules.

[Wiring example]

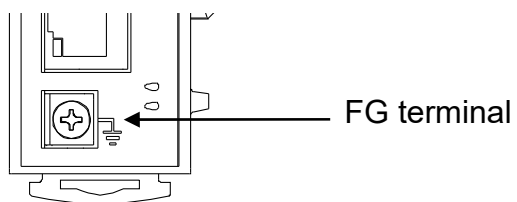
When supplied a power supply to a COM-ME



When supplied a power supply to a function module



■ FG terminal



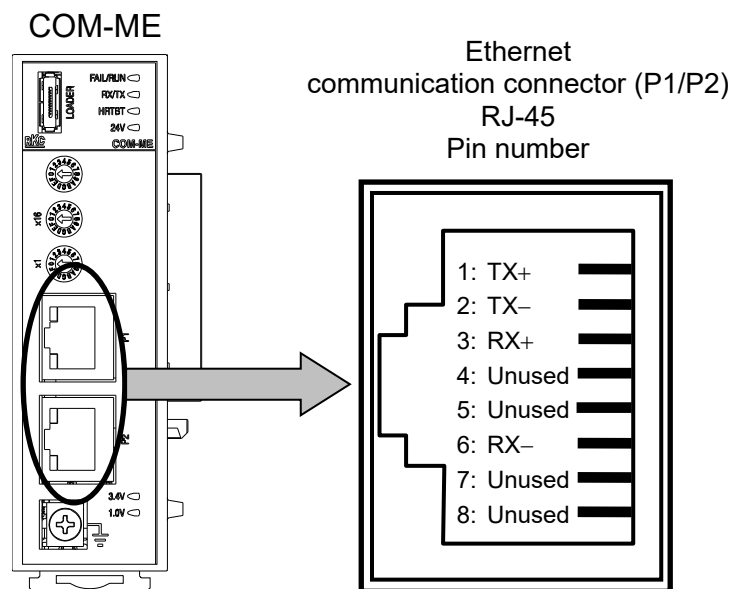
Low part of the front

- Ground the instrument separately from other equipment.
- The grounding resistance should be $100\ \Omega$ or less. Use grounding wires with a cross section area of $2\ \text{mm}^2$ or more.

4.3 Connection to Ethernet

Connect COM-ME to Ethernet.

■ Pin layout of connector



■ Connector pin number and signal details

Pin No.	Signal name	Symbol
1	Send data +	TX+
2	Send data -	TX-
3	Receive data +	RX+
4	Unused	—
5	Unused	—
6	Receive data -	RX-
7	Unused	—
8	Unused	—



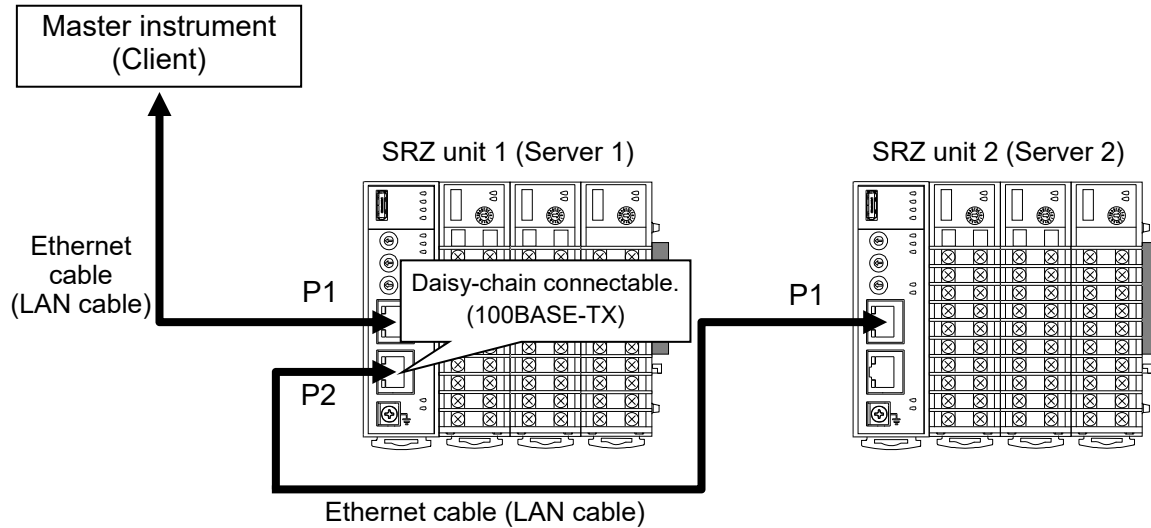
The cable must be provided by the customer.




Used cable: The cable is based on the 10BASE-T or the 100BASE-TX standard of Ethernet.

Used connector: RJ-45 type

■ Wiring example

The Ethernet cable (LAN cable) which is marketed can be connected. The Ethernet cable (LAN cable) must be provided by the customer.



-  Ethernet straight through cable and Ethernet crossover cable may be used. Use category 5 Ethernet cable (LAN cable).
-  Daisy-chain connection is available only when the instrument is used in 100BASE-TX. Use a switching hub if the instrument is used in 10BASE-T.
-  Identification of the SRZ unit connected to Ethernet is done by the IP address of the COM-ME connected to each unit. To use two or more SRZ units, set a unique IP address to each unit.

4.4 Connection to Host Computer

This section explains the connections for using the host computer and the operation panel to set COM-ME data and controller (SRZ) data.

4.4.1 Configurations that can be connected to a host computer

WARNING

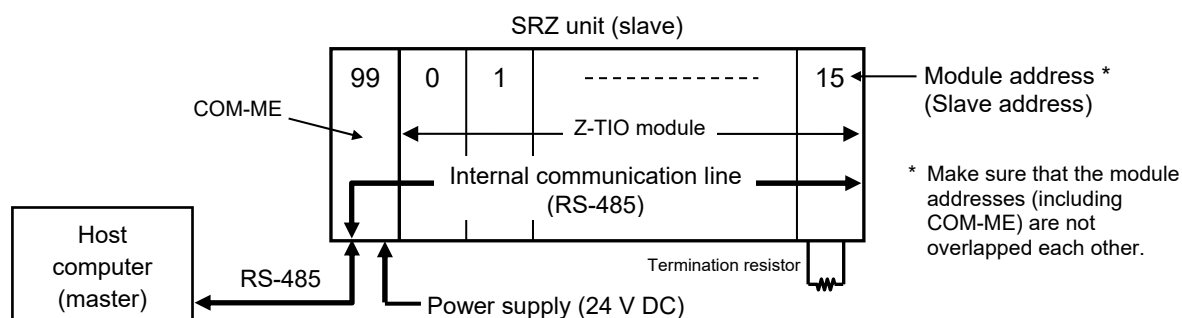
To prevent electric shock or instrument failure, turn off the power before connecting or disconnecting the instrument and peripheral equipment.

Examples of configurations of SRZ units that can be connected to a host computer are shown below.

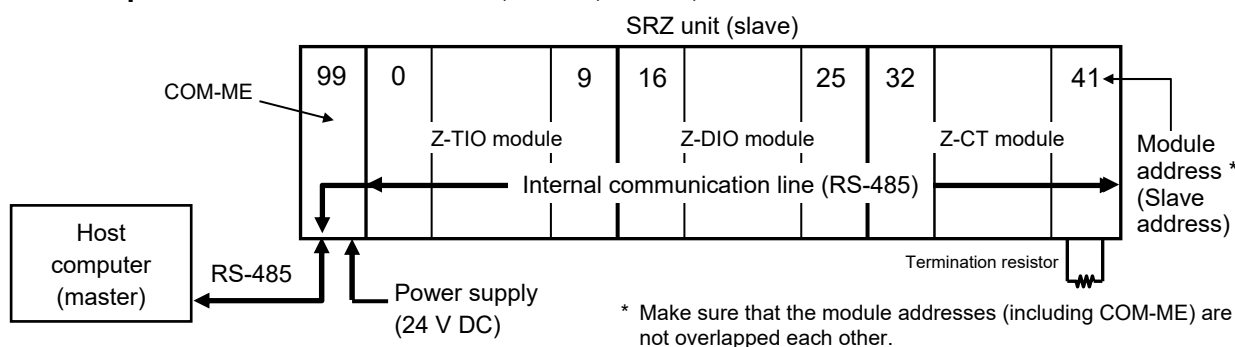


“SRZ units” here means a set of modules consisting of a COM-ME and SRZ modules (Z-TIO, Z-DIO, and Z-CT) connected together.

● When COM-ME and two or more Z-TIO module are connected



● When plural modules of COM-ME, Z-TIO, Z-DIO, and Z-CT are connected

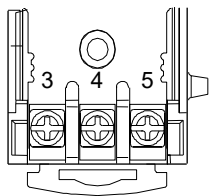


The maximum number of function modules (Z-TIO, Z-DIO, and Z-CT) connectable to one COM-ME is described below.

- When joining function modules of the same type: Up to 16 modules
- When joining function modules of two or more different types: Up to 30 modules (However, the maximum joinable number of function modules of the same type is 16.)

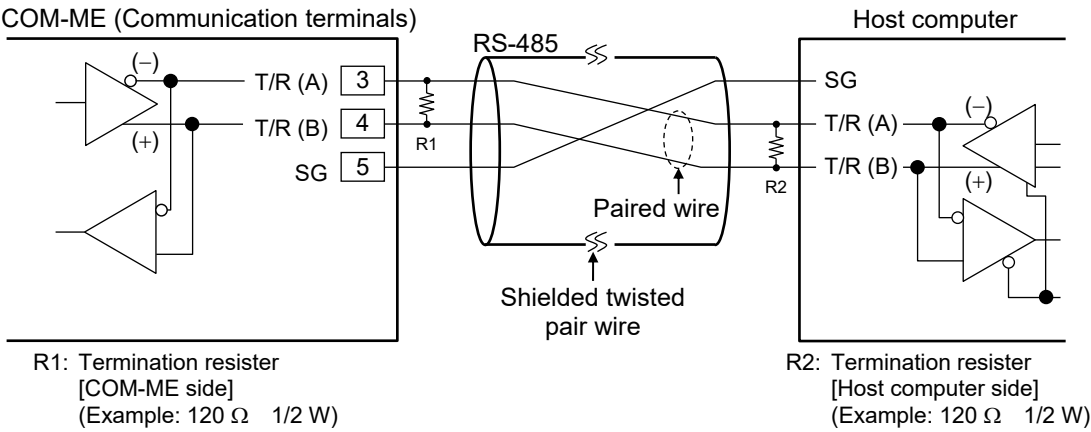
4.4.2 When connected with RS-485



■ Communication terminal number and signal details



Terminal No.	Signal name	Symbol
3	Send/receive data	T/R (A)
4	Send/receive data	T/R (B)
5	Signal ground	SG

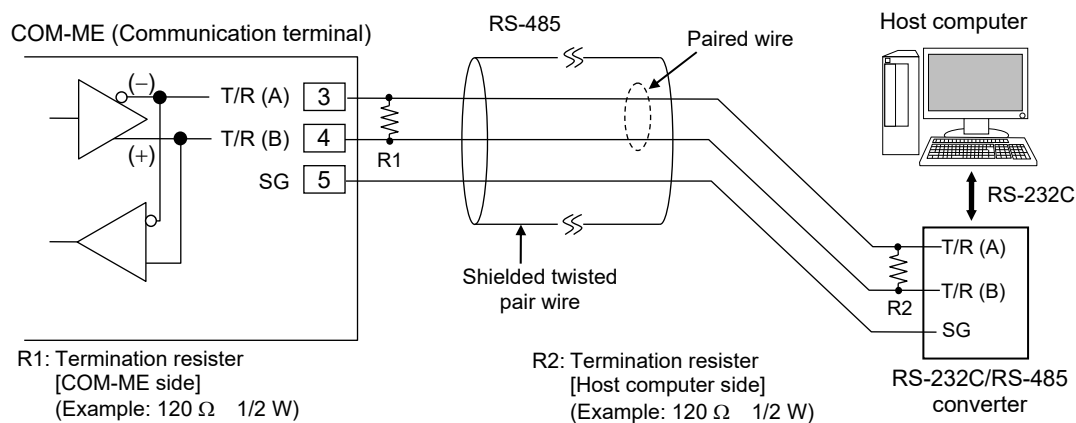
■ Wiring



-  **NOTE**
If communication errors occur frequently due to the operation environment or the communication distance, connect termination resistors.
-  Up to 31 modules of SRZ can be connected to one communication port of the host computer.

■ When the interface of host computer is RS-232C

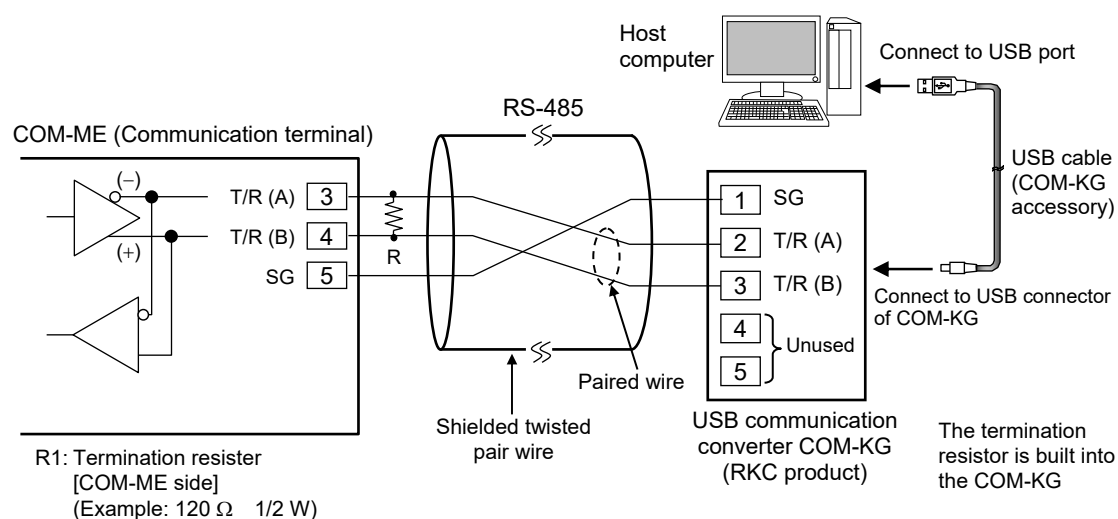
Connect the RS-232C/RS-485 converter between the host computer and the COM-ME.



Recommended RS-232C/RS-485 converter:
CD485, CD485/V Data Link product, Inc. or equivalent.

■ When the host computer has a USB connector

Connect the USB communication converter between the host computer and the COM-ME.



For the COM-KG, refer to the **COM-KG Instruction Manual**.
You can also use our USB communication converter COM-K2.

4.4.3 Connections for loader communication

Connect a USB communication converter COM-KG or COM-K2 (sold separately)* between the host computer and the COM-ME.

Loader communication makes it possible to check and set data of the COM-ME and the controller (SRZ).

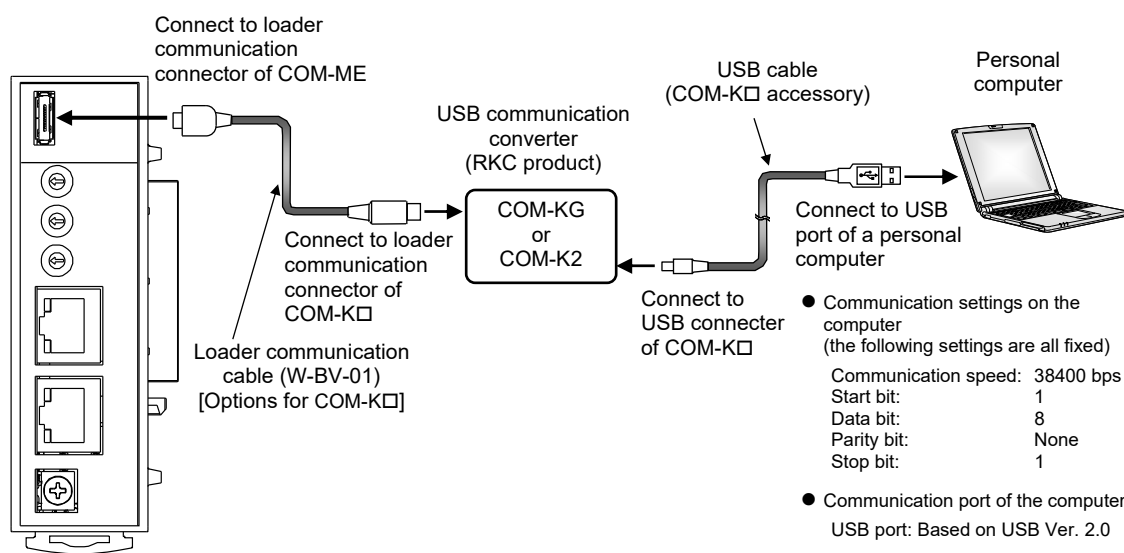
Our communication tool PROTEM2 can be used to check and set the data.

* A loader communication cable (option) is required for the connection to the loader communication connector on the COM-ME.

Model of USB communication converter with Loader communication cable:

COM-KG-1N (cable length: 1.5 m)

COM-K2-1 (cable length: 1.5 m)



Connection example of loader communication

NOTE

The Loader port is only for parameter setup. Not used for data logging during operation.

- The PROTEM2 can be downloaded from the official RKC website.
- During the loader communication, the COM-ME requires an external power source. The COM-ME will not function on the USB power from a personal computer alone.
- The module address for loader communication is fixed at "0."
- Loader communication corresponds to RKC communication (based on ANSI X3.28-1976 subcategories 2.5 and B1).
- When using the loader communication, USB driver for COM-KG (for Windows7) and COM-K2 must be installed on the personal computer. The USB driver can be downloaded the official RKC website.
Installation of the USB driver is not necessary when the COM-KG is used on Windows 10.
- For the COM-KG, refer to the **COM-KG Instruction Manual**.
For the COM-K2, refer to the **COM-K2 Instruction Manual**.

5. HOST COMMUNICATION SETTING OF COM-ME

WARNING

- To prevent electric shock or instrument failure, always turn off the power before setting the switch.
- To prevent electric shock or instrument failure, never touch any section other than those instructed in this manual.

5.1 Address Setting of COM-ME

The address of the COM-ME in the host communication is set. The address setting switches (SW2, SW3) are used for this setting. Set an address for the COM-ME using a small blade screwdriver.

NOTE

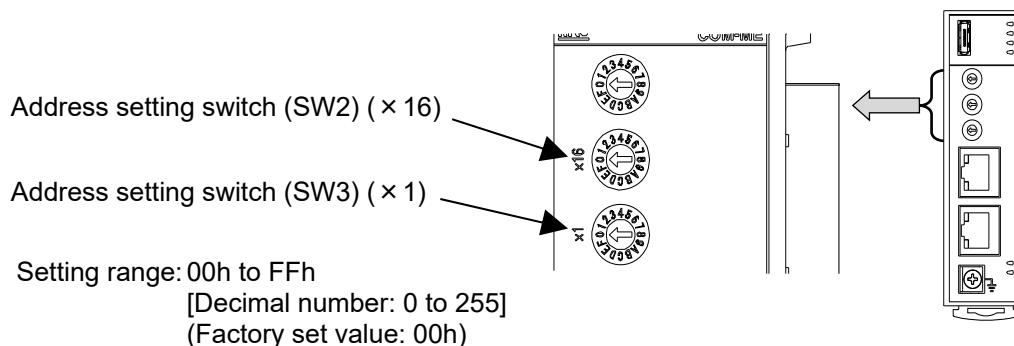
When two or more COM-ME and SRZ function module are connected, to avoid problems or malfunction, do not duplicate an address on the same communication line.



To activate the set device address, turn off the power once and turn it back on again.



In RKC communication: If the address is set to 99 or more (decimal number), it works as “99”.
In Modbus: If the address is set to 0, it works as “1”.



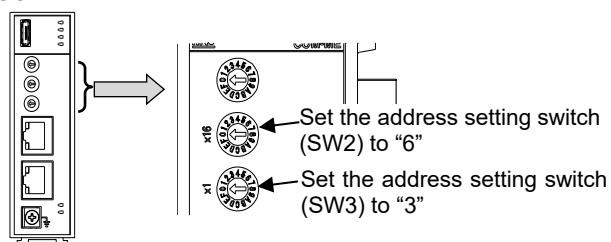
■ Setting example

When setting the address of the COM-ME to “99 (decimal)”:

You have to set the address in hexadecimal format on the address setting switch, that is, 63 (hex) for 99 (decimal).

99 (DEC) → 63h (HEX)

COM-ME



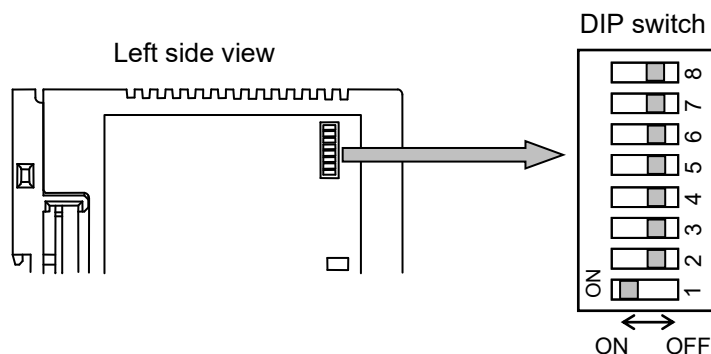
Setting range:

- RKC communication
00h to 63h (0 to 99: DEC)
- Modbus
00h to FFh (0 to 255: DEC)

Factory set value: 0

5.2 DIP Switch Setting of COM-ME

Use the DIP switch at the left side of the COM-ME to set the speed and protocol of host communication, and DIP switch validate/invalidate.



1	2	Host communication speed
OFF	OFF	9600 bps
ON	OFF	19200 bps [Factory set value]
OFF	ON	38400 bps
ON	ON	57600 bps ¹

¹ When the communication speed of the COM-ME is 57600 bps, the host communication to function modules is not available. When using only the COM-ME through the host communication, set the communication speed and the protocol of the function modules connected to the COM-ME to “38400 bps” and to “Modbus” respectively.

3	Communication protocol/Data bit configuration
OFF	RKC communication (Data 8 bits, non parity, Stop 1 bit) [Factory set value]
ON	Modbus (Data 8 bits, non parity, Stop 1 bit)

4	5	
OFF	OFF	Fixed (Do not change)

DIP switch No. 6 and No. 7

The DIP switch No.6 and No.7 are used to set Ethernet [Modbus/TCP] communication.

☞ For details of DIP switch No. 6 and No. 7, see P. 33.

8	DIP switch enable/disable
OFF	Enable (enable the DIP switch settings) [Factory set value]
ON	Disable (enable the host communication or loader communication settings) ²

² The only host communication or loader communication settings that are validated are the host communication speed and protocol and the data bit configuration.



When the communication protocol is set with the DIP switch, the data bit configuration is automatically set to “data 8 bits, non parity, stop 1 bit.” To change to another data bit configuration, set the configuration in host communication or loader communication.



If you wish to set the data bit configuration, host communication speed, and communication protocol in host communication or loader communication, first set DIP switch No. 8 to ON.

6. COMMUNICATION SETTING OF SRZ FUNCTION MODULE

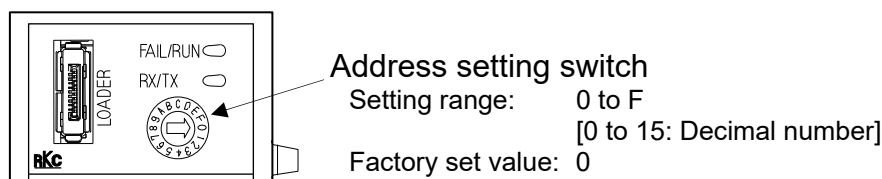
6.1 Address Setting of the Function Modules

Set the address of the function modules. When using two or more function modules, set the desired module address to each module. For this setting, use a small blade screwdriver.



NOTE

To avoid problems or malfunction, do not duplicate a module address on the same communication line. (The module addresses of the COM-ME and function modules must not overlap with each other)



Module address number of each module:

	RKC communication	Modbus
Z-TIO module	0 to 15 (Decimal number)	1 to 16 (Decimal number) The value obtained by adding "1" to the set address corresponds to the address used for the actual program.
Z-DIO module	16 to 31 (Decimal number) The value obtained by adding "16" to the set address corresponds to the address used for the actual program.	17 to 32 (Decimal number) The value obtained by adding "17" to the set address corresponds to the address used for the actual program.
Z-CT module	32 to 47 (Decimal number) The value obtained by adding "32" to the set address corresponds to the address used for the actual program.	33 to 48 (Decimal number) The value obtained by adding "33" to the set address corresponds to the address used for the actual program.



The maximum number of function modules (Z-TIO-A/B, Z-DIO-A, and Z-CT-A) connectable to one COM-ME is described below.

- When joining function modules of the same type: Up to 16 modules
- When joining function modules of two or more different types: Up to 30 modules
(However, the maximum joinable number of function modules of the same type is 16.)



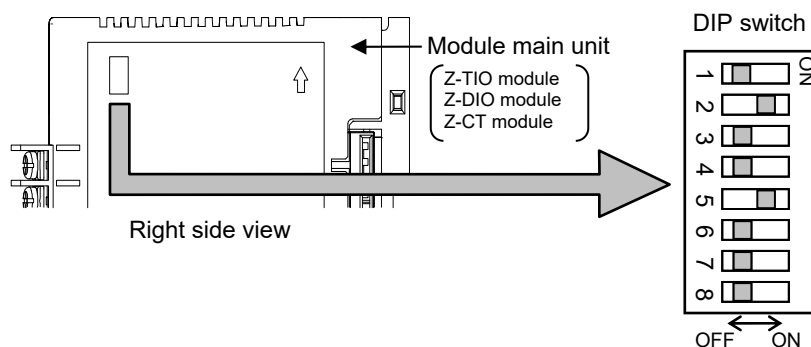
For relation of the module address and channel number, see **6.3 Temperature Control Channel of SRZ Unit (P. 25)** and **6.4 Digital Input/Output Channel of Z-DIO Module (P. 26)** and **6.5 Current Transformer (CT) Input Channel of Z-CT Module (P. 27)**.

Address setting example of function module (Z-TIO: 12, Z-DIO: 8, Z-CT: 10)



6.2 Protocol Selections and Communication Speed Setting of Function Modules

Use the DIP switch on the right side of module to select communication speed, data bit, configuration and protocol. The data changes become valid when the power is turned on again or when changed to RUN/STOP.



■ Setting for Ethernet [Modbus/TCP] communication

When only Ethernet [Modbus/TCP] communication is conducted, there is no need of setting up the communication speed of function modules, the data bit configuration, and the communication protocol. Only the function module addresses need to be set up.

■ Setting up the host communication

When the communication speed of the COM-ME is set to one of 9600 bps, 19200 bps, or 38400 bps:

The settings of function modules on the same line must be the same as those of the COM-ME.

When the communication speed of the COM-ME is set to 57600 bps:

Set the communication protocol to “Modbus” and the communication speed to “38400 bps” regardless of the communication protocol setting. If not set so, communication error may occur. The data bit configuration can be different from the COM-ME.

The function modules are not available for the communication speed of 57600 bps. If the setting the communication speed of the COM-ME to 57600 bps, the host communication between the function modules and the COM-ME cannot be established.

In addition to the host communication, the COM-ME reads and writes the data of the function modules internally, the host communication with the COM-ME, even if set to 57600 bps, will allow monitoring the communication data of functional modules and changing various setting values.

- ✎ For the setting of communication speed, data bit configuration, and communication protocol of the function module, refer to the **SRZ Instruction Manual** or **Z-CT Instruction Manual [Detailed version]**.

6.3 Temperature Control Channel of the SRZ Unit

Setting the Z-TIO module address determines the temperature control channel number used for communication. To each Z-TIO module address, the relevant temperature control channel is assigned. Each temperature control channel number can be calculated from the following equation.

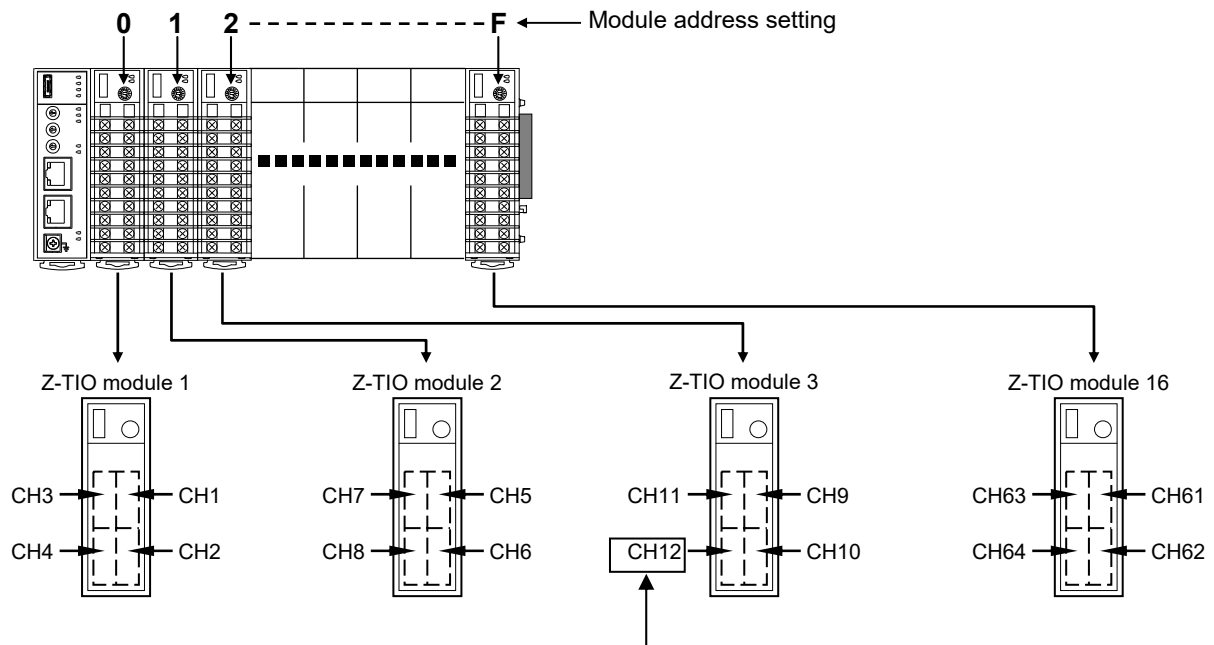
Temperature control channel number of communication =

$$[\text{Module address setting}^a] \times [\text{Maximum channel number of the function module}^b] + [\text{Channel number in a module}]$$

^a When the setting is A to F, it is a decimal number.

^b For the Z-TIO module, it is calculated by “4.”

Example: When 16 Z-TIO modules (4-channel type) are joined



- Z-TIO module 3: The temperature control channel number used for communication of channel 4 —
 $2 \times 4 + 4 = 12$

6.4 Digital Input/Output Channel of Z-DIO Module

Setting the Z-DIO module address determines the digital input/output channel number of SRZ unit. To each Z-DIO module address, the relevant digital input/output channel is assigned. Each digital input/output channel can be calculated from the following equation.

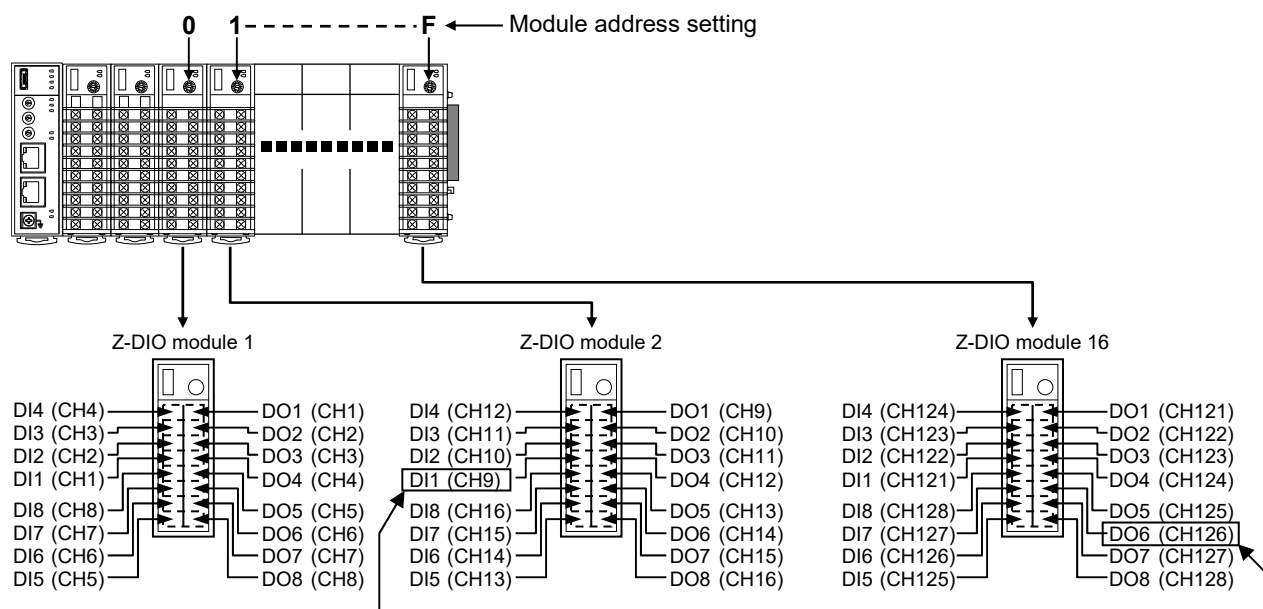
Digital input/output channel number =

$$[\text{Module address setting}^a] \times [\text{Maximum channel number of the function module}^b] + [\text{Input (or output) channel number in a module}]$$

^a When the setting is A to F, it is a decimal number.

^b For the Z-DIO module, it is calculated by "8."

Example: When 16 Z-DIO modules are joined



- Digital input channel number of digital input (DI) channel 1 of Z-DIO module 2
 $1 \times 8 + 1 = 9$
- Digital output channel number of digital output (DO) channel 6 of Z-DIO module 16
 $15 \times 8 + 6 = 126$

6.5 Current Transformer (CT) Input Channel of Z-CT Module

Setting the Z-CT module address determines the current transformer (CT) input channel number of SRZ unit. To each Z-CT module address, the relevant current transformer (CT) input channel is assigned. Each current transformer (CT) input channel can be calculated from the following equation.

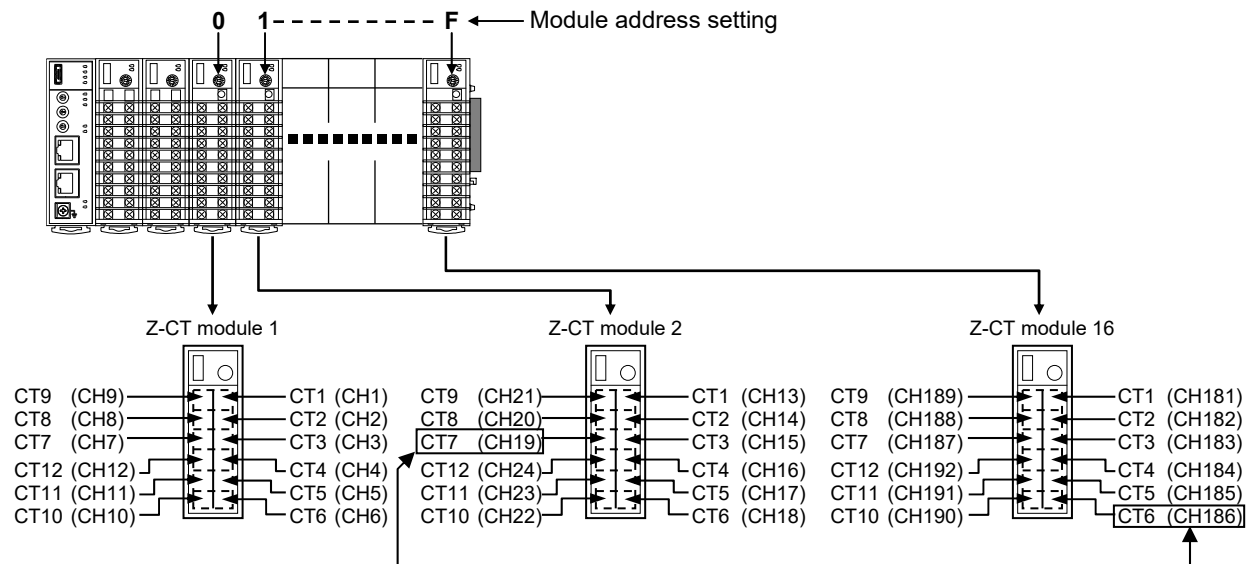
Current transformer (CT) input channel number =

$$[\text{Module address setting}^a] \times [\text{Maximum channel number of the function module}^b] + [\text{Channel number in a module}]$$

^a When the setting is A to F, it is a decimal number.

^b For the Z-CT module, it is calculated by "12."

Example: When 16 Z-CT modules are joined



- Channel number of current transformer (CT) input channel 7 of Z-CT module 2

$$1 \times 12 + 7 = 19$$

- Channel number of current transformer (CT) input channel 6 of Z-CT module 16

$$15 \times 12 + 6 = 186$$

7. IP ADDRESS SETTINGS

To use the COM-ME on Ethernet [Modbus/TCP], IP address setting is necessary. The IP address can be set in host communication, loader communication or by the switch.



Identification of the SRZ unit connected to Ethernet is done by the IP address of the COM-ME connected to each unit. To use two or more SRZ units, set a unique IP address to each unit.

7.1 Host Communication Settings

■ Fixed IP address setting

When setting via host communication, see the following RKC communication identifiers and Modbus register addresses to set the IP address. Also set the TCP port number.

For the set value, the power must be turned off and then on, in order for the settings to take effect.

Name	RKC identifier	Modbus register address		Data range	Factory set value
		HEX	DEC		
First-byte of IP address	QB	801B	32795	0 to 255	192
Second-byte of IP address	QC	801C	32796	0 to 255	168
Third-byte of IP address	QD	801D	32797	0 to 255	1
Fourth-byte of IP address	QE	801E	32798	0 to 255	1
TCP port number	VM	8002	32770	0 to 65535	502

(Factory set value for COM-ME IP address: 192.168.1.1)



NOTE

For the IP address, check with the administrator of the network (LAN) to which the COM-ME is connected.



The DIP switches can be used to return the IP address to the factory set value setting.
For operating procedure, see **7.3.2 Default IP address setting (P. 36)**.



Our **Communication tool “PROTEM 2”** can be used for the communication setup.
This tool can be downloaded from the official RKC website.



For information on connecting the COM-ME to a host computer, see **4.4 Connection to Host Computer (P. 17)**.

7.2 Loader Communication Settings

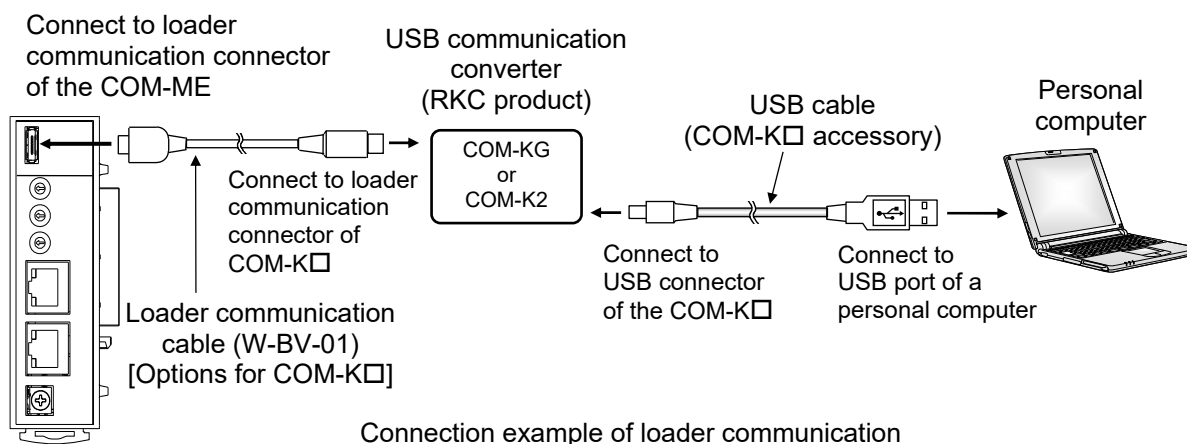
■ Preparation

To perform Loader communication, our converter and a communication cable are required.

- USB communication converter COM-KG or COM-K2 (With USB cable)
To use the Loader communication, USB driver for COM-KG (for Windows7) or COM-K2 must be installed on the personal computer. The USB driver can be downloaded from the official RKC website.
Installation of the USB driver is not necessary when the COM-KG is used on Windows 10.
- Loader communication cable W-BV-01 [Options for COM-KG or COM-K2]
- Communication tool PROTEM 2
This tool can be downloaded from the official RKC website.

■ Connection method

Connect the COM-ME, the COM-KG (COM-K2), and the personal computer with a USB cable and a loader communication cable.



During the loader communication, the COM-ME requires an external power source. The COM-ME will not function on the USB power from a personal computer alone.

■ Setting of loader communication

The device address, the communication speed and the data bit configuration are fixed as follows for the loader communication.

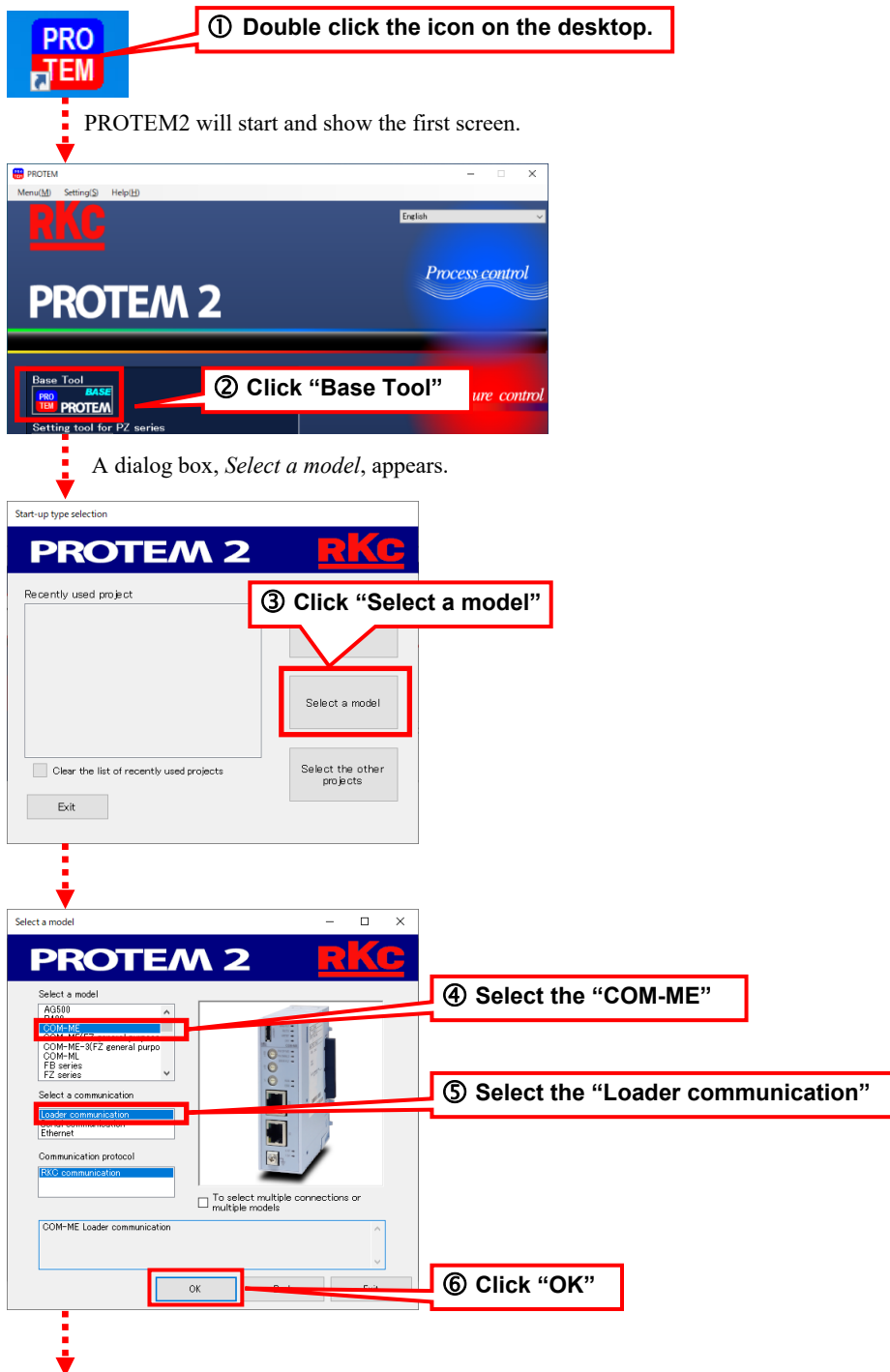
- Device address: 0
- Communication speed: 38400 bps
- Data bit configuration: Start 1 bit, Data 8 bits, Non parity, Stop 1 bit

■ Setting of PROTEM 2

1. Turn on the power of the COM-ME (SRZ unit).

2. Start PROTEM2, and set the communication port.

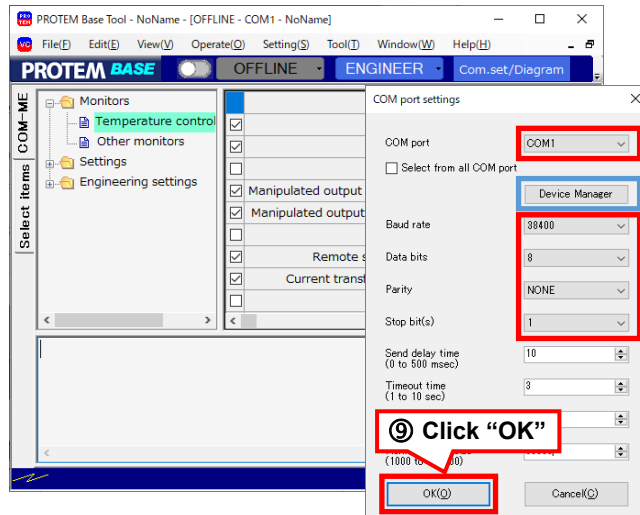
If you use the PROTEM2 for the first time, you have to create a new project and set a communication port.



Continued on the next page.

Continued from the previous page.

(Base tool screen)



⑦ Set up the communication port

Configure the communication port according to the PC you use.

If you are unaware of the port number, click "Device Manager" and check the port number. Set the port number "RKC USB-to-Serial Bridge (COM□)" shown under "Ports (COM & LPT)."

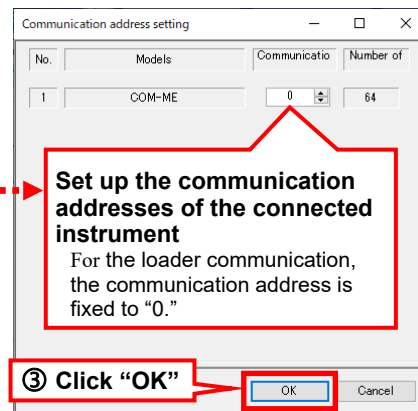
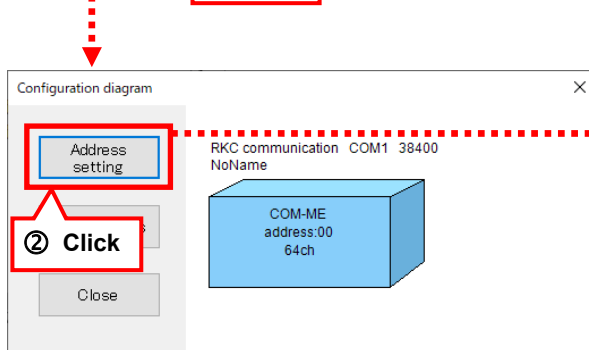
⑧ Check the loader communication setting

Communication speed and data bit configuration are fixed for the loader communication.

- Communication speed: 38400 bps
- Data bit: 8
- Parity bit: NONE
- Stop bit: 1

3. Click "Com.set/Diagram" and check the communication address.

① Click

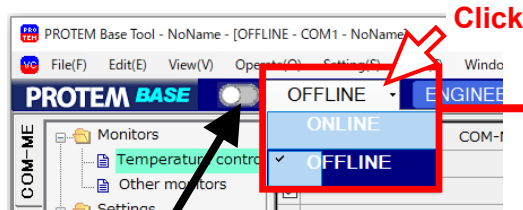


Set up the communication addresses of the connected instrument

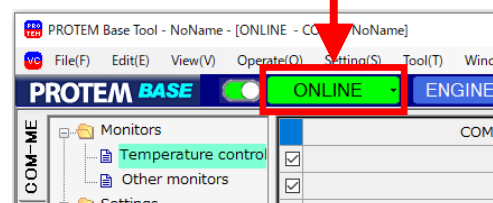
For the loader communication, the communication address is fixed to "0."

4. Switching to online

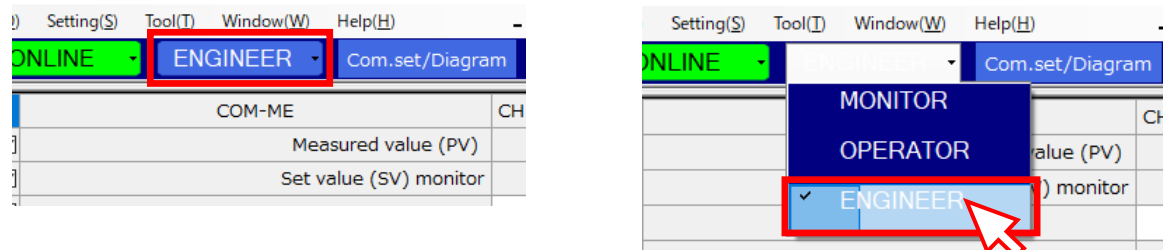
Click "OFFLINE" to select "ONLINE"



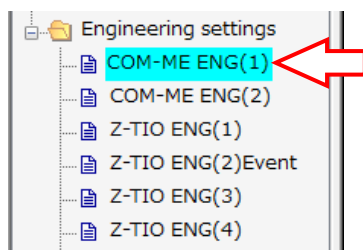
You can switch ONLINE/OFFLINE by clicking this toggle button.



5. Make sure “ENGINEER” is displayed at the top bar. If any display other than ENGINEER (e.g. MONITOR, OPERATOR) appears, click the displayed part to select ENGINEER.



6. Select “COM-ME ENG(1)” under the “Engineering settings.”



7. Set the IP address and the TCP port number of the COM-ME.

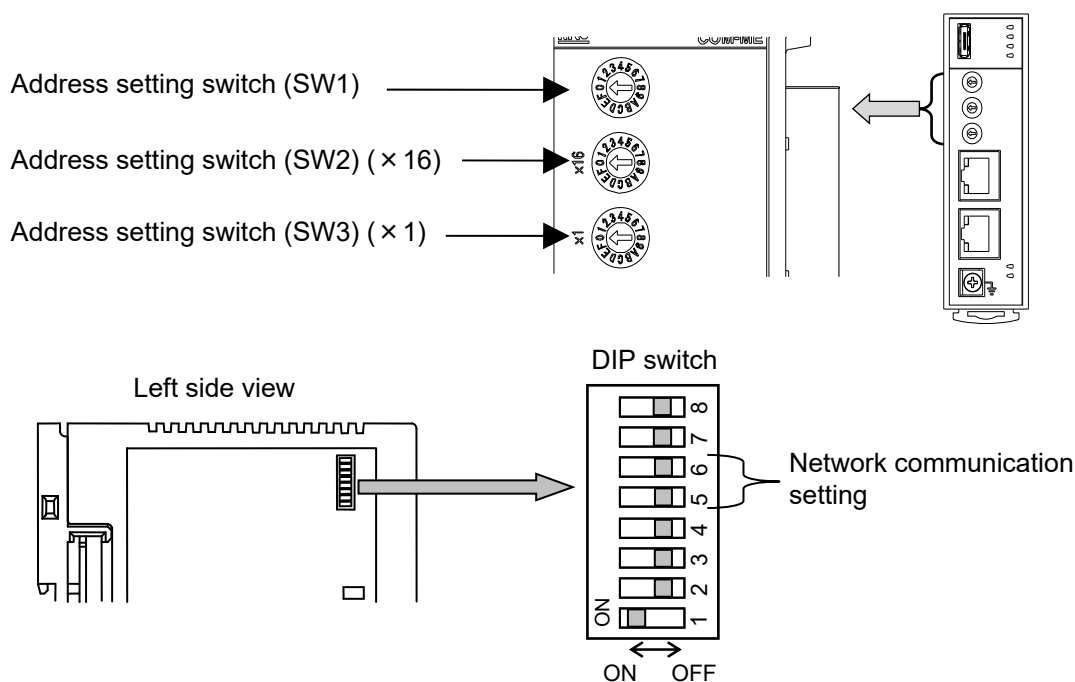
	COM-ME	CH 1	
<input checked="" type="checkbox"/>	First-byte of IP address	192	The IP address of the COM-ME (Factory set value: 192.168.1.1)
<input checked="" type="checkbox"/>	Second-byte of IP address	168	
<input checked="" type="checkbox"/>	Third-byte of IP address	1	
<input checked="" type="checkbox"/>	Fourth-byte of IP address	1	
<input checked="" type="checkbox"/>	TCP port number	502	← TCP port number of the COM-ME (Factory set value: 502)
<input type="checkbox"/>			
<input checked="" type="checkbox"/>	First-byte of remote IP address	192	Remote IP address (Factory set value: 192.168.1.2) There is no need to change the remote IP address. Please use the factory set value as it is.
<input checked="" type="checkbox"/>	Second-byte of remote IP address	168	
<input checked="" type="checkbox"/>	Third-byte of remote IP address	1	
<input checked="" type="checkbox"/>	Fourth-byte of remote IP address	2	

8. The set IP address and the TCP port number of the COM-ME are enabled by turning OFF the power and then turning it ON again.

7.3 Switch Settings

7.3.1 Setting the IP address on the switch

The IP address can be set on the three address setting switches on the front of the COM-ME and the DIP switch on the left side.



6	7	Network communication
OFF	OFF	Operates with the set IP address [Factory set value]
ON	OFF	Do not change
OFF	ON	Performs IP address setting on the Address setting switches
ON	ON	Executes the default IP address setting *

* See 7.3.2 Default IP address setting (P. 36).

● Settable items

First-byte of IP address	TCP port number
Second-byte of IP address	Subnet mask CIDR
Third-byte of IP address	
Fourth-byte of IP address	

NOTE

IP addressing of the COM-ME by the switch requires the entire operating procedure to be performed. You are unable to set only specific items. If you quit setting halfway through, all the settings you have done so far will be invalid.



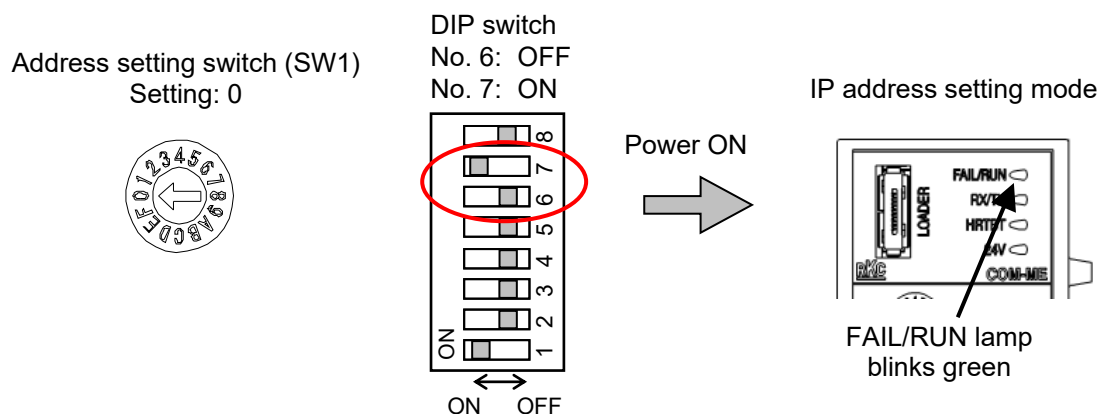
The value of the Subnet mask CIDR, when set with the switch, will be forced to the factory preset value “24”. To change the Subnet mask CIDR to another value, set the configuration through the host communication or loader communication.

■ Setting procedures

1. Turn off the power.

Set the DIP switch No.6 to OFF and No.7 to ON. Power on the instrument with the Address setting switch (SW1) set to 0. The instrument is in the IP address setting mode.

Make sure the FAIL/RUN lamp blinks green (at 500ms cycles).



See the following table for Steps 2. to 21.

Step	Setting items	SW1 setting	SW2 setting	SW3 setting	FAIL/RUN lamp	Operation
2.	First-byte of IP address	0	High-order 4 bits	Low-order 4 bits	Green lamp blinks	Set a value on SW2 and 3. (see Example 1)
3.	First-byte of IP address	0→1			Red lamp lights on	Modify a value on SW1 and set it.
4.	Second-byte of IP address	1	High-order 4 bits	Low-order 4 bits	Red lamp lights on	Set a value on SW2 and 3.
5.	Second-byte of IP address	1→2			Lights off	Modify a value on SW1 and set it.
6.	Third-byte of IP address	2	High-order 4 bits	Low-order 4 bits	Lights off	Set a value on SW2 and 3.
7.	Third-byte of IP address	2→3			Red lamp lights on	Modify a value on SW1 and set it.
8.	Fourth-byte of IP address	3	High-order 4 bits	Low-order 4 bits	Red lamp lights on	Set a value on SW2 and 3.
9.	Fourth-byte of IP address	3→4			Lights off	Modify a value on SW1 and set it.
10.	High-order byte of TCP port number	4	High-order 4 bits	Low-order 4 bits	Lights off	Set a value on SW2 and 3. (see Example 2)
11.	High-order byte of TCP port number	4→5			Red lamp lights on	Modify a value on SW1 and set it.

Example 1: To set “192”, as it is expressed as “C0” in hexadecimal notation, set “C” on SW2 and “0” on SW3.

Example 2: To set “502”, as it is expressed as “01F6” in hexadecimal notation and the high-order byte is “01”. Set “0” on SW2 and “1” on SW3.

Step	Setting items	SW1 setting	SW2 setting	SW3 setting	FAIL/RUN lamp	Operation
12.	Low-order byte of TCP port number	5	High-order 4 bits	Low-order 4 bits	Red lamp lights on	Set a value on SW2 and 3. (see Example 3)
13.	Low-order byte of TCP port number	5→6			Lights off	Modify a value on SW1 and set it.
14.	First-byte of remote IP address ¹	6	Setting not necessary	Setting not necessary	Lights off	Set a value on SW2 and 3.
15.	First-byte of remote IP address	6→7			Red lamp lights on	Modify a value on SW1 and set it.
16.	Second-byte of remote IP address ¹	7	Setting not necessary	Setting not necessary	Red lamp lights on	Set a value on SW2 and 3.
17.	Second-byte of remote IP address	7→8			Lights off	Modify a value on SW1 and set it.
18.	Third-byte of remote IP address ¹	8	Setting not necessary	Setting not necessary	Lights off	Set a value on SW2 and 3.
19.	Third-byte of remote IP address	8→9			Red lamp lights on	Modify a value on SW1 and set it.
20.	Fourth-byte of remote IP address ¹	9	Setting not necessary	Setting not necessary	Red lamp lights on	Set a value on SW2 and 3.
21.	Fourth-byte of remote IP address Subnet mask CIDR ²	9→A			Lights off	Modify a value on SW1 and set it. If FAIL/RUN lamp turns off, backup was successfully completed. If FAIL/RUN lamp blinks red, backup failed.

¹ There is no need to change the remote IP address. Please use the factory set value as it is.

² The Subnet mask CIDR is set to a default value of 24.

Example 3: When “502” is set, as it is expressed as “01F6” in hexadecimal notation, the low-order byte is “F6”. Set “F” on SW2 and “6” on SW3.

22. Turn off the power.

Set the DIP switch No.6 to OFF and No.7 to OFF. Return the setting of SW1, SW2 and SW3 to the original values. Turn ON the power. This completes the setting.



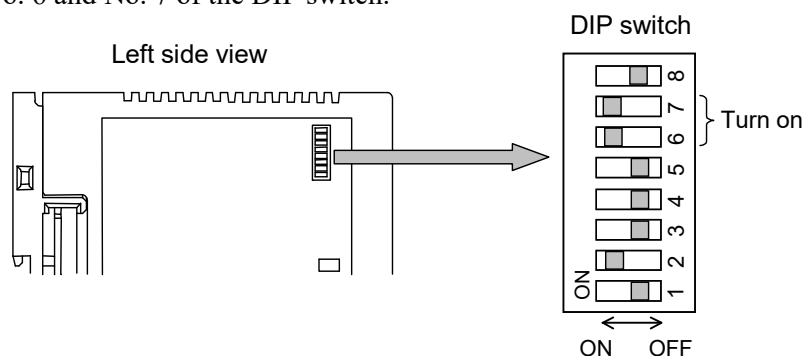
To redo the setting halfway through, start from Step 1.

7.3.2 Default IP address setting

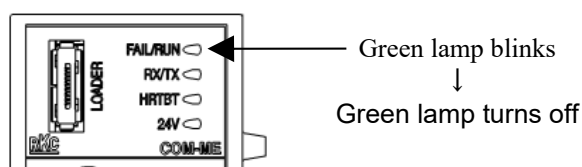
The IP address of the COM-ME can be set to the factory set value using the DIP switches.


■ Operation procedure

1. Turn off the power of the COM-ME.
2. Turn on No. 6 and No. 7 of the DIP switch.




3. Turn on the power of the COM-ME.
4. The FAIL/RUN lamp will blink green for about 5 seconds and then turns off.
At this point, the IP address of the COM-ME changes to the factory set value “192.168.1.1.”



 If default IP address setting fails, the FAIL/RUN lamp blinks green for about 5 seconds, then turns off. After that, the FAIL/RUN lamp starts blinking red.

5. Turn off the power of the COM-ME once again and return DIP switches No. 6 and No. 7 to OFF.

 If DIP switches No. 6 and No. 7 are left ON, the set IP address of the COM-ME will revert to the factory set value every time the power is turned on.

6. Turn the power of the COM-ME back on. This completes the procedure.

7.4 Other Communication Data Settings

Set communication data (PID constants and event set values of the Z-TIO module, DO manual output of the Z-DIO module, etc.) using host communication or loader communication.



When host communication or loader communication is used to configure the IP address setting, and thus it is possible to continue configuring other communication data settings after the IP address setting.



For each of the communication setting items, see **9. COMMUNICATION DATA LIST (P. 52)**.

■ Host communication settings by loader communication

Communication protocol, communication speed and data bit configuration can be set by loader communication.



NOTE

To activate the setting via the Loader communication or the Host communication, set the DIP switch No.8 to ON. When the switch is set to “ON”, the setting of the DIP switch will be disabled.

Set the items in the same way as “7.2 Loader Communication Settings” (P. 29; same procedures up to Step 5 of “Setting of PROTEM 2”).

<input checked="" type="checkbox"/>	Host communication protocol	0
<input checked="" type="checkbox"/>	Host communication communication speed	2
<input checked="" type="checkbox"/>	Host communication data bit configuration	0
<input checked="" type="checkbox"/>	Host communication interval time	10

R/W: Read/Write

Name	RKC identifier	Modbus register address		Digits	Attribute	Data range	Factory set value
		HEX	DEC				
Host communication Protocol	VP	8004	32772	1	R/W	0: RKC communication 1: Modbus	0
Host communication Communication speed	VU	8005	32773	1	R/W	0: 9600 bps 1: 9600 bps 2: 19200 bps 3: 38400 bps 4: 57600 bps	2
Host communication Data bit configuration	VW	8006	32774	7	R/W	Modbus: 0 to 2, 6 to 8 RKC communication: 0 to 11 See Data bit configuration table (P. 38) .	0
Host communication Interval time	VX	8007	32775	7	R/W	0 to 250 ms	10

Data bit configuration table

Set value	Data bit	Parity bit	Stop bit	Modbus	RKC communication
0	8	None	1	Can be set	Can be set
1	8	Even	1		
2	8	Odd	1		
3	7	None	1	Cannot be set	
4	7	Even	1		
5	7	Odd	1		
6	8	None	2	Can be set	
7	8	Even	2		
8	8	Odd	2		
9	7	None	2	Cannot be set	
10	7	Even	2		
11	7	Odd	2		

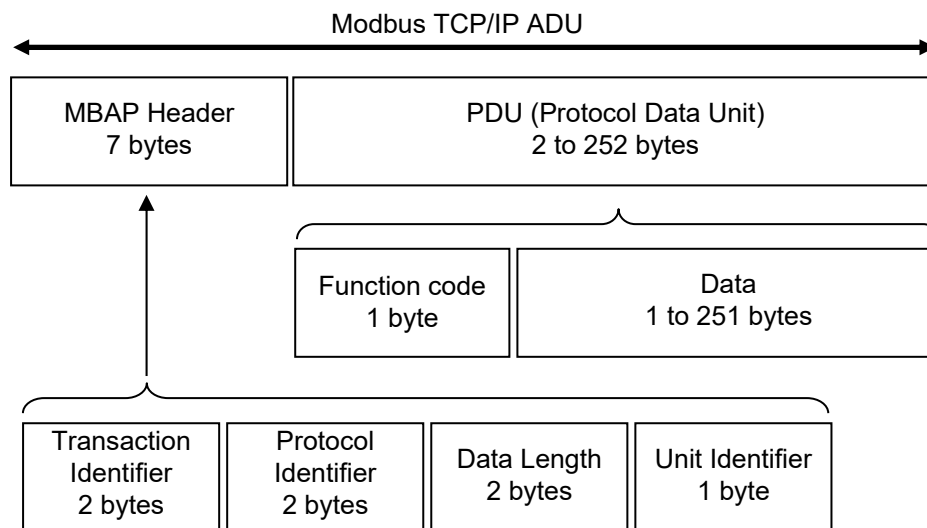
8. MODBUS/TCP PROTOCOL

Modbus/TCP is an open field network provided with the Modbus protocol on the TCP/IP protocol of Ethernet.

The data request side is called “client” (such as computer) and the data response (supply) side is called “server” (COM-ME).

8.1 Message Configuration

Modbus ADU (Application Data Unit) on TCP/IP is in the following configuration.



■ MBAP Header

MBAP (Modbus Application Protocol) header contains the following fields: Transaction Identifier, Protocol Identifier, Data Length and Unit Identifier.

Fields	Length	Request (Client)	Response (Server)
Transaction Identifier	2 bytes	Unused However, data corresponding to two bytes is sent According to need, request and the response are used in order to take consistency	Returns data from the client as is
Protocol Identifier	2 bytes	“0” fixed (Modbus protocol = 0)	Returns data from the client as is
Data Length	2 bytes	The total number of bytes of Unit Identifier and PDU (253 bytes max.)	The total number of bytes of Unit Identifier and PDU (253 bytes max.)
Unit Identifier	1 byte	Unused However, data corresponding to one byte is sent According to need, request and the response are used in order to take consistency	Returns data from the client as is

■ PDU

PDU (Protocol Data Unit) consists of two blocks: function codes and data.

Fields	Length	Request (Client)	Response (Server)
Function code	1 byte	03H: Read holding registers 06H: Write single register 10H: Write multiple registers	Normal response Returns data from the client as is Error response 80H + Function code
Data	1 to 251 bytes	Data meeting the function code	Normal response Data meeting the function code Error response Exception code 01H: Illegal function code 02H: Illegal register address 03H: Illegal data value

8.2 Function Code

● Function code contents

Function code	Function	Contents
03H	Read holding registers	Measured value, Control output value, Current transformer input value, Event status, etc.
06H	Write single register	Set value, PID constants, Event set value, etc.
10H	Write multiple registers	Set value, PID constants, Event set value, etc.

● Message (PDU) length of each function [Unit: byte]

Function code	Function	Request message		Response message	
		Min	Max	Min	Max
03H	Read holding registers	5	5	4	252
06H	Write single register	5	5	5	5
10H	Write multiple registers	8	252	5	5

8.3 Server (COM-ME) Responses

■ Normal response

- In the response message of the read holding registers, the server (COM-ME) returns the “Function code,” “Number of data items” and the “Read out data” as the response message.
- In the response message of the write single register, the server (COM-ME) returns the same message as the request message.
- In the response message of the write multiple registers, the server (COM-ME) returns the “Function code,” the “Register address number” and the “Number of register” as the response message.

■ Defective message response

- If the request message from the client is defective, except for transmission error, the server (COM-ME) returns the exception response message without any action.
- If the self-diagnostic function of the server (COM-ME) detects an error, the server will return an exception response message to all request messages.
- The function code of each exception response message is obtained by adding “80H” to the function code of the request message.

Function code
Exception code

Exception response message

Exception code	Contents	Causes
01H	Illegal function code	An unsupported function code was specified
02H	Illegal register address	When the mismatched register address is specified.
03H	Illegal data value	<ul style="list-style-type: none"> • The number of specified data points was out of the following range during data read or write. Function code 03H: 1 to 125 Function code 10H: 1 to 123 • When the data written exceeds the setting range

Exception code priority order

Order of a no response in PDU data length error > 01H > 03H > 02H

■ No response

The server (COM-ME) ignores the request message and does not respond when:

- The IP address does not coincide.
- The server (COM-ME) is not connected to the network.
- The PDU (Protocol Data Unit) data length is abnormal.

When the PDU data length specified by the request message does not coincide with the number of bytes received as one TCP packet.

8.4 Message Format

8.4.1 Read holding registers [03H]

The request message specifies the starting register address number and quantity of register addresses to be read.

The contents of the registers are entered in the response message as data, divided into two parts: the high-order eight bits and low-order eight bits, arranged in the order of the register numbers.

Example: The contents of the four registers from 01FCH to 01FFH are the read out.

Request message [Client]

Transaction Identifier	High	00H	} MBAP Header
	Low	00H	
Protocol Identifier	High	00H	
	Low	00H	
Data Length	High	00H	
	Low	06H	
Unit Identifier		00H	} First register address
Function code		03H	
Register address	High	01H	} The setting must be between 1 (0001H) and 125 (007DH).
	Low	FCH	
Quantity (Number of words)	High	00H	
	Low	04H	

Normal response message [Server]

Transaction Identifier	High	00H	} MBAP Header
	Low	00H	
Protocol Identifier	High	00H	
	Low	00H	
Data Length	High	00H	
	Low	0BH	
Unit Identifier		00H	} Number of registers × 2
Function code		03H	
Number of data (byte)		08H	
First register contents	High	01H	
	Low	24H	
Next register contents	High	01H	
	Low	1BH	
Next register contents	High	01H	
	Low	2BH	
Next register contents	High	01H	
	Low	22H	

Exception response message [Sever]

Transaction Identifier	High	00H	} MBAP Header
	Low	00H	
Protocol Identifier	High	00H	
	Low	00H	
Data Length	High	00H	
	Low	03H	
Unit Identifier		00H	} Outside the specified number of data points
80H + Function code		83H	
Exception code		03H	

8.4.2 Write single register [06H]

The request message specifies data to be written into the designated register.

Write data items are arranged in the request message in order starting from the smallest register address number. In addition, each register address is assigned in the order of high-order eight bits and low-order eight bits, respectively.

Example: When 100 (64H) is written to the register 0ADCH

Request message [Client]

Transaction Identifier	High	00H	} MBAP Header
	Low	00H	
Protocol Identifier	High	00H	
	Low	00H	
Data Length	High	00H	
	Low	06H	
Unit Identifier		00H	} Any data within the range
Function code		06H	
Register address	High	0AH	} Any data within the range
	Low	DCH	
Write data	High	00H	
	Low	64H	

Normal response message [Server]

Transaction Identifier	High	00H	} Contents will be the same as request message data
	Low	00H	
Protocol Identifier	High	00H	
	Low	00H	
Data Length	High	00H	
	Low	06H	
Unit Identifier		00H	
Function code		06H	
Register address	High	0AH	
	Low	DCH	
Write data	High	00H	
	Low	64H	

Exception response message [Sever]

Transaction Identifier	High	00H	} MBAP Header
	Low	00H	
Protocol Identifier	High	00H	
	Low	00H	
Data Length	High	00H	
	Low	03H	
Unit Identifier		00H	→ When the data exceeds the setting range
80H + Function code		86H	
Exception code		03H	

8.4.3 Write multiple registers [10H]

Each data is written to registers in specified quantities starting from the specified register address. Write data items are arranged in the request message in order starting from the smallest register address number. In addition, each register address is assigned in the order of high-order eight bits and low-order eight bits, respectively.

Example: When 100 (64H) and 120 (78H) are written to the register 0ADCH and 0ADDH (two in total)

Request message [Client]

Transaction Identifier	High	00H	} MBAP Header
	Low	00H	
Protocol Identifier	High	00H	
	Low	00H	
Data Length	High	00H	
	Low	0BH	
Unit Identifier		00H	} First register address
Function code		10H	
Register address	High	0AH	} The setting must be between 1 (0001H) and 123 (007BH).
	Low	DCH	
Quantity (Number of words)	High	00H	} Quantity (Number of words) × 2
	Low	02H	
Number of data (byte)		04H	
Data to first register	High	00H	
	Low	64H	
Data to next register	High	00H	
	Low	78H	

Normal response message [Server]

Transaction Identifier	High	00H	} MBAP Header
	Low	00H	
Protocol Identifier	High	00H	
	Low	00H	
Data Length	High	00H	
	Low	06H	
Unit Identifier		00H	} First register address
Function code		10H	
Register address	High	0AH	
	Low	DCH	
Quantity (Number of words)	High	00H	
	Low	02H	

Exception response message [Sever]

Transaction Identifier	High	00H	} MBAP Header
	Low	00H	
Protocol Identifier	High	00H	
	Low	00H	
Data Length	High	00H	
	Low	03H	
Unit Identifier		00H	
80H + Function code		90H	
Exception code		03H	→ When the data exceeds the setting range

8.5 Data Processing Precautions

- The numeric range of data used in Modbus protocol is 0000H to FFFFH. Only the set value within the setting range is effective.



FFFFH represents -1.

- The Modbus protocol does not recognize data with decimal points during communication.

Example1: When Heater break alarm (HBA) set value is 20.0 A, 20.0 is processed as 200,
200 = 00C8H

Heater break alarm (HBA) set value	High	00H
	Low	C8H

Example2: When Set value (SV) is -20.0 °C, -20.0 is processed as -200,
-200 = 0000H - 00C8H = FF38H

Set value (SV)	High	FFH
	Low	38H

- In this communication, the data that memory area includes handles different address with for Control area and for setting area.
- If data (register) exceeding the accessible address range is accessed, an exception response message is returned.
- Read data of unused item is a default value.
- Any attempt to write to an unused item is not processed as an error. Data cannot be written into an unused item.
- If an error (data range error) is detected in the data writing process, an exception response message is returned. Writing is aborted at and after the addresses where an error occurred. After having completed the setting, check to see if the data was properly written.
- An attribute of the item for functions which are not in the controller is RO (read only). If read action to this item is performed, the read data will be "0." If write action to this item is performed, no error message is indicated and no data is written.



For details, see **9. COMMUNICATION DATA LIST (P. 52)**.

- When writing of the following communication data of a Z-TIO module is performed, the next writing procedure for the changed Z-TIO module will not be possible for 4 to 6 seconds.
 - Input type
 - Display unit
 - Decimal point position
 - Integral/Derivative time decimal point position

8.6 How to Use Memory Area Data

Memory area function can store up to 8 individual sets of SVs and parameters. One of the areas is used for control, and the currently selected area is Control area.

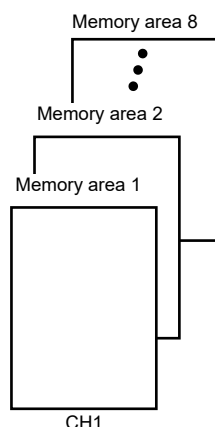
Memory area data can be used to check and change settings that belong to memory areas other than the Control area. Reading and writing of memory area data is performed by channel.

■ Read and write of memory area data

If any Memory area number to perform data read and write is specified by the Setting memory area number (386CH to 38ABH), data corresponding to the specified Memory area number is called up to the register addresses from 38ACH to 3DABH. By using these register addresses from 38ACH to 3DABH, it becomes possible to read and write data in any memory area.

	Register address				
	CH1	CH2	CH64	
Setting memory area number	386CH	386DH	38ABH	← Register address to specify memory area
Event 1 set value (EV1)	38ACH	38ADH	38EBH	
Event 2 set value (EV2)	38ECH	38EDH	392BH	Register address of memory area data
Event 3 set value (EV3)	392CH	392DH	396BH	
Event 4 set value (EV4)	396CH	396DH	39ABH	
Control loop break alarm (LBA) time	39ACH	39ADH	39EBH	
LBA deadband	39ECH	39EDH	3A2BH	
Set value (SV)	3A2CH	3A2DH	3A6BH	
Proportional band [heat-side]	3A6CH	3A6DH	3AABH	
Integral time [heat-side]	3AACH	3AADH	3AEBH	
Derivative time [heat-side]	3AECH	3AEDH	3B2BH	
Control response parameter	3B2CH	3B2DH	3B6BH	
Proportional band [cool-side]	3B6CH	3B6DH	3BABH	
Integral time [cool-side]	3BACH	3BADH	3BEBH	
Derivative time [cool-side]	3BECH	3BEDH	3C2BH	
Overlap/Deadband	3C2CH	3C2DH	3C6BH	
Manual reset	3C6CH	3C6DH	3CABH	
Setting change rate limiter (up)	3CACH	3CADH	3CEBH	
Setting change rate limiter (down)	3CECH	3CEDH	3D2BH	
Area soak time	3D2CH	3D2DH	3D6BH	
Link area number	3D6CH	3D6DH	3DABH	

☞ For the Memory area data list, see **9.4 Memory Area Data Address of Z-TIO Module (only for Modbus) (P. 83)**.



A memory area number which data is read/written is written to the register address, 386CH (for CH1).

Data corresponding to a specified Memory area number is called up to the CH1 register addresses.

Event 1 set value (EV1) (38ACH)
 Event 2 set value (EV2) (38ECH)
 Event 3 set value (EV3) (392CH)
 Event 4 set value (EV4) (396CH)
 Control loop break alarm (LBA) time (39ACH)
 LBA deadband (39ECH)
 Set value (SV) (3A2CH)
 Proportional band [heat-side] (3A6CH)
 Integral time [heat-side] (3AACH)
 Derivative time [heat-side] (3AECH)
 Control response parameter (3B2CH)
 Proportional band [cool-side] (3B6CH)
 Integral time [cool-side] (3BACH)
 Derivative time [cool-side] (3BECH)
 Overlap/Deadband (3C2CH)
 Manual reset (3C6CH)
 Setting change rate limiter (up) (3CACH)
 Setting change rate limiter (down) (3CECH)
 Area soak time (3D2CH)
 Link area number (3D6CH)

[Example 1] When data on the Event 1 set value in Memory area 2 of CH1 is read

1. The Memory area number, "2" is written to the CH1 Setting memory area number (386CH).
Data in Memory area 2 is called up to the CH1 register addresses.

CH1 register addresses			
Setting memory area number	386CH	2	← Memory area number "2"
Event 1 set value (EV1)	38ACH	50	The data of memory area 2 is loaded into these register addresses.
Event 2 set value (EV2)	38ECH		
Event 3 set value (EV3)	392CH		
Event 4 set value (EV4)	396CH		
Control loop break alarm (LBA) time	39ACH		
LBA deadband	39ECH		
Set value (SV)	3A2CH		
Proportional band [heat-side]	3A6CH		
Integral time [heat-side]	3AACH		
Derivative time [heat-side]	3AECH		
Control response parameter	3B2CH		
Proportional band [cool-side]	3B6CH		
Integral time [cool-side]	3BACH		
Derivative time [cool-side]	3BECH		
Overlap/Deadband	3C2CH		
Manual reset	3C6CH		
Setting change rate limiter (up)	3CACH		
Setting change rate limiter (down)	3CECH		
Area soak time	3D2CH		
Link area number	3D6CH		

2. Data "50" on Event 1 set value (38ACH) is read.

[Example 2] When the Set value (SV) in Memory area 3 of CH1 is changed to 200

1. The Memory area number, "3" is written to the CH1 Setting memory area number (386CH).
Data in Memory area 3 is called up to the CH1 register addresses.

CH1 register addresses			
Setting memory area number	386CH	3	← Memory area number "3"
Event 1 set value (EV1)	38ACH		The data of memory area 3 is loaded into these register addresses.
Event 2 set value (EV2)	38ECH		
Event 3 set value (EV3)	392CH		
Event 4 set value (EV4)	396CH		
Control loop break alarm (LBA) time	39ACH		
LBA deadband	39ECH		
Set value (SV)	3A2CH	150	
Proportional band [heat-side]	3A6CH		
Integral time [heat-side]	3AACH		
Derivative time [heat-side]	3AECH		
Control response parameter	3B2CH		
Proportional band [cool-side]	3B6CH		
Integral time [cool-side]	3BACH		
Derivative time [cool-side]	3BECH		
Overlap/Deadband	3C2CH		
Manual reset	3C6CH		
Setting change rate limiter (up)	3CACH		
Setting change rate limiter (down)	3CECH		
Area soak time	3D2CH		
Link area number	3D6CH		

2. "200" is written to the Set value (SV) (3A2CH).

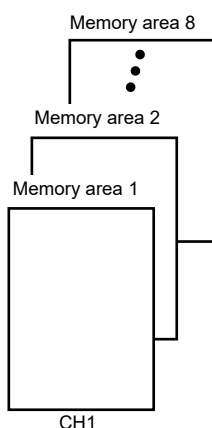
■ Control area transfer

Any memory area used for control is specified by the Memory area transfer (08DCH to 091BH). The area (095CH to 0E5BH) now used for control is called Control area.



The Memory area number (Control area) can be changed at either RUN or STOP.

	Register address				
	CH1	CH2	CH64	
Memory area transfer	08DCH	08DDH	091BH	← Register address to specify Control area
Event 1 set value (EV1)	095CH	095DH	099BH	
Event 2 set value (EV2)	099CH	099DH	09DBH	Register address of memory area data
Event 3 set value (EV3)	09DCH	09DDH	0A1BH	
Event 4 set value (EV4)	0A1CH	0A1DH	0A5BH	
Control loop break alarm (LBA) time	0A5CH	0A5DH	0A9BH	
LBA deadband	0A9CH	0A9DH	0ADBH	
Set value (SV)	0ADCH	0ADDH	0B1BH	
Proportional band [heat-side]	0B1CH	0B1DH	0B5BH	
Integral time [heat-side]	0B5CH	0B5DH	0B9BH	
Derivative time [heat-side]	0B9CH	0B9DH	0BDBH	
Control response parameter	0BDCH	0BDDH	0C1BH	
Proportional band [cool-side]	0C1CH	0C1DH	0C5BH	
Integral time [cool-side]	0C5CH	0C5DH	0C9BH	
Derivative time [cool-side]	0C9CH	0C9DH	0CDBH	
Overlap/Deadband	0CDCH	0CDDH	0CDCH	
Manual reset	0D1CH	0D1DH	0D5BH	
Setting change rate limiter (up)	0D5CH	0D5DH	0D9BH	
Setting change rate limiter (down)	0D9CH	0D9DH	0DDBH	
Area soak time	0DDCH	0DDDH	0E1BH	
Link area number	0E1CH	0E1CH	0E5BH	



Any memory area number used for control is written to the register address, 08DCH (for CH1).

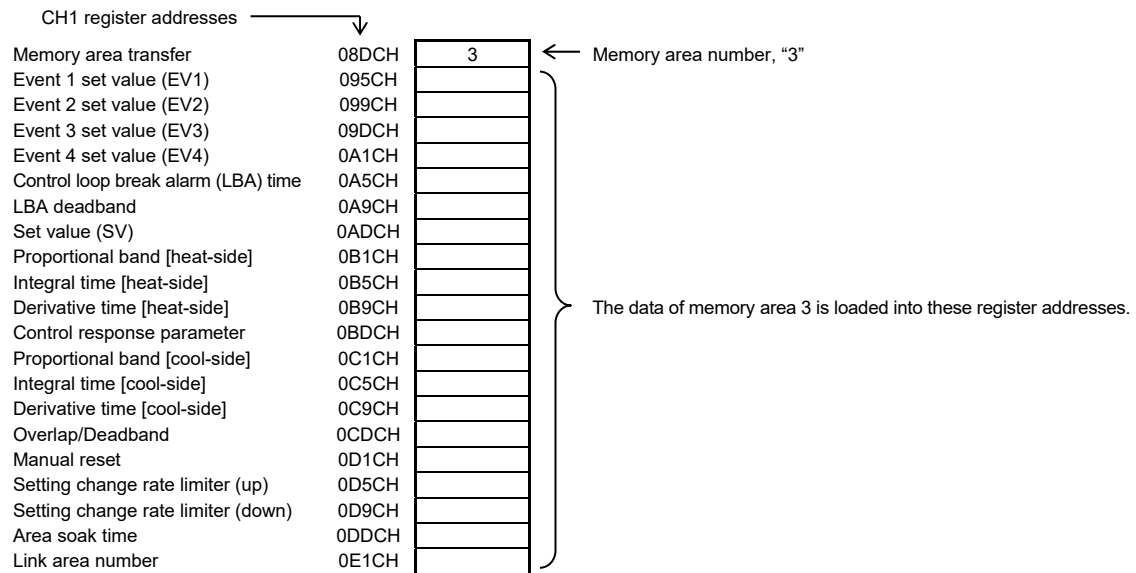
Data corresponding to a specified Memory area number is called up to the CH1 register addresses.

— Control area —

- Event 1 set value (EV1) (095CH)
- Event 2 set value (EV2) (099CH)
- Event 3 set value (EV3) (09DCH)
- Event 4 set value (EV4) (0A1CH)
- Control loop break alarm (LBA) time (0A5CH)
- LBA deadband (0A9CH)
- Set value (SV) (0ADCH)
- Proportional band [heat-side] (0B1CH)
- Integral time [heat-side] (0B5CH)
- Derivative time [heat-side] (0B9CH)
- Control response parameter (0BDCH)
- Proportional band [cool-side] (0C1CH)
- Integral time [cool-side] (0C5CH)
- Derivative time [cool-side] (0C9CH)
- Overlap/Deadband (0CDCH)
- Manual reset (0D1CH)
- Setting change rate limiter (up) (0D5CH)
- Setting change rate limiter (down) (0D9CH)
- Area soak time (0DDCH)
- Link area number (0E1CH)

[Example] When performing control by calling up data in Memory area 3 of CH1

1. The Memory area number, "3" is written to the Memory area transfer (08DCH).
Data in Memory area 3 is called up to the CH1 register addresses.



2. Control of CH1 is performed by using data in the register addresses.



If the Memory area transfer (08DCH to 091BH) and the setting Memory area number (386CH to 38ABH) are set to the same Memory area number, the respective data can be synchronized.

- (1) Values in the Control areas (095CH to 0E5BH) and the Setting memory area number (38ACH to 3DABH) are set to the same Memory area number, the respective data can be synchronized.
- (2) If data in the Control area is changed, data in the memory area is also changed.
- (3) If data in the memory area is changed, data in the Control area is also changed.

9. COMMUNICATION DATA LIST

9.1 Reference to Communication Data List

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
1	Measured value (PV)	M1	CH1 . . CH64	01FC . . 023B	508 . . 571	7	RO	C	Input scale low to Input scale high	—

(1) **Name:** Communication data name

(2) **RKC identifier:** Communication identifier of RKC communication

(3) **Channel:** Channel number of data of one unit

(4) **Modbus register address:**

Register address of Modbus data item specification

HEX: Hexadecimal

DEC: Decimal

(5) **Digits:** The number of communication data digits in RKC communication

(6) **Attribute:** A method of how communication data items are read or written when viewed from the host computer is described

RO: Read only data

Data direction
Host computer ← COM-ME

R/W: Read and Write data

Data direction
Host computer ↔ COM-ME

(7) **Structure:** C: Data for each channel ^{1,2}

M: Data for each module

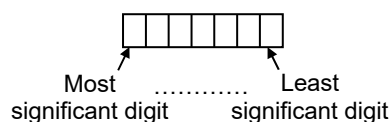
U: Data for each SRZ unit

¹ On a Z-TIO module (2-channel type), the communication data of the CH3 and CH4 becomes invalid.

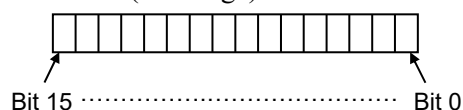
² Parameters only used for Heat/Cool control or position proportioning control, therefore data for CH2 and CH4 of Z-TIO modules are unused. [Read is possible (0 is shown), but the result of Write is disregarded.]

(8) **Data range:** Read or write range of communication data

• ASCII code data (Example: 7 digits)



• 16-bit data (bit image)



(9) **Factory set value:** Factory set value of communication data



This area is not used by COM-ME-1.

WARNING

The Engineering setting data should be set according to the application before setting any parameter related to operation. Once the communication data in the Engineering mode are set correctly, no further changes need to be made to parameters for the same application under normal conditions. If they are changed unnecessarily, it may result in malfunction or failure of the instrument. RKC will not bear any responsibility for malfunction or failure as a result of improper changes in the Engineering mode.

**NOTE**

Some of the communication data of the COM-ME will not be enabled until the power is turned on again.

Communication data No. 21, 23, 25 to 27*, 40 to 43, 45 and 47 to 51

* COM-ME communication data Nos. 25 to 27 will also be enabled when the RUN/STOP transfer (Each unit) [Identifier: SR, Register address: 0133H] is switched from STOP to RUN.

**NOTE**

Communication data includes both “Normal setting data” and “Engineering setting data.” During RUN (control), the attribute of Engineering setting data is RO. To configure Engineering setting data, the RUN/STOP transfer (Each unit) [Identifier: SR, Register address: 0133H] must be set to STOP (control stopped).

Z-TIO module: Normal setting data No. 1 to 85

Engineering setting data No. 86 to 208 ^{1,2}

¹ No. 147, 148, 151 and 152:

Settable during control (RUN state)

² No. 89 to 133, No.135 to 146, No.149, No. 150, and No. 153 to 206:

Settable: when the RUN/STOP transfer (Each unit) [Identifier: SR, Register address: 0133H] is set to STOP or when the Operation mode [Identifier: EI, Register address: 161CH to 165BH] is set in the RUN state (control) to “0: Unused” or to “1: Monitor”.

Z-DIO module: Normal setting data No. 1 to 13

Engineering setting data No. 14 to 27 ³

³ No. 24 and 25:

Settable during control (RUN state)

Z-CT module: Normal setting data No. 1 to 16

Engineering setting data No. 17 to 28 ⁴

⁴ No. 17 to 28:

When the set lock [Identifier: LK, Register address: 5E0CH to 5E1BH] is set to “0: Unlock,” writing data is possible.

9.2 Communication Data of COM-ME

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
1	Serial number (COM-ME)	RX	CH1	—	—	8	RO	M	Character	—
2	Serial number (Function module)	RZ	CH1 ⋮ CH100	—	—	8	RO	M	Character	—
3	Model code (COM-ME)	ID	CH1	—	—	32	RO	M	Model code (character)	—
4	Model code (Function module)	IE	CH1 ⋮ CH100	—	—	32	RO	M	Model code (character)	—
5	ROM version (COM-ME)	VR	CH1	—	—	8	RO	M	ROM version	—
6	ROM version (Function module)	VQ	CH1 ⋮ CH100	—	—	8	RO	M	ROM version	—
7	Integrated operating time monitor (COM-ME)	UT	CH1	—	—	7	RO	M	0 to 19999 hours	—
8	Integrated operating time monitor (Function module)	UV	CH1 ⋮ CH100	—	—	7	RO	M	0 to 19999 hours	—
9	Error code (COM-ME)	ER	CH1	0000	0	7	RO	U	1: Adjustment data error ¹ 2: Data back-up error 4: A/D conversion error ¹ (Temperature compensation error included) 16: Internal communication error ² 32: Error of custom data ¹ (Error of downloaded data of logic output) 64: Stack overflow ² ¹ Only the function module ² Only the COM-ME The error condition is shown by the OR of each module. When multiple errors occur, the error No. is the sum value.	—
10	Error code (Function module)	EZ	CH1 ⋮ CH100	0001 ⋮ 0064	1 ⋮ 100	7	RO	M	1: Adjustment data error 2: Data back-up error 4: A/D conversion error (Temperature compensation error included) 32: Error of custom data (Error of downloaded data of logic output) When multiple errors occur, the error No. is the sum value.	—

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
11	Backup memory state monitor (COM-ME)	EM	CH1	0065	101	1	RO	M	0: The content of the backup memory does not coincide with that of the RAM. 1: The content of the backup memory coincides with that of the RAM.	—
12	Backup memory state monitor (Function module)	CZ	CH1 ⋮ CH100	0066 ⋮ 00C9	102 ⋮ 201	1	RO	M		—
13	System communication state	QM	CH1	00CA	202	1	RO	U	Bit data Bit 0: Data collection condition Bit 1 to Bit 15: Unused Data 0: Before data collection is completed 1: Data collection is completed [Decimal number: 0, 1]	—
14	—	—	—	00CB	203	—	—	—	—	—
15	Network error code	ES	CH1	00CC	204	7	RO	U	Bit data Bit 0: Network operation not possible Bit 1 to Bit 15: Unused Data 0: OFF 1: ON [Decimal number: 0, 1]	—
16	—	—	—	00CD ⋮ 0131	205 ⋮ 305	—	—	—	—	—
17	Monitor for the number of connected modules	QK	CH1	0132	306	7	RO	U	0 to 31	—
18	RUN/STOP transfer ¹ (Each unit)	SR	CH1	0133	307	1	R/W	U	0: STOP (Control stop) 1: RUN (Control start)	0
19	RUN/STOP transfer ² (Each module)	SW	CH1 ⋮ CH100	0134 ⋮ 0197	308 ⋮ 407	1	R/W	M	0: STOP (Control stop) 1: RUN (Control start)	0
20	Control RUN/STOP holding setting ^{2,3} (Each module)	X1	CH1 ⋮ CH100	0198 ⋮ 01FB	408 ⋮ 507	1	R/W	M	0: Not holding (STOP start) 1: Holding (RUN/STOP hold)	1
21	Ethernet selection ⁴	VK	CH1	8000	32768	1	R/W	U	0: Modbus/TCP 1 to 9999: Reserved	0
22	—	—	—	8001	32769	—	—	—	—	—
23	TCP port number ⁴	VM	CH1	8002	32770	7	R/W	U	0 to 65535	502
24	—	—	—	8003	322771	—	—	—	—	—

¹ When RUN/STOP transfer (Each unit) [Identifier: SR, Register address: 0133H] becomes STOP, the set lock [Identifier: LK, Register address: 5E0CH to 5E1BH] of the Z-CT module becomes “0: Unlock”.

² This item does not support a Z-CT module.

³ Settable only when the RUN/STOP transfer (Each unit) [Identifier: SR, Register address: 0133H] is switched to STOP.

⁴ Data that are activated by rebooting

9. COMMUNICATION DATA LIST

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
25	Host communication protocol ^{1,2}	VP	CH1	8004	32772	1	R/W	U	0: RKC communication 1: Modbus	0
26	Host communication communication speed ^{1,2}	VU	CH1	8005	32773	1	R/W	U	0: 9600 bps 1: 9600 bps 2: 19200 bps 3: 38400 bps 4: 57600 bps	2
27	Host communication data bit configuration ^{1,2}	VW	CH1	8006	32774	7	R/W	U	0 to 11 See Table 1: Data bit configuration	0
28	Host communication interval time	VX	CH1	8007	32775	7	R/W	U	0 to 250 ms	10
29	—	—	—	8008 ⋮ 8010	32776 ⋮ 32784	—	—	—	—	—
30	Method for setting the number of connected modules	RY	CH1	8011	32785	7	R/W	U	0: No action 1: Automatically set the maximum number of connected function modules only when power is turned on. 2: Execute automatic setting of the maximum number of connected function modules. (After automatic setting of the number of connected function modules, the value automatically reverts to 0.)	1
31	—	—	—	8012	32786	—	—	—	—	—
32	Number of connected modules ³ (Z-TIO module)	QY	CH1	8013	32787	7	R/W	U	0 to 16 This is the maximum address of the Z-TIO module that is connected to the COM-ME.	—
33	Number of connected modules ³ (Z-DIO module)	QU	CH1	8014	32788	7	R/W	U	0 to 16 This is the maximum address of the Z-DIO module that is connected to the COM-ME.	—
34	Number of connected modules ³ (Z-CT module)	QO	CH1	8015	32789	7	R/W	U	0 to 16 This is the maximum address of the Z-CT module that is connected to the COM-ME.	—
35	Number of connected modules (Module 4)	QP	CH1	8016	32790	7	R/W	U	0 to 16	—
36	Number of connected modules (Module 5)	QR	CH1	8017	32791	7	R/W	U	0 to 16	—
37	Number of connected modules (Module 6)	RI	CH1	8018	32792	7	R/W	U	0 to 16	—

¹ Data that are activated by rebooting

² Enabled when the RUN/STOP transfer (Each unit) [Identifier: SR, Register address: 0133H] is switched to RUN from STOP.

³ When 1 or 2 is set for the communication identifier RY (method of setting the number of connected modules), the maximum number of connected modules is set automatically. When 0 is set, the maximum number of connected modules is set manually.
Maximum number of connected modules: Maximum address of function modules (address setting switch set value + 1)
COM-ME uses this set value to calculate the number of channels of communication data (RKC communication only).

Table 1: Data bit configuration

Set value	Data bit	Parity bit	Stop bit	Settable communication
0	8	None	1	Modbus RKC communication
1	8	Even	1	
2	8	Odd	1	
3	7	None	1	RKC communication
4	7	Even	1	
5	7	Odd	1	

Set value	Data bit	Parity bit	Stop bit	Settable communication
6	8	None	2	Modbus RKC communication
7	8	Even	2	
8	8	Odd	2	
9	7	None	2	RKC communication
10	7	Even	2	
11	7	Odd	2	

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
38	Number of connected modules (Module 7)	RQ	CH1	8019	32793	7	R/W	U	0 to 4	—
39	—	—	—	801A	32794	—	—	—	—	—
40	First-byte of IP address *	QB	CH1	801B	32795	7	R/W	U	0 to 255	192
41	Second-byte of IP address *	QC	CH1	801C	32796	7	R/W	U	0 to 255	168
42	Third-byte of IP address *	QD	CH1	801D	32797	7	R/W	U	0 to 255	1
43	Fourth-byte of IP address *	QE	CH1	801E	32798	7	R/W	U	0 to 255	1
44	—	—	—	801F ⋮ 80B6	32799 ⋮ 32950	—	—	—	—	—
45	Control RUN/STOP holding setting * (Each unit)	X2	CH1	80B7	32951	1	R/W	U	0: Not holding (STOP start) 1: Holding (RUN/STOP hold)	1
46	—	—	—	80B8 ⋮ 813E	32952 ⋮ 33086	—	—	—	—	—
47	First-byte of gateway address *	W1	CH1	813F	33087	7	R/W	U	0 to 255	0
48	Second-byte of gateway address *	W2	CH1	8140	33088	7	R/W	U	0 to 255	0
49	Third-byte of gateway address *	W3	CH1	8141	33089	7	R/W	U	0 to 255	0
50	Fourth-byte of gateway address *	W4	CH1	8142	33090	7	R/W	U	0 to 255	0
51	Subnet mask CIDR *	W5	CH1	8143	33091	7	R/W	U	0 to 32	24
52	—	—	—	8144 ⋮ 8FFF	33092 ⋮ 36863	—	—	—	—	—

* Data that are activated by rebooting

9.3 Communication Data of Z-TIO Module

☞ For details of Z-TIO module communication data, refer to **SRZ Instruction Manual (IMS01T04-E□)**.

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
1	Measured value (PV)	M1	CH1 ⋮ CH64	01FC ⋮ 023B	508 ⋮ 571	7	RO	C	Input scale low to Input scale high	—
2	Comprehensive event state	AJ	CH1 ⋮ CH64	023C ⋮ 027B	572 ⋮ 635	7	RO	C	<ul style="list-style-type: none"> • RKC communication Least significant digit: <ul style="list-style-type: none"> Event 1 2nd digit: Event 2 3rd digit: Event 3 4th digit: Event 4 5th digit: Heater break alarm (HBA) 6th digit: Temperature rise completion 7th digit: Burnout Data 0: OFF 1: ON • Modbus Bit data Bit 0: Event 1 Bit 1: Event 2 Bit 2: Event 3 Bit 3: Event 4 Bit 4: Heater break alarm (HBA) Bit 5: Temperature rise completion Bit 6: Burnout Bit 7 to Bit 15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 127] 	—
3	Operation mode state monitor	L0	CH1 ⋮ CH64	027C ⋮ 02BB	636 ⋮ 699	7	RO	C	<ul style="list-style-type: none"> • RKC communication Least significant digit: <ul style="list-style-type: none"> Control STOP 2nd digit: Control RUN 3rd digit: Manual mode 4th digit: Remote mode 5th digit to Most significant digit: Unused Data 0: OFF 1: ON • Modbus Bit data Bit 0: Control STOP Bit 1: Control RUN Bit 2: Manual mode Bit 3: Remote mode Bit 4 to Bit 15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 15] 	—
4	—	—	—	02BC ⋮ 02CB	700 ⋮ 715	—	—	—	—	—
5	Manipulated output value (MV) monitor [heat-side] ¹	O1	CH1 ⋮ CH64	02CC ⋮ 030B	716 ⋮ 779	7	RO	C	PID control or Heat/Cool PID control: –5.0 to +105.0 % Position proportioning PID control with feedback resistance (FBR) input: 0.0 to 100.0 %	—
6	Manipulated output value (MV) monitor [cool-side] ²	O2	CH1 ⋮ CH64	030C ⋮ 034B	780 ⋮ 843	7	RO	C	–5.0 to +105.0 %	—

¹ The values on channels 2 and 4 on each Z-TIO module will be “0” for readout under Heat/Cool PID control or Position proportioning PID control.

² The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control as well as all of the channels of the Z-TIO module under the control mode other than Heat/Cool PID control will be “0” for readout.

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
7	Current transformer (CT) input value monitor	M3	CH1 ⋮ CH64	034C ⋮ 038B	844 ⋮ 907	7	RO	C	CTL-6-P-N: 0.0 to 30.0 A CTL-12-S56-10L-N: 0.0 to 100.0 A	—
8	Set value (SV) monitor	MS	CH1 ⋮ CH64	038C ⋮ 03CB	908 ⋮ 971	7	RO	C	Setting limiter low to Setting limiter high	—
9	Remote setting (RS) input value monitor	S2	CH1 ⋮ CH64	03CC ⋮ 040B	972 ⋮ 1035	7	RO	C	Setting limiter low to Setting limiter high	—
10	Burnout state monitor	B1	CH1 ⋮ CH64	040C ⋮ 044B	1036 ⋮ 1099	1	RO	C	0: OFF 1: ON	—
11	Event 1 state monitor	AA	CH1 ⋮ CH64	044C ⋮ 048B	1100 ⋮ 1163	1	RO	C	If the Event 3 type is temperature rise completion, check the temperature rise completion state in the comprehensive event state (Identifier: AJ, Register address: 023CH to 027BH). (The Event 3 state monitor does not turn ON.)	—
12	Event 2 state monitor	AB	CH1 ⋮ CH64	048C ⋮ 04CB	1164 ⋮ 1227	1	RO	C		—
13	Event 3 state monitor	AC	CH1 ⋮ CH64	04CC ⋮ 050B	1228 ⋮ 1291	1	RO	C		—
14	Event 4 state monitor	AD	CH1 ⋮ CH64	050C ⋮ 054B	1292 ⋮ 1355	1	RO	C		—
15	Heater break alarm (HBA) state monitor	AE	CH1 ⋮ CH64	054C ⋮ 058B	1356 ⋮ 1419	1	RO	C	0: OFF 1: ON	—
16	Output state monitor	Q1	CH1 ⋮ CH16	058C ⋮ 059B	1420 ⋮ 1435	7	RO	M	<ul style="list-style-type: none"> • RKC communication Least significant digit: OUT1 2nd digit: OUT2 3rd digit: OUT3 4th digit: OUT4 5th digit to Most significant digit: Unused Data 0: OFF 1: ON <ul style="list-style-type: none"> • Modbus Bit data Bit 0: OUT1 Bit 1: OUT2 Bit 2: OUT3 Bit 3: OUT4 Bit 4 to Bit 15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 15] Valid only for time-proportional control output.	—
17	Memory area soak time monitor	TR	CH1 ⋮ CH64	059C ⋮ 05DB	1436 ⋮ 1499	7	RO	C	0 minutes 00 seconds to 199 minutes 59 seconds: RKC communication: 0:00 to 199:59 (min:sec) Modbus: 0 to 11999 seconds 0 hours 00 minutes to 99 hours 59 minutes: RKC communication: 0:00 to 99:59 (hrs:min) Modbus: 0 to 5999 minutes Data range of Area soak time can be selected on the Soak time unit.	—

9. COMMUNICATION DATA LIST

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
18	—	—	—	05DC ⋮ 05EB	1500 ⋮ 1515	—	—	—	—	—
19	Holding peak value ambient temperature monitor	Hp	CH1 ⋮ CH64	05EC ⋮ 062B	1516 ⋮ 1579	7	RO	C	−10.0 to +100.0 °C (14.0 to 212.0 °F)	—
20	—	—	—	062C ⋮ 063B	1580 ⋮ 1595	—	—	—	—	—
21	Logic output monitor 1	ED	CH1 ⋮ CH16	063C ⋮ 064B	1596 ⋮ 1611	7	RO	M	<ul style="list-style-type: none"> • RKC communication Least significant digit: Logic output 1 2nd digit: Logic output 2 3rd digit: Logic output 3 4th digit: Logic output 4 5th digit to Most significant digit: Unused Data 0: OFF 1: ON <ul style="list-style-type: none"> • Modbus Bit data Bit 0: Logic output 1 Bit 1: Logic output 2 Bit 2: Logic output 3 Bit 3: Logic output 4 Bit 4: Logic output 5 Bit 5: Logic output 6 Bit 6: Logic output 7 Bit 7: Logic output 8 Bit 8 to Bit 15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 255]	—
22	Logic output monitor 2	EE	CH1 ⋮ CH16	—	—	7	RO	M	<ul style="list-style-type: none"> • RKC communication Least significant digit: Logic output 5 2nd digit: Logic output 6 3rd digit: Logic output 7 4th digit: Logic output 8 5th digit to Most significant digit: Unused Data 0: OFF 1: ON	
23	—	—	—	064C ⋮ 080B	1612 ⋮ 2059	—	—	—	—	—
24	PID/AT transfer	G1	CH1 ⋮ CH64	080C ⋮ 084B	2060 ⋮ 2123	1	R/W	C	0: PID control 1: Autotuning (AT) * * Automatically reverts to 0 after autotuning ends.	0
25	Auto/Manual transfer ♣	J1	CH1 ⋮ CH64	084C ⋮ 088B	2124 ⋮ 2187	1	R/W	C	0: Auto mode 1: Manual mode	0
26	Remote/Local transfer	C1	CH1 ⋮ CH64	088C ⋮ 08CB	2188 ⋮ 2251	1	R/W	C	0: Local mode 1: Remote mode When performing remote control by remote setting input and also performing cascade control and ratio setting, transfer to the Remote mode.	0
27	—	—	—	08CC ⋮ 08DB	2252 ⋮ 2267	—	—	—	—	—
28	Memory area transfer	ZA	CH1 ⋮ CH64	08DC ⋮ 091B	2268 ⋮ 2331	7	R/W	C	1 to 8	1

♣ The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control or Position proportioning PID control will be “0” for readout and ignored for writing.

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
29	Interlock release	AR	CH1 ⋮ CH64	091C ⋮ 095B	2332 ⋮ 2395	1	R/W	C	0: Normal state 1: Interlock release execution	0
30	Event 1 set value (EV1) ★	A1	CH1 ⋮ CH64	095C ⋮ 099B	2396 ⋮ 2459	7	R/W	C	Deviation action, Deviation action between channels, Temperature rise completion range: –Input span to +Input span	50 (50.0)
31	Event 2 set value (EV2) ★	A2	CH1 ⋮ CH64	099C ⋮ 09DB	2460 ⋮ 2523	7	R/W	C	Process action, SV action: Input scale low to Input scale high	50 (50.0)
32	Event 3 set value (EV3) ★	A3	CH1 ⋮ CH64	09DC ⋮ 0A1B	2524 ⋮ 2587	7	R/W	C	MV action: –5.0 to +105.0 % If the Event type corresponds to “0: None,” set to RO (Only reading data is possible). If Event 3 corresponds to “9: Temperature rise completion,” the Event 3 set value becomes the range for determining temperature rise completion.	50 (50.0)
33	Event 4 set value (EV4) ★	A4	CH1 ⋮ CH64	0A1C ⋮ 0A5B	2588 ⋮ 2651	7	R/W	C	If Event 4 corresponds to “9: Control loop break alarm (LBA),” the Event 4 set value becomes RO (Only reading data is possible).	50 (50.0)
34	Control loop break alarm (LBA) time ★	A5	CH1 ⋮ CH64	0A5C ⋮ 0A9B	2652 ⋮ 2715	7	R/W	C	0 to 7200 seconds (0: Unused)	480
35	LBA deadband ★ ♣	N1	CH1 ⋮ CH64	0A9C ⋮ 0ADB	2716 ⋮ 2779	7	R/W	C	0 (0.0) to Input span Varies with the setting of the decimal point position.	0 (0.0)
36	Set value (SV) ★	S1	CH1 ⋮ CH64	0ADC ⋮ 0B1B	2780 ⋮ 2843	7	R/W	C	Setting limiter low to Setting limiter high	TC/RTD: 0 (0.0) V/I: 0.0
37	Proportional band [heat-side] ★ ♣	P1	CH1 ⋮ CH64	0B1C ⋮ 0B5B	2844 ⋮ 2907	7	R/W	C	TC/RTD inputs: 0 (0.0) to Input span (Unit: °C [°F]) Varies with the setting of the decimal point position selection. Voltage (V)/current (I) inputs: 0.0 to 1000.0 % of input span 0 (0.0): ON/OFF action (ON/OFF action for both heat and cool actions in case of a Heat/Cool control type.)	TC/RTD: 30 (30.0) V/I: 30.0
38	Integral time [heat-side] ★ ♣	I1	CH1 ⋮ CH64	0B5C ⋮ 0B9B	2908 ⋮ 2971	7	R/W	C	PID control or Heat/Cool PID control: 0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PD action) Position proportioning PID control: 1 to 3600 seconds or 0.1 to 1999.9 seconds Varies with the setting of the Integral/ Derivative time decimal point position.	240
39	Derivative time [heat-side] ★ ♣	D1	CH1 ⋮ CH64	0B9C ⋮ 0BDB	2972 ⋮ 3035	7	R/W	C	0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PI action) Varies with the setting of the Integral/ Derivative time decimal point position.	60

★ Parameters which can be used in multi-memory area function

♣ The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control or Position proportioning PID control will be “0” for readout and ignored for writing.

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
40	Control response parameter ★ ♣	CA	CH1 ⋮ CH64	0BDC ⋮ 0C1B	3036 ⋮ 3099	1	R/W	C	0: Slow 1: Medium 2: Fast When the P or PD action is selected, this setting becomes invalid.	PID control, Position proportioning PID control: 0 Heat/Cool PID control: 2
41	Proportional band [cool-side] ★ ■	P2	CH1 ⋮ CH64	0C1C ⋮ 0C5B	3100 ⋮ 3163	7	R/W	C	TC/RTD inputs: 1 (0.1) to Input span (Unit: °C [°F]) Varies with the setting of the decimal point position selection. Voltage (V)/current (I) inputs: 0.1 to 1000.0 % of input span If control is other than Heat/Cool PID control, set to RO (Only reading data is possible).	TC/RTD: 30 (30.0) V/I: 30.0
42	Integral time [cool-side] ★ ■	I2	CH1 ⋮ CH64	0C5C ⋮ 0C9B	3164 ⋮ 3227	7	R/W	C	0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PD action) Varies with the setting of the Integral/ Derivative time decimal point position selection. If control is other than Heat/Cool PID control, set to RO (Only reading data is possible).	240
43	Derivative time [cool-side] ★ ■	D2	CH1 ⋮ CH64	0C9C ⋮ 0CDB	3228 ⋮ 3291	7	R/W	C	0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PI action) Varies with the setting of the Integral/ Derivative time decimal point position selection. If control is other than Heat/Cool PID control, set to RO (Only reading data is possible).	60
44	Overlap/Deadband ★ ■	V1	CH1 ⋮ CH64	0CDC ⋮ 0D1B	3292 ⋮ 3355	7	R/W	C	TC/RTD inputs: –Input span to +Input span (Unit: °C [°F]) Voltage (V)/current (I) inputs: –100.0 to +100.0 % of input span Minus (–) setting results in overlap. However, the overlapping range is within the proportional range. If control is other than Heat/Cool PID control, set to RO (Only reading data is possible).	0 (0.0)
45	Manual reset ★ ♣	MR	CH1 ⋮ CH64	0D1C ⋮ 0D5B	3356 ⋮ 3419	7	R/W	C	–100.0 to +100.0 % If the integral function is valid, set to RO (Only reading data is possible). When integral action (heating or cooling side) is zero, manual reset value is added to the control output.	0.0
46	Setting change rate limiter (up) ★	HH	CH1 ⋮ CH64	0D5C ⋮ 0D9B	3420 ⋮ 3483	7	R/W	C	0 (0.0) to Input span/unit time * 0 (0.0): Unused	0 (0.0)
47	Setting change rate limiter (down) ★	HL	CH1 ⋮ CH64	0D9C ⋮ 0DDB	3484 ⋮ 3547	7	R/W	C	* Unit time: 60 seconds (factory set value)	0 (0.0)

★ Parameters which can be used in multi-memory area function

♣ The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control or Position proportioning PID control will be “0” for readout and ignored for writing.

■ The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control will be “0” for readout and ignored for writing.
All of the channels of the Z-TIO module under control mode other than Heat/Cool PID control will be “0” for readout and ignored for writing.

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
48	Area soak time ★	TM	CH1 ⋮ CH64	0DDC ⋮ 0E1B	3548 ⋮ 3611	7	R/W	C	0 minutes 00 seconds to 199 minutes 59 seconds: RKC communication: 0:00 to 199:59 (min:sec) Modbus: 0 to 11999 seconds 0 hours 00 minutes to 99 hours 59 minutes: RKC communication: 0:00 to 99:59 (hrs:min) Modbus: 0 to 5999 minutes Data range of Area soak time can be selected on the Soak time unit.	RKC communication: 0:00 Modbus: 0
49	Link area number ★	LP	CH1 ⋮ CH64	0E1C ⋮ 0E5B	3612 ⋮ 3675	7	R/W	C	0 to 8 (0: No link)	0
50	Heater break alarm (HBA) set value	A7	CH1 ⋮ CH64	0E5C ⋮ 0E9B	3676 ⋮ 3739	7	R/W	C	When CT is CTL-6-P-N: 0.0 to 30.0 A (0.0: Not used) When CT is CTL-12-S56-10L-N: 0.0 to 100.0 A (0.0: Not used) If there is no current transformer (CT) or CT is assigned to "0: None," set to RO (Only reading data is possible).	0.0
51	Heater break determination point	NE	CH1 ⋮ CH64	0E9C ⋮ 0EDB	3740 ⋮ 3803	7	R/W	C	0.0 to 100.0 % of HBA set value (0.0: Heater break determination is invalid) If there is no current transformer (CT) or CT is assigned to "0: None," set to RO (Only reading data is possible). If Heater break alarm (HBA) corresponds to "0: Type A," set to RO (Only reading data is possible).	30.0
52	Heater melting determination point	NF	CH1 ⋮ CH64	0EDC ⋮ 0F1B	3804 ⋮ 3867	7	R/W	C	0.0 to 100.0 % of HBA set value (0.0: Heater melting determination is invalid) If there is no current transformer (CT) or CT is assigned to "0: None," set to RO (Only reading data is possible). If Heater break alarm (HBA) corresponds to "0: Type A," set to RO (Only reading data is possible).	30.0
53	PV bias	PB	CH1 ⋮ CH64	0F1C ⋮ 0F5B	3868 ⋮ 3931	7	R/W	C	–Input span to +Input span Varies with the setting of the decimal point position.	0 (0.0)
54	PV digital filter	F1	CH1 ⋮ CH64	0F5C ⋮ 0F9B	3932 ⋮ 3995	7	R/W	C	0.0 to 100.0 seconds (0.0: Unused)	0.0
55	PV ratio	PR	CH1 ⋮ CH64	0F9C ⋮ 0FDB	3996 ⋮ 4059	7	R/W	C	0.500 to 1.500	1.000
56	PV low input cut-off	DP	CH1 ⋮ CH64	0FDC ⋮ 101B	4060 ⋮ 4123	7	R/W	C	0.00 to 25.00 % of input span If the Square root extraction corresponds to "0: Unused," set to RO (Only reading data is possible).	0.00
57	RS bias *	RB	CH1 ⋮ CH64	101C ⋮ 105B	4124 ⋮ 4187	7	R/W	C	–Input span to +Input span Varies with the setting of the decimal point position.	0 (0.0)
58	RS digital filter *	F2	CH1 ⋮ CH64	105C ⋮ 109B	4188 ⋮ 4251	7	R/W	C	0.0 to 100.0 seconds (0.0: Unused)	0.0

* Data on RS bias, RS ratio and RS digital filter is that in cascade control or ratio setting.

★ Parameters which can be used in multi-memory area function

9. COMMUNICATION DATA LIST

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
59	RS ratio *	RR	CH1 ⋮ CH64	109C ⋮ 10DB	4252 ⋮ 4315	7	R/W	C	0.001 to 9.999	1.000
60	Output distribution selection	DV	CH1 ⋮ CH64	10DC ⋮ 111B	4316 ⋮ 4379	1	R/W	C	0: Control output 1: Distribution output	0
61	Output distribution bias	DW	CH1 ⋮ CH64	111C ⋮ 115B	4380 ⋮ 4443	7	R/W	C	−100.0 to +100.0 %	0.0
62	Output distribution ratio	DQ	CH1 ⋮ CH64	115C ⋮ 119B	4444 ⋮ 4507	7	R/W	C	−9.999 to +9.999	1.000
63	Proportional cycle time	T0	CH1 ⋮ CH64	119C ⋮ 11DB	4508 ⋮ 4571	7	R/W	C	0.1 to 100.0 seconds This item becomes RO (Only reading data is possible) for the Voltage/Current output specification. This parameter is valid when “0: Control output” has been selected at No.95 “Output assignment.”	Relay contact output: 20.0 Voltage pulse output, triac output and open collector output: 2.0
64	Minimum ON/OFF time of proportioning cycle	VI	CH1 ⋮ CH64	11DC ⋮ 121B	4572 ⋮ 4635	7	R/W	C	0 to 1000 ms This item becomes RO (Only reading data is possible) for the Voltage/Current output specification.	0
65	Manual manipulated output value ♣	ON	CH1 ⋮ CH64	121C ⋮ 125B	4636 ⋮ 4699	7	R/W	C	PID control: Output limiter low to Output limiter high Heat/Cool PID control: −Cool-side output limiter (high) to +Heat-side output limiter (high) Position proportioning PID control: When there is feedback resistance (FBR) input and it does not break: Output limiter low to Output limiter high When there is no feedback resistance (FBR) input or the feedback resistance (FBR) input is disconnected: 0: Close-side output OFF, Open-side output OFF 1: Close-side output ON, Open-side output OFF 2: Close-side output OFF, Open-side output ON	0.0
66	Area soak time stop function	RV	CH1 ⋮ CH64	125C ⋮ 129B	4700 ⋮ 4763	1	R/W	C	0: No function 1: Event 1 2: Event 2 3: Event 3 4: Event 4	0
67	EDS mode (for disturbance 1)	NG	CH1 ⋮ CH64	129C ⋮ 12DB	4764 ⋮ 4827	1	R/W	C	0: No function 1: EDS function mode 2: Learning mode 3: Tuning mode	0
68	EDS mode (for disturbance 2)	NX	CH1 ⋮ CH64	12DC ⋮ 131B	4828 ⋮ 4891	1	R/W	C	EDS function: External disturbance suppression function	0

* Data on RS bias, RS ratio and RS digital filter is that in cascade control or ratio setting.

♣ The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control or Position proportioning PID control will be “0” for readout and ignored for writing.

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
69	EDS value 1 (for disturbance 1)	NI	CH1 ⋮ CH64	131C ⋮ 135B	4892 ⋮ 4955	7	R/W	C	-100.0 to +100.0 %	0.0
70	EDS value 1 (for disturbance 2)	NJ	CH1 ⋮ CH64	135C ⋮ 139B	4956 ⋮ 5019	7	R/W	C		0.0
71	EDS value 2 (for disturbance 1)	NK	CH1 ⋮ CH64	139C ⋮ 13DB	5020 ⋮ 5083	7	R/W	C	-100.0 to +100.0 %	0.0
72	EDS value 2 (for disturbance 2)	NM	CH1 ⋮ CH64	13DC ⋮ 141B	5084 ⋮ 5147	7	R/W	C		0.0
73	EDS transfer time (for disturbance 1)	NN	CH1 ⋮ CH64	141C ⋮ 145B	5148 ⋮ 5211	7	R/W	C	0 to 3600 seconds or 0.0 to 1999.9 seconds	0
74	EDS transfer time (for disturbance 2)	NO	CH1 ⋮ CH64	145C ⋮ 149B	5212 ⋮ 5275	7	R/W	C		0
75	EDS action time (for disturbance 1)	NQ	CH1 ⋮ CH64	149C ⋮ 14DB	5276 ⋮ 5339	7	R/W	C	1 to 3600 seconds	600
76	EDS action time (for disturbance 2)	NL	CH1 ⋮ CH64	14DC ⋮ 151B	5340 ⋮ 5403	7	R/W	C		600
77	EDS action wait time (for disturbance 1)	NR	CH1 ⋮ CH64	151C ⋮ 155B	5404 ⋮ 5467	7	R/W	C	0.0 to 600.0 seconds	0.0
78	EDS action wait time (for disturbance 2)	NY	CH1 ⋮ CH64	155C ⋮ 159B	5468 ⋮ 5531	7	R/W	C		0.0
79	EDS value learning times	NT	CH1 ⋮ CH64	159C ⋮ 15DB	5532 ⋮ 5595	7	R/W	C	0 to 10 times (0: No learning mode)	1
80	EDS start signal	NU	CH1 ⋮ CH64	15DC ⋮ 161B	5596 ⋮ 5659	1	R/W	C	0: EDS start signal OFF 1: EDS start signal ON (for disturbance 1) 2: EDS start signal ON (for disturbance 2)	0
81	Operation mode	EI	CH1 ⋮ CH64	161C ⋮ 165B	5660 ⋮ 5723	1	R/W	C	0: Unused 1: Monitor 2: Monitor + Event function 3: Control	3
82	Startup tuning (ST) ♣	ST	CH1 ⋮ CH64	165C ⋮ 169B	5724 ⋮ 5787	1	R/W	C	0: ST unused 1: Execute once * 2: Execute always * When the Startup tuning (ST) is finished, the setting will automatically returns to "0: ST unused." The Startup tuning (ST) function is activated according to the ST start condition selected. If control is Position proportioning PID control, set to RO (Only reading data is possible).	0
83	Automatic temperature rise learning ♣	Y8	CH1 ⋮ CH64	169C ⋮ 16DB	5788 ⋮ 5851	1	R/W	C	0: Unused 1: Learning * * When the automatic temperature rise learning is finished, the setting will automatically returns to "0: Unused."	0

♣ The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control or Position proportioning PID control will be "0" for readout and ignored for writing.

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
84	Communication switch for logic	EF	CH1 ⋮ CH16	16DC ⋮ 16EB	5852 ⋮ 5867	7	R/W	M	<ul style="list-style-type: none"> • RKC communication Least significant digit: Communication switch 1 2nd digit: Communication switch 2 3rd digit: Communication switch 3 4th digit: Communication switch 4 5th digit to Most significant digit: Unused Data 0: OFF 1: ON • Modbus Bit data Bit 0: Communication switch 1 Bit 1: Communication switch 2 Bit 2: Communication switch 3 Bit 3: Communication switch 4 Bit 4 to Bit 15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 15] 	0
85	—	—	—	16EC ⋮ 196B	5868 ⋮ 6507	—	—	—	—	—
Set data No. 86 or later are for engineering setting [Writable in the STOP mode]										
86	Input type	XI	CH1 ⋮ CH64	196C ⋮ 19AB	6508 ⋮ 6571	7	R/W	C	0: TC input K 1: TC input J 2: TC input R 3: TC input S 4: TC input B 5: TC input E 6: TC input N 7: TC input T 8: TC input W5Re/W26Re 9: TC input PLII 12: RTD input Pt100 13: RTD input JPt100 14: Current input 0 to 20 mA DC 15: Current input 4 to 20 mA DC 16: Voltage (high) input 0 to 10 V DC 17: Voltage (high) input 0 to 5 V DC 18: Voltage (high) input 1 to 5 V DC 19: Voltage (low) input 0 to 1 V DC 20: Voltage (low) input 0 to 100 mV DC 21: Voltage (low) input 0 to 10 mV DC 22: Feedback resistance input 100 to 150 Ω 23: Feedback resistance input 151 Ω to 6 kΩ If changed to Voltage (high) input from TC/RTD/Current/Voltage (low)/ Feedback resistance input, select the hardware by the input selector switch at the side of the module. Refer to SRZ Instruction Manual (IMS01T04-E□) .	Based on model code When not specifying: 0
87	Display unit	PU	CH1 ⋮ CH64	19AC ⋮ 19EB	6572 ⋮ 6635	7	R/W	C	0: °C 1: °F Use to select the temperature unit for thermocouple (TC) and RTD inputs.	Based on model code When not specifying: 0

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
88	Decimal point position	XU	CH1 ⋮ CH64	19EC ⋮ 1A2B	6636 ⋮ 6699	7	R/W	C	0: No decimal place 1: One decimal place 2: Two decimal places 3: Three decimal places 4: Four decimal places TC input: • K, J, T, E: Only 0 or 1 can be set. • R, S, B, N, PLII, W5Re/W26Re: Only 0 can be set. RTD input: Only 0 or 1 can be set. Voltage (V)/Current (I) inputs: From 0 to 4 can be set.	Based on model code When not specifying: TC/RTD: 1 V/I: 1
89	Input scale high	XV	CH1 ⋮ CH64	1A2C ⋮ 1A6B	6700 ⋮ 6763	7	R/W	C	TC/RTD inputs: (Input scale low + 1 digit) to Maximum value of the selected input range Voltage (V)/Current (I) inputs: (Input scale low + 1 digit) to +19999 (However, a span is 20000 or less.) Varies with the setting of the decimal point position.	TC/RTD: Maximum value of the selected input range V/I: 100.0
90	Input scale low	XW	CH1 ⋮ CH64	1A6C ⋮ 1AAB	6764 ⋮ 6827	7	R/W	C	TC/RTD inputs: Minimum value of the selected input range to (Input scale high – 1 digit) Voltage (V)/Current (I) inputs: –19999 to (Input scale high – 1 digit) (However, a span is 20000 or less.) Varies with the setting of the decimal point position.	TC/RTD: Minimum value of the selected input range V/I: 0.0
91	Input error determination point (high)	AV	CH1 ⋮ CH64	1AAC ⋮ 1AEB	6828 ⋮ 6891	7	R/W	C	Input error determination point (low limit) to (Input range high + 5 % of Input span) Varies with the setting of the decimal point position.	Input range high + (5 % of Input span)
92	Input error determination point (low)	AW	CH1 ⋮ CH64	1AEC ⋮ 1B2B	6892 ⋮ 6955	7	R/W	C	(Input range low – 5 % of Input span) to Input error determination point (high limit) Varies with the setting of the decimal point position.	Input range low – (5 % of Input span)
93	Burnout direction	BS	CH1 ⋮ CH64	1B2C ⋮ 1B6B	6956 ⋮ 7019	1	R/W	C	0: Upscale 1: Downscale Valid only when the TC input and voltage (low) input are selected.	0
94	Square root extraction	XH	CH1 ⋮ CH64	1B6C ⋮ 1BAB	7020 ⋮ 7083	1	R/W	C	0: Unused 1: Used	0
95	Output assignment (Logic output selection function)	E0	CH1 ⋮ CH64	1BAC ⋮ 1BEB	7084 ⋮ 7147	1	R/W	C	0: Control output 1: Logic output result 2: FAIL output	0
96	Energized/De-energized (Logic output selection function)	NA	CH1 ⋮ CH64	1BEC ⋮ 1C2B	7148 ⋮ 7211	1	R/W	C	0: Energized 1: De-energized	0

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
97	Event 1 type	XA	CH1 ⋮ CH64	1C2C ⋮ 1C6B	7212 ⋮ 7275	7	R/W	C	0: None 1: Deviation high (Using SV monitor value) ¹ 2: Deviation low (Using SV monitor value) ¹ 3: Deviation high/low (Using SV monitor value) ¹ 4: Band (Using SV monitor value) ¹ 5: Process high ¹ 6: Process low ¹ 7: SV high 8: SV low 9: Unused 10: MV high [heat-side] ^{1,2} 11: MV low [heat-side] ^{1,2} 12: MV high [cool-side] ¹ 13: MV low [cool-side] ¹ 14: Deviation high (Using local SV value) ¹ 15: Deviation low (Using local SV value) ¹ 16: Deviation high/low (Using local SV value) ¹ 17: Band (Using local SV value) ¹ 18: Deviation between channels high ¹ 19: Deviation between channels low ¹ 20: Deviation between channels high/low ¹ 21: Deviation between channels band ¹ ¹ Event hold action is available. ² If there is feedback resistance (FBR) input in Position proportioning PID control, set to the feedback resistance (FBR) input value.	Based on model code When not specifying: 0
98	Event 1 channel setting	FA	CH1 ⋮ CH64	1C6C ⋮ 1CAB	7276 ⋮ 7339	1	R/W	C	1: Channel 1 3: Channel 3 2: Channel 2 4: Channel 4 This function is valid when "deviation between channels" is selected.	1
99	Event 1 hold action	WA	CH1 ⋮ CH64	1CAC ⋮ 1CEB	7340 ⋮ 7403	1	R/W	C	0: OFF 1: Hold action ON (when power turned on; when transferred from STOP to RUN) 2: Re-hold action ON (when power turned on; when transferred from STOP to RUN; SV changed) This function is valid when input value, deviation or manipulated value action has been selected. In case of a deviation action, this function is not available while in remote mode and while setting changing rate limiter is working.	Based on model code When not specifying: 0
100	Event 1 interlock	LF	CH1 ⋮ CH64	1CEC ⋮ 1D2B	7404 ⋮ 7467	1	R/W	C	0: Unused 1: Used	0
101	Event 1 differential gap	HA	CH1 ⋮ CH64	1D2C ⋮ 1D6B	7468 ⋮ 7531	7	R/W	C	① Deviation, process, set value, or Deviation action between channels: 0 (0.0) to Input span (Unit: °C [°F]) Varies with the setting of the decimal point position. ② MV: 0.0 to 110.0 %	①: 1 ②: 1.0
102	Event 1 delay timer	TD	CH1 ⋮ CH64	1D6C ⋮ 1DAB	7532 ⋮ 7595	7	R/W	C	0 to 18000 seconds	0

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
103	Force ON of Event 1 action	OA	CH1 ⋮ CH64	1DAC ⋮ 1DEB	7596 ⋮ 7659	7	R/W	C	<ul style="list-style-type: none"> • RKC communication Least significant digit: Event output turned on at input error occurrence 2nd digit: Event output turned on in manual mode 3rd digit: Event output turned on during the Autotuning (AT) function is being executed 4th digit: Event output turned on during the setting change rate limiter is being operated 5th digit to Most significant digit: Unused Data 0: Invalid 1: Valid • Modbus Bit data Bit 0: Event output turned on at input error occurrence Bit 1: Event output turned on in manual mode Bit 2: Event output turned on during the Autotuning (AT) function is being executed Bit 3: Event output turned on during the setting change rate limiter is being operated Bit 4 to Bit 15: Unused Data 0: Invalid 1: Valid [Decimal number: 0 to 15] 	0
104	Event 2 type	XB	CH1 ⋮ CH64	1DEC ⋮ 1E2B	7660 ⋮ 7723	7	R/W	C	0: None 1: Deviation high (Using SV monitor value) ¹ 2: Deviation low (Using SV monitor value) ¹ 3: Deviation high/low (Using SV monitor value) ¹ 4: Band (Using SV monitor value) ¹ 5: Process high ¹ 6: Process low ¹ 7: SV high 8: SV low 9: Unused 10: MV high [heat-side] ^{1, 2} 11: MV low [heat-side] ^{1, 2} 12: MV high [cool-side] ¹ 13: MV low [cool-side] ¹ 14: Deviation high (Using local SV value) ¹ 15: Deviation low (Using local SV value) ¹ 16: Deviation high/low (Using local SV value) ¹ 17: Band (Using local SV value) ¹ 18: Deviation between channels high ¹ 19: Deviation between channels low ¹ 20: Deviation between channels high/low ¹ 21: Deviation between channels band ¹ ¹ Event hold action is available. ² If there is feedback resistance (FBR) input in Position proportioning PID control, set to the feedback resistance (FBR) input value.	Based on model code When not specifying: 0

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
105	Event 2 channel setting	FB	CH1 ⋮ CH64	1E2C ⋮ 1E6B	7724 ⋮ 7787	1	R/W	C	1: Channel 1 2: Channel 2 3: Channel 3 4: Channel 4 This function is valid when “deviation between channels” is selected.	1
106	Event 2 hold action	WB	CH1 ⋮ CH64	1E6C ⋮ 1EAB	7788 ⋮ 7851	1	R/W	C	0: OFF 1: Hold action ON (when power turned on; when transferred from STOP to RUN) 2: Re-hold action ON (when power turned on; when transferred from STOP to RUN; SV changed) This function is valid when input value, deviation or manipulated value action has been selected. In case of a deviation action, this function is not available while in remote mode and while setting changing rate limiter is working.	Based on model code When not specifying: 0
107	Event 2 interlock	LG	CH1 ⋮ CH64	1EAC ⋮ 1EEB	7852 ⋮ 7915	1	R/W	C	0: Unused 1: Used	0
108	Event 2 differential gap	HB	CH1 ⋮ CH64	1EEC ⋮ 1F2B	7916 ⋮ 7979	7	R/W	C	① Deviation, process, set value, or Deviation action between channels: 0 (0.0) to Input span (Unit: °C [°F]) Varies with the setting of the decimal point position. ② MV: 0.0 to 110.0 %	①: 1 ②: 1.0
109	Event 2 delay timer	TG	CH1 ⋮ CH64	1F2C ⋮ 1F6B	7980 ⋮ 8043	7	R/W	C	0 to 18000 seconds	0
110	Force ON of Event 2 action	OB	CH1 ⋮ CH64	1F6C ⋮ 1FAB	8044 ⋮ 8107	7	R/W	C	<ul style="list-style-type: none"> RKC communication Least significant digit: Event output turned on at input error occurrence 2nd digit: Event output turned on in manual mode 3rd digit: Event output turned on during the Autotuning (AT) function is being executed 4th digit: Event output turned on during the setting change rate limiter is being operated 5th digit to Most significant digit: Unused Data 0: Invalid 1: Valid Modbus Bit data Bit 0: Event output turned on at input error occurrence Bit 1: Event output turned on in manual mode Bit 2: Event output turned on during the Autotuning (AT) function is being executed Bit 3: Event output turned on during the setting change rate limiter is being operated Bit 4 to Bit 15: Unused Data 0: Invalid 1: Valid [Decimal number: 0 to 15] 	0

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
111	Event 3 type	XC	CH1 ⋮ CH64	1FAC ⋮ 1FEB	8108 ⋮ 8171	7	R/W	C	0: None 1: Deviation high (Using SV monitor value) ¹ 2: Deviation low (Using SV monitor value) ¹ 3: Deviation high/low (Using SV monitor value) ¹ 4: Band (Using SV monitor value) ¹ 5: Process high ¹ 6: Process low ¹ 7: SV high 8: SV low 9: Temperature rise completion 10: MV high [heat-side] ^{1, 2} 11: MV low [heat-side] ^{1, 2} 12: MV high [cool-side] ¹ 13: MV low [cool-side] ¹ 14: Deviation high (Using local SV value) ¹ 15: Deviation low (Using local SV value) ¹ 16: Deviation high/low (Using local SV value) ¹ 17: Band (Using local SV value) ¹ 18: Deviation between channels high ¹ 19: Deviation between channels low ¹ 20: Deviation between channels high/low ¹ 21: Deviation between channels band ¹ ¹ Event hold action is available. ² If there is feedback resistance (FBR) input in Position proportioning PID control, set to the feedback resistance (FBR) input value.	Based on model code When not specifying: 0
112	Event 3 channel setting	FC	CH1 ⋮ CH64	1FEC ⋮ 202B	8172 ⋮ 8235	1	R/W	C	1: Channel 1 2: Channel 2 3: Channel 3 4: Channel 4 This function is valid when “deviation between channels” is selected.	1
113	Event 3 hold action	WC	CH1 ⋮ CH64	202C ⋮ 206B	8236 ⋮ 8299	1	R/W	C	0: OFF 1: Hold action ON (when power turned on; when transferred from STOP to RUN) 2: Re-hold action ON (when power turned on; when transferred from STOP to RUN; SV changed) This function is valid when input value, deviation or manipulated value action has been selected. In case of a deviation action, this function is not available while in remote mode and while setting changing rate limiter is working.	Based on model code When not specifying: 0
114	Event 3 interlock	LH	CH1 ⋮ CH64	206C ⋮ 20AB	8300 ⋮ 8363	1	R/W	C	0: Unused 1: Used	0
115	Event 3 differential gap	HC	CH1 ⋮ CH64	20AC ⋮ 20EB	8364 ⋮ 8427	7	R/W	C	① Deviation, process, set value, or Deviation action between channels: 0 (0.0) to Input span (Unit: °C [°F]) Varies with the setting of the decimal point position. ② MV: 0.0 to 110.0 %	①: 1 ②: 1.0
116	Event 3 delay timer	TE	CH1 ⋮ CH64	20EC ⋮ 212B	8428 ⋮ 8491	7	R/W	C	0 to 18000 seconds If Event 3 corresponds to “9: Temperature rise completion,” the Event 3 delay timer becomes the temperature rise completion soak time.	0

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
117	Force ON of Event 3 action	OC	CH1 ⋮ CH64	212C ⋮ 216B	8492 ⋮ 8555	7	R/W	C	<ul style="list-style-type: none"> • RKC communication Least significant digit: Event output turned on at input error occurrence 2nd digit: Event output turned on in manual mode 3rd digit: Event output turned on during the Autotuning (AT) function is being executed 4th digit: Event output turned on during the setting change rate limiter is being operated 5th digit to Most significant digit: Unused Data 0: Invalid 1: Valid • Modbus Bit data Bit 0: Event output turned on at input error occurrence Bit 1: Event output turned on in manual mode Bit 2: Event output turned on during the Autotuning (AT) function is being executed Bit 3: Event output turned on during the setting change rate limiter is being operated Bit 4 to Bit 15: Unused Data 0: Invalid 1: Valid [Decimal number: 0 to 15] 	0
118	Event 4 type	XD	CH1 ⋮ CH64	216C ⋮ 21AB	8556 ⋮ 8619	7	R/W	C	0: None 1: Deviation high (Using SV monitor value) ¹ 2: Deviation low (Using SV monitor value) ¹ 3: Deviation high/low (Using SV monitor value) ¹ 4: Band (Using SV monitor value) ¹ 5: Process high ¹ 6: Process low ¹ 7: SV high 8: SV low 9: Control loop break alarm (LBA) 10: MV high [heat-side] ^{1, 2} 11: MV low [heat-side] ^{1, 2} 12: MV high [cool-side] ¹ 13: MV low [cool-side] ¹ 14: Deviation high (Using local SV value) ¹ 15: Deviation low (Using local SV value) ¹ 16: Deviation high/low (Using local SV value) ¹ 17: Band (Using local SV value) ¹ 18: Deviation between channels high ¹ 19: Deviation between channels low ¹ 20: Deviation between channels high/low ¹ 21: Deviation between channels band ¹ ¹ Event hold action is available. ² If there is feedback resistance (FBR) input in Position proportioning PID control, set to the feedback resistance (FBR) input value.	Based on model code When not specifying: 0

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
119	Event 4 channel setting	FD	CH1 ⋮ CH64	21AC ⋮ 21EB	8620 ⋮ 8683	1	R/W	C	1: Channel 1 2: Channel 2 3: Channel 3 4: Channel 4 This function is valid when "deviation between channels" is selected.	1
120	Event 4 hold action	WD	CH1 ⋮ CH64	21EC ⋮ 222B	8684 ⋮ 8747	1	R/W	C	0: OFF 1: Hold action ON (when power turned on; when transferred from STOP to RUN) 2: Re-hold action ON (when power turned on; when transferred from STOP to RUN; SV changed) This function is valid when input value, deviation or manipulated value action has been selected. In case of a deviation action, this function is not available while in remote mode and while setting changing rate limiter is working.	Based on model code When not specifying: 0
121	Event 4 interlock	LI	CH1 ⋮ CH64	222C ⋮ 226B	8748 ⋮ 8811	1	R/W	C	0: Unused 1: Used	0
122	Event 4 differential gap	HD	CH1 ⋮ CH64	226C ⋮ 22AB	8812 ⋮ 8875	7	R/W	C	① Deviation, process, set value, or Deviation action between channels: 0 (0.0) to Input span (Unit: °C [°F]) Varies with the setting of the decimal point position. ② MV: 0.0 to 110.0 % Becomes invalid when the Event 4 type corresponds to "9: Control loop break alarm (LBA)."	①: 1 ②: 1.0
123	Event 4 delay timer	TF	CH1 ⋮ CH64	22AC ⋮ 22EB	8876 ⋮ 8939	7	R/W	C	0 to 18000 seconds	0
124	Force ON of Event 4 action	OD	CH1 ⋮ CH64	22EC ⋮ 232B	8940 ⋮ 9003	7	R/W	C	<ul style="list-style-type: none"> • RKC communication Least significant digit: Event output turned on at input error occurrence 2nd digit: Event output turned on in manual mode 3rd digit: Event output turned on during the Autotuning (AT) function is being executed 4th digit: Event output turned on during the setting change rate limiter is being operated 5th digit to Most significant digit: Unused Data 0: Invalid 1: Valid <ul style="list-style-type: none"> • Modbus Bit data Bit 0: Event output turned on at input error occurrence Bit 1: Event output turned on in manual mode Bit 2: Event output turned on during the Autotuning (AT) function is being executed Bit 3: Event output turned on during the setting change rate limiter is being operated Bit 4 to Bit 15: Unused Data 0: Invalid 1: Valid [Decimal number: 0 to 15]	0

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
125	CT ratio	XS	CH1 ⋮ CH64	232C ⋮ 236B	9004 ⋮ 9067	7	R/W	C	0 to 9999	CTL-6-P-N: 800 CTL-12-S56-10L-N: 1000
126	CT assignment	ZF	CH1 ⋮ CH64	236C ⋮ 23AB	9068 ⋮ 9131	1	R/W	C	0: None 1: OUT1 2: OUT2 3: OUT3 4: OUT4	CH1: 1, CH2: 2 CH3: 3, CH4: 4 (for each Z-TIO module)
127	Heater break alarm (HBA) type	ND	CH1 ⋮ CH64	23AC ⋮ 23EB	9132 ⋮ 9195	1	R/W	C	0: Heater break alarm (HBA) type A (Time-proportional control output) 1: Heater break alarm (HBA) type B (Continuous control output and time-proportional control output)	Set value is based on the Output type specified at ordering.
128	Number of heater break alarm (HBA) delay times	DH	CH1 ⋮ CH64	23EC ⋮ 242B	9196 ⋮ 9259	7	R/W	C	0 to 255 times	5
129	Hot/Cold start	XN	CH1 ⋮ CH64	242C ⋮ 246B	9260 ⋮ 9323	1	R/W	C	0: Hot start 1 1: Hot start 2 2: Cold start	0
130	Start determination point	SX	CH1 ⋮ CH64	246C ⋮ 24AB	9324 ⋮ 9387	7	R/W	C	0 (0.0) to Input span (The unit is the same as input value.) 0 (0.0): Action depending on the Hot/Cold start selection Varies with the setting of the decimal point position.	Based on specification
131	SV tracking	XL	CH1 ⋮ CH64	24AC ⋮ 24EB	9388 ⋮ 9451	1	R/W	C	0: Unused 1: Used	1
132	MV transfer function [Action taken when changed to Manual mode from Auto mode]	OT	CH1 ⋮ CH64	24EC ⋮ 252B	9452 ⋮ 9515	1	R/W	C	0: MV in Auto mode is used. [Balanceless-bumpless function] 1: MV in previous Manual mode is used.	0
133	Control action	XE	CH1 ⋮ CH64	252C ⋮ 256B	9516 ⋮ 9579	1	R/W	C	0: Brilliant II PID control (Direct action) 1: Brilliant II PID control (Reverse action) 2: Brilliant II Heat/Cool PID control [Water cooling type] 3: Brilliant II Heat/Cool PID control [Air cooling type] 4: Brilliant II Heat/Cool PID control [Cooling gain linear type] 5: Brilliant II position proportioning PID control Odd channel: From 0 to 5 can be set. Even channel: Only 0 or 1 can be set. * * In Heat/Cool PID control and Position proportioning PID control, control action is not performed. Only PV monitor and event action is performed.	Based on model code When not specifying: 1
134	Integral/Derivative time decimal point position ♣	PK	CH1 ⋮ CH64	256C ⋮ 25AB	9580 ⋮ 9643	1	R/W	C	0: 1 second setting (No decimal place) 1: 0.1 seconds setting (One decimal place)	0
135	Derivative action ♣	KA	CH1 ⋮ CH64	25AC ⋮ 25EB	9644 ⋮ 9707	1	R/W	C	0: Measured value derivative 1: Deviation derivative	0

♣ The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control or Position proportioning PID control will be “0” for readout and ignored for writing.

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
136	Undershoot suppression factor ■	KB	CH1 ⋮ CH64	25EC ⋮ 262B	9708 ⋮ 9771	7	R/W	C	0.000 to 1.000	Water cooling: 0.100 Air cooling: 0.250 Cooling gain linear type: 1.000
137	Derivative gain ♣	DG	CH1 ⋮ CH64	262C ⋮ 266B	9772 ⋮ 9835	7	R/W	C	0.1 to 10.0	6.0
138	ON/OFF action differential gap (upper)	IV	CH1 ⋮ CH64	266C ⋮ 26AB	9836 ⋮ 9899	7	R/W	C	TC/RTD inputs: 0 (0.0) to Input span (Unit: °C [°F]) Varies with the setting of the decimal point position.	TC/RTD: 1 V/I: 0.1
139	ON/OFF action differential gap (lower)	IW	CH1 ⋮ CH64	26AC ⋮ 26EB	9900 ⋮ 9963	7	R/W	C	Voltage (V)/Current (I) inputs: 0.0 to 100.0 % of input span	TC/RTD: 1 V/I: 0.1
140	Action (high) at input error	WH	CH1 ⋮ CH64	26EC ⋮ 272B	9964 ⋮ 10027	1	R/W	C	0: Normal control 1: Manipulated output value at Input error	0
141	Action (low) at input error	WL	CH1 ⋮ CH64	272C ⋮ 276B	10028 ⋮ 10091	1	R/W	C		0
142	Manipulated output value at input error	OE	CH1 ⋮ CH64	276C ⋮ 27AB	10092 ⋮ 10155	7	R/W	C	−105.0 to +105.0 % Actual output values become those restricted by the output limiter. Position proportioning PID control: If there is no feedback resistance (FBR) input or the feedback resistance (FBR) input is disconnected, an action taken when abnormal is in accordance with the value action setting during STOP.	0.0
143	Manipulated output value at STOP mode [heat-side] ♣	OF	CH1 ⋮ CH64	27AC ⋮ 27EB	10156 ⋮ 10219	7	R/W	C	−5.0 to +105.0 % Position proportioning PID control: Only when there is feedback resistance (FBR) input and it does not break, the manipulated output value [heat-side] at STOP is output.	−5.0
144	Manipulated output value at STOP mode [cool-side] ■	OG	CH1 ⋮ CH64	27EC ⋮ 282B	10220 ⋮ 10283	7	R/W	C		−5.0
145	Output change rate limiter (up) [heat-side] ♣	PH	CH1 ⋮ CH64	282C ⋮ 286B	10284 ⋮ 10347	7	R/W	C	0.0 to 100.0 %/seconds (0.0: OFF) Becomes invalid when in Position proportioning PID control.	0.0
146	Output change rate limiter (down) [heat-side] ♣	PL	CH1 ⋮ CH64	286C ⋮ 28AB	10348 ⋮ 10411	7	R/W	C		0.0
147	Output limiter (high) [heat-side] ♣ *	OH	CH1 ⋮ CH64	28AC ⋮ 28EB	10412 ⋮ 10475	7	R/W	C	Output limiter (low) [heat-side] to 105.0 % Position proportioning PID control: Becomes valid only when there is feedback resistance (FBR) input and it does not break.	105.0
148	Output limiter (low) [heat-side] ♣ *	OL	CH1 ⋮ CH64	28EC ⋮ 292B	10476 ⋮ 10539	7	R/W	C	−5.0 % to Output limiter (high) [heat-side] Position proportioning PID control: Becomes valid only when there is feedback resistance (FBR) input and it does not break.	−5.0

- The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control will be “0” for readout and ignored for writing.
All of the channels of the Z-TIO module under control mode other than Heat/Cool PID control will be “0” for readout and ignored for writing.
- ♣ The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control or Position proportioning PID control will be “0” for readout and ignored for writing.
- * Data that are activated by rebooting

9. COMMUNICATION DATA LIST

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
149	Output change rate limiter (up) [cool-side] ■	PX	CH1 ⋮ CH64	292C ⋮ 296B	10540 ⋮ 10603	7	R/W	C	0.0 to 100.0 % of manipulated output/seconds (0.0: OFF)	0.0
150	Output change rate limiter (down) [cool-side] ■	PY	CH1 ⋮ CH64	296C ⋮ 29AB	10604 ⋮ 10667	7	R/W	C	Becomes invalid when in Position proportioning PID control.	0.0
151	Output limiter (high) [cool-side] ■ *	OX	CH1 ⋮ CH64	29AC ⋮ 29EB	10668 ⋮ 10731	7	R/W	C	Output limiter low [cool-side] to 105.0 %	105.0
152	Output limiter (low) [cool-side] ■ *	OY	CH1 ⋮ CH64	29EC ⋮ 2A2B	10732 ⋮ 10795	7	R/W	C	-5.0 % to Output limiter high [cool-side]	-5.0
153	AT bias ♣	GB	CH1 ⋮ CH64	2A2C ⋮ 2A6B	10796 ⋮ 10859	7	R/W	C	-Input span to +Input span Varies with the setting of the decimal point position.	0 (0.0)
154	AT cycles ♣	G3	CH1 ⋮ CH64	2A6C ⋮ 2AAB	10860 ⋮ 10923	1	R/W	C	0: 1.5 cycles 1: 2.0 cycles 2: 2.5 cycles 3: 3.0 cycles	1
155	Output value with AT turned on ♣	OP	CH1 ⋮ CH64	2AAC ⋮ 2AEB	10924 ⋮ 10987	7	R/W	C	Output value with AT turned off to +105.0 % Actual output values become those restricted by the output limiter. Position proportioning PID control: Becomes valid only when there is feedback resistance (FBR) input and it does not break (high limit of feedback resistance input at AT).	105.0
156	Output value with AT turned off ♣	OQ	CH1 ⋮ CH64	2AEC ⋮ 2B2B	10988 ⋮ 11051	7	R/W	C	-105.0 % to Output value with AT turned on Actual output values become those restricted by the output limiter. Position proportioning PID control: Becomes valid only when there is feedback resistance (FBR) input and it does not break (low limit of feedback resistance input at AT).	-105.0
157	AT differential gap time ♣	GH	CH1 ⋮ CH64	2B2C ⋮ 2B6B	11052 ⋮ 11115	7	R/W	C	0.0 to 50.0 seconds	10.0
158	Proportional band adjusting factor [heat-side] ♣	KC	CH1 ⋮ CH64	2B6C ⋮ 2BAB	11116 ⋮ 11179	7	R/W	C	0.01 to 10.00 times	1.00
159	Integral time adjusting factor [heat-side] ♣	KD	CH1 ⋮ CH64	2BAC ⋮ 2BEB	11180 ⋮ 11243	7	R/W	C	0.01 to 10.00 times	1.00
160	Derivative time adjusting factor [heat-side] ♣	KE	CH1 ⋮ CH64	2BEC ⋮ 2C2B	11244 ⋮ 11307	7	R/W	C	0.01 to 10.00 times	1.00
161	Proportional band adjusting factor [cool-side] ■	KF	CH1 ⋮ CH64	2C2C ⋮ 2C6B	11308 ⋮ 11371	7	R/W	C	0.01 to 10.00 times	1.00

■ The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control will be “0” for readout and ignored for writing.
All of the channels of the Z-TIO module under control mode other than Heat/Cool PID control will be “0” for readout and ignored for writing.

* Data that are activated by rebooting

♣ The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control or Position proportioning PID control will be “0” for readout and ignored for writing.

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
162	Integral time adjusting factor [cool-side] ■	KG	CH1 ⋮ CH64	2C6C ⋮ 2CAB	11372 ⋮ 11435	7	R/W	C	0.01 to 10.00 times	1.00
163	Derivative time adjusting factor [cool-side] ■	KH	CH1 ⋮ CH64	2CAC ⋮ 2CEB	11436 ⋮ 11499	7	R/W	C	0.01 to 10.00 times	1.00
164	Proportional band limiter (high) [heat-side] ♣	P6	CH1 ⋮ CH64	2CEC ⋮ 2D2B	11500 ⋮ 11563	7	R/W	C	TC/RTD inputs: Proportional band limiter (low) [heat-side] to Input span (Unit: °C [°F]) Varies with the setting of the decimal point position selection. Voltage (V)/Current (I) inputs: Proportional band limiter (low) [heat-side] to 1000.0 (Unit: %) 0 (0.0): ON/OFF action (ON/OFF action for both heat and cool actions in case of a Heat/Cool PID control type.)	TC/RTD: Input span V/I: 1000.0
165	Proportional band limiter (low) [heat-side] ♣	P7	CH1 ⋮ CH64	2D2C ⋮ 2D6B	11564 ⋮ 11627	7	R/W	C	TC/RTD inputs: 0 (0.0) to Proportional band limiter (high) [heat-side] (Unit: °C [°F]) Varies with the setting of the decimal point position selection. Voltage (V)/Current (I) inputs: 0.0 to Proportional band limiter (high) [heat-side] (Unit: %) 0 (0.0): ON/OFF action (ON/OFF action for both heat and cool actions in case of a Heat/Cool PID control type.)	TC/RTD: 0 (0.0) V/I: 0.0
166	Integral time limiter (high) [heat-side] ♣	I6	CH1 ⋮ CH64	2D6C ⋮ 2DAB	11628 ⋮ 11691	7	R/W	C	Integral time limiter (low) [heat-side] to 3600 or Integral time limiter (low) [heat-side] to 1999.9 (Unit: second) Varies with the setting of the Integral/Derivative time decimal point position selection.	3600
167	Integral time limiter (low) [heat-side] ♣	I7	CH1 ⋮ CH64	2DAC ⋮ 2DEB	11692 ⋮ 11755	7	R/W	C	PID control or Heat/Cool PID control: 0 (0.0) to Integral time limiter (high) [heat-side] (Unit: second) Position proportioning PID control: 1 (0.1) to Integral time limiter (high) [heat-side] (Unit: second) Varies with the setting of the Integral/Derivative time decimal point position selection.	PID control, Heat/Cool PID control: 0 Position proportioning PID control: 1

- The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control will be “0” for readout and ignored for writing.
All of the channels of the Z-TIO module under control mode other than Heat/Cool PID control will be “0” for readout and ignored for writing.
- ♣ The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control or Position proportioning PID control will be “0” for readout and ignored for writing.

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
168	Derivative time limiter (high) [heat-side] ♣	D6	CH1 ⋮ CH64	2DEC ⋮ 2E2B	11756 ⋮ 11819	7	R/W	C	Derivative time limiter (low) [heat-side] to 3600 or Derivative time limiter (low) [heat-side] to 1999.9 (Unit: second) Varies with the setting of the Integral/Derivative time decimal point position selection.	3600
169	Derivative time limiter (low) [heat-side] ♣	D7	CH1 ⋮ CH64	2E2C ⋮ 2E6B	11820 ⋮ 11883	7	R/W	C	0 (0.0) to Derivative time limiter (high) [heat-side] (Unit: second) Varies with the setting of the Integral/Derivative time decimal point position selection.	0
170	Proportional band limiter (high) [cool-side] ■	P8	CH1 ⋮ CH64	2E6C ⋮ 2EAB	11884 ⋮ 11947	7	R/W	C	TC/RTD inputs: Proportional band limiter (low) [cool-side] to Input span (Unit: °C [°F]) Varies with the setting of the decimal point position selection. Voltage (V)/Current (I) inputs: Proportional band limiter (low) [cool-side] to 1000.0 (Unit: %)	TC/RTD: Input span V/I: 1000.0
171	Proportional band limiter (low) [cool-side] ■	P9	CH1 ⋮ CH64	2EAC ⋮ 2EEB	11948 ⋮ 12011	7	R/W	C	TC/RTD inputs: 1 (1.0) to Proportional band limiter (high) [cool-side] (Unit: °C [°F]) Varies with the setting of the decimal point position selection. Voltage (V)/Current (I) inputs: 0.1 to Proportional band limiter (high) [cool-side] (Unit: %)	TC/RTD: 1 (0.1) V/I: 0.1
172	Integral time limiter (high) [cool-side] ■	I8	CH1 ⋮ CH64	2EEC ⋮ 2F2B	12012 ⋮ 12075	7	R/W	C	Integral time limiter (low) [cool-side] to 3600 or Integral time limiter (low) [cool-side] to 1999.9 (Unit: second) Varies with the setting of the Integral/Derivative time decimal point position selection.	3600
173	Integral time limiter (low) [cool-side] ■	I9	CH1 ⋮ CH64	2F2C ⋮ 2F6B	12076 ⋮ 12139	7	R/W	C	0 (0.0) to Integral time limiter (high) [cool-side] (Unit: second) Varies with the setting of the Integral/Derivative time decimal point position selection.	0
174	Derivative time limiter (high) [cool-side] ■	D8	CH1 ⋮ CH64	2F6C ⋮ 2FAB	12140 ⋮ 12203	7	R/W	C	Derivative time limiter (low) [cool-side] to 3600 or Derivative time limiter (low) [cool-side] to 1999.9 (Unit: second) Varies with the setting of the Integral/Derivative time decimal point position selection.	3600
175	Derivative time limiter (low) [cool-side] ■	D9	CH1 ⋮ CH64	2FAC ⋮ 2FEB	12204 ⋮ 12267	7	R/W	C	0 (0.0) to Derivative time limiter (high) [cool-side] (Unit: second) Varies with the setting of the Integral/Derivative time decimal point position selection.	0

♣ The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control or Position proportioning PID control will be “0” for readout and ignored for writing.

■ The values on channels 2 and 4 of each Z-TIO module under Heat/Cool PID control will be “0” for readout and ignored for writing.
All of the channels of the Z-TIO module under control mode other than Heat/Cool PID control will be “0” for readout and ignored for writing.

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
176	Open/Close output neutral zone *	V2	CH1 ⋮ CH64	2FEC ⋮ 301C	12268 ⋮ 12331	7	R/W	C	0.1 to 10.0 % of output	2.0
177	Action at feedback resistance (FBR) input error *	SY	CH1 ⋮ CH64	302C ⋮ 306B	12332 ⋮ 12395	1	R/W	C	0: Action depending on the valve action at STOP 1: Control action continued	0
178	Feedback adjustment *	FV	CH1 ⋮ CH64	306C ⋮ 30AB	12396 ⋮ 12459	1	R/W	C	0 to 2 (Only 1 can be set) 0: Adjustment end 1: Open-side adjustment start 2: Close-side adjustment start	—
179	Control motor time *	TN	CH1 ⋮ CH64	30AC ⋮ 30EB	12460 ⋮ 12523	7	R/W	C	5 to 1000 seconds	10
180	Integrated output limiter *	OI	CH1 ⋮ CH64	30EC ⋮ 312B	12524 ⋮ 12587	7	R/W	C	0.0 to 200.0 % of control motor time (0.0: OFF) Becomes invalid when there is feedback resistance (FBR) input.	150.0
181	Valve action at STOP *	VS	CH1 ⋮ CH64	312C ⋮ 316B	12588 ⋮ 12651	1	R/W	C	0: Close-side output OFF, Open-side output OFF 1: Close-side output ON, Open-side output OFF 2: Close-side output OFF, Open-side output ON Becomes valid when there is no feedback resistance (FBR) input or the feedback resistance (FBR) input is disconnected.	0
182	ST proportional band adjusting factor	KI	CH1 ⋮ CH64	316C ⋮ 31AB	12652 ⋮ 12715	7	R/W	C	0.01 to 10.00 times	1.00
183	ST integral time adjusting factor	KJ	CH1 ⋮ CH64	31AC ⋮ 31EB	12716 ⋮ 12779	7	R/W	C	0.01 to 10.00 times	1.00
184	ST derivative time adjusting factor	KK	CH1 ⋮ CH64	31EC ⋮ 322B	12780 ⋮ 12843	7	R/W	C	0.01 to 10.00 times	1.00
185	ST start condition	SU	CH1 ⋮ CH64	322C ⋮ 326B	12844 ⋮ 12907	1	R/W	C	0: Activate the Startup tuning (ST) function when the power is turned on; when transferred from STOP to RUN; or when the Set value (SV) is changed. 1: Activate the Startup tuning (ST) function when the power is turned on; or when transferred from STOP to RUN. 2: Activate the Startup tuning (ST) function when the Set value (SV) is changed.	0
186	Automatic temperature rise group	Y7	CH1 ⋮ CH64	326C ⋮ 32AB	12908 ⋮ 12971	7	R/W	C	0 to 16 (0: Automatic temperature rise function OFF)	0
187	Automatic temperature rise dead time	RT	CH1 ⋮ CH64	32AC ⋮ 32EB	12972 ⋮ 13035	7	R/W	C	0.1 to 1999.9 seconds	10.0
188	Automatic temperature rise gradient data	R2	CH1 ⋮ CH64	32EC ⋮ 332B	13036 ⋮ 13099	7	R/W	C	0.1 to Input span/minutes Varies with the setting of the decimal point position.	1.0

* Available only in the Position proportioning PID control.

9. COMMUNICATION DATA LIST

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
189	EDS transfer time decimal point position	NS	CH1 ⋮ CH64	332C ⋮ 336B	13100 ⋮ 13163	1	R/W	C	0: 1 second setting (No decimal place) 1: 0.1 seconds setting (One decimal place)	0
190	Output average processing time for EDS	NV	CH1 ⋮ CH64	336C ⋮ 33AB	13164 ⋮ 13227	7	R/W	C	0.1 to 200.0 seconds	1.0
191	Responsive action trigger point for EDS	NW	CH1 ⋮ CH64	33AC ⋮ 33EB	13228 ⋮ 13291	7	R/W	C	TC/RTD inputs: 0 (0.0) to Input span (Unit: °C [°F]) Varies with the setting of the decimal point position selection. Voltage (V)/Current (I) inputs: 0.0 to Input span (Unit: %)	TC/RTD: 1 (1.0) V/I: 1.0
192	Setting change rate limiter unit time	HU	CH1 ⋮ CH64	33EC ⋮ 342B	13292 ⋮ 13355	7	R/W	C	1 to 3600 seconds	60
193	Soak time unit	RU	CH1 ⋮ CH64	342C ⋮ 346B	13356 ⋮ 13419	7	R/W	C	<ul style="list-style-type: none"> • RKC communication 0: 0:00 to 99:59 (hrs:min) [0 hours 00 minutes to 99 hours 59 minutes] 1: 0:00 to 199:59 (min:sec) [0 minutes 00 seconds to 199 minutes 59 seconds] • Modbus 0: 0 to 5999 minutes [0 hours 00 minutes to 99 hours 59 minutes] 1: 0 to 11999 seconds [0 minutes 00 seconds to 199 minutes 59 seconds] Set the data range of Memory area soak time monitor and Area soak time.	1
194	Setting limiter high	SH	CH1 ⋮ CH64	346C ⋮ 34AB	13420 ⋮ 13483	7	R/W	C	Setting limiter low to Input scale high Varies with the setting of the decimal point position.	Input scale high
195	Setting limiter low	SL	CH1 ⋮ CH64	34AC ⋮ 34EB	13484 ⋮ 13547	7	R/W	C	Input scale low to Setting limiter high Varies with the setting of the decimal point position.	Input scale low
196	PV transfer function	TS	CH1 ⋮ CH64	34EC ⋮ 352B	13548 ⋮ 13611	1	R/W	C	0: Unused 1: Used	0
197	Operation mode assignment 1 (Logic output selection function) Logic output 1 to 4	EA	CH1 ⋮ CH64	352C ⋮ 356B	13612 ⋮ 13675	7	R/W	C	0: No assignment 1: Operation mode (monitor, control) 2: Operation mode (monitor, event function, control) 3: Auto/Manual 4: Remote/Local 5: Unused (Do not set this one)	0
198	Operation mode assignment 2 (Logic output selection function) Logic output 5 to 8	EB	CH1 ⋮ CH64	356C ⋮ 35AB	13676 ⋮ 13739	7	R/W	C	0: No assignment 1: Operation mode (monitor, control) 2: Operation mode (monitor, event function, control) 3: Auto/Manual 4: Remote/Local 5: Unused (Do not set this one)	0

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
199	SV select function	KM	CH1 ⋮ CH64	35AC ⋮ 35EB	13740 ⋮ 13803	1	R/W	C	0: Remote SV function 1: Cascade control function 2: Ratio setting function 3: Cascade control 2 function	0
200	Remote SV function master channel module address	MC	CH1 ⋮ CH64	35EC ⋮ 362B	13804 ⋮ 13867	7	R/W	C	−1 (Master channel is selected from itself) 0 to 99 (Master channel is selected from other modules)	−1
201	Remote SV function master channel selection	MN	CH1 ⋮ CH64	362C ⋮ 366B	13868 ⋮ 13931	7	R/W	C	1 to 99	1
202	Output distribution master channel module address	DY	CH1 ⋮ CH64	366C ⋮ 36AB	13932 ⋮ 13995	7	R/W	C	−1 (Master channel is selected from itself) 0 to 99 (Master channel is selected from other modules)	−1
203	Output distribution master channel selection	DZ	CH1 ⋮ CH64	36AC ⋮ 36EB	13996 ⋮ 14059	7	R/W	C	1 to 99	1
204	Address of interacting modules	RL	CH1 ⋮ CH64	36EC ⋮ 372B	14060 ⋮ 14123	7	R/W	C	−1 (Interact with its own module address) 0 to 99 (Interact with the addresses of other modules)	−1
205	Channel selection of interacting modules	RM	CH1 ⋮ CH64	372C ⋮ 376B	14124 ⋮ 14187	7	R/W	C	1 to 99 Becomes valid when the selected module is “Z-TIO module.”	1
206	Selection switch of interacting modules	RN	CH1 ⋮ CH64	376C ⋮ 37AB	14188 ⋮ 14251	7	R/W	C	<ul style="list-style-type: none"> • RKC communication Least significant digit: <ul style="list-style-type: none"> Memory area number 2nd digit: Operation mode 3rd digit: Auto/Manual 4th digit: Remote/Local 5th digit: EDS start signal 6th digit: Interlock release Most significant digit: <ul style="list-style-type: none"> Suspension of area soak time Data 0: No interaction 1: Interact with other channels • Modbus Bit data Bit 0: Memory area number Bit 1: Operation mode Bit 2: Auto/Manual Bit 3: Remote/Local Bit 4: EDS start signal Bit 5: Interlock release Bit 6: Suspension of area soak time Bit 7 to Bit 15: Unused Data 0: No interaction 1: Interact with other channels [Decimal number: 0 to 127]	0

No.	Name	RKC iden- tifier	Chan- nel	Modbus register address		Digits	Attri- bute	Struc- ture	Data range	Factory set value
				HEX	DEC					
207	TIO Interval time	VG	CH1 ⋮ CH16	37AC ⋮ 37BB	14252 ⋮ 14267	7	R/W	M	0 to 250 ms	10
208	—	—	—	37BC ⋮ 386B	14268 ⋮ 14443	—	—	—	—	—

9.4 Memory Area Data Address of Z-TIO Module (only for Modbus)

The register addresses, 386CH to 3DABH are used for checking and changing each set value belonging to the memory area.

No.	Name	Channel	Modbus register address		Attribute	Structure	Data range	Factory set value
			HEX	DEC				
1	Setting memory area number	CH1 ⋮ CH64	386C ⋮ 38AB	14444 ⋮ 14507	R/W	C	1 to 8	1
2	Event 1 set value (EV1)	CH1 ⋮ CH64	38AC ⋮ 38EB	14508 ⋮ 14571	R/W	C	Deviation action, Deviation action between channels, Temperature rise completion range: –Input span to +Input span Process action, SV action: Input scale low to Input scale high MV action: –5.0 to +105.0 %	50 (50.0)
3	Event 2 set value (EV2)	CH1 ⋮ CH64	38EC ⋮ 392B	14572 ⋮ 14635	R/W	C		50 (50.0)
4	Event 3 set value (EV3)	CH1 ⋮ CH64	392C ⋮ 396B	14636 ⋮ 14699	R/W	C		50 (50.0)
5	Event 4 set value (EV4)	CH1 ⋮ CH64	396C ⋮ 39AB	14700 ⋮ 14763	R/W	C		50 (50.0)
6	Control loop break alarm (LBA) time	CH1 ⋮ CH64	39AC ⋮ 39EB	14764 ⋮ 14827	R/W	C	0 to 7200 seconds (0: Unused)	480
7	LBA deadband	CH1 ⋮ CH64	39EC ⋮ 3A2B	14828 ⋮ 14791	R/W	C	0 (0.0) to Input span Varies with the setting of the decimal point position.	0 (0.0)
8	Set value (SV)	CH1 ⋮ CH64	3A2C ⋮ 3A6B	14892 ⋮ 14955	R/W	C	Setting limiter low to Setting limiter high	TC/RTD: 0 (0.0) V/I: 0.0
9	Proportional band [heat-side]	CH1 ⋮ CH64	3A6C ⋮ 3AAB	14956 ⋮ 15019	R/W	C	TC/RTD inputs: 0 (0.0) to Input span (Unit: °C [°F]) Varies with the setting of the decimal point position. Voltage (V)/Current (I) inputs: 0.0 to 1000.0 % of input span 0 (0.0): ON/OFF action (ON/OFF action for both heat and cool actions in case of a Heat/Cool PID control type.)	TC/RTD: 30 (30.0) V/I: 30.0
10	Integral time [heat-side]	CH1 ⋮ CH64	3AAC ⋮ 3AEB	15020 ⋮ 15083	R/W	C	PID control or Heat/Cool PID control: 0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PD action) Position proportioning PID control: 1 to 3600 seconds or 0.1 to 1999.9 seconds	240
11	Derivative time [heat-side]	CH1 ⋮ CH64	3AEC ⋮ 3B2B	15084 ⋮ 15147	R/W	C	0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PI action)	60
12	Control response parameter	CH1 ⋮ CH64	3B2C ⋮ 3B6B	15148 ⋮ 15211	R/W	C	0: Slow 1: Medium 2: Fast When the P or PD action is selected, this setting becomes invalid.	PID control, Position proportioning PID control: 0 Heat/Cool PID control: 2

9. COMMUNICATION DATA LIST

No.	Name	Chan- nel	Modbus register address		Attri- bute	Struc- ture	Data range	Factory set value
			HEX	DEC				
13	Proportional band [cool-side]	CH1 ⋮ CH64	3B6C ⋮ 3BAB	15212 ⋮ 15275	R/W	C	TC/RTD inputs: 1 to Input span or 0.1 to Input span (Unit: °C [°F]) Varies with the setting of the decimal point position. Voltage (V)/Current (I) inputs: 0.1 to 1000.0 % of input span	TC/RTD: 30 (30.0) V/I: 30.0
14	Integral time [cool-side]	CH1 ⋮ CH64	3BAC ⋮ 3BEB	15276 ⋮ 15339	R/W	C	0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PD action) Varies with the setting of the Integral/Derivative time decimal point position selection.	240
15	Derivative time [cool-side]	CH1 ⋮ CH64	3BEC ⋮ 3C2B	15340 ⋮ 15403	R/W	C	0 to 3600 seconds or 0.0 to 1999.9 seconds (0, 0.0: PI action) Varies with the setting of the Integral/Derivative time decimal point position selection.	60
16	Overlap/Deadband	CH1 ⋮ CH64	3C2C ⋮ 3C6B	15404 ⋮ 15467	R/W	C	TC/RTD inputs: –Input span to +Input span (Unit: °C [°F]) Varies with the setting of the decimal point position. Voltage (V)/Current (I) inputs: –100.0 to +100.0 % of input span Minus (–) setting results in overlap. However, the overlapping range is within the proportional range.	0 (0.0)
17	Manual reset	CH1 ⋮ CH64	3C6C ⋮ 3CAB	15468 ⋮ 15531	R/W	C	–100.0 to +100.0 % If the integral function is valid, set to RO (Only reading data is possible). When integral action (heating or cooling side) is zero, manual reset value is added to the control output.	0.0
18	Setting change rate limiter (up)	CH1 ⋮ CH64	3CAC ⋮ 3CEB	15532 ⋮ 15595	R/W	C	0 (0.0) to Input span/unit time * 0 (0.0): Unused Varies with the setting of the decimal point position.	0 (0.0)
19	Setting change rate limiter (down)	CH1 ⋮ CH64	3CEC ⋮ 3D2B	15596 ⋮ 15659	R/W	C	* Unit time: 60 seconds (factory set value)	0 (0.0)
20	Area soak time	CH1 ⋮ CH64	3D2C ⋮ 3D6B	15660 ⋮ 15723	R/W	C	0 minutes 00 seconds to 199 minutes 59 seconds: 0 to 11999 seconds 0 hours 00 minutes to 99 hours 59 minutes: 0 to 5999 minutes Data range of Area soak time can be selected on the Soak time unit.	0
21	Link area number	CH1 ⋮ CH64	3D6C ⋮ 3DAB	15724 ⋮ 15787	R/W	C	0 to 8 (0: No link)	0
22	—	—	3DAC ⋮ 3E6B	15788 ⋮ 15979	—	—	—	—

9.5 Communication Data of Z-DIO Module

☞ For details of Z-DIO module communication data, refer to **SRZ Instruction Manual (IMS01T04-E□)**.

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
1	Digital input (DI) state 1	L1	CH1 ⋮ CH16	3E6C ⋮ 3E7B	15980 ⋮ 15995	7	RO	M	<ul style="list-style-type: none"> • RKC communication Least significant digit: DI1 2nd digit: DI2 3rd digit: DI3 4th digit: DI4 5th digit to Most significant digit: Unused Data 0: Contact open 1: Contact closed • Modbus Bit data Bit 0: DI1 Bit 1: DI2 Bit 2: DI3 Bit 3: DI4 Bit 4: DI5 Bit 5: DI6 Bit 6: DI7 Bit 7: DI8 Bit 8 to Bit 15: Unused Data 0: Contact open 1: Contact closed [Decimal number: 0 to 255] 	—
2	Digital input (DI) state 2	L6	CH1 ⋮ CH16	—	—	7	RO	M	<ul style="list-style-type: none"> • RKC communication Least significant digit: DI5 2nd digit: DI6 3rd digit: DI7 4th digit: DI8 5th digit to Most significant digit: Unused Data 0: Contact open 1: Contact closed 	—
3	Digital output (DO) state 1	Q2	CH1 ⋮ CH16	3E7C ⋮ 3E8B	15996 ⋮ 16011	7	RO	M	<ul style="list-style-type: none"> • RKC communication Least significant digit: DO1 2nd digit: DO2 3rd digit: DO3 4th digit: DO4 5th digit to Most significant digit: Unused Data 0: OFF 1: ON • Modbus Bit data Bit 0: DO1 Bit 1: DO2 Bit 2: DO3 Bit 3: DO4 Bit 4: DO5 Bit 5: DO6 Bit 6: DO7 Bit 7: DO8 Bit 8 to Bit 15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 255] 	—
4	Digital output (DO) state 2	Q3	CH1 ⋮ CH16	—	—	7	RO	M	<ul style="list-style-type: none"> • RKC communication Least significant digit: DO5 2nd digit: DO6 3rd digit: DO7 4th digit: DO8 5th digit to Most significant digit: Unused Data 0: OFF 1: ON 	—

9. COMMUNICATION DATA LIST

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
5	—	—	—	3E8C ⋮ 3FDB	16012 ⋮ 16347	—	—	—	—	—
6	DO manual output 1	Q4	CH1 ⋮ CH16	3FDC ⋮ 3FEB	16348 ⋮ 16363	7	R/W	M	<ul style="list-style-type: none"> • RKC communication Least significant digit: DO1 manual output 2nd digit: DO2 manual output 3rd digit: DO3 manual output 4th digit: DO4 manual output 5th digit to Most significant digit: Unused Data 0: OFF 1: ON <ul style="list-style-type: none"> • Modbus Bit data Bit 0: DO1 manual output Bit 1: DO2 manual output Bit 2: DO3 manual output Bit 3: DO4 manual output Bit 4: DO5 manual output Bit 5: DO6 manual output Bit 6: DO7 manual output Bit 7: DO8 manual output Bit 8 to Bit 15: Unused Data 0: OFF 1: ON [Decimal number: 0 to 255]	0
7	DO manual output 2	Q5	CH1 ⋮ CH16	—	—	7	R/W	M	<ul style="list-style-type: none"> • RKC communication Least significant digit: DO5 manual output 2nd digit: DO6 manual output 3rd digit: DO7 manual output 4th digit: DO8 manual output 5th digit to Most significant digit: Unused Data 0: OFF 1: ON	0
8	DO output distribution selection	DO	CH1 ⋮ CH128	3FEC ⋮ 406B	16364 ⋮ 16491	1	R/W	C	0: DO output 1: Distribution output	0
9	DO output distribution bias	O8	CH1 ⋮ CH128	406C ⋮ 40EB	16492 ⋮ 16619	7	R/W	C	−100.0 to +100.0 %	0.0
10	DO output distribution ratio	O9	CH1 ⋮ CH128	40EC ⋮ 416B	16620 ⋮ 16747	7	R/W	C	−9.999 to +9.999	1.000
11	DO proportional cycle time	V0	CH1 ⋮ CH128	416C ⋮ 41EB	16748 ⋮ 16875	7	R/W	C	0.1 to 100.0 seconds	Relay contact output: 20.0 Open collector output: 2.0
12	DO minimum ON/OFF time of proportioning cycle	VJ	CH1 ⋮ CH128	41EC ⋮ 426B	16876 ⋮ 17003	7	R/W	C	0 to 1000 ms	0
13	—	—	—	426C ⋮ 433B	17004 ⋮ 17211	—	—	—	—	—
Set data No. 14 or later are for engineering setting [Writable in the STOP mode]										
14	DI function assignment	H2	CH1 ⋮ CH16	433C ⋮ 434B	17212 ⋮ 17227	7	R/W	M	0 to 29 (See P. 88.)	Depends on model code. When not specifying: 0

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
15	Memory area setting signal	E1	CH1 ⋮ CH16	434C ⋮ 435B	17228 ⋮ 17243	1	R/W	M	0: Valid 1: Invalid	1
16	DO signal assignment module address 1 [DO1 to DO4]	LQ	CH1 ⋮ CH16	435C ⋮ 436B	17244 ⋮ 17259	7	R/W	M	–1, 0 to 99 When “–1” is selected, all of the signals of the same type (except temperature rise completion and DO manual output value) are <i>OR</i> -operated and produced as outputs from DO.	–1
17	DO signal assignment module address 2 [DO5 to DO8]	LR	CH1 ⋮ CH16	436C ⋮ 437B	17260 ⋮ 17275	7	R/W	M	–1, 0 to 99 When “–1” is selected, all of the signals of the same type (except temperature rise completion and DO manual output value) are <i>OR</i> -operated and produced as outputs from DO.	–1
18	DO output assignment 1 [DO1 to DO4]	LT	CH1 ⋮ CH16	437C ⋮ 438B	17276 ⋮ 17291	7	R/W	M	0 to 13 (See P. 89 .)	Based on model code. When not specifying: 0
19	DO output assignment 2 [DO5 to DO8]	LX	CH1 ⋮ CH16	438C ⋮ 439B	17292 ⋮ 17307	7	R/W	M	0 to 13 (See P. 89 .)	Based on model code. When not specifying: 0
20	DO energized/de-energized	NB	CH1 ⋮ CH128	439C ⋮ 441B	17308 ⋮ 17435	7	R/W	C	0: Energized 1: De-energized	0
21	DO output distribution master channel module address	DD	CH1 ⋮ CH128	441C ⋮ 449B	17436 ⋮ 17563	7	R/W	C	–1 (Master channel is selected from itself) 0 to 99 (Master channel is selected from other modules)	–1
22	DO output distribution master channel selection	DJ	CH1 ⋮ CH128	449C ⋮ 451B	17564 ⋮ 17691	7	R/W	C	1 to 99	1
23	DO manipulated output value (MV) at STOP mode	OJ	CH1 ⋮ CH128	451C ⋮ 459B	17692 ⋮ 17819	7	R/W	C	–5.0 to +105.0 %	–5.0
24	DO output limiter (high) *	D3	CH1 ⋮ CH128	459C ⋮ 461B	17820 ⋮ 17947	7	R/W	C	DO output limiter (low) to 105.0 %	105.0
25	DO output limiter (low) *	D4	CH1 ⋮ CH128	461C ⋮ 469B	17948 ⋮ 18075	7	R/W	C	–5.0 % to DO output limiter (high)	–5.0
26	DIO Interval time	VF	CH1 ⋮ CH16	469C ⋮ 46AB	18076 ⋮ 18091	7	R/W	M	0 to 250 ms	10
27	—	—	—	46AC ⋮ 46BB	18092 ⋮ 18107	—	—	—	—	—

* Settable during control (RUN state).

Table 1: DI assignment table

Set value	DI1	DI2	DI3	DI4	DI5	DI6	DI7	DI8	
0	No assignment								
1	Memory area transfer (1 to 8) ¹			Area set ²	Operation mode ³		Interlock release	AUTO/MAN ⁴	
2								REM/LOC ⁴	
3								EDS start signal 1	
4								Soak stop	
5							RUN/STOP ⁴		
6							REM/LOC ⁴		
7							EDS start signal 1		
8							Soak stop		
9							RUN/STOP ⁴		
10							EDS start signal 1		
11							Soak stop		
12							RUN/STOP ⁴		
13							EDS start signal 1		
14							Soak stop		
15							RUN/STOP ⁴		
16							EDS start signal 1		
17					Soak stop				
18					RUN/STOP ⁴				
19					EDS start signal 1				
20					Soak stop				
21					RUN/STOP ⁴				
22					EDS start signal 1				
23					Soak stop				
24					RUN/STOP ⁴				
25					REM/LOC	EDS start signal 1	Interlock release	AUTO/MAN ⁴	REM/LOC ⁴
26	Memory area transfer (1, 2) ¹	Area set ²	Interlock release	RUN/STOP ⁴	AUTO/MAN ⁴	REM/LOC ⁴			Operation mode ³
27	Memory area transfer (1 to 8) ¹			Area set ²	Operation mode ³				EDS start signal 1
28	Memory area transfer (1, 2) ¹	Area set ²	Interlock release	RUN/STOP ⁴	AUTO/MAN ⁴	REM/LOC ⁴	EDS start signal 1	EDS start signal 2	
29	EDS start signal 1	EDS start signal 2							Operation mode ³

RUN/STOP: RUN/STOP transfer (Contact closed: RUN)

AUTO/MAN: Auto/Manual transfer (Contact closed: Manual mode)

REM/LOC: Remote/Local transfer (Contact closed: Remote mode)

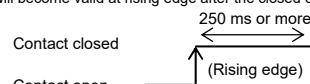
Interlock release (Interlock release when rising edge is detected)

EDS start signal 1 (EDS start signal ON when rising edge is detected [for disturbance 1])

EDS start signal 2 (EDS start signal ON when rising edge is detected [for disturbance 2])

Soak stop (Contact closed: Soak stop)

DI signal will become valid at rising edge after the closed contact is held for 250 ms.



1 Memory area transfer

(x: Contact open -/: Contact closed)

	Memory area number							
	1	2	3	4	5	6	7	8
DI1	x	-	x	-	x	-	x	-
DI2	x	x	-	-	x	x	-	-
DI3	x	x	x	x	-	-	-	-

2 Area set becomes invalid prior to factory shipment.

3 Operation mode transfer

(x: Contact open -/: Contact closed)

	Operation mode			
	Unused	Monitor	Monitor + Event function	Control
DI5 (DI7)	x	-	x	-
DI6 (DI8)	x	x	-	-

4 Actual device states (AUTO/MAN, REM/LOC, RUN/STOP)

	DI-switched state	Communication-switched state	Actual device state
Auto/Manual transfer ^a (AUTO/MAN)	Manual (Contact closed)	Manual → Auto	Manual mode
		Auto → Manual	
	Auto (Contact open)	Manual → Auto	Auto mode
		Auto → Manual	
Remote/Local transfer ^a (REM/LOC)	Remote (Contact closed)	Remote → Local	Remote mode
		Local → Remote	
	Local (Contact open)	Remote → Local	Local mode
		Local → Remote	
RUN/STOP ^b	RUN (Contact closed)	STOP → RUN	RUN
		RUN → STOP	
	STOP (Contact open)	STOP → RUN	STOP

^a Device state when AUTO/MAN or REM/LOC assigned to DI is set so that the Z-TIO module and Z-DIO module are linked using the Master-slave mode of the Z-TIO module.

^b STOP of RUN/STOP switching is given priority regardless of communication or DI switching.

Table 2: DO assignment table

[DO1 to DO4]

Set value	DO1	DO2	DO3	DO4
0	No assignment			
1	DO1 manual output	DO2 manual output	DO3 manual output	DO4 manual output
2	Event 1 comprehensive output ¹	Event 2 comprehensive output ²	Event 3 comprehensive output ³	Event 4 comprehensive output ⁴
3	Event 1 (CH1)	Event 2 (CH1)	Event 3 (CH1)	Event 4 (CH1)
4	Event 1 (CH2)	Event 2 (CH2)	Event 3 (CH2)	Event 4 (CH2)
5	Event 1 (CH3)	Event 2 (CH3)	Event 3 (CH3)	Event 4 (CH3)
6	Event 1 (CH4)	Event 2 (CH4)	Event 3 (CH4)	Event 4 (CH4)
7	Event 1 (CH1)	Event 1 (CH2)	Event 1 (CH3)	Event 1 (CH4)
8	Event 2 (CH1)	Event 2 (CH2)	Event 2 (CH3)	Event 2 (CH4)
9	Event 3 (CH1)	Event 3 (CH2)	Event 3 (CH3)	Event 3 (CH4)
10	Event 4 (CH1)	Event 4 (CH2)	Event 4 (CH3)	Event 4 (CH4)
11	HBA (CH1) of Z-TIO module	HBA (CH2) of Z-TIO module	HBA (CH3) of Z-TIO module	HBA (CH4) of Z-TIO module
12	Burnout status (CH1)	Burnout status (CH2)	Burnout status (CH3)	Burnout status (CH4)
13	Temperature rise completion ⁵	HBA comprehensive output ⁶	Burnout state comprehensive output ⁷	DO4 manual output

[DO5 to DO8]

Set value	DO5	DO6	DO7	DO8
0	No assignment			
1	DO5 manual output	DO6 manual output	DO7 manual output	DO8 manual output
2	Event 1 comprehensive output ¹	Event 2 comprehensive output ²	Event 3 comprehensive output ³	Event 4 comprehensive output ⁴
3	Event 1 (CH1)	Event 2 (CH1)	Event 3 (CH1)	Event 4 (CH1)
4	Event 1 (CH2)	Event 2 (CH2)	Event 3 (CH2)	Event 4 (CH2)
5	Event 1 (CH3)	Event 2 (CH3)	Event 3 (CH3)	Event 4 (CH3)
6	Event 1 (CH4)	Event 2 (CH4)	Event 3 (CH4)	Event 4 (CH4)
7	Event 1 (CH1)	Event 1 (CH2)	Event 1 (CH3)	Event 1 (CH4)
8	Event 2 (CH1)	Event 2 (CH2)	Event 2 (CH3)	Event 2 (CH4)
9	Event 3 (CH1)	Event 3 (CH2)	Event 3 (CH3)	Event 3 (CH4)
10	Event 4 (CH1)	Event 4 (CH2)	Event 4 (CH3)	Event 4 (CH4)
11	HBA (CH1) of Z-TIO module	HBA (CH2) of Z-TIO module	HBA (CH3) of Z-TIO module	HBA (CH4) of Z-TIO module
12	Burnout status (CH1)	Burnout status (CH2)	Burnout status (CH3)	Burnout status (CH4)
13	Temperature rise completion ⁵	HBA comprehensive output ⁶	Burnout state comprehensive output ⁷	DO8 manual output


¹ Logical OR of Event 1 (ch1 to ch4)² Logical OR of Event 2 (ch1 to ch4)³ Logical OR of Event 3 (ch1 to ch4)⁴ Logical OR of Event 4 (ch1 to ch4)⁵ Temperature rise completion status (ON when temperature rise completion occurs for all channels for which event 3 is set to temperature rise completion.)⁶ The following signals are output depending on the setting of the DO signal assignment module address.

- Logical OR of HBA (ch1 to ch4) of Z-TIO module
- Logical OR of HBA (ch1 to ch12) of Z-CT module
- Logical OR of HBA (ch1 to ch4) of Z-TIO module and HBA (ch1 to ch12) of Z-CT module

⁷ Logical OR of burnout state (ch1 to ch4)

To output the HBA signal of a Z-CT module from DO, set “13.” For details of the Z-CT module, refer to **Z-CT Instruction Manual [Detailed version] (IMS01T21-E□)**.

9.6 Communication Data of Z-CT Module

 For details of Z-CT module communication data, refer to **Z-CT Instruction Manual [Detailed version] (IMS01T21-E□)**.

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
1	Current transformer (CT) input value monitor	M4	CH1 ⋮ CH192	46BC ⋮ 477B	18108 ⋮ 18299	7	RO	C	CTL-6-P-Z: 0.0 to 10.0 A CTL-6-P-N: 0.0 to 30.0 A CTL-12-S56-10L-N: 0.0 to 100.0 A	—
2	Load factor conversion CT monitor	M5	CH1 ⋮ CH192	477C ⋮ 483B	18300 ⋮ 18491	7	RO	C	0.0 to 100.0 A	—
3	Heater break alarm (HBA) state monitor	AF	CH1 ⋮ CH192	483C ⋮ 48FB	18492 ⋮ 18683	1	RO	C	0: Normal 1: Break 2: Melting	—
4	Heater overcurrent alarm state monitor	AG	CH1 ⋮ CH192	48FC ⋮ 49BB	18684 ⋮ 18875	1	RO	C	0: Normal 1: Heater overcurrent	—
5	Automatic setting state monitor ¹	CJ	CH1 ⋮ CH16	49BC ⋮ 49CB	18876 ⋮ 18891	1	RO	M	0: Normal state 1: Automatic setting execution 2: Automatic setting failure	—
6	—	—	—	49CC ⋮ 4FCB	18892 ⋮ 20427	—	—	—	—	—
7	Heater break/Heater overcurrent alarm automatic setting selection	BT	CH1 ⋮ CH192	4FCC ⋮ 508B	20428 ⋮ 20619	1	R/W	C	0: Automatic setting is disabled. (Alarm set value cannot be automatically set by the push button and communication.) 1: Automatic setting for heater break alarm (HBA) is enabled. 2: Automatic setting for heater overcurrent alarm set value is enabled. 3: Automatic setting for heater break alarm (HBA) and heater overcurrent alarm set values are enabled.	1
8	Automatic setting transfer ²	BU	CH1 ⋮ CH192	508C ⋮ 514B	20620 ⋮ 20811	1	R/W	C	0: Normal state 1: Automatic setting execution When automatic setting ends normally, this reverts to “0: Normal state.” 2: Automatic setting failure (RO)	0
9	Heater break alarm (HBA) set value	A8	CH1 ⋮ CH192	514C ⋮ 520B	20812 ⋮ 21003	1	R/W	C	0.0 to 100.0 A 0.0: Heater break alarm function (HBA) OFF (HBA function OFF: The current transformer (CT) input value monitoring is available.)	0.0
10	Heater break alarm (HBA) selection	BZ	CH1 ⋮ CH192	520C ⋮ 52CB	21004 ⋮ 21195	1	R/W	C	0: Heater break alarm (HBA) unused 1: Heater break alarm (HBA) 2: Heater break alarm (HBA) (With alarm interlock function)	1

¹ This is linked to the solid lighting or blinking state of the automatic setting state indication lamp (SET).

² Automatic setting is only possible for channels that have been set to other than “0: Automatic setting is disabled” in heater break/heater overcurrent alarm automatic setting selection.

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
11	Heater overcurrent alarm set value	A6	CH1 ⋮ CH192	52CC ⋮ 538B	21196 ⋮ 21387	7	R/W	C	0.0 to 105.0 A 0.0: Heater overcurrent alarm function OFF	0.0
12	Heater overcurrent alarm selection	BO	CH1 ⋮ CH192	538C ⋮ 544B	21388 ⋮ 21579	1	R/W	C	0: Heater overcurrent alarm unused 1: Heater overcurrent alarm 2: Heater overcurrent alarm (With alarm interlock function)	1
13	Heater break alarm (HBA) interlock release	CX	CH1 ⋮ CH192	544C ⋮ 550B	21580 ⋮ 21771	1	R/W	C	0: Normal state 1: Interlock release execution After the interlock is released, this automatically returns to "0."	0
14	Heater overcurrent alarm interlock release	CY	CH1 ⋮ CH192	550C ⋮ 55CB	21772 ⋮ 21963	1	R/W	C	0: Normal state 1: Interlock release execution After the interlock is released, this automatically returns to "0."	0
15	—	—	—	55CC ⋮ 5E0B	21964 ⋮ 24075	—	—	—	—	—
16	Set lock ¹	LK	CH1 ⋮ CH16	5E0C ⋮ 5E1B	24076 ⋮ 24091	1	R/W	M	0: Unlock 1: Lock	0
Set data No. 17 or later are for engineering setting [Writable in the STOP mode]										
17	CT type ²	BV	CH1 ⋮ CH192	5E1C ⋮ 5EDB	24092 ⋮ 24283	1	R/W ³	C	0: CTL-6-P-N (0.0 to 30.0 A) 1: CTL-12-S56-10L-N (0.0 to 100.0 A) 2: CTL-6-P-Z (0.0 to 10.0 A)	Based on model code. When not specifying: 0
18	CT ratio ⁴ (CT number of winds)	XT	CH1 ⋮ CH192	5EDC ⋮ 5F9B	24284 ⋮ 24475	7	R/W ³	C	0 to 9999	CTL-6-P-N, CTL-6-P-Z: 800 CTL-12-S56-10L-N: 1000
19	Number of heater break alarm (HBA) delay times	DI	CH1 ⋮ CH192	5F9C ⋮ 605B	24476 ⋮ 24667	7	R/W ³	C	0 to 255 times	5
20	Automatic setting factor for heater break alarm (HBA)	BW	CH1 ⋮ CH192	605C ⋮ 611B	24668 ⋮ 24859	7	R/W ³	C	1 to 100 %	75
21	Automatic setting factor for heater overcurrent alarm	B9	CH1 ⋮ CH192	611C ⋮ 61DB	24860 ⋮ 25051	7	R/W ³	C	100 to 1000 %	200
22	Determination current value for automatic setting	BP	CH1 ⋮ CH192	61DC ⋮ 629B	25052 ⋮ 25243	7	R/W ³	C	0.0 to 100.0 A	1.0
23	Automatic setting time	BQ	CH1 ⋮ CH192	629C ⋮ 635B	25244 ⋮ 25435	7	R/W ³	C	10 to 250 seconds	60

¹ When the RUN/STOP transfer (Each unit) [Identifier: SR, Register address: 0133H] of the COM-ME becomes STOP, set lock becomes "0: Unlock". (i.e. The engineering setting data is writable.)

² When using a non-specified CT, set to "1: CTL-12-S56-10L-N (0.0 to 100.0 A)".

³ When the set lock [Identifier: LK, Register address: 5E0CH to 5E1BH] is set to "0: Unlock" (the RUN/STOP transfer of the COM-ME becomes STOP), writing data is possible.

⁴ When using a non-specified CT, set the number of winds of the CT.

No.	Name	RKC identifier	Channel	Modbus register address		Digits	Attribute	Structure	Data range	Factory set value
				HEX	DEC					
24	Module address assignments for CT input	BX	CH1 ⋮ CH192	635C ⋮ 641B	25436 ⋮ 25627	7	R/W ¹	C	0 to 99	0
25	Module channel assignments for CT input	BY	CH1 ⋮ CH192	641C ⋮ 64DB	25628 ⋮ 25819	7	R/W ¹	C	1 to 99	1
26	Load factor conversion method ²	IC	CH1 ⋮ CH192	64DC ⋮ 659B	25820 ⋮ 26011	1	R/W ¹	C	0: Mean conversion 1: Root mean squared value conversion	0
27	CT Interval time	VH	CH1 ⋮ CH16	659C ⋮ 65AB	26012 ⋮ 26027	7	R/W ¹	M	0 to 250 ms	10
28	—	—	—	65AC ⋮ 666B	26028 ⋮ 26219	—	—	—	—	—

¹ When the set lock [Identifier: LK, Register address: 5E0CH to 5E1BH] is set to “0: Unlock” (the RUN/STOP transfer of the COM-ME becomes STOP), writing data is possible.

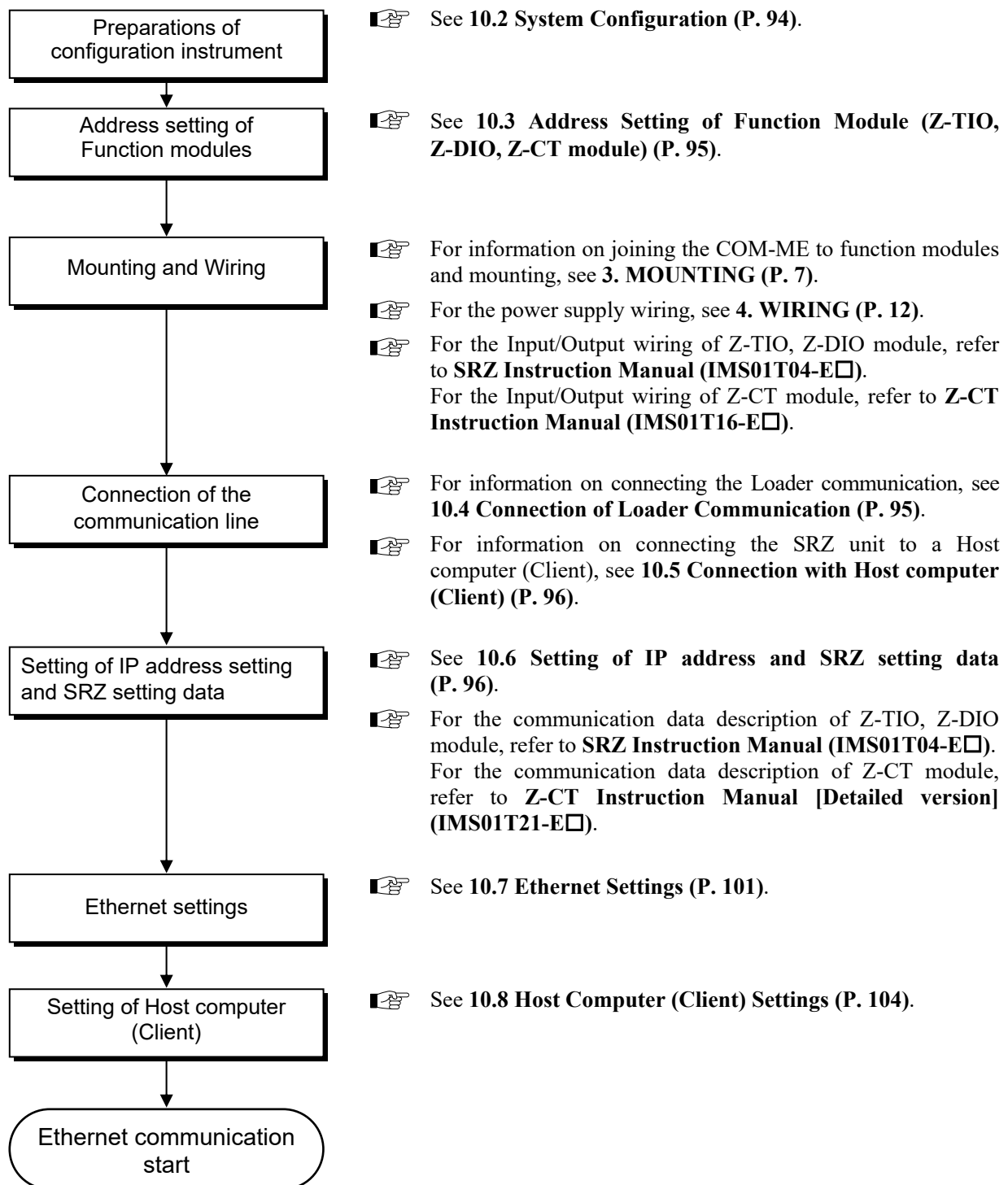
² For monitoring using “0: Mean conversion” or “1: Root mean squared value conversion,” the following settings are required:

- Module address assignments for CT input must be set.
- Module channel assignments for CT input must be set.
- The heater break alarm (HBA) value must be set to other than “0.0”.

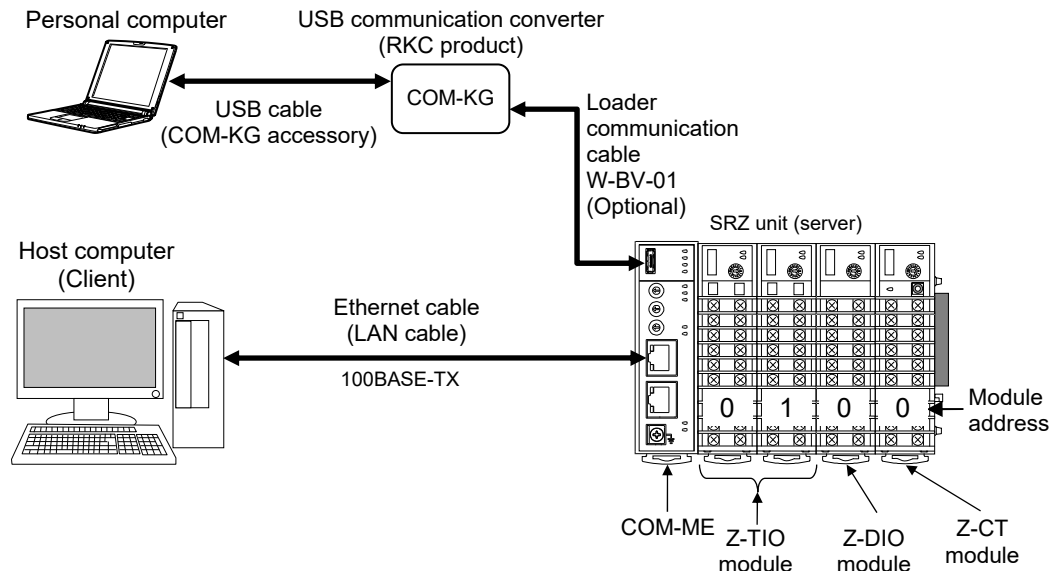
10.SETTING EXAMPLE OF MODBUS/TCP

10.1 Handling procedures

In this Chapter, an example of setting procedure is explained when the COM-ME (SRZ unit) is connected to a Host computer (Client). In this example, IP address of the COM-ME and SRZ setting data settings are configured by loader communication.



10.2 System Configuration



■ Use instruments

● Ethernet Modbus/TCP communication converter COM-ME-1

COM-ME-15 * 02/11 1

● SRZ function module

Temperature control module Z-TIO-A 2

Digital I/O module Z-DIO-A 1

Current transformer (CT) input module Z-CT-A 1

● Communication converter

USB communication converter COM-KG (RKC product) 1

● Connection cable for connecting COM-ME and personal computer

USB cable (COM-KG accessory) [Cable length: 1 m] 1

W-BV-01 (COM-KG optional) [Cable length: 1.5 m] 1

● Others

Ethernet cable (LAN cable) 1

● Personal computer and Host computer (Client)

Install our configuration software PROTEM2 on your PC and host computer (client) as shown in the picture. You can configure communication and data setting of modules using PROTEM2. You can choose Modbus/TCP as a communication protocol to send/receive the data between the SRZ unit and the host computer (client).

The PROTEM2 can be downloaded from the RKC official website.

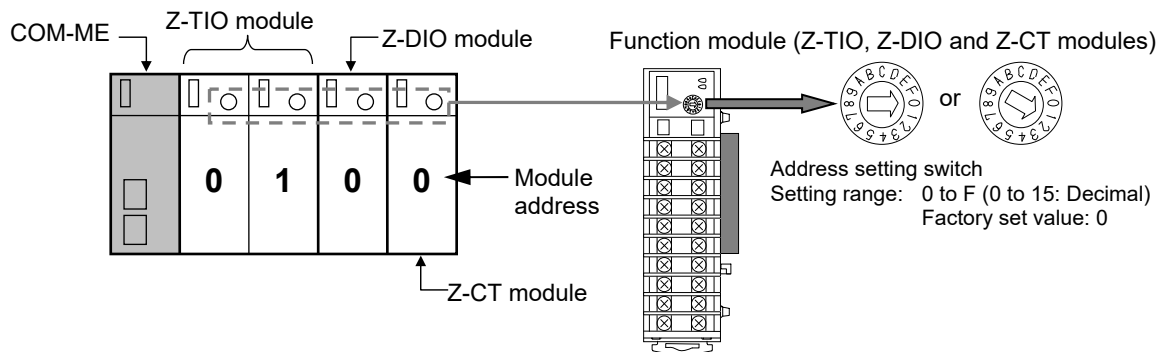
10.3 Address Setting of Function Module (Z-TIO, Z-DIO, Z-CT module)

Set the module address by address setting switch of front of module. For this setting, use a small blade screwdriver. In this application, make the setting as follows.

Z-TIO module address: 0, 1

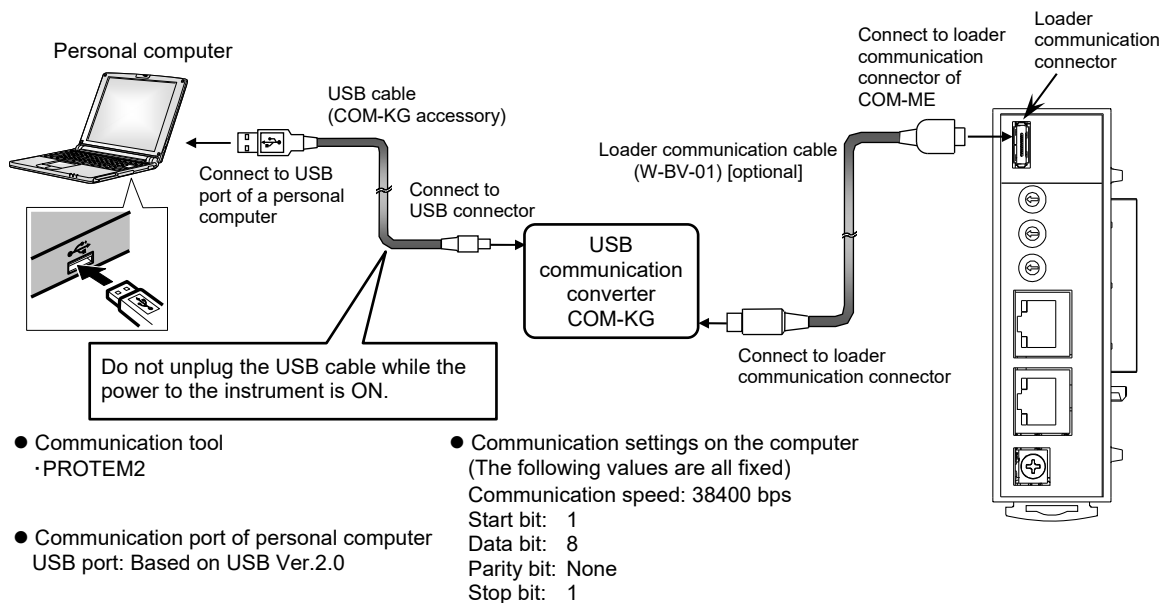
Z-DIO module address: 0

Z-CT module address: 0



10.4 Connection of Loader Communication

Connect a personal computer, COM-KG and COM-ME (SRZ unit).



During the loader communication, the COM-ME requires an external power source. The COM-ME will not function on the USB power from a personal computer alone.

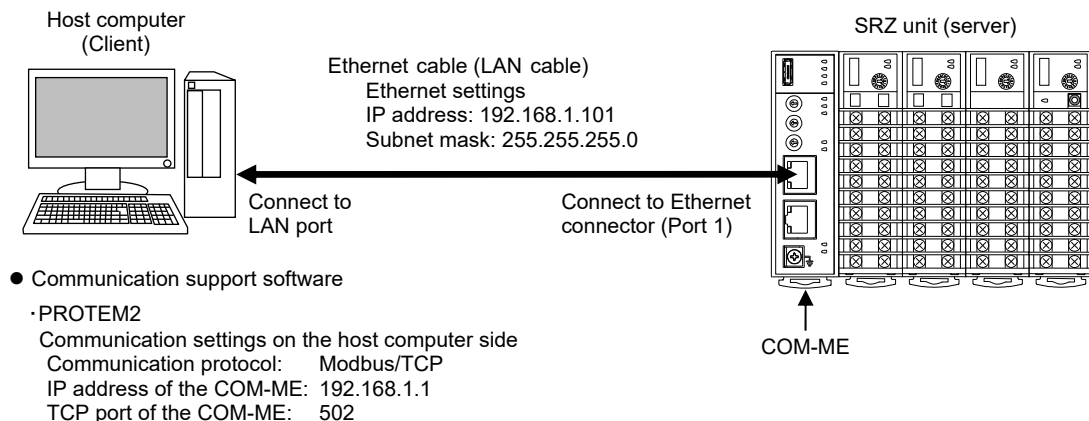


For the COM-KG, refer to **COM-KG Instruction Manual**.

10.5 Connection with Host Computer (Client)

Standard Ethernet cable (LAN cable) which is marketed can be used.

(Switching hub is not required for 100BASE-TX)



10.6 Setting of IP address and SRZ setting data

■ Turn on the power of the personal computer and SRZ unit

The COM-ME starts collecting data on function modules (Z-TIO, Z-DIO and Z-CT modules) jointed from the time when the power is turned on. Data collection takes about 10 seconds.

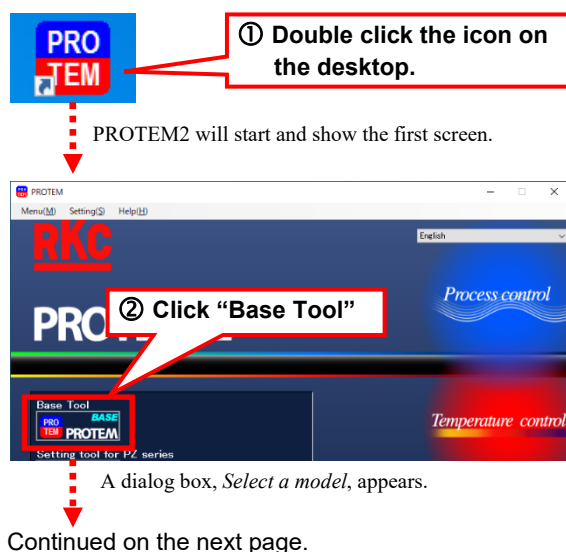
If you will use Loader communication to configure the COM-ME System data (setting items) and the communication data of the function modules (Z-TIO, Z-DIO and Z-CT modules), do so after data collection is finished.

■ Setting the IP address

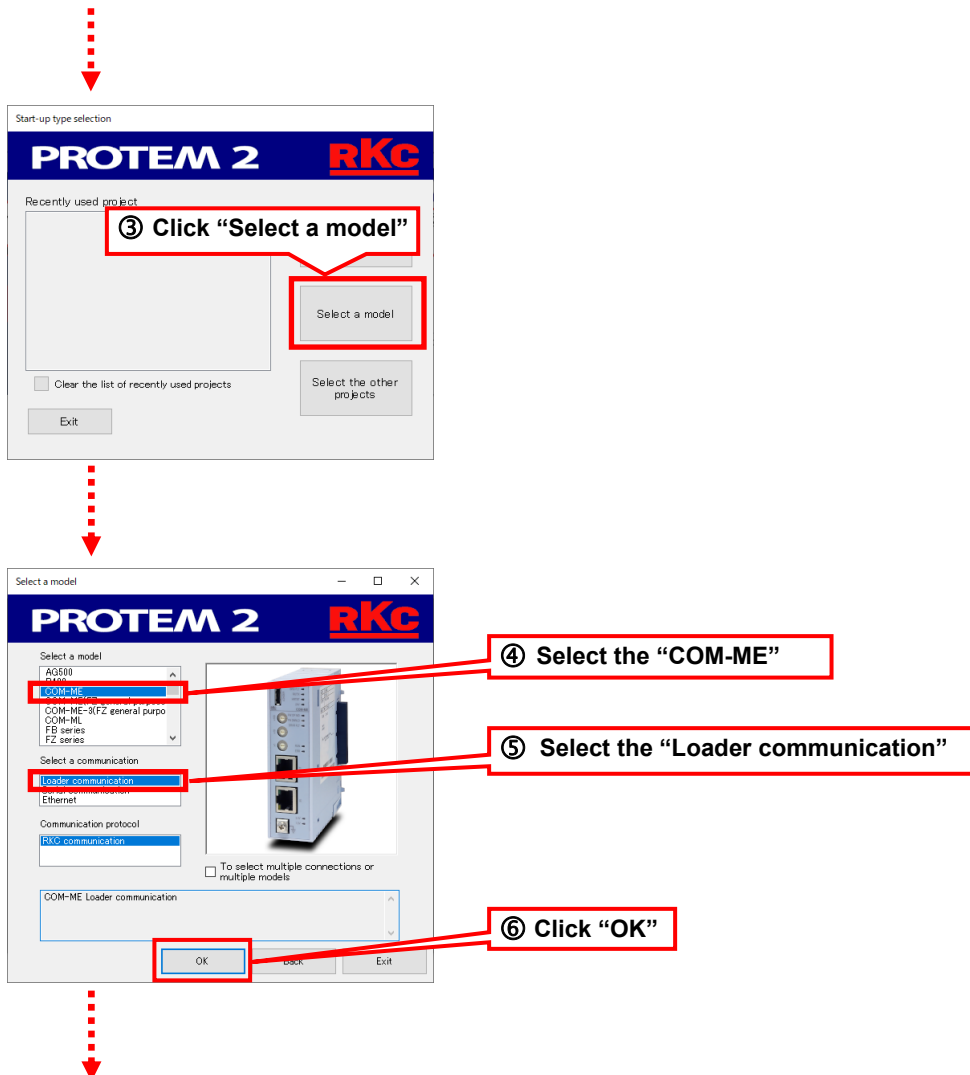
Use PROTEM2 to set the IP address of the COM-ME and the TCP port number.

1. Start PROTEM2, and set the communication port.

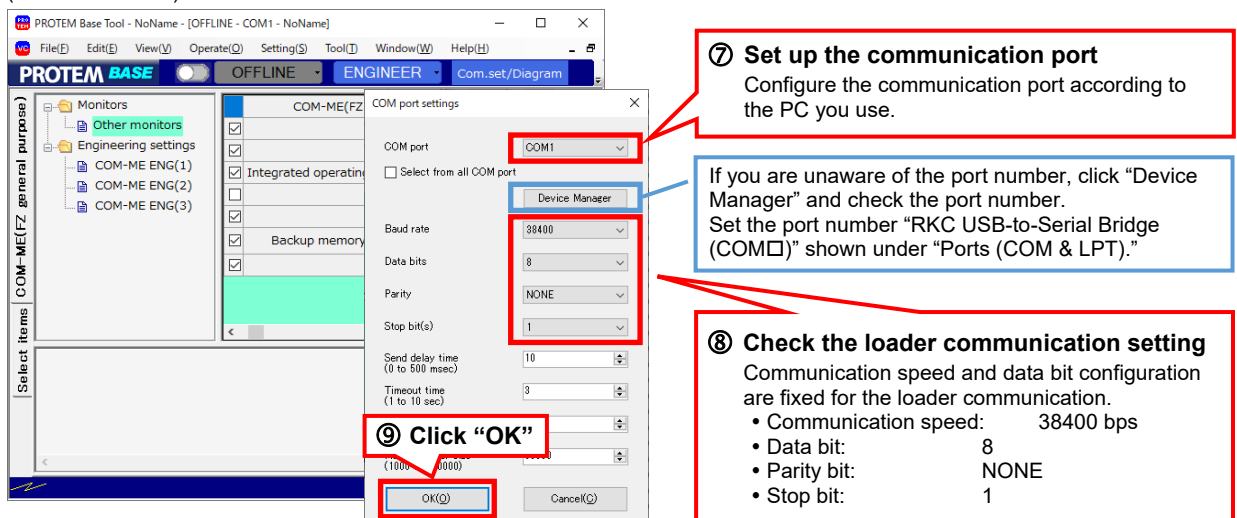
If you use the PROTEM 2 for the first time, you have to create a new project and set a communication port.



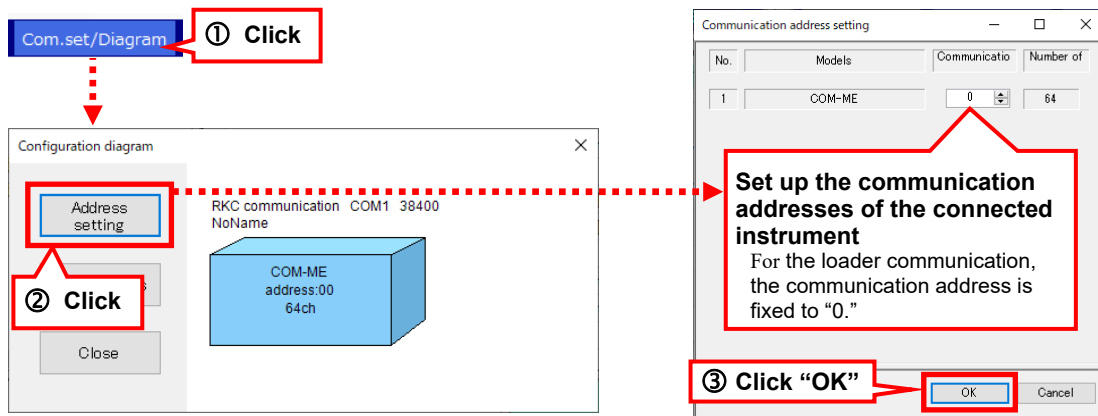
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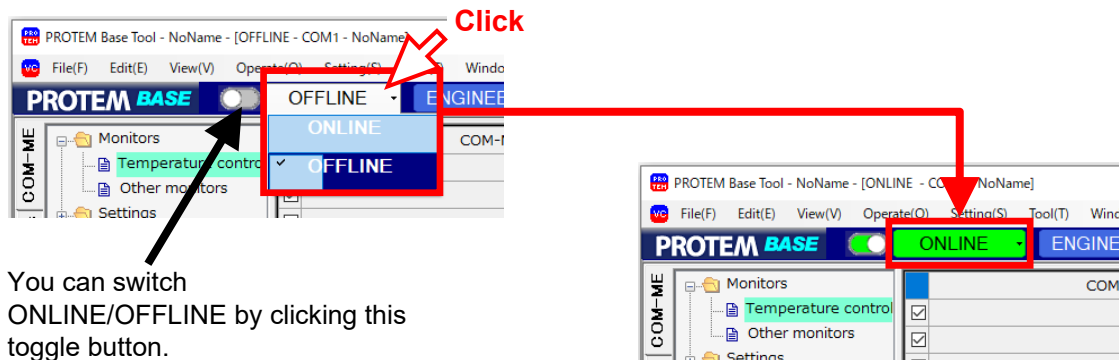
(Base tool screen)



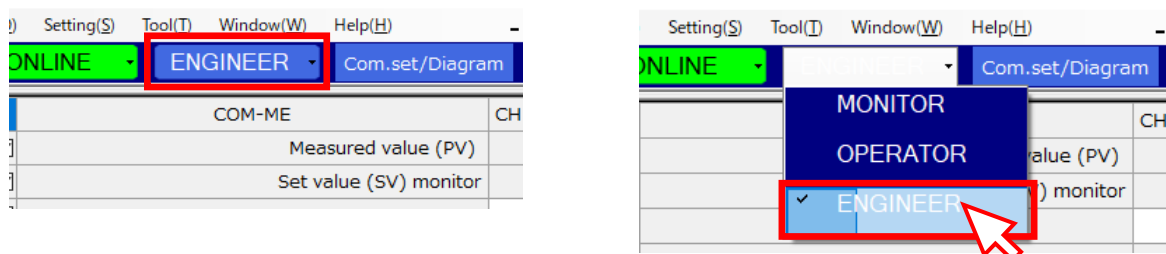
2. Click “Com.set/Diagram” and check the communication address.



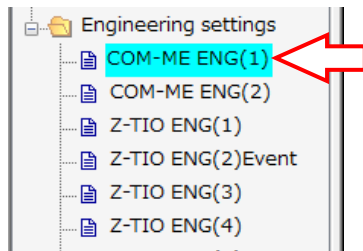
3. Switching to online
Click “OFFLINE” to select “ONLINE”



4. Make sure “ENGINEER” is displayed at the top bar. If any display other than ENGINEER (e.g. MONITOR, OPERATOR) appears, click the displayed part to select ENGINEER.



5. Select “COM-ME ENG(1)” under the “Engineering settings.”



6. Set the IP address and the TCP port number of the COM-ME.

	COM-ME	CH 1	
<input checked="" type="checkbox"/>	First-byte of IP address	192	} IP address of the COM-ME Example of IP address setting: 192.168.1.1 (Factory set value)
<input checked="" type="checkbox"/>	Second-byte of IP address	168	
<input checked="" type="checkbox"/>	Third-byte of IP address	1	
<input checked="" type="checkbox"/>	Fourth-byte of IP address	1	
<input checked="" type="checkbox"/>	TCP port number	502	← Setting example of “the TCP port number of the COM-ME”: 502
<input type="checkbox"/>			
<input checked="" type="checkbox"/>	First-byte of remote IP address	192	} IP address of the host computer (client) There is no need to change the remote IP address. Please use the factory set value as it is.
<input checked="" type="checkbox"/>	Second-byte of remote IP address	168	
<input checked="" type="checkbox"/>	Third-byte of remote IP address	1	
<input checked="" type="checkbox"/>	Fourth-byte of remote IP address	2	



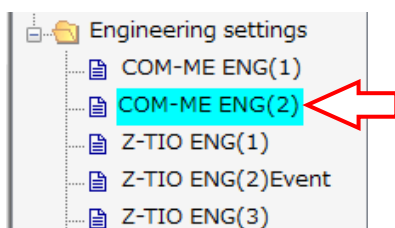
Local loop back address (127.0.0.1 to 127.255.255.254) is not available.



The instrument can be used with the factory preset values for the IP address and the TCP port number of the COM-ME. Change the setting according to the system configuration.

■ Confirm the Ethernet selection

1. Select “COM-ME ENG(2)” under the “Engineering settings.”



2. Confirm that the Ethernet selection is “0: Modbus/TCP.”

	COM-ME	CH 1
<input checked="" type="checkbox"/>	Ethernet selection	0
<input checked="" type="checkbox"/>	ASCII/Binary selection	1

■ Setting SRZ setting data by Loader communication

The communication data of function modules (Z-TIO, Z-DIO and Z-CT modules) can be set through the loader communication. (engineering data, operation data, etc.)

PROTEM2 activated to set “**■ Setting the IP address (P. 96)**” can be used without any changes.



NOTE

If the control is the control start (RUN), transfer to the control stop (STOP).

Engineering data can only be set in Z-TIO, Z-DIO and Z-CT modules when the SRZ unit is stopped.



For the data range of function modules (Z-TIO, Z-DIO and Z-CT modules), see **9. COMMUNICATION DATA LIST (P. 52)**.



For the function description of Z-TIO and Z-DIO modules communication data, refer to **SRZ Instruction Manual (IMS01T04-E□)**.

For the function description of Z-CT module communication data, refer to **Z-CT Instruction Manual [Detailed version] (IMS01T21-E□)**.

■ Turn off the power of the host computer and SRZ unit

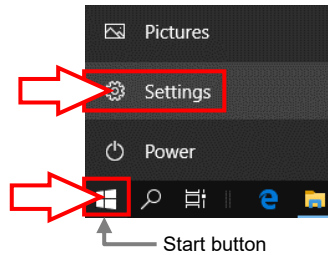
To make the newly configured system data (settings) take effect, turn off the power of the host computer and SRZ unit.

The settings will take effect the next time the power is turned on.

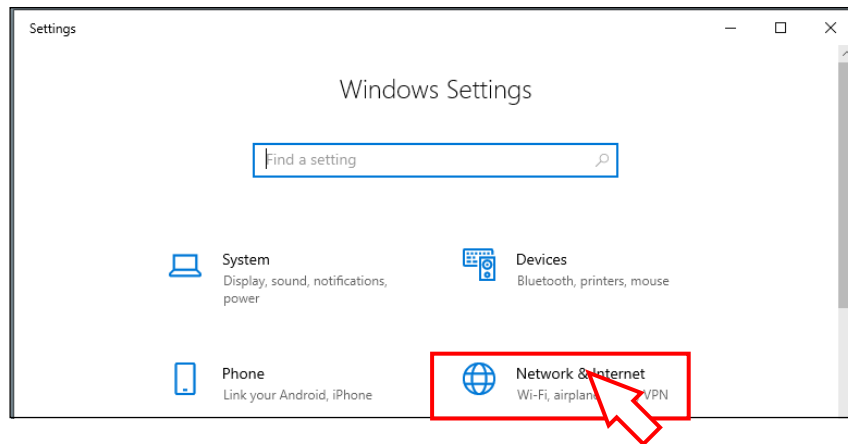
10.7 Ethernet Settings

Set the Ethernet IP address and subnet mask.

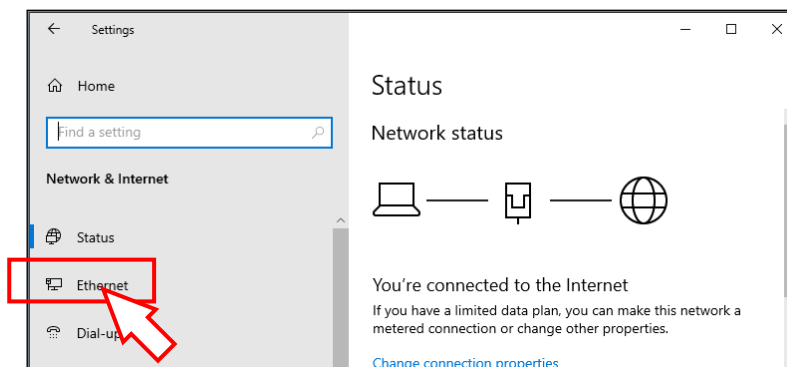
1. Click the Windows Start button and click “Settings” from the Start menu.



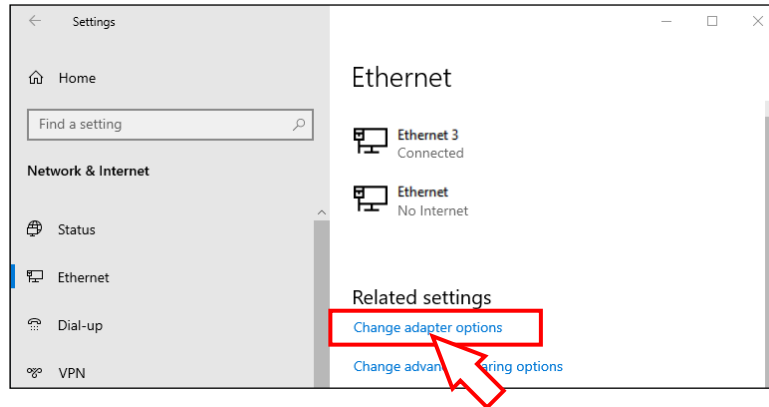
2. Click “Network & Internet” on the “Windows Settings” screen.



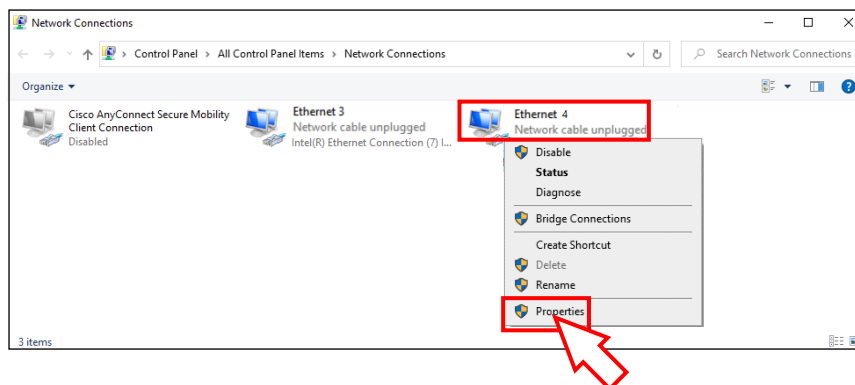
3. Click “Ethernet.”



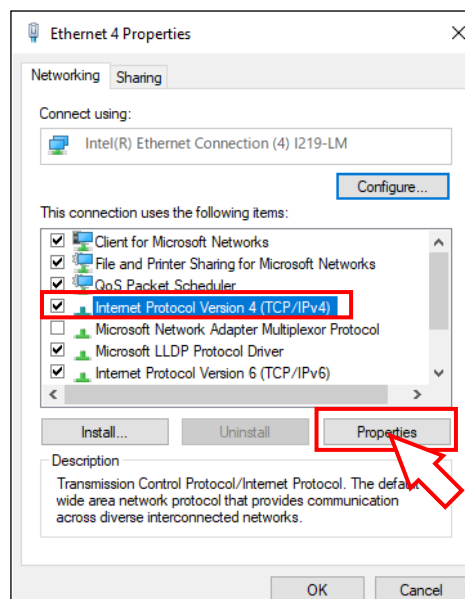
4. Click “Change adapter options.”



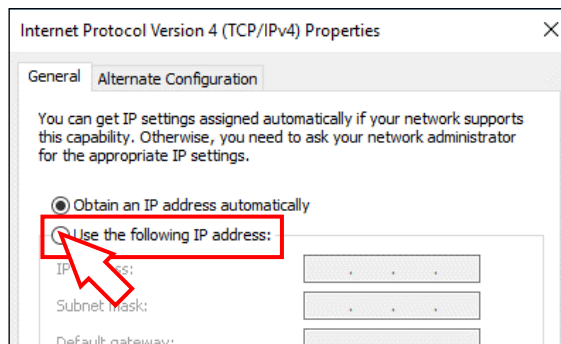
5. Right click the connection icon that shows the name of the adapter to be changed. Then, click “Properties.”



6. Make sure the “Internet Protocol Version 4 (TCP/IPv4)” is checked. Select “Internet Protocol Version 4 (TCP/IPv4)” and click “Properties.”



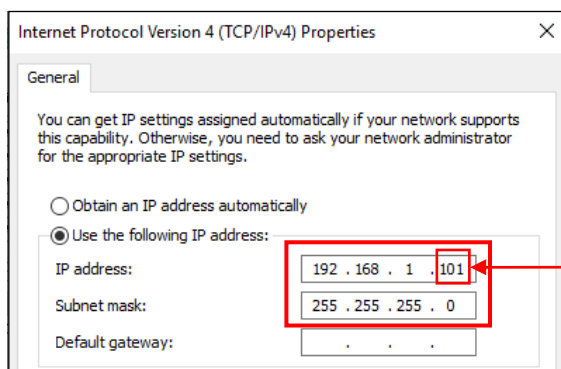
7. Click “Use the following IP address.”



8. Set the IP address and the Subnet mask as follows. Set the IP address to the one that is not overlapped with the IP address of the COM-ME.

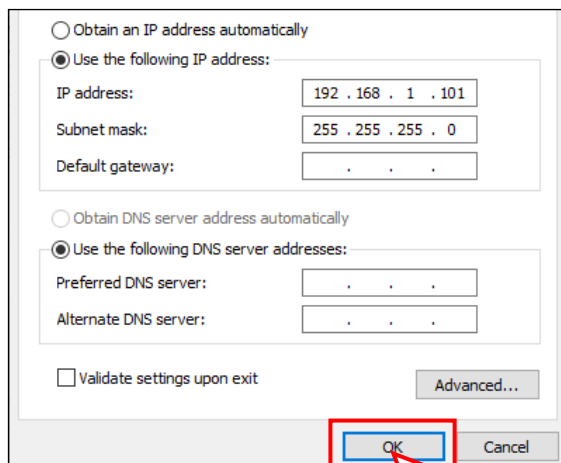
IP address: 192.168.1.101

Subnet mask: 255.255.255.0



Change the last numbers of the IP address (4th Octet) so that the IP address will not overlap the others.

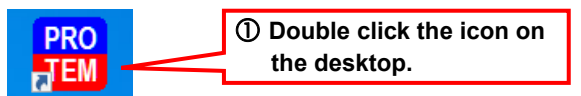
9. Click “OK” to complete the setting.



10.8 Host Computer (Client) Settings

Configure the communication setting of the PROTEM2 software installed on the host computer (client) to send/receive the data over Ethernet [Modbus/TCP].

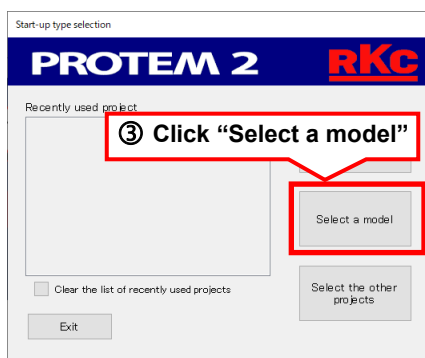
1. Turn on the host computer (client).
2. Start PROTEM2, and set the communication port.



PROTEM2 will start and show the first screen.



A dialog box, *Select a model*, appears.



Continued on the next page.

Continued from the previous page.

④ Select the "COM-ME"

⑤ Select the "Ethernet"

⑥ Click "OK"

⑦ Set the IP address of the COM-ME.

⑧ Set the TCP port number of the COM-ME.

⑨ Click "OK"

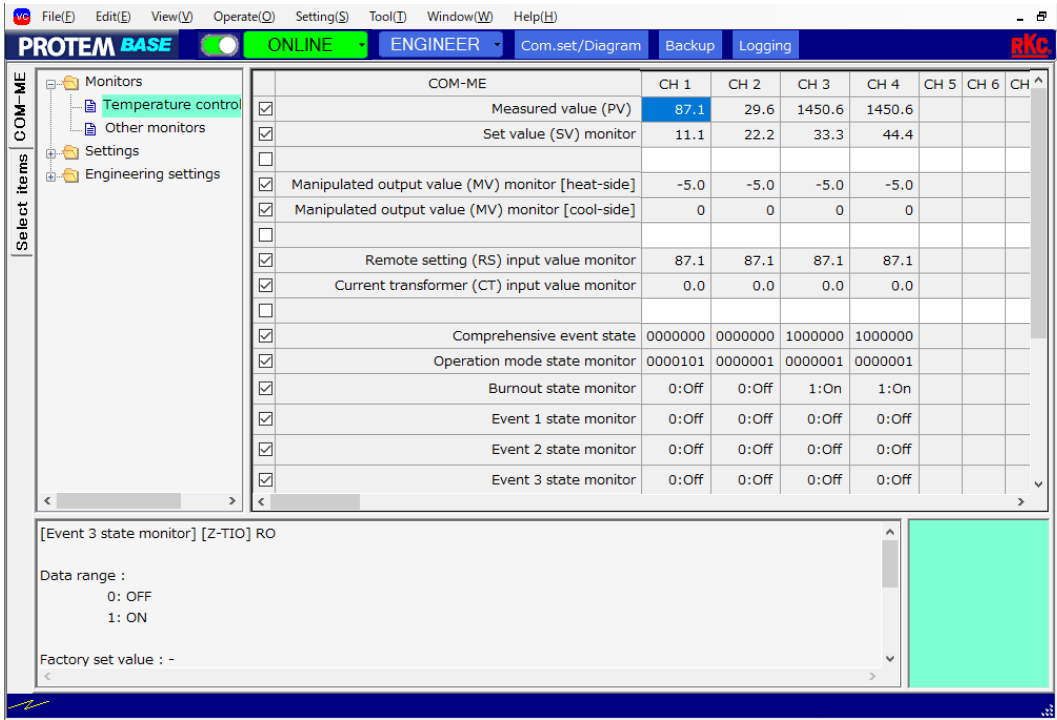
3. Switching to online.

Click "OFFLINE" to select "ONLINE"

Click

You can switch ONLINE/OFFLINE by clicking this toggle button.

4. Communication data of function modules will be displayed on the screen of PROTEM2 and the communication over Ethernet [Modbus/TCP] has been enabled.



11. TROUBLESHOOTING

This section explains possible causes and solutions if any abnormality occurs in the instrument. For any inquiries or to confirm the specifications of the product, please contact RKC sales office or the agent.

If the instrument needs to be replaced, always strictly observe the warnings below.

WARNING

- To prevent electric shock or instrument failure, always turn off the system power before replacing the instrument.
- To prevent electric shock or instrument failure, always turn off the power before mounting or removing the instrument.
- To prevent electric shock or instrument failure, do not turn on the power until all wiring is completed. Make sure that the wiring is correct before applying power to the instrument.
- To prevent electric shock or instrument failure, do not touch the inside of the instrument.
- All wiring must be performed by authorized personnel with electrical experience in this type of work.

CAUTION

All wiring must be completed before power is turned on to prevent electric shock, instrument failure, or incorrect action.

NOTE

When replacing the module with a new one, always use the module with the same model code. If the module is replaced, it is necessary to re-set each data item.

■ COM-ME

Problem	Possible cause	Solution
Any of the lamps for 24V, 3.4V, and 1.0V will not light.	Power not being supplied	Check external breaker etc.
	Appropriate power supply voltage not being supplied	Check the power supply
	Power supply terminal contact defect	Tighten the screw with a recommended tightening torque of 0.4 N·m (4 kgf·cm).
	Power supply section defect	Replace COM-ME
All indication lamps stay off even while the instrument is powered on or FAIL/RUN lamp turns red: Major fault occur	Power supply voltage monitoring error	Turn off the power to the instrument. If the same error occurs when the power is turned back on, please contact RKC sales office or the agent.
FAIL/RUN lamp turns red, and HRTBT lamp turns off: Major fault occur	Watchdog timer error	
FAIL/RUN lamp blinks green: Recoverable fault occur	Data backup error (Error code 2) EEPROM read/write error	
	Stack overflow (Error code 64) Runaway of the program, etc.	

■ Ethernet

Problem	Probable cause	Solution
No response	Wrong connection, no connection or disconnection of the communication cable	Confirm the connection method or condition and connect correctly
	Breakage, wrong wiring, or imperfect contact of the communication cable	Confirm the wiring or connector and repair or replace the wrong one
	Wrong IP address setting	Confirm the settings and set them correctly
LNK/ACT lamp: OFF	Link has not been established. Destination is not on Ethernet.	Confirm that the power supply is ON and the Ethernet cable is connected correctly. Then permit the connection of the destination device.

■ Modbus/TCP

Problem	Probable cause	Solution
No response	Wrong connection, no connection or disconnection of the communication cable	Confirm the connection method or condition and connect correctly
	Breakage, wrong wiring, or imperfect contact of the communication cable	Confirm the wiring or connector and repair or replace the wrong one
	Wrong IP address setting	Confirm the settings and set them correctly
	There is length of query message exceeds set range	
	The number of data points is not twice the specified number of data points at the time of data write	
Exception code: 01H	Illegal function code (An unsupported function code was specified)	Confirm the function code
Exception code: 02H	Illegal register address (When the mismatched register address is specified)	Confirm the address of holding register
Exception code: 03H	Illegal data value <ul style="list-style-type: none"> The number of specified data points was out of the following range during data read or write. Function code 03H: 1 to 125 Function code 10H: 1 to 123 When the data written exceeds the setting range 	Confirm the setting data

■ Host communication (RKC communication)

Problem	Probable cause	Solution
No response	Wrong connection, no connection or disconnection of the communication cable	Confirm the connection method or condition and connect correctly
	Breakage, wrong wiring, or imperfect contact of the communication cable	Confirm the wiring or connector and repair or replace the wrong one
	Mismatch of the setting data of Communication speed and Data bit configuration with those of the host computer	Confirm the settings and set them correctly
	Wrong address setting	
	Error in the data format	Reexamine the communication program
	Transmission line is not set to the receive state after data send	
EOT return	The specified identifier is invalid	Confirm the identifier is correct or that with the correct function is specified. Otherwise correct it
	Error in the data format	Reexamine the communication program
NAK return	Error occurs on the line (parity error, framing error, etc.)	Confirm the cause of error, and solve the problem appropriately. (Confirm the transmitting data, and resend data)
	BCC error	
	The data exceeds the setting range	Confirm the setting range and transmit correct data
	The specified identifier is invalid	Confirm the identifier is correct or that with the correct function is specified. Otherwise correct it

■ Host communication (Modbus)

Problem	Probable cause	Solution
No response	Wrong connection, no connection or disconnection of the communication cable	Confirm the connection method or condition and connect correctly
	Breakage, wrong wiring, or imperfect contact of the communication cable	Confirm the wiring or connector and repair or replace the wrong one
	Mismatch of the setting data of Communication speed and Data bit configuration with those of the host computer	Confirm the settings and set them correctly
	Wrong address setting	
	The length of query message exceeds set range	
	At the time of "Preset multiple registers (Write multiple registers)," the number of data (the number of requested byte) or "the requested number of data" does not match the actual number of the data.	Re-transmit after time-out occurs or verify communication program
	A transmission error (overrun error, framing error, parity error or CRC-16 error) is found in the query message	
	The time interval between adjacent data in the query message is too long, exceeding 24-bit time	
Error code 1	Function code error (Specifying nonexistent function code)	Confirm the function code
Error code 2	When the mismatched address (9000h to FFFFh) is specified	Confirm the address of holding register
Error code 3	<ul style="list-style-type: none"> When the specified number of data items in the query message exceeds the maximum number of data items available When the data written exceeds the setting range 	Confirm the setting data

12. SPECIFICATIONS

■ Ethernet communication

● Modbus/TCP

Physical layer:	10BASE-T/100BASE-TX automatic recognition
User layer:	Modbus/TCP
Communication data:	Conforms to the host communication (Modbus) map
Connector type:	RJ-45 (2 ports)
IP address:	0.0.0.0 to 255.255.255.255 The Local Loopback Address (127.0.0.1 to 127.255.255.254) cannot be used.
Subnet mast:	0.0.0.0 to 255.255.255.255

■ Host communication

Interface:	Based on EIA, RS-485 standard
Protocol:	<ul style="list-style-type: none">● RKC communication Based on ANSI X3.28-1976 subcategories 2.5 and B1 Polling/selecting type Error control: Vertical parity (with parity bit selected) Horizontal parity (BCC check) Data types: ASCII 7-bit code● Modbus Signal transmission mode: Remote Terminal Unit (RTU) mode Function codes: 03H Read holding registers 06H Preset single register 08H Diagnostics (loopback test) 10H Preset multiple registers Error check method: CRC-16 Error codes: 1: Function code error (An unsupported function code was specified) 2: When the mismatched address is specified. 3: ● When the specified number of data items in the query message exceeds the maximum number of data items available ● When the data written exceeds the setting range.
Synchronous method:	Start/Stop synchronous type
Connection method:	2-wire system, half-duplex multi-drop connection
Communication speed:	9600 bps, 19200 bps, 38400 bps, 57600 bps * * When the host communication is used at 57600 bps, set the communication speed of the connected function modules to “38400 bps” and the protocol to “Modbus.”

Data bit configuration: Start bit: 1
Data bit: 7 or 8 (Modbus: 8 fixed)
Parity bit: None, Odd or Even
Stop bit: 1

Interval time: 0 to 250 ms

Maximum connections: 31 modules (including function modules in the SRZ unit)

Connection method: Terminal block

Termination resistor: External connection is necessary (Example: 120 Ω , 1/2 W)

Maximum transmission distance:
Conforms to RS-485 (1.2 km max.)

■ Loader communication

Interface: Connection with a loader communication cable for our USB converter COM-KG or COM-K2 (sold separately).

Protocol: RKC communication (ANSI X3.28-1976 subcategories 2.5 and B1)

Synchronous method: Start/Stop synchronous type

Communication speed: 38400 bps

Data bit configuration: Start bit: 1
Data bit: 8
Parity bit: None
Stop bit: 1

Maximum connections: One module

■ Self-diagnostic function

● Major fault

Monitoring of the operation:

Error display:	All indication lamps stay off or FAIL/RUN lamp turns red
Error communication:	Communication stop
Recovery:	Power off the instrument once and power it on again.

Watchdog timer error:

Error display:	FAIL/RUN lamp turns red and HRTBT lamp turns off
Error communication:	Communication stop
Recovery:	Power off the instrument once and power it on again.

● Recoverable fault

Data back-up error:	Error display:	A green lamp (FAIL/RUN) blinks
	Error communication:	Error code 2
	Recovery:	Power off the instrument once, and power it on again.
Stack overflow:	Error display:	A green lamp (FAIL/RUN) blinks
	Error communication:	Error code 64
	Recovery:	Power off the instrument once, and power it on again.

■ General specifications

Power supply voltage:	21.6 to 26.4 V DC [Including power supply voltage variation] (Rating 24 V DC)
Power consumption (at maximum load):	150 mA max. (at 24 V DC)
Rush current:	15 A or less
Insulation resistance:	See table shown below

	①	②	③
① Grounding terminal			
② Power supply terminal, Host communication	20 MΩ or more at 500 V DC		
③ Network communication	20 MΩ or more at 500 V DC	20 MΩ or more at 500 V DC	
④ Loader communication	20 MΩ or more at 500 V DC	20 MΩ or more at 500 V DC	20 MΩ or more at 500 V DC

Withstand voltage:	See table shown below
---------------------------	-----------------------

Time: 1 min.	①	②	③
① Grounding terminal			
② Power supply terminal, Host communication	750 V AC		
③ Network communication	750 V AC	750 V AC	
④ Loader communication	750 V AC	750 V AC	750 V AC

Power failure:	A power failure of 4 ms or less will not affect the control action.
Memory backup:	Backed up by non-volatile memory
	Number of writing: Approx. 1,000,000 times
	Data storage period: Approx. 10 years
Vibration:	Frequency range: 10 to 150 Hz
	Amplitude: < 0.075 mm
	Acceleration: < 9.8 m/s ²
	Each direction of XYZ axes
Shock:	Free fall: Height 50 mm or less
	Each direction of XYZ axes (de-energized state)

Allowable ambient temperature:

-10 to +55 °C

Allowable ambient humidity: 5 to 95 %RH(Absolute humidity: MAX.W.C 29 g/m³ dry air at 101.3 kPa)**Operating environment:**

Avoid the following conditions when selecting the mounting location.

- Rapid changes in ambient temperature which may cause condensation.
- Corrosive or inflammable gases.
- Water, oil, chemicals, vapor or steam splashes.
- Direct air flow from an air conditioner.
- Exposure to direct sunlight.
- Excessive heat accumulation.

Weight:

Approx. 150 g

Dimensions:

30.0 × 100.0 × 76.9 mm (W×H×D) (Not including protruding parts)

■ Standard**Safety standards:**

UL: UL 61010-1

cUL: CAN/CSA-C22.2 No.61010-1

CE/UKCA marking:

EMC: EN61326-1

RoHS: EN IEC 63000

RCM:

EN55011

Environment conditions:

POLLUTION DEGREE 2

Altitude up to 2000 m (Indoor use)

APPENDIX.

HOST COMMUNICATION PROTOCOL

A.1 Communication Requirements

■ Processing times during data send/receive

When the host computer is using either the polling or selecting procedure for communication, the following processing times are required for SRZ unit to send data:

- Response wait time after SRZ unit sends BCC in polling procedure
- Response wait time after SRZ unit sends ACK or NAK in selecting procedure

RKC communication (Polling procedure)

Procedure details	Time
Response send time after controller receives ENQ	60 ms max.
Response send time after controller receives ACK	60 ms max.
Response send time after controller receives NAK	60 ms max.
Response send time after controller sends BCC	2 ms max.

RKC communication (Selecting procedure)

Procedure details	Time
Response send time after controller receives BCC	60 ms max. ^{1, 2}
Response wait time after controller sends ACK	2 ms max.
Response wait time after controller sends NAK	2 ms max.

Modbus

Procedure details	Time
Read holding registers [03H] Response send time after the slave receives the query message	60 ms max.
Preset single register [06H] Response send time after the slave receives the query message	100 ms max.
Diagnostics (loopback test) [08H] Response send time after the slave receives the query message	30 ms max.
Preset multiple registers [10H] Response send time after the slave receives the query message	100 ms max. ²

¹ When selecting is performed for 128 or more channels on a Z-CT module, the maximum time is 90 ms.

² In the case of RKC communication (selecting procedure), the time will be “the time after BCC reception until an acknowledgment [ACK] is sent.”

- When successive changes are made to the setting of the same item
[Example] Successive changes to a Set value (SV), control by manual manipulated output value, etc.
- When successive changes are made to multiple items
[Example] Configuring initial settings

Processing times (Varies with the function module types.)

Function module (When connected maximum connection number)	Time
Setting items of the Z-TIO module	750 ms max.
Setting items of the Z-DIO module	2000 ms max.
Setting items of the Z-CT module	5000 ms max.

■ Caution for selecting

When selecting of the following communication data of a Z-TIO module is performed, the next selecting procedure for the changed Z-TIO module will not be possible for 4 to 6 seconds.

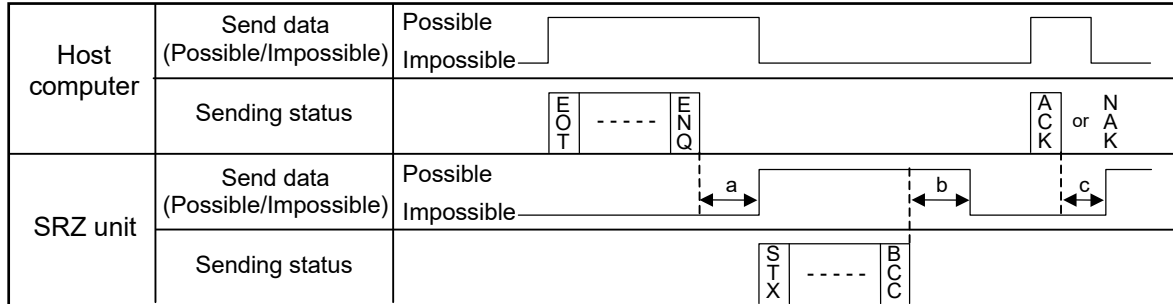
For this reason, when there are many channels to be changed, do not perform selecting for each channel individually; perform selecting for all channels at once. Note that if the communication data exceeds 136 bytes, the data will be separated into blocks by ETB.

- Input type
- Display unit
- Decimal point position
- Integral/Derivative time decimal point position

■ RS-485 (2-wire system) send/receive timing

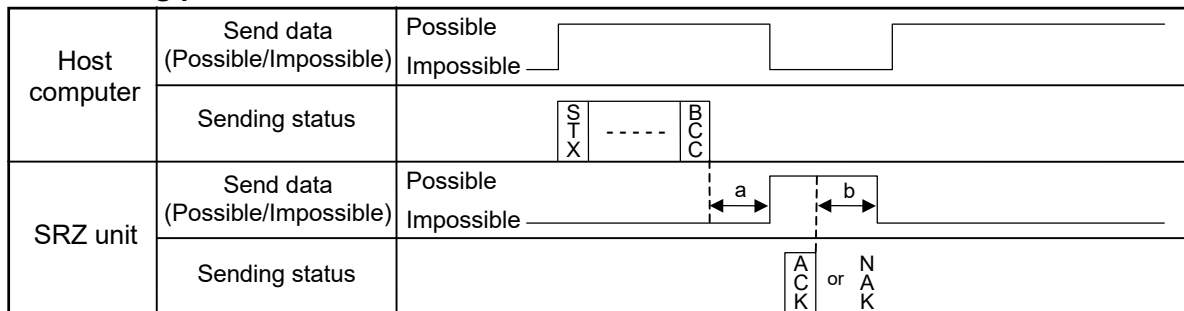
RS-485 communication is conducted through two wires, therefore the transmission and reception of data requires precise timing.

● Polling procedure



- a: Response send time after the controller receives [ENQ] + Interval time
b: Response send time after the controller sends BCC
c: Response send time after the controller receives [ACK] + Interval time or
Response send time after the controller receives [NAK] + Interval time

● Selecting procedure



- a: Response send time after the controller receives BCC + Interval time
b: Response wait time after the controller sends ACK or Response wait time after the controller sends NAK



To switch the host computer from transmission to reception, send data must be on line.



The following processing times are required for the SRZ unit to process data.

- In Polling procedure, Response wait time after the SRZ unit sends BCC
- In Selecting procedure, Response wait time after the SRZ unit sends ACK or NAK

■ Fail-safe

A transmission error may occur with the transmission line disconnected, shorted or set to the high-impedance state. In order to prevent the above error, it is recommended that the fail-safe function be provided on the receiver side of the host computer. The fail-safe function can prevent a framing error from its occurrence by making the receiver output stable to the MARK (1) when the transmission line is in the high-impedance state.

A.2 RKC Communication Protocol

RKC communication uses the Polling/Selecting method to establish a data link. The basic procedure is followed ANSI X3.28-1976 subcategories 2.5 and B1 basic mode data transmission control procedure (Fast selecting is the selecting method used in SRZ unit).

- The Polling/Selecting procedures are a centralized control method where the host computer controls the entire process. The host computer initiates all communication so the SRZ unit responds according to queries and commands from the host.
- The code use in communication is 7-bit ASCII code including transmission control characters.

Transmission control characters used in SRZ unit:

EOT (04H), ENQ (05H), ACK (06H), NAK (15H), STX (02H), ETB (17H), ETX (03H)

(): Hexadecimal



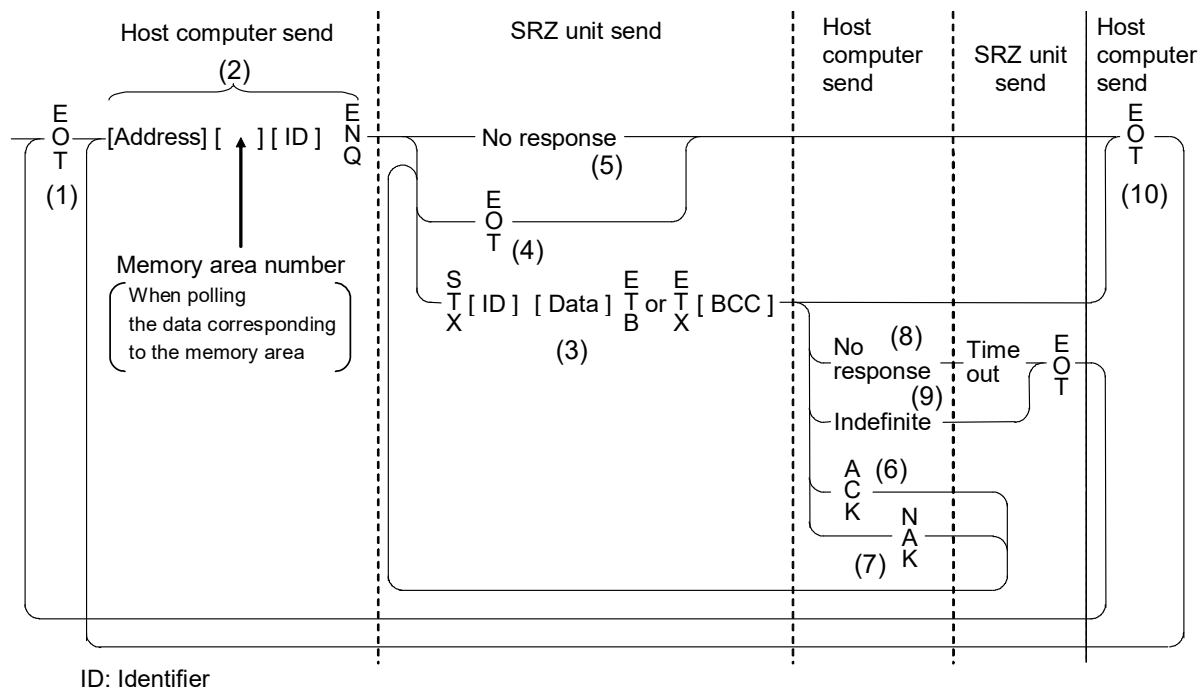
Data send/receive state (communication data monitoring and setting) of RKC communication can be checked by using the following software:

Communication Tool “PROTEM2”

The software can be downloaded from the official RKC website.

A.2.1 Polling procedures

Polling is the action where the host computer requests one of the connected SRZ units to transmit data. An example of the polling procedure is shown below:



(1) Data link initialization

Host computer sends EOT to the controllers to initiate data link before polling sequence.

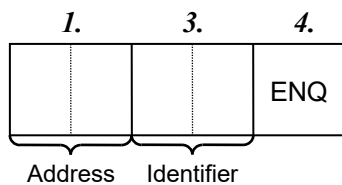
(2) Data sent from host computer - Polling sequence

The host computer sends the polling sequence in the following two types of formats:

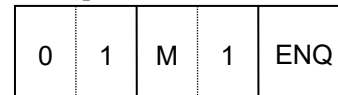
- Format in which no memory area number is specified, and
- Format in which the memory area number is specified.

- When no memory area number is specified

To be sent in this format for any identifier not corresponding to the memory area.

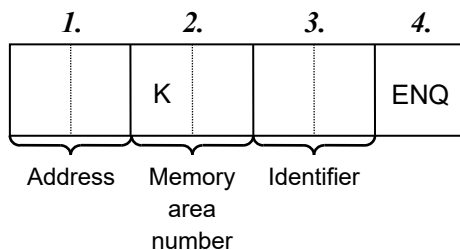


Example:

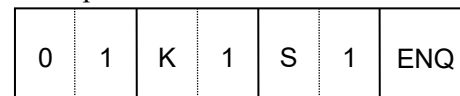


- When the memory area number is specified

To be sent in this format for any identifier corresponding to the memory area.



Example:



1. Address (2 digits)

This data is a host communication address of the COM-ME for polled and must be the same as the unit address set value in item **5.1 Address Setting of COM-ME (P. 21)**.



The polling address which transmitted a message once becomes effective so long as data link is not initialized by transmit and receive of EOT.

2. Memory area number (2 digits)

This is the identifier to specify the memory area number. It is expressed by “K1” to “K8” to each memory area number (from 1 to 8). If the memory area number is assigned with “K0,” this represents that control area is specified.



The memory area now used for control is called “Control area.”



If the memory area number is not specified when polling the identifier corresponding to the memory area, this represents that the control area is specified.



If any identifier not corresponding to the memory area is assigned with a memory area number, this memory area number is ignored.

3. Identifier (2 digits)

The identifier specifies the type of data that is requested from the SRZ unit. Always attach the ENQ code to the end of the identifier.

 See 9. COMMUNICATION DATA LIST (P. 52).

4. ENQ

The ENQ is the transmission control character that indicates the end of the polling sequence. The host computer then must wait for a response from the SRZ unit.

(3) Data sent from the SRZ unit

If the polling sequence is received correctly, the SRZ unit sends data in the following format:

1.	2.	3.	4.	6.
STX	Identifier	Data	ETB	BCC

or

1.	2.	3.	5.	6.
STX	Identifier	Data	ETX	BCC

 If the length of send data (from STX to BCC) exceeds 128 bytes, it is divided into blocks by ETB. In this case, the succeeding divided data is sent after STX.

1. STX

STX is the transmission control character which indicates the start of the text transmission (identifier and data).

2. Identifier (2 digits)

The identifier indicates the type of data (measured value, status and set value) sent to the host computer.

 See 9. COMMUNICATION DATA LIST (P. 52).

3. Data

Data which is indicated by an identifier of SRZ unit, consisting of channel numbers, data, etc. Each channel number and data are delimited by a space (20H). The data and the next channel number are delimited by a comma (2CH).

- Channel number: 3-digit ASCII code, not zero-suppressed. Channels without channel numbers may exist depending on the type of identifier.
- Data: ASCII code, zero-suppressed with spaces (20H). The number of digits varies depending on the type of identifier.



Memory area soak time monitor and area soak time become the following data:

- When data range is 0 hour 00 minute to 99 hours 59 minutes:
Data range is 0:00 to 99:59, punctuation of time unit is expressed in colon “: (3AH).”
- When data range is 0 minute 00 second to 199 minutes 59 seconds:
Data range is 0:00 to 199:59, punctuation of time unit is expressed in colon “: (3AH).”



“0” (without a decimal point) is sent for unused channels and for data that is invalid due to the function selection.

4. ETB

Transmission control character indicating the end of the block.

5. ETX

Transmission control character indicating the end of the text.

6. BCC

BCC (Block Check Character) detects error by using horizontal parity (even number).

Calculation method of BCC: *Exclusive OR* all data and characters from STX through ETB or ETX, not including STX.

Example:

STX	M	1	0	1			1	5	0	.	0	ETX	BCC
-----	---	---	---	---	--	--	---	---	---	---	---	-----	-----

4DH 31H 30H 31H 20H 20H 31H 35H 30H 2EH 30H 03H

Hexadecimal numbers

$$\text{BCC} = 4\text{DH} \oplus 31\text{H} \oplus 30\text{H} \oplus 31\text{H} \oplus 20\text{H} \oplus 20\text{H} \oplus 31\text{H} \oplus 35\text{H} \oplus 30\text{H} \oplus 2\text{EH} \oplus 30\text{H} \oplus 03\text{H} = 54\text{H}$$

(\oplus : *Exclusive OR*)

Value of BCC becomes 54H

(4) EOT send (Ending data transmission from the SRZ unit)

In the following cases, the SRZ unit sends EOT to terminate the data link:

- When the specified identifier is invalid
- When there is an error in the data format
- When all the data has been sent
- When the module that relates to the identifier is not connected

(5) No response from the SRZ unit

The SRZ unit will not respond if the polling address is not received correctly. It may be necessary for the host computer to take corrective action such as a time-out.

(6) ACK (Acknowledgment)

An acknowledgment ACK is sent by the host computer when data received is correct. When the SRZ unit receives ACK from the host computer, the SRZ unit will send any remaining data of the next identifier* without additional action from the host computer. When host computer determines to terminate the data link, EOT is sent from the host computer.

- When ACK is received after ETX and BCC are sent, the next identifier data is sent according to the order of the communication data list.
- When ACK is received after ETB and BCC are sent, the data after ETB is sent.

* The data is sent in the following sequence.

1. Communication Data of COM-ME No. 1 to 20
2. Communication Data of Z-TIO Module
3. Communication Data of Z-DIO Module
4. Communication Data of Z-CT Module
5. Communication Data of COM-ME No. 21 to 51

(7) NAK (Negative acknowledge)

If the host computer does not receive correct data from the SRZ unit, it sends a negative acknowledgment NAK to the SRZ unit. The SRZ unit will re-send the same data when NAK is received. This cycle will go on continuously until either recovery is achieved or the data link is corrected at the host computer.

The format of the data that an SRZ unit re-sends is as follows.

STX	Identifier	Data	ETB or ETX	BCC
-----	------------	------	------------------	-----

(8) No response from host computer

When the host computer does not respond within approximately three seconds after the SRZ unit sends data, the SRZ unit sends EOT to terminate the data link (time-out time: about 3 seconds).

(9) Indefinite response from host computer

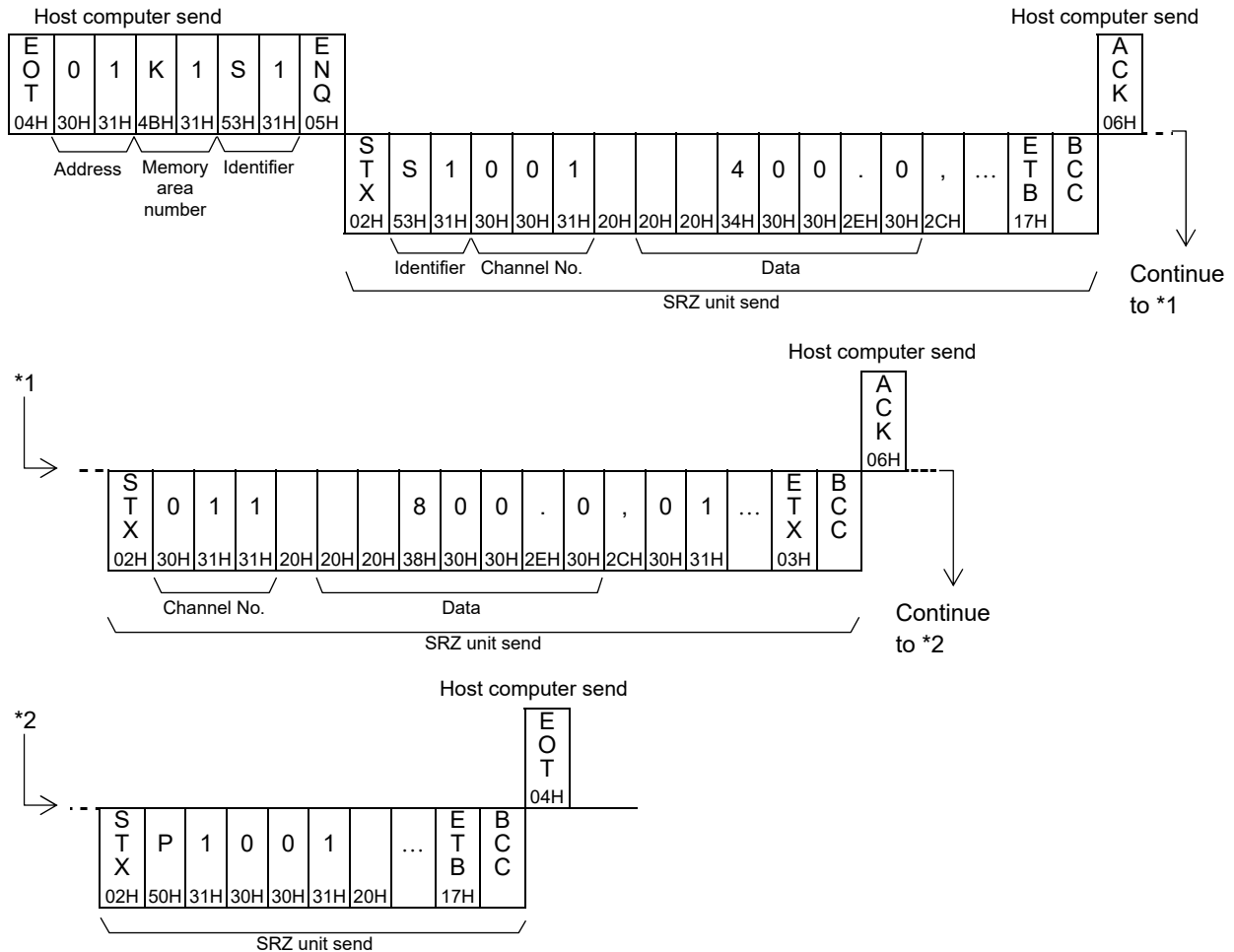
The SRZ unit sends EOT to terminate the data link when the host computer response is indefinite.

(10) EOT (Data link termination)

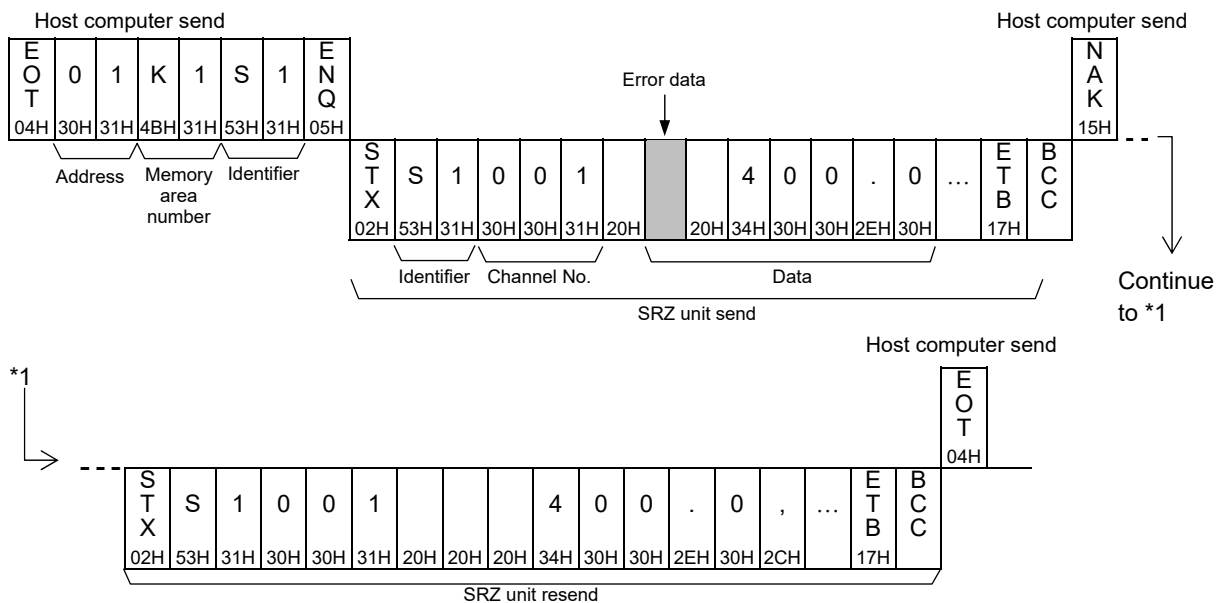
The host computer sends EOT message when it is necessary to suspend communication with the SRZ unit or to terminate the data link due lack of response from the SRZ unit.

■ Polling procedure example (When the host computer requests data)

● Normal transmission

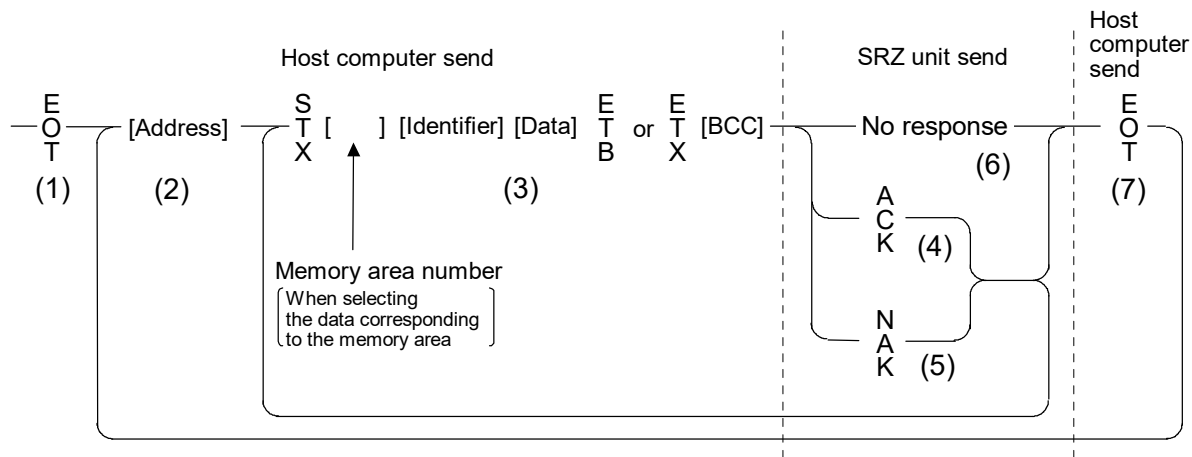


● Error transmission



A.2.2 Selecting procedures

Selecting is the action where the host computer requests one of the connected SRZ units to receive data. An example of the selecting procedure is shown below:




(1) Data link initialization

Host computer sends EOT to the SRZ unit to initiate data link before selecting sequence.

(2) Sending selecting address from the host computer

Host computer sends selecting address for the selecting sequence.

Address (2 digits):
This data is a host communication address of the COM-ME to be selected and must be the same as the unit address set value in item **5.1 Address Setting of COM-ME (P. 21)**.

 As long as the data link is not initialized by sending or receiving EOT, the selecting address once sent becomes valid.

(3) Data sent from the host computer

The host computer sends data for the selecting sequence with the following format:

- When no memory area number is specified

STX	Identifier	Data	ETB	BCC
-----	------------	------	-----	-----

or

STX	Identifier	Data	ETX	BCC
-----	------------	------	-----	-----

- When the memory area number is specified

STX	Memory area number	Identifier	Data	ETB	BCC
-----	--------------------	------------	------	-----	-----

or

STX	Memory area number	Identifier	Data	ETX	BCC
-----	--------------------	------------	------	-----	-----



For the STX, Memory area number Identifier, Data, ETB, ETX and BCC, see **A.2.1 Polling procedures (P. 118)**.



If the length of send data (from STX to BCC) exceeds 128 bytes, it is divided into blocks by ETB. In this case, the succeeding divided data is sent after STX.



Area soak time set data as the following:

- When data range is 0 hour 00 minute to 99 hours 59 minutes:
Data range is 0:00 to 99:59, punctuation of time unit is expressed in colon “:” (3AH).”
- When data range is 0 hour 00 minute to 99 hours 59 minutes:
Data range is 0:00 to 99:59, punctuation of time unit is expressed in colon “:” (3AH).”

In addition to above, when minute and second data are set in more than 60, become as the following:

Example: 1:65 (1 hour 65 minutes) → 2:05 (2 hours 05 minutes)
0:65 (0 minute 65 seconds) → 1:05 (1 minute 05 seconds)

● About numerical data

[The data that receipt of letter is possible]

- Data with numbers below the decimal point omitted or zero-suppressed data can be received.

(Number of digits: Within 7 digits)

<Example>

When data send with -001.5, -01.5, -1.5, -1.50, -1.500 at the time of -1.5, SRZ unit can receive a data.

- When the host computer sends data with decimal point to item of without decimal point, the SRZ unit receives a message with the value that cut off below the decimal point.

<Example>

When setting range is 0 to 200, the SRZ unit receives as follows.

Send data	0.5	100.5
Receive data	0	100

- The SRZ unit receives value in accordance with decided place after the decimal point. The value below the decided place after the decimal point is cut off.

<Example>

When setting range is -10.00 to +10.00, the controller receives as a following.

Send data	-.5	-.058	.05	-0
Receive data	-0.50	-0.05	0.05	0.00



If the host computer sends “decimal point only (.)” or “minus sign and decimal point only (-.),” the SRZ unit receives this as “0.” However, the decimal point position will be the same as the decimal point position of the transmitted data item.

[The data that receipt of letter is impossible]

The SRZ unit sends NAK when received a following data.

+	Plus sign and the data that gained plus sing
-	Only minus sign (there is no figure)

(4) ACK (Acknowledgment)

An acknowledgment ACK is sent by the SRZ unit when data received is correct. When the host computer receives ACK from the SRZ unit, the host computer will send any remaining data. If there is no more data to be sent to the SRZ unit, the host computer sends EOT to terminate the data link.

(5) NAK (Negative acknowledge)

If the SRZ unit does not receive correct data from the host computer, it sends a negative acknowledgment NAK to the host computer. Corrections, such as re-send, must be made at the host computer.

The send conditions of NAK (after reception of ETX or BCC)

- When an error occurs on communication the line (parity error, framing error, etc.)
- When a BCC check error occurs
- When the specified identifier is invalid
- When receive data exceeds the setting range
- When receive data is the identifier of RO (read only)
- When the module related to the identifier received by the SRZ is not connected

The send conditions of NAK (after reception of ETB or BCC)

- When a BCC check error occurs

(6) No response from SRZ unit

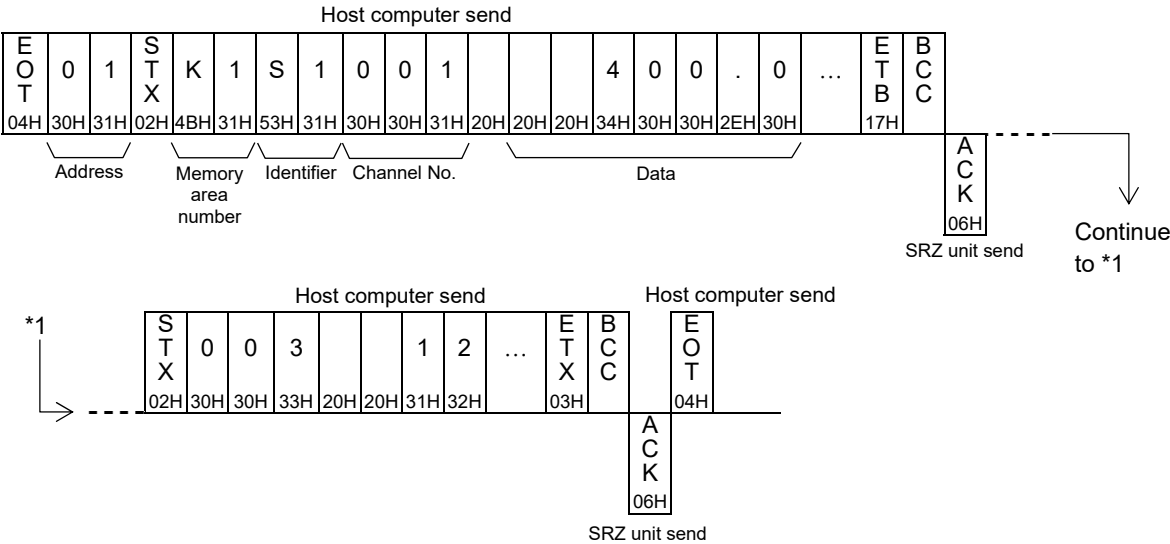
The SRZ unit does not respond when it cannot receive the selecting address, STX, ETB, ETX or BCC.

(7) EOT (Data link termination)

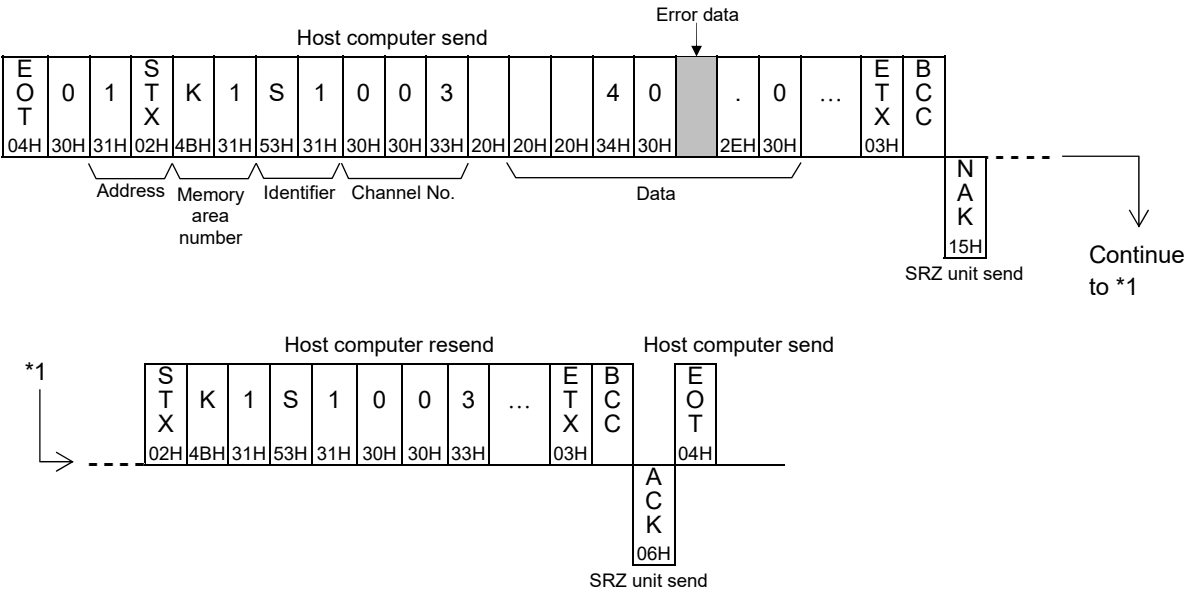
The host computer sends EOT when there is no more data to be sent from the host computer or there is no response from the SRZ unit.

■ Selecting procedure example (when the host computer sends data)

● Normal transmission

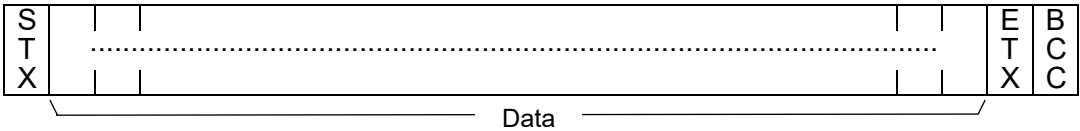


● Error transmission



A.2.3 Communication data structure

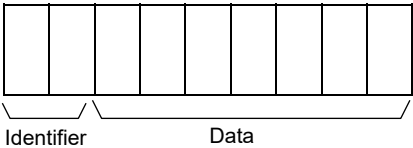
■ Data description



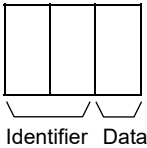
Part of the data above is shown below.

● Data for each unit (Without channel)

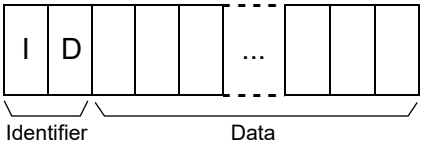
Data length 7 digits



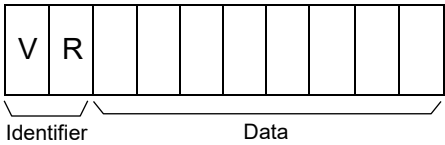
Data length 1 digit



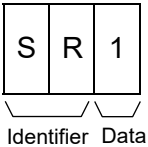
Data length 32 digits (Model code)



Data length 8 digits (ROM version)

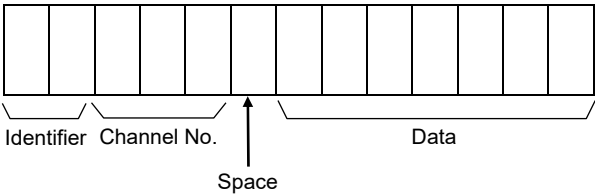


Example) Data structure for control RUN/STOP switching in each SRZ unit

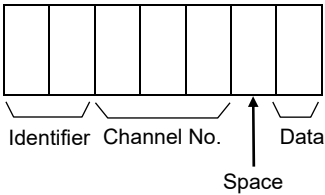


● Data for each module

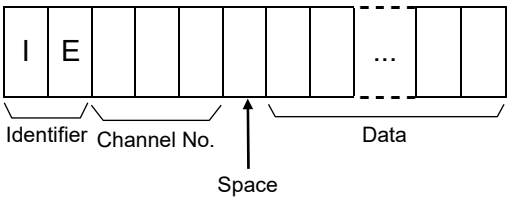
Data length 7 digits



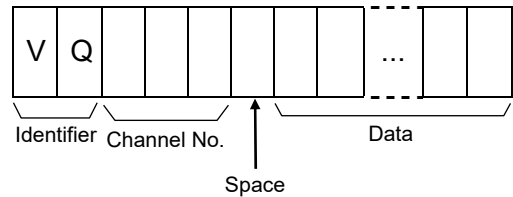
Data length 1 digit



Data length 32 digits (Model code)

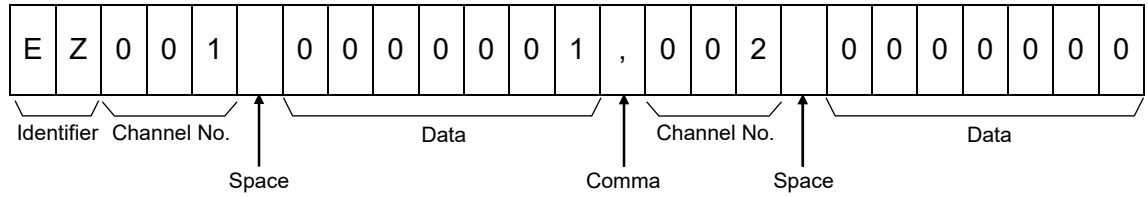


Data length 8 digits (ROM version)



Continued on the next page.

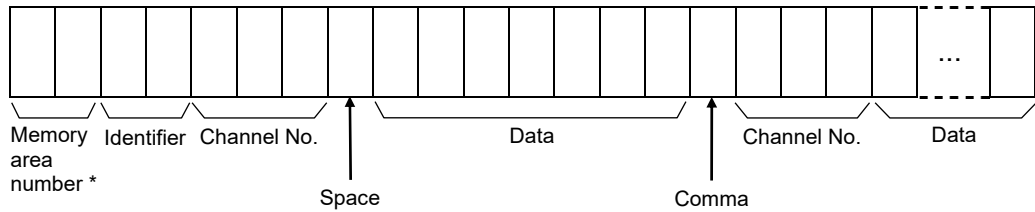
Example) Data structure of error codes of Z-TIO, Z-DIO and Z-CT modules



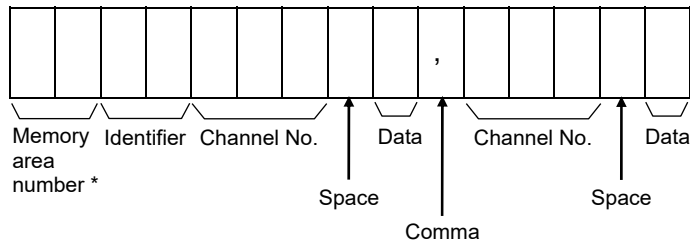
For the calculation method of the channel number, see **6.3 Temperature Control Channel of the SRZ unit (P. 25)**, **6.4 Digital Input/Output Channel of Z-DIO Module (P. 26)** and **6.5 Current Transformer (CT) Input Channel of Z-CT Module (P. 27)**.

● Data for each channel

Data length 7 digits

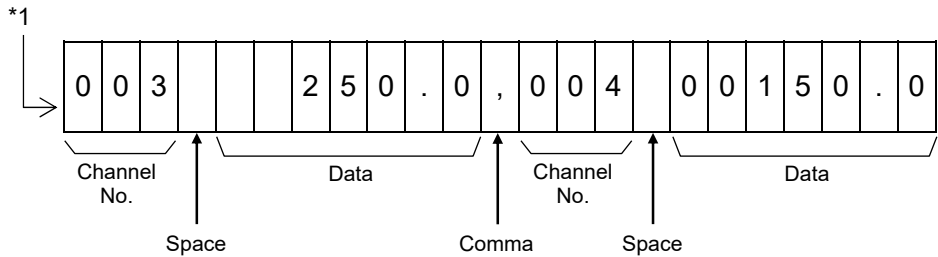
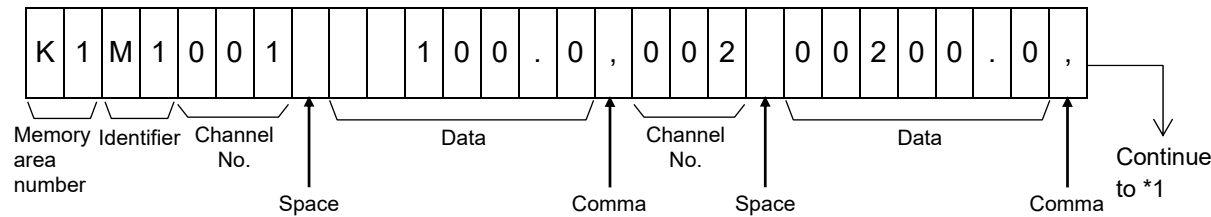


Data length 1 digit



* To select data corresponding to a memory area, specify the number of the appropriate memory area.
If a memory area number is specified for data that does not correspond to a memory area, the specification will be invalid.

Example) Data configuration of measured value (PV) of Z-TIO module



For the calculation method of the channel number, see **6.3 Temperature Control Channel of the SRZ unit (P. 25)**, **6.4 Digital Input/Output Channel of Z-DIO Module (P. 26)** and **6.5 Current Transformer (CT) Input Channel of Z-CT Module (P. 27)**.

A.3 Modbus Protocol

The master controls communication between master and slave. A typical message consists of a request (query message) sent from the master followed by an answer (response message) from the slave (SRZ unit). When master begins data transmission, a set of data is sent to the slave in a fixed sequence. When it is received, the slave decodes it, takes the necessary action, and returns data to the master.



Data send/receive state (communication data monitoring and setting) of Modbus can be checked by using the following software:

Communication Tool “PROTEM2”

The software can be downloaded from the official RKC website.

A.3.1 Message format

The message consists of four parts: slave address, function code, data, and error check code which are always transmitted in the same sequence.

Slave address
Function code
Data
Error check (CRC-16)

Message format

■ Slave address

The slave address is a number from 0 to F manually set at the address setting switch located at the front of COM-ME.



For details, see **5.1 Address Setting of COM-ME (P. 21)**.

Although all connected slave units receive the query message sent from the master, only the slave with the slave address coinciding with the query message will accept the message.

■ Function code

The function codes are the instructions set at the master and sent to the slave describing the action to be executed. The function codes are included when the slave responds to the master.



For details, see **A.3.2 Function code (P. 132)**.

■ Data

The data to execute the function specified by the function code is sent to the slave and corresponding data returned to the master from the slave.



For details, see **A.3.6 Register read and write (P. 137)**, **A.3.7 Caution for handling communication data (P. 141)** and **9. COMMUNICATION DATA LIST (P. 52)**.

■ Error check

An error checking code (CRC-16: Cyclic Redundancy Check) is used to detect an error in the signal transmission.



For details, see **A.3.5 Calculating CRC-16 (P. 134)**.

A.3.2 Function code

- Function code contents

Function code (Hexadecimal)	Function	Contents
03H	Read holding registers	Measured value, control output value, current transformer input value, Event status, etc.
06H	Preset single register	Set value, PID constants, event set value, etc.
08H	Diagnostics (loopback test)	Loopback test
10H	Preset multiple registers	Set value, PID constants, event set value, etc.

- Message length of each function (Unit: byte)

Function code (Hexadecimal)	Function	Query message		Response message	
		Min	Max	Min	Max
03H	Read holding registers	8	8	7	255
06H	Preset single register	8	8	8	8
08H	Diagnostics (loopback test)	8	8	8	8
10H	Preset multiple registers	11	255	8	8

A.3.3 Communication mode

Signal transmission between the master and slaves is conducted in Remote Terminal Unit (RTU) mode.

Items	Contents
Data bit length	8-bit (Binary)
Start mark of message	Unused
End mark of message	Unused
Message length	See A.3.2 Function code
Data time interval	Less than 24-bit time *
Error check	CRC-16 (Cyclic Redundancy Check)

* When sending a command message from the master, set intervals of data configuring one message to time shorter than the 24-bit time. If time intervals become time longer than the 24-bit time the relevant slave assumes that message sending from the master is terminated to deform the message format. As a result, the slave does not make a response.

A.3.4 Slave responses

(1) Normal response

- In the response message of the Read Holding Registers, the slave returns the read out data and the number of data items with the same slave address and function code as the query message.
- In the response message of the Preset Single Register, the slave returns the same message as the query message.
- In the response message of the Diagnostics (Loopback test), the slave returns the same message as the query message.
- In the response message of the Preset Multiple Registers, the slave returns the slave address, the function code, starting number, and number of holding registers in the multi-query message.

(2) Defective message response

- If the query message from the master is defective, except for transmission error, the slave (SRZ unit) returns the error response message without any action.

Example: If there is a problem in the data range of CH3 when writing data of four channels, the data of CH1 and CH2 will be written. The data of CH3 and CH4 will be disregarded and an error response message will be returned.

Slave address
Function code
Error code
Error check CRC-16

Error response message

- If the self-diagnostic function of the slave (SRZ unit) detects an error, the slave (SRZ unit) will return an error response message to all query messages.
- The function code of each error response message is obtained by adding 80H to the function code of the query message.

Error code	Contents
1	Function code error (An unsupported function code was specified)
2	When the mismatched address (9000h to FFFFh) is specified.
3	<ul style="list-style-type: none"> • The maximum number (Read from a read holding register) has been exceeded. • When the data written exceeds the setting range

- Order of determination of error
Error code 1 > Error code 3 > Error code 2

(3) No response

The slave (SRZ unit) ignores the query message and does not respond when:

- The slave address in the query message does not coincide with any slave address settings.
- The CRC code of the master does not coincide with that of the slave.
- Transmission error such as overrun, framing, parity and etc., is found in the query message.
- Data time interval in the query message from the master exceeds 24-bit time.
- At the time of “Preset multiple registers (Write multiple registers),” the number of data (the number of requested byte) or “the requested number of data” does not match the actual number of the data.

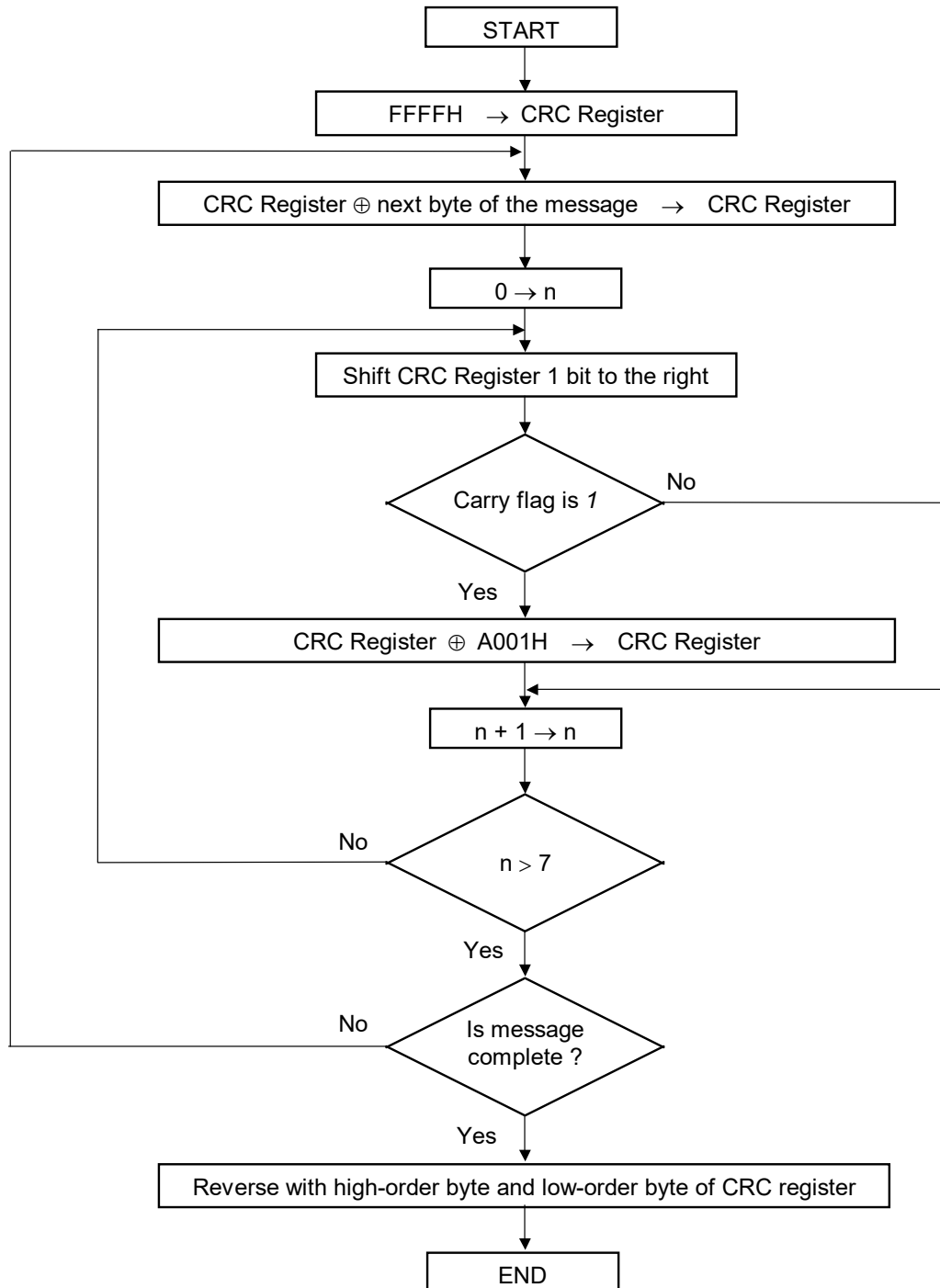
A.3.5 Calculating CRC-16

The Cyclic Redundancy Check (CRC) is a 2 byte (16-bit) error check code. After constructing the data message, not including start, stop, or parity bit, the master calculates a CRC code and appends this to the end of the message. The slave will calculate a CRC code from the received message, and compare it with the CRC code from the master. If they do not match, a communication error has occurred and the slave does not respond.

The CRC code is formed in the following sequence:

1. Load FFFFH to a 16-bit CRC register.
2. *Exclusive OR* (\oplus) the first byte (8 bits) of the message with the CRC register. Return the result to the CRC register.
3. Shift the CRC register 1 bit to the right.
4. If the carry flag is 1, *exclusive OR* the CRC register with A001 hex and return the result to the CRC register. If the carry flag is 0, repeat step 3.
5. Repeat step 3 and 4 until there have been 8 shifts.
6. *Exclusive OR* the next byte (8 bits) of the message with the CRC register.
7. Repeat step 3 through 6 for all bytes of the message (except the CRC).
8. The CRC register contains the 2 byte CRC error code. When they are appended to the message, the low-order byte is appended first, followed by the high-order byte.

■ The flow chart of CRC-16



The \oplus symbol indicates an *exclusive OR* operation. The symbol for the number of data bits is n .

■ Example of a CRC calculation in the 'C' language

This routine assumes that the data types 'uint16' and 'uint8' exists. These are unsigned 16-bit integer (usually an 'unsigned short int' for most compiler types) and unsigned 8-bit integer (unsigned char). 'z_p' is a pointer to a Modbus message, and 'z_messaage_length' is its length, excluding the CRC. Note that the Modbus message will probably contain NULL characters and so normal C string handling techniques will not work.

```
uint16 calculate_crc (byte *z_p, uint16 z_message_length)

/* CRC runs cyclic Redundancy Check Algorithm on input z_p */
/* Returns value of 16 bit CRC after completion and */
/* always adds 2 crc bytes to message */
/* returns 0 if incoming message has correct CRC */

{
    uint16 CRC= 0xffff;
    uint16 next;
    uint16 carry;
    uint16 n;
    uint8 crch, crcl;

    while (z_message_length--) {
        next = (uint16) *z_p;
        CRC ^= next;
        for (n = 0; n < 8; n++) {
            carry = CRC & 1;
            CRC >>= 1;
            if (carry) {
                CRC ^= 0xA001;
            }
        }
        z_p++;
    }
    crch = CRC / 256;
    crcl = CRC % 256
    z_p [z_message_length++] = crcl;
    z_p [z_message_length] = crch;
    return CRC;
}
```

A.3.6 Register read and write

■ Read holding registers [03H]

The query message specifies the starting register address and quantity of registers to be read. The contents of the holding registers are entered in the response message as data, divided into two parts: the high-order 8-bit and the low-order 8-bit, arranged in the order of the register numbers.

Example: The contents of the four holding registers from 01FCH to 01FFH are the read out from slave address 2.

Query message

Slave address		02H
Function code		03H
Starting number	High	01H
	Low	FCH
Quantity	High	00H
	Low	04H
CRC-16	High	85H
	Low	F6H

} First holding register address

} The setting must be between 1 (0001H) and 125 (007DH).

Normal response message

Slave address		02H
Function code		03H
Number of data		08H
First holding register contents	High	01H
	Low	24H
Next holding register contents	High	01H
	Low	1BH
Next holding register contents	High	01H
	Low	2BH
Next holding register contents	High	01H
	Low	22H
CRC-16	High	AAH
	Low	F3H

→ Number of holding registers × 2

Error response message

Slave address		02H
80H + Function code		83H
Error code		03H
CRC-16	High	F1H
	Low	31H

■ Preset single register [06H]

The query message specifies data to be written into the designated holding register. The write data is arranged in the query message with high-order 8-bit first and low-order 8-bit next. Only R/W holding registers can be specified.

Example: Data is written into the holding register 0ADCH of slave address 1.

Query message

Slave address		01H	} Any data within the range
Function code		06H	
Holding register number	High	0AH	
	Low	DCH	
Write data	High	00H	
	Low	64H	
CRC-16	High	4AH	
	Low	03H	

Normal response message

Slave address		01H	} Contents will be the same as query message data.
Function code		06H	
Holding register number	High	0AH	
	Low	DCH	
Write data	High	00H	
	Low	64H	
CRC-16	High	4AH	
	Low	03H	

Error response message

Slave address		01H
80H + Function code		86H
Error code		02H
CRC-16	High	C3H
	Low	A1H

■ Diagnostics (Loopback test) [08H]

The master's query message will be returned as the response message from the slave (SRZ unit).
This function checks the communication system between the master and slave (SRZ unit).

Example: Loopback test for slave address 1

Query message

Slave address		01H	
Function code		08H	
Test code	High	00H	} Test code must be set to 00.
	Low	00H	
Data	High	1FH	} Any pertinent data
	Low	34H	
CRC-16	High	E9H	
	Low	ECH	

Normal response message

Slave address		01H	
Function code		08H	
Test code	High	00H	} Contents will be the same as query message data.
	Low	00H	
Data	High	1FH	
	Low	34H	
CRC-16	High	E9H	
	Low	ECH	

Error response message

Slave address		01H
80H + Function code		88H
Error code		02H
CRC-16	High	C7H
	Low	C1H

■ Preset multiple registers [10H]

The query message specifies the starting register address and quantity of registers to be written. The write data is arranged in the query message with high-order 8-bit first and low-order 8-bit next. Only R/W holding registers can be specified.

Example: Data is written into the two holding registers from 0ADCH to 0ADDH of slave address 1.

Query message

Slave address		01H	
Function code		10H	
Starting number	High	0AH	} First holding register address
	Low	DCH	
Quantity	High	00H	} The setting must be between 1 (0001H) and 123 (007BH).
	Low	02H	
Number of data		04H	→ Number of holding registers × 2
Data to first register	High	00H	} Any pertinent data
	Low	64H	
Data to next register	High	00H	
	Low	64H	
CRC-16	High	C0H	
	Low	32H	

Normal response message

Slave address		01H
Function code		10H
Starting number	High	0AH
	Low	DCH
Quantity	High	00H
	Low	02H
CRC-16	High	83H
	Low	EAH

Error response message

Slave address		01H
80H + Function code		90H
Error code		02H
CRC-16	High	CDH
	Low	C1H

A.3.7 Caution for handling communication data

- The numeric range of data used in Modbus protocol is 0000H to FFFFH. Only the set value within the setting range is effective.



FFFFH represents -1.

- The Modbus protocol does not recognize data with decimal points during communication.

Example1: When Heater break alarm (HBA) set value is 20.0 A, 20.0 is processed as 200,
200 = 00C8H

Heater break alarm (HBA) set value	High	00H
	Low	C8H

Example2: When Set value (SV) is -20.0 °C, -20.0 is processed as -200,
-200 = 0000H - 00C8H = FF38H

Set value (SV)	High	FFH
	Low	38H

- In this communication, the data that memory area includes handles different address for Control area and for setting area.
- When an address (9000h to FFFFh), which is outside the address range accessible by the data (holding register), is accessed, an error message is returned.
- Read data of unused item is a default value.
- Any attempt to write to an unused item is not processed as an error. Data cannot be written into an unused item.
- If an error (data range error or address error) is detected in the data writing process, an error is returned. Writing is aborted at and after the addresses where an error occurred. After having completed the setting, check to see if the data was properly written.
- An attribute of the item for functions which are not in the controller is RO (read only). If read action to this item is performed, the read data will be "0." If write action to this item is performed, no error message is indicated and no data is written.



For details, see **9. COMMUNICATION DATA LIST (P. 52)**.

- Send the next command message at time intervals of 24 bits after the master receives the response message.

A.3.8 How to use memory area data

Memory area function can store up to 8 individual sets of SVs and parameters. One of the areas is used for control, and the currently selected area is “Control area.”

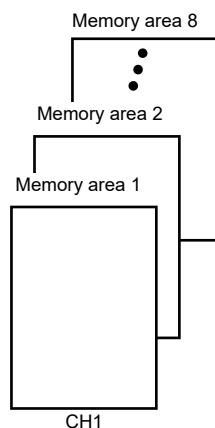
Memory area data can be used to check and change settings that belong to memory areas other than the control area. Reading and writing of memory area data is performed by channel.

■ Read and write of memory area data

If any memory area number to perform data read and write is specified by the setting memory area number (386CH to 38ABH), data corresponding to the specified memory area number is called up to the register addresses from 38ACH to 3DABH. By using these register addresses from 38ACH to 3DABH, it becomes possible to read and write data in any memory area.

	Register address				
	CH1	CH2	CH64	
Setting memory area number	386CH	386DH	38ABH	← Register address to specify memory area
Event 1 set value (EV1)	38ACH	38ADH	38EBH	
Event 2 set value (EV2)	38ECH	38EDH	392BH	
Event 3 set value (EV3)	392CH	392DH	396BH	
Event 4 set value (EV4)	396CH	396DH	39ABH	Register address of memory area data
Control loop break alarm (LBA) time	39ACH	39ADH	39EBH	
LBA deadband	39ECH	39EDH	3A2BH	
Set value (SV)	3A2CH	3A2DH	3A6BH	
Proportional band [heat-side]	3A6CH	3A6DH	3AABH	
Integral time [heat-side]	3AACH	3AADH	3AEBH	
Derivative time [heat-side]	3AECH	3AEDH	3B2BH	
Control response parameter	3B2CH	3B2DH	3B6BH	
Proportional band [cool-side]	3B6CH	3B6DH	3BABH	
Integral time [cool-side]	3BACH	3BADH	3BEBH	
Derivative time [cool-side]	3BECH	3BEDH	3C2BH	
Overlap/Deadband	3C2CH	3C2DH	3C6BH	
Manual reset	3C6CH	3C6DH	3CABH	
Setting change rate limiter (up)	3CACH	3CADH	3CEBH	
Setting change rate limiter (down)	3CECH	3CEDH	3D2BH	
Area soak time	3D2CH	3D2DH	3D6BH	
Link area number	3D6CH	3D6DH	3DABH	

☞ For the Memory area data list, see **9.4 Memory Area Data Address of Z-TIO Module (only for Modbus) (P. 83)**.



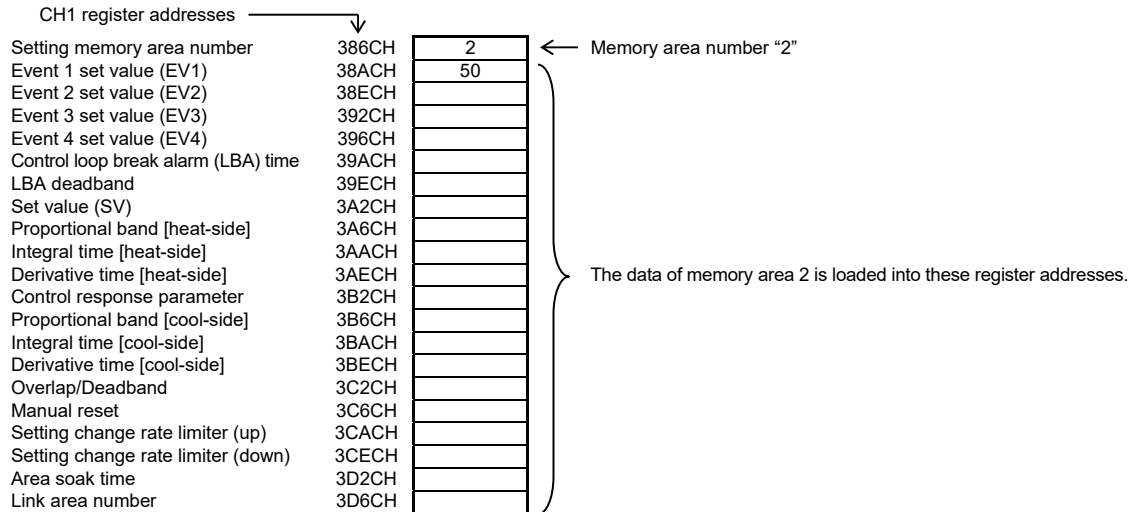
A memory area number which data is read/written is written to the register address, 386CH (for CH1).

Data corresponding to a specified memory area number is called up to the CH1 register addresses.

Event 1 set value (EV1) (38ACH)
 Event 2 set value (EV2) (38ECH)
 Event 3 set value (EV3) (392CH)
 Event 4 set value (EV4) (396CH)
 Control loop break alarm (LBA) time (39ACH)
 LBA deadband (39ECH)
 Set value (SV) (3A2CH)
 Proportional band [heat-side] (3A6CH)
 Integral time [heat-side] (3AACH)
 Derivative time [heat-side] (3AECH)
 Control response parameter (3B2CH)
 Proportional band [cool-side] (3B6CH)
 Integral time [cool-side] (3BACH)
 Derivative time [cool-side] (3BECH)
 Overlap/Deadband (3C2CH)
 Manual reset (3C6CH)
 Setting change rate limiter (up) (3CACH)
 Setting change rate limiter (down) (3CECH)
 Area soak time (3D2CH)
 Link area number (3D6CH)

[Example 1] When data on the Event 1 set value in Memory area 2 of CH1 is read

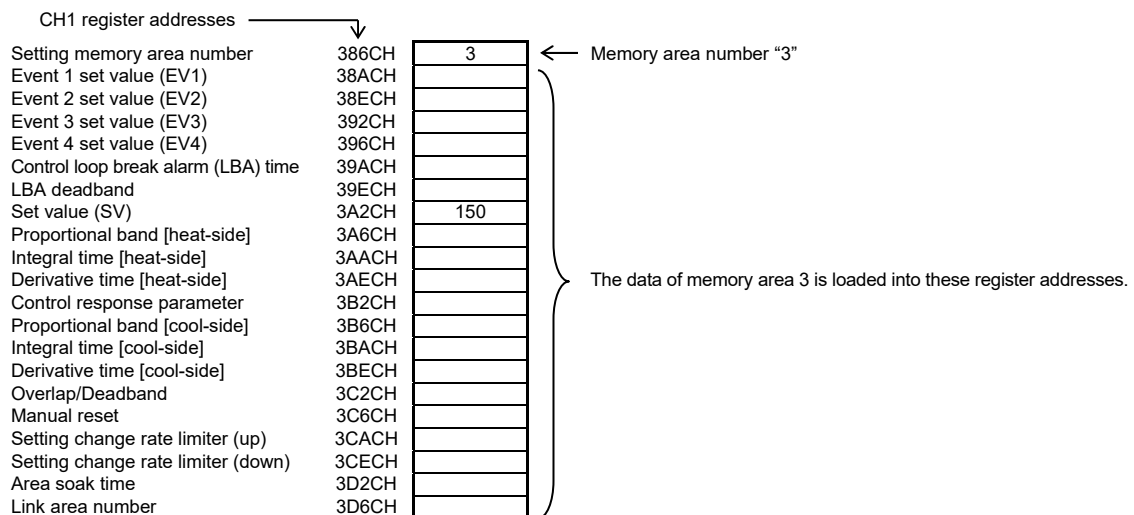
1. The memory area number, “2” is written to the CH1 setting memory area number (386CH).
Data in Memory area 2 is called up to the CH1 register addresses.



2. Data “50” on Event 1 set value (38ACH) is read.

[Example 2] When the set value (SV) in Memory area 3 of CH1 is changed to 200

1. The memory area number, “3” is written to the CH1 setting memory area number (386CH).
Data in Memory area 3 is called up to the CH1 register addresses.



2. “200” is written to the set value (SV) (3A2CH).

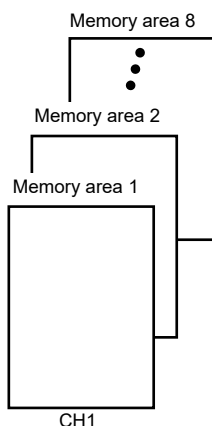
■ Control area transfer

Any memory area used for control is specified by the memory area transfer (08DCH to 091BH). The area (095CH to 0E5BH) now used for control is called “Control area.”



The memory area number (control area) can be changed at either RUN or STOP.

	Register address				
	CH1	CH2	CH64	
Memory area transfer	08DCH	08DDH	091BH	← Register address to specify control area
Event 1 set value (EV1)	095CH	095DH	099BH	
Event 2 set value (EV2)	099CH	099DH	09DBH	Register address of memory area data
Event 3 set value (EV3)	09DCH	09DDH	0A1BH	
Event 4 set value (EV4)	0A1CH	0A1DH	0A5BH	
Control loop break alarm (LBA) time	0A5CH	0A5DH	0A9BH	
LBA deadband	0A9CH	0A9DH	0ADBH	
Set value (SV)	0ADCH	0ADDH	0B1BH	
Proportional band [heat-side]	0B1CH	0B1DH	0B5BH	
Integral time [heat-side]	0B5CH	0B5DH	0B9BH	
Derivative time [heat-side]	0B9CH	0B9DH	0BDBH	
Control response parameter	0BDCH	0BDDH	0C1BH	
Proportional band [cool-side]	0C1CH	0C1DH	0C5BH	
Integral time [cool-side]	0C5CH	0C5DH	0C9BH	
Derivative time [cool-side]	0C9CH	0C9DH	0CDBH	
Overlap/Deadband	0CDCH	0CDDH	0CDCH	
Manual reset	0D1CH	0D1DH	0D5BH	
Setting change rate limiter (up)	0D5CH	0D5DH	0D9BH	
Setting change rate limiter (down)	0D9CH	0D9DH	0DDBH	
Area soak time	0DDCH	0DDDH	0E1BH	
Link area number	0E1CH	0E1CH	0E5BH	



Any memory area number used for control is written to the register address, 08DCH (for CH1).

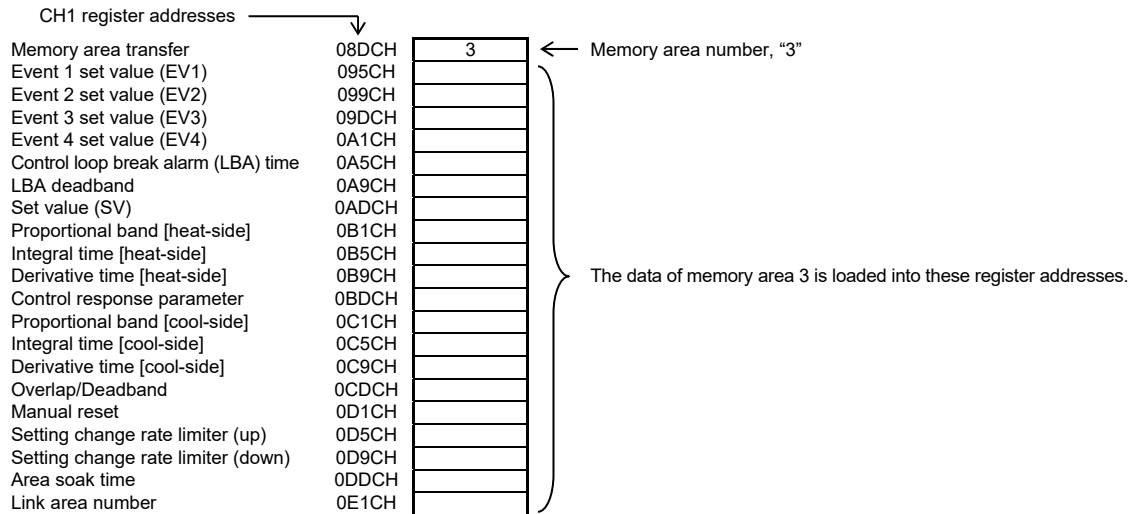
Data corresponding to a specified memory area number is called up to the CH1 register addresses.

— Control area —

Event 1 set value (EV1) (095CH)
 Event 2 set value (EV2) (099CH)
 Event 3 set value (EV3) (09DCH)
 Event 4 set value (EV4) (0A1CH)
 Control loop break alarm (LBA) time (0A5CH)
 LBA deadband (0A9CH)
 Set value (SV) (0ADCH)
 Proportional band [heat-side] (0B1CH)
 Integral time [heat-side] (0B5CH)
 Derivative time [heat-side] (0B9CH)
 Control response parameter (0BDCH)
 Proportional band [cool-side] (0C1CH)
 Integral time [cool-side] (0C5CH)
 Derivative time [cool-side] (0C9CH)
 Overlap/Deadband (0CDCH)
 Manual reset (0D1CH)
 Setting change rate limiter (up) (0D5CH)
 Setting change rate limiter (down) (0D9CH)
 Area soak time (0DDCH)
 Link area number (0E1CH)

[Example] When performing control by calling up data in Memory area 3 of CH1

1. The memory area number, "3" is written to the memory area transfer (08DCH).
Data in Memory area 3 is called up to the CH1 register addresses.



2. Control of CH1 is performed by using data in the register addresses.



If the memory area transfer (08DCH to 091BH) and the setting memory area number (386CH to 38ABH) are set to the same memory area number, the respective data can be synchronized.

- Values in the control areas (095CH to 0E5BH) and the setting memory area number (38ACH to 3DABH) are set to the same memory area number, the respective data can be synchronized.
- If data in the control area is changed, data in the memory area is also changed.
- If data in the memory area is changed, data in the control area is also changed.

■ Data mapping function

When using a COM-ME joined to function modules, the data mapping function cannot be used.

MEMO



RKC INSTRUMENT INC.

HEADQUARTERS: 16-6, KUGAHARA 5-CHOME, OHTA-KU TOKYO 146-8515 JAPAN

PHONE: 03-3751-9799 (+81 3 3751 9799)

E-mail: info@rkcinst.co.jp

Website: <https://www.rkcinst.co.jp/english/>

